Reti Bayesiane III

IALab A.A. 2018/2019

Inferenza Approssimata

Inference by stochastic simulation

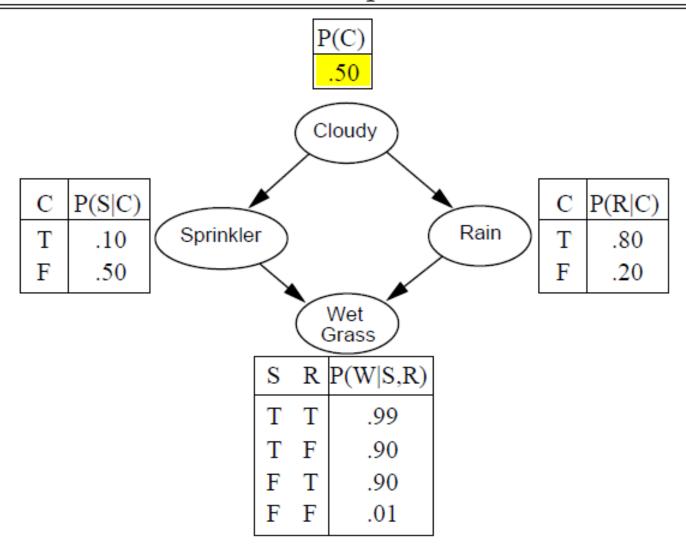
Basic idea:

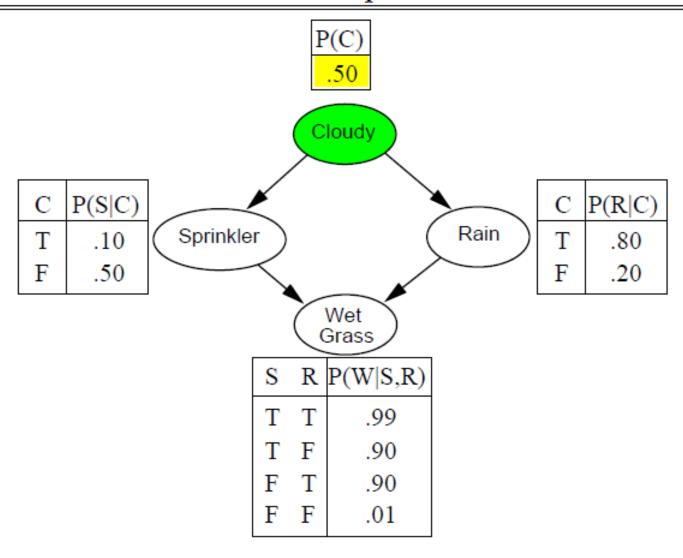
- 1) Draw N samples from a sampling distribution S
- 2) Compute an approximate posterior probability \hat{P}
- 3) Show this converges to the true probability P

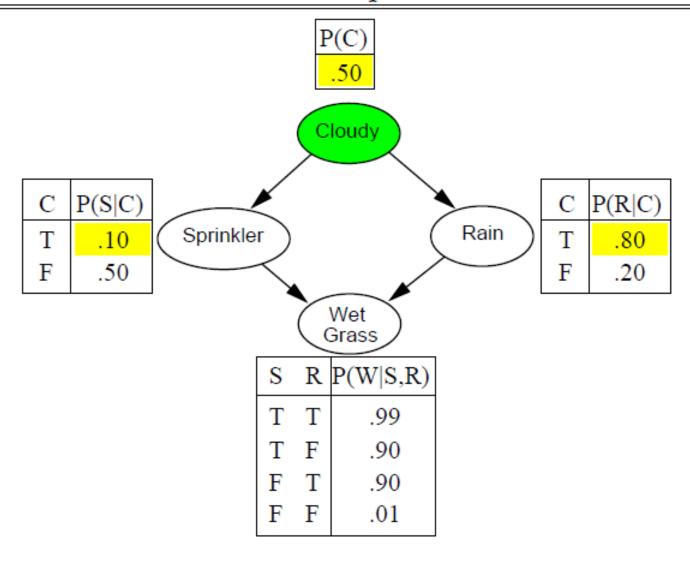
Outline:

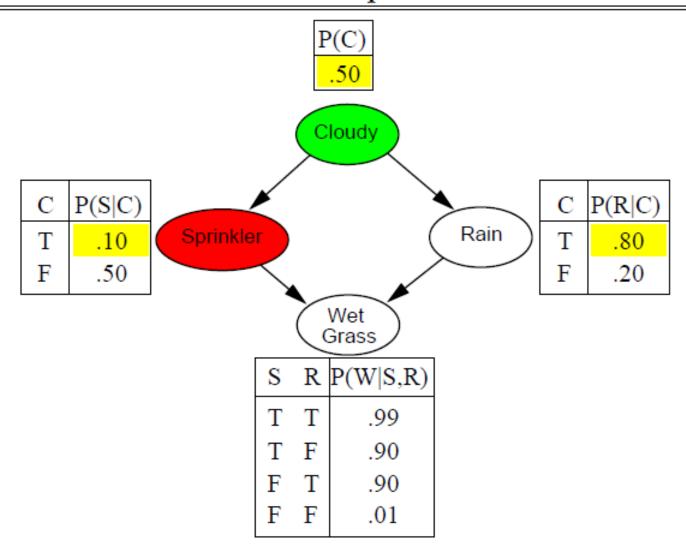
- Sampling from an empty network
- Rejection sampling: reject samples disagreeing with evidence
- Likelihood weighting: use evidence to weight samples

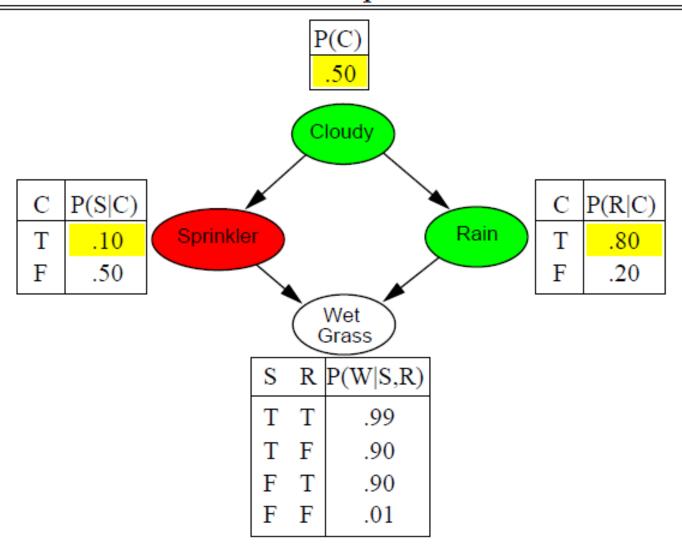


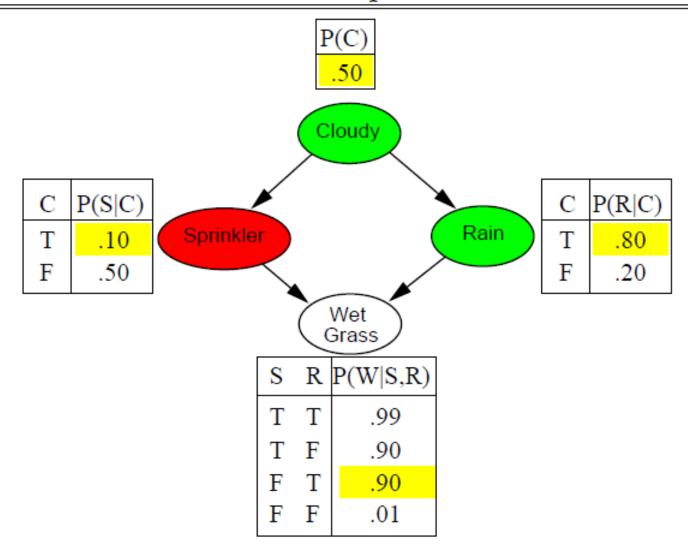


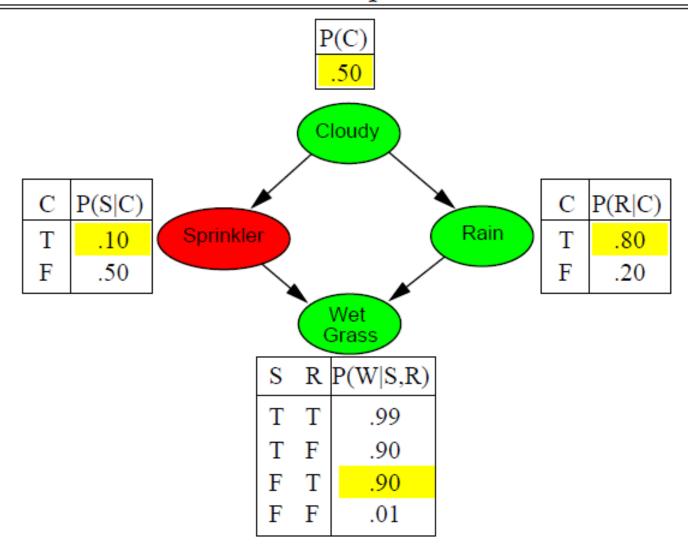












Sampling from an empty network contd.

Probability that PRIORSAMPLE generates a particular event

$$S_{PS}(x_1 \dots x_n) = \prod_{i=1}^n P(x_i|parents(X_i)) = P(x_1 \dots x_n)$$

i.e., the true prior probability

E.g.,
$$S_{PS}(t, f, t, t) = 0.5 \times 0.9 \times 0.8 \times 0.9 = 0.324 = P(t, f, t, t)$$

Let $N_{PS}(x_1 \dots x_n)$ be the number of samples generated for event x_1, \dots, x_n

Then we have

stima

$$\lim_{N \to \infty} \hat{P}(x_1, \dots, x_n) = \lim_{N \to \infty} N_{PS}(x_1, \dots, x_n)/N$$

$$= S_{PS}(x_1, \dots, x_n)$$

$$= P(x_1 \dots x_n)$$
numeri

That is, estimates derived from PRIORSAMPLE are consistent

Shorthand:
$$\hat{P}(x_1, \ldots, x_n) \approx P(x_1 \ldots x_n)$$

Rejection sampling

 $\hat{\mathbf{P}}(X|\mathbf{e})$ estimated from samples agreeing with \mathbf{e}

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function Rejection-Sampling(X, e, bn, N) returns an estimate of P(X|e) local variables: N, a vector of counts over X, initially zero for j=1 to N do x \leftarrow \text{PRIOR-Sample}(bn) if x is consistent with e then N[x] \leftarrow N[x] + 1 \text{ where } x \text{ is the value of } X \text{ in } x return NORMALIZE(N[X])
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E.g., estimate P(Rain|Sprinkler=true) using 100 samples 27 samples have Sprinkler=true Of these, 8 have Rain=true and 19 have Rain=false.
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$$\hat{\mathbf{P}}(Rain|Sprinkler = true) = \text{Normalize}(\langle 8, 19 \rangle) = \langle 0.296, 0.704 \rangle$$

Similar to a basic real-world empirical estimation procedure

Analysis of rejection sampling

```
\hat{\mathbf{P}}(X|\mathbf{e}) = \alpha \mathbf{N}_{PS}(X,\mathbf{e}) (algorithm defn.)

= \mathbf{N}_{PS}(X,\mathbf{e})/N_{PS}(\mathbf{e}) (normalized by N_{PS}(\mathbf{e}))

\approx \mathbf{P}(X,\mathbf{e})/P(\mathbf{e}) (property of PRIORSAMPLE)

= \mathbf{P}(X|\mathbf{e}) (defn. of conditional probability)
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Hence rejection sampling returns consistent posterior estimates

Problem: hopelessly expensive if P(e) is small

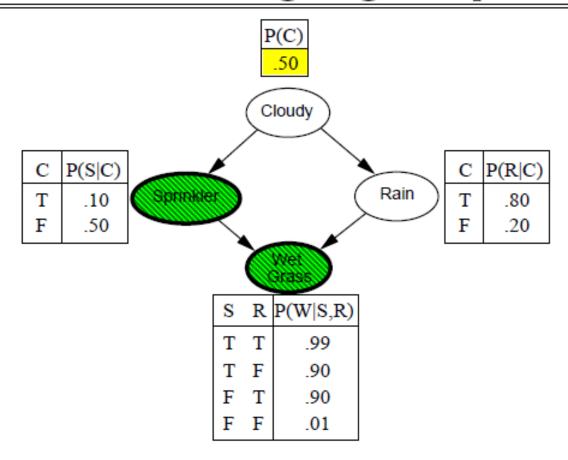
 $P(\mathbf{e})$ drops off exponentially with number of evidence variables!

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N_{PS}(X,e)/N\approx P(X,e)

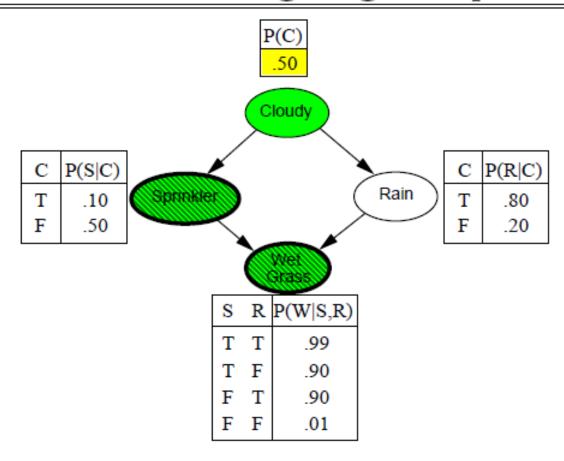
N_{PS}(e)/N\approx P(e)
```

Likelihood weighting

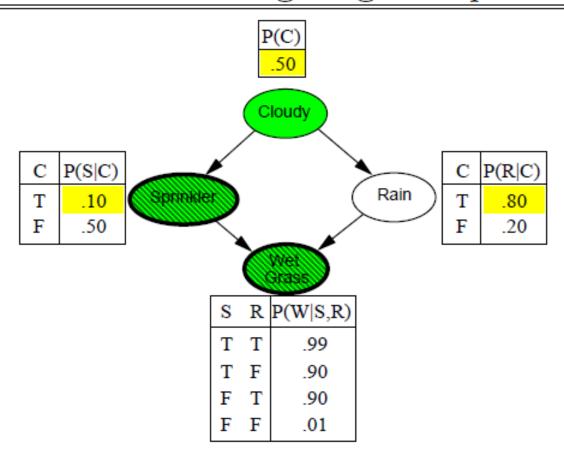
Idea: fix evidence variables, sample only nonevidence variables, and weight each sample by the likelihood it accords the evidence



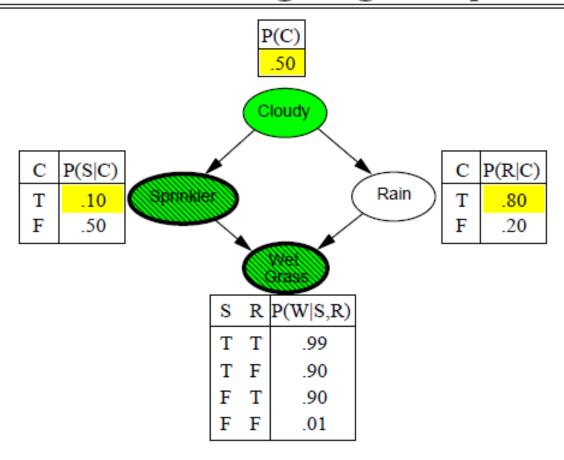
w = 1.0



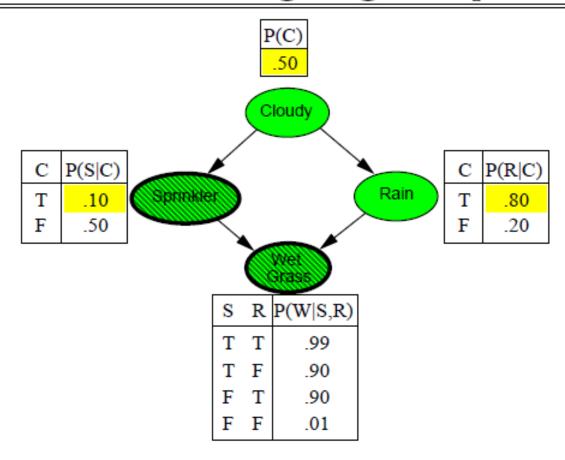
w = 1.0



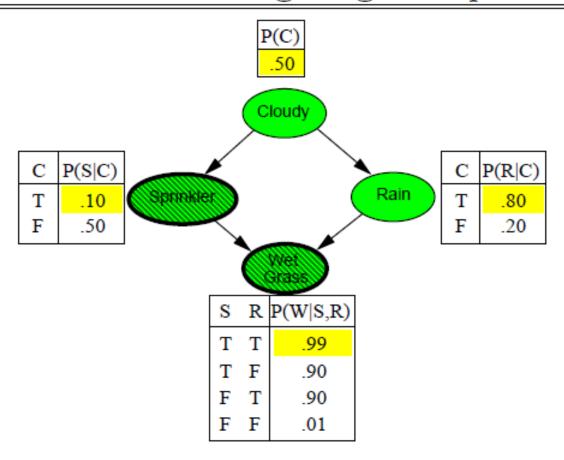
w = 1.0



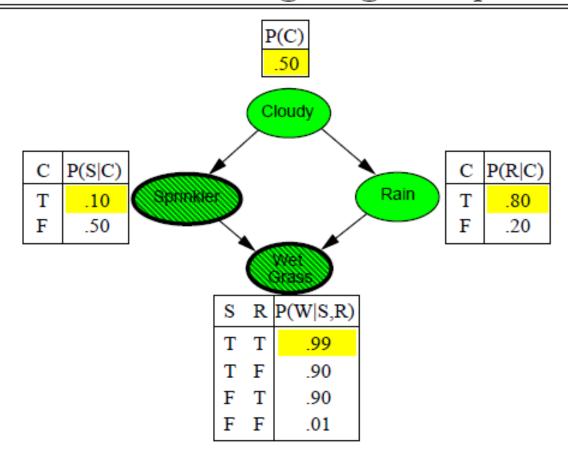
 $w = 1.0 \times 0.1$



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$$w = 1.0 \times 0.1 \times 0.99 = 0.099$$

Likelihood weighting analysis

m variabili e

di evidenza

Sampling probability for WeightedSample is

$$S_{WS}(\mathbf{z}, \mathbf{e}) = \prod_{i=1}^{l} P(z_i | parents(Z_i))$$
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Note: pays attention to evidence in ancestors only

⇒ somewhere "in between" prior and posterior distribution

Weight for a given sample z, e is

$$w(\mathbf{z}, \mathbf{e}) = \prod_{i=1}^{m} P(e_i | parents(E_i))$$

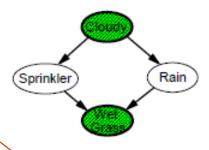
Weighted sampling probability is

$$S_{WS}(\mathbf{z}, \mathbf{e})w(\mathbf{z}, \mathbf{e})$$

= $\prod_{i=1}^{l} P(z_i|parents(Z_i)) \prod_{i=1}^{m} P(e_i|parents(E_i))$
= $P(\mathbf{z}, \mathbf{e})$ (by standard global semantics of network)

Hence likelihood weighting returns consistent estimates
but performance still degrades with many evidence variables
because a few samples have nearly all the total weight

l variabili **z** di non-evidenza



prossima slide

Likelihood Weighting

• che impatto ha il fatto che l'evidenza riguardi le "prime" o le "ultime" variabili (nell'ordinamento topologico)?

Likelihood Weighting

- che impatto ha il fatto che l'evidenza riguardi le "prime" o le "ultime" variabili (nell'ordinamento topologico)?
- se l'evidenza è nelle "prime" variabili, i campioni generati saranno più probabili data l'evidenza stessa, quindi con peso maggiore (più significativi)
- se l'evidenza è nelle "ultime" variabili, i campioni generati saranno generati essenzialmente secondo le probabilità a priori, e gli verranno assegnati pesi potenzialmente molto bassi (poco significativi)

Esercizio Inferenza Approssimata

- sperimentate con le implementazioni AIMA code di Rejection Sampling (RS) e Likelihood Weighting (LW) per verificare:
 - la dipendenza dell'accuratezza dei due algoritmi dal numero di campioni generati
 - la miglior convergenza di LW rispetto a RS
 - la miglior convergenza di LW quando le osservazioni sono all'inizio dell'ordine topologico