

Conoscenza Incerta

IALab A.A. 2018/2019

Uncertainty

Let action A_t = leave for airport t minutes before flight

Will A_t get me there on time?

Problems:

- 1) partial observability (road state, other drivers' plans, etc.)
- 2) noisy sensors (KCBS traffic reports)
- 3) uncertainty in action outcomes (flat tire, etc.)
- 4) immense complexity of modelling and predicting traffic

Hence a purely logical approach either

- 1) risks falsehood: " A_{25} will get me there on time"

or 2) leads to conclusions that are too weak for decision making:

" A_{25} will get me there on time if there's no accident on the bridge and it doesn't rain and my tires remain intact etc etc."

(A_{1440} might reasonably be said to get me there on time but I'd have to stay overnight in the airport ...)

Probability

Probabilistic assertions **summarize** effects of

laziness: failure to enumerate exceptions, qualifications, etc.

ignorance: lack of relevant facts, initial conditions, etc.

Subjective or Bayesian probability:

Probabilities relate propositions to one's own state of knowledge

e.g., $P(A_{25} | \text{no reported accidents}) = 0.06$

These are **not** claims of a “probabilistic tendency” in the current situation
(but might be learned from past experience of similar situations)

Probabilities of propositions change with new evidence:

e.g., $P(A_{25} | \text{no reported accidents, 5 a.m.}) = 0.15$

(Analogous to logical entailment status $KB \models \alpha$, not truth.)

Making decisions under uncertainty

Suppose I believe the following:

$$P(A_{25} \text{ gets me there on time} | \dots) = 0.04$$

$$P(A_{90} \text{ gets me there on time} | \dots) = 0.70$$

$$P(A_{120} \text{ gets me there on time} | \dots) = 0.95$$

$$P(A_{1440} \text{ gets me there on time} | \dots) = 0.9999$$

Which action to choose?

Depends on my preferences for missing flight vs. airport cuisine, etc.

Utility theory is used to represent and infer preferences

Decision theory = utility theory + probability theory

Probability basics

Begin with a set Ω —the sample space

e.g., 6 possible rolls of a die.

$\omega \in \Omega$ is a sample point/possible world/atomic event

A probability space or probability model is a sample space with an assignment $P(\omega)$ for every $\omega \in \Omega$ s.t.

$$0 \leq P(\omega) \leq 1$$

$$\sum_{\omega} P(\omega) = 1$$

e.g., $P(1) = P(2) = P(3) = P(4) = P(5) = P(6) = 1/6$.

An event A is any subset of Ω

$$P(A) = \sum_{\{\omega \in A\}} P(\omega)$$

E.g., $P(\text{die roll} < 4) = P(1) + P(2) + P(3) = 1/6 + 1/6 + 1/6 = 1/2$

Random variables

A **random variable** is a function from sample points to some range, e.g., the reals or Booleans

e.g., $Odd(1) = true$.

P induces a **probability distribution** for any r.v. X :

$$P(X = x_i) = \sum_{\{\omega: X(\omega) = x_i\}} P(\omega)$$

e.g., $P(Odd = true) = P(1) + P(3) + P(5) = 1/6 + 1/6 + 1/6 = 1/2$

Propositions

Think of a proposition as the event (set of sample points) where the proposition is true

Given Boolean random variables A and B :

event a = set of sample points where $A(\omega) = \text{true}$

event $\neg a$ = set of sample points where $A(\omega) = \text{false}$

event $a \wedge b$ = points where $A(\omega) = \text{true}$ and $B(\omega) = \text{true}$

proposizioni su valori R.V.:
($A=\text{true}$), ($A=\text{false}$),
($A=\text{true}$) & ($B=\text{true}$)

Often in AI applications, the sample points are **defined** by the values of a set of random variables, i.e., the sample space is the Cartesian product of the ranges of the variables

With Boolean variables, **sample point = propositional logic model**

e.g., $A = \text{true}$, $B = \text{false}$, or $a \wedge \neg b$.

Proposition = disjunction of atomic events in which it is true

e.g., $(a \vee b) \equiv (\neg a \wedge b) \vee (a \wedge \neg b) \vee (a \wedge b)$

$\Rightarrow P(a \vee b) = P(\neg a \wedge b) + P(a \wedge \neg b) + P(a \wedge b)$

Syntax for propositions

Propositional or Boolean random variables

e.g., *Cavity* (do I have a cavity?)

Cavity = true is a proposition, also written *cavity*

Discrete random variables (finite or infinite)

e.g., *Weather* is one of $\langle \textit{sunny}, \textit{rain}, \textit{cloudy}, \textit{snow} \rangle$

Weather = rain is a proposition

Values must be exhaustive and mutually exclusive

Continuous random variables (bounded or unbounded)

e.g., *Temp = 21.6*; also allow, e.g., *Temp < 22.0*.

Arbitrary Boolean combinations of basic propositions

Prior probability

Prior or unconditional probabilities of propositions

e.g., $P(Cavity = true) = 0.1$ and $P(Weather = sunny) = 0.72$

correspond to belief prior to arrival of any (new) evidence

Probability distribution gives values for all possible assignments:

$P(Weather) = \langle 0.72, 0.1, 0.08, 0.1 \rangle$ (normalized, i.e., sums to 1)

Joint probability distribution for a set of r.v.s gives the

probability of every atomic event on those r.v.s (i.e., every sample point)

$P(Weather, Cavity) =$ a 4×2 matrix of values:

<i>Weather =</i>	<i>sunny</i>	<i>rain</i>	<i>cloudy</i>	<i>snow</i>
<i>Cavity = true</i>	0.144	0.02	0.016	0.02
<i>Cavity = false</i>	0.576	0.08	0.064	0.08

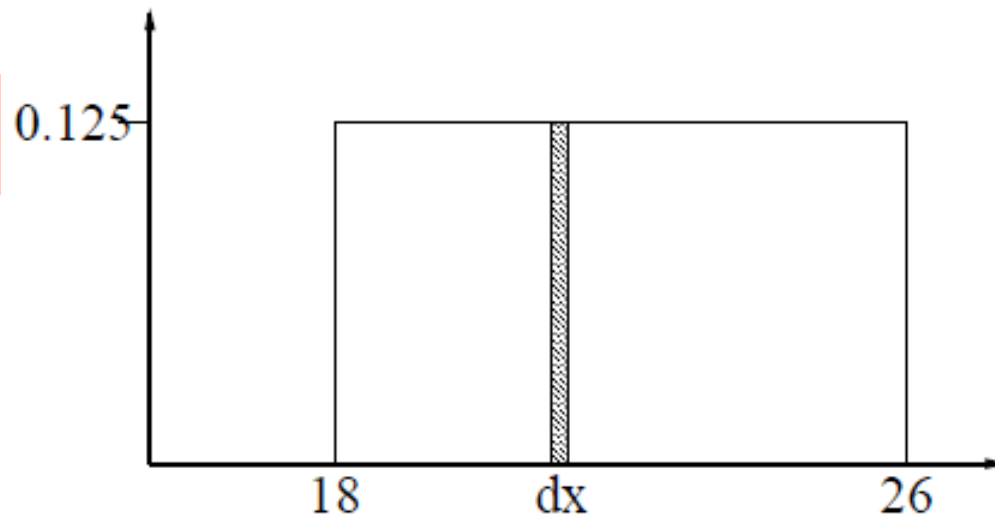
Every question about a domain can be answered by the joint distribution because every event is a sum of sample points

Probability for continuous variables

Express distribution as a parameterized function of value:

$$P(X = x) = U[18, 26](x) = \text{uniform density between 18 and 26}$$

pdf ==
probability density function



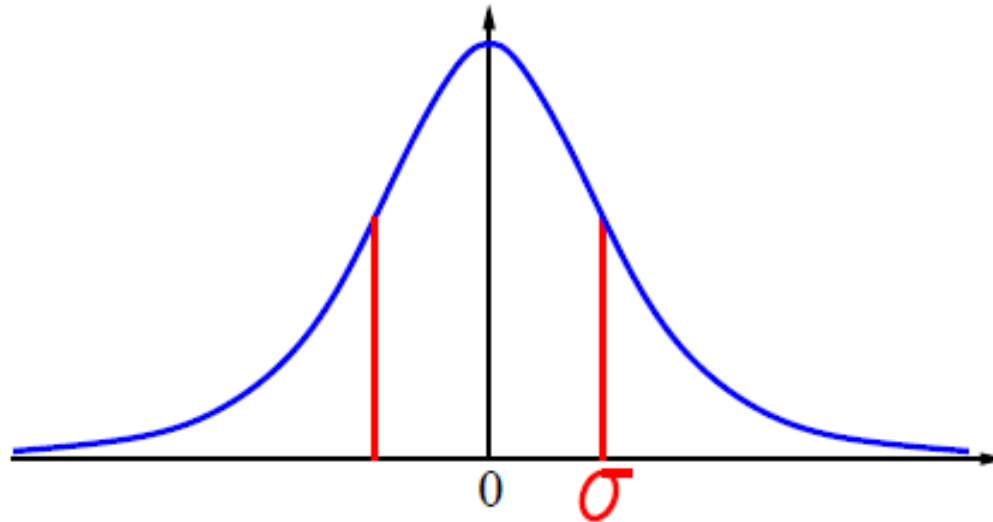
Here P is a density; integrates to 1.

$P(X = 20.5) = 0.125$ really means

$$\lim_{dx \rightarrow 0} P(20.5 \leq X \leq 20.5 + dx) / dx = 0.125$$

Gaussian density

$$P(x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-(x-\mu)^2/2\sigma^2}$$



Conditional probability

Conditional or posterior probabilities

e.g., $P(\text{cavity}|\text{toothache}) = 0.8$

i.e., given that *toothache* is all I know

NOT "if *toothache* then 80% chance of *cavity*"

(Notation for conditional distributions:

$P(\text{Cavity}|\text{Toothache}) = 2\text{-element vector of } 2\text{-element vectors})$

If we know more, e.g., *cavity* is also given, then we have

$P(\text{cavity}|\text{toothache}, \text{cavity}) = 1$

Note: the less specific belief **remains valid** after more evidence arrives, but is not always **useful**

New evidence may be irrelevant, allowing simplification, e.g.,

$P(\text{cavity}|\text{toothache}, \text{49ersWin}) = P(\text{cavity}|\text{toothache}) = 0.8$

This kind of inference, sanctioned by domain knowledge, **is crucial**

Conditional probability

Definition of conditional probability:

$$P(a|b) = \frac{P(a \wedge b)}{P(b)} \text{ if } P(b) \neq 0$$

Product rule gives an alternative formulation:

$$P(a \wedge b) = P(a|b)P(b) = P(b|a)P(a)$$

A general version holds for whole distributions, e.g.,

$$\mathbf{P}(\textit{Weather}, \textit{Cavity}) = \mathbf{P}(\textit{Weather}|\textit{Cavity})\mathbf{P}(\textit{Cavity})$$

(View as a 4×2 set of equations, **not** matrix mult.)

prossima
slide

Chain rule is derived by successive application of product rule:

$$\begin{aligned} \mathbf{P}(X_1, \dots, X_n) &= \mathbf{P}(X_1, \dots, X_{n-1}) \mathbf{P}(X_n|X_1, \dots, X_{n-1}) \\ &= \mathbf{P}(X_1, \dots, X_{n-2}) \mathbf{P}(X_{n-1}|X_1, \dots, X_{n-2}) \mathbf{P}(X_n|X_1, \dots, X_{n-1}) \\ &= \dots \\ &= \prod_{i=1}^n \mathbf{P}(X_i|X_1, \dots, X_{i-1}) \end{aligned}$$

Conditional Probability

La seguente definizione su V.A.:

$$\mathbf{P}(\text{Weather}, \text{Cavity}) = \mathbf{P}(\text{Weather} \mid \text{Cavity})\mathbf{P}(\text{Cavity})$$

si traduce in 8 equazioni "semplici":

$$P(\text{sunny}, \text{cavity}) = P(\text{sunny} \mid \text{cavity})P(\text{cavity})$$

$$P(\text{sunny}, \neg \text{cavity}) = P(\text{sunny} \mid \neg \text{cavity})P(\neg \text{cavity})$$

$$P(\text{rain}, \text{cavity}) = P(\text{rain} \mid \text{cavity})P(\text{cavity})$$

$$P(\text{rain}, \neg \text{cavity}) = P(\text{rain} \mid \neg \text{cavity})P(\neg \text{cavity})$$

$$P(\text{cloudy}, \text{cavity}) = P(\text{cloudy} \mid \text{cavity})P(\text{cavity})$$

$$P(\text{cloudy}, \neg \text{cavity}) = P(\text{cloudy} \mid \neg \text{cavity})P(\neg \text{cavity})$$

$$P(\text{snow}, \text{cavity}) = P(\text{snow} \mid \text{cavity})P(\text{cavity})$$

$$P(\text{snow}, \neg \text{cavity}) = P(\text{snow} \mid \neg \text{cavity})P(\neg \text{cavity})$$

Inference by enumeration

Start with the joint distribution:

	<i>toothache</i>		\neg <i>toothache</i>	
	<i>catch</i>	\neg <i>catch</i>	<i>catch</i>	\neg <i>catch</i>
<i>cavity</i>	.108	.012	.072	.008
\neg <i>cavity</i>	.016	.064	.144	.576

For any proposition ϕ , sum the atomic events where it is true:

$$P(\phi) = \sum_{\omega: \omega \models \phi} P(\omega)$$

Inference by enumeration

Start with the joint distribution:

	<i>toothache</i>		\neg <i>toothache</i>	
	<i>catch</i>	\neg <i>catch</i>	<i>catch</i>	\neg <i>catch</i>
<i>cavity</i>	.108	.012	.072	.008
\neg <i>cavity</i>	.016	.064	.144	.576

For any proposition ϕ , sum the atomic events where it is true:

$$P(\phi) = \sum_{\omega: \omega \models \phi} P(\omega)$$

$$P(\text{toothache}) = 0.108 + 0.012 + 0.016 + 0.064 = 0.2$$

Inference by enumeration

Start with the joint distribution:

	<i>toothache</i>		\neg <i>toothache</i>	
	<i>catch</i>	\neg <i>catch</i>	<i>catch</i>	\neg <i>catch</i>
<i>cavity</i>	.108	.012	.072	.008
\neg <i>cavity</i>	.016	.064	.144	.576

For any proposition ϕ , sum the atomic events where it is true:

$$P(\phi) = \sum_{\omega: \omega \models \phi} P(\omega)$$

$$P(\text{cavity} \vee \text{toothache}) = 0.108 + 0.012 + 0.072 + 0.008 + 0.016 + 0.064 = 0.28$$

Inference by enumeration

Start with the joint distribution:

	<i>toothache</i>		\neg <i>toothache</i>	
	<i>catch</i>	\neg <i>catch</i>	<i>catch</i>	\neg <i>catch</i>
<i>cavity</i>	.108	.012	.072	.008
\neg <i>cavity</i>	.016	.064	.144	.576

Can also compute conditional probabilities:

$$\begin{aligned} P(\neg \text{cavity} | \text{toothache}) &= \frac{P(\neg \text{cavity} \wedge \text{toothache})}{P(\text{toothache})} \\ &= \frac{0.016 + 0.064}{0.108 + 0.012 + 0.016 + 0.064} = 0.4 \end{aligned}$$

Normalization

	<i>toothache</i>		\neg <i>toothache</i>	
	<i>catch</i>	\neg <i>catch</i>	<i>catch</i>	\neg <i>catch</i>
<i>cavity</i>	.108	.012	.072	.008
\neg <i>cavity</i>	.016	.064	.144	.576

-

Denominator can be viewed as a normalization constant α

$$\begin{aligned}
 P(Cavity|toothache) &= \alpha P(Cavity, toothache) \\
 &= \alpha [P(Cavity, toothache, catch) + P(Cavity, toothache, \neg catch)] \\
 &= \alpha [\langle 0.108, 0.016 \rangle + \langle 0.012, 0.064 \rangle] \\
 &= \alpha \langle 0.12, 0.08 \rangle = \langle 0.6, 0.4 \rangle
 \end{aligned}$$

General idea: compute distribution on query variable
by fixing evidence variables and summing over hidden variables

Inference by enumeration, contd.

Let \mathbf{X} be all the variables. Typically, we want the posterior joint distribution of the query variables \mathbf{Y} given specific values \mathbf{e} for the evidence variables \mathbf{E}

marginalizzazione

Let the hidden variables be $\mathbf{H} = \mathbf{X} - \mathbf{Y} - \mathbf{E}$

Then the required summation of joint entries is done by **summing out** the hidden variables:

$$P(\mathbf{Y}|\mathbf{E}=\mathbf{e}) = \alpha P(\mathbf{Y}, \mathbf{E}=\mathbf{e}) = \alpha \sum_{\mathbf{h}} P(\mathbf{Y}, \mathbf{E}=\mathbf{e}, \mathbf{H}=\mathbf{h})$$

The terms in the summation are joint entries because \mathbf{Y} , \mathbf{E} , and \mathbf{H} together exhaust the set of random variables

Inference by enumeration, contd.

Let \mathbf{X} be all the variables. Typically, we want
the posterior joint distribution of the query variables \mathbf{Y}
given specific values \mathbf{e} for the evidence variables \mathbf{E}

Let the hidden variables be $\mathbf{H} = \mathbf{X} - \mathbf{Y} - \mathbf{E}$

Then the required summation of joint entries is done by summing out the hidden variables:

$$P(\mathbf{Y}|\mathbf{E}=\mathbf{e}) = \alpha P(\mathbf{Y}, \mathbf{E}=\mathbf{e}) = \alpha \sum_{\mathbf{h}} P(\mathbf{Y}, \mathbf{E}=\mathbf{e}, \mathbf{H}=\mathbf{h})$$

The terms in the summation are joint entries because \mathbf{Y} , \mathbf{E} , and \mathbf{H} together exhaust the set of random variables

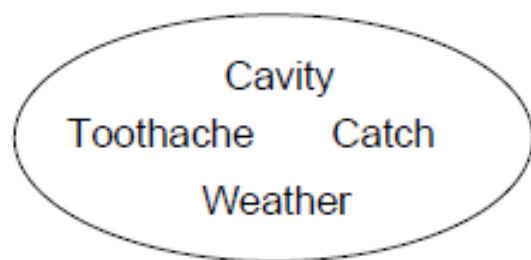
Obvious problems:

- 1) Worst-case time complexity $O(d^n)$ where d is the largest arity
- 2) Space complexity $O(d^n)$ to store the joint distribution
- 3) How to find the numbers for $O(d^n)$ entries???

Independence

A and B are independent iff

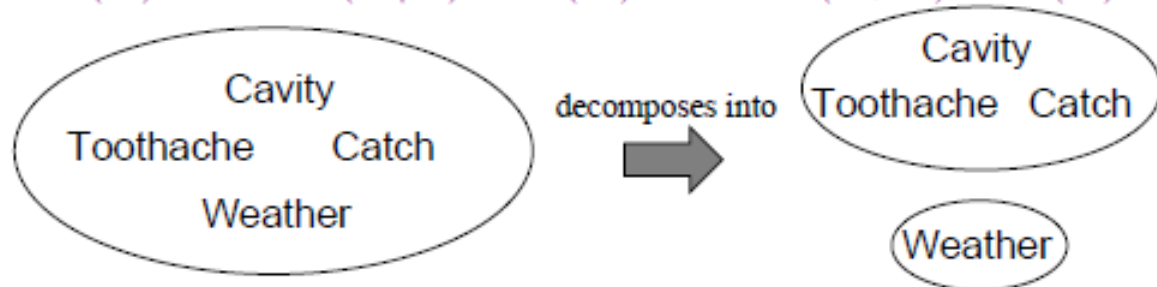
$$P(A|B) = P(A) \quad \text{or} \quad P(B|A) = P(B) \quad \text{or} \quad P(A, B) = P(A)P(B)$$



Independence

A and B are independent iff

$$P(A|B) = P(A) \quad \text{or} \quad P(B|A) = P(B) \quad \text{or} \quad P(A, B) = P(A)P(B)$$



$$P(\text{Toothache}, \text{Catch}, \text{Cavity}, \text{Weather}) \\ = P(\text{Toothache}, \text{Catch}, \text{Cavity})P(\text{Weather})$$

32 entries reduced to 12; for n independent biased coins, $2^n \rightarrow n$

Absolute independence powerful but rare

Dentistry is a large field with hundreds of variables,
none of which are independent. What to do?

Conditional independence

$P(\textit{Toothache}, \textit{Cavity}, \textit{Catch})$ has $2^3 - 1 = 7$ independent entries

If I have a cavity, the probability that the probe catches in it doesn't depend on whether I have a toothache:

$$(1) P(\textit{catch}|\textit{toothache}, \textit{cavity}) = P(\textit{catch}|\textit{cavity})$$

The same independence holds if I haven't got a cavity:

$$(2) P(\textit{catch}|\textit{toothache}, \neg \textit{cavity}) = P(\textit{catch}|\neg \textit{cavity})$$

Catch is conditionally independent of *Toothache* given *Cavity*:

$$P(\textit{Catch}|\textit{Toothache}, \textit{Cavity}) = P(\textit{Catch}|\textit{Cavity})$$

Equivalent statements:

$$P(\textit{Toothache}|\textit{Catch}, \textit{Cavity}) = P(\textit{Toothache}|\textit{Cavity})$$

$$P(\textit{Toothache}, \textit{Catch}|\textit{Cavity}) = P(\textit{Toothache}|\textit{Cavity})P(\textit{Catch}|\textit{Cavity})$$

prossima
slide

Conditional Independence

L'indipendenza condizionale di *Catch* e *Toothache* **dato** *Cavity*:

$$\mathbf{P}(\text{Catch} \mid \text{Toothache}, \text{Cavity}) = \mathbf{P}(\text{Catch} \mid \text{Cavity})$$

si esprime in modo *equivalente* come:

$$\mathbf{P}(\text{Toothache} \mid \text{Catch}, \text{Cavity}) = \mathbf{P}(\text{Toothache} \mid \text{Cavity})$$

Infatti:

$$\begin{aligned} P(\text{To} \mid \text{Ca}, \text{Cv}) &= \frac{P(\text{To}, \text{Ca}, \text{Cv})}{P(\text{Ca}, \text{Cv})} = \frac{P(\text{Ca} \mid \text{To}, \text{Cv})P(\text{To}, \text{Cv})}{P(\text{Ca} \mid \text{Cv})P(\text{Cv})} \\ &= \frac{P(\text{Ca} \mid \text{Cv})P(\text{To}, \text{Cv})}{P(\text{Ca} \mid \text{Cv})P(\text{Cv})} = P(\text{To} \mid \text{Cv}) \end{aligned}$$

uso definizione di prob. cond., product rule E assunzione

$$P(\text{Ca} \mid \text{To}, \text{Cv}) = P(\text{Ca} \mid \text{Cv})$$

Conditional Independence

L'indipendenza condizionale di *Catch* e *Toothache* **dato** *Cavity*:

$$\mathbf{P}(\text{Catch} \mid \text{Toothache}, \text{Cavity}) = \mathbf{P}(\text{Catch} \mid \text{Cavity})$$

si esprime in modo ***equivalente*** ***anche*** come:

$$\mathbf{P}(\text{Toothache}, \text{Catch} \mid \text{Cavity}) = \mathbf{P}(\text{Toothache} \mid \text{Cavity})\mathbf{P}(\text{Catch} \mid \text{Cavity})$$

Infatti:

$$\begin{aligned} P(\text{To}, \text{Ca} \mid \text{Cv}) &= \frac{P(\text{To}, \text{Ca}, \text{Cv})}{P(\text{Cv})} = \frac{P(\text{To} \mid \text{Ca}, \text{Cv})P(\text{Ca}, \text{Cv})}{P(\text{Cv})} \\ &= \frac{P(\text{To} \mid \text{Cv})P(\text{Ca} \mid \text{Cv})P(\text{Cv})}{P(\text{Cv})} \\ &= P(\text{To} \mid \text{Cv})P(\text{Ca} \mid \text{Cv}) \end{aligned}$$

uso definizione di prob. cond., regola del prodotto E
risultato slide precedente

Conditional independence contd.

Write out full joint distribution using chain rule:

$$\begin{aligned} &P(\textit{Toothache}, \textit{Catch}, \textit{Cavity}) \\ &= P(\textit{Toothache} | \textit{Catch}, \textit{Cavity}) P(\textit{Catch}, \textit{Cavity}) \\ &= P(\textit{Toothache} | \textit{Catch}, \textit{Cavity}) P(\textit{Catch} | \textit{Cavity}) P(\textit{Cavity}) \\ &= P(\textit{Toothache} | \textit{Cavity}) P(\textit{Catch} | \textit{Cavity}) P(\textit{Cavity}) \end{aligned}$$

I.e., $2 + 2 + 1 = 5$ independent numbers (equations 1 and 2 remove 2)

In most cases, the use of conditional independence reduces the size of the representation of the joint distribution from exponential in n to linear in n .

Conditional independence is our most basic and robust form of knowledge about uncertain environments.

Bayes' Rule

Product rule $P(a \wedge b) = P(a|b)P(b) = P(b|a)P(a)$

$$\Rightarrow \text{Bayes' rule } P(a|b) = \frac{P(b|a)P(a)}{P(b)}$$

or in distribution form

$$P(Y|X) = \frac{P(X|Y)P(Y)}{P(X)} = \alpha P(X|Y)P(Y)$$

Useful for assessing **diagnostic probability** from causal probability:

$$P(Cause|Effect) = \frac{P(Effect|Cause)P(Cause)}{P(Effect)}$$

E.g., let M be meningitis, S be stiff neck:

$$P(m|s) = \frac{P(s|m)P(m)}{P(s)} = \frac{0.8 \times 0.0001}{0.1} = 0.0008$$

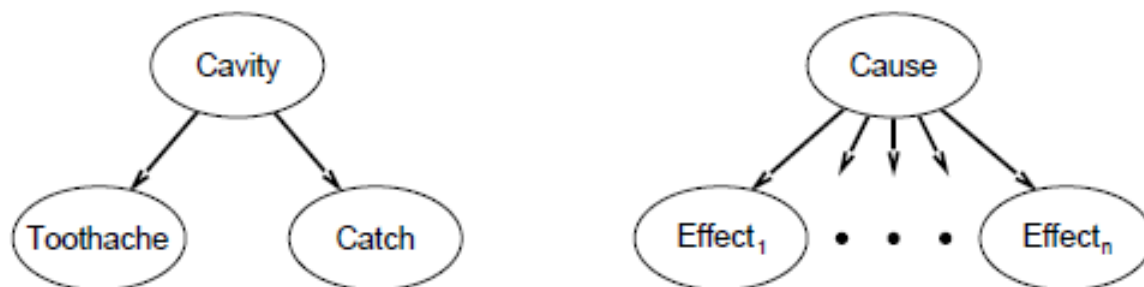
Note: posterior probability of meningitis still very small!

Bayes' Rule and conditional independence

$$\begin{aligned} & \mathbf{P}(Cavity|toothache \wedge catch) \\ &= \alpha \mathbf{P}(toothache \wedge catch|Cavity)\mathbf{P}(Cavity) \\ &= \alpha \mathbf{P}(toothache|Cavity)\mathbf{P}(catch|Cavity)\mathbf{P}(Cavity) \end{aligned}$$

This is an example of a naive Bayes model:

$$\mathbf{P}(Cause, Effect_1, \dots, Effect_n) = \mathbf{P}(Cause) \prod_i \mathbf{P}(Effect_i|Cause)$$



Total number of parameters is **linear** in n

Esercizio su Probabilità Condizionali

Il dottore vi dice:

- (brutta notizia) risultate positivo a un test T per una malattia M accurato al 99%
- (bella notizia) la probabilità di avere la malattia M alla vostra età è $1 / 10.000$

Riflettere **qualitativamente** sulla probabilità che abbiate la malattia M e calcolate **quantitativamente** tale probabilità in base alle informazioni ricevute.

Esercizio su Indipendenza Condizionale

- considerate Bellezza, Talento e Celebrità
- Bellezza e Talento sono indipendenti in senso assoluto?
- Bellezza e Talento sono indipendenti dato che conosciamo Celebrità?