

view_frames Result

Recorded at time: 1560968483.405

os1_sensor

Broadcaster: /os1_cloud_node

Average rate: 10000.000 Hz

Most recent transform: 0.000 (1560968483.405 sec old)

Buffer length: 0.000 sec

Broadcaster: /os1_cloud_node

Average rate: 10000.000 Hz

Most recent transform: 0.000 (1560968483.405 sec old)

Buffer length: 0.000 sec

os1_imu

os1_lidar