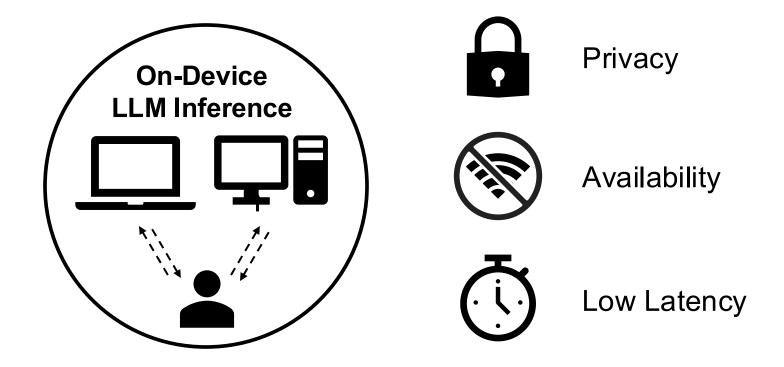
DecDEC: A Systems Approach to Advancing Low-Bit LLM Quantization

Yeonhong Park*, Jake Hyun*, Hojoon Kim, Jae W. Lee Seoul National University

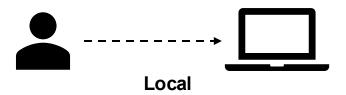
* These authors equally contributed to this work

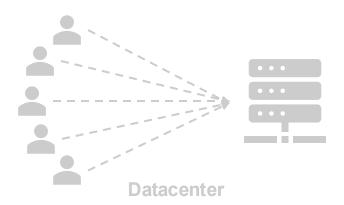
Preliminary: On-Device LLM Inference



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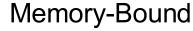
Single-Query Inference

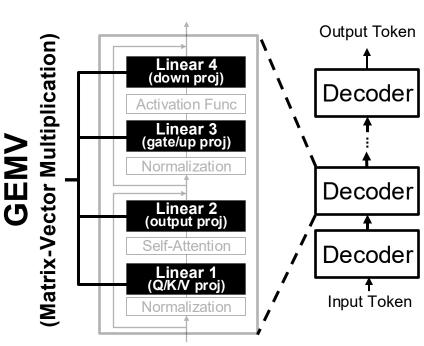




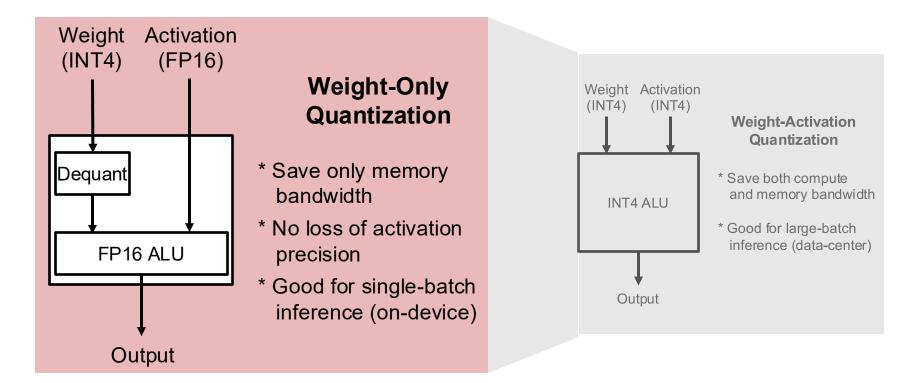
Preliminary: On-Device LLM Inference

Single-Query Inference Local **Datacenter**

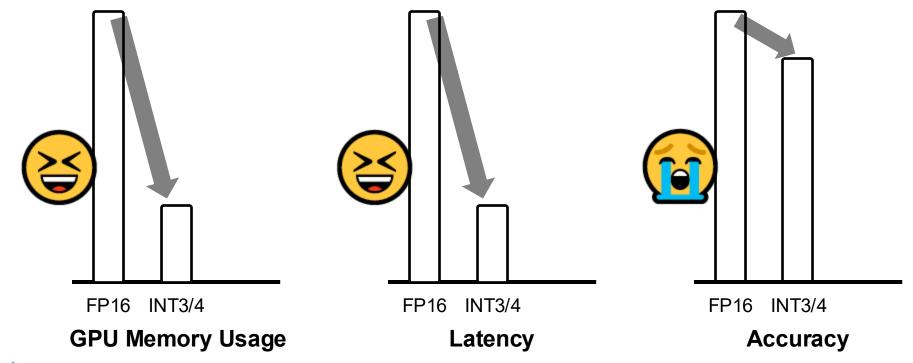




Preliminary: Weight-Only Quantization

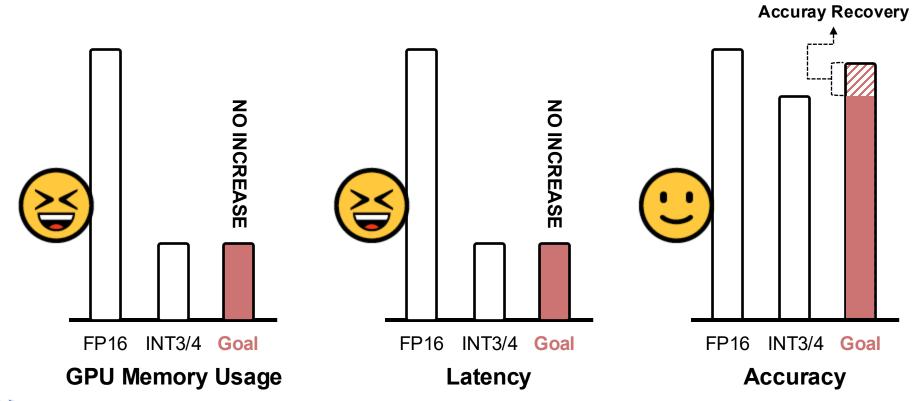


Upsides and Downsides of Quantization



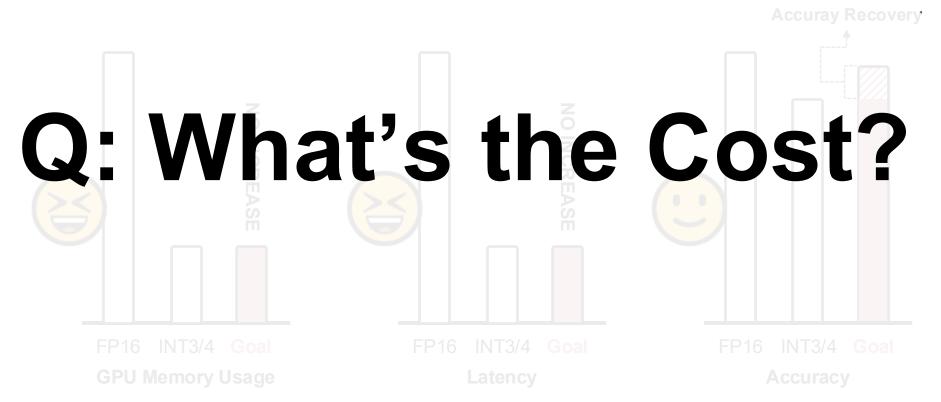


Research Goal: (Almost) Free Accuracy Recovery

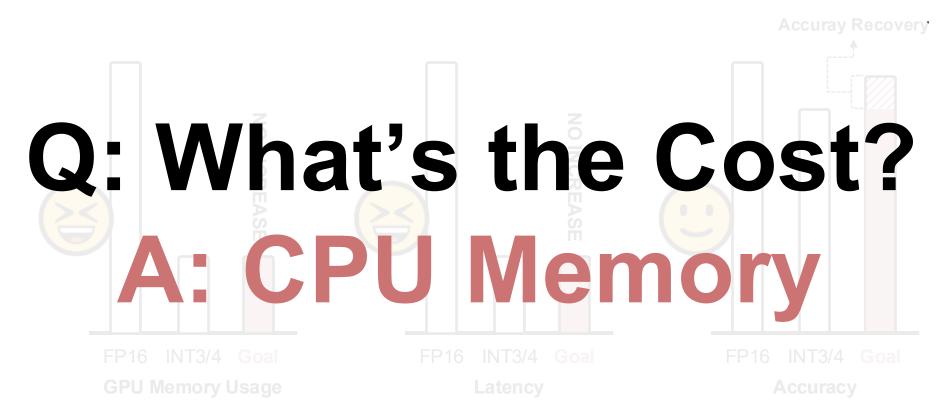


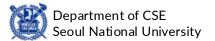


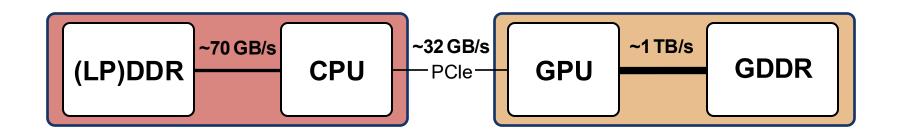
Research Goal: (Almost) Free Accuracy Recovery

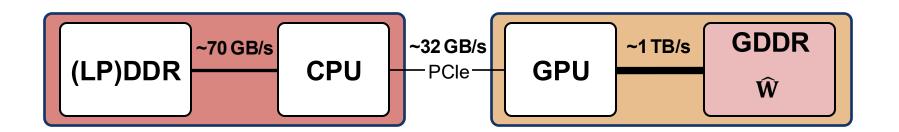


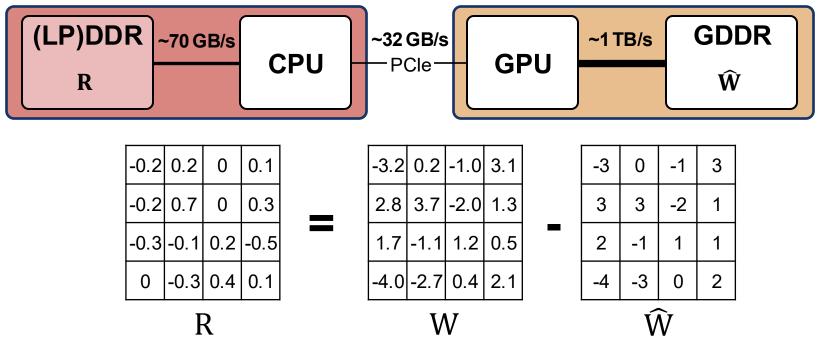
Research Goal: (Almost) Free Accuracy Recovery



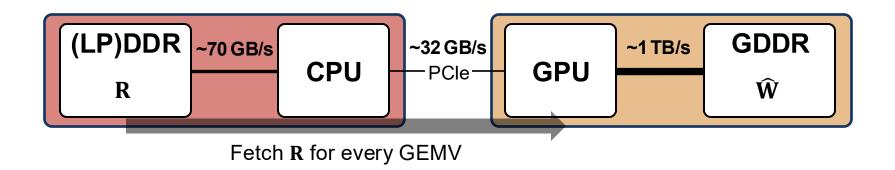












$$(\widehat{\mathbf{W}} + \mathbf{R}) * \mathbf{x} = \mathbf{W} * \mathbf{x}$$

Can fully recover full-precision weight, but may incur prohibitive slowdown

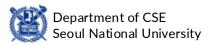




Selectively fetch R⊙M for every GEMV

$$(\widehat{\mathbf{W}} + \mathbf{R} \mathbf{O} \mathbf{M}) * \mathbf{x} = \mathbf{W} * \mathbf{x}$$

M: binary mask



Key Research Question

How to determine a subset of residuals to fetch (M)?

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A good **M** should:

* Select the most impactful portions For RTX-4090, PCIe BW: GPU BW = 32 GB/s: 1 TB/s

 \approx 1: 30

Key Research Question

How to determine a subset of residuals to fetch (M)?

A good **M** should:

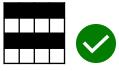
* Select the most impactful portions For RTX-4090, PCIe BW: GPU BW = 32 GB/s: 1 TB/s

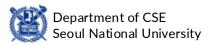
 \approx 1: 30

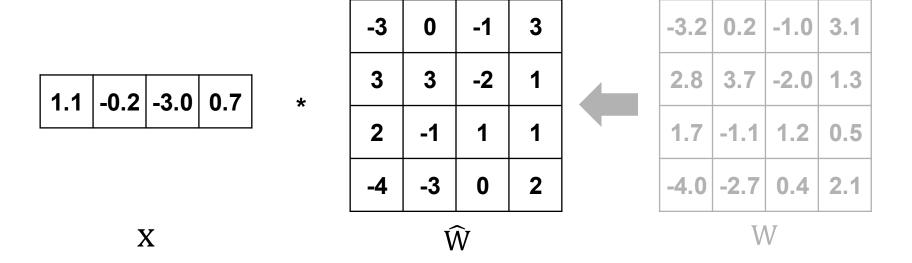
* Be structured for efficient processing

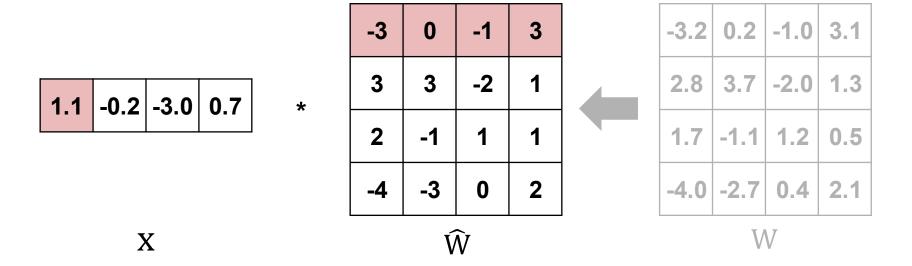


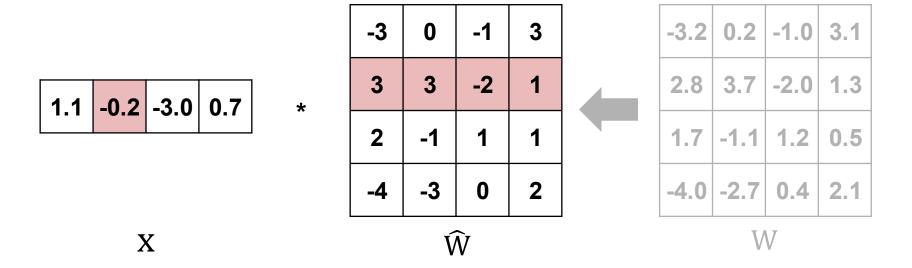


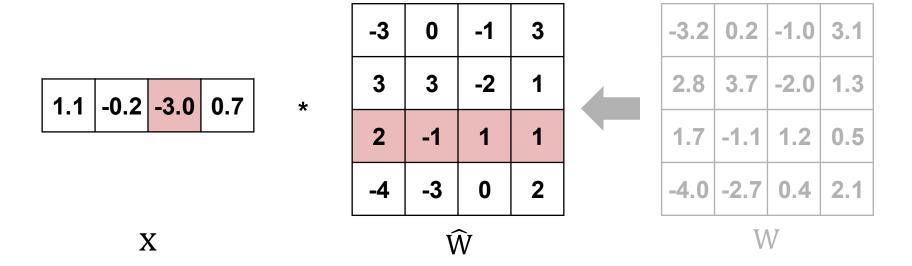


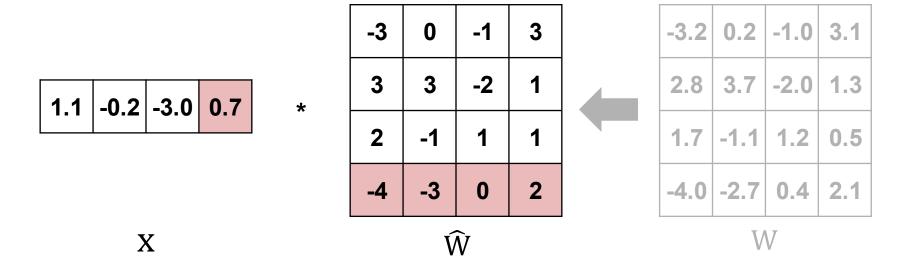


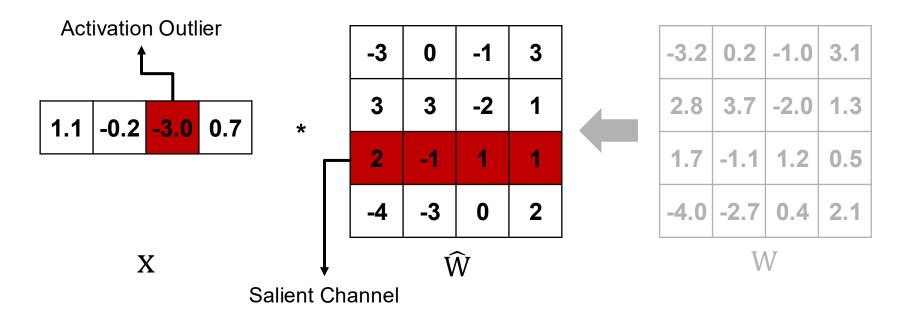


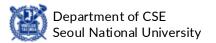


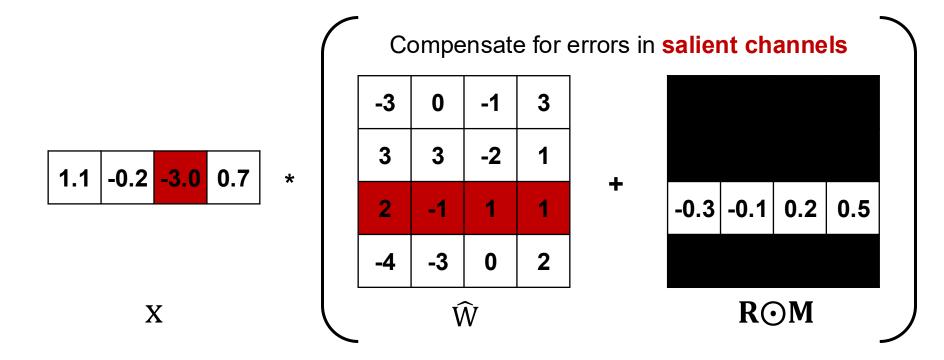




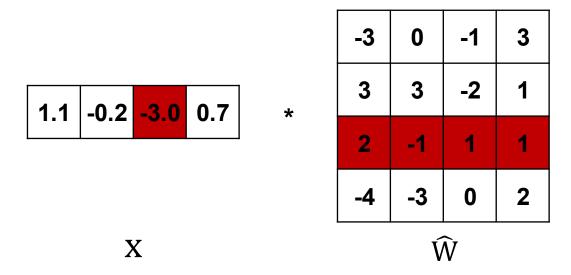




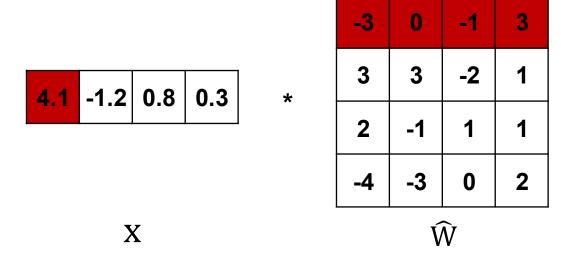




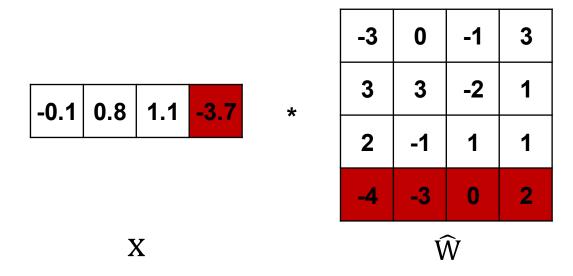
Decoding Step i

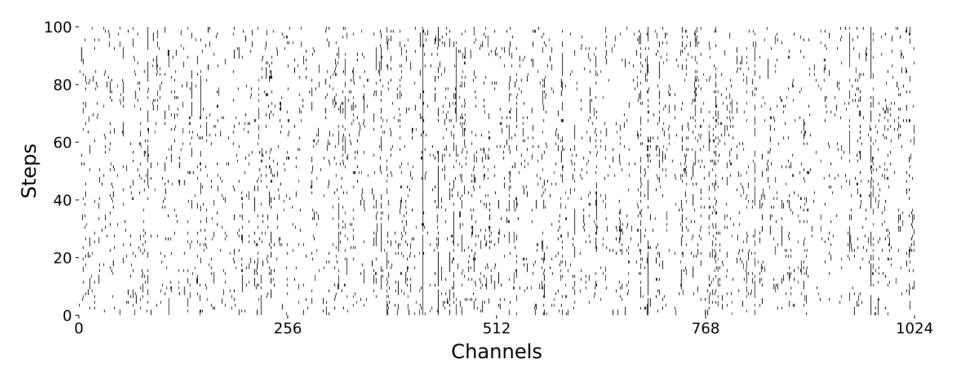


Decoding Step i + 1

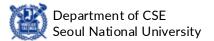


Decoding Step i + 2



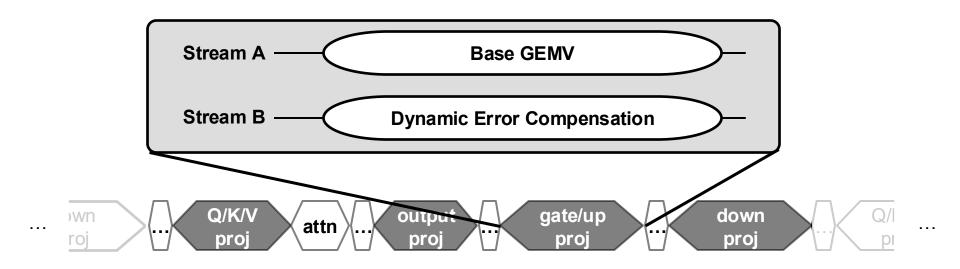


Distribution of activation outliers (top 5%) across 100 decoding steps

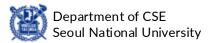


DecDEC: Decoding with Dynamic Error Compensation

Inference system for quantized LLMs that performs **Dec**oding with **D**ynamic **E**rror **C**ompenstation

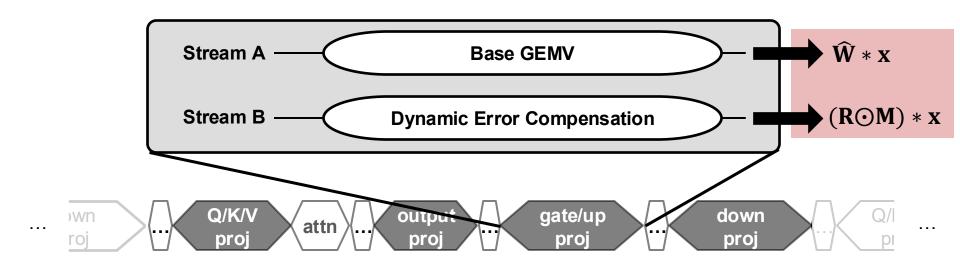


Augment each linear layer with dynamic error compensataion (DEC)

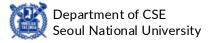


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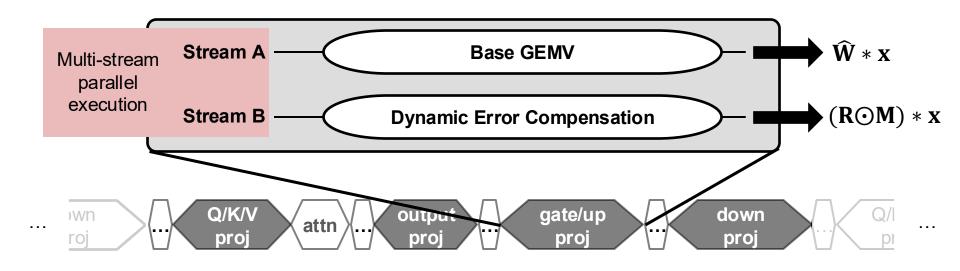


Augment each linear layer with **dynamic error compensataion (DEC)**

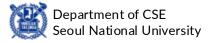


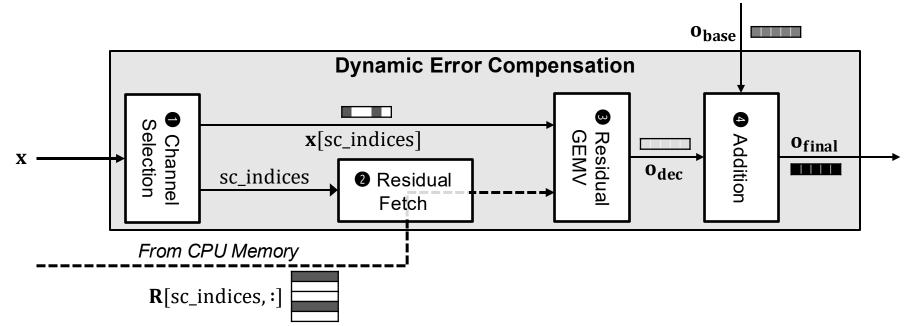
DecDEC: Decoding with Dynamic Error Compensation

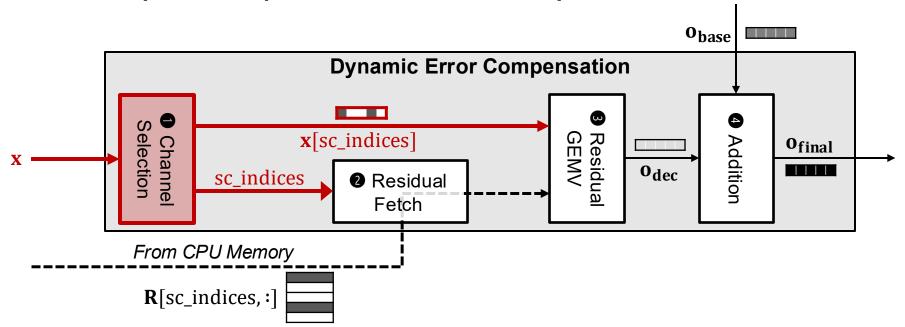
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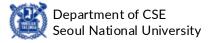
Augment each linear layer with **dynamic error compensataion (DEC)**

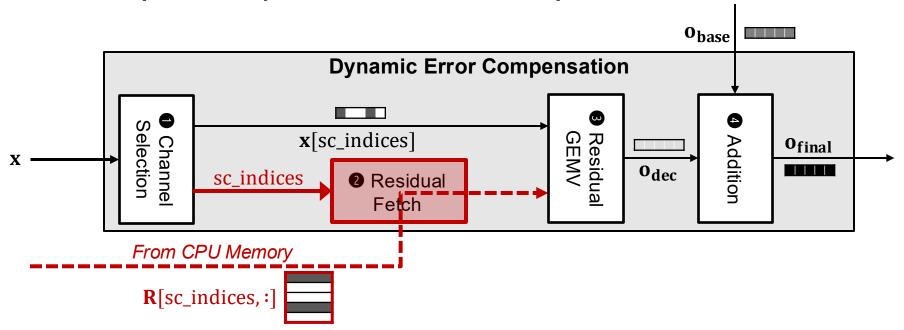




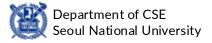


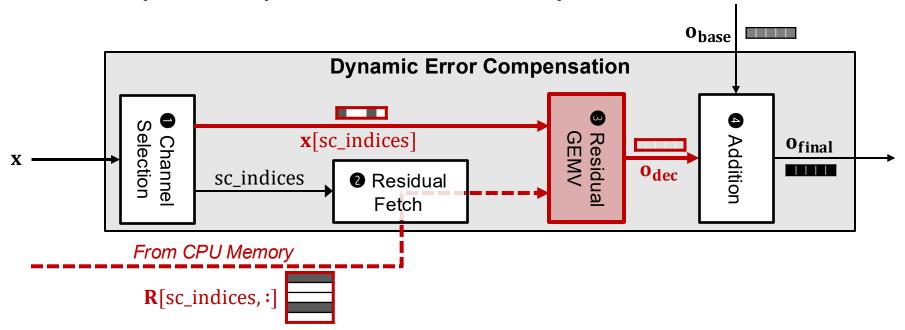
1 Perform Top-K on the input activation vector (x)



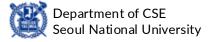


Fetch residuals for the selected channels from CPU (R[sc indices,:])

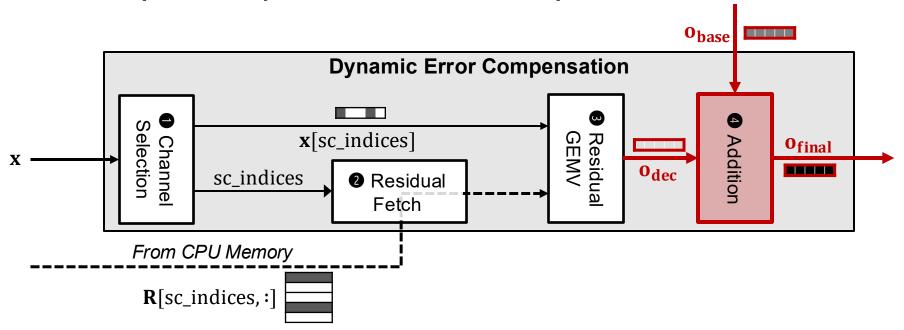




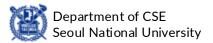
(3) Multiply the input activation by the selected residuals



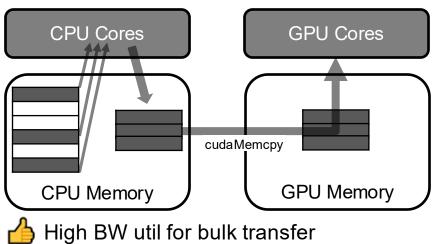
Four Steps of Dynamic Error Compensation

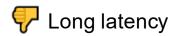


4 Add base GEMV result (o_{base}) & residual GEMV result (o_{dec})

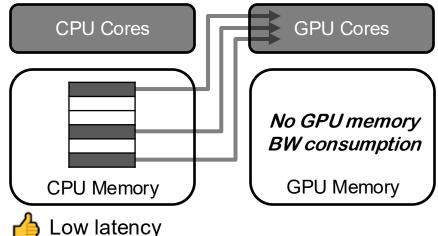


DMA-based Approach





Zero-Copy-based Approach





Fine-grained, cacheline-sized data access



GPU core consumption

Zero-Copy is the answer!

- * Need low-latency, fine-grained data access
- * GPU core consumption is OK, while BW contention is undesirable (Base GEMV is memory-bound)

CPU Memory Low latency

GPU core consumption

CPU Cores

Zero-Copy-based Approach

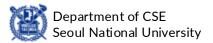
Fine-grained, cacheline-sized data access

GPU Cores

No GPU memory **BW** consumption

GPU Memory

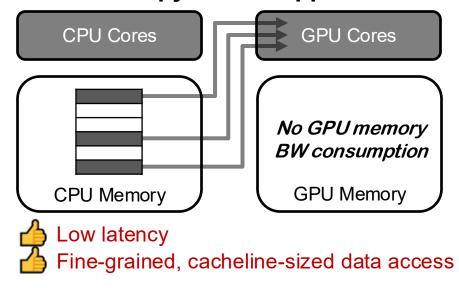




Zero-Copy is the answer!

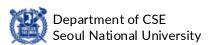
- * Need low-latency, fine-grained data access
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Zero-Copy-based Approach





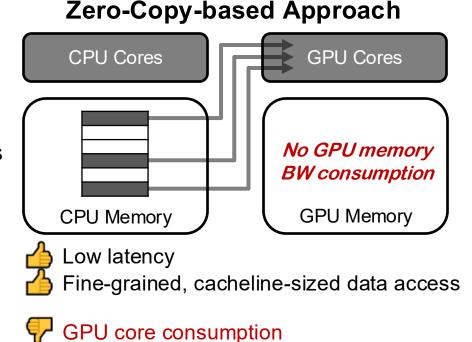
GPU core consumption

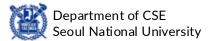


Zero-Copy is the answer!

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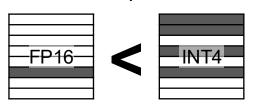






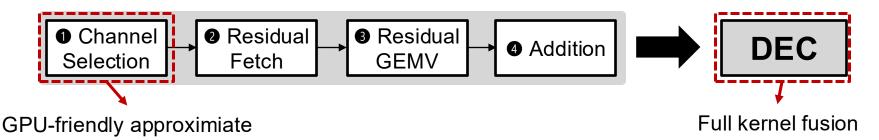
Other Optimizations

4-bit residual quantization



Introduces approximation errors, but enables fetching more channels

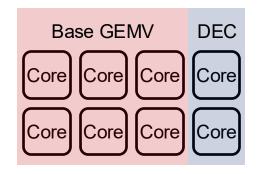
GPU kernel optimizations

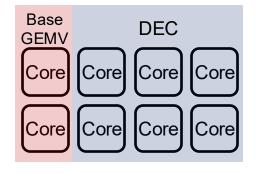


Top-K selection

DecDEC Parameter Tuner

- Two system parameters should be carefully tuned
 - *n_{th}*: # of thread blocks (≈ # of GPU cores) to allocate to DEC



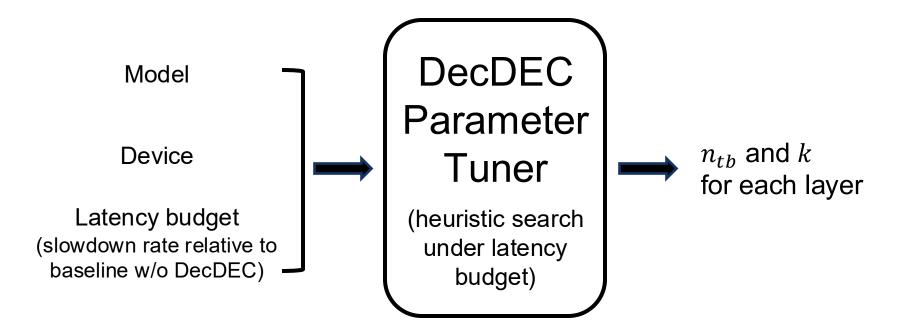


Too small n_{th} (i.e., 2) underutilizes PCIe BW

Too large n_{th} (i.e., 6) slows down the base GEMV

- **k**: # channels to fetch
 - → Larger is better, up to the point it incurs too high latency overhead

DecDEC Parameter Tuner



Key Result #1:

DEC is effectively overlapped with base GEMV using appropriate n_{th} and k

Key Result #2:

DecDEC significantly improves quality with limited latency overhead

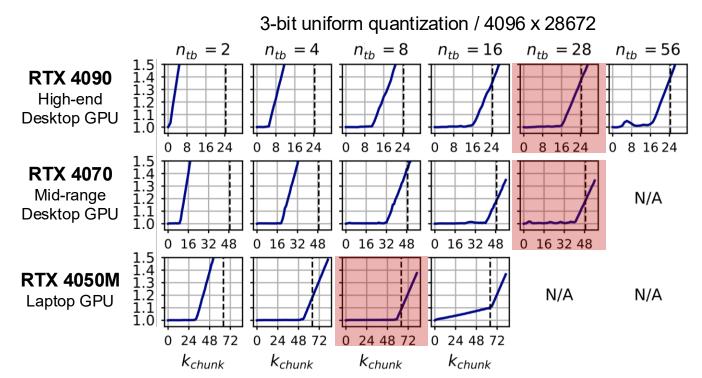
Key Result #1:

DEC is effectively overlapped with base GEMV using appropriate n_{th} and k

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DecDEC significantly improves quality with limited latency overhead

DecDEC Kernel Evaluation



With appropriate n_{th} , DecDEC incurs almost no overhead up to a certain value of k (k_{chunk} : k per 1024 channels)



Key Result #1:

DEC is effectively overlapped with base GEMV using appropriate n_{th} and k

Key Result #2:

DecDEC significantly improves quality with limited latency overhead

End-to-End Evaluation

Perplexity vs. Latency under 2.5%, 5%, 10%, and 20% target slowdown rate

