

Carl Qi

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Education

University of Texas at Austin <i>Ph.D. in Electrical & Computer Engineering</i>	August 2023 – Present GPA: 4.0
Carnegie Mellon University <i>M.S. in Machine Learning</i>	August 2021 – December 2022 GPA: 3.96
University of California, Berkeley <i>B.A. in Computer Science, B.A. in Applied Mathematics</i>	August 2017 – August 2021 GPA: 3.976 (Summa Cum Laude)

Industry Experience

Amazon Robotics <i>Applied Scientist Intern</i>	Sunnyvale, CA May 2025 – August 2025
• Fine-tuned large vision-language models (VLMs) to enhance robotic failure detection and reasoning • Designed ARMOR, a self-refining algorithm that enables VLMs to iteratively improve their predictions by generating detection outcomes and natural language reasoning conditioned on prior outputs • Achieved state-of-the-art performance with 30% improvement in failure detection rate and up to 100% gain in reasoning accuracy over baseline models; resulted in first-authored paper at ICLR 2026	
UC Berkeley Electrical Engineering and Computer Science (EECS) <i>Instructor CS188 – Intro to AI</i>	Berkeley, CA June 2021 – August 2021
• Gave 25 lectures on fundamental AI techniques such as reinforcement learning to 250+ students • Recruited and led 20 staff members to develop course materials: 2 exams, 5 projects and 10 homework	
Goldman Sachs <i>Quantitative Strategist Intern</i>	New York City, NY July 2020 – August 2020
• Undertook backend development in a digital storefront that delivers cross-asset access to global markets • Developed 2 production-level endpoints that allowed investors to assess risk profile in various scenarios • Integrated the endpoints with an open-source Python library that resulted in 100+ client visits per day	

Research Experience

MIDI Lab, UT Austin <i>Graduate Student Researcher</i>	Austin, Texas August 2023 – Present
• Work with Prof. Amy Zhang on improving generalization of reinforcement learning algorithms	
The Robotics Institute, Carnegie Mellon University <i>Graduate Student Researcher</i>	Pittsburgh, PA August 2021 – June 2023
• Worked with Prof. David Held on computer vision and machine learning for robotic manipulation • Conducted research on policy training and long horizon reasoning for deformable object manipulation • First authored multiple papers in major conferences and got media coverage in the Washington Post	
Berkeley Artificial Intelligence Research (BAIR) <i>Undergraduate Student Researcher</i>	Berkeley, CA April 2020 – April 2021
• Worked with Prof. Pieter Abbeel and Prof. Aditya Grover on robust imitation learning	

Selected Publications

- [1] Carl Qi, Xiaojie Wang, Silong Yong, Stephen Sheng, Huitan Mao, Sriram Srinivasan, Manikantan Nambi, Amy Zhang, and Yesh Dattatreya. “Self-Refining Vision Language Model for Robotic Failure Detection and Reasoning”. In: *Submitted to The Fourteenth International Conference on Learning Representations*. under review. 2026. url: <https://openreview.net/forum?id=jr9hGWQioP>.
- [2] Tal Daniel, Carl Qi, Dan Haramati, Amir Zadeh, Chuan Li, Aviv Tamar, Deepak Pathak, and David Held. “Latent Particle World Models: Self-supervised Object-centric Stochastic Dynamics Modeling”. In: *Submitted to The Fourteenth International Conference on Learning Representations*. under review. 2026. url: <https://openreview.net/forum?id=lTaPtGiUUC>.
- [3] Dan Haramati, Carl Qi, Tal Daniel, Amy Zhang, Aviv Tamar, and George Konidaris. “Hierarchical Entity-centric Reinforcement Learning with Factored Subgoal Diffusion”. In: *Submitted to The Fourteenth International Conference on Learning Representations*. under review. 2026. url: <https://openreview.net/forum?id=TimC6hxVHj>.
- [4] Carl Qi, Dan Haramati, Tal Daniel, Aviv Tamar, and Amy Zhang. “EC-Diffuser: Multi-Object Manipulation via Entity-Centric Behavior Generation”. In: *The Thirteenth International Conference on Learning Representations*. 2025. url: <https://openreview.net/forum?id=o3pjU5QCtv>.
- [5] Caleb Chuck, Fan Feng, Carl Qi, Chang Shi, Siddhant Agarwal, Amy Zhang, and Scott Niekum. “Null Counterfactual Factor Interactions for Goal-Conditioned Reinforcement Learning”. In: *The Thirteenth International Conference on Learning Representations*. 2025.
- [6] Caleb Chuck*, Carl Qi*, et al. “Robot Air Hockey: A Manipulation Testbed for Robot Learning with Reinforcement Learning”. In: *CoRR* (2024).
- [7] Carl Qi, Yilin Wu, Lifan Yu, Haoyue Liu, Bowen Jiang, Xingyu Lin, and David Held. “Learning Generalizable Tool-use Skills through Trajectory Generation”. In: *2024 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*. 2024, pages 2847–2854. doi: 10.1109/IROS58592.2024.10801653.
- [8] Carl Qi, Xingyu Lin, and David Held. “Learning Closed-Loop Dough Manipulation Using a Differentiable Reset Module”. In: *IEEE Robotics and Automation Letters* 7.4 (2022), pages 9857–9864. doi: 10.1109/LRA.2022.3191239.
- [9] Xingyu Lin*, Carl Qi*, Yunchu Zhang, Yunzhu Li, Zhiao Huang, Katerina Fragkiadaki, Chuang Gan, and David Held. “Planning with Spatial-Temporal Abstraction from Point Clouds for Deformable Object Manipulation”. In: *6th Annual Conference on Robot Learning*. 2022. url: <https://openreview.net/forum?id=tyxyBj2w4vw>.
- [10] Carl Qi, Pieter Abbeel, and Aditya Grover. “Imitating, fast and slow: Robust learning from demonstrations via decision-time planning”. In: *arXiv preprint arXiv:2204.08597* (2022).

Awards & Honors

Qualcomm Innovation Fellowship Finalist	
<i>Qualcomm</i>	2023
2nd Place Winner of East Coast Regional Datathon	
<i>Citadel Securities</i>	2021
2nd Place Winner in Cisco EN Hackathon	
<i>Cisco</i>	2019

2nd Place Winner in Sodahacks

University of California, Berkeley

2018

1st Prize in Beijing High School Mechanics Contest

Chinese Society of Physics

2015

Teaching

10-418/618: ML for Structured Data

TA

Carnegie Mellon University

Spring 2022

10-725: Convex Optimization

TA

Carnegie Mellon University

Fall 2021

CS188: Artificial Intelligence

Instructor

Univeristy of California, Berkeley

Summer 2021

CS188: Artificial Intelligence

TA

Univeristy of California, Berkeley

Spring 2021

CS188: Artificial Intelligence

TA

Univeristy of California, Berkeley

Fall 2020

CS188: Artificial Intelligence

TA

Univeristy of California, Berkeley

Spring 2020

CS188: Artificial Intelligence

TA

Univeristy of California, Berkeley

Fall 2019

Service

Reviewer

IROS '24, ICLR '25, '26, RSS '25, NeurIPS '25