# Carl Qi

Gates Dell Complex 2317 Speedway Austin, TX, 78712 Website: https://carl-qi.github.io

Email: carlq@utexas.edu

#### Education

University of Texas at Austin

Ph.D. in Electrical & Computer Engineering

Carnegie Mellon University

M.S. in Machine Learning

University of California, Berkeley

B.A. in Computer Science, B.A. in Applied Mathematics

August 2023 – Present

GPA: 4.0

August 2021 - December 2022

GPA: 3.96

August 2017 – August 2021

GPA: 3.976 (Summa Cum Laude)

## Research Experience

### The Robotics Institute, Carnegie Mellon University

Pittsburgh, PA

Graduate Student Researcher

August 2021 - April 2022

- Work with Prof. David Held on computer vision and machine learning for robotic manipulation
- Conduct research on policy training and long horizon reasoning for deformable object manipulation
- First authored multiple papers in major conferences and got media coverage in the Washington Post

# Berkeley Artificial Intelligence Research (BAIR)

Berkeley, CA

Undergraduate Student Researcher

April 2020 – April 2021

- Worked with Prof. Pieter Abbeel and Prof. Aditya Grover on robust imitation learning
- Designed and implemented all experiments that improved existing SOTA performance by 35%

# **Industry Experience**

# UC Berkeley Electrical Engineering and Computer Science (EECS)

Berkeley, CA

Instructor | CS188 - Intro to AI

June 2021 – August 2021

- Gave 25 lectures on fundamental AI techniques such as reinforcement learning to 250+ students
- Recruited and led 20 staff members to develop course materials: 2 exams, 5 projects and 10 homework
- Invented policies that facilitated remote learning to accommodate students from 6 different time zones

#### Goldman Sachs

New York City, NY

Quantitative Strategist Intern

July 2020 - August 2020

- Undertook backend development in a digital storefront that delivers cross-asset access to global markets
- Developed 2 production-level endpoints that allowed investors to assess risk profile in various scenarios
- Integrated the endpoints with an open-source Python library that resulted in 100+ client visits per day

### **Publications & Preprints**

- [1] Carl Qi, Sarthak Shetty, Xingyu Lin, and David Held. "Learning Generalizable Tool-use Skills through Trajectory Generation". In: *arXiv preprint arXiv:2310.00156* (2023).
- [2] Xingyu Lin\*, Carl Qi\*, Yunchu Zhang, Yunzhu Li, Zhiao Huang, Katerina Fragkiadaki, Chuang Gan, and David Held. "Planning with Spatial-Temporal Abstraction from Point Clouds for Deformable Object Manipulation". In: 6th Annual Conference on Robot Learning. 2022. URL: https://openreview.net/forum?id=tyxyBi2w4vw.
- [3] Carl Qi, Pieter Abbeel, and Aditya Grover. "Imitating, Fast and Slow: Robust learning from demonstrations via decision-time planning". In: arXiv preprint arXiv:2204.03597 (2022).

[4] Carl Qi, Xingyu Lin, and David Held. "Learning Closed-Loop Dough Manipulation Using a Differentiable Reset Module". In: *IEEE Robotics and Automation Letters* 7.4 (2022), pages 9857–9864. DOI: 10.1109/LRA.2022.3191239.

# Awards & Honors

TA

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2nd Place Winner of East Coast Regional Datathon Citadel Securities	2021
2nd Place Winner in Cisco EN Hackathon	
Cisco	2019
2nd Place Winner in Sodahacks University of California, Berkeley	2018
1st Prize in Beijing High School Mechanics Contest	
Chinese Society of Physics	2015
Teaching	
10-418/618: ML for Structured Data	Carnegie Mellon University
TA	Spring 2022
10-725: Convex Optimization	Carnegie Mellon University
TA	Fall 2021
CS188: Artificial Intelligence	Univeristy of California, Berkeley
Instructor	Summer 2021
CS188: Artificial Intelligence	Univeristy of California, Berkeley
TA	Spring 2021
CS188: Artificial Intelligence	Univeristy of California, Berkeley
TA	Fall 2020
CS188: Artificial Intelligence	Univeristy of California, Berkeley
TA	Spring 2020
CS188: Artificial Intelligence	Univeristy of California, Berkeley

Fall 2019