Carl Qi

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Education

University of Texas at Austin

Ph.D. in Electrical & Computer Engineering

Carnegie Mellon University

M.S. in Machine Learning

University of California, Berkeley

B.A. in Computer Science, B.A. in Applied Mathematics

August 2023 - Present

GPA: 4.0

August 2021 – December 2022

GPA: 3.96

August 2017 – August 2021

GPA: 3.976 (Summa Cum Laude)

Research Experience

MIDI Lab, UT Austin

Austin, Texas

Graduate Student Researcher

August 2023 - Present

· Work with Prof. Amy Zhang on improving generalization of reinforcement learning algorithms

The Robotics Institute, Carnegie Mellon University

Pittsburgh, PA

Graduate Student Researcher

August 2021 – June 2023

- · Worked with Prof. David Held on computer vision and machine learning for robotic manipulation
- Conducted research on policy training and long horizon reasoning for deformable object manipulation
- First authored multiple papers in major conferences and got media coverage in the Washington Post

Berkeley Artificial Intelligence Research (BAIR)

Berkeley, CA

Undergraduate Student Researcher

April 2020 – April 2021

• Worked with Prof. Pieter Abbeel and Prof. Aditya Grover on robust imitation learning

Industry Experience

Amazon Robotics

Sunnyvale, CA

Applied Scientist Intern

May 2025 - August 2025

- Fine-tuned vision-language foundation models to enhance robotic failure detection and reasoning
- Designed an algorithm enabling VLMs to iteratively refine responses; led to a first-authored paper

UC Berkeley Electrical Engineering and Computer Science (EECS)

Berkeley, CA

Instructor | CS188 - Intro to AI

June 2021 - August 2021

- Gave 25 lectures on fundamental AI techniques such as reinforcement learning to 250+ students
- Recruited and led 20 staff members to develop course materials: 2 exams, 5 projects and 10 homework
- Invented policies that facilitated remote learning to accommodate students from 6 different time zones

Goldman Sachs

New York City, NY

Quantitative Strategist Intern

July 2020 - August 2020

- · Undertook backend development in a digital storefront that delivers cross-asset access to global markets
- Developed 2 production-level endpoints that allowed investors to assess risk profile in various scenarios
- Integrated the endpoints with an open-source Python library that resulted in 100+ client visits per day

Selected Publications

- [1] Caleb Chuck, Fan Feng, Carl Qi, Chang Shi, Siddhant Agarwal, Amy Zhang, and Scott Niekum. "Null Counterfactual Factor Interactions for Goal-Conditioned Reinforcement Learning". In: *The Thirteenth International Conference on Learning Representations*. 2025.
- [2] Carl Qi, Dan Haramarti, Tal Daniel, Aviv Tamar, and Amy Zhang. "EC-Diffuser: Multi-Object Manipulation via Entity-Centric Behavior Generation". In: *The Thirteenth International Conference on Learning Representations*. 2025. URL: https://openreview.net/forum?id=o3pJU5QCtv.
- [3] Caleb Chuck*, Carl Qi*, et al. "Robot Air Hockey: A Manipulation Testbed for Robot Learning with Reinforcement Learning". In: *CoRR* (2024).
- [4] Carl Qi, Yilin Wu, Lifan Yu, Haoyue Liu, Bowen Jiang, Xingyu Lin, and David Held. "Learning Generalizable Tool-use Skills through Trajectory Generation". In: 2024 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS). 2024, pages 2847–2854. DOI: 10.1109/IROS58592.2024.10801653.
- [5] Xingyu Lin*, Carl Qi*, Yunchu Zhang, Yunzhu Li, Zhiao Huang, Katerina Fragkiadaki, Chuang Gan, and David Held. "Planning with Spatial-Temporal Abstraction from Point Clouds for Deformable Object Manipulation". In: 6th Annual Conference on Robot Learning. 2022. URL: https://openreview.net/forum?id=tyxyBj2w4vw.
- [6] Carl Qi, Pieter Abbeel, and Aditya Grover. "Imitating, fast and slow: Robust learning from demonstrations via decision-time planning". In: *arXiv preprint arXiv:2204.03597* (2022).
- [7] Carl Qi, Xingyu Lin, and David Held. "Learning Closed-Loop Dough Manipulation Using a Differentiable Reset Module". In: *IEEE Robotics and Automation Letters* 7.4 (2022), pages 9857–9864. DOI: 10.1109/LRA.2022.3191239.

Awards & Honors

Qualcomm Innovation Fellowship Finalist	
Qualcomm	2023
2nd Place Winner of East Coast Regional Datathon	
Citadel Securities	2021
2nd Place Winner in Cisco EN Hackathon	
Cisco	2019
2nd Place Winner in Sodahacks	
University of California, Berkeley	2018
1st Prize in Beijing High School Mechanics Contest	
Chinese Society of Physics	2015

Teaching

10-418/618: ML for Structured Data	Carnegie Mellon University
TA	Spring 2022
10-725: Convex Optimization	Carnegie Mellon University
TA	Fall 2021
CS188: Artificial Intelligence	Univeristy of California, Berkeley
Instructor	Summer 2021
CS188: Artificial Intelligence	Univeristy of California, Berkeley
TA	Spring 2021

CS188: Artificial IntelligenceUniveristy of California, BerkeleyTAFall 2020CS188: Artificial IntelligenceUniveristy of California, BerkeleyTASpring 2020CS188: Artificial IntelligenceUniveristy of California, BerkeleyTAFall 2019

Service

Reviewer

IROS 2024, ICLR 2025, RSS 2025, NeurIPS 2025