

# A filtered Boris algorithm for charged-particle dynamics in a strong magnetic field

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# Outline

## 1. Introduction

## 2. Presentation of algorithms

- Standard Boris algorithm

- Filtered Boris algorithm

- Two-point filtered Boris algorithm

## 3. Results

## 4. Conclusion

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# Introduction

Propose and analyse a numerical integrator for the equations of motion of a charged particle

$$\ddot{x}(t) = \dot{x}(t) \times B(x(t), t) + E(x(t), t), \quad x(t), B(x, t), E(x, t) \in \mathbb{R}^3 \quad (1)$$

# Introduction

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in a strong inhomogeneous magnetic field

$$B(x, t) = \frac{1}{\varepsilon} B_0(\varepsilon x) + B_1(x, t) \quad \text{for } 0 < \varepsilon \ll 1 \quad (2)$$

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# Standard Boris algorithm

De facto algorithm for charged particles in a magnetic field.

$$(x^n, v^{n-1/2}) \mapsto (x^{n+1}, v^{n+1/2})$$

$$v_+^{n-1/2} = v_+^{n-1/2} + \frac{h}{2} E(x^n, t^n) \quad (3)$$

$$v_-^{n+1/2} - v_+^{n-1/2} = \frac{h}{2} \left( v_-^{n+1/2} + v_+^{n-1/2} \right) \times B(x^n, t^n) \quad (4)$$

$$v_-^{n+1/2} = v_-^{n+1/2} + \frac{h}{2} E(x^n, t^n) \quad (5)$$

$$x^{n+1} = x^n + h v^{n+1/2} \quad (6)$$

# Guiding center approximation

$$x_{\odot}^n = x^n + \frac{v^n \times B(x^n, t^n)}{|B(x^n, t^n)|^2} \quad \text{guiding center approximation}$$

$$\bar{x}^n = \theta^n x^n + (1 - \theta^n) x_{\odot}^n \quad \text{point on the straight line connecting } x \text{ and } x_{\odot}$$

$$\theta^n = \theta(h|B(x^n, t^n)|)$$

$$\theta(\xi) = \frac{1}{\text{sinc}(\xi/2)^2} \quad \text{with} \quad \text{sinc}(\xi) = \frac{\sin(\xi)}{\xi}$$



# Notation

$$B^n = B(x^n, t^n)$$

$$\bar{B}^n = B(\bar{x}^n, t^n)$$

$$E^n = E(x^n, t^n)$$

We will also express  $v \times B = -\hat{B}v$ , where  $B = (b_1, b_2, b_3)$ , and so

$$\hat{B} = \begin{pmatrix} 0 & -b_3 & b_2 \\ b_3 & 0 & -b_1 \\ -b_2 & b_1 & 0 \end{pmatrix} \quad (7)$$

$$(x^n, v^{n-1/2}) \mapsto (x^{n+1}, v^{n+1/2})$$

$$v^{n+1/2} = v^{n-1/2} + \frac{h}{2} \Psi(h\hat{B}^n) E^n \quad (8)$$

$$v_-^{n+1/2} = \exp(-h\hat{B}^n) v^{n-1/2} \quad (9)$$

$$v_-^{n+1/2} = v_-^{n+1/2} + \frac{h}{2} \Psi(h\hat{B}^n) E^n \quad (10)$$

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# Filtered Boris

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where  $\Psi(\zeta) = \text{tanch}(\zeta/2)$  with  $\text{tanch}(\zeta) = \tanh(\zeta)/\zeta$ .

# Filtered Boris

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$\Psi(h\hat{B})$  can therefore be expressed as:

$$\Psi(h\hat{B}) = I + \frac{1 - \text{tanc}(h|B|/2)}{|B|^2} \hat{B}^2 \quad (12)$$

# Filtered Boris

Since we have

$$v_-^{n+1/2} = \exp(-h\hat{B}^n)v^{n-1/2}, \quad (9)$$

and

$$\begin{aligned}\bar{x}^n &= \theta^n x^n + (1 - \theta^n) x_\odot^n, \\ x_\odot^n &= x^n + \frac{v^n \times B^n}{|B^n|^2},\end{aligned}$$

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we need to compute  $v^n$  with the following approximation,

$$v^n = \Phi_1(hB^n) \frac{v_-^{n+1} - v_+^{n-1}}{2} - h\Gamma(hB^n)E^n, \quad (13)$$

where  $\Phi_1(\zeta) = \frac{1}{\sinh(\zeta)}$  with  $\sinh(\zeta) = \frac{\sinh(\zeta)}{\zeta}$ , and  $\Gamma(\zeta) = \Phi_1(\zeta) - 1$ .

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We therefore need to solve the equation with a fixed-point iteration to get  $v^n$ .



# Variants

When  $\theta(x, t) = 1 \rightarrow \bar{x}^n = x^n$ , and so the algorithm is explicit, we will call it **Exp-A**

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When  $\theta(x, t) = \frac{1}{\text{sinc}(h|B(x, t)|/2)^2} \rightarrow$  algorithm is implicit, we will call it **Imp-A**

# Two-Point Filtered Boris Algorithm

$$(x^n, v^{n-1/2}) \mapsto (x^{n+1}, v^{n+1/2})$$

$$v_+^{n-1/2} = v^{n-1/2} + \frac{h}{2} \Psi(h\hat{B}^n) E^n \quad (14)$$

$$\Phi_2(h\hat{B}_{\odot}^n)(v_-^{n+1/2} - v_+^{n-1/2}) = \frac{h}{2} \Phi_1(h\hat{B}^n)(v_-^{n+1/2} + v_+^{n-1/2}) \times B^n \quad (15)$$

$$v_-^{n+1/2} = v_-^{n-1/2} + \frac{h}{2} \Psi(h\hat{B}^n) E^n \quad (16)$$

$$x^{n+1} = x^n + h v^{n+1/2} \quad (17)$$

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where  $\Psi(\zeta) = \text{tanch}(\zeta/2)$  and  $\Phi_1(\zeta) = \frac{1}{\text{sinch}(\zeta)}$  and  $\Phi_2(\zeta) = \frac{1}{\text{sinch}(\zeta/2)^2}$ .

# Two-Point Filtered Boris Algorithm

This method is also implicit.

The fixed-point iteration for  $x_{\odot}^n$  requires:

- the evaluation of matrix functions by the Rodriguez formula
- and the solution of a linear system with the 3x3 matrix  $\Phi_2(h\hat{B}_{\odot}^n) + \frac{1}{2}h\hat{B}^n\Phi_1(h\hat{B}^n)$ .

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# Numerical experiment

$$\begin{aligned} B(x, t) &= \nabla \times \frac{1}{\epsilon} (0 \ x_1 \ 0) + \nabla \times (0 \ x_1 x_3 \ 0) \\ &= \frac{1}{\epsilon} (0 \ 0 \ 1) + (-x_1 \ 0 \ x_3) \end{aligned}$$

$$E(x, t) = -\nabla_x U(x)$$

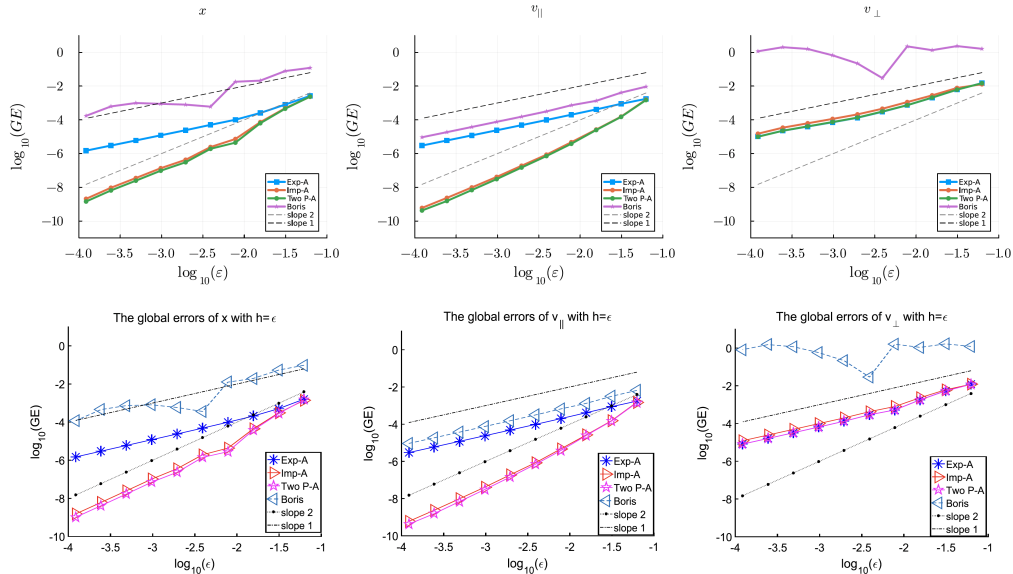
$$U(x) = \frac{1}{\sqrt{x_1^2 + x_2^2}}$$

Initial conditions:

$$x(0) = \left( \frac{1}{3}, \frac{1}{4}, \frac{1}{2} \right)^\top$$

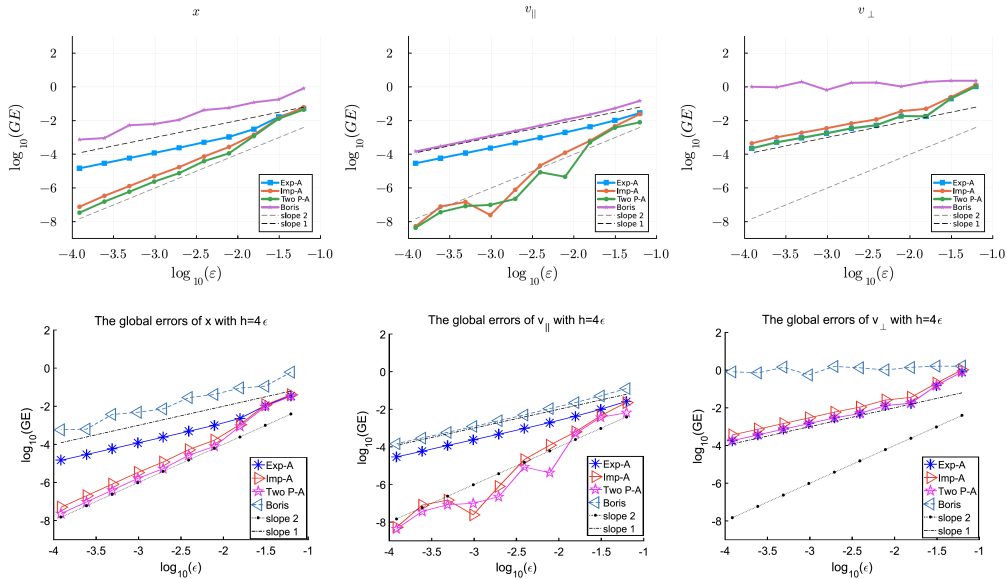
$$v(0) = \left( \frac{2}{5}, \frac{2}{3}, 1 \right)^\top$$

$$0 \leq t \leq 1$$

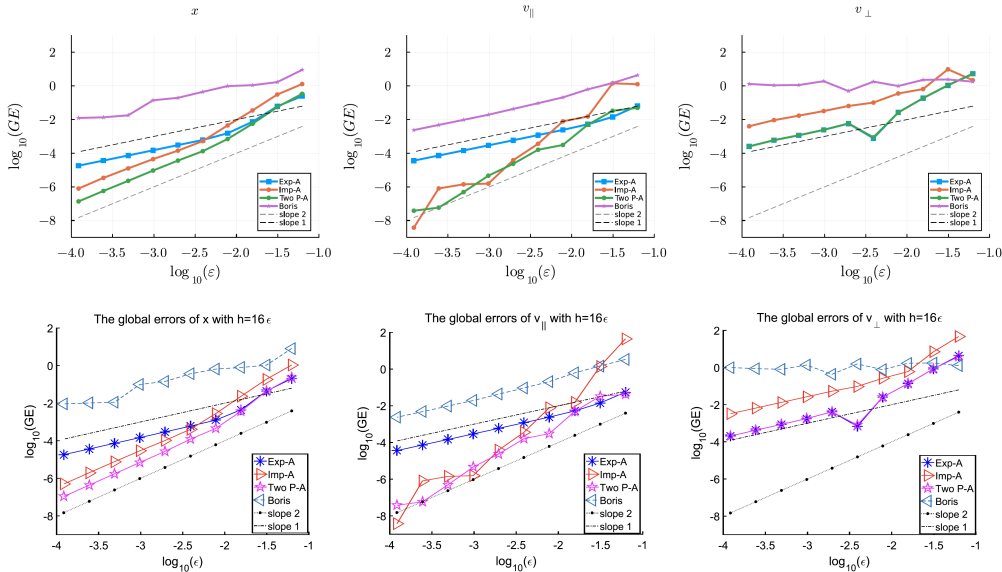


**Figure:** The logarithm of the global error at  $t=1$  against the logarithm of  $\epsilon$  for  $h = 1\epsilon$

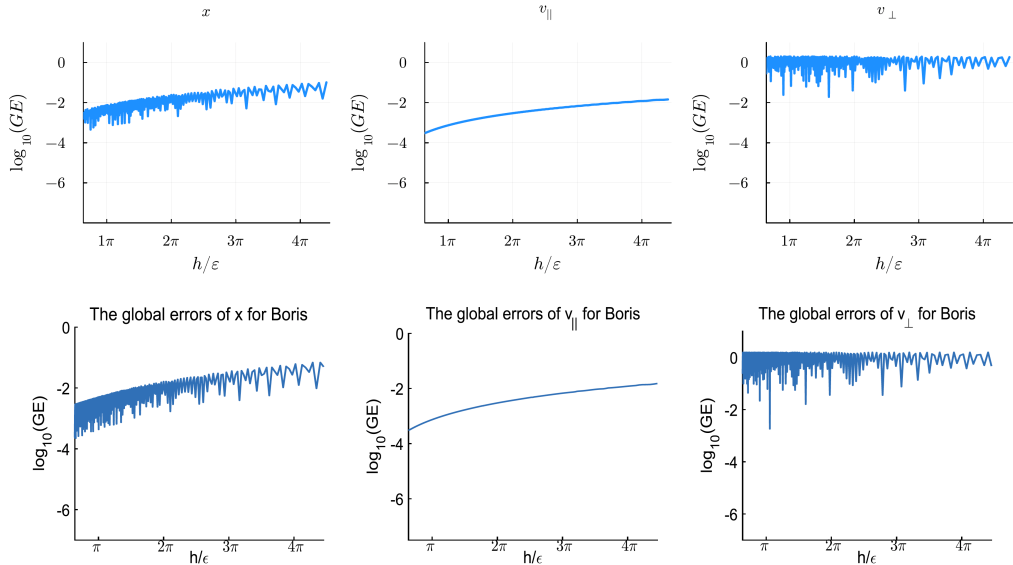




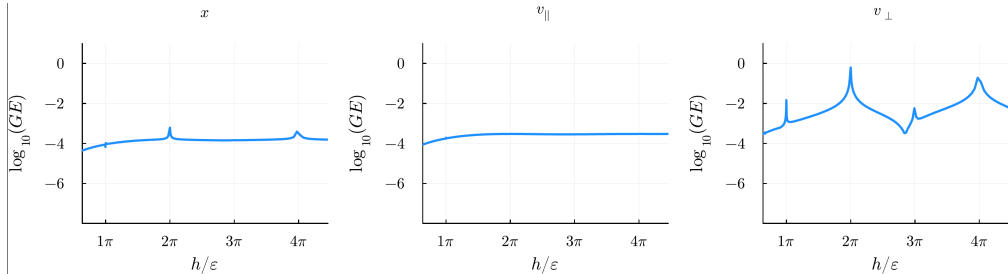
**Figure:** The logarithm of the global error at  $t=1$  against the logarithm of  $\epsilon$  for  $h = 4\epsilon$



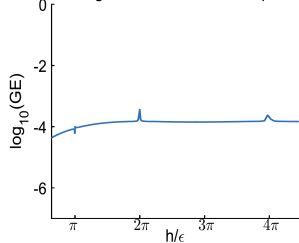
**Figure:** The logarithm of the global error at  $t=1$  against the logarithm of  $\epsilon$  for  $h = 16\epsilon$



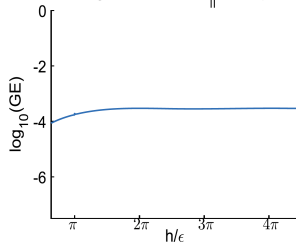
**Figure:** The logarithm of the global error at  $t = 1$  against  $h/\epsilon$  for  $\epsilon = (1/2)^{10}$  and  $h = 1/k$ ,  $k = 60, 61, \dots, 600$



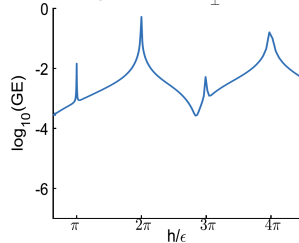
The global errors of  $x$  for Exp-A



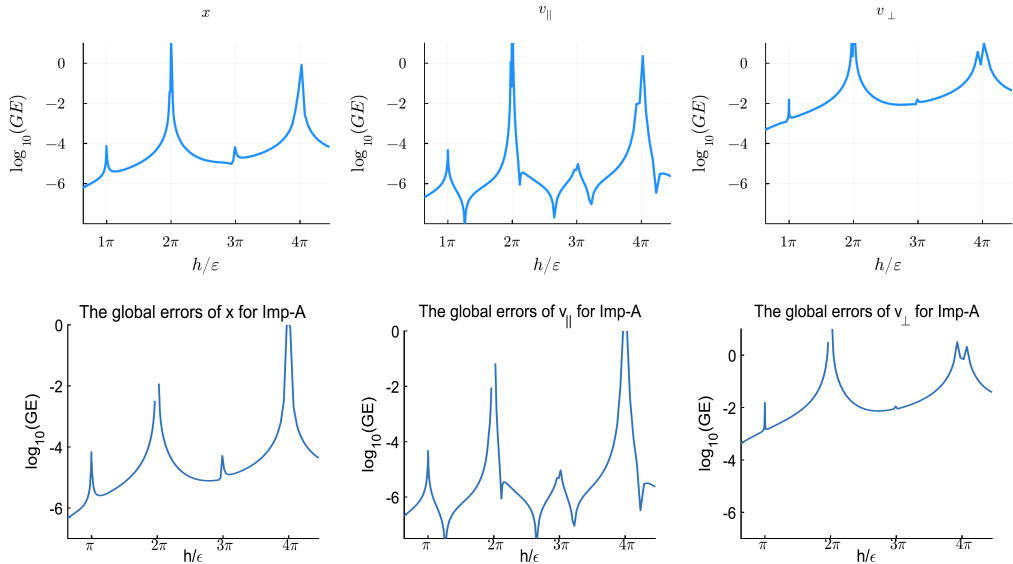
The global errors of  $v_{\parallel}$  for Exp-A



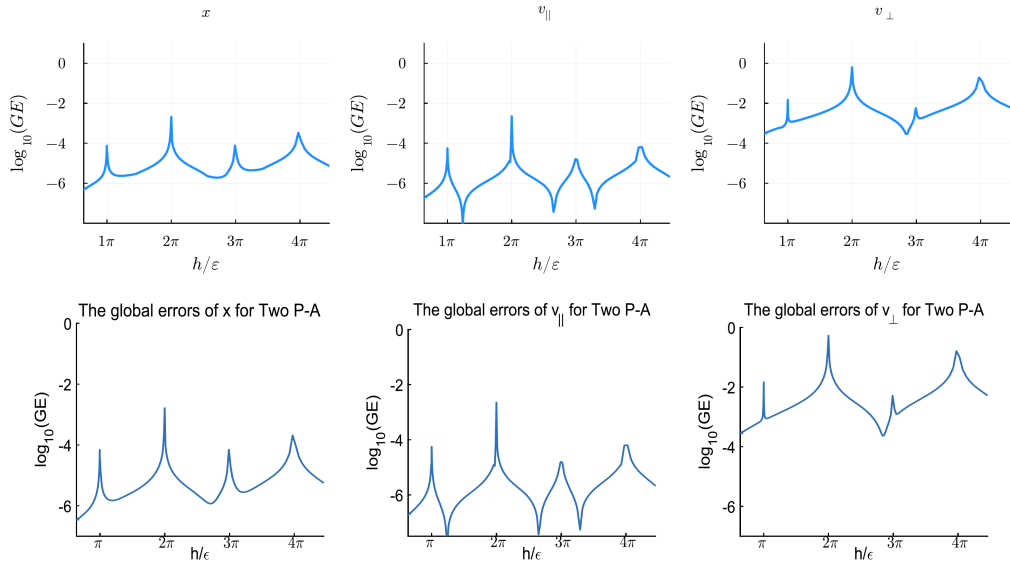
The global errors of  $v_{\perp}$  for Exp-A



**Figure:** The logarithm of the global error at  $t = 1$  against  $h/\epsilon$  for  $\epsilon = (1/2)^{10}$  and  $h = 1/k$ ,  $k = 60, 61, \dots, 600$



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# Challenges

- Reference solution of the ODE was not stated, solved it using RK ode45 equivalent in Julia with appropriate tolerance.
- Most standard libraries/ programming languages (Julia, Python, Matlab but not Mathematica!) implement  $\text{sinc}(\zeta)$  as  $\sin(\pi\zeta)/(\pi\zeta)$  which gave incorrect results since the authors used  $\sin(\zeta)/\zeta$ .
- Derivation of the efficient computation of filter functions using a Rodriguez type formula was included in the Appendix of the paper but does not include intermediate steps, and not much literature is found regarding this.
- This and the miscalculation of  $\text{sinc}$  lead me to believe that the derivation of the matrix filter functions using Rodriguez like formula was incorrect.
- Which in turn lead me to try other computation methods for the matrix functions using matrix identities which yielded correct results.
- However, with one concrete example, the derivation of the rest of the filter functions using the Rodriguez like formula is straightforward and I was able to verify the results and derive the not explicitly stated filter functions.

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# Conclusion

- It is observed that all three filtered Boris methods improve considerably over the standard Boris method, and the optimally filtered methods Imp-A and Two P-A show second order, whereas method Exp-A only shows first order.
- Methods Imp-A and Two P-A behave very similar away from stepsize resonances, but method Two P-A appears more robust near stepsize resonances.

Thank you for your attention!

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