

## Parameter Study

- 1. Set up the model.
- 2. Validate the case study.
- 3. Gather parameter study data.
- 4. Share results and analysis.

# Systems of Equations: Physics

Position: 
$$r(t)$$
 for  $r(t) = x_0$ 

Velocity: 
$$\frac{dr}{dt} = v(t)$$
 for  $v(t) = v_0$ 

Acceleration: 
$$\frac{d^2r}{dt^2} = \frac{dv}{dt} = a(t)$$

General Euler Equation: 
$$y_{i+1} = y_i + F(x_i, y_i)h$$

$$\downarrow \qquad \qquad \downarrow \qquad \qquad \downarrow$$
Position Euler Equation:  $r_1 = r_0 + v(t) \times h$ 

# Case Study: Lunar Lander

#### Diagram:



r=1,793,000 m : Altitude v=-410.28 m/s : Velocity

T=0 m/s<sup>2</sup>: Rocket Deceleration

t<sub>o</sub>=0 s : Initial Time

 $r_0$ =1,781,870 m: Initial Altitude  $v_0$ =-450 m/s : Initial Velocity T=4 m/s<sup>2</sup> : Rocket Deceleration

R=1,740,000 m: Lunar Surface

r=0 m: To Lunar Core

#### The Differential Equation:

$$F = ma = \frac{GMm}{r^2} \qquad a = \frac{GM}{r^2}$$

$$a(t) = T - \frac{GM}{r^2}$$

#### Note:

- 1. The lander's altitude [r] is measured from the center of the moon.
- 2. To calculate initial conditions
  - 1. Use a chain rule substitution.
  - 2. Integrate using separation of variables.
  - 3. Evaluate at T=0 and T=4.
  - 4. Set the equations equal and solve.

### System of Equations: Lunar Lander

Altitude: 
$$r = x(t)$$
 for  $x(0) = 1,781,870 m$ 

Velocity: 
$$\frac{dr_1}{dt} = v(t) \text{ for } v(0) = -450 \text{ m/s}$$

Acceleration: 
$$\frac{dr_2}{dt} = T - \frac{GM}{x^2}$$

General Euler Equation: 
$$y_{i+1} = y_i + F(x_i, y_i)h$$

Position Euler Equation:  $y_{i+1} = y_i + F(x_i, y_i)h$ 

 $\dot{r}_1 = 1,781,870 + (-450)h$ Position Euler Equation:

# Case Study Values

- Constants
  - Deceleration from thrust:  $T = 4 \text{ m/s}^2$
  - Gravitational constant :  $G = 6.6726 \times 10^{-11} \, \text{N*m}^2/\text{kg}^2$
  - Lunar mass:  $M = 7.35 \times 10^{22} \text{ kg}$
  - Lunar radius: R = 1,740,000 m
- □ Inputs
  - Initial time value:  $x_0 = 0$  s
  - Initial altitude value:  $y_0[0] = 1,781,870 \text{ m}$
  - Initial velocity value:  $y_0[1] = -450 \text{ m/s}$
  - $\blacksquare$  Upper limit of integration:  $x_n = 200 \text{ s}$
  - Number of steps: n = 200
- Calculations
  - Step size: h = 1 s

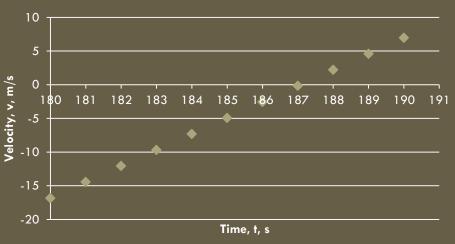
# Case Study Results

Step		Time	Case Study Altitude	Simulation Altitude	Case Study Velocity	Simulation Velocity
	180	180	1740059	1740059	-16.83	-16.83
	181	181	1740044	1740043	-14.45	-14.45
	182	182	1740030	1740030	-12.07	-12.07
	183	183	1740019	1740019	-9.69	-9.69
	184	184	1740011	1740011	-7.31	<i>-7.</i> 31
	185	185	1740005	1740005	-4.93	-4.93
	186	186	1740001	1740001	-2.55	-2.55
	187	187	1740000	1740000	-0.17	-0.17
	188	188	1740001	1740001	2.21	2.21
	189	189	1740004	1740004	4.59	4.59
	190	190	1740010	1740010	6.97	6.97

#### Altitude Vs. Time

#### 180 181 182 183 184 185 186 187 188 189 190 191 Time, t, s

#### Velocity Vs. Time



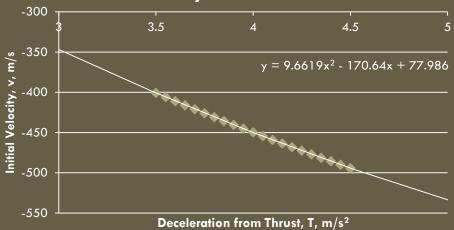
## Parameter Study

- □ Fixed retro-rocket ignition altitude
- □ Independent variable:
  - Acceleration from Thrust
  - Domain 3.5≤T≤4.5
  - Steps size: 0.05
- □ Dependent variables:
  - Landing Time
  - Starting velocity at fixed ignition point
  - Tolerances:  $r = \pm 5m$  and  $v = \pm 1m/s$

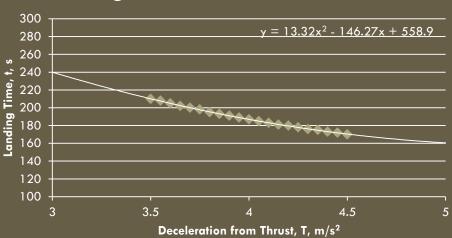
# Landing Solutions

Thrust (T)	Time (t)	Start Velocity (v <sub>0</sub> )
3.5	210	-400.8
3.55	208	-406
3.6	205	-411.12
3.65	202	-416.18
3.7	200	-421.18
3.75	198	-426.1
3.8	195	-431
3.85	193	-435.8
3.9	191	-440.6
3.95	189	-445.3
4	187	-450
4.05	185	-454.6
4.1	183	-459.2
4.15	181	-463.72
4.2	180	-468.26
4.25	178	-472.66
4.3	176	-477.1
4.35	175	-481.44
4.4	173	-485.8
4.45	172	-490.1
4.5	170	-494.31

#### Initial Velocity Vs. Decel. from Thrust



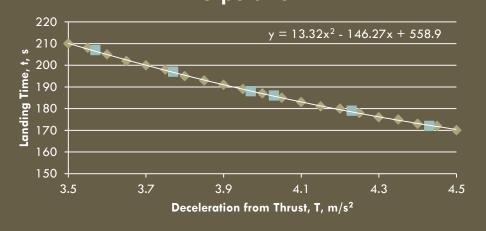
#### Landing Time Vs. Decel. from Thrust



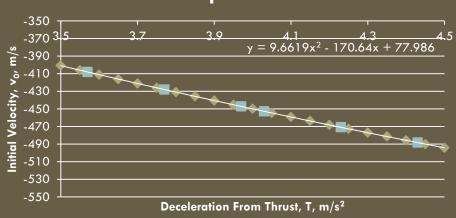
### Interpolation

Thrust	Estimated Time	Estimated Velocity	Numerical Time	Numerical Velocity	% Diff. Time	% Diff. Velocity
3.57	206.478168	-408.0588507	207	-408.05	0.25%	0.00%
3.77	196.777928	-428.0031815	197	-428.08	0.11%	0.02%
3.97	188.143288	-447.1745603	188	-447.22	0.08%	0.01%
4.03	185.760688	-452.7752483	186	-452.76	0.13%	0.00%
4.23	178.511328	-470.9417895	179	-470.89	0.27%	0.01%
4.43	172.327568	-488.3353787	172	-488.35	0.19%	0.00%

### Landing Time Vs. Decel. from Thrust Interpolation



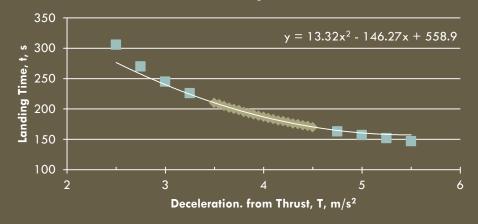
### Initial Velocity Vs. Decel. from Thrust Interpolation



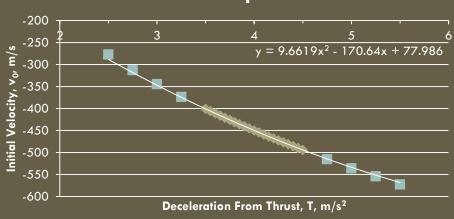
## Extrapolation

Thrust	<b>Estimated Time</b>	Estimated Velocity	Numerical Time	Numerical Velocity	% Difference Time	% Difference Velocity
5.5	157.35	-568.26	147	-572.78	7.04%	0.79%
5.25	158.12	-551.57	152	-554.2	4.03%	0.47%
5	160.55	-533.67	1 <i>57</i>	-535.98	2.26%	0.43%
4.75	164.65	-514.56	163	-515.05	1.01%	0.10%
3.25	224.22	-374.54	226	-373.78	0.79%	0.20%
3	239.97	-346.98	245	-344.63	2.05%	0.68%
2.75	257.39	-318.21	270	-312.78	4.67%	1.74%
2.5	276.48	-288.23	306	-277.3	9.65%	3.94%

### Landing Time Vs. Deceleration from Thrust Extrapolation



#### Initial Velocity Vs. Deceleration from Thrust Extrapolation



## Summary

- □ The quadratic curve is reliable for interpolation and close extrapolations.
- Changes to best-fit curve
  - Interpolation shows no change.
  - A cubic best-fit curve increases accuracy for extrapolation within short increments of the data set.
  - Higher order polynomials decrease the reliability of extrapolations.
  - Power curve fit improves extrapolations for Landing Time vs. Deceleration from Thrust.
    - $t = 600.14x^{-0.84}$
  - Logarithmic curve fit improves extrapolations for Initial Velocity vs. Deceleration from Thrust.
    - $v = -372 \ln(x) + 75.565$