University of BRISTOL

Overview of Computer Architecture

Operating Systems

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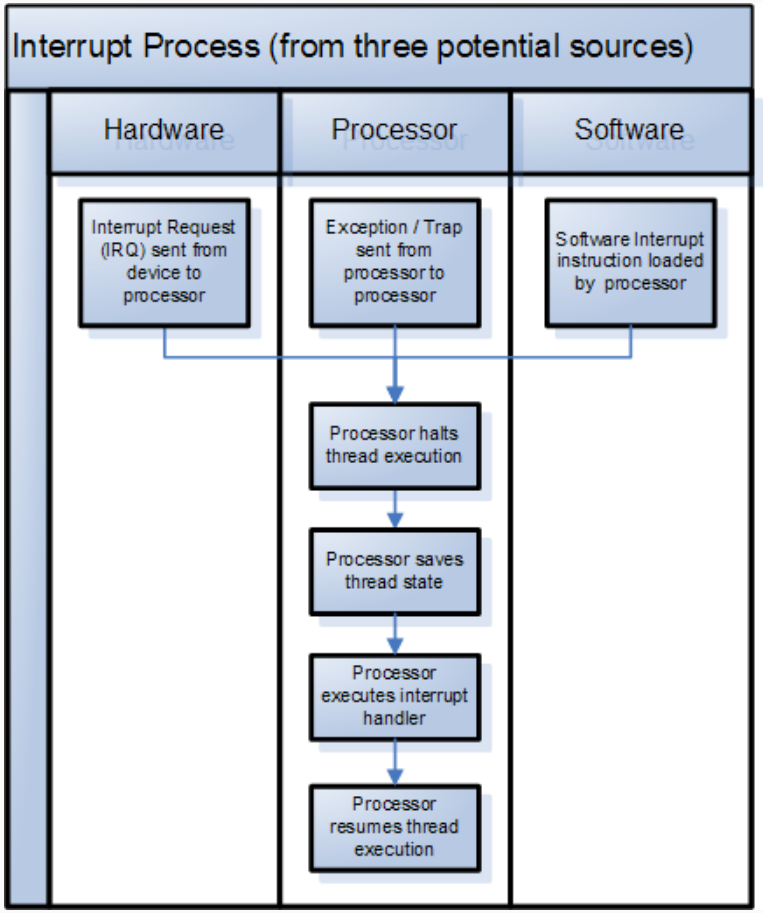
http://carlhenrik.com

a) Potential energy

(b) Kinetic energy

Interrupts

- Software `instruction`
- Processor `TRAP`
- Hardware `IRQ`



Software Interrupts

Code

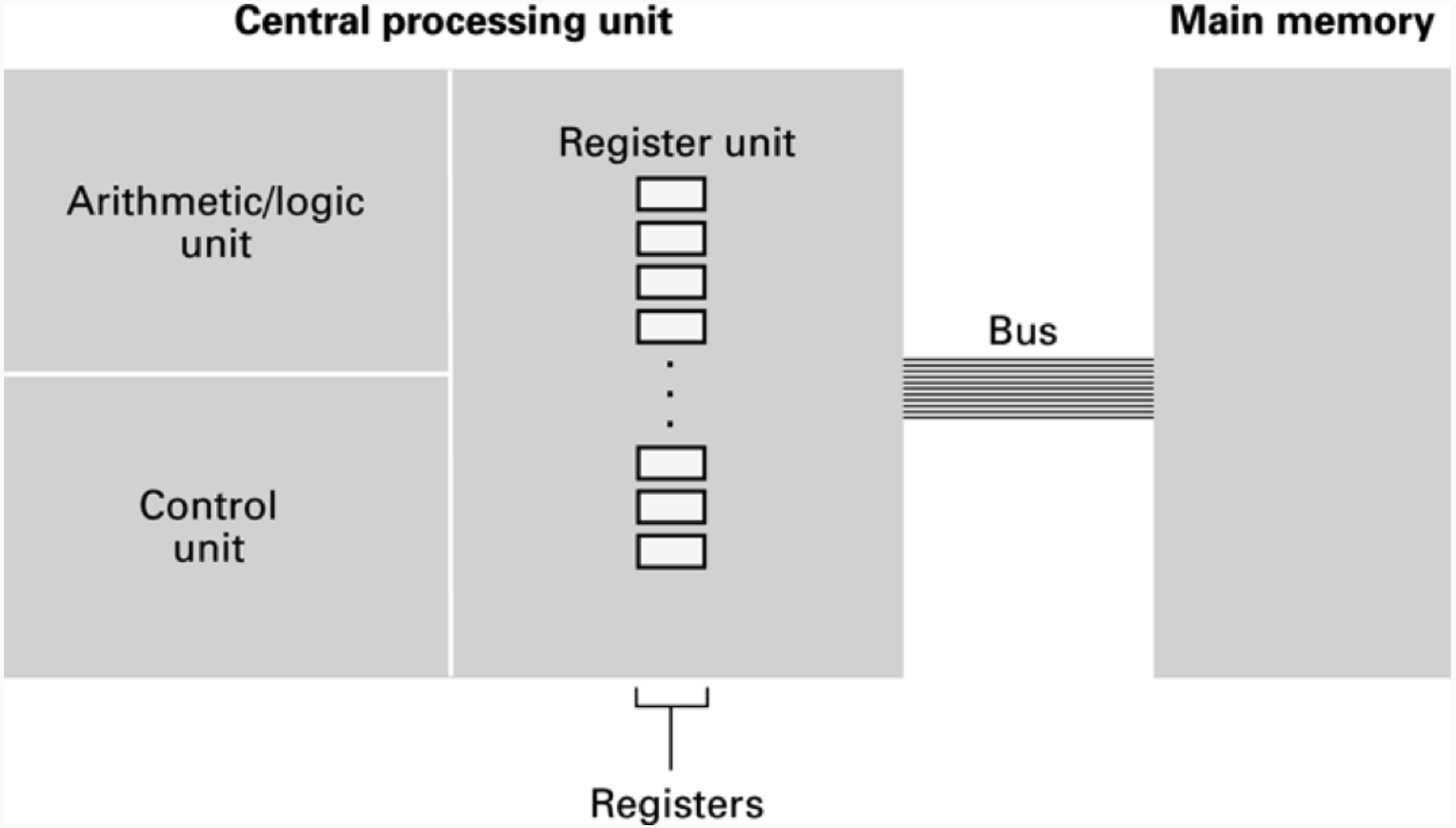
```
swi         0x11
```

TRAP

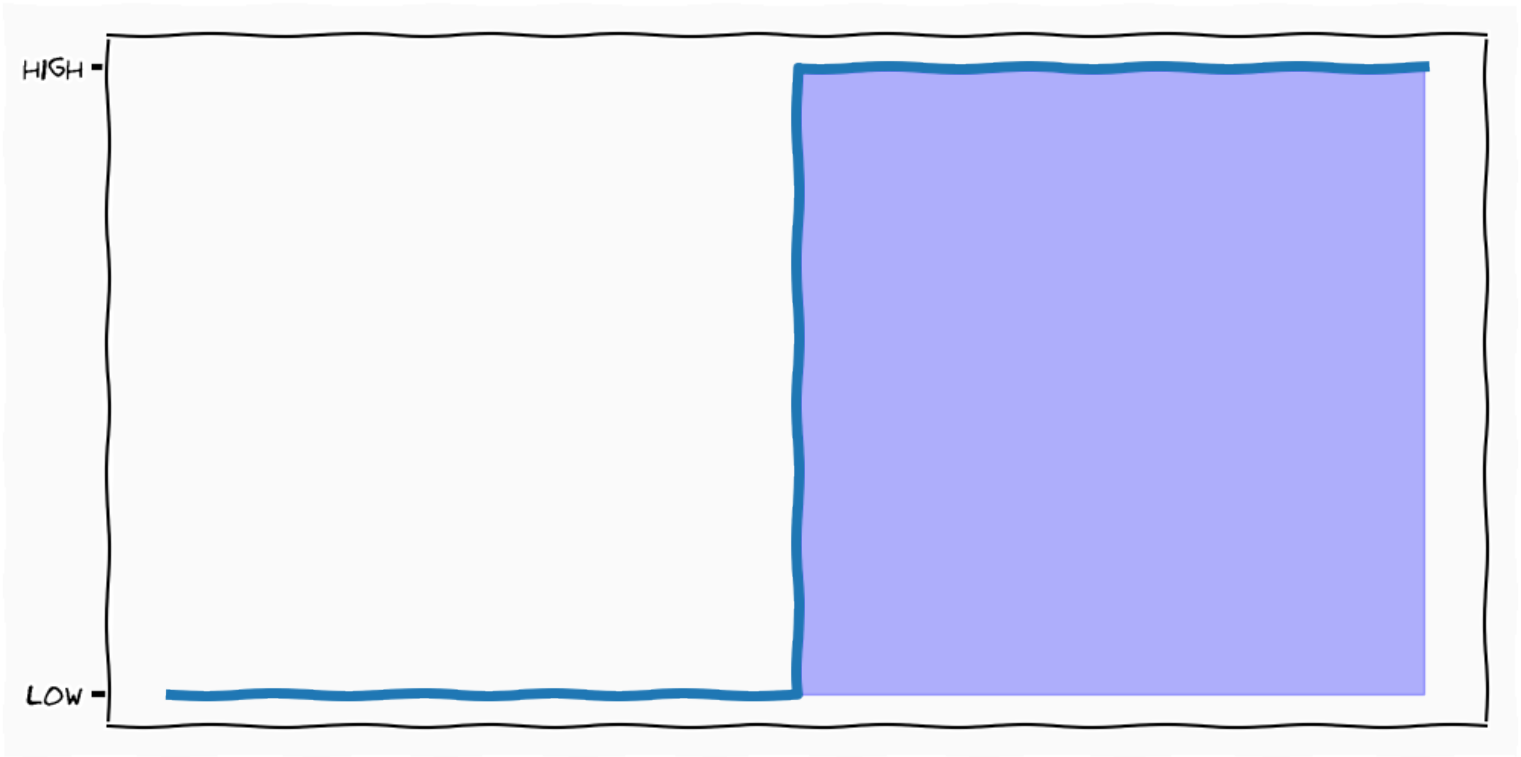
Code

```
mov         r0, #42
eor         r1, r1, r1
sdiv         r2, r1, r0
```

CPU


Central processing unit
Main memory
Arithmetic/logic unit
Control unit
Register unit
Bus
Registers

Hardware Interrupts



- ARM has 72 dedicated IRQ lines
- x86 has 16 dedicated IRQ lines

Interrupt is Triggered

1. Interrupt is triggered

Interrupt is Triggered

1. Interrupt is triggered
2. Disable Interrupts

Interrupt is Triggered

1. Interrupt is triggered
2. Disable Interrupts
3. Processor halts execution

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2. Disable Interrupts
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4. Save state of current context

Interrupt is Triggered

1. Interrupt is triggered
2. Disable Interrupts
3. Processor halts execution
4. Save state of current context
5. Call Interrupt Handler

Interrupt is Triggered

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2. Disable Interrupts
3. Processor halts execution
4. Save state of current context
5. Call Interrupt Handler
6. Restore state of previous context

Interrupt is Triggered

1. Interrupt is triggered
2. Disable Interrupts
3. Processor halts execution
4. Save state of current context
5. Call Interrupt Handler
6. Restore state of previous context
7. Enable Interrupts

Interrupt Vector Table

Interrupt ID	Address of Routine
IRQ 0	0x000fff00
IRQ 7	0x0ff0ff00

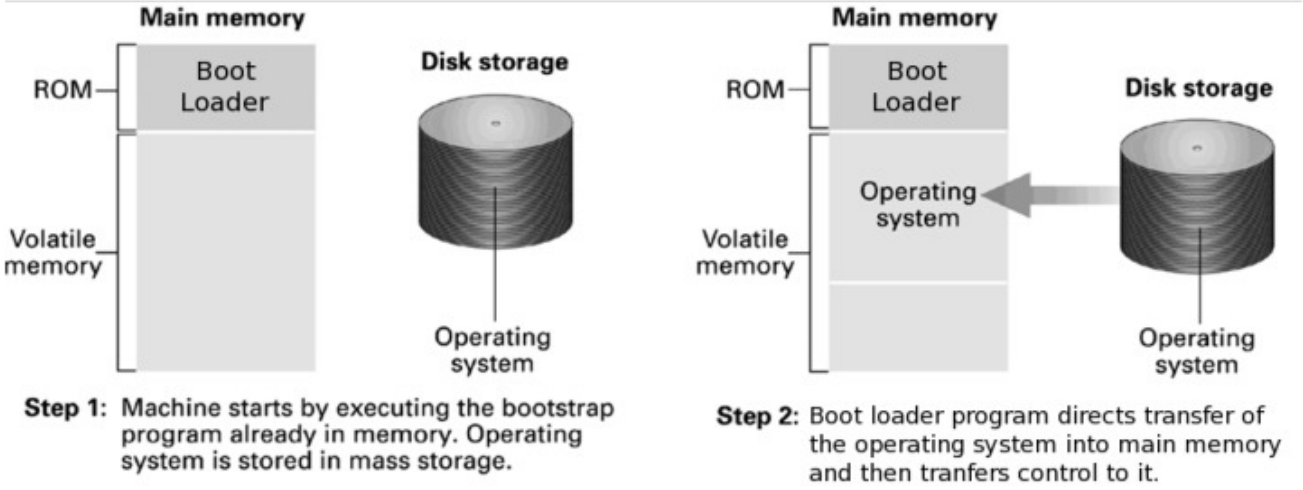
/proc/interrupts

Code

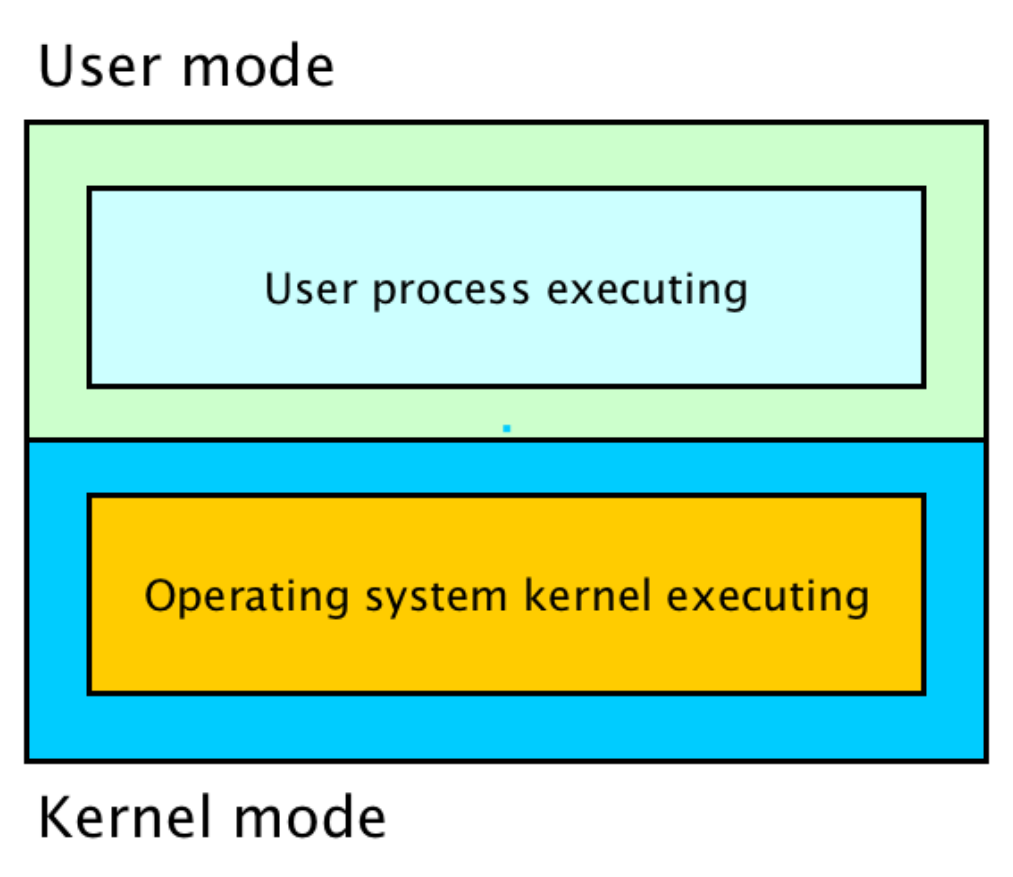
```
cat /proc/interrupts
```

Start

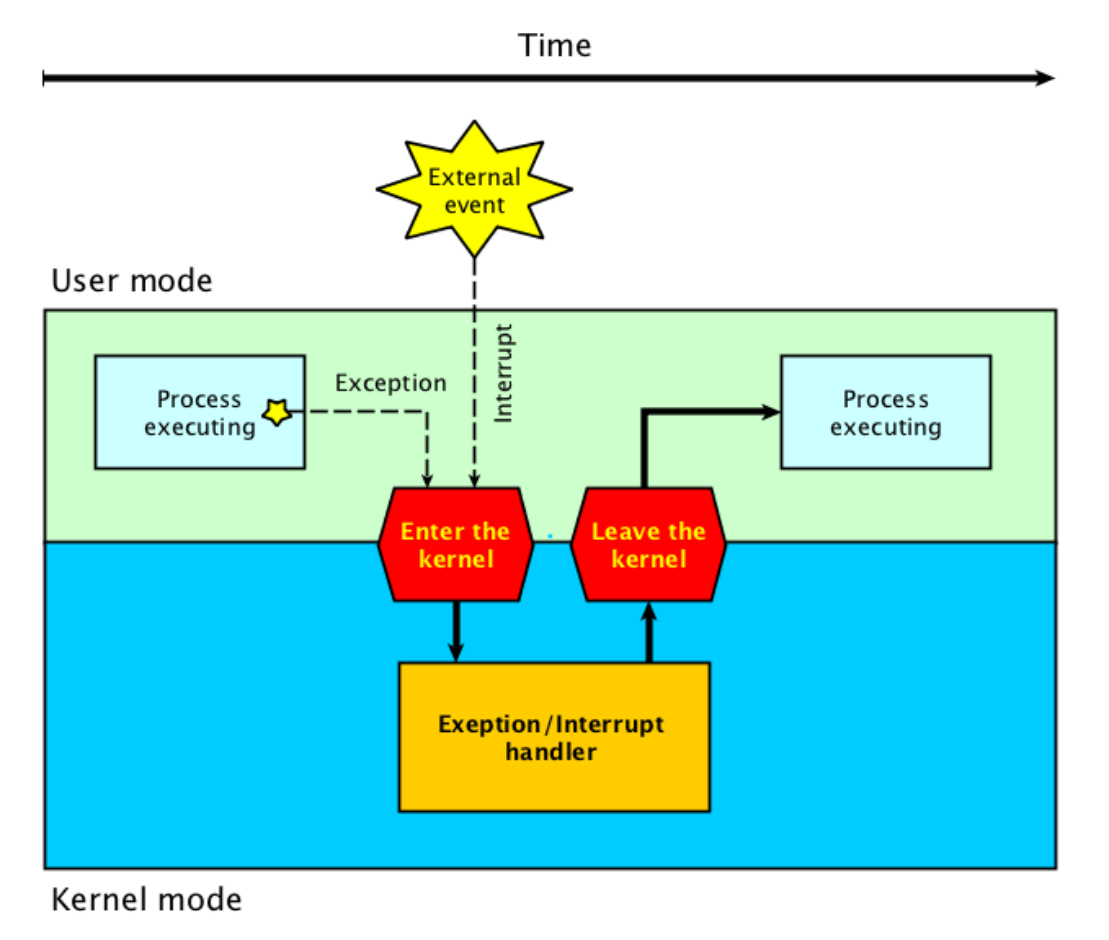
BIOS


Main memory
ROM
Boot Loader
Volatile memory
Disk storage
Operating system
Step 1: Machine starts by executing the bootstrap program already in memory. Operating system is stored in mass storage.
Main memory
ROM
Boot Loader
Operating system
Volatile memory
Disk storage
Operating system
Step 2: Boot loader program directs transfer of the operating system into main memory and then tranfers control to it.

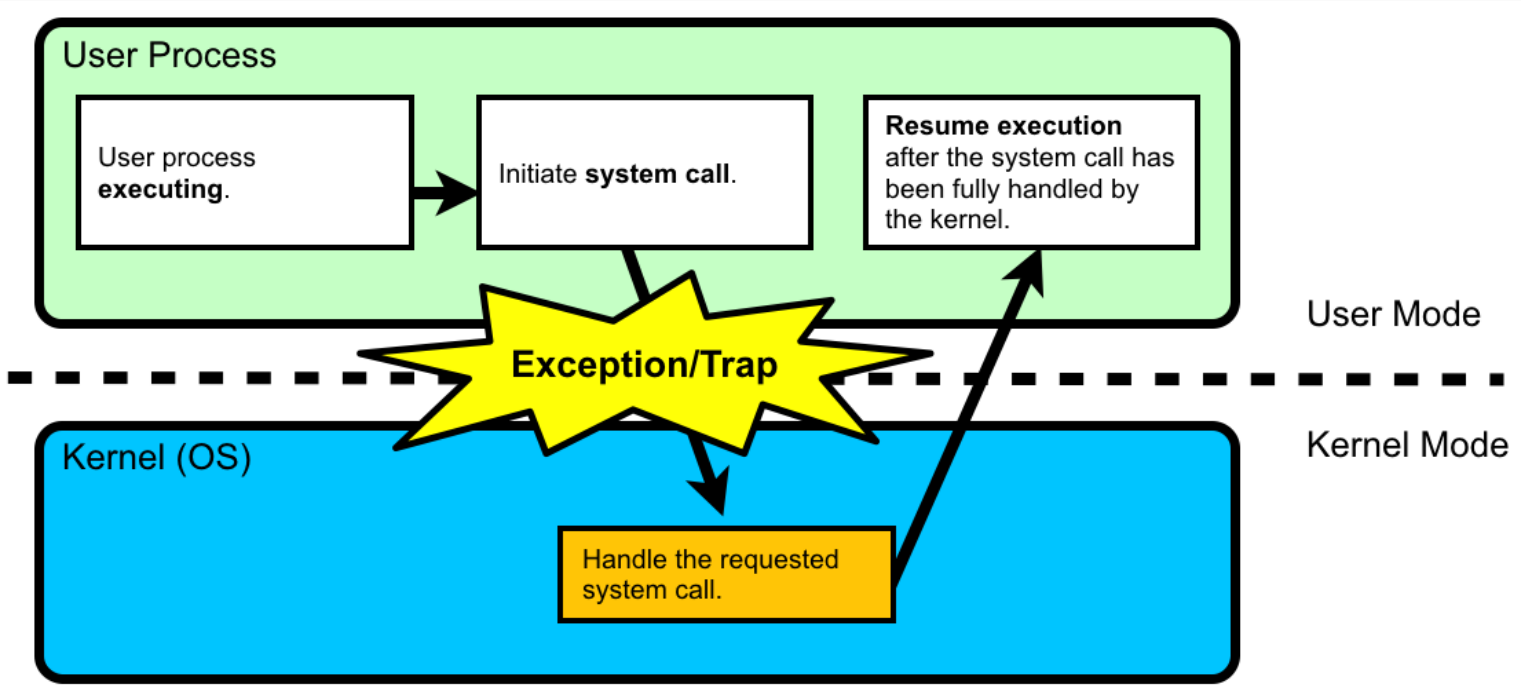
User/Kernel Mode



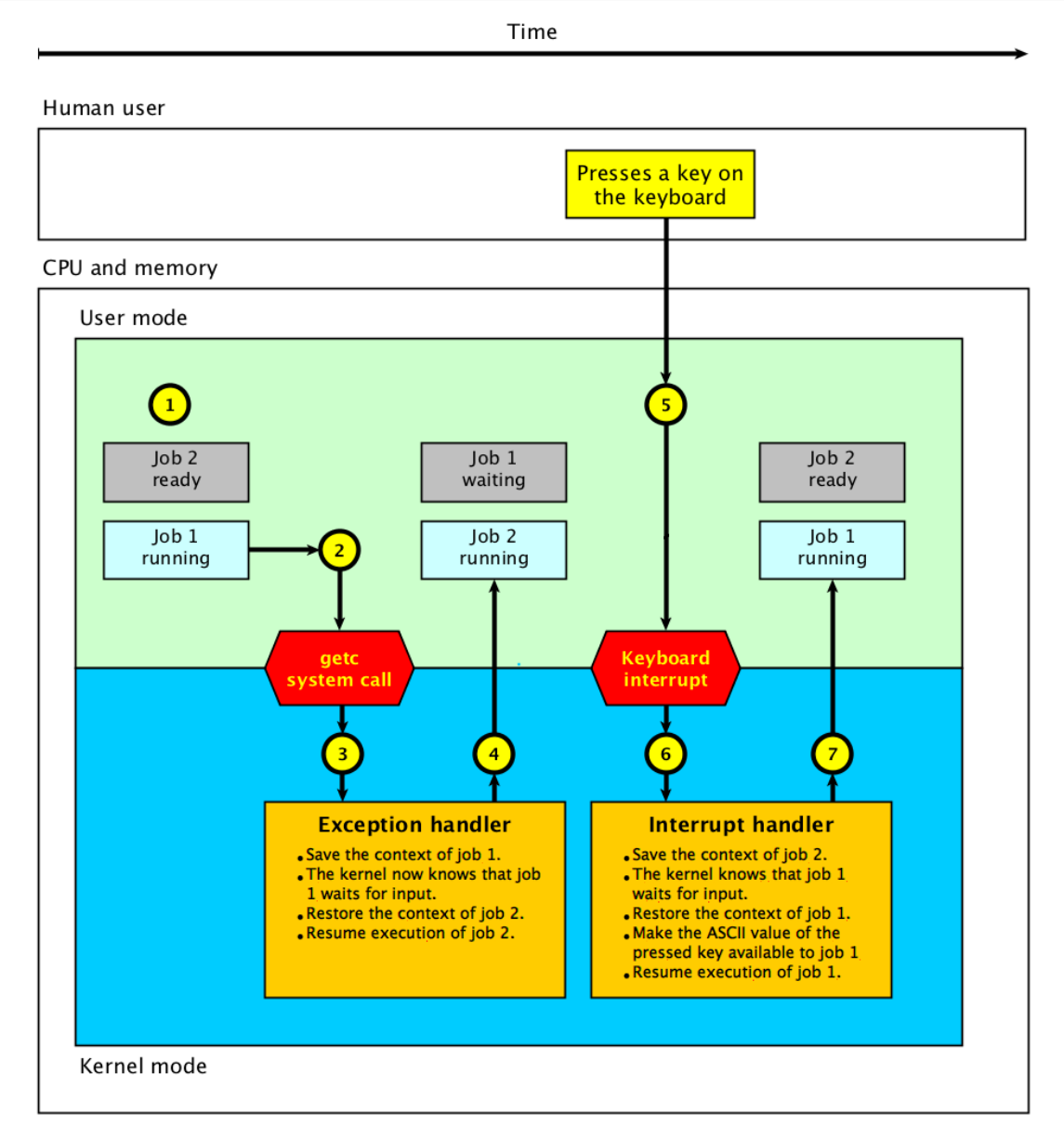
Interrupt


Time
External event
User mode
Process executing
Exception
Interrupt
Process executing
Enter the kernel
Leave the kernel
Exeption/Interrupt handler
Kernel mode

Interrupt


User Process
User process executing.
Initiate system call.
Resume execution after the system call has been fully handled by the kernel.
Exception/Trap
User Mode
Kernel Mode
Kernel (OS)
Handle the requested system call.

Multiple Processes



Operating Systems

Operating Systems

- 1969 UNIX
  - Dennis Ritchie, Kenneth Thompson
- 1974 CP/M
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- 1980 (86/Q)-DOS
  - Seattle Computer Products
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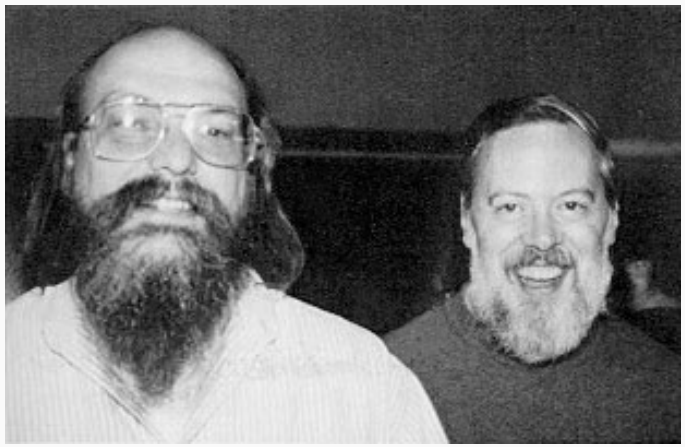

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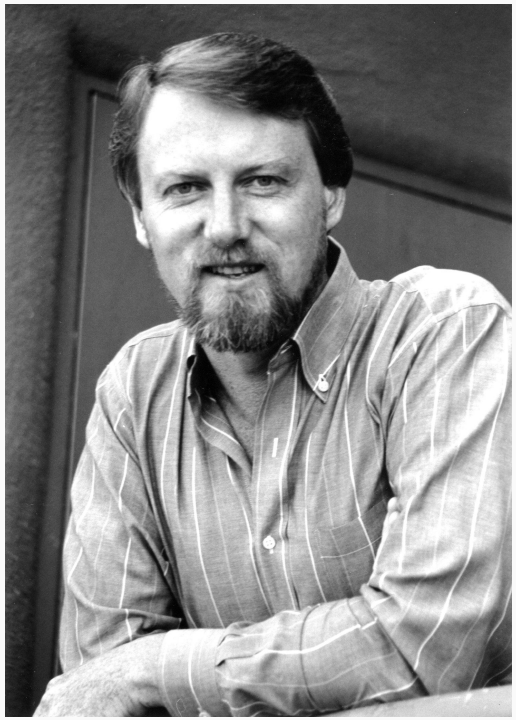

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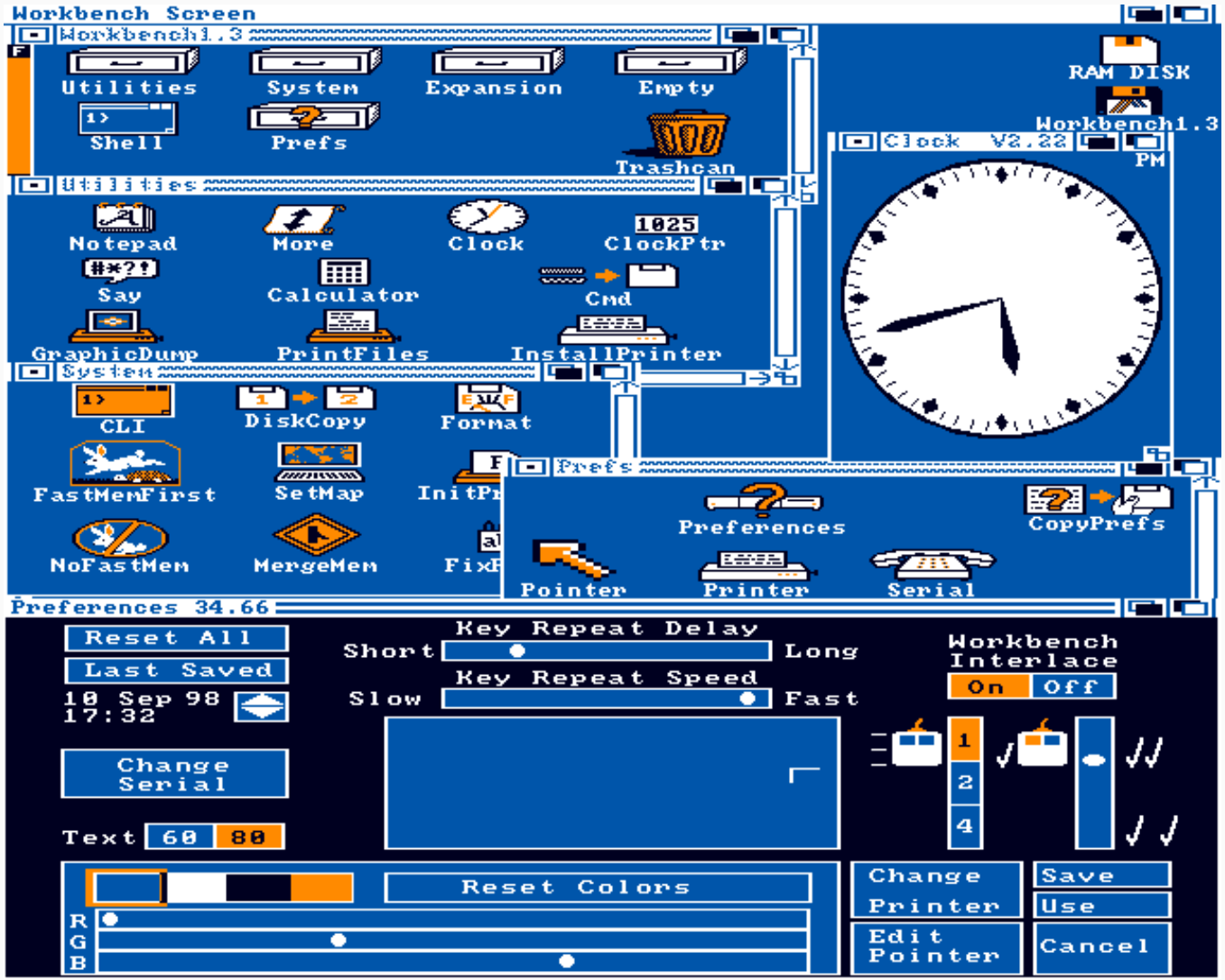

UNIX

Henry Spencer Those who do not understand UNIX are condemned to reinvent it, poorly.

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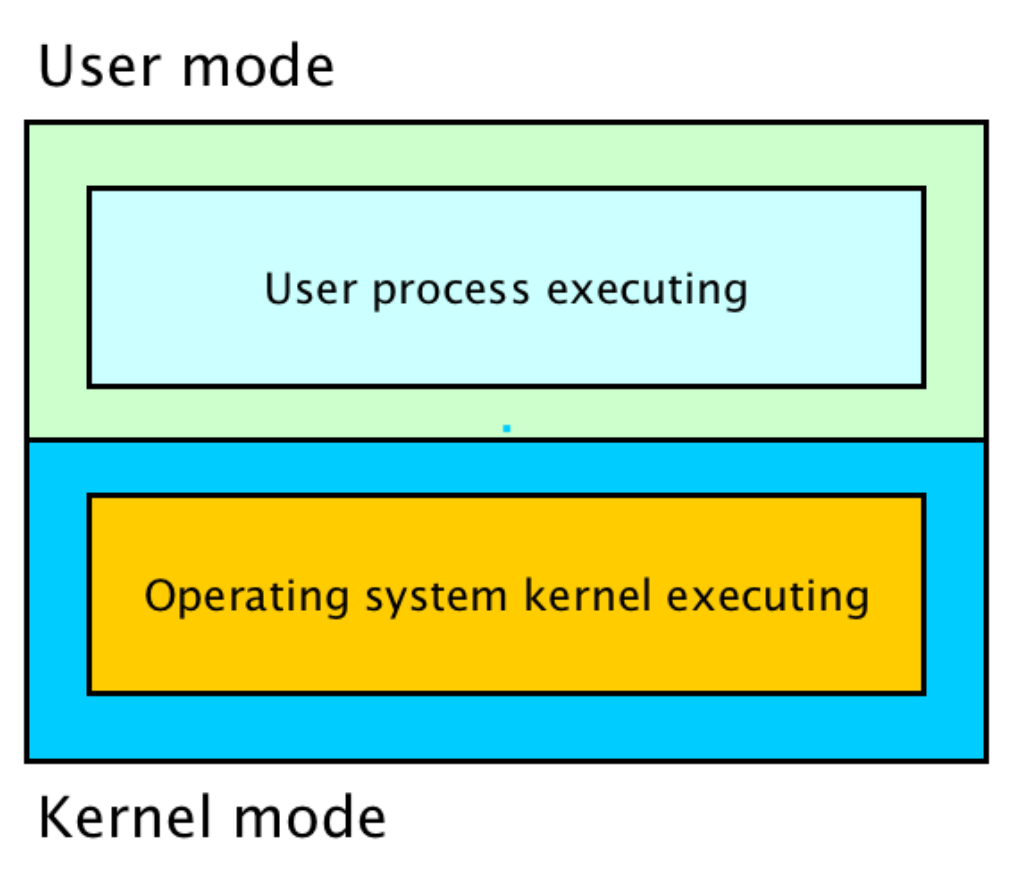
Jeremy S. Anderson There are two major products that came out of Berkeley: LSD and UNIX. We don't believe this to be a coincidence.

Today

1. Processes
2. Process Scheduling
3. Memory Management

User/Kernel Mode



Process

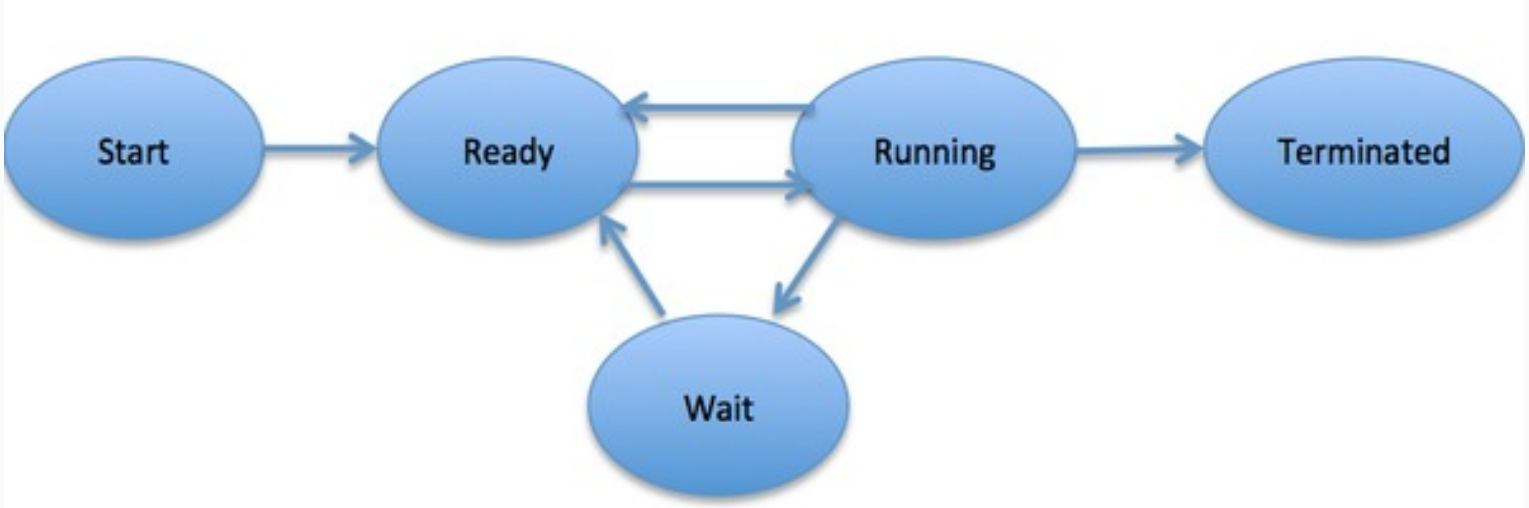
Code

```c
#include <stdio.h>

int main(void)
{
  int j = 0;
  for(int i=0;i<0xffff; i++)
    {
      j += i;
    }

  return j;
}
```

Process



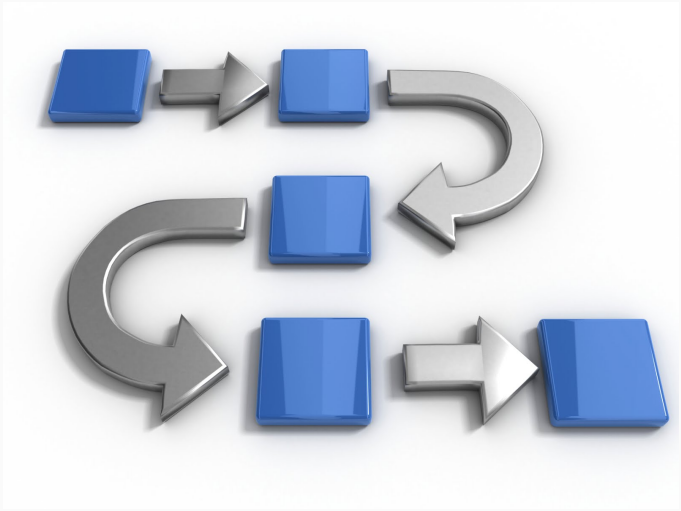
Process

Code

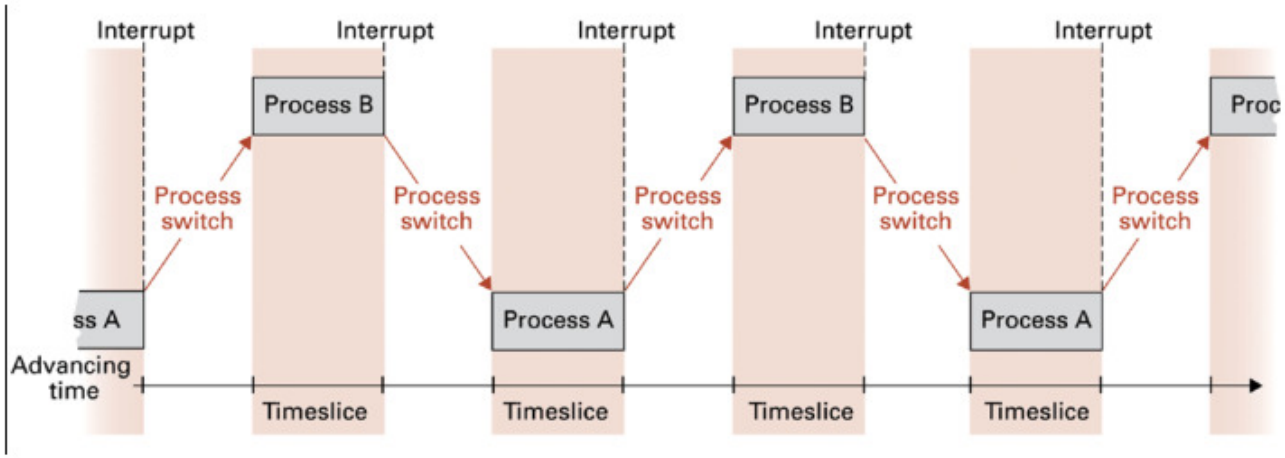
```
pstree
top
ps - e | grep xterm
sudo ls -l /proc/{PID}
```

Scheduler

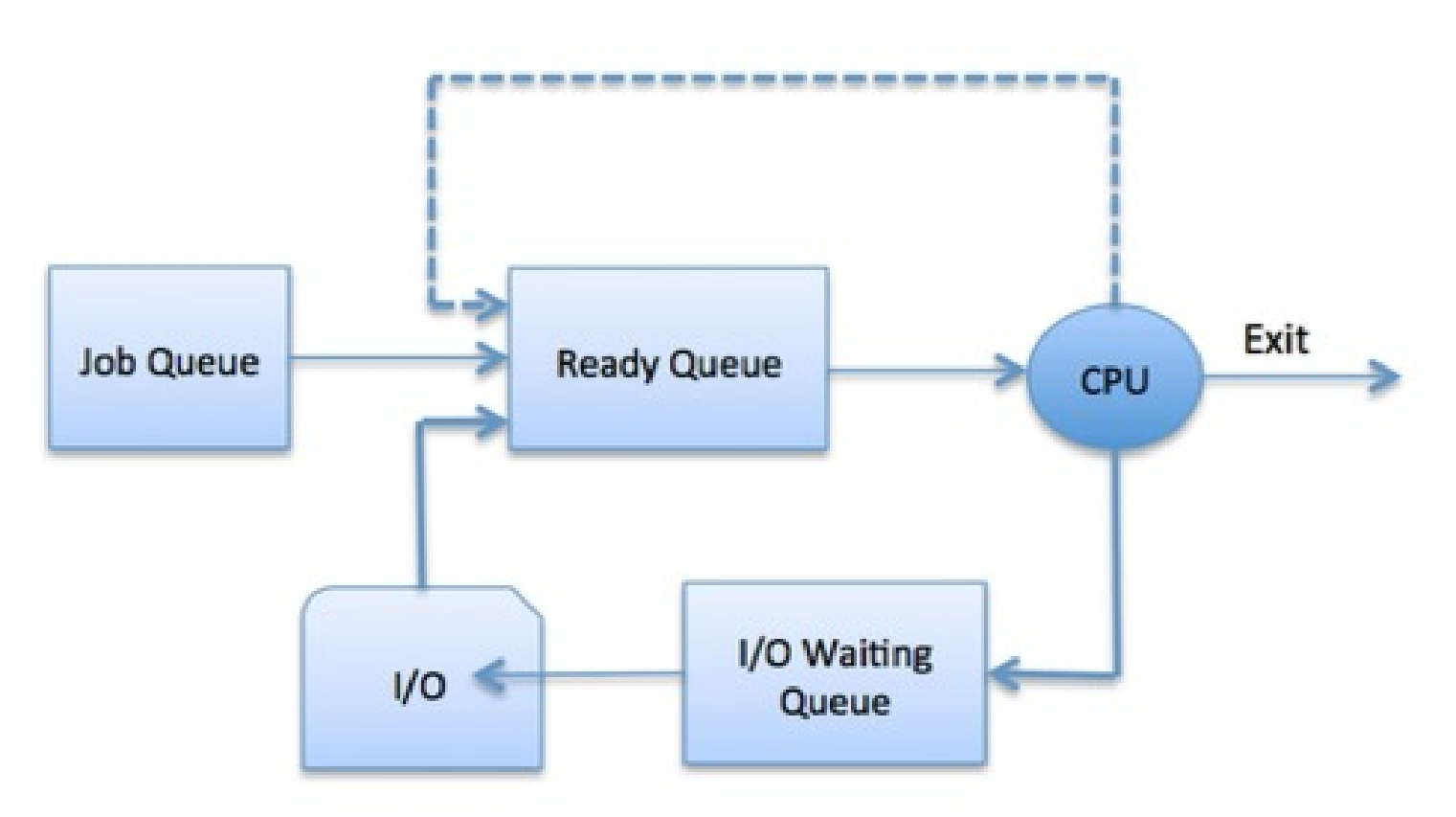
- Program is static
- Execution is not
- Process state
  - Program Counter
  - Registers
  - (Memory)
- Context switch



Scheduler


Interrupt
Interrupt
Interrupt
Interrupt
Interrupt
Process B
Process B
Proc
Process switch
Process switch
Process switch
Process switch
Process switch
ss A
Process A
Process A
Advancing time
Timeslice
Timeslice
Timeslice
Timeslice

Scheduler

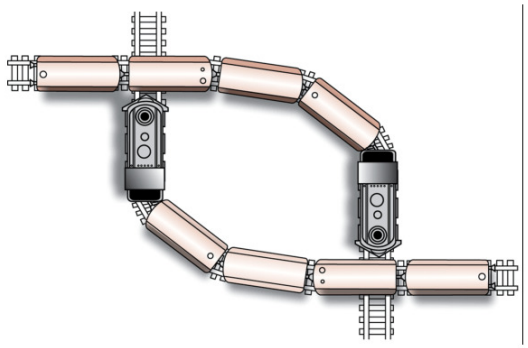


Short Term Scheduler

- How to structure execution?

Short Term Scheduler

- How to structure execution?
- Deadlock



Short Term Scheduler

- How to structure execution?
- Deadlock
- Starvation

Scheduling

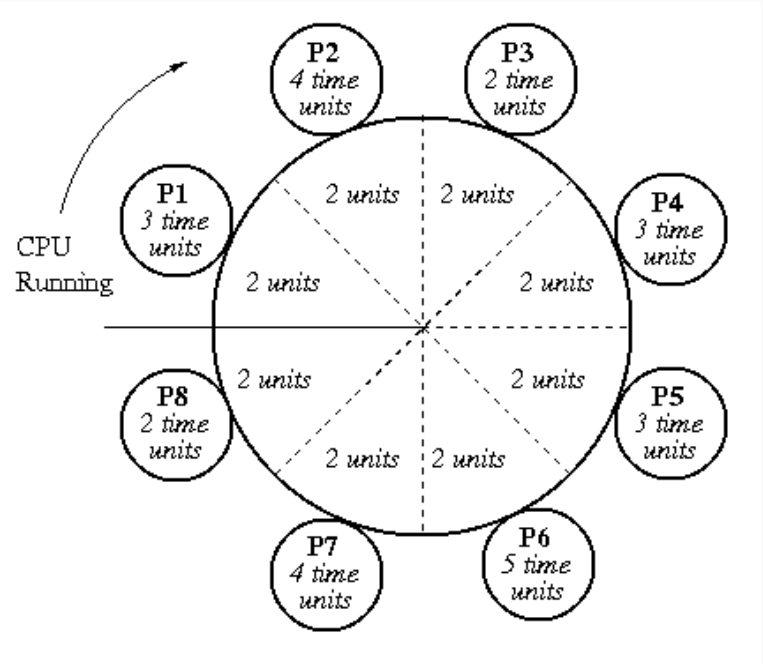
- Maximise Throughput
- Minimise Latency
- Minimise Overhead
- Responsiveness
- Real-time (deadline)

FIFO

- Naive
- Simple to Implement
- Low overhead

Round-Robin

- Slice time
- Each process in turn
- No starvation
- "Fair"
- Not sensible for real-time



Scheduling

- Each process associated with different priority
- Starvation
  - Ageing - increase priority over time
- Allows for real-time

Scheduling

- Multiple FIFO quest
- Different priority of queue
- Time-slicing per queue
- Lowest-level have round-robing

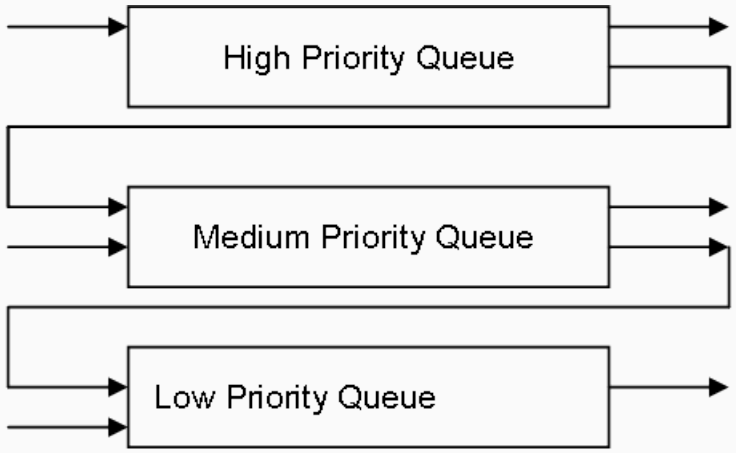


Figure – Multilevel Feedback Queue Scheduling

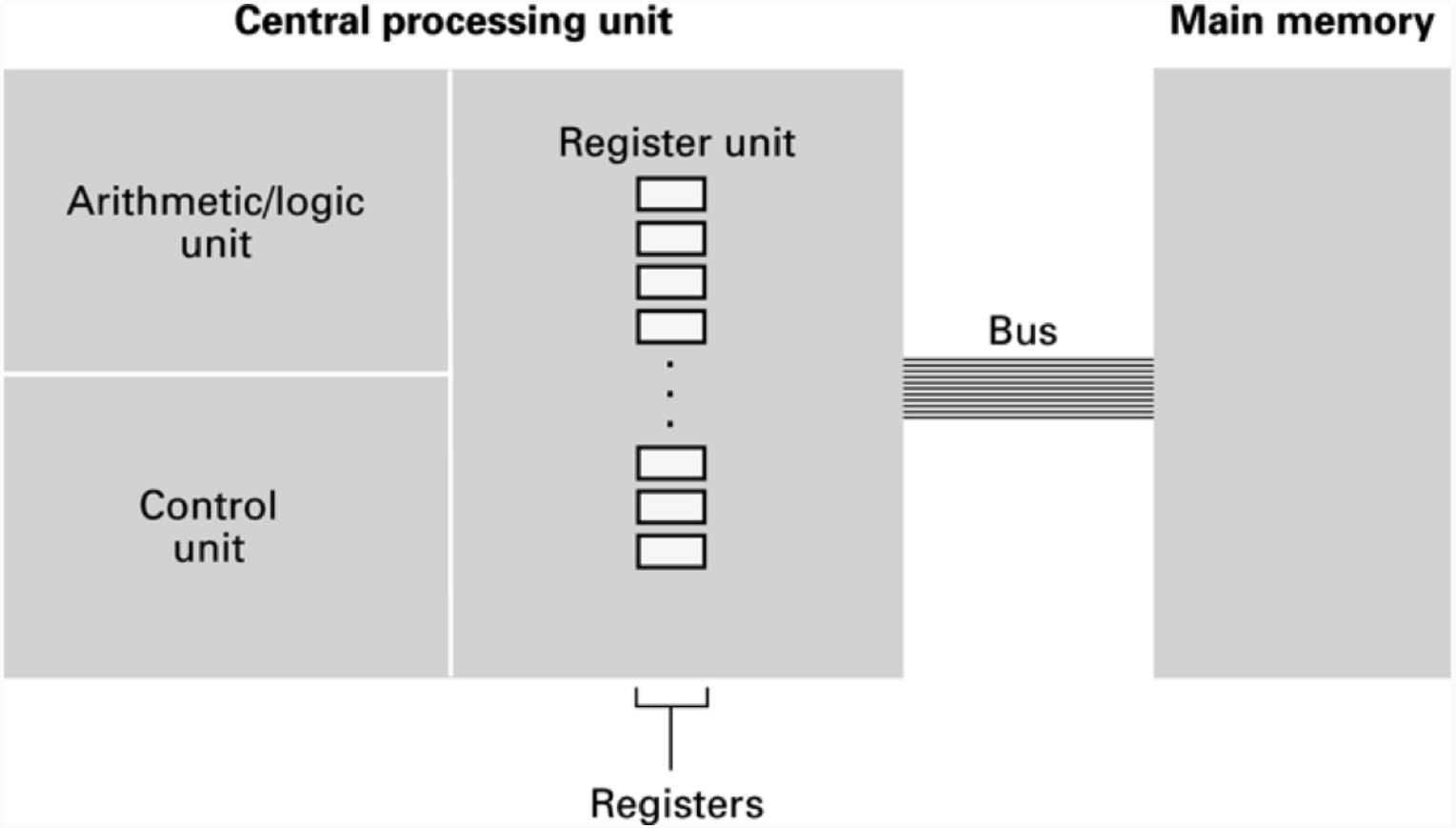
Linux Scheduling

- Interrupt ever 10^{-3} seconds
- Each process have priority N
  - A process runs uninterrupted for N slices
- *Goodness* measure of importance of process

Summary

- Scheduling is very very hard
- Responsible for much of the look'n'feel of an operating system
- Combination of many different strategies common
- Remember *starvation* and *deadlock*

CPU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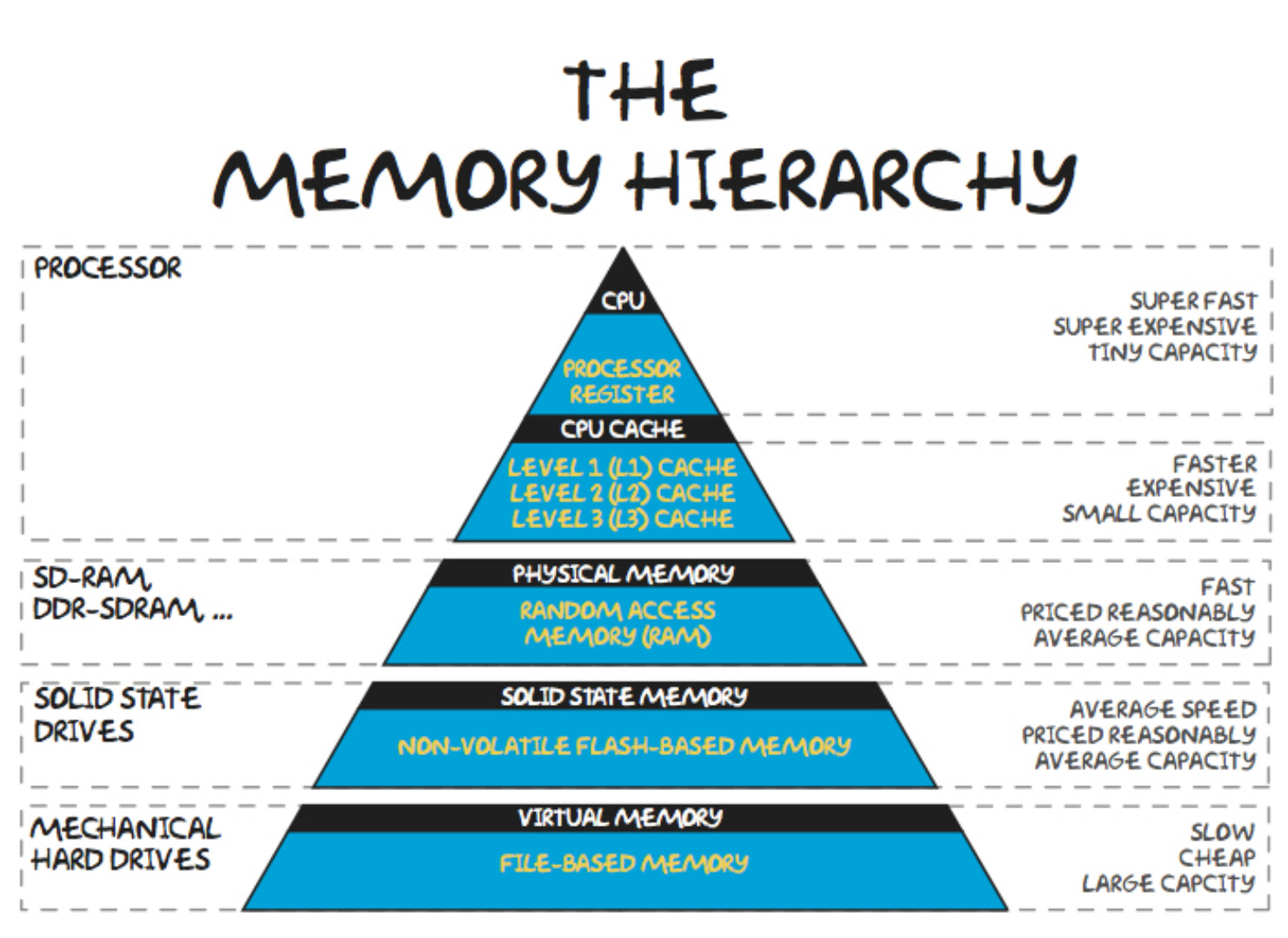
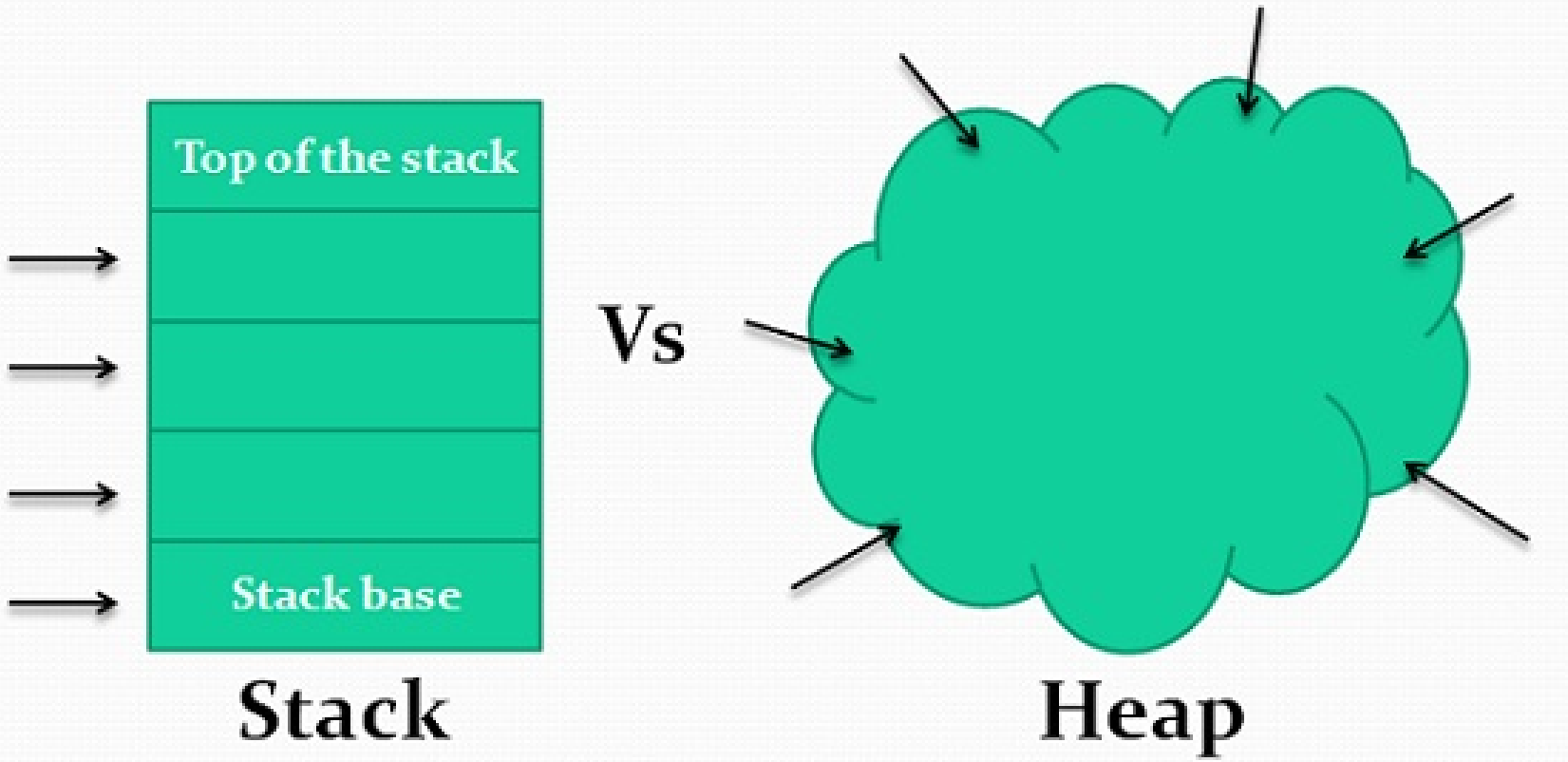
Memory Hierarchy



Memory

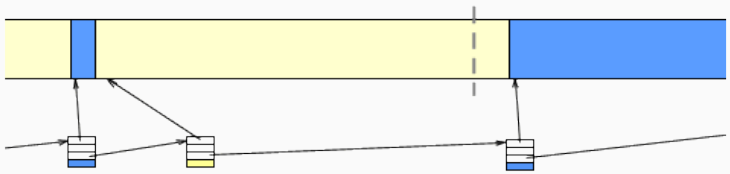
- Bus can address memory
- Tasks
  - Allocation (distribution)
  - Protection
- Fragmentation
- Overhead

Memory: Allocation

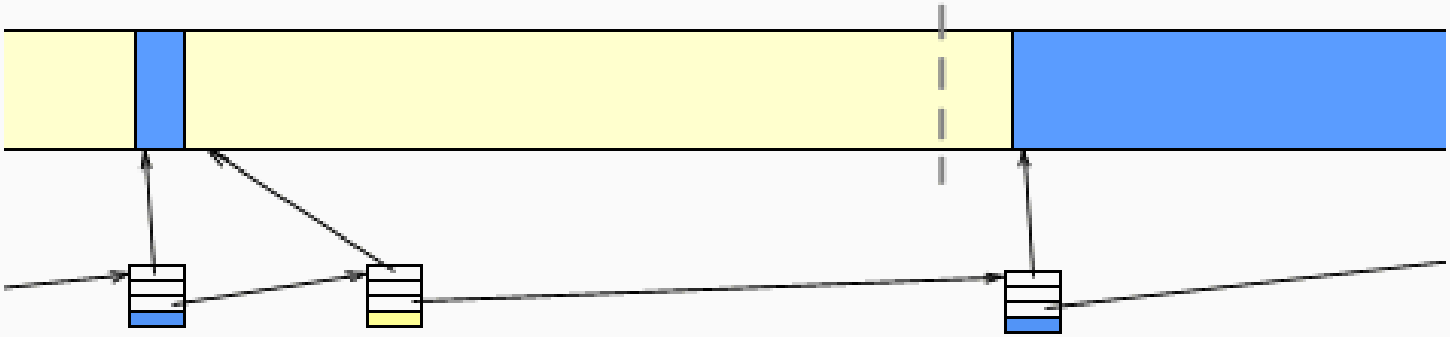


Memory: Allocation

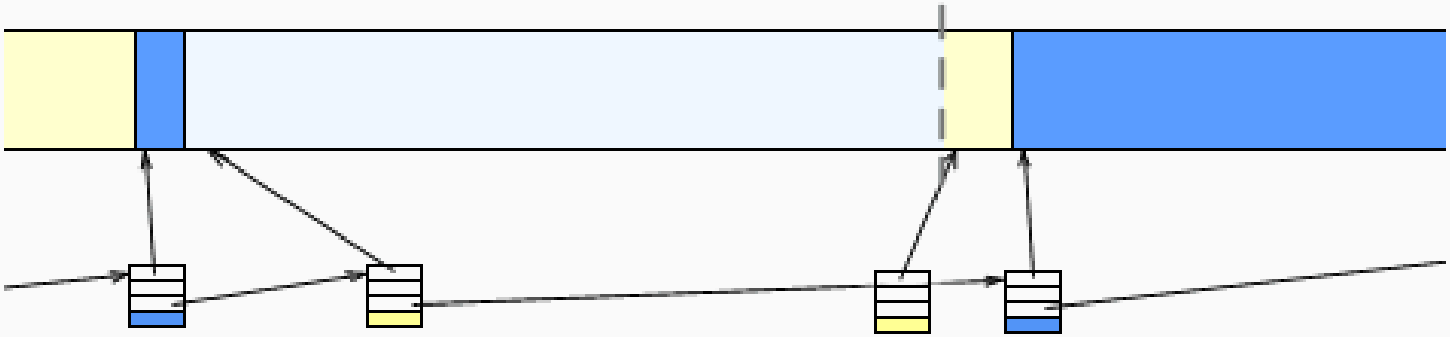
- Allocation
  - First fit
  - Best fit
  - Worst fit
- Sorting for quicker allocation



Memory: Allocation



Memory: Allocation



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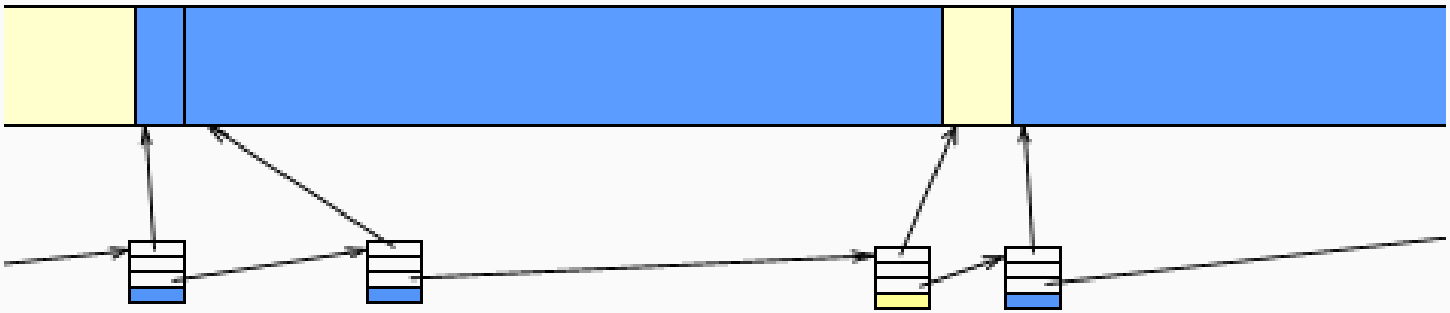
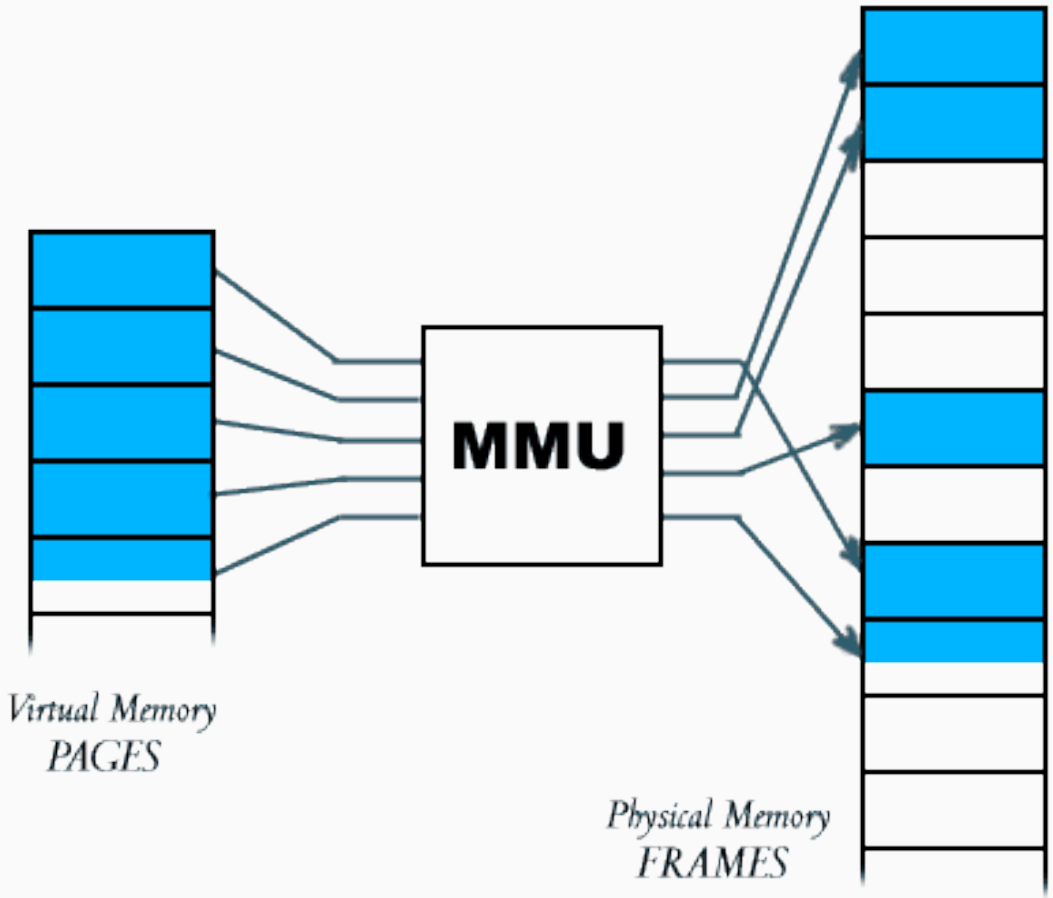
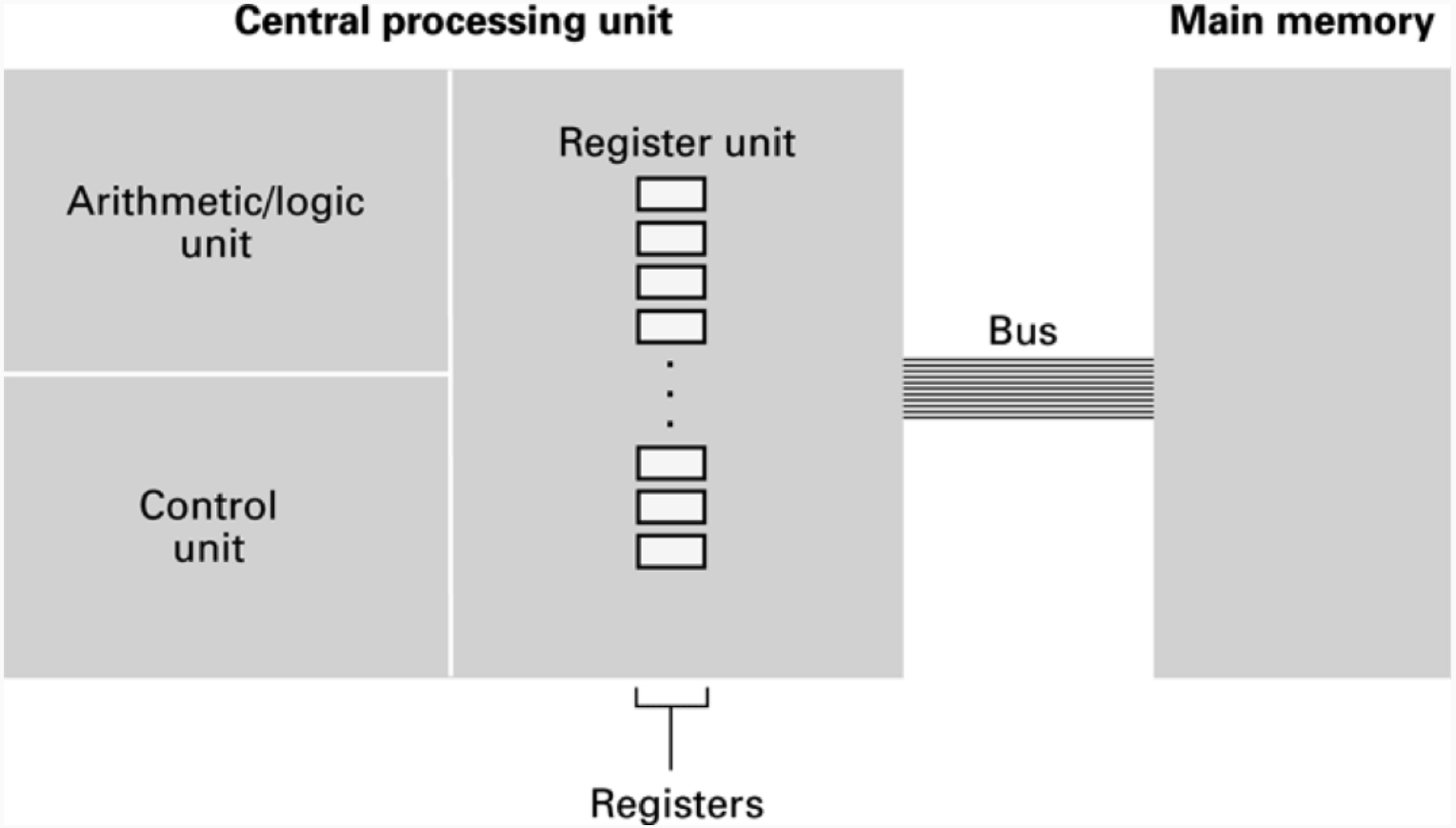


Memory Management Unit



Memory Protection



Summary

- Memory management is very hard
- Trade-off between overhead and efficiency
- Allocation/Protection

Summary

Summary

- Booting
- Kernel/User space
- Executing management
- Memory management
- Its not important to know how the work, but to know why we have them