Theory

Baseline Model: No Censoring, No Covariates, Single Sequence

Draw y_1, y_2, \ldots from $y_i \sim \text{Bernoulli}(\pi)$ until $y_i = 1$. This sampling procedure produces a sequence of n-1 zeros and a single one, where n is a random variable. In fact, $n \sim \text{geometric}(\pi)$.

Use the sample average $\bar{y} = \frac{1}{n}$ to estimate π . Is \bar{y} an unbiased estimator of π , so that $E(\bar{y}) = \pi$?

Result: \bar{y} is biased upward by a factor of $\frac{-\log(\pi)}{1-\pi}$.

First, notice that, by construction, $\bar{y} = \frac{1}{n}$ (remember that n is a random variable).

But what is the distribution of $\frac{1}{n}$?

$$P\left(\frac{1}{n} = 1\right) = \pi$$

$$P\left(\frac{1}{n} = \frac{1}{2}\right) = (1 - \pi)\pi$$

$$P\left(\frac{1}{n} = \frac{1}{3}\right) = (1 - \pi)^2\pi$$

$$\vdots$$

$$P\left(\frac{1}{n} = \frac{1}{k}\right) = (1 - \pi)^{k-1}\pi$$

$$\vdots$$

Then

$$E\left(\frac{1}{n}\right) = \frac{\pi}{1-\pi} \sum_{i=1}^{\infty} \frac{1}{i} (1-\pi)^i$$

.

The series $\frac{1}{i}(1-\pi)^i$ converges because $(1-\pi) \le 1 \le |\frac{1}{i}|^{-\frac{1}{i}}$ for all i. (See radius of convergence for a power series.)

We now need the sum $\sum_{i=1}^{\infty} \frac{1}{i} (1-\pi)^i$. For simplicity, let $q=1-\pi$, so that we need the sum $\sum_{i=1}^{\infty} \frac{1}{i} q^i$.

$$\sum_{i=1}^{\infty} \frac{1}{i} q^i = \sum_{i=1}^{\infty} \int_0^q x^{(i-1)} dx \text{ (by the F.T.C.)}$$

$$= \int_0^q \sum_{i=1}^{\infty} x^{(i-1)} dx \text{ (sum of integrals equals the integral of sums)}$$

$$= \int_0^q \frac{1}{1-x} dx \text{ (sum of a geometric series with } -1 < r < 1)$$

$$= \int_1^{1-q} \frac{1}{u} (-du) \text{ (integration by substitution; let } u = 1 - x, du = -dx, \text{ adjust limits)}$$

$$= -\log(u) \Big|_1^{1-q} \text{ (} \int \frac{1}{z} dz = \log(z) + C \text{ for } z > 0)$$

$$= -[\log(1-q) - \log(1)] \text{ (evaluate integral at limits)}$$

$$= -\log(1-q) \text{ (simplify)}$$

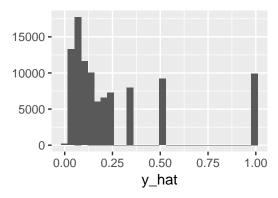
Substituting this result in, we have $\sum_{i=1}^{\infty} \frac{1}{i} (1-\pi)^i = -\log(\pi)$. Then we have that

$$E(\bar{y}) = E\left(\frac{1}{n}\right) = \frac{\pi}{1-\pi} \sum_{i=1}^{\infty} \frac{1}{i} (1-\pi)^i = \frac{-\pi \log(\pi)}{1-\pi}$$

For an unbiased \hat{y} , we would have $E(\bar{y}) = \pi$, but we have $E(\bar{y}) = \pi \left[\frac{-\log(\pi)}{1-\pi}\right]$. We can see that $\frac{-\log(\pi)}{1-\pi} = 1$ when $\pi = 1$. Further, we can see that it decreases with π for $0 \le \pi \le 1$. This implies that \bar{y} is biased upward by a factor of $\frac{-\log(\pi)}{1-\pi}$.

The simulation below confirms the result.

```
# number of mc simulations
n_sims <- 100000
pi <- 0.1
# draw y from geometric distribution
## note: this is the number of failures (0s)
## before a success
x <- rgeom(n_sims, prob = pi)
# the mean of the series with x Os and a single 1
y_hat <- 1/(x + 1)
# estimate E(y-hat)
mean(y_hat)
## [1] 0.2560564
# theoretical solution
-pi*log(pi)/(1-pi)
## [1] 0.2558428
# plot sampling distribution
library(ggplot2)
qplot(y_hat)
```



The figure below shows the adjustment factor $\frac{-\log(\pi)}{1-\pi}.$

```
# adjustment factor
adj_fn <- function(p) {
    -log(p)/(1 - p)
}

# plot adjustment factor
library(ggplot2)
ggplot(data.frame(x = c(0.01, 1)), aes(x)) +
    stat_function(fun = adj_fn, geom = "line")</pre>
```

