

FPTAS - 0/1 Knapsack with Volume constraint

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0/1 Knapsack - Simple version

- n objects
- p_k profit for object k
- w_k weight of object k
- b capacity

Maximize

$$z = \sum_{k=1}^n p_k x_k$$

subject to:

$$\sum_{k=1}^n w_k x_k \leq b$$

$$x_k \in \{0, 1\} \quad k = 1, \dots, n$$

0/1 Knapsack with DP

- s = remaining capacity
- solution is $f_1(b)$

Recursion

$$f_k(s) = \max \begin{cases} p_k + f_{k+1}(s - w_k) & x_k = 1 \\ f_{k+1}(s) & x_k = 0 \end{cases}$$

Base

$$f_n(s) = \begin{cases} 0 & s < w_n \\ p_n & s \geq w_n \end{cases}$$

Time complexity: $O(nb)$

0/1 Knapsack with Volume constraint

- n objects
- p_k profit for object k
- w_k weight of object k
- v_k volume of object k
- b tot. capacity, V tot. volume

Maximize

$$z = \sum_{k=1}^n p_k x_k$$

subject to:

$$\sum_{k=1}^n w_k x_k \leq b \quad (1)$$

$$\sum_{k=1}^n v_k x_k \leq V, \quad x_k \in \{0, 1\} \quad k = 1, \dots, n \quad (2)$$

0/1 Knapsack with Volume constraint - DP

- $s = \langle \text{remaining capacity, remaining volume} \rangle$ (s is a tuple)
- solution is $f_1(\langle b, V \rangle)$

Recursion

$$f_k(s) = \max \begin{cases} f_{k+1}(s - \langle w_k, v_k \rangle) + p_k & x_k = 1 \\ f_{k+1}(s) & x_k = 0 \end{cases}$$

Base

$$f_n(s) = \begin{cases} 0 & s < \langle w_n, v_n \rangle \\ p_n & s \geq \langle w_n, v_n \rangle \end{cases}$$

Time complexity: $O(nbV)$

0/1 Knapsack - DP alternative version

- Recursion on profit
- s = remaining units of profit ($0 \dots P$)
- idea: find a set of objects with maximum total profit ($\leq s$) and $\langle \text{weight, volume} \rangle \leq \langle b, V \rangle$

Recursion

$$f_k(s) = \min \begin{cases} f_{k+1}(s - p_k) + \langle w_k, v_k \rangle & x_k = 1 \\ f_{k+1}(s) & x_k = 0 \end{cases}$$

Base

$$f_n(s) = \begin{cases} \langle +\infty, +\infty \rangle & s \neq p_n \\ \langle w_n, v_n \rangle & s = p_n \\ \langle 0, 0 \rangle & s = 0 \end{cases}$$

Time complexity

- Time complexity is **pseudo-polynomial**: $O(nP)$
- Theoretical upper bound of $P \rightarrow np_{max}$

Time complexity

- Time complexity is **pseudo-polynomial**: $O(nP)$
- Theoretical upper bound of $P \rightarrow np_{max}$
- If P is small \rightarrow *polynomial* time

- Fully-Polynomial time approximation scheme
- Scale profits down so that time is polynomial (scale factor ε)
- Solve scaled instance I of the problem
- Solution $A(I)$ is a ε -approximation of the optimal solution

$$A(I) \geq (1 - \varepsilon)OPT(I)$$

given $\varepsilon > 0$

- ① let $p_{max} = \max\{p_0, \dots, p_n\}$
- ② let $K = \frac{\varepsilon p_{max}}{n}$
- ③ for each object i , define $p'_i = \lfloor \frac{p_i}{K} \rfloor$
- ④ Solve scaled instance with dynamic programming
- ⑤ Return solution S'

Time Complexity

$$O(nP') = O(n * np'_{max}) = O(n^2 * \frac{p_{max}}{K}) = O(n^3 * \frac{1}{\varepsilon})$$

$$P(S') \geq (1 - \varepsilon)OPT(I)$$

Proof 1/2

- For every object $i \rightarrow Kp'_i \leq p_i$
- $p_i - Kp'_i = K$ **at most**
- Be O the optimal set with the maximum profit \rightarrow the maximum difference between the profit $P(O)$ of the original instance and the profit $P'(O)$ of the scaled instance is:

$$(a.) \quad P(O) - KP'(O) \leq nK$$

- Be S' the solution of the scaled instance found by dynamic programming $\rightarrow P(S')$ at least as good as $KP'(O)$

Proof 2/2

$$P(S') \geq KP'(O) \quad (3)$$

$$\geq P(O) - nK \quad (\text{for } a.) \quad (4)$$

$$= OPT - \varepsilon p_{\max} \quad (5)$$

Since $OPT \geq p_{\max}$

$$OPT - \varepsilon p_{\max} \geq OPT - \varepsilon OPT = (1 - \varepsilon)OPT$$

And so

$$P(S') \geq (1 - \varepsilon)OPT$$