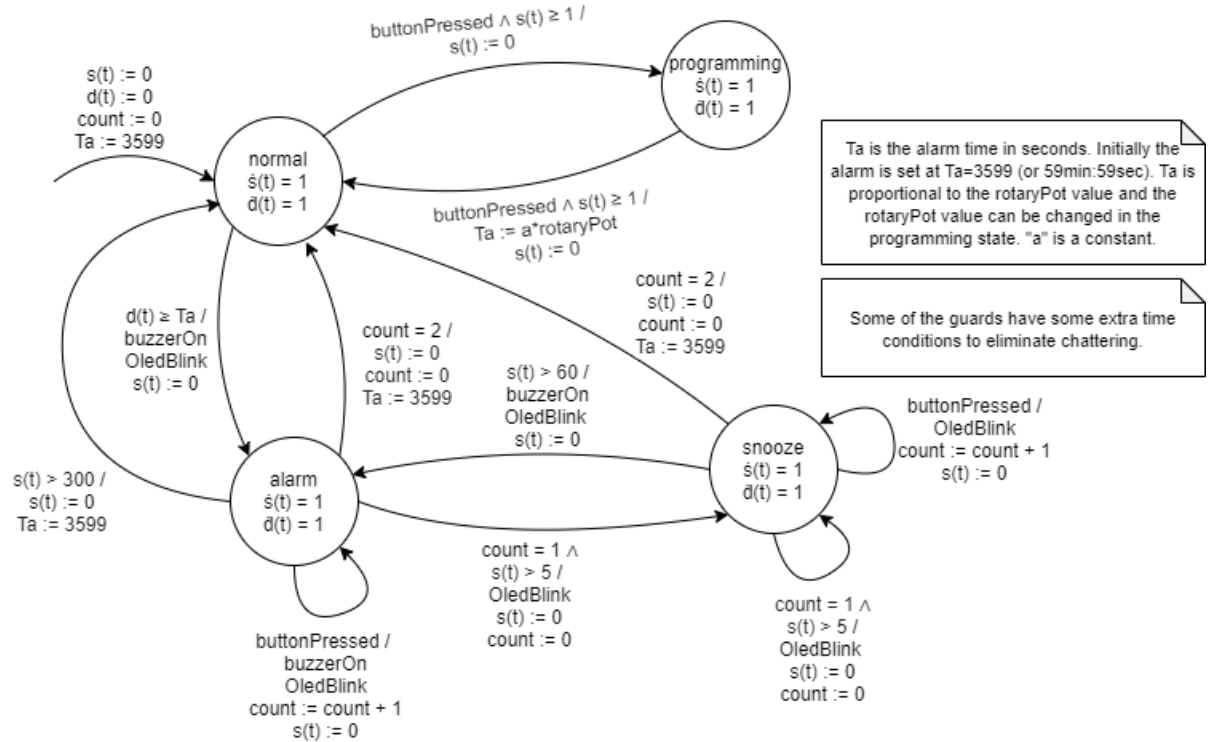


State Diagram and State-Transition Logic Table

continuous variables: $d(t)$, $s(t)$: R
 variables: count: {0,1,2}, Ta: {0, 1, ..., 3599}
 inputs: buttonPressed: pure, rotaryPot: {0, 1, ..., 1023}
 outputs: buzzerOn, OledBlink: pure



Inputs	Variables	Continuous Variables	Current State	Next State	Outputs	Actions
buttonPressed	-	$s(t) \geq 1$	normal	programming	-	$s(t) := 0$
-	-	$d(t) \geq Ta$	normal	alarm	buzzerOn OledBlink	$s(t) := 0$
buttonPressed rotaryPot	-	$s(t) \geq 1$	programming	normal	-	$Ta := a \cdot rotaryPot$ $s(t) := 0$
-	count = 2	-	alarm	normal	-	$s(t) := 0$ count := 0 $Ta := 3599$
-	count = 1	$s(t) > 5$	alarm	snooze	OledBlink	$s(t) := 0$ count := 0
-	-	$s(t) > 300$	alarm	normal	-	$s(t) := 0$ $Ta := 3599$
buttonPressed	-	-	alarm	alarm	buzzerOn OledBlink	count := count + 1 $s(t) := 0$
-	count = 2	-	snooze	normal	-	$s(t) := 0$ count := 0 $Ta := 3599$
-	count = 1	$s(t) > 5$	snooze	snooze	OledBlink	$s(t) := 0$ count := 0
-	-	$s(t) > 60$	snooze	alarm	buzzerOn OledBlink	$s(t) := 0$
buttonPressed	-	-	snooze	snooze	OledBlink	count := count + 1