

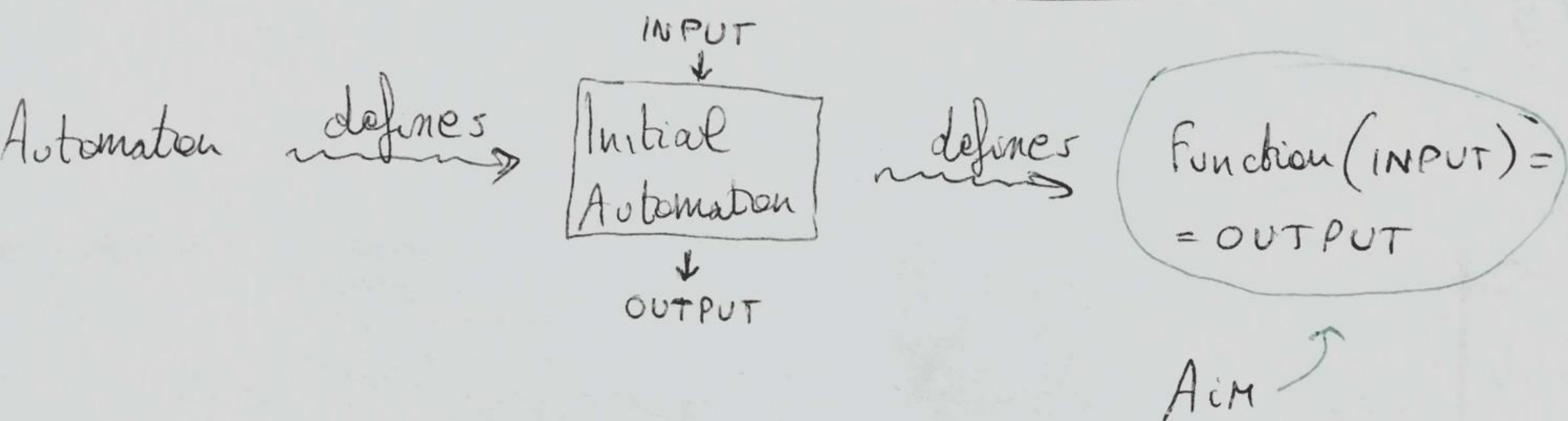
GROUPS OF AUTOMATA

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Automata are a MODEL OF COMPUTATION:



1st part:

- (1) INPUT and OUTPUT
- (2) Automata and their visualization
- (3) Initial Automata and "actions"

Then we will analyse the functions in detail.

Finally: interesting examples

INPUT and OUTPUT

①

• X = finite set of symbols

Ex] ~~X~~ = $\{0, 1\}$

• X^* = set of words of $X = \{x_1 \cdot \dots \cdot x_n \mid x_i \in X, n \in \mathbb{N}\} = \{\text{finite strings of } X\}$

• $|w| = |x_1 \cdot \dots \cdot x_n| := n = \text{length of } w$

Monoid Structure

$\phi := \text{empty word} = \text{identity respect to } \cdot$

$$(x_1 \cdot \dots \cdot x_n) \cdot (y_1 \cdot \dots \cdot y_m) = x_1 \cdot \dots \cdot x_n y_1 \cdot \dots \cdot y_m$$

Ex] 001 \cdot 101 = 001101

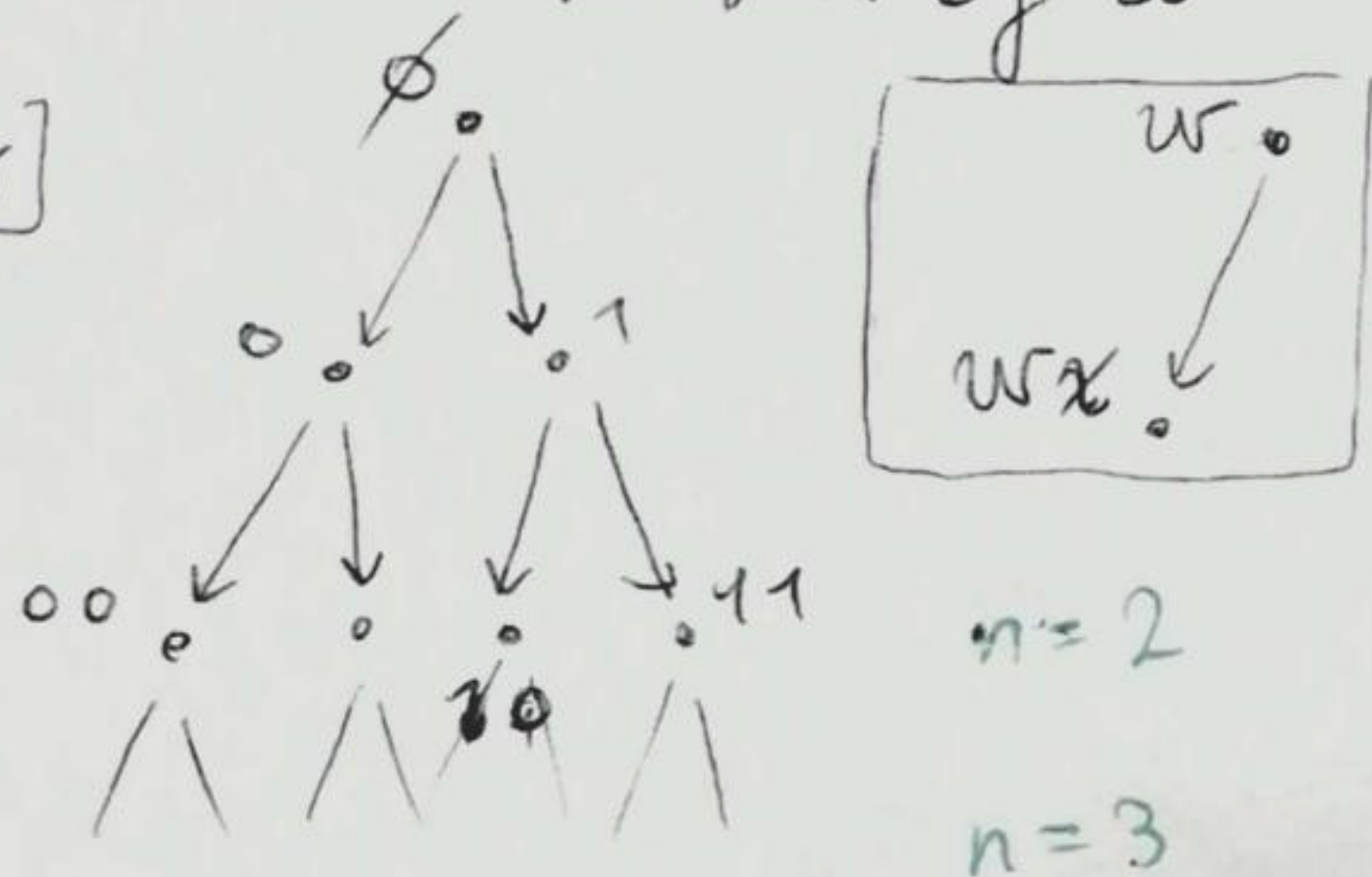
TREE STRUCTURE

$\phi = \text{root}$

v is son of w whenever $v = w x$

$$\underbrace{w}_{\text{parent}} \underbrace{x}_{\text{child}}$$

Ex]



Observation:

$$X^n = \{\text{words of length } n\}$$

\downarrow

$$= n\text{-th level of } X$$

AUTOMATA

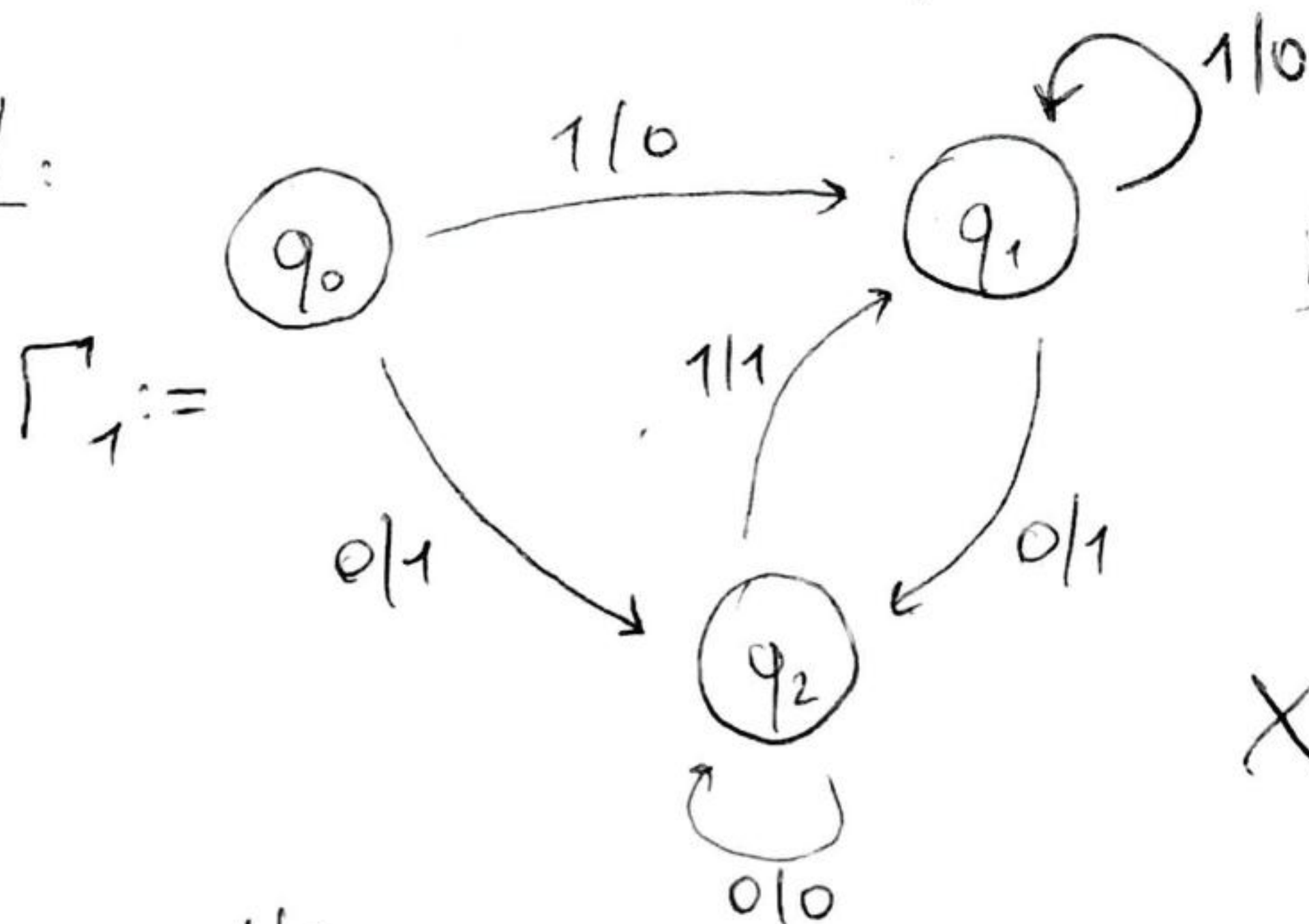
2a

DEF A SYNCHRONOUS INVERTIBLE AUTOMATON \mathcal{A} is a tuple $\mathcal{A} = (X, Q, \lambda, \pi)$ where

- (1) X is a finite set, the INPUT and OUTPUT ALPHABET
- (2) Q is a set, the SET OF STATES
- (3) $\pi : Q \times X \rightarrow Q$ is the TRANSITION FUNCTION
- (4) $\lambda : Q \times X \rightarrow X$ is a function such that $\lambda(q; \cdot) : X \rightarrow X$ is bijective (\Rightarrow permutation), and it's called OUTPUT FUNCTION

[From now on AUTOMATON = SYNC. INV. AUTOMATON]

Example 1:



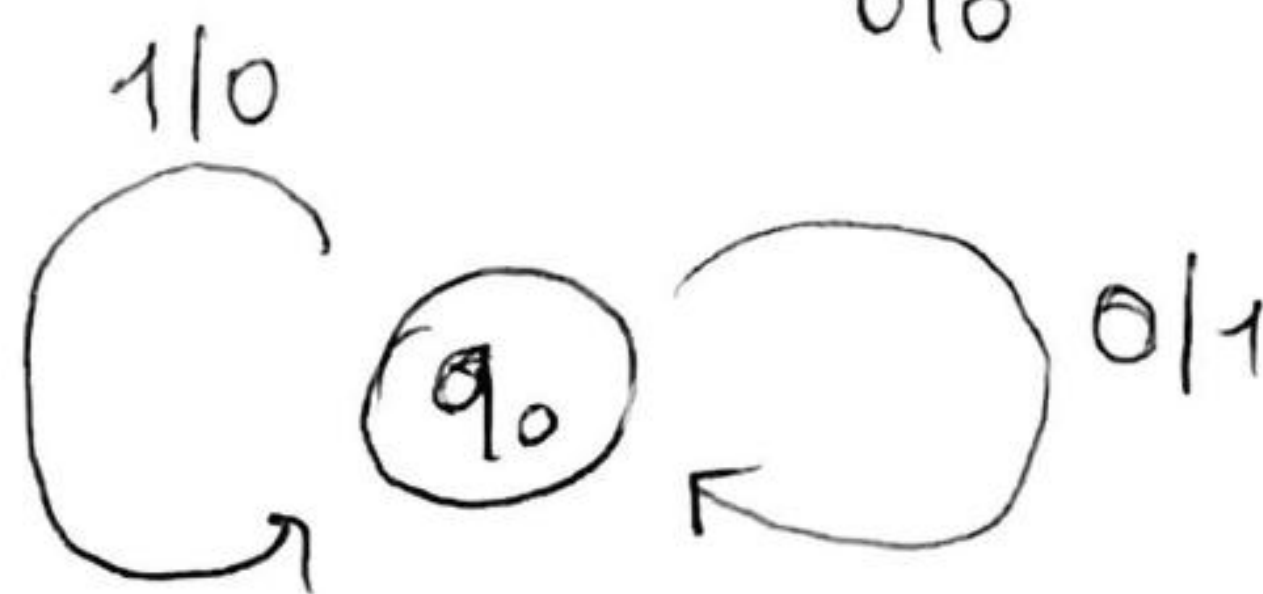
Notation:

INPUT LETTER / OUTPUT LETTER

$X = \{0, 1\}$

Ex. 2

$\Gamma_2 :=$



Extension of π and λ

(2B)

$$\pi(q, x) = q$$

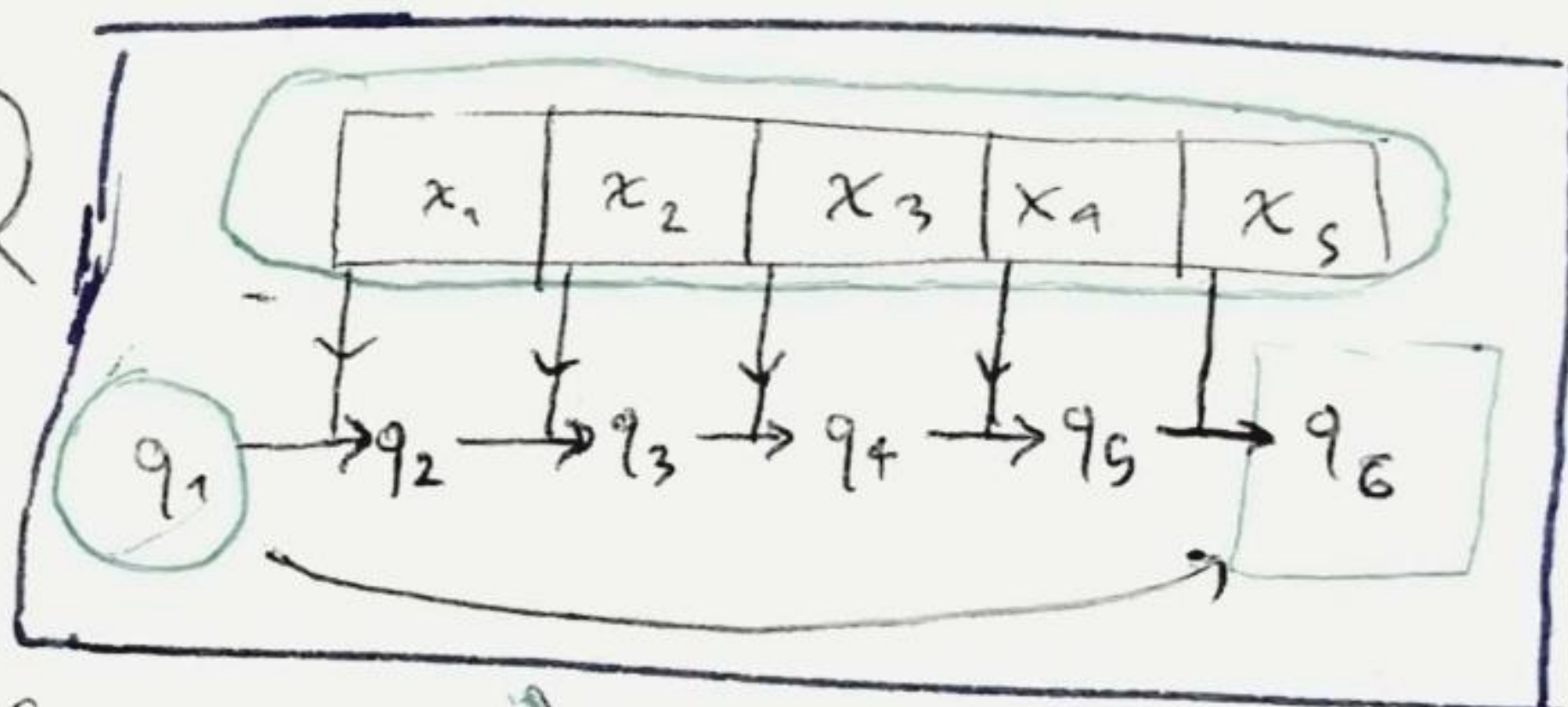
$$\pi: Q \times X \rightarrow Q$$

$$\lambda(q, x) = y$$

$$\lambda: Q \times X \rightarrow X$$

Recursive Extension:

$$\bar{\pi}: Q \times X^* \rightarrow Q$$



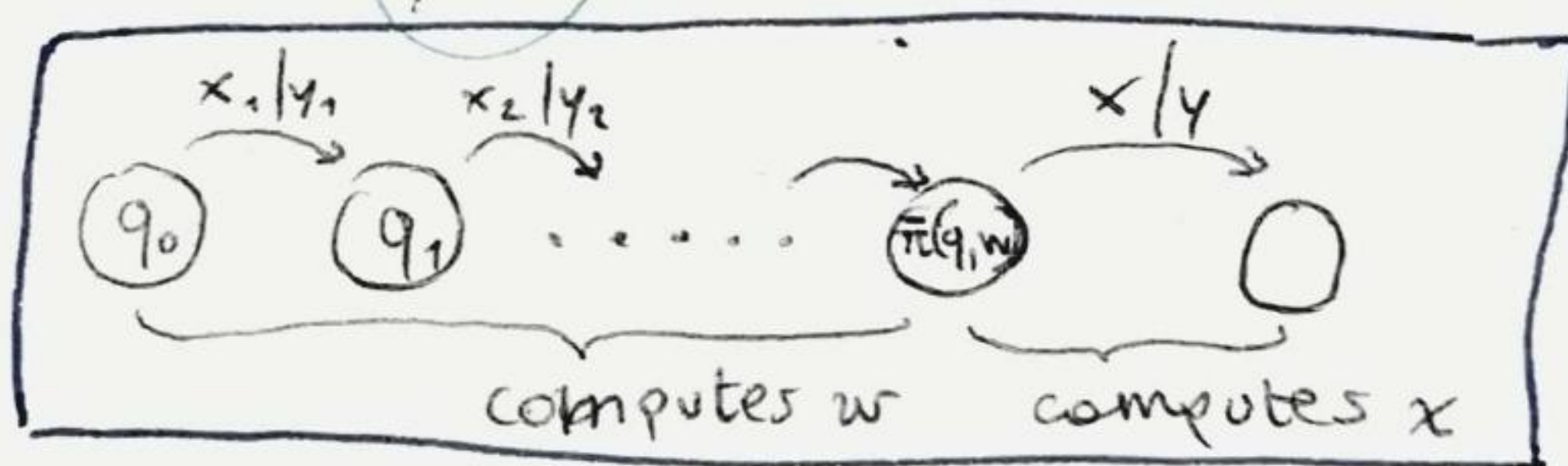
$$\bar{\pi}(q, \phi) := q$$

$$\bar{\pi}(q, w \cdot x) := \bar{\pi}(\bar{\pi}(q, w), x)$$

$\underbrace{w}_{\in X^*} \cdot \underbrace{x}_{\in X}$

Ex: page 2A

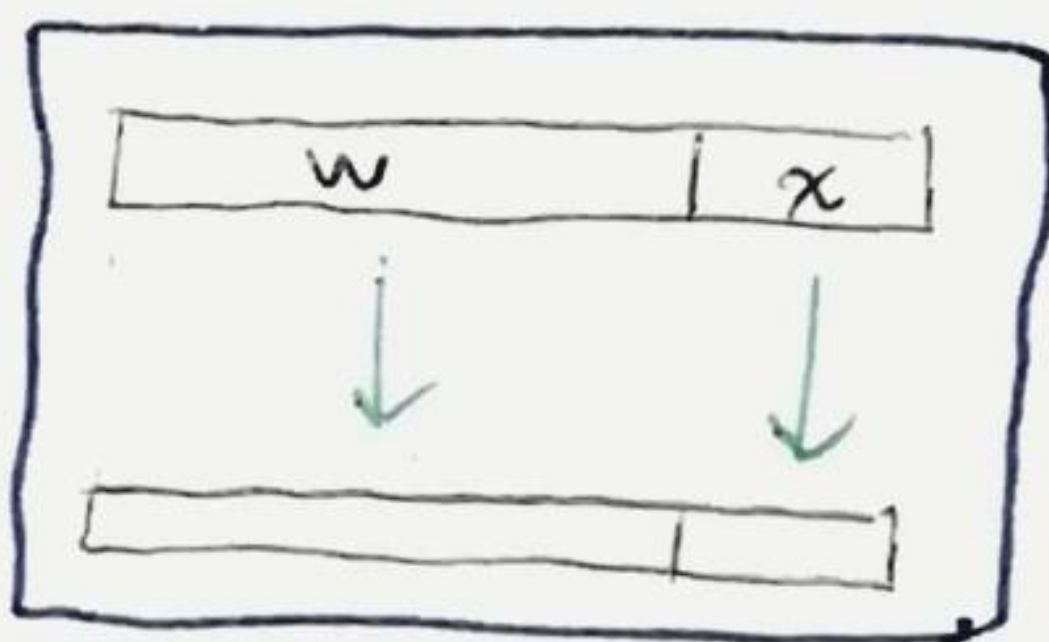
$$\bar{\lambda}: Q \times X^* \rightarrow X^*$$



$$\bar{\lambda}(q, \phi) := \phi$$

$$\bar{\lambda}(q, w \cdot x) := \bar{\lambda}(q, w) \cdot \bar{\lambda}(\bar{\pi}(q, w), x)$$

$\underbrace{\bar{\lambda}(q, w)}_{\in X^*} \cdot \underbrace{\bar{\lambda}(\bar{\pi}(q, w), x)}_{\in X}$



Notation: $\bar{\lambda}_q(w) := \bar{\lambda}(q, w)$

Ex: page 2A

DEF Given \mathcal{A} automaton, \mathcal{A}_{q_0} , with fixed INITIAL STATE q_0 , is called INITIAL AUTOMATON

NOTE (1) \mathcal{A}_{q_0} defines $\bar{\lambda}_{q_0}: X^* \rightarrow X^*$, called the ACTION of \mathcal{A}_{q_0}

(2) λ_q is bijective $\Rightarrow \bar{\lambda}_q$ is bijective
(on X) (on X^*)

Ex: page 2A

Povzetek:

Automation \mathcal{A} \rightsquigarrow Initial Automaton \mathcal{A}_{q_0} \rightsquigarrow action $\bar{\lambda}_{q_0}$
($X^* \rightarrow X^*$)

Note $\forall \mathcal{A}$ we can define $|Q|$ different \mathcal{A}_q

Ex (1) Page 2A: $(\Gamma_1) \rightsquigarrow \begin{cases} (\Gamma_1)_{q_0} \rightsquigarrow \bar{\lambda}_{q_0} \\ (\Gamma_1)_{q_1} \rightsquigarrow \bar{\lambda}_{q_1} \\ (\Gamma_2)_{q_2} \rightsquigarrow \bar{\lambda}_{q_2} \end{cases}$

(2) $(\Gamma_2) \rightsquigarrow (\Gamma_2)_q \rightsquigarrow \bar{\lambda}_q$

DEF $f: X^* \rightarrow X^*$ is synchronous automatic if is definable as the action of some initial automaton A_{q_0} , i.e. $(\exists q_0) f = \bar{\lambda}_{q_0}$.

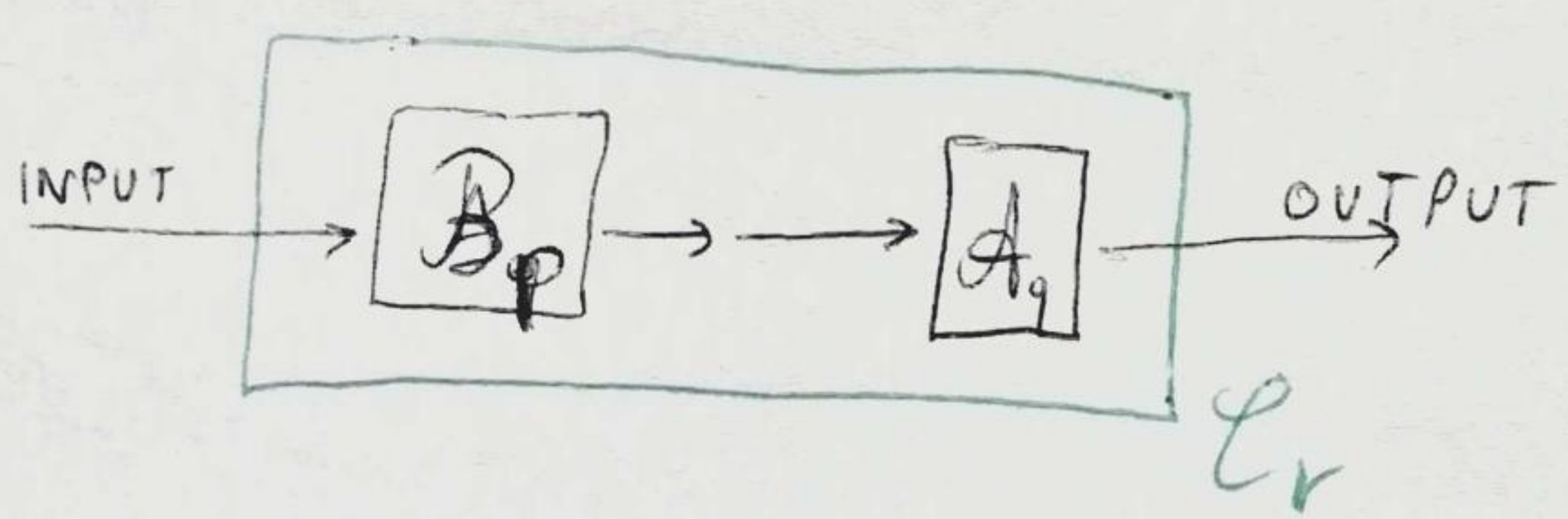
DEF $S := \{f: X^* \rightarrow X^* \mid f \text{ is synchronous automatic}\}$

Note $f \in S \Rightarrow f = \bar{\lambda}_{q_0} \Rightarrow f$ is bijective

We want to study S

Composition Lemma Given A_q and B_p , initial automata on X , $\exists C_r$, initial automaton, such that:

$$\left(\text{Action of } C_r \right) = \left(\text{Action of } A_q \right) \circ \left(\text{Action of } B_p \right)$$



$\Rightarrow S$ is closed under composition!

Similarly we have:

$$[f \in S \Rightarrow f^{-1} \in S]$$

$$\Rightarrow (id: X^* \rightarrow X^*) \in S$$

$\Rightarrow (S, \circ)$ is a group

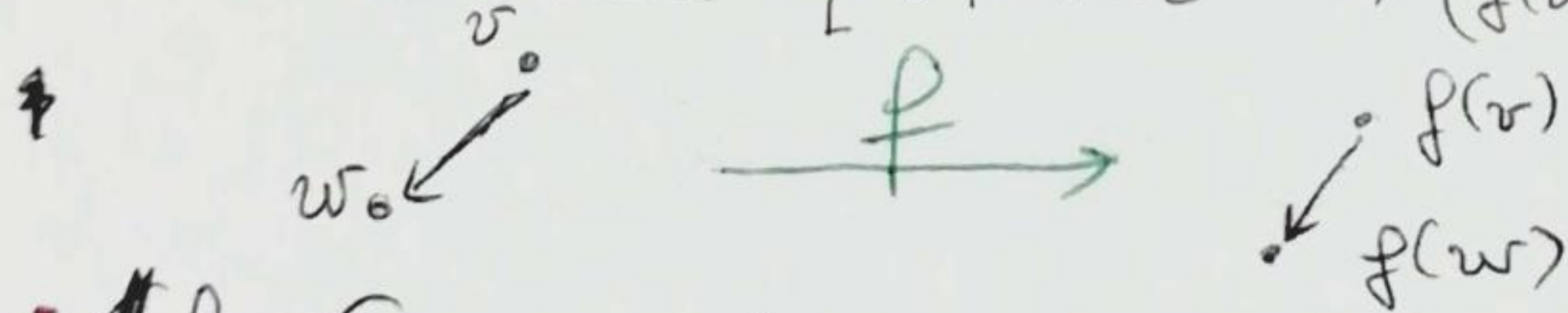
CHARACTERIZATION OF THE ACTIONS OF AUTOMATA

Povzetek:

Automation \rightsquigarrow Initial automaton $\rightsquigarrow \hat{I}_{q_0} : X^* \rightarrow X^*$

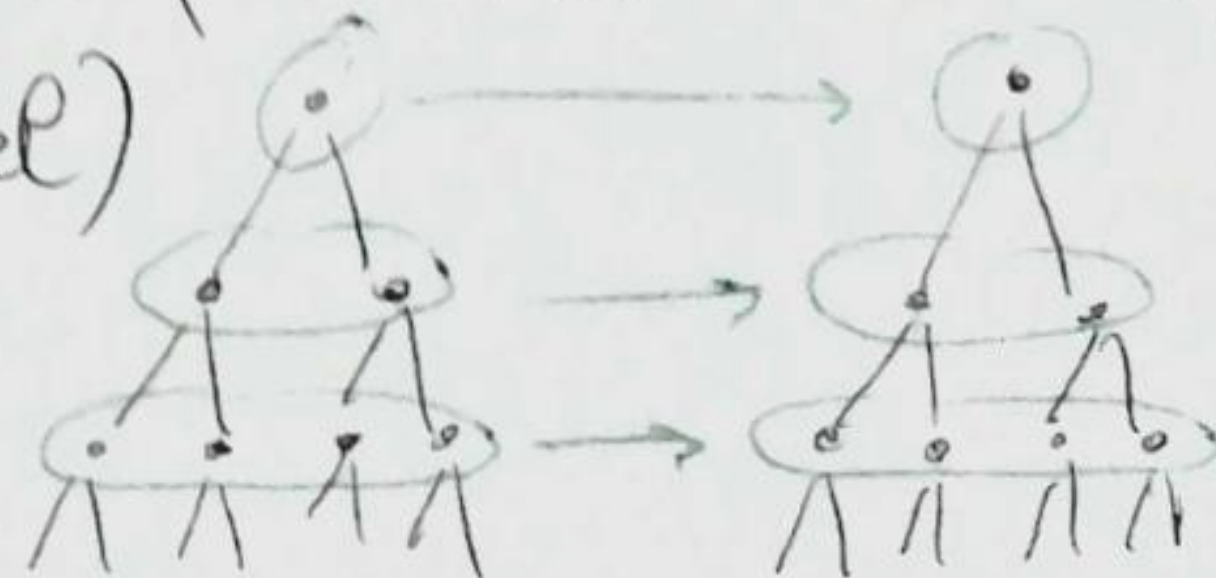
$$S := \{ f : X^* \rightarrow X^* \mid f \text{ is the action of some } A_{q_0} \}$$

Remark • Given $G = (V, E)$ graph, $f : V \rightarrow V$ is said to be a graph-homomorphism if preserve the adjacencies $[(v, w) \in E \Rightarrow (f(v), f(w)) \in E]$



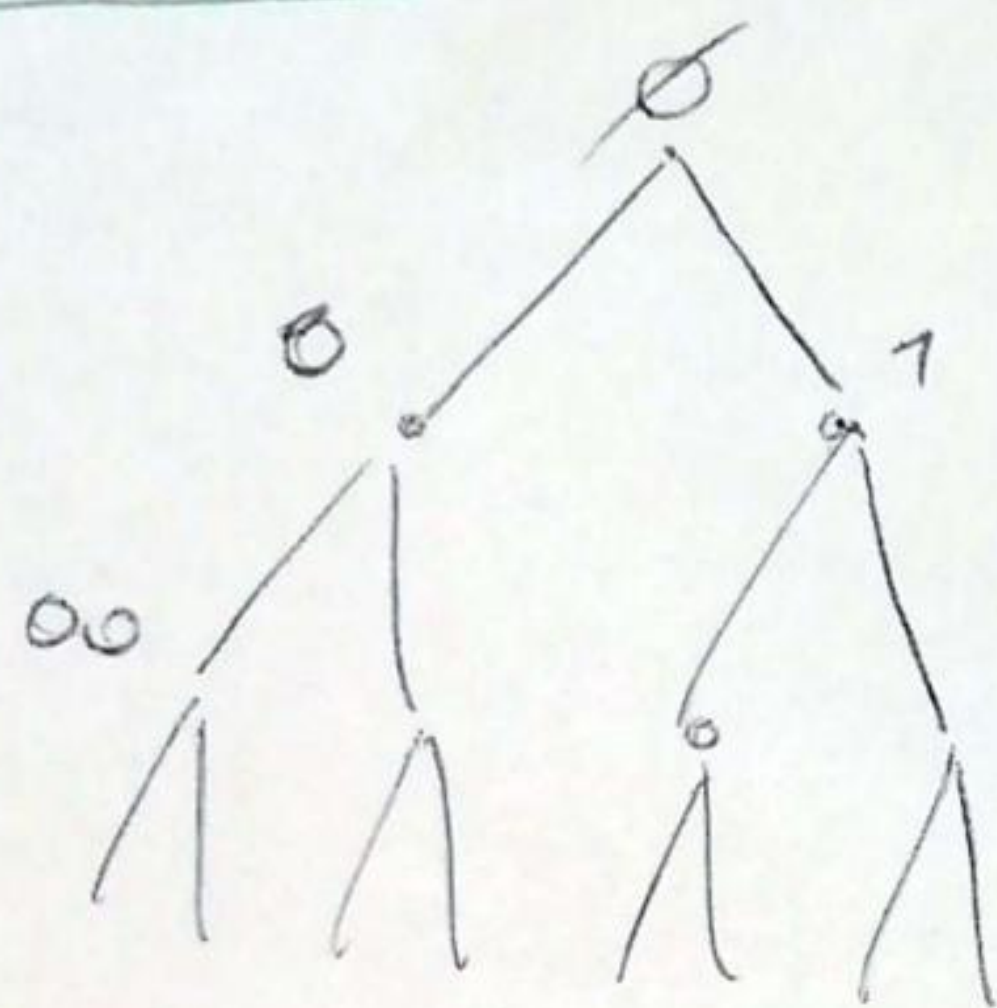
• If G is a tree, f is said to be a graph-homomorphism that preserves the root if (1) is a graph-homomorphism and if (2) $f(r) = r$, where r is the root of G

Note If f is a graph-hom. that preserves the root, $f(n\text{-th level of } G) \subseteq (n\text{-th level})$



Proposition f is synch. automatic if and only if f is a graph-homomorphism that preserves the root on X^* (53)

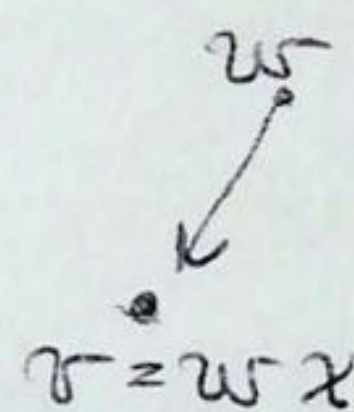
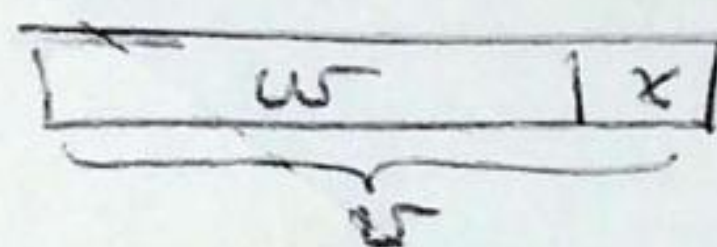
Observation Remembering that X^* is a tree, what does it mean to be a graph-homomorphism that preserve the root on X^* ?



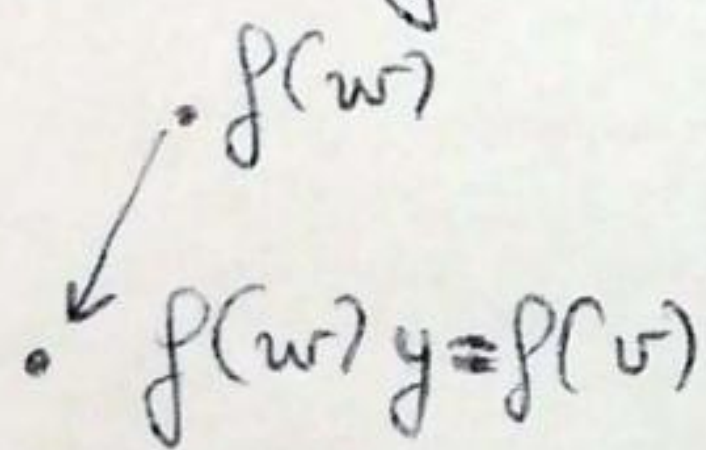
• Given a f with this property condition $f(r) = r$ means

$$f(\epsilon) = \epsilon$$

• The condition of being a map homomorphism? In X^* , v is son of w if and only if $v = wx$



So if we want $f(v)$ to be son of $f(w)$ means $f(v) = f(w)y$ for some $y \in X$.



Dokaz (\Rightarrow)

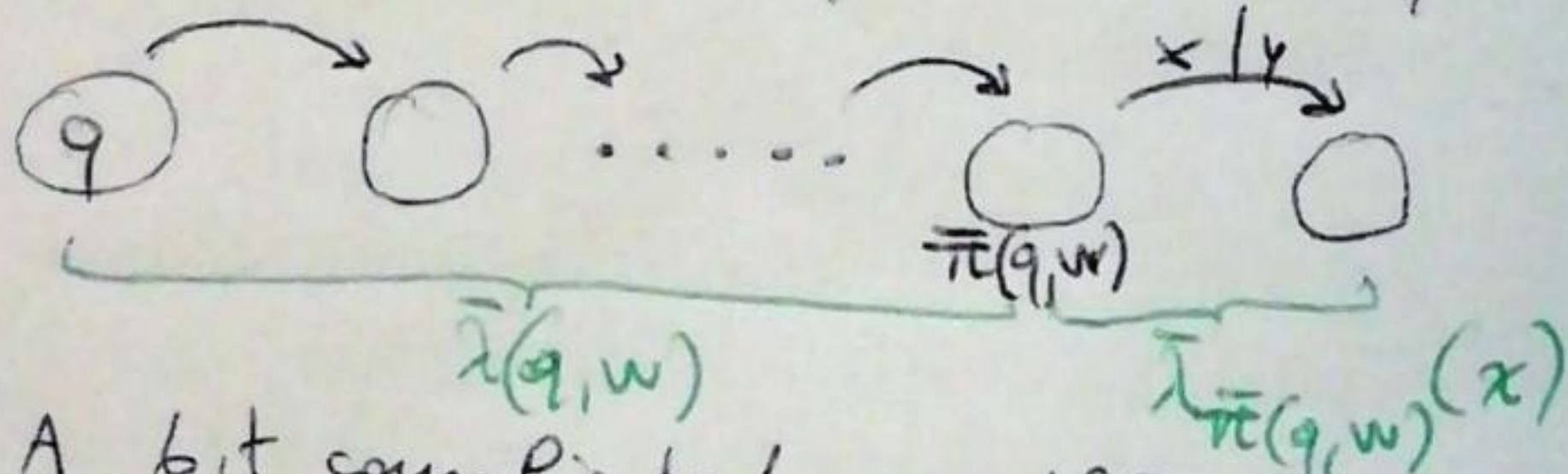
Given f synch. autom, we have $f = \bar{\lambda}_q$

For some action of some q .

(1) $f(\epsilon) = \bar{\lambda}_q(\epsilon) = \epsilon$ ✓

(2) Given $v = wx$ (v son of w) we have:

$$f(v) = f(wx) = \bar{\lambda}_q(wx) = \bar{\lambda}_q(w) \cdot \bar{\lambda}_{\pi(q,w)}(x) = f(w)y \quad y \in X$$



(\Leftarrow) A bit complicated, we'll not see it

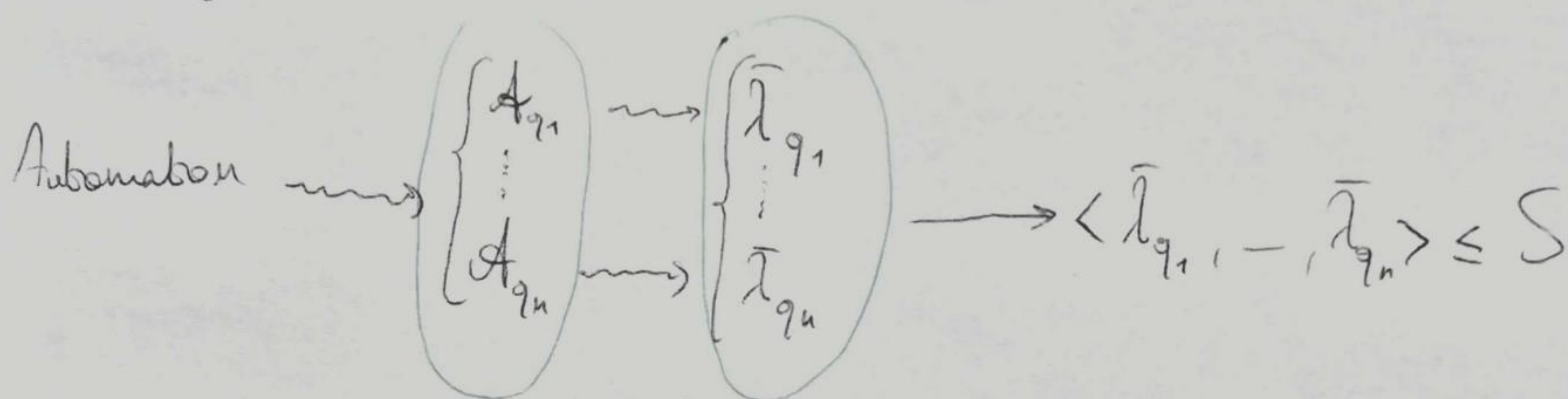
Corollary $S = \{\text{bijective graph-homom. that preserve } \epsilon \text{ on } X^*\}$ □

DEF Given \mathcal{A} automaton we can define $|Q|$ initial automata \mathcal{A}_q , so $|Q|$ actions $\bar{\lambda}_q \in S$.

(6)

The group generated by \mathcal{A} is defined as:

$$G(\mathcal{A}) := \langle \{\bar{\lambda}_q \mid q \in Q \text{ of } \mathcal{A}\} \rangle \leq S$$

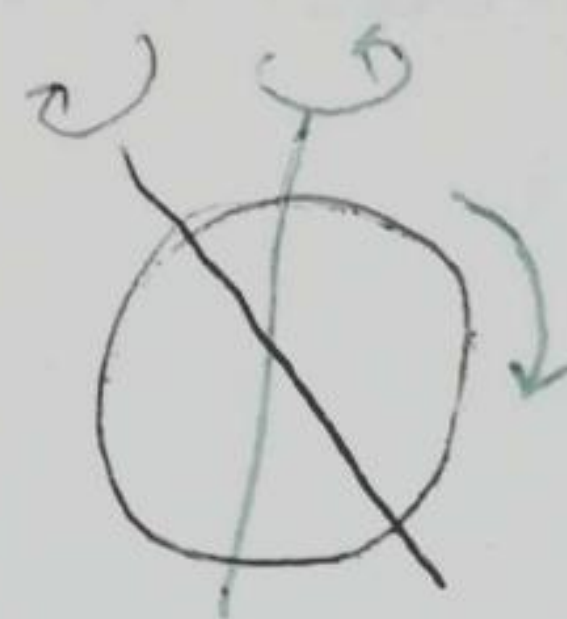


Ex: page 2A, (1) Γ_1 defines $G(\Gamma_1) := \langle \bar{\lambda}_{q_0}, \bar{\lambda}_{q_1}, \bar{\lambda}_{q_2} \rangle$

Interesting Results and Examples

Proposition Given $X = \{0, 1\}$, and \mathcal{A} , 2-state automaton on X , $G(\mathcal{A})$ must be isomorphic to one of these groups:

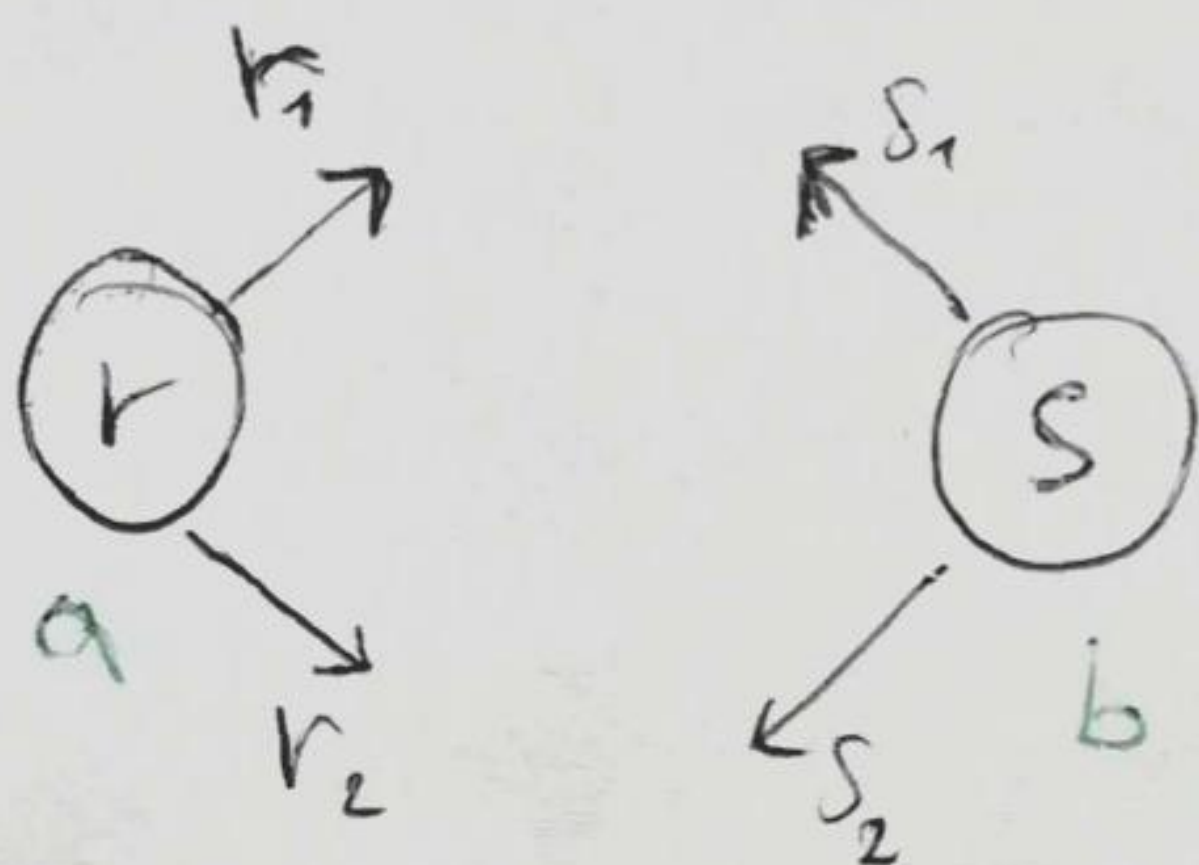
- (1) $\{1_G\}$
- (2) \mathbb{Z}_2
- (3) $\mathbb{Z}_2 \oplus \mathbb{Z}_2$
- (4) \mathbb{Z}
- (5) $D_\infty = \text{Infinite dihedral group} = \{\text{symm. of the circle}\}$
- (6) $\mathbb{Z} \wr \mathbb{Z}_2 = \text{lamplighter group}$



Sketch of proof: Q , the set of states

(7)

$$Q = \{r, s\}, \quad X = \{0, 1\}. \quad \mathcal{A} = (X, Q, \pi, \lambda)$$



• $\lambda_s, \lambda_r: X \rightarrow X$ are permutations of a 2-element set $X \Rightarrow \lambda_s, \lambda_r \in S_2$,
 $S_2 = \{id = 1, \sigma\}$

~~id = 1~~ $\begin{cases} \sigma(0) = 1 \\ \sigma(1) = 0 \end{cases}$

• each arrow in $\{r_1, r_2, s_1, s_2\}$ can ~~not~~ point on an element of $Q = \{r, s\}$

So all the possible \mathcal{A} , with $Q = \{r, s\}$, $X = \{0, 1\}$ are the ones in which $\lambda_s, \lambda_r \in S_2$ (uniquely determined λ), and $r_1, r_2, s_1, s_2 \in \{r, s\}$

(uniquely determines π) \Rightarrow

$$\Rightarrow \text{they are } \underset{\lambda_s}{2} \cdot \underset{\lambda_r}{2} \cdot \underset{r_1}{2} \cdot \underset{r_2}{2} \cdot \underset{s_1}{2} \cdot \underset{s_2}{2} = 2^6.$$

Analysing each case we get $[G(\mathcal{A}) \text{ is isomorphic to one case of the latter cases}]$.

Interesting group :

$$\mathbb{Z} \wr \mathbb{Z}_2 := (\mathbb{Z} \times \mathbb{Z}_2^{(\mathbb{Z})}, \star)$$

- $\mathbb{Z}_2^{(\mathbb{Z})} := \{ (b_i)_{i \in \mathbb{Z}} \mid b_i \in \mathbb{Z}_2 = \{0, 1\}, b_i = 1 \text{ just for a finite set of indexes } I \}$

Practically:



Infinite dark road \mathbb{Z}

indexes of the ~~open~~ lamps turned on (indexes in I)

Ex] The previous represented element is

$((\tilde{b}_i)_{i \in \mathbb{Z}})$, where $b_{-5}, b_{-2}, b_2 = 1$.

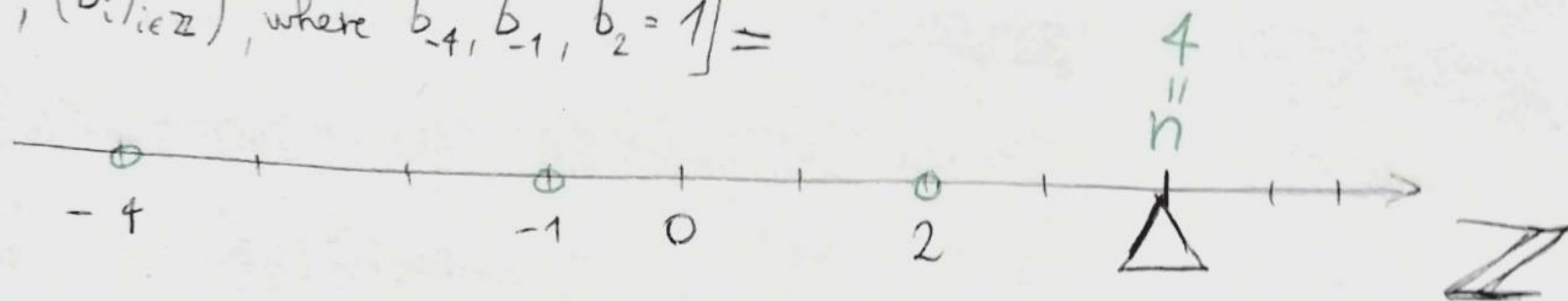
[We can sign $(\tilde{b}_i)_{i \in \mathbb{Z}}$ with $\{-5, -2, 2\} = I$]

- \star is not a direct product!

$$\begin{aligned} (n_1, (b_i)_{i \in \mathbb{Z}}) \star (n_2, (q_i)_{i \in \mathbb{Z}}) &:= \\ &= (\textcircled{n_1} + n_2, (b_i + q_{i + \textcircled{n_1}})_{i \in \mathbb{Z}}) \end{aligned}$$

Visualization:

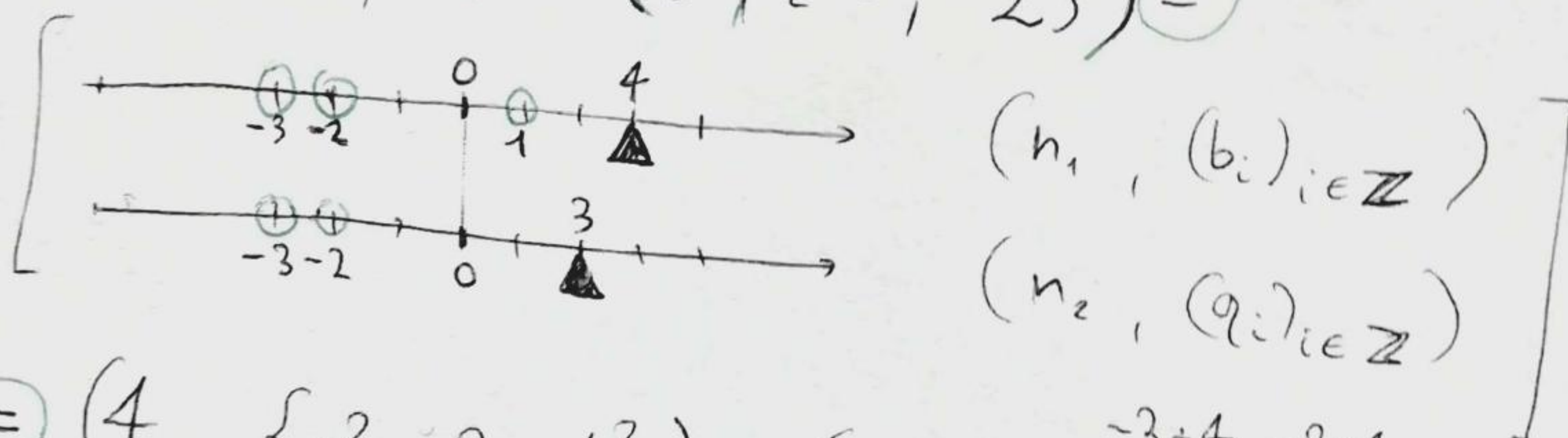
- OF an element $(n, (b_i)_{i \in \mathbb{Z}}) \in \mathbb{Z} \times \mathbb{Z}_2^{(\mathbb{Z})}$
 $[(4, (b_i)_{i \in \mathbb{Z}}), \text{ where } b_{-4}, b_{-1}, b_2 = 1] =$



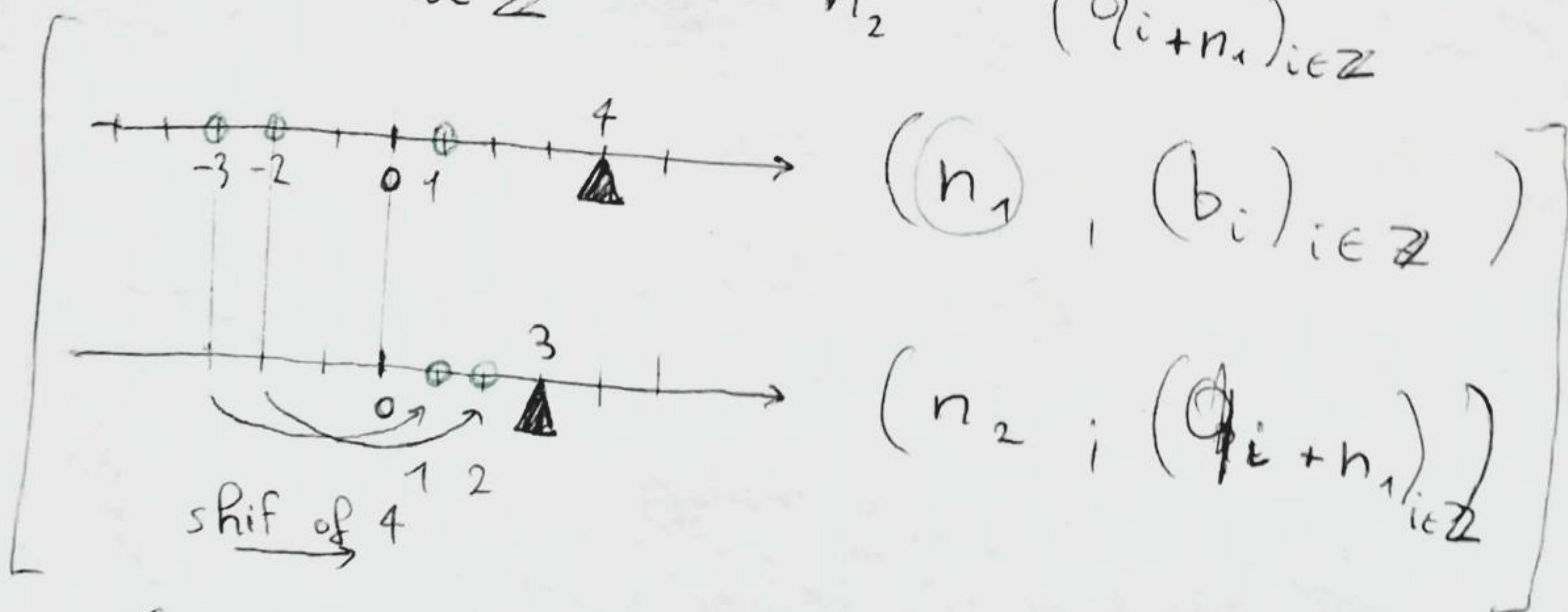
n = position of the "camp light" on the infinite road

- OF the product \star :

$$\left(4, \{ -3, -2, 1 \} \right) \star \left(3, \{ -3, -2 \} \right) =$$



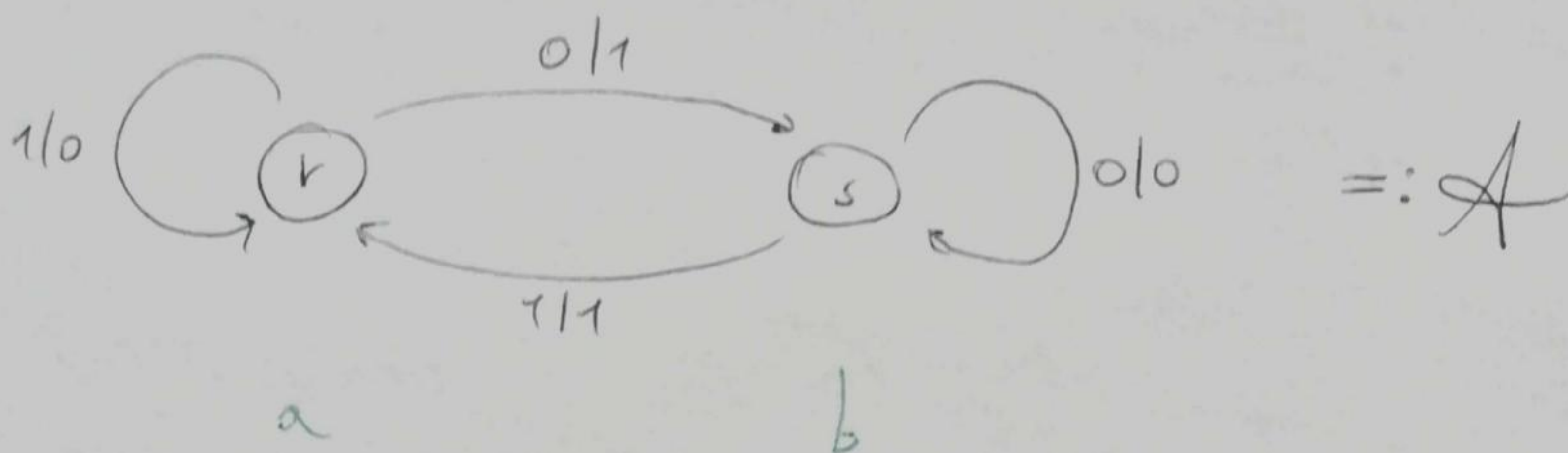
$$= \left(4, \{ -3, -2, -1 \} \right) + \left(3, \{ 1, 2 \} \right) =$$



$$= (4+3, \{ -3, -2, 2 \})$$

The automaton which defines $\mathbb{Z} \int \mathbb{Z}_2$:

(10)



$$a := \bar{\lambda}_r, \quad b := \bar{\lambda}_s$$

$$\mathbb{Z} \int \mathbb{Z}_2 = \langle a, b \rangle = G(\mathcal{A})$$

let's watch closer:

$$\begin{cases} a(0v) = 1b(v) \\ a(1v) = 0b(v) \end{cases}$$

$$\begin{cases} b(0v) = 0b(v) \\ b(1v) = 1a(v) \end{cases}$$

$$\lambda_r: X \rightarrow X$$

$$\lambda_s: X \rightarrow X$$

$$\lambda_r = \sigma \in S_2$$

$$\lambda_s = \text{id} \in S_2$$

$$\Rightarrow \begin{matrix} \bar{b}^{-1} \\ \vdots \\ X^* \\ \downarrow \\ X^p \end{matrix} = \begin{cases} \bar{b}^{-1}(0v) = 0\bar{b}^{-1}(v) \\ \bar{b}^{-1}(1v) = 1\bar{a}^{-1}(v) \end{cases}$$

$$c := b^{-1} \cdot a = a \circ b^{-1}$$

$$\begin{cases} c(0v) = a \circ b^{-1}(0v) = a(0 \underbrace{b^{-1}(v)}^{\text{id}}) = 1 \cdot \underbrace{b \cdot b^{-1}(v)}^{\text{id}} = 1v \\ \underline{c(1v)} = a \circ b^{-1}(1v) = a(1 \underbrace{b^{-1}(v)}^{\text{id}}) = 0 \cdot \underbrace{b \cdot b^{-1}(v)}^{\text{id}} = 0v \end{cases}$$

• we see $\langle a, b \rangle = \langle \underbrace{b^{-1}a}_{\underline{c}}, b \rangle = \langle \underline{c}, b \rangle = G(\underline{A})$

• $\Sigma_2 = (X; +_{\Sigma_2})$

$$0+0=0$$

$$1+1=0$$

$$1+0=1$$

$$c(x_1 x_2 x_3 -) = (x_1 + 1) x_2 x_3 -$$

we search an explicit formula for b :

$$b(x_1 x_2 x_3 -) = y_1 y_2 y_3 - \quad y_n = ?$$

$$\begin{aligned} \text{we claim (A)} \quad b(x_1 x_2 - x_n \overset{(n+1)}{0} x_{n+2} -) &= \\ &= y_1 y_2 \dots y_n y_{n+1} b(x_{n+2} -) \end{aligned}$$

$$\begin{aligned} \text{(B)} \quad b(x_1 x_2 - x_n \overset{(n+1)}{1} x_{n+2} -) &= \\ &= y_1 y_2 - y_n y_{n+1} a(x_{n+2} -) \end{aligned}$$

Proof

(A) Watch diagram of A . Whenever we encounter a "0", b acts on the next letter

(B) Analogous

(12)

We claim $b(x_1 x_2 \dots x_n \text{---}) = x_1 \underbrace{(x_2 + x_1)}_{y_2} \text{---} \underbrace{(x_n + x_{n-1})}_{y_n} \text{---}$

Proof: For induction on n .

$n=1$ We set $x_0 = 0 \Rightarrow y_1 = x_1 = x_1 + 0 = x_1 + x_0$

$n \rightarrow n+1$ 4 cases: $x_n, x_{n+1} \in \{00, 01, 10, 11\}$

Case 00: $y_n = \cancel{x_n} + \cancel{x_{n+1}} ; y_{n+1} = ?$

$$b(x_1 \text{---} x_{n-1} \overset{n}{0} \overset{(n+1)}{0} x_{n+2} \text{---}) \stackrel{(4)}{=} y_1 \text{---} y_n b(0 x_{n+2} \text{---}) =$$

$$= y_1 \text{---} y_n 0 y_{n+2} \text{---}$$

$$y_{n+1} = 0 = 0 + 0 = x_n + x_{n+1}$$

The other cases are analogous ✓

$$\Rightarrow c(x_1 x_2 x_3 \text{---}) = \underbrace{(x_1 + 1)}_{\sigma(x_1)} x_2 x_3 \text{---}$$

$$b(x_1 x_2 x_3 \text{---}) = x_1 (x_2 + x_1) (x_3 + x_2) \text{---} =$$

$$= x_1 \quad x_2 \quad x_3 \quad x_4 \text{---} +$$

[shift to right]

$$x_1 \quad x_2 \quad x_3 \text{---}$$

It can be proved, with these formulas, that

$$\langle b, c \rangle = \mathbb{Z} \int \mathbb{Z}_2$$