Tspeed

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Sun Sep 8 2013 22:31:00

Contents

1	Nam	nespace	Index			1
	1.1	Names	space List		 	 1
2	Hier	archica	l Index			3
	2.1	Class I	Hierarchy		 	 3
3	Clas	s Index				5
	3.1	Class I	List		 	 5
4	File	Index				7
	4.1	File Lis	st		 	 7
5	Nam	nespace	Documer	ntation		9
	5.1	Tspeed	d Namespa	ace Reference	 	 9
		5.1.1	Typedef I	Documentation	 	 11
			5.1.1.1	FESpace_ptr	 	 11
			5.1.1.2	Force_ptr	 	 11
			5.1.1.3	Mesh_ptr	 	 11
		5.1.2	Enumera	ation Type Documentation	 	 11
			5.1.2.1	Bc	 	 11
		5.1.3	Function	Documentation	 	 11
			5.1.3.1	CTensorProduct	 	 11
			5.1.3.2	jacobi_polynomial	 	 11
			5.1.3.3	mat_dot	 	 11
			5.1.3.4	operator*	 	 12
			5.1.3.5	operator*	 	 12
			5.1.3.6	operator*	 	 12
			5.1.3.7	operator*	 	 12
			5.1.3.8	operator*	 	 12
			5.1.3.9	operator*	 	 12
			5.1.3.10	operator+	 	 12
			5.1.3.11	operator+	 	 12
			5 1 3 12	operator±		12

ii CONTENTS

			5.1.3.13	operator+	2
			5.1.3.14	operator+	2
	5.2	Tspeed	d::Geo Nar	nespace Reference	2
		5.2.1	Function	Documentation	3
			5.2.1.1	operator*	3
			5.2.1.2	operator+	3
			5.2.1.3	operator+	3
			5.2.1.4	operator+	3
			5.2.1.5	operator	3
			5.2.1.6	operator	3
			5.2.1.7	operator	4
			5.2.1.8	operator<< 14	4
			5.2.1.9	operator<< 14	4
_	01	- D			_
6	6.1		mentation	1! Class Reference	
	0.1	6.1.1		Description	
		6.1.2		tor & Destructor Documentation	
		0.1.2	6.1.2.1	BaseMat	
			6.1.2.2	BaseMat	
			6.1.2.3	BaseMat	
			6.1.2.4	~BaseMat	
		6.1.3		Function Documentation	
		0.1.5	6.1.3.1	block	
			6.1.3.2	block	
			6.1.3.3		
			6.1.3.4	elem	
			6.1.3.5	elem	
			6.1.3.6	elem	
			6.1.3.7	nr	
			6.1.3.8	rowlnd	
			6.1.3.9	set_collnd	
			6.1.3.10	set rowlnd	
			6.1.3.11	setblock	
			6.1.3.12	size	
				vecMult	
		6.1.4		Data Documentation	
			6.1.4.1	M c	
			6.1.4.2	M m	
			6.1.4.3	M nc	
			3		_

CONTENTS

		6.1.4.4	M_nln	18
		6.1.4.5	M_nr	18
		6.1.4.6	$M_r \ldots \ldots \ldots \ldots \ldots$	18
6.2	Tspeed	d::Boundar	ryAdapted < N > Class Template Reference	18
	6.2.1	Detailed	Description	19
	6.2.2	Member	Enumeration Documentation	19
		6.2.2.1	anonymous enum	19
	6.2.3	Construc	tor & Destructor Documentation	19
		6.2.3.1	~BoundaryAdapted	19
		6.2.3.2	BoundaryAdapted	19
6.3	Tspeed	d::Dubiner	< N > Class Template Reference	19
	6.3.1	Detailed	Description	20
	6.3.2	Member	Enumeration Documentation	20
		6.3.2.1	anonymous enum	20
	6.3.3	Construc	tor & Destructor Documentation	20
		6.3.3.1	~Dubiner	20
		6.3.3.2	Dubiner	20
6.4	Tspeed	d::Dunavar	nt < N > Class Template Reference	20
	6.4.1	Detailed	Description	21
	6.4.2	Member	Typedef Documentation	21
		6.4.2.1	Mat	21
		6.4.2.2	Vec	21
		6.4.2.3	Vec2	21
	6.4.3	Member	Enumeration Documentation	21
		6.4.3.1	anonymous enum	21
		6.4.3.2	anonymous enum	21
	6.4.4	Construc	tor & Destructor Documentation	22
		6.4.4.1	Dunavant	22
6.5	Tspeed	d::Geo::Ed	ge Class Reference	22
	6.5.1	Detailed	Description	22
	6.5.2	Construc	tor & Destructor Documentation	22
		6.5.2.1	Edge	22
		6.5.2.2	Edge	23
		6.5.2.3	Edge	23
		6.5.2.4	~Edge	23
	6.5.3	Member	Function Documentation	23
		6.5.3.1	length	23
		6.5.3.2	normal	23
		6.5.3.3	operator=	23
6.6	Tspeed	d::Entity Cl	lass Reference	23

iv CONTENTS

	6.6.1	Detailed I	Description	24
	6.6.2	Member ³	Typedef Documentation	25
		6.6.2.1	$Id \ldots \ldots$	25
	6.6.3	Construc	tor & Destructor Documentation	25
		6.6.3.1	Entity	25
	6.6.4	Member I	Function Documentation	25
		6.6.4.1	bcld	25
		6.6.4.2	bold	25
		6.6.4.3	$id \ldots \ldots$	25
		6.6.4.4	$id \ldots \ldots$	25
		6.6.4.5	reg	25
		6.6.4.6	reg	26
		6.6.4.7	unassignedBc	26
		6.6.4.8	unassignedId	26
		6.6.4.9	unassignedReg	26
	6.6.5	Member I	Data Documentation	26
		6.6.5.1	M_bcld	26
		6.6.5.2	$M_id \ \ldots \ldots$	26
		6.6.5.3	M_reg	26
6.7	Tspeed	d::FESpace	e< N, Q, S > Class Template Reference	27
	6.7.1	Detailed I	Description	28
	6.7.2	Construc	tor & Destructor Documentation	28
		6.7.2.1	FESpace	28
		6.7.2.2	~FESpace	28
	6.7.3	Member I	Function Documentation	28
		6.7.3.1	b_edge	28
		6.7.3.2	base_invmass	28
		6.7.3.3	base_mass	29
		6.7.3.4	field_out	29
		6.7.3.5	g_edge	29
		6.7.3.6	grad	29
		6.7.3.7	inverse_transform	30
		6.7.3.8	L2error	30
		6.7.3.9	loc_rhs	30
		6.7.3.10	mesh	31
		6.7.3.11	ne	31
		6.7.3.12	$nln \ \ldots $	31
		6.7.3.13	points_out	31
		6.7.3.14	quad	31
		6.7.3.15	shape	31

CONTENTS

	6.7.4	Member Data Documentation	31
		6.7.4.1 EIGEN_MAKE_ALIGNED_OPERATOR_NEW	31
6.8	Tspeed	:Force Class Reference	31
	6.8.1	Detailed Description	32
	6.8.2	Member Typedef Documentation	32
		6.8.2.1 SPVec	32
		6.8.2.2 Vec	32
	6.8.3	Constructor & Destructor Documentation	32
		6.8.3.1 Force	32
		6.8.3.2 Force	32
		6.8.3.3 ~Force	33
	6.8.4	Member Function Documentation	33
		6.8.4.1 eval	33
	6.8.5	Member Data Documentation	33
		6.8.5.1 M_f	33
6.9	Tspeed	:Gauss < N > Class Template Reference	33
	6.9.1	Detailed Description	33
	6.9.2	Member Typedef Documentation	34
		6.9.2.1 Mat	34
		6.9.2.2 Vec	34
		6.9.2.3 Vec2	34
	6.9.3	Member Enumeration Documentation	34
		6.9.3.1 anonymous enum	34
		6.9.3.2 anonymous enum	34
	6.9.4	Constructor & Destructor Documentation	34
		6.9.4.1 Gauss	34
6.10	Tspeed	:LeapFrog Class Reference	34
	6.10.1	Detailed Description	35
	6.10.2	Constructor & Destructor Documentation	35
		6.10.2.1 LeapFrog	35
	6.10.3	Member Function Documentation	35
		6.10.3.1 first_step	35
		6.10.3.2 step	35
6.11	Tspeed	:Matrices Class Reference	35
	6.11.1	Detailed Description	36
	6.11.2	Member Typedef Documentation	36
		6.11.2.1 SpMat	36
	6.11.3	Constructor & Destructor Documentation	36
		6.11.3.1 Matrices	36
		6.11.3.2 Matrices	36

vi CONTENTS

	6.11.4	Member I	Function Documentation	. 36
		6.11.4.1	getA	. 36
		6.11.4.2	getl	. 37
		6.11.4.3	getinvM	. 37
		6.11.4.4	getS	. 37
6.12	Tspeed	l::Mesh Cl	ass Reference	. 37
	6.12.1	Member	Typedef Documentation	. 38
		6.12.1.1	AlignedVecE	. 38
		6.12.1.2	AlignedVecP	. 38
		6.12.1.3	AlignedVecT	. 38
		6.12.1.4	size_type	. 38
	6.12.2	Construc	tor & Destructor Documentation	. 38
		6.12.2.1	Mesh	. 38
		6.12.2.2	\sim Mesh	. 38
	6.12.3	Member I	Function Documentation	. 38
		6.12.3.1	elements	. 39
		6.12.3.2	elements	. 39
		6.12.3.3	ne	. 39
		6.12.3.4	operator[]	. 39
		6.12.3.5	operator[]	. 39
		6.12.3.6	printallNeigh	. 39
		6.12.3.7	stats	. 39
	6.12.4	Member I	Data Documentation	. 40
		6.12.4.1	M_bed_map	. 40
6.13	Tspeed	l::MyMat C	Class Reference	. 40
	6.13.1	Detailed I	Description	. 40
	6.13.2	Construc	etor & Destructor Documentation	. 40
		6.13.2.1	MyMat	. 40
		6.13.2.2	MyMat	. 40
		6.13.2.3	MyMat	. 41
		6.13.2.4	MyMat	. 41
		6.13.2.5	~MyMat	. 41
	6.13.3	Member I	Function Documentation	. 41
		6.13.3.1	operator*	. 41
		6.13.3.2	operator+=	. 41
		6.13.3.3	operator+=	. 41
		6.13.3.4	operator=	. 41
		6.13.3.5	operator=	. 41
		6.13.3.6	sumtranspose	. 41
		6.13.3.7	symmetrize	. 41

CONTENTS vii

6.14	Tspeed	::MyMatBlockDia	Class Reference			 	 		41
	6.14.1	Detailed Descript	ion			 	 		42
	6.14.2	Constructor & De	structor Documentation	on		 	 		42
		6.14.2.1 MyMat	BlockDiag			 	 		42
		6.14.2.2 MyMat	BlockDiag			 	 		42
		6.14.2.3 MyMat	BlockDiag			 	 		42
		6.14.2.4 MyMat	BlockDiag			 	 		42
		6.14.2.5 ∼MyM	atBlockDiag			 	 		42
	6.14.3	Member Function	Documentation			 	 		42
		6.14.3.1 operate	or=			 	 		42
		6.14.3.2 operate	or=			 	 		42
6.15	Tspeed	::MyMatMultiDim	< T > Class Template	Reference .		 	 		42
	6.15.1	Detailed Descript	ion			 	 		43
	6.15.2	Constructor & De	structor Documentatio	on		 	 		43
		6.15.2.1 MyMat	MultiDim			 	 		43
		6.15.2.2 ∼MyM	atMultiDim			 	 		43
		6.15.2.3 MyMat	MultiDim			 	 		43
		6.15.2.4 MyMat	MultiDim			 	 		43
	6.15.3	Member Function	Documentation			 	 		43
		6.15.3.1 compo	nent			 	 		43
		6.15.3.2 compo	nent			 	 		44
		6.15.3.3 operate	or*			 	 		44
		6.15.3.4 operate	or=			 	 		44
		6.15.3.5 symme	trize			 	 		44
		6.15.3.6 vecMu	t			 	 		44
	6.15.4	Friends And Rela	ted Function Docume	ntation		 	 		44
		6.15.4.1 operate	or*			 	 		44
		6.15.4.2 operate	or+			 	 		44
		6.15.4.3 operate	or+			 	 		44
6.16	Tspeed	::MyMatMultiDimE	BlockDiag< T > Class	Template R	eference	 	 		45
	6.16.1	Detailed Descript	ion			 	 		45
	6.16.2	Constructor & De	structor Documentation	on		 	 		45
		6.16.2.1 MyMat	MultiDimBlockDiag .			 	 		45
		6.16.2.2 ∼MyM	atMultiDimBlockDiag			 	 		45
		6.16.2.3 MyMat	MultiDimBlockDiag .			 	 		45
		6.16.2.4 MyMat	MultiDimBlockDiag .			 	 		46
	6.16.3	Member Function	Documentation			 	 		46
		6.16.3.1 compo	nent			 	 		46
		6.16.3.2 compo	nent			 	 		46
		6.16.3.3 nr				 	 		46

viii CONTENTS

		6.16.3.4	operator*	 46
		6.16.3.5	operator=	 46
		6.16.3.6	vecMult	 46
	6.16.4	Friends A	And Related Function Documentation	 46
		6.16.4.1	operator*	 47
6.17	Tspeed	l::Paramet	ters Class Reference	 47
	6.17.1	Detailed I	Description	 47
	6.17.2	Construc	ctor & Destructor Documentation	 47
		6.17.2.1	~Parameters	 47
		6.17.2.2	Parameters	 47
	6.17.3	Member I	Function Documentation	 47
		6.17.3.1	avg_p	 47
		6.17.3.2	lambda	 48
		6.17.3.3	mu	 48
		6.17.3.4	rho	 48
		6.17.3.5	setp	 48
6.18	Tspeed	l::Geo::Poi	int Class Reference	 48
	6.18.1	Detailed I	Description	 50
	6.18.2	Construc	ctor & Destructor Documentation	 50
		6.18.2.1	Point	 50
		6.18.2.2	Point	 50
		6.18.2.3	Point	 50
		6.18.2.4	~Point	 50
	6.18.3	Member I	Function Documentation	 50
		6.18.3.1	norm	 50
		6.18.3.2	operator*	 50
			operator=	51
			toEig	51
			x	51
			x	51
			y	51
			y	51
	6.18.4	Friends A	And Related Function Documentation	 52
			dot	52
			operator*	52
			operator+	52
			operator+	52
			operator+	52
			operator-	53
		6.18.4.7	operator	 53

CONTENTS

		6.18.4.8 operator	3
6.19	Tspeed	I::PointWiseEntity Class Reference	3
	6.19.1	Detailed Description	4
	6.19.2	Constructor & Destructor Documentation	4
		6.19.2.1 ~PointWiseEntity	4
	6.19.3	Member Function Documentation	4
		6.19.3.1 elem	4
		6.19.3.2 M_add	4
		6.19.3.3 point	4
		6.19.3.4 shape	5
		6.19.3.5 size	5
	6.19.4	Member Data Documentation	5
		6.19.4.1 M_ie	5
		6.19.4.2 M_nel	5
		6.19.4.3 M_relp	5
		6.19.4.4 M_shape	5
6.20	Tspeed	I::PointWiseForce Class Reference	5
	6.20.1	Detailed Description	6
	6.20.2	Constructor & Destructor Documentation	6
		6.20.2.1 PointWiseForce	6
		6.20.2.2 ~PointWiseForce	6
	6.20.3	Member Function Documentation	6
		6.20.3.1 eval	6
6.21	Tspeed	I::QuadratureRule < N > Class Template Reference	7
	6.21.1	Detailed Description	8
	6.21.2	Member Typedef Documentation	8
		6.21.2.1 Mat	8
		6.21.2.2 Vec	8
		6.21.2.3 Vec2	8
	6.21.3	Constructor & Destructor Documentation	8
		6.21.3.1 QuadratureRule	8
		6.21.3.2 ~QuadratureRule	8
	6.21.4	Member Function Documentation	8
		6.21.4.1 edge_n	9
		6.21.4.2 edge_nodes	9
		6.21.4.3 edge_weights	9
		6.21.4.4 eweight	9
		6.21.4.5 inode	9
		6.21.4.6 int_n	0
		6.21.4.7 int_nodes	0

X CONTENTS

		6.21.4.8	int_weights	60
		6.21.4.9	iweight	60
		6.21.4.10	nqn2d	60
	6.21.5	Member [Data Documentation	60
		6.21.5.1	EIGEN_MAKE_ALIGNED_OPERATOR_NEW	60
		6.21.5.2	M_node_1D	60
		6.21.5.3	M_node_2D	60
		6.21.5.4	M_nqn_1D	60
		6.21.5.5	M_nqn_2D	61
		6.21.5.6	M_w_1D	61
		6.21.5.7	M_w_2D	61
6.22	Tspeed	I::Receiver	s Class Reference	61
	6.22.1	Detailed [Description	61
	6.22.2	Construct	or & Destructor Documentation	61
		6.22.2.1	Receivers	61
		6.22.2.2	Receivers	62
	6.22.3	Member F	Function Documentation	62
		6.22.3.1	add	62
		6.22.3.2	write	62
6.23	Tspeed	I::ShapeFu	unction< N > Class Template Reference	62
	6.23.1	Detailed [Description	63
	6.23.2	Member E	Enumeration Documentation	63
		6.23.2.1	anonymous enum	63
		6.23.2.2	anonymous enum	64
	6.23.3	Construct	or & Destructor Documentation	64
		6.23.3.1	\sim ShapeFunction	64
		6.23.3.2	ShapeFunction	64
	6.23.4	Member F	Function Documentation	64
		6.23.4.1	grad	64
		6.23.4.2	phi	64
		6.23.4.3	phi	64
	6.23.5	Member [Data Documentation	65
		6.23.5.1	M_grad	65
		6.23.5.2	M_phi	65
6.24	Tspeed	I::TimeAdv	ance Class Reference	65
	6.24.1	Detailed [Description	66
	6.24.2	Construct	or & Destructor Documentation	67
		6.24.2.1	TimeAdvance	67
		6.24.2.2	\sim TimeAdvance	67
	6.24.3	Member F	Function Documentation	67

CONTENTS xi

		6.24.3.1 add_force	67
		6.24.3.2 eval_receivers	67
		6.24.3.3 first_step	67
		6.24.3.4 get_uh	67
		6.24.3.5 is_running	67
		6.24.3.6 set_dt	68
		6.24.3.7 set_initial_u	68
		6.24.3.8 set_initial_v	68
		6.24.3.9 set_penalty	68
		6.24.3.10 set_tmax	68
		6.24.3.11 step	68
		6.24.3.12 u	69
		6.24.3.13 update_variables	69
		6.24.3.14 write_receivers	69
	6.24.4	Member Data Documentation	69
		6.24.4.1 B	69
		6.24.4.2 f	69
		6.24.4.3 fold	69
		6.24.4.4 foldold	69
		6.24.4.5 initial_v	69
		6.24.4.6 M_completed	69
		6.24.4.7 M_dt	69
		6.24.4.8 M_f	69
		6.24.4.9 M_last_step	69
		6.24.4.10 M_mat	69
		6.24.4.11 M_ne	69
		6.24.4.12 M_nln	69
		6.24.4.13 M_penalty	69
		6.24.4.14 M_recv	69
		6.24.4.15 M_recv_written	69
		-	69
			69
			69
			69
6.25		Ü	70
		200 22 22 62	71
	6.25.2		71
			71
		· · · · · · · · · · · · · · · · · · ·	71
		6.25.2.3 Triangle	71

xii CONTENTS

			6.25.2.4 \sim Triangle	71
		6.25.3	Member Function Documentation	71
			6.25.3.1 all_edges	71
			6.25.3.2 all_pts	71
			6.25.3.3 detJ	72
			6.25.3.4 edg	72
			6.25.3.5 intriangle	72
			6.25.3.6 invJac	72
			6.25.3.7 invmap	72
			6.25.3.8 Jac	73
			6.25.3.9 map	73
			6.25.3.10 neigh	73
			6.25.3.11 neighedges	73
			6.25.3.12 operator=	73
			6.25.3.13 printNeigh	73
			6.25.3.14 pt	74
			6.25.3.15 setNeigh	74
			6.25.3.16 setNeighedges	74
		6.25.4	Member Data Documentation	74
			6.25.4.1 numVertices	74
7	File	Docume	entation 7	75
	7.1	Examp	les/src/Lamb.cpp File Reference	75
		7.1.1	Function Documentation	75
		7.1.1		75 75
	7.2		7.1.1.1 main	
	7.2		7.1.1.1 main	75
	7.2	Examp	7.1.1.1 main	75 75
	7.2	Examp	7.1.1.1 main 7 les/src/wedge.cpp File Reference 7 Function Documentation 7 7.2.1.1 main 7	75 75 75
	7.2	Examp 7.2.1	7.1.1.1 main 7 les/src/wedge.cpp File Reference 7 Function Documentation 7 7.2.1.1 main 7 7.2.1.2 wedge_init_param 7	75 75 75 75
		Examp 7.2.1	7.1.1.1 main 7 les/src/wedge.cpp File Reference 7 Function Documentation 7 7.2.1.1 main 7 7.2.1.2 wedge_init_param 7 ide/Dunavant.hpp File Reference 7	75 75 75 75
		Examp 7.2.1	7.1.1.1 main 7 les/src/wedge.cpp File Reference 7 Function Documentation 7 7.2.1.1 main 7 7.2.1.2 wedge_init_param 7 ide/Dunavant.hpp File Reference 7 Detailed Description 7	75 75 75 75 75
		Examp 7.2.1 lib/inclu 7.3.1	7.1.1.1 main 7 les/src/wedge.cpp File Reference 7 Function Documentation 7 7.2.1.1 main 7 7.2.1.2 wedge_init_param 7 Ide/Dunavant.hpp File Reference 7 Detailed Description 7 Function Documentation 7	75 75 75 75 76
		Examp 7.2.1 lib/inclu 7.3.1	7.1.1.1 main 7 les/src/wedge.cpp File Reference 7 Function Documentation 7 7.2.1.1 main 7 7.2.1.2 wedge_init_param 7 Ide/Dunavant.hpp File Reference 7 Detailed Description 7 Function Documentation 7 7.3.2.1 dunavant_degree 7	75 75 75 75 76 76
		Examp 7.2.1 lib/inclu 7.3.1	7.1.1.1 main 7 les/src/wedge.cpp File Reference 7 Function Documentation 7 7.2.1.1 main 7 7.2.1.2 wedge_init_param 7 ide/Dunavant.hpp File Reference 7 Detailed Description 7 Function Documentation 7 7.3.2.1 dunavant_degree 7 7.3.2.2 dunavant_order_num 7	75 75 75 75 76 76 77
		Examp 7.2.1 lib/inclu 7.3.1	7.1.1.1 main 7 les/src/wedge.cpp File Reference 7 Function Documentation 7 7.2.1.1 main 7 7.2.1.2 wedge_init_param 7 ide/Dunavant.hpp File Reference 7 Detailed Description 7 Function Documentation 7 7.3.2.1 dunavant_degree 7 7.3.2.2 dunavant_order_num 7 7.3.2.3 dunavant_rule 7	75 75 75 76 76 77
		Examp 7.2.1 lib/inclu 7.3.1	7.1.1.1 main 7 les/src/wedge.cpp File Reference 7 Function Documentation 7 7.2.1.1 main 7 7.2.1.2 wedge_init_param 7 Ide/Dunavant.hpp File Reference 7 Detailed Description 7 Function Documentation 7 7.3.2.1 dunavant_degree 7 7.3.2.2 dunavant_order_num 7 7.3.2.3 dunavant_rule 7 7.3.2.4 dunavant_rule_num 7	75 75 75 76 76 77 77
		Examp 7.2.1 lib/inclu 7.3.1	7.1.1.1 main 7 les/src/wedge.cpp File Reference 7 Function Documentation 7 7.2.1.1 main 7 7.2.1.2 wedge_init_param 7 ide/Dunavant.hpp File Reference 7 Detailed Description 7 Function Documentation 7 7.3.2.1 dunavant_degree 7 7.3.2.2 dunavant_order_num 7 7.3.2.3 dunavant_rule 7 7.3.2.4 dunavant_rule_num 7 7.3.2.5 dunavant_suborder 7	75 75 75 76 76 77 77
		Examp 7.2.1 lib/inclu 7.3.1	7.1.1.1 main 7 les/src/wedge.cpp File Reference 7 Function Documentation 7 7.2.1.1 main 7 7.2.1.2 wedge_init_param 7 ide/Dunavant.hpp File Reference 7 Detailed Description 7 Function Documentation 7 7.3.2.1 dunavant_degree 7 7.3.2.2 dunavant_order_num 7 7.3.2.3 dunavant_rule 7 7.3.2.4 dunavant_rule_num 7 7.3.2.5 dunavant_suborder 7 7.3.2.6 dunavant_suborder_num 7	75 75 75 76 76 77 77 77
		Examp 7.2.1 lib/inclu 7.3.1	7.1.1.1 main 7 les/src/wedge.cpp File Reference 7 Function Documentation 7 7.2.1.1 main 7 7.2.1.2 wedge_init_param 7 ide/Dunavant.hpp File Reference 7 Detailed Description 7 Function Documentation 7 7.3.2.1 dunavant_degree 7 7.3.2.2 dunavant_order_num 7 7.3.2.3 dunavant_rule 7 7.3.2.4 dunavant_rule_num 7 7.3.2.5 dunavant_suborder 7 7.3.2.6 dunavant_suborder_num 7 7.3.2.7 dunavant_suborder_num 7	75 75 75 76 77 77 77 77

CONTENTS xiii

	7.3.2.9	dunavant_subrule_02	. //
	7.3.2.10	dunavant_subrule_03	. 77
	7.3.2.11	dunavant_subrule_04	. 77
	7.3.2.12	dunavant_subrule_05	. 77
	7.3.2.13	dunavant_subrule_06	. 77
	7.3.2.14	dunavant_subrule_07	. 77
	7.3.2.15	dunavant_subrule_08	. 77
	7.3.2.16	dunavant_subrule_09	. 77
	7.3.2.17	dunavant_subrule_10	. 77
	7.3.2.18	dunavant_subrule_11	. 77
	7.3.2.19	dunavant_subrule_12	. 77
	7.3.2.20	dunavant_subrule_13	. 77
	7.3.2.21	dunavant_subrule_14	. 77
	7.3.2.22	dunavant_subrule_15	. 77
	7.3.2.23	dunavant_subrule_16	. 77
	7.3.2.24	dunavant_subrule_17	. 77
	7.3.2.25	dunavant_subrule_18	. 77
	7.3.2.26	dunavant_subrule_19	. 77
	7.3.2.27	dunavant_subrule_20	. 77
	7.3.2.28	file_name_inc	. 78
	7.3.2.29	i4_max	. 78
	7.3.2.30	i4_min	. 78
	7.3.2.31	i4_modp	. 78
	7.3.2.32	i4_wrap	. 78
	7.3.2.33	r8_huge	. 78
	7.3.2.34	r8_nint	. 78
	7.3.2.35	reference_to_physical_t3	. 78
	7.3.2.36	s_len_trim	. 78
	7.3.2.37	timestamp	. 78
	7.3.2.38	timestring	. 78
	7.3.2.39	triangle_area	. 78
	7.3.2.40	triangle_points_plot	. 78
7.4	lib/include/FESpa	ace.hpp File Reference	. 78
	7.4.1 Detailed	Description	. 79
7.5	lib/include/FESpa	ace_imp.hpp File Reference	. 79
	7.5.1 Detailed	Description	. 79
7.6	lib/include/Force.	hpp File Reference	. 79
	7.6.1 Detailed	Description	. 80
7.7	lib/include/Force_	_imp.hpp File Reference 80
	7.7.1 Detailed	Description	. 80

XIV

7.8	lib/inclu	ide/Geometry.hpp File Reference	80
	7.8.1	Detailed Description	81
	7.8.2	Variable Documentation	81
		7.8.2.1 NVAL	81
7.9	lib/inclu	ide/Matrices_imp.hpp File Reference	81
	7.9.1	Detailed Description	82
7.10	lib/inclu	ide/Mesh.hpp File Reference	82
	7.10.1	Detailed Description	82
7.11	lib/inclu	ıde/MyMat.hpp File Reference	83
	7.11.1	Detailed Description	83
7.12	lib/inclu	ide/QuadratureRule.hpp File Reference	84
	7.12.1	Detailed Description	84
7.13	lib/inclu	ıde/QuadratureRule_imp.hpp File Reference	84
	7.13.1	Detailed Description	85
7.14	lib/inclu	ide/Receivers.hpp File Reference	85
	7.14.1	Detailed Description	85
7.15	lib/inclu	ide/Receivers_imp.hpp File Reference	85
	7.15.1	Detailed Description	86
7.16	lib/inclu	ide/ShapeFunctions.hpp File Reference	86
	7.16.1	Detailed Description	86
7.17	lib/inclu	ide/ShapeFunctions_imp.hpp File Reference	87
	7.17.1	Detailed Description	87
7.18	lib/inclu	ide/TimeAdvance.hpp File Reference	87
	7.18.1	Detailed Description	88
7.19	lib/inclu	lde/TimeAdvance_imp.hpp File Reference	88
	7.19.1	Detailed Description	88
7.20	lib/inclu	ide/TSPEED.hpp File Reference	89
7.21	TSPEE	D.hpp File Reference	89
7.22	lib/src/[Ounavant.cpp File Reference	89
	7.22.1	Detailed Description	90
	7.22.2	Macro Definition Documentation	90
		7.22.2.1 TIME_SIZE	90
		7.22.2.2 TIME_SIZE	90
	7.22.3	Function Documentation	90
		7.22.3.1 dunavant_degree	90
		7.22.3.2 dunavant_order_num	90
		7.22.3.3 dunavant_rule	91
		7.22.3.4 dunavant_rule_num	91
		7.22.3.5 dunavant_suborder	91
		7.22.3.6 dunavant_suborder_num	91

CONTENTS xv

	7.22.3.7 dunavant_subrule	. 91
	7.22.3.8 dunavant_subrule_01	. 91
	7.22.3.9 dunavant_subrule_02	. 91
	7.22.3.10 dunavant_subrule_03	. 91
	7.22.3.11 dunavant_subrule_04	. 91
	7.22.3.12 dunavant_subrule_05	. 91
	7.22.3.13 dunavant_subrule_06	. 91
	7.22.3.14 dunavant_subrule_07	. 91
	7.22.3.15 dunavant_subrule_08	. 91
	7.22.3.16 dunavant_subrule_09	. 91
	7.22.3.17 dunavant_subrule_10	. 91
	7.22.3.18 dunavant_subrule_11	. 91
	7.22.3.19 dunavant_subrule_12	. 91
	7.22.3.20 dunavant_subrule_13	. 91
	7.22.3.21 dunavant_subrule_14	. 91
	7.22.3.22 dunavant_subrule_15	. 91
	7.22.3.23 dunavant_subrule_16	. 91
	7.22.3.24 dunavant_subrule_17	. 91
	7.22.3.25 dunavant_subrule_18	. 91
	7.22.3.26 dunavant_subrule_19	. 91
	7.22.3.27 dunavant_subrule_20	. 91
	7.22.3.28 file_name_inc	. 91
	7.22.3.29 i4_max	. 91
	7.22.3.30 i4_min	. 91
	7.22.3.31 i4_modp	. 92
	7.22.3.32 i4_wrap	. 92
	7.22.3.33 r8_huge	. 92
	7.22.3.34 r8_nint	. 92
	7.22.3.35 reference_to_physical_t3	. 92
	7.22.3.36 s_len_trim	. 92
	7.22.3.37 timestamp	. 92
	7.22.3.38 timestring	. 92
	7.22.3.39 triangle_area	. 92
	7.22.3.40 triangle_points_plot	. 92
7.23	lib/src/Force.cpp File Reference	. 92
	7.23.1 Detailed Description	. 92
7.24	lib/src/Geometry.cpp File Reference	. 92
	7.24.1 Detailed Description	. 93
7.25	lib/src/Mesh.cpp File Reference	
	7.25.1 Detailed Description	. 93

xvi CONTENTS

	7.31.1.1 main	96
	7.31.1 Function Documentation	96
7.31	main.cpp File Reference	96
	7.30.1 Detailed Description	96
7.30	lib/src/TimeAdvance.cpp File Reference	95
	7.29.2.1 Arr	95
	7.29.2 Typedef Documentation	95
	7.29.1 Detailed Description	95
7.29	lib/src/ShapeFunctions.cpp File Reference	95
	7.28.1 Detailed Description	95
7.28	lib/src/Receivers.cpp File Reference	95
	7.27.1 Detailed Description	94
7.27	lib/src/Parameters.cpp File Reference	94
	7.26.1 Detailed Description	94
7.26	lib/src/MyMat.cpp File Reference	93

Chapter 1

Namespace Index

1.1 Namespace Lis	st
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i icic is a iisi oi ai	Haine	spa	CCS W	ונוו טו	iei ue	53011	iptio	113.									
Tspeed									 	 	 	 			 		
Tspeed::Geo									 	 	 	 			 		1

2 Namespace Index

Chapter 2

Hierarchical Index

2.1 Class Hierarchy

This inheritance list is sorted roughly, but not completely, alphabetically:

Tspeed::BaseMat
Tspeed::MyMat
Tspeed::MyMatBlockDiag
Tspeed::Entity
Tspeed::Geo::Edge
Tspeed::Geo::Point
Tspeed::Geo::Triangle
$Tspeed:: FESpace < N, Q, S > \dots \dots$
Tspeed::Force
Tspeed::PointWiseForce
Tspeed::Matrices
Tspeed::Mesh
$Tspeed::MyMatMultiDim < T > \dots \dots$
Tspeed::MyMatMultiDim< Tspeed::MyMat >
Tspeed::MyMatMultiDim< Tspeed::MyMatBlockDiag >
Tspeed::MyMatMultiDimBlockDiag < T >
$\label{thm:continuous} Tspeed:: MyMatMultiDimBlockDiag < Tspeed:: MyMatBlockDiag > \dots $
Tspeed::Parameters
Tspeed::PointWiseEntity
Tspeed::PointWiseForce
Tspeed::Receivers
$Tspeed::Quadrature Rule < N > \dots \qquad \qquad 57$
Tspeed::Dunavant < N >
Tspeed::Gauss < N >
$Tspeed::ShapeFunction < N > \dots \dots$
Tspeed::BoundaryAdapted < N >
Tspeed::Dubiner < N >
Tspeed::TimeAdvance
Tspeed::LeapFrog

Hierarchical Index

Chapter 3

Class Index

3.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

rspeed::Basemai	
Base monodimensional matrix class	15
Tspeed::BoundaryAdapted< N >	
Boundary adapted [2] basis	18
Tspeed::Dubiner< N >	
Dubiner [1] basis	19
Tspeed::Dunavant< N >	
Dunavant [1] quadrature rule	20
Tspeed::Geo::Edge	
Class describing an edge	22
Tspeed::Entity	
Base class for geometrical entities	23
Tspeed::FESpace < N, Q, S >	
Functional space	27
Tspeed::Force	
Virtual base class for forces	31
Tspeed::Gauss < N >	
Gauss quadrature rule on the triangle	33
Tspeed::LeapFrog	
Implementation of the second order Leap-Frog explicit time stepping scheme	34
Tspeed::Matrices	
The class containing the matrices resulting from the spatial discretization	35
Tspeed::Mesh	37
Tspeed::MyMat	
Block Matrix (monodimensial blocks of stability and interelement matrices)	40
Tspeed::MyMatBlockDiag	
Block diagonal monodimensional matrix (monodimensional block of mass and stress-strain ma-	
trices)	41
Tspeed::MyMatMultiDim< T >	
Multidimensional matrix	42
Tspeed::MyMatMultiDimBlockDiag< T >	
Matrix class for matrices where only the diagonal monodimensional matrices are non zero (i.e.	
the mass matrix)	45
Tspeed::Parameters	
Class for the parameters λ, ho, μ of the elastodynamics equations $\dots \dots \dots \dots \dots$	47
Tspeed::Geo::Point	
Class describing points	48

6 Class Index

Tspeed::PointWiseEntity	
A base class for pointwise entities, with the points and the basis function in that points	53
Tspeed::PointWiseForce	
Time dependent force acting on a point	55
Tspeed::QuadratureRule < N >	
Base class for quadrature rules	57
Tspeed::Receivers	
A class for seismic receivers, i.e., receivers recording the movement at a point	61
Tspeed::ShapeFunction< N >	
Base class for the shared functions	62
Tspeed::TimeAdvance	
Base class for time stepping methods	65
Tspeed::Geo::Triangle	
Class describing a triangle	70

Chapter 4

File Index

4.1 File List

Here is a list of all files with brief descriptions:

main.cpp	96
TSPEED.hpp	89
Examples/src/Lamb.cpp	75
Examples/src/wedge.cpp	75
lib/include/Dunavant.hpp	
Header files for the implementation of the Dunavant rules	76
lib/include/FESpace.hpp	
Header file for the Galerkin space and for the parameters of the elastodynamics equation	78
lib/include/FESpace_imp.hpp	
Implementation of the functional space class methods	79
lib/include/Force.hpp	
Header file for the force	79
lib/include/Force_imp.hpp	
Implementation of the Pointwise force template methods	80
lib/include/Geometry.hpp	
Header file for the geometrical entities	80
lib/include/Matrices_imp.hpp	
Implementation of the matrices for the method - templated part	81
lib/include/Mesh.hpp	
Header file for the mesh	82
lib/include/MyMat.hpp	
Header file for the matrices specialized for the Discontinuous Galerkin method	83
lib/include/QuadratureRule.hpp	
Header file for the quadrature rules	84
lib/include/QuadratureRule_imp.hpp	
Implementation of the quadrature rules	84
lib/include/Receivers.hpp	
Header file containg the class for receivers and a base class for pointwise entities	85
lib/include/Receivers_imp.hpp	
Implementation of the pointwise entity and receivers class	85
lib/include/ShapeFunctions.hpp	
Header file for the definition of the shape functions	86
lib/include/ShapeFunctions_imp.hpp	
Implementation of the shape functions	87
lib/include/TimeAdvance.hpp	
Header file for the implementation of the time stepping and of the matrices for the method \dots	87
lib/include/TimeAdvance_imp.hpp	
Implementation of the time advancing template methods	88

8 File Index

lib/include/TSPEED.hpp	89
lib/src/Dunavant.cpp	
Functions for Dunavant quadrature (nodes and weights, tabulated)	89
lib/src/Force.cpp	
Implementation of the Force method	92
lib/src/Geometry.cpp	
Implementation of the geometrical entities	92
lib/src/Mesh.cpp	
Implementation of the mesh	93
lib/src/MyMat.cpp	
Implementation of the matrix classes	93
lib/src/Parameters.cpp	
Implementation of the Parameters methods	94
lib/src/Receivers.cpp	
Implementation of the Receivers methods	95
lib/src/ShapeFunctions.cpp	
Implementation of the jacobi polynomials	95
lib/src/TimeAdvance.cpp	
Implmentation of the TimeAdvance methods	95

Chapter 5

Namespace Documentation

5.1 Tspeed Namespace Reference

Namespaces

· namespace Geo

Classes

· class FESpace

Functional space.

class Parameters

Class for the parameters λ, ρ, μ of the elastodynamics equations.

class Force

virtual base class for forces

class PointWiseForce

Time dependent force acting on a point.

· class Entity

Base class for geometrical entities.

- class Mesh
- · class BaseMat

Base monodimensional matrix class.

class MyMatBlockDiag

Block diagonal monodimensional matrix (monodimensional block of mass and stress-strain matrices)

· class MyMat

Block Matrix (monodimensial blocks of stability and interelement matrices)

class MyMatMultiDim

Multidimensional matrix.

· class MyMatMultiDimBlockDiag

Matrix class for matrices where only the diagonal monodimensional matrices are non zero (i.e. the mass matrix)

· class QuadratureRule

Base class for quadrature rules.

• class Gauss

Gauss quadrature rule on the triangle.

· class Dunavant

Dunavant [1] quadrature rule.

class PointWiseEntity

A base class for pointwise entities, with the points and the basis function in that points.

class Receivers

A class for seismic receivers, i.e., receivers recording the movement at a point.

class ShapeFunction

Base class for the shared functions.

· class Dubiner

Dubiner [1] basis.

class BoundaryAdapted

Boundary adapted [2] basis.

· class Matrices

The class containing the matrices resulting from the spatial discretization.

class TimeAdvance

Base class for time stepping methods.

class LeapFrog

Implementation of the second order Leap-Frog explicit time stepping scheme.

Typedefs

- template<int N, typename Q = Gauss<N+1>, typename S = Dubiner<N>>
 using FESpace_ptr = std::shared_ptr< FESpace< N, Q, S >>
 template pointer to FESpace
- typedef std::shared ptr< Force > Force ptr
- typedef std::shared_ptr< Mesh > Mesh_ptr

Shared pointer to an element of type mesh.

Enumerations

• enum Bc { Dirichlet, Neumann, Internal, Unassigned }

Functions

- MyMat operator* (double const &c, MyMat const &M)
- Eigen::VectorXd operator* (MyMat const &, Eigen::VectorXd const &)
- Eigen::VectorXd operator* (MyMatBlockDiag const &, Eigen::VectorXd const &)
- MyMat operator+ (MyMat a, MyMat const &b)
- MyMat operator+ (MyMat a, MyMatBlockDiag const &b)
- Eigen::ArrayXd jacobi polynomial (int N, int alpha, int beta, Eigen::ArrayXd const &z)
- double mat_dot (Eigen::Matrix2d const &a, Eigen::Matrix2d const &b)

Dot product between two 2x2 matrices.

Eigen::Matrix2d CTensorProduct (Eigen::Matrix2d const &A, double lambda, double mu)

tensor product between Hooke's tensor and matrix A

- Eigen::VectorXd operator* (MyMatMultiDimBlockDiag < MyMatBlockDiag > const &A, Eigen::VectorXd const &v)
- Eigen::VectorXd operator* (MyMatMultiDim< MyMat > &A, Eigen::VectorXd const &v)
- Eigen::VectorXd operator* (MyMatMultiDim< MyMatBlockDiag > &A, Eigen::VectorXd const &v)
- MyMatMultiDim< MyMat > operator+ (MyMatMultiDim< MyMat > const &a, MyMatMultiDim< MyMat > const &b)
- MyMatMultiDim< MyMat > operator+ (MyMatMultiDim< MyMat > const &a, MyMatMultiDim< MyMatBlock-Diag > const &b)
- MyMat operator+ (MyMatBlockDiag const &b, MyMat a)

5.1.1 Typedef Documentation

5.1.1.1 template < int N, typename Q = Gauss < N+1>, typename S = Dubiner < N>> using Tspeed::FESpace_ptr = typedef std::shared_ptr < FESpace < N,Q,S>>

template pointer to FESpace

Template Parameters

MOG	the same template parameters as FESpace
14.Q.S	life Saille leifiblate baraffielers as FESDace

- 5.1.1.2 typedef std::shared_ptr<Force> Tspeed::Force_ptr
- 5.1.1.3 typedef std::shared_ptr<Mesh> Tspeed::Mesh_ptr

Shared pointer to an element of type mesh.

5.1.2 Enumeration Type Documentation

5.1.2.1 enum Tspeed::Bc

Enumerator

Dirichlet

Neumann

Internal

Unassigned

5.1.3 Function Documentation

5.1.3.1 Eigen::Matrix2d Tspeed::CTensorProduct (Eigen::Matrix2d const & A, double lambda, double mu)

tensor product between Hooke's tensor and matrix A

Parameters

Α	the matrix
lambda,mu	Hooke's constants

Returns

- 5.1.3.2 Eigen::ArrayXd Tspeed::jacobi_polynomial (int N, int alpha, int beta, Eigen::ArrayXd const & z)
- 5.1.3.3 double Tspeed::mat_dot (Eigen::Matrix2d const & a, Eigen::Matrix2d const & b)

Dot product between two 2x2 matrices.

Parameters

a,b	the matrices A, B

```
Returns
```

```
\sum_{ij} A_{ij} B_{ij}
```

- 5.1.3.4 Eigen::VectorXd Tspeed::operator* (MyMatMultiDimBlockDiag < MyMatBlockDiag > const & A, Eigen::VectorXd const & ν)
- 5.1.3.5 Eigen::VectorXd Tspeed::operator* (MyMatMultiDim < MyMat > & A, Eigen::VectorXd const & v)
- 5.1.3.6 Eigen::VectorXd Tspeed::operator* (MyMatMultiDim< MyMatBlockDiag > & A, Eigen::VectorXd const & v)
- 5.1.3.7 MyMat Tspeed::operator* (double const & c, MyMat const & M)
- 5.1.3.8 Eigen::VectorXd Tspeed::operator* (MyMat const & A, Eigen::VectorXd const & x)
- 5.1.3.9 Eigen::VectorXd Tspeed::operator* (MyMatBlockDiag const & A, Eigen::VectorXd const & x)
- 5.1.3.10 MyMat Tspeed::operator+ (MyMat a, MyMat const & b)
- 5.1.3.11 MyMat Tspeed::operator+ (MyMat a, MyMatBlockDiag const & b)
- 5.1.3.12 **MyMatMultiDim**<**MyMat**> Tspeed::operator+ (MyMatMultiDim< MyMat > const & *a,* MyMatMultiDim< MyMat > const & *b*)
- 5.1.3.13 **MyMatMultiDim**<**MyMat**> Tspeed::operator+ (MyMatMultiDim< MyMat> const & *a,* MyMatMultiDim< MyMatBlockDiag > const & *b*)
- 5.1.3.14 MyMat Tspeed::operator+ (MyMatBlockDiag const & b, MyMat a)

5.2 Tspeed::Geo Namespace Reference

Classes

· class Point

Class describing points.

• class Edge

Class describing an edge.

· class Triangle

Class describing a triangle.

Functions

- std::ostream & operator<< (std::ostream &, Triangle const &)
- std::ostream & operator<< (std::ostream &, Point const &)
- Point operator- (const Point &a, const Point &b)
- Point operator- (const Eigen::Vector2d &a, const Point &b)
- Point operator- (const Point &a, const Eigen::Vector2d &b)
- Point operator+ (const Eigen::Vector2d &a, const Point &b)
- Point operator+ (const Point &a, const Eigen::Vector2d &b)
- Point operator+ (const Point &a, const Point &b)
- Point operator* (const double &d, const Point &p)

5.2.1 Function Documentation

5.2.1.1 Point Tspeed::Geo::operator* (const double & d, const Point & p)

5.2.1.2 Point Tspeed::Geo::operator+ (const Eigen::Vector2d & a, const Point & b)

Parameters

а	vector
b	Point

Returns

Point

5.2.1.3 Point Tspeed::Geo::operator+ (const Point & a, const Eigen::Vector2d & b)

Parameters

а	Point
b	vector

Returns

Point

5.2.1.4 Point Tspeed::Geo::operator+ (const Point & a, const Point & b)

Parameters

а	first point
b	second point

Returns

sum of points

5.2.1.5 Point Tspeed::Geo::operator- (const Point & a, const Point & b)

Parameters

а	first point
b	second point

Returns

difference of points

5.2.1.6 Point Tspeed::Geo::operator-(const Eigen::Vector2d & a, const Point & b)

Parameters

а	first point
b	vector

Returns

point: difference of point a vector

- 5.2.1.7 Point Tspeed::Geo::operator- (const Point & a, const Eigen::Vector2d & b)
- 5.2.1.8 std::ostream & Tspeed::Geo::operator<< (std::ostream & io, Triangle const & t)
- 5.2.1.9 std::ostream & Tspeed::Geo::operator << (std::ostream & io, Point const & p)

Chapter 6

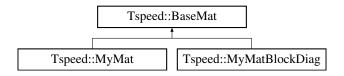
Class Documentation

6.1 Tspeed::BaseMat Class Reference

Base monodimensional matrix class.

```
#include <MyMat.hpp>
```

Inheritance diagram for Tspeed::BaseMat:



Public Member Functions

- · BaseMat ()
- BaseMat (Mesh_ptr, unsigned int nln)
- Eigen::MatrixXd const & block (unsigned int i, unsigned int j) const

Get sub-block generated by integration on elements i and j ($\neq 0$ if they are neighbors) (const version)

• Eigen::MatrixXd & block (unsigned int i, unsigned int j)

Get sub-block generated by integration on elements i and j (\neq 0 if they are neighbors) (non-const version)

• void setblock (unsigned int i, unsigned int j, Eigen::MatrixXd const &M)

Set sub-block generated by integration on elements i and j ($\neq 0$ if they are neighbors) (const version)

- BaseMat (BaseMat const &)
- virtual ∼BaseMat ()=default
- unsigned int nr () const

Get number of rows of the matrix.

std::vector< unsigned int > const & rowInd () const

Get row indices of the matrix.

• std::vector< unsigned int > const & collnd () const

Get column indices of the matrix.

void set_rowInd (std::vector< unsigned int >const &v)

Set row indices of the matrix.

void set_collnd (std::vector< unsigned int >const &v)

Set column indices of the matrix.

std::vector< Eigen::MatrixXd > const & elem () const

16 Class Documentation

Get a vector with all the sub-blocks (const version)

• std::vector< Eigen::MatrixXd > & elem ()

Get a vector with all the sub-blocks (non-const version)

• Eigen::MatrixXd const & elem (int i) const

Get sub-block linearly indexed by i.

• unsigned int size () const

Get the number of sub-blocks.

• void vecMult (Eigen::VectorXd const &x, Eigen::VectorXd &out) const

Multiplication by a vector.

Protected Attributes

- unsigned int M_nr
- unsigned int M_nc
- · unsigned int M nln
- std::vector< Eigen::MatrixXd > M_m
- std::vector< unsigned int $> M_r$
- std::vector< unsigned int > M_c

6.1.1 Detailed Description

Base monodimensional matrix class.

6.1.2 Constructor & Destructor Documentation

```
6.1.2.1 Tspeed::BaseMat::BaseMat()
```

- 6.1.2.2 Tspeed::BaseMat::BaseMat (Mesh_ptr , unsigned int nln)
- 6.1.2.3 Tspeed::BaseMat::BaseMat (BaseMat const &)
- **6.1.2.4 virtual Tspeed::BaseMat::**~BaseMat() [virtual],[default]

6.1.3 Member Function Documentation

6.1.3.1 Eigen::MatrixXd const & Tspeed::BaseMat::block (unsigned int i, unsigned int j) const

Get sub-block generated by integration on elements i and j ($\neq 0$ if they are neighbors) (const version)

Parameters

```
i,j the indices of the triangles
```

Returns

The sub-block

6.1.3.2 Eigen::MatrixXd & Tspeed::BaseMat::block (unsigned int i, unsigned int j)

Get sub-block generated by integration on elements i and j ($\neq 0$ if they are neighbors) (non-const version)

```
Parameters
```

```
i,j the indices of the triangles
```

Returns

The sub-block

6.1.3.3 std::vector<unsigned int> const& Tspeed::BaseMat::collnd() const [inline]

Get column indices of the matrix.

6.1.3.4 std::vector<Eigen::MatrixXd> const& Tspeed::BaseMat::elem () const [inline]

Get a vector with all the sub-blocks (const version)

6.1.3.5 std::vector<Eigen::MatrixXd>& Tspeed::BaseMat::elem() [inline]

Get a vector with all the sub-blocks (non-const version)

6.1.3.6 Eigen::MatrixXd const& Tspeed::BaseMat::elem (int i) const [inline]

Get sub-block linearly indexed by i.

Parameters

```
i the linear index of the sub-block
```

6.1.3.7 unsigned int Tspeed::BaseMat::nr() const [inline]

Get number of rows of the matrix.

Returns

The number of rows

 $\textbf{6.1.3.8} \quad \textbf{std::vector} < \textbf{unsigned int} > \textbf{const\& Tspeed::BaseMat::rowInd () const} \quad \texttt{[inline]}$

Get row indices of the matrix.

6.1.3.9 void Tspeed::BaseMat::set_collnd (std::vector< unsigned int >const & v) [inline]

Set column indices of the matrix.

6.1.3.10 void Tspeed::BaseMat::set_rowInd (std::vector < unsigned int >const & v) [inline]

Set row indices of the matrix.

6.1.3.11 void Tspeed::BaseMat::setblock (unsigned int i, unsigned int j, Eigen::MatrixXd const & M)

Set sub-block generated by integration on elements i and j ($\neq 0$ if they are neighbors) (const version)

18 Class Documentation

Parameters

i,j the indices of the triangles	
M the matrix assigned to the sub-block	

6.1.3.12 unsigned int Tspeed::BaseMat::size () const [inline]

Get the number of sub-blocks.

6.1.3.13 void Tspeed::BaseMat::vecMult (Eigen::VectorXd const & x, Eigen::VectorXd & out) const

Multiplication by a vector.

Parameters

in	X	term to be multiplied
out	out	result of the multiplication

6.1.4 Member Data Documentation

- **6.1.4.1 std::vector**<**unsigned int**> **Tspeed::BaseMat::M_c** [protected]
- **6.1.4.2** std::vector<Eigen::MatrixXd> Tspeed::BaseMat::M_m [protected]
- **6.1.4.3 unsigned int Tspeed::BaseMat::M_nc** [protected]
- **6.1.4.4 unsigned int Tspeed::BaseMat::M_nln** [protected]
- **6.1.4.5 unsigned int Tspeed::BaseMat::M_nr** [protected]
- **6.1.4.6** std::vector<unsigned int> Tspeed::BaseMat::M_r [protected]

The documentation for this class was generated from the following files:

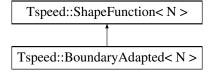
- lib/include/MyMat.hpp
- lib/src/MyMat.cpp

6.2 Tspeed::BoundaryAdapted N > Class Template Reference

Boundary adapted [2] basis.

#include <ShapeFunctions.hpp>

Inheritance diagram for Tspeed::BoundaryAdapted < N >:



Public Types

enum { is_orthonormal = false }

The basis is not orthonormal.

Public Member Functions

- virtual ∼BoundaryAdapted ()
- BoundaryAdapted ()

Additional Inherited Members

6.2.1 Detailed Description

template < int N > class Tspeed::Boundary Adapted < N >

Boundary adapted [2] basis.

Template Parameters

N degree of the space \mathbb{N}

6.2.2 Member Enumeration Documentation

6.2.2.1 template<int N> anonymous enum

The basis is not orthonormal.

Enumerator

is_orthonormal

6.2.3 Constructor & Destructor Documentation

```
6.2.3.1 template < int N> virtual Tspeed::BoundaryAdapted < N>::\simBoundaryAdapted ( ) [inline], [virtual]
```

6.2.3.2 template<int N> Tspeed::BoundaryAdapted< N>::BoundaryAdapted ()

The documentation for this class was generated from the following files:

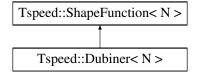
- lib/include/ShapeFunctions.hpp
- lib/include/ShapeFunctions_imp.hpp

6.3 Tspeed::Dubiner < N > Class Template Reference

Dubiner [1] basis.

#include <ShapeFunctions.hpp>

Inheritance diagram for Tspeed::Dubiner< N >:



Public Types

enum { is_orthonormal = true }
 Dubiner basis is orthonormal.

Public Member Functions

- virtual ~Dubiner ()
- Dubiner ()

Additional Inherited Members

6.3.1 Detailed Description

template<int N>class Tspeed::Dubiner< N>

Dubiner [1] basis.

Template Parameters

N degree of the space \mathbb{N}

6.3.2 Member Enumeration Documentation

6.3.2.1 template<int N> anonymous enum

Dubiner basis is orthonormal.

Enumerator

is_orthonormal

- 6.3.3 Constructor & Destructor Documentation
- **6.3.3.1** template<int N> virtual Tspeed::Dubiner< N>::~Dubiner() [inline], [virtual]
- 6.3.3.2 template<int N> Tspeed::Dubiner< N >::Dubiner ()

The documentation for this class was generated from the following files:

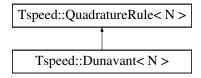
- lib/include/ShapeFunctions.hpp
- lib/include/ShapeFunctions_imp.hpp

6.4 Tspeed::Dunavant < N > Class Template Reference

Dunavant [1] quadrature rule.

#include <QuadratureRule.hpp>

Inheritance diagram for Tspeed::Dunavant< N >:



Public Types

- enum { nqn2d = dunavant_num_points<N>() }
- enum { nqn1d = N }
- typedef QuadratureRule < N >:: Vec Vec
- typedef QuadratureRule < N >::Vec Mat
- typedef QuadratureRule < N >:: Vec Vec2

Public Member Functions

• Dunavant ()

Additional Inherited Members

6.4.1 Detailed Description

template < int N > class Tspeed::Dunavant < N >

Dunavant [1] quadrature rule.

Template Parameters

N the order of the rule.

A rule of order N integrates exactly polynomials of order N $\,$

6.4.2 Member Typedef Documentation

- $6.4.2.1 \quad template < int\ N > typedef\ \textbf{QuadratureRule} < N > :: \textbf{Vec}\ \textbf{Tspeed} :: \textbf{Dunavant} < \ N > :: \textbf{Mat}$
- $6.4.2.2 \quad template < int \ N > typedef \ Quadrature Rule < N > :: Vec \ Tspeed:: Dunavant < N > :$
- 6.4.2.3 template<int N> typedef QuadratureRule<N>::Vec Tspeed::Dunavant< N>::Vec2

6.4.3 Member Enumeration Documentation

6.4.3.1 template<int N> anonymous enum

Enumerator

nqn2d

6.4.3.2 template < int N> anonymous enum

Enumerator

nqn1d

6.4.4 Constructor & Destructor Documentation

6.4.4.1 template<int N> Tspeed::Dunavant< N>::Dunavant ()

The documentation for this class was generated from the following files:

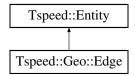
- lib/include/QuadratureRule.hpp
- lib/include/QuadratureRule_imp.hpp

6.5 Tspeed::Geo::Edge Class Reference

Class describing an edge.

```
#include <Geometry.hpp>
```

Inheritance diagram for Tspeed::Geo::Edge:



Public Member Functions

• Edge ()

Default constructor: extremal points are initialized to 0.

• Edge (const Point &a, const Point &b)

Constructor.

• Edge (const Edge &e)

copy constructor

- virtual ~Edge ()
- double length () const

Length of the edge.

• Eigen::Vector2d normal () const

Normal to the edge.

• Edge & operator= (const Edge &)

Assignement.

Additional Inherited Members

6.5.1 Detailed Description

Class describing an edge.

6.5.2 Constructor & Destructor Documentation

6.5.2.1 Tspeed::Geo::Edge::Edge() [inline]

Default constructor: extremal points are initialized to 0.

6.5.2.2 Tspeed::Geo::Edge::Edge (const Point & a, const Point & b) [inline]

Constructor.

Parameters

а	One extreme
b	The other extreme

6.5.2.3 Tspeed::Geo::Edge::Edge (const Edge & e) [inline]

copy constructor

Parameters

6.5.2.4 virtual Tspeed::Geo::Edge::~Edge() [inline],[virtual]

6.5.3 Member Function Documentation

6.5.3.1 double Tspeed::Geo::Edge::length() const [inline]

Length of the edge.

6.5.3.2 Eigen::Vector2d Tspeed::Geo::Edge::normal () const

Normal to the edge.

Returns

The normalized vector

6.5.3.3 Edge & Tspeed::Geo::Edge::operator= (const Edge & e)

Assignement.

The documentation for this class was generated from the following files:

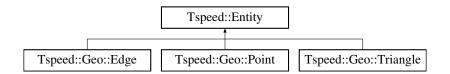
- lib/include/Geometry.hpp
- · lib/src/Geometry.cpp

6.6 Tspeed::Entity Class Reference

Base class for geometrical entities.

#include <Geometry.hpp>

Inheritance diagram for Tspeed::Entity:



Public Types

· typedef unsigned int Id

Public Member Functions

- Entity ()
- bool unassignedId () const

Check if element has assigned ld.

• bool unassignedBc () const

Check if element has assigned boundary condition.

• bool unassignedReg () const

Check if element has assigned region.

• Id & reg ()

Get region id.

• Id const & reg () const

Get region id (const version)

• Id & id ()

Get element id (const version)

· Id const & id () const

Get element id (const version)

• Bc & bcld ()

Get boundary id (const version)

• Bc const & bcld () const

Get boundary id (const version)

Protected Attributes

• Id M_reg

Region number.

• Id M_id

Id of the element.

• Bc M bcld

Boundary Id of the element.

6.6.1 Detailed Description

Base class for geometrical entities.

```
6.6.2
       Member Typedef Documentation
6.6.2.1 typedef unsigned int Tspeed::Entity::Id
6.6.3 Constructor & Destructor Documentation
6.6.3.1 Tspeed::Entity::Entity() [inline]
6.6.4 Member Function Documentation
6.6.4.1 Bc& Tspeed::Entity::bcld() [inline]
Get boundary id (const version)
Returns
    Constant reference to boundary id
6.6.4.2 Bc const& Tspeed::Entity::bcld() const [inline]
Get boundary id (const version)
Returns
    Constant reference to boundary id
6.6.4.3 Id& Tspeed::Entity::id() [inline]
Get element id (const version)
Returns
    Constant reference to element id
6.6.4.4 Id const& Tspeed::Entity::id ( ) const [inline]
Get element id (const version)
Returns
    Constant reference to element id
6.6.4.5 Id& Tspeed::Entity::reg() [inline]
Get region id.
Returns
    Reference to region id
```

```
6.6.4.6 Id const& Tspeed::Entity::reg ( ) const [inline]
Get region id (const version)
Returns
    Constant reference to region id
6.6.4.7 bool Tspeed::Entity::unassignedBc() const [inline]
Check if element has assigned boundary condition.
Returns
    TRUE if Bc is not assigned
6.6.4.8 bool Tspeed::Entity::unassignedId ( ) const [inline]
Check if element has assigned Id.
Returns
    TRUE if Id is not assigned
6.6.4.9 bool Tspeed::Entity::unassignedReg() const [inline]
Check if element has assigned region.
Returns
    TRUE if region is not assigned
6.6.5 Member Data Documentation
6.6.5.1 Bc Tspeed::Entity::M_bcld [protected]
Boundary Id of the element.
6.6.5.2 Id Tspeed::Entity::M_id [protected]
Id of the element.
6.6.5.3 Id Tspeed::Entity::M_reg [protected]
Region number.
The documentation for this class was generated from the following file:
```

• lib/include/Geometry.hpp

6.7 Tspeed::FESpace < N, Q, S > Class Template Reference

Functional space.

#include <FESpace.hpp>

Public Member Functions

FESpace (Mesh ptr m)

Constructor from the mesh.

- virtual ∼FESpace ()
- Mesh_ptr mesh () const

Get pointer ot mesh.

· Q const & quad () const

Get quadrature rule.

• ShapeFunction< N > const & shape () const

Get Shapefunction.

· unsigned int nln () const

Number of degrees of freedom per element.

• unsigned int ne () const

Number of elements in the mesh.

· Eigen::Vector2d grad (unsigned int k, unsigned int i) const

Get value of the gradient of the basis function i on quadrature point k.

• Eigen::VectorXd b_edge (unsigned int k, unsigned int iedg) const

Get value of all basis function on quadrature node k, on edge iedg.

• Eigen::Vector2d g_edge (unsigned int k, unsigned int i, unsigned short int edg) const

value of the gradient of basis function i, on edge edg, quadrature node k

• Eigen::VectorXd inverse_transform (std::function< std::array< double, 2 >(double, double)> const &fun) const

Transform a function u(x,y) into its expantion modes \hat{u}_i s.t.

$$\sum_{i} \hat{u}_{i} \psi_{i}(x, y) = u(x, y)$$

double L2error (std::function< std::array< double, 2 >(double, double)> const &uex, Eigen::VectorXd const &uh) const

L2 norm of the difference uex-uh.

Eigen::VectorXd loc_rhs (Geo::Triangle const &ie, std::function< std::array< double, 2 >(double, double)> const &fun) const

Integration of a function against all basis function, in triangle ie, i.e.

$$l_i = \int_{\mathrm{ie}} f \, \psi_i$$

· void points out (std::string const &fname) const

Write a set of points of the mesh to file.

void field_out (std::string const &fname, Eigen::VectorXd const &uh, unsigned int step) const
 Write a field to file, on the points given by points_out.

· Eigen::MatrixXd base mass () const

Evaluate the mass matrix M s.t.

$$M_{ij} = \int_{\mathscr{T}^2} \psi_i \psi_j$$

• Eigen::MatrixXd base_invmass () const

Evaluate the inverse of the mass matrix \mathbf{M}^{-1} .

Public Attributes

• EIGEN MAKE ALIGNED OPERATOR NEW

6.7.1 Detailed Description

template < int N, typename Q = Gauss < N+1>, typename S = Dubiner < N>>class Tspeed::FESpace < N, Q, S >

Functional space.

Template Parameters

N	order of the polynomials
Q	quadrature rule
S	basis functions

6.7.2 Constructor & Destructor Documentation

6.7.2.1 template<int N, typename Q , typename S > Tspeed::FESpace< N, Q, S >::FESpace(Mesh_ptr m) [explicit]

Constructor from the mesh.

Parameters

m	shared pointer to Mesh

- 6.7.2.2 template<int N, typename Q = Gauss<N+1>, typename S = Dubiner<N>> virtual Tspeed::FESpace< N, Q, S >::~FESpace() [inline], [virtual]
- 6.7.3 Member Function Documentation

Get value of all basis function on quadrature node k, on edge iedg.

Parameters

k	index of the quadrature point
iedg	index of the edge (=0,1,2)

Returns

vector of all the values

Evaluate the inverse of the mass matrix \mathbf{M}^{-1} .

Returns

 \mathbf{M}^{-1}

Evaluate the mass matrix M s.t.

$$M_{ij} = \int_{\mathscr{T}^2} \psi_i \psi_j$$

Returns

the matrix M

6.7.3.4 template<int N, typename Q, typename S > void Tspeed::FESpace< N, Q, S >::field_out (std::string const & fname, Eigen::VectorXd const & uh, unsigned int step) const

Write a field to file, on the points given by points_out.

Parameters

fname	name of the output file
uh	vector of the coefficients of a FE function
step	the time step (gets appended to the file name)

6.7.3.5 template<int N, typename Q = Gauss<N+1>, typename S = Dubiner<N>> Eigen::Vector2d Tspeed::FESpace<
N, Q, S >::g_edge (unsigned int k, unsigned int i, unsigned short int edg) const [inline]

value of the gradient of basis function i, on edge edg, quadrature node k

Parameters

k	index of the quadrature node
i	indec of the basis function
edg	edg number

Returns

a vector with the x and y derivatives

6.7.3.6 template<int N, typename Q = Gauss<N+1>, typename S = Dubiner<N>> Eigen::Vector2d Tspeed::FESpace<N, Q, S >::grad (unsigned int k, unsigned int i) const [inline]

Get value of the gradient of the basis function i on quadrature point k.

Parameters

k	index of the quadrature node
i	index of the basis function

Returns

A vector with the x and y derivatives

6.7.3.7 template < int N, typename Q , typename S > Eigen::VectorXd Tspeed::FESpace < N, Q, S >::inverse_transform (std::function < std::array < double, 2 > (double, double) > const & fun) const

Transform a function u(x,y) into its expantion modes \hat{u}_i s.t.

$$\sum_{i} \hat{u}_i \psi_i(x, y) = u(x, y)$$

.

Parameters

fun	the function

Returns

the vector of \hat{u}_i

6.7.3.8 template < int N, typename Q , typename S > double Tspeed::FESpace < N, Q, S >::L2error (std::function < std::array < double, 2 > (double, double) > const & uex, Eigen::VectorXd const & uh) const

L2 norm of the difference uex-uh.

Parameters

uex	A function
uh	A vector of expansion modes

Returns

The norm

6.7.3.9 template<int N, typename Q = Gauss<N+1>, typename S = Dubiner<N>> Eigen::VectorXd Tspeed::FESpace<
N, Q, S >::loc_rhs (Geo::Triangle const & ie, std::function< std::array< double, 2 >(double, double)> const & fun
) const [inline]

Integration of a function against all basis function, in triangle ie, i.e.

$$l_i = \int_{ie} f \psi_i$$

•

Parameters

ie	the index of the triangle
fun	the function to be integrated

Returns

the vector made by l_i

6.7.3.10 template<int N, typename Q = Gauss<N+1>, typename S = Dubiner<N>> Mesh_ptr Tspeed::FESpace< N, Q, S>::mesh() const [inline]

Get pointer ot mesh.

Returns

pointer to the mesh

6.7.3.11 template<int N, typename Q = Gauss<N+1>, typename S = Dubiner<N>> unsigned int Tspeed::FESpace<N, Q, S >::ne () const [inline]

Number of elements in the mesh.

6.7.3.12 template < int N, typename Q = Gauss < N+1>, typename S = Dubiner < N>> unsigned int Tspeed::FESpace < N, Q, S>::nIn () const [inline]

Number of degrees of freedom per element.

6.7.3.13 template<int N, typename Q, typename S > void Tspeed::FESpace< N, Q, S >::points_out (std::string const & fname) const

Write a set of points of the mesh to file.

Parameters

fname | name of the outpu file

6.7.3.14 template < int N, typename Q = Gauss < N+1>, typename S = Dubiner < N>> Q const& Tspeed::FESpace < N, Q, S >::quad () const [inline]

Get quadrature rule.

6.7.3.15 template<int N, typename Q = Gauss<N+1>, typename S = Dubiner<N>> ShapeFunction<N> const& Tspeed::FESpace< N, Q, S >::shape () const [inline]

Get Shapefunction.

- 6.7.4 Member Data Documentation
- 6.7.4.1 template<int N, typename Q = Gauss<N+1>, typename S = Dubiner<N>> Tspeed::FESpace< N, Q, S >::EIGEN_MAKE_ALIGNED_OPERATOR_NEW

The documentation for this class was generated from the following files:

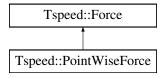
- lib/include/FESpace.hpp
- lib/include/FESpace_imp.hpp

6.8 Tspeed::Force Class Reference

virtual base class for forces

```
#include <Force.hpp>
```

Inheritance diagram for Tspeed::Force:



Public Types

- typedef Eigen::SparseVector
 double > SPVec
- typedef Eigen::VectorXd Vec

Public Member Functions

- Force ()
- Force (std::function < std::array < double, 2 > (const double &) > const & fun)
 Constructor, taking the function (time dependent)
- virtual ∼Force ()
- virtual Vec eval (const double &) const =0

Protected Attributes

std::function< std::array
 double, 2 > const double &)> M_f

6.8.1 Detailed Description

virtual base class for forces

6.8.2 Member Typedef Documentation

- 6.8.2.1 typedef Eigen::SparseVector<double> Tspeed::Force::SPVec
- 6.8.2.2 typedef Eigen::VectorXd Tspeed::Force::Vec

6.8.3 Constructor & Destructor Documentation

- **6.8.3.1 Tspeed::Force::Force()** [inline]
- $6.8.3.2 \quad \text{Tspeed::Force::Force (std::function} < \text{std::array} < \text{double, 2} > (\text{const double \&}) > \text{const \& } \textit{fun)}$

Constructor, taking the function (time dependent)

Parameters

fun	The function

```
6.8.3.3 virtual Tspeed::Force::~Force() [inline], [virtual]
```

6.8.4 Member Function Documentation

6.8.4.1 virtual Vec Tspeed::Force::eval (const double &) const [pure virtual]

Implemented in Tspeed::PointWiseForce.

6.8.5 Member Data Documentation

6.8.5.1 std::function<std::array<double,2>const double &)> Tspeed::Force::M_f [protected]

The documentation for this class was generated from the following file:

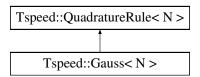
lib/include/Force.hpp

6.9 Tspeed::Gauss < N > Class Template Reference

Gauss quadrature rule on the triangle.

```
#include <QuadratureRule.hpp>
```

Inheritance diagram for Tspeed::Gauss < N >:



Public Types

- enum { nqn2d = N*N }
- enum { nqn1d = N }
- typedef QuadratureRule < N >:: Vec Vec
- typedef QuadratureRule < N >::Vec Mat
- typedef QuadratureRule < N >:: Vec Vec2

Public Member Functions

• Gauss ()

Additional Inherited Members

6.9.1 Detailed Description

template < int N> class Tspeed::Gauss < N>

Gauss quadrature rule on the triangle.

Template Parameters

N the order of the rule

The internal nodes will be N^2 ; N+1 is the required order to integrate polynomials of order 2N.

6.9.2 Member Typedef Documentation

6.9.2.1 template<int N> typedef QuadratureRule<N>::Vec Tspeed::Gauss< N>::Mat

6.9.2.2 template<int N> typedef QuadratureRule<N>::Vec Tspeed::Gauss< N>::Vec

6.9.2.3 template<int N> typedef QuadratureRule<N>::Vec Tspeed::Gauss< N>::Vec2

6.9.3 Member Enumeration Documentation

6.9.3.1 template<int N> anonymous enum

Enumerator

nqn2d

6.9.3.2 template<int N> anonymous enum

Enumerator

ngn1d

6.9.4 Constructor & Destructor Documentation

6.9.4.1 template<int N> Tspeed::Gauss< N>::Gauss ()

The documentation for this class was generated from the following files:

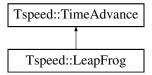
- lib/include/QuadratureRule.hpp
- lib/include/QuadratureRule_imp.hpp

6.10 Tspeed::LeapFrog Class Reference

Implementation of the second order Leap-Frog explicit time stepping scheme.

```
#include <TimeAdvance.hpp>
```

Inheritance diagram for Tspeed::LeapFrog:



Public Member Functions

- · void first step ()

First step for the Leap-Frog method.

void step (double)

Step at time t for the Leap-Frog method.

Additional Inherited Members

6.10.1 Detailed Description

Implementation of the second order Leap-Frog explicit time stepping scheme.

6.10.2 Constructor & Destructor Documentation

```
6.10.2.1 template < int N, typename Q , typename S > Tspeed::LeapFrog::LeapFrog ( FESpace_ptr < N, Q, S > Xh, Parameters const & p, Receivers const & r)
```

6.10.3 Member Function Documentation

```
6.10.3.1 void Tspeed::LeapFrog::first_step ( )
```

First step for the Leap-Frog method.

```
6.10.3.2 void Tspeed::LeapFrog::step ( double t )
```

Step at time t for the Leap-Frog method.

Parameters

```
t time
```

The documentation for this class was generated from the following files:

- lib/include/TimeAdvance.hpp
- lib/include/TimeAdvance_imp.hpp
- lib/src/TimeAdvance.cpp

6.11 Tspeed::Matrices Class Reference

The class containing the matrices resulting from the spatial discretization.

```
#include <TimeAdvance.hpp>
```

Public Types

typedef Eigen::SparseMatrix
 double > SpMat

Public Member Functions

 template < int N, typename Q , typename S > Matrices (FESpace_ptr< N, Q, S >, Parameters const &)

Constructor taking the space and the parameters.

MyMatMultiDim< MyMatBlockDiag > const & getA ()

Get the stiffness matrix

$$A_{ij} = \sum_{K} \int_{K} \sigma(\phi_{j}) : \varepsilon(\phi_{i})$$

• MyMatMultiDim< MyMat > const & getS ()

Get the stability matrix

$$S_{ij} = \sum_{e} \int_{e} [[\phi_j]] : [[\phi_i]]$$

MyMatMultiDim< MyMat > const & getl ()

Get the interelement matrix

$$S_{ij} = \sum_{e} \int_{e} \{ \{ \sigma(\phi_j) \} \} : [[\phi_i]] + \{ \{ \sigma(\phi_i) \} \} : [[\phi_j]]$$

· MyMatMultiDimBlockDiag

< MyMatBlockDiag > const & getinvM ()

Get inverse of the global mass matrix.

template<int N, typename Q, typename T >
 Matrices (FESpace_ptr< N, Q, T > Xh, Parameters const &P)

6.11.1 Detailed Description

The class containing the matrices resulting from the spatial discretization.

- 6.11.2 Member Typedef Documentation
- 6.11.2.1 typedef Eigen::SparseMatrix<double> Tspeed::Matrices::SpMat
- 6.11.3 Constructor & Destructor Documentation
- 6.11.3.1 template < int N, typename Q , typename S > Tspeed::Matrices (FESpace_ptr< N, Q, S > , Parameters const &)

Constructor taking the space and the parameters.

- 6.11.3.2 template < int N, typename Q , typename T > Tspeed::Matrices (FESpace_ptr < N, Q, T > $\it Xh$, Parameters const & $\it P$)
- 6.11.4 Member Function Documentation
- 6.11.4.1 MyMatMultiDim<MyMatBlockDiag> const& Tspeed::Matrices::getA() [inline]

Get the stiffness matrix

$$A_{ij} = \sum_{K} \int_{K} \sigma(\phi_{j}) : \varepsilon(\phi_{i})$$

Returns

A

6.11.4.2 MyMatMultiDim<MyMat> const& Tspeed::Matrices::getl() [inline]

Get the interelement matrix

$$S_{ij} = \sum_{e} \int_{e} \{ \{ \sigma(\phi_j) \} \} : [[\phi_i]] + \{ \{ \sigma(\phi_i) \} \} : [[\phi_j]]$$

Returns

 \mathbf{S}

6.11.4.3 MyMatMultiDimBlockDiag<MyMatBlockDiag> const& Tspeed::Matrices::getinvM() [inline]

Get inverse of the global mass matrix.

Returns

 \mathbf{M}^{-1}

6.11.4.4 MyMatMultiDim<MyMat> const& Tspeed::Matrices::getS() [inline]

Get the stability matrix

$$S_{ij} = \sum_{e} \int_{e} [[\phi_j]] : [[\phi_i]]$$

.

Returns

 \mathbf{S}

The documentation for this class was generated from the following files:

- lib/include/TimeAdvance.hpp
- lib/include/Matrices imp.hpp

6.12 Tspeed::Mesh Class Reference

#include <Mesh.hpp>

Public Types

- typedef unsigned int size_type
- · typedef std::vector

< Geo::Triangle,

Eigen::aligned_allocator

< Eigen::Vector2d > > AlignedVecT

• typedef std::vector< Geo::Edge,

Eigen::aligned_allocator

< Eigen::Vector2d > > AlignedVecE

· typedef std::vector

< Geo::Point,

Eigen::aligned_allocator

< Eigen::Vector2d > > AlignedVecP

Public Member Functions

Mesh (const std::string fileName)

Generate mesh from a Gmsh mesh.

Geo::Triangle const & operator[] (size_t i) const

Get triangle with index i (const)

• Geo::Triangle & operator[] (size_t i)

Get triangle with index i (non-const)

• AlignedVecT const & elements () const

Get all triangles in the mesh (const)

• AlignedVecT & elements ()

Get all triangles in the mesh (non-const)

- ~Mesh ()
- · void stats () const

Print stats about the mesh (e.g. number of elements, anisotropy etc.)

• unsigned int ne () const

Get number of triangles in the mesh.

• void printallNeigh () const

Print neighbors structure.

Public Attributes

```
    std::vector< std::pair</li>
    unsigned int, unsigned int > > M_bed_map
```

6.12.1 Member Typedef Documentation

```
6.12.1.1 typedef std::vector < Geo::Edge, Eigen::aligned_allocator < Eigen::Vector2d> > Tspeed::Mesh::AlignedVecE
```

 $6.12.1.2 \quad typedef \ std:: vector < Geo:: Point, Eigen:: aligned_allocator < Eigen:: Vector 2d >> Tspeed:: Mesh:: Aligned Vec Point, Eigen:: Aligned Vec Point, Eigen:: Vector 2d >> Tspeed:: Mesh:: Aligned Vec Point, Eigen:: Aligned Vec Point, Eigen:: Aligned Vec Point, Eigen:: Vector 2d >> Tspeed:: Mesh:: Aligned Vec Point, Eigen:: Aligned V$

```
6.12.1.3 typedef std::vector<Geo::Triangle,Eigen::aligned_allocator<Eigen::Vector2d>>
```

Tspeed::Mesh::AlignedVecT

6.12.1.4 typedef unsigned int Tspeed::Mesh::size_type

6.12.2 Constructor & Destructor Documentation

6.12.2.1 Tspeed::Mesh::Mesh (const std::string fileName) [explicit]

Generate mesh from a Gmsh mesh.

Parameters

```
fileName Name of the .msh file containing the mesh
```

```
6.12.2.2 Tspeed::Mesh::∼Mesh() [inline]
```

6.12.3 Member Function Documentation

```
6.12.3.1 AlignedVecT const& Tspeed::Mesh::elements ( ) const [inline]
Get all triangles in the mesh (const)
Returns
    Constant reference to a vector of triangles
6.12.3.2 AlignedVecT& Tspeed::Mesh::elements ( ) [inline]
Get all triangles in the mesh (non-const)
Returns
    Reference to a vector of triangles
6.12.3.3 unsigned int Tspeed::Mesh::ne( ) const [inline]
Get number of triangles in the mesh.
6.12.3.4 Geo::Triangle const& Tspeed::Mesh::operator[]( size_t i ) const [inline]
Get triangle with index i (const)
Parameters
                 i index of the triangle
Returns
    Constant reference to triangle
6.12.3.5 Geo::Triangle& Tspeed::Mesh::operator[]( size_t i ) [inline]
Get triangle with index i (non-const)
Parameters
                 i index of the triangle
Returns
    Reference to triangle
6.12.3.6 void Tspeed::Mesh::printallNeigh() const [inline]
Print neighbors structure.
6.12.3.7 void Tspeed::Mesh::stats ( ) const
Print stats about the mesh (e.g. number of elements, anisotropy etc.)
```

6.12.4 Member Data Documentation

6.12.4.1 std::vector<std::pair<unsigned int,unsigned int> > Tspeed::Mesh::M_bed_map

The documentation for this class was generated from the following files:

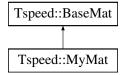
- lib/include/Mesh.hpp
- lib/src/Mesh.cpp

6.13 Tspeed::MyMat Class Reference

Block Matrix (monodimensial blocks of stability and interelement matrices)

```
#include <MyMat.hpp>
```

Inheritance diagram for Tspeed::MyMat:



Public Member Functions

- MyMat ()
- MyMat (Mesh_ptr, unsigned int nln)

Contructor from the mesh.

- MyMat (MyMat &&)=default
- MyMat (MyMat const &)
- MyMat & operator= (MyMat &&)=default
- MyMat & operator= (MyMat const &)=default
- virtual ~MyMat () noexcept(true)=default
- void symmetrize ()

sum with self transposed

• void sumtranspose (MyMat const &ot)

Sum with ot transposed.

- MyMat operator+= (MyMat const &)
- MyMat operator+= (MyMatBlockDiag const &)
- MyMat operator* (double const &) const

Additional Inherited Members

6.13.1 Detailed Description

Block Matrix (monodimensial blocks of stability and interelement matrices)

6.13.2 Constructor & Destructor Documentation

6.13.2.1 Tspeed::MyMat::MyMat() [inline]

6.13.2.2 Tspeed::MyMat::MyMat (Mesh_ptr Th, unsigned int nln)

Contructor from the mesh.

Parameters

Th pointer to the mesh	
nln	number of degrees of freedom per element

```
6.13.2.3 Tspeed::MyMat::MyMat( MyMat && ) [default]
6.13.2.4 Tspeed::MyMat::MyMat( MyMat const & m )
6.13.2.5 virtual Tspeed::MyMat::~MyMat( ) [virtual], [default], [noexcept]
6.13.3 Member Function Documentation
6.13.3.1 MyMat Tspeed::MyMat::operator*( double const & c ) const
6.13.3.2 MyMat Tspeed::MyMat::operator+=( MyMat const & a )
6.13.3.3 MyMat Tspeed::MyMat::operator+=( MyMatBlockDiag const & a )
6.13.3.4 MyMat& Tspeed::MyMat::operator=( MyMat && ) [default]
6.13.3.5 MyMat& Tspeed::MyMat::operator=( MyMat const & ) [default]
```

Sum with ot transposed.

Parameters

ot	The const matrix to be transposed and summed to current

6.13.3.7 void Tspeed::MyMat::symmetrize ()

sum with self transposed

The documentation for this class was generated from the following files:

- lib/include/MyMat.hpp
- · lib/src/MyMat.cpp

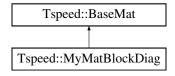
6.14 Tspeed::MyMatBlockDiag Class Reference

6.13.3.6 void Tspeed::MyMat::sumtranspose (MyMat const & ot)

Block diagonal monodimensional matrix (monodimensional block of mass and stress-strain matrices)

#include <MyMat.hpp>

Inheritance diagram for Tspeed::MyMatBlockDiag:



Public Member Functions

- MyMatBlockDiag ()
- MyMatBlockDiag (Mesh_ptr Th, unsigned int nln)

Contructor from the mesh.

- MyMatBlockDiag (MyMatBlockDiag &&)=default
- MyMatBlockDiag (MyMatBlockDiag const &)=default
- MyMatBlockDiag & operator= (MyMatBlockDiag &&)=default
- MyMatBlockDiag & operator= (MyMatBlockDiag const &)=default
- virtual ~MyMatBlockDiag () noexcept(true)=default

Additional Inherited Members

6.14.1 Detailed Description

Block diagonal monodimensional matrix (monodimensional block of mass and stress-strain matrices)

6.14.2 Constructor & Destructor Documentation

```
6.14.2.1 Tspeed::MyMatBlockDiag::MyMatBlockDiag() [inline]
```

6.14.2.2 Tspeed::MyMatBlockDiag::MyMatBlockDiag (Mesh_ptr Th, unsigned int nln)

Contructor from the mesh.

Parameters

Th pointer to the mesh	
nln	number of degrees of freedom per element

```
6.14.2.3 Tspeed::MyMatBlockDiag::MyMatBlockDiag ( MyMatBlockDiag && ) [default]
6.14.2.4 Tspeed::MyMatBlockDiag::MyMatBlockDiag ( MyMatBlockDiag const & ) [default]
6.14.2.5 virtual Tspeed::MyMatBlockDiag::~MyMatBlockDiag ( ) [virtual], [default], [noexcept]
6.14.3 Member Function Documentation
6.14.3.1 MyMatBlockDiag& Tspeed::MyMatBlockDiag::operator=( MyMatBlockDiag && ) [default]
6.14.3.2 MyMatBlockDiag& Tspeed::MyMatBlockDiag::operator=( MyMatBlockDiag const & ) [default]
```

The documentation for this class was generated from the following files:

- lib/include/MyMat.hpp
- lib/src/MyMat.cpp

6.15 Tspeed::MyMatMultiDim < T > Class Template Reference

Multidimensional matrix.

#include <MyMat.hpp>

Public Member Functions

- MyMatMultiDim ()=default
- virtual ∼MyMatMultiDim ()=default
- MyMatMultiDim (Mesh_ptr, unsigned int nln)
- T & component (int i, int j)

Return monodimensimenial block (i,j)

T const & component (int i, int j) const

Return monodimensimenial block (i,j) (const version)

void symmetrize ()

Sum matrix to self transposed.

• void vecMult (Eigen::VectorXd const &x, Eigen::VectorXd &out) const

Multiplication by a vector.

- MyMatMultiDim (MyMatMultiDim &a)
- MyMatMultiDim & operator= (MyMatMultiDim &&)=default
- Eigen::VectorXd operator* (Eigen::VectorXd const &v) const

Friends

- MyMatMultiDim< MyMat > operator+ (MyMatMultiDim< MyMat > const &a, MyMatMultiDim< MyMat > const &b)
- MyMatMultiDim< MyMat > operator+ (MyMatMultiDim< MyMat > const &a, MyMatMultiDim< MyMatBlock-Diag > const &b)
- MyMatMultiDim< T > operator* (double const &x, MyMatMultiDim< T > const &A)

6.15.1 Detailed Description

template<typename T>class Tspeed::MyMatMultiDim<T>

Multidimensional matrix.

Template Parameters

T | type of the monodimensional blocks

6.15.2 Constructor & Destructor Documentation

- 6.15.2.1 template<typename T> Tspeed::MyMatMultiDim< T>::MyMatMultiDim() [default]
- 6.15.2.2 template<typename T> virtual Tspeed::MyMatMultiDim< T>:: \sim MyMatMultiDim() [virtual], [default]
- 6.15.2.3 template<typename T > Tspeed::MyMatMultiDim < T >::MyMatMultiDim (Mesh_ptr m, unsigned int nln)
- 6.15.2.4 template < typename T > Tspeed::MyMatMultiDim < T > ::MyMatMultiDim (MyMatMultiDim < T > & a) [inline]

6.15.3 Member Function Documentation

6.15.3.1 template < typename T > T& Tspeed::MyMatMultiDim < T >::component(int i, int j) [inline]

Return monodimensimenial block (i,j)

Parameters

i	"row" index
j	"column" index

Returns

A monodimensional matrix of type

6.15.3.2 template<typename T> T const& Tspeed::MyMatMultiDim<T>::component(int i, int j) const [inline]

Return monodimensimenial block (i,j) (const version)

Parameters

i	"row" index
j	"column" index

Returns

A monodimensional matrix of type

- 6.15.3.3 template < typename T > Eigen::VectorXd Tspeed::MyMatMultiDim < T >::operator* (Eigen::VectorXd const & ν) const
- 6.15.3.4 template < typename T > MyMatMultiDim & Tspeed::MyMatMultiDim < T >::operator= (MyMatMultiDim < T > &&) [default]
- $6.15.3.5 \quad template < typename \ T > void \ Tspeed:: MyMatMultiDim < T > :: symmetrize \ (\quad)$

Sum matrix to self transposed.

6.15.3.6 template < typename T > void Tspeed::MyMatMultiDim < T >::vecMult (Eigen::VectorXd const & x, Eigen::VectorXd & out) const

Multiplication by a vector.

Parameters

in	X	term to be multiplied
out	out	result of the multiplication

- 6.15.4 Friends And Related Function Documentation
- 6.15.4.1 template < typename T > MyMatMultiDim < T > operator * (double const & x, MyMatMultiDim < T > const & A) [friend]
- 6.15.4.2 template<typename T> MyMatMultiDim<MyMat> operator+ (MyMatMultiDim< MyMat > const & a, MyMatMultiDim< MyMat > const & b) [friend]
- 6.15.4.3 template<typename T> MyMatMultiDim<MyMat> operator+ (MyMatMultiDim< MyMat> const & a, MyMatMultiDim< MyMatBlockDiag > const & b) [friend]

The documentation for this class was generated from the following file:

• lib/include/MyMat.hpp

6.16 Tspeed::MyMatMultiDimBlockDiag < T > Class Template Reference

Matrix class for matrices where only the diagonal monodimensional matrices are non zero (i.e. the mass matrix) #include <MyMat.hpp>

Public Member Functions

- MyMatMultiDimBlockDiag ()=default
- virtual ~MyMatMultiDimBlockDiag ()=default
- MyMatMultiDimBlockDiag (Mesh ptr, unsigned int nln)
- T & component (int i)

Get monodimensional component (0,0) if i=0 or (1,1) if i=1:

• T const & component (int i) const

Get monodimensional component (0,0) if i=0 or (1,1) if i=1 (const version)

• void vecMult (Eigen::VectorXd const &x, Eigen::VectorXd &out) const

Multiplication by a vector.

- MyMatMultiDimBlockDiag (MyMatMultiDimBlockDiag &&)=default
- MyMatMultiDimBlockDiag & operator= (MyMatMultiDimBlockDiag &&)=default
- unsigned int nr () const

Get total number of rows.

• Eigen::VectorXd operator* (Eigen::VectorXd const &v) const

Friends

• MyMatMultiDimBlockDiag const & operator* (double const &x, MyMatMultiDimBlockDiag const &A)

6.16.1 Detailed Description

 $template < typename \ T > class \ Tspeed:: MyMatMultiDimBlockDiag < T >$

Matrix class for matrices where only the diagonal monodimensional matrices are non zero (i.e. the mass matrix)

Template Parameters

Т

6.16.2 Constructor & Destructor Documentation

- 6.16.2.2 template < typename T> virtual Tspeed::MyMatMultiDimBlockDiag < T>:: \sim MyMatMultiDimBlockDiag () [virtual], [default]
- 6.16.2.3 template<typename T > Tspeed::MyMatMultiDimBlockDiag< T >::MyMatMultiDimBlockDiag (Mesh_ptr m, unsigned int nln)

6.16.2.4 template < typename T > Tspeed::MyMatMultiDimBlockDiag < T >::MyMatMultiDimBlockDiag (MyMatMultiDimBlockDiag < T > &&) [default]

6.16.3 Member Function Documentation

6.16.3.1 template < typename T > T& Tspeed::MyMatMultiDimBlockDiag < T >::component (int i) [inline]

Get monodimensional component (0,0) if i=0 or (1,1) if i=1:

Parameters

i	Select component

Returns

Monodimensional matrix of type T

6.16.3.2 template < typename T> T const& Tspeed::MyMatMultiDimBlockDiag < T>::component (int i) const [inline]

Get monodimensional component (0,0) if i=0 or (1,1) if i=1 (const version)

Parameters

i	Select component

Returns

Monodimensional matrix of type T

 $\textbf{6.16.3.3} \quad \textbf{template} < \textbf{typename T} > \textbf{unsigned int Tspeed::MyMatMultiDimBlockDiag} < \textbf{T} > :: \textbf{nr () const} \quad \texttt{[inline]}$

Get total number of rows.

- 6.16.3.4 template < typename T > Eigen::VectorXd Tspeed::MyMatMultiDimBlockDiag < T >::operator * (Eigen::VectorXd const & v) const
- 6.16.3.5 template<typename T> MyMatMultiDimBlockDiag& Tspeed::MyMatMultiDimBlockDiag< T>::operator= (MyMatMultiDimBlockDiag< T> &&) [default]
- 6.16.3.6 template < typename T > void Tspeed::MyMatMultiDimBlockDiag < T >::vecMult (Eigen::VectorXd const & x, Eigen::VectorXd & out) const

Multiplication by a vector.

Parameters

in	Х	term to be multiplied
out	out	result of the multiplication

6.16.4 Friends And Related Function Documentation

6.16.4.1 template < typename T > MyMatMultiDimBlockDiag const& operator* (double const & x, MyMatMultiDimBlockDiag < T > const & A) [friend]

The documentation for this class was generated from the following file:

lib/include/MyMat.hpp

6.17 Tspeed::Parameters Class Reference

Class for the parameters λ,ρ,μ of the elastodynamics equations.

```
#include <FESpace.hpp>
```

Public Member Functions

- virtual ∼Parameters ()
- Parameters (Mesh_ptr m)
- void setp (std::string const &p, int const lab, double const lambda)

Set a parameter.

• double const & lambda (int i) const

Get lambda on element i.

· double const & mu (int i) const

Get mu on element i.

· double const & rho (int i) const

Get rho on element i.

double avg_p (std::string const &p, int i, int j) const

Get the value of the harmonic average of a parameter between two elements.

6.17.1 Detailed Description

Class for the parameters λ, ρ, μ of the elastodynamics equations.

6.17.2 Constructor & Destructor Documentation

```
6.17.2.1 virtual Tspeed::Parameters::~Parameters() [inline], [virtual]
```

6.17.2.2 Tspeed::Parameters::Parameters (Mesh_ptr m) [inline]

6.17.3 Member Function Documentation

6.17.3.1 double Tspeed::Parameters::avg_p (std::string const & p, int i, int j) const

Get the value of the harmonic average of a parameter between two elements.

Parameters

p string with the name of the parameter ("lambda", "mu", "rho")			
	i	index of one element	
	i	index of the seocnd element	

Returns

harmonic average

6.17.3.2 double const& Tspeed::Parameters::lambda (int i) const [inline]

Get lambda on element i.

Parameters

i	the index of the element	

6.17.3.3 double const& Tspeed::Parameters::mu (int i) const [inline]

Get mu on element i.

Parameters

i	the index of the element

6.17.3.4 double const& Tspeed::Parameters::rho (int i) const [inline]

Get rho on element i.

Parameters

i	the index of the element

6.17.3.5 void Tspeed::Parameters::setp (std::string const & p, int const lab, double const lambda)

Set a parameter.

Parameters

р	string with the name of the parameter ("lambda", "mu", "rho")
lab	attribute of the mesh partition on which the parameter is set
lambda	value of the parameter

The documentation for this class was generated from the following files:

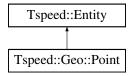
- lib/include/FESpace.hpp
- lib/src/Parameters.cpp

6.18 Tspeed::Geo::Point Class Reference

Class describing points.

#include <Geometry.hpp>

Inheritance diagram for Tspeed::Geo::Point:



Public Member Functions

Point (const double &x=0, const double &y=0)

Constructor taking the two coordinates of the point. By default, a point is initialized to the origin.

• Point (const Point &p)

Copy constructor. Everything is copied.

Point (const Eigen::Vector2d &v)

Constructor taking an Eigen fixed size vector. The components are copied, ids are not assigned.

- virtual ~Point ()
- double x () const

first coordinate

double y () const

second coordinate

• double & x ()

Reference to first coordinate.

double & y ()

Reference to second coordinate.

• Point & operator= (const Point &)

assignemnt operator

• Point operator* (const double &a) const

Multuply a point by a scalar.

• double norm () const

Norm of the vector from the origin to the point.

• Eigen::Vector2d toEig () const

convert the point into an Eigen::vector. Useful for matrix tranformations

Friends

• Point operator+ (const Point &a, const Point &b)

Operator summing two points.

• Point operator+ (const Eigen::Vector2d &a, const Point &b)

Sum a point and en eigen vector.

• Point operator+ (const Point &a, const Eigen::Vector2d &b)

Sum a point and en eigen vector.

Point operator- (const Point &a, const Point &b)

Operator sutracting two points.

• Point operator- (const Eigen::Vector2d &a, const Point &b)

Operator sutracting a point and a vector.

- Point operator- (const Point &, const Eigen::Vector2d &)
- Point operator* (const double &, const Point &)
- double dot (const Point &a, const Point &b)

vector-style dot product between points

Additional Inherited Members

6.18.1 Detailed Description

Class describing points.

6.18.2 Constructor & Destructor Documentation

```
6.18.2.1 Tspeed::Geo::Point::Point ( const double & x = 0, const double & y = 0 ) [inline]
```

Constructor taking the two coordinates of the point. By default, a point is initialized to the origin.

Parameters

X	x-coordinate
у	y-coordinate

6.18.2.2 Tspeed::Geo::Point::Point (const Point & p) [inline]

Copy constructor. Everything is copied.

Parameters

р	A point
•	·

6.18.2.3 Tspeed::Geo::Point::Point (const Eigen::Vector2d & v) [inline]

Constructor taking an Eigen fixed size vector. The components are copied, ids are not assigned.

Parameters

```
V
```

6.18.2.4 virtual Tspeed::Geo::Point::~Point() [inline], [virtual]

6.18.3 Member Function Documentation

6.18.3.1 double Tspeed::Geo::Point::norm () const [inline]

Norm of the vector from the origin to the point.

Returns

the euler norm

6.18.3.2 Point Tspeed::Geo::Point::operator* (const double & a) const

Multuply a point by a scalar.

Parameters

а	scalar

Returns

```
a both with both coordinates multiplied
6.18.3.3 Point & Tspeed::Geo::Point::operator= ( const Point & p )
assignemnt operator
6.18.3.4 Eigen::Vector2d Tspeed::Geo::Point::toEig() const [inline]
convert the point into an Eigen::vector. Useful for matrix tranformations
Returns
    the eigen vector with the coordinates as components
6.18.3.5 double Tspeed::Geo::Point::x() const [inline]
first coordinate
Returns
    x-coordinate
6.18.3.6 double& Tspeed::Geo::Point::x() [inline]
Reference to first coordinate.
Returns
    Reference to x-coord
6.18.3.7 double Tspeed::Geo::Point::y( )const [inline]
second coordinate
Returns
    y-coordinate
6.18.3.8 double& Tspeed::Geo::Point::y() [inline]
Reference to second coordinate.
Returns
```

Reference to y-coord

6.18.4 Friends And Related Function Documentation

6.18.4.1 double dot (const Point & a, const Point & b) [friend]

vector-style dot product between points

Parameters

а	first point
b	second point

Returns

a scalar

6.18.4.2 Point operator* (const double & *d***, const Point &** *p* **)** [friend]

6.18.4.3 Point operator+ (const Point & a, const Point & b) [friend]

Operator summing two points.

Parameters

а	first point
b	second point

Returns

sum of points

6.18.4.4 Point operator+ (const Eigen::Vector2d & a, const Point & b) [friend]

Sum a point and en eigen vector.

Parameters

а	vector
b	Point

Returns

Point

6.18.4.5 Point operator+ (const Point & a, const Eigen::Vector2d & b) [friend]

Sum a point and en eigen vector.

Parameters

а	Point
b	vector

Returns

Point

6.18.4.6 Point operator-(const Point & a, const Point & b) [friend]

Operator sutracting two points.

Parameters

а	first point
b	second point

Returns

difference of points

6.18.4.7 Point operator-(const Eigen::Vector2d & a, const Point & b) [friend]

Operator sutracting a point and a vector.

Parameters

а	first point
b	vector

Returns

point: difference of point a vector

6.18.4.8 Point operator-(const Point & a, const Eigen::Vector2d & b) [friend]

The documentation for this class was generated from the following files:

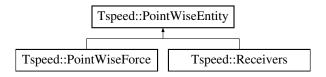
- lib/include/Geometry.hpp
- · lib/src/Geometry.cpp

6.19 Tspeed::PointWiseEntity Class Reference

A base class for pointwise entities, with the points and the basis function in that points.

#include <Receivers.hpp>

Inheritance diagram for Tspeed::PointWiseEntity:



Public Member Functions

- virtual ∼PointWiseEntity ()
- Eigen::ArrayXd const & shape (int i) const

All shape functions at point i.

Geo::Point const & point (int i) const

Point i, with coordinates in the reference triangle.

• unsigned int const & elem (int i) const

The index of the element where point i resides.

• unsigned int size () const

The number of points.

Protected Member Functions

```
    template<int N, typename Q, typename S >
    void M_add (FESpace_ptr< N, Q, S >, Geo::Point const &)
```

Protected Attributes

- std::vector< unsigned int > M_ie
- std::vector< Geo::Point > M_relp
- std::vector< Eigen::ArrayXd > M_shape
- unsigned int M nel

6.19.1 Detailed Description

A base class for pointwise entities, with the points and the basis function in that points.

6.19.2 Constructor & Destructor Documentation

```
\textbf{6.19.2.1} \quad \textbf{virtual Tspeed::PointWiseEntity::} \sim \textbf{PointWiseEntity ( )} \quad \texttt{[inline], [virtual]}
```

6.19.3 Member Function Documentation

```
6.19.3.1 unsigned int const& Tspeed::PointWiseEntity::elem ( int i ) const [inline]
```

The index of the element where point i resides.

Parameters

```
i the index of the point
```

Returns

the index of the triangle

```
6.19.3.2 template < int N, typename Q , typename S > void Tspeed::PointWiseEntity::M_add ( FESpace_ptr < N, Q, S > Xh, Geo::Point const & p ) [protected]
```

6.19.3.3 Geo::Point const& Tspeed::PointWiseEntity::point(inti) const [inline]

Point i, with coordinates in the reference triangle.

Parameters

i the index of the point

Returns

The point

6.19.3.4 Eigen::ArrayXd const& Tspeed::PointWiseEntity::shape (int i) const [inline]

All shape functions at point i.

Parameters

```
i the index of the point
```

Returns

an array of all functions

6.19.3.5 unsigned int Tspeed::PointWiseEntity::size () const [inline]

The number of points.

6.19.4 Member Data Documentation

6.19.4.1 std::vector<unsigned int> Tspeed::PointWiseEntity::M_ie [protected]

6.19.4.2 unsigned int Tspeed::PointWiseEntity::M_nel [protected]

6.19.4.3 std::vector<Geo::Point> Tspeed::PointWiseEntity::M_relp [protected]

 $\textbf{6.19.4.4} \quad \textbf{std::vector} < \textbf{Eigen::ArrayXd} > \textbf{Tspeed::PointWiseEntity::M_shape} \quad \texttt{[protected]}$

The documentation for this class was generated from the following files:

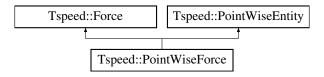
- lib/include/Receivers.hpp
- lib/include/Receivers_imp.hpp

6.20 Tspeed::PointWiseForce Class Reference

Time dependent force acting on a point.

#include <Force.hpp>

Inheritance diagram for Tspeed::PointWiseForce:



Public Member Functions

template<int N, typename Q, typename S >
 PointWiseForce (std::function< std::array< double, 2 >(const double &)> const &f, Geo::Point p, FESpace_ptr< N, Q, S > Xh)

Costructor taking the function, the point where the force is applied and the function space.

- virtual ~PointWiseForce ()
- · Vec eval (const double &t) const

Get value of force vector, i.e.

$$r_i = \int_K f \psi_i$$

at time t, where f is non null in K.

Additional Inherited Members

6.20.1 Detailed Description

Time dependent force acting on a point.

6.20.2 Constructor & Destructor Documentation

6.20.2.1 template < int N, typename Q , typename S > Tspeed::PointWiseForce::PointWiseForce (std::function < std::array < double, 2 > (const double &) > const & f, Geo::Point p, FESpace_ptr < N, Q, S > Xh)

Costructor taking the function, the point where the force is applied and the function space.

Template Parameters

N,Q,S	the template parameters of the function space

Parameters

f	the force
р	the point
Xh	the space

 $\textbf{6.20.2.2} \quad \textbf{virtual Tspeed::PointWiseForce::} \sim \textbf{PointWiseForce()} \quad [\texttt{inline}], \texttt{[virtual]}$

6.20.3 Member Function Documentation

6.20.3.1 Eigen::VectorXd Tspeed::PointWiseForce::eval (const double & t) const [virtual]

Get value of force vector, i.e.

$$r_i = \int_{K} f \psi_i$$

at time t, where f is non null in K.

Parameters

t	the time

Returns

a vector with elements r_i

Implements Tspeed::Force.

The documentation for this class was generated from the following files:

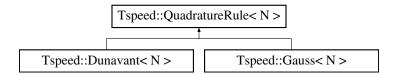
- lib/include/Force.hpp
- lib/include/Force_imp.hpp
- lib/src/Force.cpp

6.21 Tspeed::QuadratureRule < N > Class Template Reference

Base class for quadrature rules.

#include <QuadratureRule.hpp>

Inheritance diagram for Tspeed::QuadratureRule < N >:



Public Member Functions

- QuadratureRule ()=default
- Vec edge_weights () const

Get weights on the edge.

• Vec2 int_weights () const

Get internal weights.

· Geo::Point inode (unsigned int i) const

Get i-th qudrature node.

· double eweight (unsigned int i) const

Get i-th weight on the edge.

· double iweight (unsigned int i) const

Get i-th interior weight.

size_t edge_n () const

Number of nodes or weights on the edge.

size_t int_n () const

Number of interior nodes or weights.

Mat int_nodes () const

Get all interior nodes.

• Eigen::Matrix< double, N, 2 > edge_nodes (int i) const

Get all nodes on edge i of the reference triangle.

- virtual ∼QuadratureRule ()
- · unsigned int nqn2d () const

Number of internal nodes/weights.

Public Attributes

 EIGEN_MAKE_ALIGNED_OPERATOR_NEW Required by Eigen.

Protected Types

- typedef Eigen::Matrix< double, Eigen::Dynamic, 1 > Vec2
- typedef Eigen::Matrix< double, Eigen::Dynamic, 2 > Mat
- typedef Eigen::Matrix< double,
 N, 1 > Vec

Protected Attributes

- Vec2 M_w_2D
- Mat M node 2D
- Vec M_node_1D
- Vec M_w_1D
- size_t M_nqn_1D
- size_t M_nqn_2D

6.21.1 Detailed Description

template<int N>class Tspeed::QuadratureRule< N>

Base class for quadrature rules.

Template Parameters

N order of the rule

6.21.2 Member Typedef Documentation

- 6.21.2.1 template < int N > typedef Eigen::Matrix < double, Eigen::Dynamic, 2 > Tspeed::QuadratureRule < N >::Mat [protected]
- $\textbf{6.21.2.2} \quad \textbf{template} \\ < \textbf{int N} > \textbf{typedef Eigen::Matrix} \\ < \textbf{double, N, 1} > \textbf{Tspeed::QuadratureRule} \\ < \textbf{N} > \\ :: \textbf{Vec} \\ \\ [\texttt{protected}]$
- $\textbf{6.21.2.3} \quad \textbf{template} < \textbf{int N} > \textbf{typedef Eigen::Matrix} < \textbf{double, Eigen::Dynamic, 1} > \textbf{Tspeed::QuadratureRule} < \textbf{N} > :: \textbf{Vec2} \\ [\texttt{protected}]$

6.21.3 Constructor & Destructor Documentation

- $\textbf{6.21.3.1} \quad \textbf{template} < \textbf{int N} > \textbf{Tspeed::QuadratureRule} < \textbf{N} > \textbf{::QuadratureRule} (\ \textbf{)} \quad \texttt{[default]}$
- 6.21.3.2 template < int N> virtual Tspeed::QuadratureRule < N>:: \sim QuadratureRule () [inline], [virtual]

6.21.4 Member Function Documentation

6.21.4.1 template<int N> size_t Tspeed::QuadratureRule< N>::edge_n()const [inline]

Number of nodes or weights on the edge.

6.21.4.2 template < int N> Eigen::Matrix< double, N, 2> Tspeed::QuadratureRule< N>::edge_nodes (int i) const [inline]

Get all nodes on edge i of the reference triangle.

Note that ede nodes always have a Gauss-Legendre distribution, whatever rule is used in the interior

Parameters

```
i The edge of the reference triangle
```

Returns

A matrix of size number of nodes x 2

6.21.4.3 template < int N > Vec Tspeed::QuadratureRule < N >::edge_weights () const [inline]

Get weights on the edge.

Returns

The vector of the weights

6.21.4.4 template<int N> double Tspeed::QuadratureRule< N>::eweight (unsigned int i) const [inline]

Get i-th weight on the edge.

Parameters

i	the index of the weight

Returns

the weight

6.21.4.5 template < int N > Geo::Point Tspeed::QuadratureRule < N >::inode (unsigned int i) const [inline]

Get i-th qudrature node.

Parameters

i	The index of the node

```
Returns
```

A Point

6.21.4.6 template < int N > size_t Tspeed::QuadratureRule < N >::int_n () const [inline]

Number of interior nodes or weights.

6.21.4.7 template<int N> Mat Tspeed::QuadratureRule< N>::int_nodes() const [inline]

Get all interior nodes.

Returns

A matrix of size number of nodes x 2

 $\textbf{6.21.4.8} \quad \textbf{template} < \textbf{int N} > \textbf{Vec2 Tspeed::QuadratureRule} < \textbf{N} > :: \textbf{int_weights () const} \quad \texttt{[inline]}$

Get internal weights.

Returns

The vector of the weights

6.21.4.9 template < int N > double Tspeed::QuadratureRule < N >::iweight (unsigned int i) const [inline]

Get i-th interior weight.

Parameters

i the index of the weight

Returns

the weight

6.21.4.10 template < int N > unsigned int Tspeed::QuadratureRule < N >::nqn2d() const [inline]

Number of internal nodes/weights.

6.21.5 Member Data Documentation

6.21.5.1 template<int N> Tspeed::QuadratureRule< N>::EIGEN_MAKE_ALIGNED_OPERATOR_NEW

Required by Eigen.

6.21.5.2 template < int N > Vec Tspeed::QuadratureRule < N >::M_node_1D [protected]

6.21.5.3 template<int N> Mat Tspeed::QuadratureRule< N>::M_node_2D [protected]

6.21.5.4 template<int N> size_t Tspeed::QuadratureRule< N>::M_nqn_1D [protected]

- 6.21.5.5 template < int N > size_t Tspeed::QuadratureRule < N >::M_nqn_2D [protected]
- 6.21.5.6 template<int N> Vec Tspeed::QuadratureRule< N>::M_w_1D [protected]
- 6.21.5.7 template < int N > Vec2 Tspeed::QuadratureRule < N >::M_w_2D [protected]

The documentation for this class was generated from the following files:

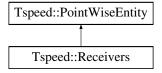
- lib/include/QuadratureRule.hpp
- lib/include/QuadratureRule_imp.hpp

6.22 Tspeed::Receivers Class Reference

A class for seismic receivers, i.e., receivers recording the movement at a point.

#include <Receivers.hpp>

Inheritance diagram for Tspeed::Receivers:



Public Member Functions

template<int N, typename Q, typename S >
 Receivers (FESpace ptr< N, Q, S > Xh, std::string const &fname)

Constructor taking the function space and a file with the coordinates of the receivers listed (x-coord and y-coord on every row)

template<int N, typename Q, typename S >
 Receivers (FESpace_ptr< N, Q, S > Xh, Geo::Point const &p)

Constructor taking the function space and a point.

- · void add (double const &x, double const &y, unsigned int const &ir, unsigned int const &step)
 - Add the the value (x,y) of receiver ir at time step step.
- · void write (std::string const &fn) const

Write all recorded values to file.

Additional Inherited Members

6.22.1 Detailed Description

A class for seismic receivers, i.e., receivers recording the movement at a point.

6.22.2 Constructor & Destructor Documentation

6.22.2.1 template < int N, typename Q , typename S > Tspeed::Receivers::Receivers (FESpace_ptr< N, Q, S > Xh, std::string const & fname)

Constructor taking the function space and a file with the coordinates of the receivers listed (x-coord and y-coord on every row)

Template Parameters

N,Q,S	the template parameters of the function space

Parameters

Xh	the space
fname	the name of the file with the receivers

6.22.2.2 template < int N, typename Q , typename S > Tspeed::Receivers::Receivers (FESpace_ptr < N, Q, S > Xh, Geo::Point const & p)

Constructor taking the function space and a point.

Template Parameters

N,Q,S	the template parameters of the function space

Parameters

Xh	the space
р	the point where the receiver is

6.22.3 Member Function Documentation

6.22.3.1 void Tspeed::Receivers::add (double const & x, double const & y, unsigned int const & ir, unsigned int const & step)

Add the the value (x,y) of receiver ir at time step step.

Parameters

X	the x displacement recorded
У	the y displacement recorded
ir	the index of the receiver
step	the time step of the simulation

6.22.3.2 void Tspeed::Receivers::write (std::string const & fn) const

Write all recorded values to file.

Parameters

fn	the name of the output file

The documentation for this class was generated from the following files:

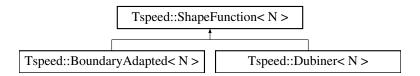
- lib/include/Receivers.hpp
- lib/include/Receivers imp.hpp
- lib/src/Receivers.cpp

6.23 Tspeed::ShapeFunction < N > Class Template Reference

Base class for the shared functions.

#include <ShapeFunctions.hpp>

Inheritance diagram for Tspeed::ShapeFunction < N >:



Public Types

• enum { gdl = (N+1)*(N+2)/2 }

Number of degrees of freedom.

enum { is_orthonormal = false }

Orthonormality of the basis.

Public Member Functions

- virtual ∼ShapeFunction ()
- ShapeFunction ()
- Eigen::ArrayXd phi (unsigned int s, Arr const &v, Arr const &w) const

Get value of base function with index s, on points (v,w)

• double phi (unsigned int s, double x, double y) const

Get value of base function with index s, on point (x,y)

ArrG grad (unsigned int s, Arr const &v, Arr const &w)

Get values of gradient of basis function s, on points (v,w)

Protected Attributes

- std::vector< std::function
 - < Arr(Arr const &, Arr const &)> > M_phi
- std::vector< std::function
 - < ArrG(Arr const &, Arr const &)> > M_grad

6.23.1 Detailed Description

template<int N>class Tspeed::ShapeFunction< N>

Base class for the shared functions.

Template Parameters

N degree of the space \mathbb{P}_N

6.23.2 Member Enumeration Documentation

6.23.2.1 template < int N > anonymous enum

Number of degrees of freedom.

Enumerator

gdl

6.23.2.2 template < int N> anonymous enum

Orthonormality of the basis.

Enumerator

is orthonormal

6.23.3 Constructor & Destructor Documentation

```
6.23.3.1 template < int N> virtual Tspeed::ShapeFunction < N>::\simShapeFunction ( ) [inline], [virtual]
```

- 6.23.3.2 template < int N > Tspeed::ShapeFunction < N >::ShapeFunction () [inline]
- 6.23.4 Member Function Documentation
- 6.23.4.1 template < int N> ArrG Tspeed::ShapeFunction < N>::grad (unsigned int s, Arr const & v, Arr const & w) [inline]

Get values of gradient of basis function s, on points (v,w)

Parameters

S	Index f the function
V	x-coordinates of the points
W	y-coordinates of the points

Returns

An array of dimension length(v), 2 with the values

6.23.4.2 template<int N> Eigen::ArrayXd Tspeed::ShapeFunction< N>::phi (unsigned int s, Arr const & v, Arr const & w) const [inline]

Get value of base function with index s, on points (v,w)

Parameters

S	index of the basis function
V	x-coordinates of the points
W	y-coordinates of the points

Returns

An Eigen array with the values

6.23.4.3 template < int N> double Tspeed::ShapeFunction < N>::phi (unsigned int s, double x, double y) const [inline]

Get value of base function with index s, on point (x,y)

Parameters

S	index of the basis function
X	x-coordinates of the point
У	y-coordinates of the point

Returns

the value

6.23.5 Member Data Documentation

```
6.23.5.1 template < int N> std::vector< std::function< Arr G(Arr const &, Arr const &)>> Tspeed::ShapeFunction< N>::M_grad [protected]
```

The documentation for this class was generated from the following file:

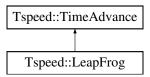
• lib/include/ShapeFunctions.hpp

6.24 Tspeed::TimeAdvance Class Reference

Base class for time stepping methods.

```
#include <TimeAdvance.hpp>
```

Inheritance diagram for Tspeed::TimeAdvance:



Public Member Functions

template<int N, typename Q, typename S >
 TimeAdvance (FESpace_ptr< N, Q, S > Xh, Parameters const &p, Receivers const &r)
 constructor from the space, parameters and receivers

void first_step ()

The first step of the method (which is different for 2nd order methods)

void step (double t)

step at time t

- virtual ∼TimeAdvance ()
- void set_dt (double dt)

Set time step δt .

void set_tmax (double tmax)

Set end time of the simulation.

void set_penalty (double p)

set penalty for the stability matrix

void add_force (std::shared_ptr< Force > f)

Add the force.

template<int N, typename Q, typename S >
 void set_initial_v (FESpace_ptr< N, Q, S > Xh, std::function< std::array< double, 2 >(double, double)>
 fun)

Set initial speed ü.

template<int N, typename Q, typename S>
 void set_initial_u (FESpace_ptr< N, Q, S > Xh, std::function< std::array< double, 2 >(double, double)>
 fun)

Set initial displacement u.

• bool is_running ()

Check if the method has arrived at the final time.

Vec const & get_uh () const

Get the coefficients of the numerical solution u_h .

- Vec const & u () const
- void eval_receivers ()

Compute and store the value of the displacement at the receivers.

void write_receivers (std::string const &fn) const

Write the time series of the displacement at the receivers.

Protected Member Functions

• void update_variables (double t)

Protected Attributes

- double M_penalty
- double M_dt
- double M_tmax
- Vec f
- Vec fold
- · Vec foldold
- Vec uh
- Vec uhold
- · Vec uholdold
- · Vec initial v
- Receivers M_recv
- Matrices M_mat
- MyMatMultiDim< MyMat > B
- std::shared_ptr< Force > M_f
- bool M_completed
- double M_last_step
- unsigned int M_recv_written
- unsigned int M_nln
- unsigned int M_ne

6.24.1 Detailed Description

Base class for time stepping methods.

6.24.2 Constructor & Destructor Documentation

6.24.2.1 template < int N, typename Q , typename S > Tspeed::TimeAdvance::TimeAdvance (FESpace_ptr< N, Q, S > Xh, Parameters const & p, Receivers const & r)

constructor from the space, parameters and receivers

Template Parameters

N,Q,S	template parameters of the space

Parameters

Xh	the function space
р	the parameters of the materials
r	the receivers

6.24.2.2 virtual Tspeed::TimeAdvance::~TimeAdvance() [inline], [virtual]

6.24.3 Member Function Documentation

6.24.3.1 void Tspeed::TimeAdvance::add_force(std::shared_ptr< Force > f) [inline]

Add the force.

Parameters

f	force

6.24.3.2 void Tspeed::TimeAdvance::eval_receivers ()

Compute and store the value of the displacement at the receivers.

6.24.3.3 void Tspeed::TimeAdvance::first_step ()

The first step of the method (which is different for 2nd order methods)

6.24.3.4 Vec const& Tspeed::TimeAdvance::get_uh() const [inline]

Get the coefficients of the numerical solution u_h .

Returns

 u_h

6.24.3.5 bool Tspeed::TimeAdvance::is_running() [inline]

Check if the method has arrived at the final time.

Returns

TRUE if it is still running

6.24.3.6 void Tspeed::TimeAdvance::set_dt (double dt) [inline]

Set time step δt .

Parameters

41.	the time step
dt	the lime step

6.24.3.7 template < int N, typename Q , typename S > void Tspeed::TimeAdvance::set_initial_u (FESpace_ptr < N, Q, S > $\it Xh$, std::function < std::array < double, 2 > (double, double) > $\it fun$)

Set initial displacement u.

Parameters

Xh	the function space
fun	u(x,y)

6.24.3.8 template < int N, typename Q , typename S > void Tspeed::TimeAdvance::set_initial_v (FESpace_ptr < N, Q, S > Xh, std::function < std::array < double, 2 > (double, double) > fun)

Set initial speed \dot{u} .

Parameters

Xh	the function space
fun	$\dot{u}(x,y)$

6.24.3.9 void Tspeed::TimeAdvance::set_penalty (double p) [inline]

set penalty for the stability matrix

Parameters

р	the penalty value

6.24.3.10 void Tspeed::TimeAdvance::set_tmax (double tmax) [inline]

Set end time of the simulation.

Parameters

tmax	the end time

6.24.3.11 void Tspeed::TimeAdvance::step (double t)

step at time t

Parameters

t the	the time
-------	----------

```
6.24.3.12 Vec const& Tspeed::TimeAdvance::u( ) const [inline]
6.24.3.13 void Tspeed::TimeAdvance::update_variables ( double t ) [inline], [protected]
6.24.3.14 void Tspeed::TimeAdvance::write_receivers ( std::string const & fn ) const [inline]
```

Write the time series of the displacement at the receivers.

Parameters

fn Base output file name

```
6.24.4
       Member Data Documentation
6.24.4.1 MyMatMultiDim<MyMat> Tspeed::TimeAdvance::B [protected]
6.24.4.2 Vec Tspeed::TimeAdvance::f [protected]
6.24.4.3 Vec Tspeed::TimeAdvance::fold [protected]
6.24.4.4 Vec Tspeed::TimeAdvance::foldold [protected]
6.24.4.5 Vec Tspeed::TimeAdvance::initial_v [protected]
6.24.4.6 bool Tspeed::TimeAdvance::M_completed [protected]
6.24.4.7 double Tspeed::TimeAdvance::M_dt [protected]
6.24.4.8 std::shared_ptr<Force> Tspeed::TimeAdvance::M_f [protected]
6.24.4.9 double Tspeed::TimeAdvance::M_last_step [protected]
6.24.4.10 Matrices Tspeed::TimeAdvance::M_mat [protected]
6.24.4.11 unsigned int Tspeed::TimeAdvance::M_ne [protected]
6.24.4.12 unsigned int Tspeed::TimeAdvance::M_nln [protected]
6.24.4.13 double Tspeed::TimeAdvance::M_penalty [protected]
6.24.4.14 Receivers Tspeed::TimeAdvance::M_recv [protected]
6.24.4.15 unsigned int Tspeed::TimeAdvance::M_recv_written [protected]
6.24.4.16 double Tspeed::TimeAdvance::M_tmax [protected]
6.24.4.17 Vec Tspeed::TimeAdvance::uh [protected]
6.24.4.18 Vec Tspeed::TimeAdvance::uhold [protected]
6.24.4.19 Vec Tspeed::TimeAdvance::uholdold [protected]
```

The documentation for this class was generated from the following files:

- lib/include/TimeAdvance.hpp
- lib/include/TimeAdvance_imp.hpp

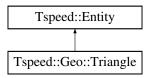
· lib/src/TimeAdvance.cpp

6.25 Tspeed::Geo::Triangle Class Reference

Class describing a triangle.

#include <Geometry.hpp>

Inheritance diagram for Tspeed::Geo::Triangle:



Public Member Functions

- Triangle ()
- Triangle (const Point &a, const Point &b, const Point &c)

Create a triangle from three points.

• Triangle (const Triangle &)=default

Copy constructor.

• Triangle & operator= (const Triangle &)

Assignement.

- virtual ∼Triangle ()
- std::array< Point, 3 > all_pts () const

Get all points of the triangle.

std::array< Edge, 3 > all_edges () const

Get all edges of a triangle.

· Point const & pt (int i) const

Get a point.

Edge const & edg (int i) const

Get a edge.

• Eigen::Matrix2d Jac () const

Get Jacobian of the transformation from the reference triangle.

Eigen::Matrix2d invJac () const

Get the inverse Jacobian of the transformation from the reference triangle.

double detJ () const

Get the determinant of the Jacobian of the tranformation from the reference triangle.

Point map (Point const &p) const

Map a point from its relative position in the reference triangle to the physical point.

Point invmap (Point const &p) const

Map a point from the physical triangle to the reference one.

· int const & neigh (int i) const

Ged index of neighboring triangle on edge i.

• int const & neighedges (int i) const

Index of the edge i in the nieghboring triangle.

· void setNeigh (int i, int j)

Set neighboring triangle.

• void setNeighedges (int i, int j)

Set index of the edge of the nieghboring triangle.

• void printNeigh () const

Pirnt neighbors for the current triangle.

• bool intriangle (const Point &p) const

Check if point p is in triangle.

Static Public Attributes

• static const int numVertices =3

Additional Inherited Members

6.25.1 Detailed Description

Class describing a triangle.

6.25.2 Constructor & Destructor Documentation

```
6.25.2.1 Tspeed::Geo::Triangle::Triangle ( )
```

6.25.2.2 Tspeed::Geo::Triangle::Triangle (const Point & a, const Point & b, const Point & c)

Create a triangle from three points.

Parameters

```
a,b,c The three points
```

```
6.25.2.3 Tspeed::Geo::Triangle::Triangle ( const Triangle & ) [default]
```

Copy constructor.

```
6.25.2.4 virtual Tspeed::Geo::Triangle::~Triangle() [inline], [virtual]
```

6.25.3 Member Function Documentation

```
6.25.3.1 std::array<Edge,3> Tspeed::Geo::Triangle::all_edges( ) const [inline]
```

Get all edges of a triangle.

Returns

An array of the three edge

```
6.25.3.2 std::array<Point,3> Tspeed::Geo::Triangle::all_pts ( ) const [inline]
```

Get all points of the triangle.

Returns

An array of three points

6.25.3.3 double Tspeed::Geo::Triangle::detJ () const

Get the determinant of the Jacobian of the tranformation from the reference triangle.

Returns

the determinant of the Jacobian (i.e., Area(T)*2)

6.25.3.4 Edge const& Tspeed::Geo::Triangle::edg (int *i*) **const** [inline]

Get a edge.

Parameters

i Number of the edge in the triangle

Returns

The i-th edge

6.25.3.5 bool Tspeed::Geo::Triangle::intriangle (const Point & p) const

Check if point p is in triangle.

Parameters

n	The point
ρ	rne point

Returns

TRUE if the point is in the triangle

6.25.3.6 Eigen::Matrix2d Tspeed::Geo::Triangle::invJac () const

Get the inverse Jacobian of the transformation from the reference triangle.

Returns

The inverse Jacobian, in matrix form

6.25.3.7 Point Tspeed::Geo::Triangle::invmap (Point const & p) const

Map a point from the physical triangle to the reference one.

Parameters

р	The physical point

Returns

The point in the reference triangle

6.25.3.8 Eigen::Matrix2d Tspeed::Geo::Triangle::Jac () const

Get Jacobian of the transformation from the reference triangle.

Returns

The Jacobian, in matrix form

6.25.3.9 Point Tspeed::Geo::Triangle::map (Point const & p) const

Map a point from its relative position in the reference triangle to the physical point.

Parameters

```
p The point in the reference triangle
```

Returns

The physical point in the actual triangle

6.25.3.10 int const& Tspeed::Geo::Triangle::neigh (int i) const [inline]

Ged index of neighboring triangle on edge i.

Parameters

```
i Edge of the triangle
```

Returns

Index of the neighbor

6.25.3.11 int const& Tspeed::Geo::Triangle::neighedges (int *i*) const [inline]

Index of the edge i in the nieghboring triangle.

Parameters

```
i Edge of the present triangle
```

Returns

Index of the edge in the neighboring triangle

6.25.3.12 Triangle & Tspeed::Geo::Triangle::operator= (const Triangle & t)

Assignement.

6.25.3.13 void Tspeed::Geo::Triangle::printNeigh() const [inline]

Pirnt neighbors for the current triangle.

6.25.3.14 Point const& Tspeed::Geo::Triangle::pt (int *i* **) const** [inline]

Get a point.

Parameters

i Number of the point in the triangle	

Returns

The i-th point

6.25.3.15 void Tspeed::Geo::Triangle::setNeigh (int *i***, int** *j* **)** [inline]

Set neighboring triangle.

Parameters

i	Edge of the current triangle
j	Index of the neighbor

6.25.3.16 void Tspeed::Geo::Triangle::setNeighedges(int i, int j) [inline]

Set index of the edge of the nieghboring triangle.

Parameters

i	Edge of the current trinagle
j	Edge in the neighboring triangle

6.25.4 Member Data Documentation

6.25.4.1 const int Tspeed::Geo::Triangle::numVertices =3 [static]

The documentation for this class was generated from the following files:

- lib/include/Geometry.hpp
- lib/src/Geometry.cpp

Chapter 7

File Documentation

7.1 Examples/src/Lamb.cpp File Reference

```
#include "TSPEED.hpp"
#include <iostream>
```

Functions

• int main ()

7.1.1 Function Documentation

```
7.1.1.1 int main ( )
```

7.2 Examples/src/wedge.cpp File Reference

```
#include "TSPEED.hpp"
#include <iostream>
#include <memory>
```

Functions

- void wedge_init_param (double I, double m, double rho, double cf, double csurf, double &k, double &q, double &s, double &beta)
- int main ()

7.2.1 Function Documentation

```
7.2.1.1 int main ( )
```

7.2.1.2 void wedge_init_param (double *I*, double *m*, double *rho*, double *cf*, double *csurf*, double & *k*, double & *q*, double & *s*, double & *beta*)

7.3 lib/include/Dunavant.hpp File Reference

Header files for the implementation of the Dunavant rules.

Functions

- int dunavant_degree (int rule)
- int dunavant_order_num (int rule)
- void dunavant_rule (int rule, int order_num, double xy[], double w[])
- int dunavant_rule_num (void)
- int * dunavant suborder (int rule, int suborder num)
- int dunavant suborder num (int rule)
- void dunavant_subrule (int rule, int suborder_num, double suborder_xyz[], double suborder_w[])
- void dunavant_subrule_01 (int suborder_num, double suborder_xyz[], double suborder_w[])
- void dunavant_subrule_02 (int suborder_num, double suborder_xyz[], double suborder_w[])
- void dunavant_subrule_03 (int suborder_num, double suborder_xyz[], double suborder_w[])
- void dunavant_subrule_04 (int suborder_num, double suborder_xyz[], double suborder_w[])
- void dunavant_subrule_05 (int suborder_num, double suborder_xyz[], double suborder_w[])
- void dunavant subrule 06 (int suborder num, double suborder xyz[], double suborder w[])
- void dunavant subrule 07 (int suborder num, double suborder xyz[], double suborder w[])
- void dunavant subrule 08 (int suborder num, double suborder xyz[], double suborder w[])
- and the second subsection of the second subsec
- void dunavant_subrule_09 (int suborder_num, double suborder_xyz[], double suborder_w[])
- void dunavant_subrule_10 (int suborder_num, double suborder_xyz[], double suborder_w[])
- void dunavant_subrule_11 (int suborder_num, double suborder_xyz[], double suborder_w[])
- void dunavant_subrule_12 (int suborder_num, double suborder_xyz[], double suborder_w[])
- void dunavant_subrule_13 (int suborder_num, double suborder_xyz[], double suborder_w[])
- void dunavant_subrule_14 (int suborder_num, double suborder_xyz[], double suborder_w[])
- void dunavant_subrule_15 (int suborder_num, double suborder_xyz[], double suborder_w[])
- void dunavant_subrule_16 (int suborder_num, double suborder_xyz[], double suborder_w[])
 void dunavant_subrule_17 (int suborder_num, double suborder_xyz[], double suborder_w[])
- void dunavant subrule 18 (int suborder num, double suborder xyz[], double suborder w[])
- void dunavant subrule 19 (int suborder num, double suborder xyz[], double suborder w[])
- void dunavant subrule 20 (int suborder num, double suborder xyz[], double suborder w[])
- void file name inc (char *file name)
- int i4_max (int i1, int i2)
- int i4_min (int i1, int i2)
- int i4_modp (int i, int j)
- int i4_wrap (int ival, int ilo, int ihi)
- double r8 huge (void)
- int r8 nint (double x)
- void reference_to_physical_t3 (double t[], int n, double ref[], double phy[])
- int s_len_trim (char *s)
- · void timestamp (void)
- char * timestring (void)
- double triangle area (double t[2 *3])
- void triangle_points_plot (char *file_name, double node_xy[], int node_show, int point_num, double point_xy[], int point_show)

7.3.1 Detailed Description

Header files for the implementation of the Dunavant rules.

Author

John Burkardt

```
7.3.2
        Function Documentation
7.3.2.1
        int dunavant_degree ( int rule )
7.3.2.2
        int dunavant_order_num ( int rule )
        void dunavant_rule ( int rule, int order_num, double xy[], double w[] )
7.3.2.3
7.3.2.4
        int dunavant_rule_num ( void )
        int* dunavant_suborder ( int rule, int suborder_num )
7.3.2.5
7.3.2.6
        int dunavant_suborder_num ( int rule )
7.3.2.7
        void dunavant_subrule ( int rule, int suborder_num, double suborder_xyz[], double suborder_w[] )
7.3.2.8
        void dunavant_subrule_01 ( int suborder_num, double suborder_xyz[], double suborder_w[] )
7.3.2.9
        void dunavant_subrule_02 ( int suborder_num, double suborder_xyz[], double suborder_w[] )
7.3.2.10
         void dunavant_subrule_03 ( int suborder_num, double suborder_xyz[], double suborder_w[] )
7.3.2.11
         void dunavant_subrule_04 ( int suborder_num, double suborder_xyz[], double suborder_w[] )
         void dunavant_subrule_05 ( int suborder_num, double suborder_xyz[], double suborder_w[] )
         void dunavant_subrule_06 ( int suborder_num, double suborder_xyz[], double suborder_w[] )
         void dunavant_subrule_07 ( int suborder_num, double suborder_xyz[], double suborder_w[] )
         void dunavant_subrule_08 ( int suborder_num, double suborder_xyz[], double suborder_w[] )
7.3.2.15
7.3.2.16
         void dunavant_subrule_09 ( int suborder_num, double suborder_xyz[], double suborder_w[] )
         void dunavant_subrule_10 ( int suborder_num, double suborder_xyz[], double suborder_w[] )
7.3.2.17
         void dunavant_subrule_11 ( int suborder_num, double suborder_xyz[], double suborder_w[] )
7.3.2.18
7.3.2.19
         void dunavant_subrule_12 ( int suborder_num, double suborder_xyz[], double suborder_w[] )
7.3.2.20
         void dunavant_subrule_13 ( int suborder_num, double suborder_xyz[], double suborder_w[] )
7.3.2.21
         void dunavant_subrule_14 ( int suborder_num, double suborder_xyz[], double suborder_w[] )
         void dunavant_subrule_15 ( int suborder_num, double suborder_xyz[], double suborder_w[] )
7.3.2.23
         void dunavant_subrule_16 ( int suborder_num, double suborder_xyz[], double suborder_w[] )
         void dunavant_subrule_17 ( int suborder_num, double suborder_xyz[], double suborder_w[] )
7.3.2.24
7.3.2.25
         void dunavant_subrule_18 ( int suborder_num, double suborder_xyz[], double suborder_w[] )
         void dunavant_subrule_19 ( int suborder_num, double suborder_xyz[], double suborder_w[] )
7.3.2.26
```

void dunavant_subrule_20 (int suborder_num, double suborder_xyz[], double suborder_w[])

7.3.2.27

```
7.3.2.28 void file_name_inc ( char * file_name )

7.3.2.29 int i4_max ( int i1, int i2 )

7.3.2.30 int i4_min ( int i1, int i2 )

7.3.2.31 int i4_modp ( int i, int j )

7.3.2.32 int i4_wrap ( int ival, int ilo, int ihi )

7.3.2.33 double r8_huge ( void )

7.3.2.34 int r8_nint ( double x )

7.3.2.35 void reference_to_physical_t3 ( double t[], int n, double ref[], double phy[] )

7.3.2.36 int s_len_trim ( char * s )

7.3.2.37 void timestamp ( void )

7.3.2.38 char* timestring ( void )

7.3.2.39 double triangle_area ( double t[2*3] )

7.3.2.40 void triangle_points_plot ( char * file_name, double node_xy[], int node_show, int point_num, double point_xy[], int point_show )
```

7.4 lib/include/FESpace.hpp File Reference

Header file for the Galerkin space and for the parameters of the elastodynamics equation.

```
#include "QuadratureRule.hpp"
#include "ShapeFunctions.hpp"
#include "Mesh.hpp"
#include <Eigen/Dense>
#include <Eigen/StdVector>
#include <functional>
#include "FESpace_imp.hpp"
```

Classes

```
class Tspeed::FESpace < N, Q, S >
```

Functional space.

• class Tspeed::Parameters

Class for the parameters λ, ρ, μ of the elastodynamics equations.

Namespaces

namespace Tspeed

Typedefs

template<int N, typename Q = Gauss<N+1>, typename S = Dubiner<N>>
using Tspeed::FESpace_ptr = std::shared_ptr< FESpace< N, Q, S >>

template pointer to FESpace

7.4.1 Detailed Description

Header file for the Galerkin space and for the parameters of the elastodynamics equation.

Author

Carlo Marcati

Date

2013-09-08

7.5 lib/include/FESpace_imp.hpp File Reference

Implementation of the functional space class methods.

Namespaces

· namespace Tspeed

7.5.1 Detailed Description

Implementation of the functional space class methods.

Author

Carlo Marcati

Date

2013-09-08

7.6 lib/include/Force.hpp File Reference

Header file for the force.

```
#include <functional>
#include <Eigen/SparseCore>
#include "Receivers.hpp"
#include "FESpace.hpp"
#include <array>
#include "Force_imp.hpp"
```

Classes

• class Tspeed::Force virtual base class for forces

· class Tspeed::PointWiseForce

Time dependent force acting on a point.

Namespaces

namespace Tspeed

Typedefs

```
typedef std::shared_ptr< Force > Tspeed::Force_ptr
```

7.6.1 Detailed Description

Header file for the force.

Author

Carlo Marcati

Date

2013-09-08

7.7 lib/include/Force_imp.hpp File Reference

Implementation of the Pointwise force template methods.

```
#include "Force.hpp"
```

Namespaces

namespace Tspeed

7.7.1 Detailed Description

Implementation of the Pointwise force template methods.

Author

Carlo Marcati

Date

2013-09-08

7.8 lib/include/Geometry.hpp File Reference

Header file for the geometrical entities.

```
#include <array>
#include <cmath>
#include <Eigen/Dense>
#include <memory>
#include <limits>
#include <iostream>
```

Classes

class Tspeed::Entity

Base class for geometrical entities.

· class Tspeed::Geo::Point

Class describing points.

• class Tspeed::Geo::Edge

Class describing an edge.

· class Tspeed::Geo::Triangle

Class describing a triangle.

Namespaces

- namespace Tspeed
- namespace Tspeed::Geo

Enumerations

• enum Tspeed::Bc { Tspeed::Dirichlet, Tspeed::Neumann, Tspeed::Internal, Tspeed::Unassigned }

Functions

- std::ostream & Tspeed::Geo::operator<< (std::ostream &, Triangle const &)
- std::ostream & Tspeed::Geo::operator<< (std::ostream &, Point const &)

Variables

const unsigned int NVAL =std::numeric_limits<unsigned int>::max()

7.8.1 Detailed Description

Header file for the geometrical entities.

Author

Carlo Marcati

Date

2013-09-08

7.8.2 Variable Documentation

7.8.2.1 const unsigned int NVAL =std::numeric_limits<unsigned int>::max()

7.9 lib/include/Matrices_imp.hpp File Reference

Implementation of the matrices for the method - templated part.

Namespaces

namespace Tspeed

7.9.1 Detailed Description

Implementation of the matrices for the method - templated part.

Author

Carlo Marcati

Date

2013-09-08

7.10 lib/include/Mesh.hpp File Reference

Header file for the mesh.

```
#include <string>
#include <fstream>
#include <iostream>
#include <algorithm>
#include <map>
#include <Eigen/StdVector>
#include "Geometry.hpp"
```

Classes

· class Tspeed::Mesh

Namespaces

· namespace Tspeed

Typedefs

typedef std::shared_ptr< Mesh > Tspeed::Mesh_ptr
 Shared pointer to an element of type mesh.

7.10.1 Detailed Description

Header file for the mesh.

Author

Carlo Marcati

Date

2013-09-08

7.11 lib/include/MyMat.hpp File Reference

Header file for the matrices specialized for the Discontinuous Galerkin method.

```
#include <Eigen/Dense>
#include <vector>
#include "Mesh.hpp"
#include <fstream>
```

Classes

· class Tspeed::BaseMat

Base monodimensional matrix class.

class Tspeed::MyMatBlockDiag

Block diagonal monodimensional matrix (monodimensional block of mass and stress-strain matrices)

class Tspeed::MyMat

Block Matrix (monodimensial blocks of stability and interelement matrices)

class Tspeed::MyMatMultiDim< T >

Multidimensional matrix.

class Tspeed::MyMatMultiDimBlockDiag< T >

Matrix class for matrices where only the diagonal monodimensional matrices are non zero (i.e. the mass matrix)

Namespaces

namespace Tspeed

Functions

- MyMat Tspeed::operator* (double const &c, MyMat const &M)
- Eigen::VectorXd Tspeed::operator* (MyMat const &, Eigen::VectorXd const &)
- Eigen::VectorXd Tspeed::operator* (MyMatBlockDiag const &, Eigen::VectorXd const &)
- MyMat Tspeed::operator+ (MyMat a, MyMat const &b)
- MyMat Tspeed::operator+ (MyMat a, MyMatBlockDiag const &b)

7.11.1 Detailed Description

Header file for the matrices specialized for the Discontinuous Galerkin method.

Author

Carlo Marcati

Date

2013-09-08

7.12 lib/include/QuadratureRule.hpp File Reference

Header file for the quadrature rules.

```
#include <Eigen/Dense>
#include <limits>
#include <iostream>
#include "Geometry.hpp"
#include "Dunavant.hpp"
#include "QuadratureRule_imp.hpp"
```

Classes

class Tspeed::QuadratureRule< N >

Base class for quadrature rules.

class Tspeed::Gauss < N >

Gauss quadrature rule on the triangle.

class Tspeed::Dunavant< N >

Dunavant [1] quadrature rule.

Namespaces

· namespace Tspeed

7.12.1 Detailed Description

Header file for the quadrature rules. A base class is implemented, with derived classes which implement Gauss quadrature on the triangle and Dunavant quadrature

Reference: [1] D. A. Dunavant, High degree efficient symmetrical Gaussian quadra- ture rules for the triangle, Internat. J. Numer. Methods Engrg. 21 (1985), no. 6, 1129–1148.

Author

Carlo Marcati

Date

2013-09-08

7.13 lib/include/QuadratureRule_imp.hpp File Reference

Implementation of the quadrature rules.

Namespaces

namespace Tspeed

7.13.1 Detailed Description

Implementation of the quadrature rules.

Author

Carlo Marcati

Date

2013-09-08

7.14 lib/include/Receivers.hpp File Reference

Header file containg the class for receivers and a base class for pointwise entities.

```
#include <string>
#include "Geometry.hpp"
#include "FESpace.hpp"
#include <fstream>
#include <vector>
#include "Receivers_imp.hpp"
```

Classes

· class Tspeed::PointWiseEntity

A base class for pointwise entities, with the points and the basis function in that points.

• class Tspeed::Receivers

A class for seismic receivers, i.e., receivers recording the movement at a point.

Namespaces

namespace Tspeed

7.14.1 Detailed Description

Header file containg the class for receivers and a base class for pointwise entities.

Author

Carlo Marcati

Date

2013-09-08

7.15 lib/include/Receivers_imp.hpp File Reference

Implementation of the pointwise entity and receivers class.

```
#include "Receivers.hpp"
```

Namespaces

namespace Tspeed

7.15.1 Detailed Description

Implementation of the pointwise entity and receivers class.

Author

Carlo Marcati

Date

2013-09-08

7.16 lib/include/ShapeFunctions.hpp File Reference

Header file for the definition of the shape functions.

```
#include <functional>
#include <vector>
#include <Eigen/Dense>
#include "ShapeFunctions_imp.hpp"
```

Classes

- class Tspeed::ShapeFunction < N >

Base class for the shared functions.

 $\bullet \ \, {\it class Tspeed::} Dubiner < N >$

Dubiner [1] basis.

class Tspeed::BoundaryAdapted< N >

Boundary adapted [2] basis.

Namespaces

· namespace Tspeed

7.16.1 Detailed Description

Header file for the definition of the shape functions. A base class is used, and the Dubiner and Boundary adapted derived classes are implemented. See

[1] M. Dubiner, Spectral methods on triangles and other domains, Journal of Scientific Computing 6 (1991), no. 4, 345–390

[2] G. E. Karniadakis and S. J. Sherwin, Spectral/hp element methods for computational fluid dynamics, second ed., Numerical Mathemat ics and Scientific Computation, Oxford University Press, New York.

Author

Carlo Marcati

Date

2013-09-08

7.17 lib/include/ShapeFunctions_imp.hpp File Reference

Implementation of the shape functions.

Namespaces

namespace Tspeed

Functions

• Eigen::ArrayXd Tspeed::jacobi_polynomial (int N, int alpha, int beta, Eigen::ArrayXd const &z)

7.17.1 Detailed Description

Implementation of the shape functions.

Author

Carlo Marcati

Date

2013-09-08

7.18 lib/include/TimeAdvance.hpp File Reference

Header file for the implementation of the time stepping and of the matrices for the method.

```
#include <Eigen/SparseCore>
#include <Eigen/Dense>
#include "FESpace.hpp"
#include "Receivers.hpp"
#include "Geometry.hpp"
#include "Force.hpp"
#include "MyMat.hpp"
#include <memory>
#include <limits>
#include "Matrices_imp.hpp"
#include "TimeAdvance_imp.hpp"
```

Classes

class Tspeed::Matrices

The class containing the matrices resulting from the spatial discretization.

· class Tspeed::TimeAdvance

Base class for time stepping methods.

class Tspeed::LeapFrog

Implementation of the second order Leap-Frog explicit time stepping scheme.

Namespaces

· namespace Tspeed

Functions

double Tspeed::mat_dot (Eigen::Matrix2d const &a, Eigen::Matrix2d const &b)
 Dot product between two 2x2 matrices.

• Eigen::Matrix2d Tspeed::CTensorProduct (Eigen::Matrix2d const &A, double lambda, double mu) tensor product between Hooke's tensor and matrix A

7.18.1 Detailed Description

Header file for the implementation of the time stepping and of the matrices for the method.

Author

Carlo Marcati

Version

Date

2013-09-08

7.19 lib/include/TimeAdvance_imp.hpp File Reference

Implementation of the time advancing template methods.

```
#include "TimeAdvance.hpp"
```

Namespaces

namespace Tspeed

7.19.1 Detailed Description

Implementation of the time advancing template methods.

Author

Carlo Marcati

Date

2013-09-08

7.20 lib/include/TSPEED.hpp File Reference

```
#include "QuadratureRule.hpp"
#include "ShapeFunctions.hpp"
#include "FESpace.hpp"
#include "Mesh.hpp"
#include "Receivers.hpp"
#include "Force.hpp"
#include "TimeAdvance.hpp"
#include "MyMat.hpp"
```

7.21 TSPEED.hpp File Reference

```
#include "QuadratureRule.hpp"
#include "ShapeFunctions.hpp"
#include "FESpace.hpp"
#include "Mesh.hpp"
#include "Receivers.hpp"
#include "Force.hpp"
#include "TimeAdvance.hpp"
#include "MyMat.hpp"
```

7.22 lib/src/Dunavant.cpp File Reference

Functions for Dunavant quadrature (nodes and weights, tabulated)

```
#include <cstdlib>
#include <iostream>
#include <fstream>
#include <iomanip>
#include <cmath>
#include <ctime>
#include <cstring>
#include "Dunavant.hpp"
```

Macros

```
#define TIME_SIZE 40#define TIME_SIZE 40
```

Functions

- int dunavant_degree (int rule)
- int dunavant_order_num (int rule)
- void dunavant_rule (int rule, int order_num, double xy[], double w[])
- int dunavant_rule_num ()
- int * dunavant_suborder (int rule, int suborder_num)
- int dunavant_suborder_num (int rule)
- void dunavant_subrule (int rule, int suborder_num, double suborder_xyz[], double suborder_w[])
- void dunavant_subrule_01 (int suborder_num, double suborder_xyz[], double suborder_w[])

```
    void dunavant_subrule_02 (int suborder_num, double suborder_xyz[], double suborder_w[])

    void dunavant_subrule_03 (int suborder_num, double suborder_xyz[], double suborder_w[])

    • void dunavant_subrule_04 (int suborder_num, double suborder_xyz[], double suborder_w[])

    void dunavant_subrule_05 (int suborder_num, double suborder_xyz[], double suborder_w[])

    void dunavant_subrule_06 (int suborder_num, double suborder_xyz[], double suborder_w[])

    • void dunavant subrule_07 (int suborder_num, double suborder_xyz[], double suborder_w[])

    void dunavant_subrule_08 (int suborder_num, double suborder_xyz[], double suborder_w[])

    • void dunavant_subrule_09 (int suborder_num, double suborder_xyz[], double suborder_w[])
    • void dunayant subrule 10 (int suborder num, double suborder xyz[], double suborder w[])
    • void dunavant_subrule_11 (int suborder_num, double suborder_xyz[], double suborder_w[])

    void dunavant_subrule_12 (int suborder_num, double suborder_xyz[], double suborder_w[])

    void dunavant subrule 13 (int suborder num, double suborder xyz[], double suborder w[])

    void dunavant_subrule_14 (int suborder_num, double suborder_xyz[], double suborder_w[])

    • void dunavant subrule 15 (int suborder num, double suborder xyz[], double suborder w[])
    • void dunavant subrule 16 (int suborder num, double suborder xyz[], double suborder w[])

    void dunavant subrule 17 (int suborder num, double suborder xyz[], double suborder w[])

    void dunavant_subrule_18 (int suborder_num, double suborder_xyz[], double suborder_w[])

    • void dunavant subrule 19 (int suborder num, double suborder xyz[], double suborder w[])

    void dunavant_subrule_20 (int suborder_num, double suborder_xyz[], double suborder_w[])

    • void file name inc (char *file name)

    int i4 max (int i1, int i2)

    • int i4_min (int i1, int i2)
    • int i4_modp (int i, int j)
    • int i4 wrap (int ival, int ilo, int ihi)
    • double r8 huge ()

    int r8_nint (double x)

    void reference_to_physical_t3 (double t[], int n, double ref[], double phy[])

    int s_len_trim (char *s)

    void timestamp ()

    char * timestring ()

    double triangle_area (double t[2 *3])

    void triangle_points_plot (char *file_name, double node_xy[], int node_show, int point_num, double point_-

      xy[], int point_show)
        Detailed Description
Functions for Dunavant quadrature (nodes and weights, tabulated)
```

Author

John Burkardt

Macro Definition Documentation

#define TIME_SIZE 40 7.22.2.1

#define TIME_SIZE 40 7.22.2.2

7.22.3 **Function Documentation**

7.22.3.1 int dunavant_degree (int rule)

7.22.3.2 int dunavant_order_num (int rule)

```
void dunavant_rule ( int rule, int order_num, double xy[], double w[] )
7.22.3.4
         int dunavant_rule_num ( void )
         int* dunavant_suborder ( int rule, int suborder_num )
7.22.3.5
7.22.3.6
         int dunavant_suborder_num ( int rule )
7.22.3.7
         void dunavant_subrule ( int rule, int suborder_num, double suborder_xyz[], double suborder_w[] )
         void dunavant_subrule_01 ( int suborder_num, double suborder_xyz[], double suborder_w[] )
7.22.3.9
         void dunavant_subrule_02 ( int suborder_num, double suborder_xyz[], double suborder_w[] )
7.22.3.10 void dunavant_subrule_03 ( int suborder_num, double suborder_xyz[], double suborder_w[] )
7.22.3.11 void dunavant_subrule_04 ( int suborder_num, double suborder_xyz[], double suborder_w[] )
7.22.3.12 void dunavant_subrule_05 ( int suborder_num, double suborder_xyz[], double suborder_w[] )
7.22.3.13 void dunavant_subrule_06 ( int suborder_num, double suborder_xyz[], double suborder_w[] )
7.22.3.14 void dunavant_subrule_07 ( int suborder_num, double suborder_xyz[], double suborder_w[] )
7.22.3.15 void dunavant_subrule_08 ( int suborder_num, double suborder_xyz[], double suborder_w[] )
7.22.3.16 void dunavant_subrule_09 ( int suborder_num, double suborder_xyz[], double suborder_w[] )
7.22.3.17 void dunavant_subrule_10 ( int suborder_num, double suborder_xyz[], double suborder_w[] )
7.22.3.18 void dunavant_subrule_11 ( int suborder_num, double suborder_xyz[], double suborder_w[] )
7.22.3.19 void dunavant_subrule_12 ( int suborder_num, double suborder_xyz[], double suborder_w[] )
7.22.3.20
          void dunavant_subrule_13 ( int suborder_num, double suborder_xyz[], double suborder_w[] )
7.22.3.21 void dunavant_subrule_14 ( int suborder_num, double suborder_xyz[], double suborder_w[] )
7.22.3.22 void dunavant_subrule_15 ( int suborder_num, double suborder_xyz[], double suborder_w[] )
7.22.3.23 void dunavant_subrule_16 ( int suborder_num, double suborder_xyz[], double suborder_w[] )
7.22.3.24
          void dunavant_subrule_17 ( int suborder_num, double suborder_xyz[], double suborder_w[] )
7.22.3.25 void dunavant_subrule_18 ( int suborder_num, double suborder_xyz[], double suborder_w[])
7.22.3.26 void dunavant_subrule_19 ( int suborder_num, double suborder_xyz[], double suborder_w[] )
7.22.3.27
          void dunavant_subrule_20 ( int suborder_num, double suborder_xyz[], double suborder_w[] )
7.22.3.28
          void file_name_inc ( char * file_name )
7.22.3.29
         int i4_max ( int i1, int i2 )
7.22.3.30 int i4_min ( int i1, int i2 )
```

92 File Documentation

```
7.22.3.31 int i4_modp ( int i, int j )
7.22.3.32 int i4_wrap ( int ival, int ilo, int ihi )
7.22.3.33 double r8_huge ( void )
7.22.3.34 int r8_nint ( double x )
7.22.3.35 void reference_to_physical_t3 ( double t[], int n, double ref[], double phy[] )
7.22.3.36 int s_len_trim ( char * s )
7.22.3.37 void timestamp ( void )
7.22.3.38 char* timestring ( void )
7.22.3.39 double triangle_area ( double t[2*3] )
7.22.3.40 void triangle_points_plot ( char * file_name, double node_xy[], int node_show, int point_num, double point_xy[], int point_show )
```

7.23 lib/src/Force.cpp File Reference

Implementation of the Force method.

```
#include "Force.hpp"
```

Namespaces

· namespace Tspeed

7.23.1 Detailed Description

Implementation of the Force method.

Author

Carlo Marcati

Date

2013-09-08

7.24 lib/src/Geometry.cpp File Reference

Implementation of the geometrical entities.

```
#include "Geometry.hpp"
```

Namespaces

- namespace Tspeed
- namespace Tspeed::Geo

Functions

- std::ostream & Tspeed::Geo::operator<< (std::ostream &, Point const &)
- Point Tspeed::Geo::operator- (const Point &a, const Point &b)
- Point Tspeed::Geo::operator- (const Eigen::Vector2d &a, const Point &b)
- Point Tspeed::Geo::operator- (const Point &a, const Eigen::Vector2d &b)
- Point Tspeed::Geo::operator+ (const Eigen::Vector2d &a, const Point &b)
- Point Tspeed::Geo::operator+ (const Point &a, const Eigen::Vector2d &b)
- Point Tspeed::Geo::operator+ (const Point &a, const Point &b)
- Point Tspeed::Geo::operator* (const double &d, const Point &p)
- std::ostream & Tspeed::Geo::operator<< (std::ostream &, Triangle const &)

7.24.1 Detailed Description

Implementation of the geometrical entities.

Author

Carlo Marcati

Date

2013-09-08

7.25 lib/src/Mesh.cpp File Reference

Implementation of the mesh.

```
#include "Mesh.hpp"
```

Namespaces

· namespace Tspeed

7.25.1 Detailed Description

Implementation of the mesh.

Author

Carlo Marcati

Date

2013-09-08

7.26 lib/src/MyMat.cpp File Reference

Implementation of the matrix classes.

```
#include "MyMat.hpp"
```

94 File Documentation

Namespaces

· namespace Tspeed

Functions

- Eigen::VectorXd Tspeed::operator* (MyMatMultiDimBlockDiag > const &A, Eigen::VectorXd const &v)
- Eigen::VectorXd Tspeed::operator* (MyMatMultiDim< MyMat > &A, Eigen::VectorXd const &v)
- Eigen::VectorXd Tspeed::operator* (MyMatMultiDim< MyMatBlockDiag > &A, Eigen::VectorXd const &v)
- MyMat Tspeed::operator* (double const &c, MyMat const &M)
- MyMatMultiDim< MyMat > Tspeed::operator+ (MyMatMultiDim< MyMat > const &a, MyMatMultiDim< MyMat > const &b)
- MyMatMultiDim< MyMat > Tspeed::operator+ (MyMatMultiDim< MyMat > const &a, MyMatMultiDim< My-MatBlockDiag > const &b)
- MyMat Tspeed::operator+ (MyMatBlockDiag const &b, MyMat a)
- MyMat Tspeed::operator+ (MyMat a, MyMatBlockDiag const &b)
- MyMat Tspeed::operator+ (MyMat a, MyMat const &b)
- Eigen::VectorXd Tspeed::operator* (MyMatBlockDiag const &, Eigen::VectorXd const &)
- Eigen::VectorXd Tspeed::operator* (MyMat const &, Eigen::VectorXd const &)

7.26.1 Detailed Description

Implementation of the matrix classes.

Author

Carlo Marcati

Date

2013-09-08

7.27 lib/src/Parameters.cpp File Reference

Implementation of the Parameters methods.

```
#include "FESpace.hpp"
```

Namespaces

namespace Tspeed

7.27.1 Detailed Description

Implementation of the Parameters methods.

Author

Carlo Marcati

Date

2013-09-08

7.28 lib/src/Receivers.cpp File Reference

Implementation of the Receivers methods.

```
#include "Receivers.hpp"
```

Namespaces

namespace Tspeed

7.28.1 Detailed Description

Implementation of the Receivers methods.

Author

Carlo Marcati

Date

2013-09-08

7.29 lib/src/ShapeFunctions.cpp File Reference

Implementation of the jacobi polynomials.

```
#include "ShapeFunctions.hpp"
```

Typedefs

• typedef Eigen::ArrayXd Arr

7.29.1 Detailed Description

Implementation of the jacobi polynomials.

Author

Carlo Marcati

Date

2013-09-08

7.29.2 Typedef Documentation

7.29.2.1 typedef Eigen::ArrayXd Arr

7.30 lib/src/TimeAdvance.cpp File Reference

Implmentation of the TimeAdvance methods.

```
#include "TimeAdvance.hpp"
```

96 File Documentation

Namespaces

namespace Tspeed

Functions

• Eigen::Matrix2d Tspeed::CTensorProduct (Eigen::Matrix2d const &A, double lambda, double mu) tensor product between Hooke's tensor and matrix A

• double Tspeed::mat_dot (Eigen::Matrix2d const &a, Eigen::Matrix2d const &b)

Dot product between two 2x2 matrices.

7.30.1 Detailed Description

Implmentation of the TimeAdvance methods.

Author

Carlo Marcati

Date

2013-09-08

7.31 main.cpp File Reference

```
#include "Dunavant.hpp"
#include <iostream>
```

Functions

• int main ()

7.31.1 Function Documentation

7.31.1.1 int main ()

Index

\sim BaseMat	Tspeed::Geo::Triangle, 71
Tspeed::BaseMat, 16	all_pts
\sim BoundaryAdapted	Tspeed::Geo::Triangle, 71
Tspeed::BoundaryAdapted, 19	Arr
~Dubiner	ShapeFunctions.cpp, 95
Tspeed::Dubiner, 20	avg_p
~Edge	Tspeed::Parameters, 47
Tspeed::Geo::Edge, 23	ropodam aramotoro, m
∼FESpace	В
Tspeed::FESpace, 28	Tspeed::TimeAdvance, 69
~Force	b_edge
Tspeed::Force, 32	Tspeed::FESpace, 28
~Mesh	base_invmass
	Tspeed::FESpace, 28
Tspeed::Mesh, 38	base mass
~MyMat	-
Tspeed::MyMat, 41	Tspeed::FESpace, 28
~MyMatBlockDiag	BaseMat
Tspeed::MyMatBlockDiag, 42	Tspeed::BaseMat, 16
~MyMatMultiDim	Bc
Tspeed::MyMatMultiDim, 43	Tspeed, 11
~MyMatMultiDimBlockDiag	bcld
Tspeed::MyMatMultiDimBlockDiag, 45	Tspeed::Entity, 25
\sim Parameters	block
Tspeed::Parameters, 47	Tspeed::BaseMat, 16
~Point	BoundaryAdapted
Tspeed::Geo::Point, 50	Tspeed::BoundaryAdapted, 19
\sim PointWiseEntity	
Tspeed::PointWiseEntity, 54	CTensorProduct
\sim PointWiseForce	Tspeed, 11
Tspeed::PointWiseForce, 56	collnd
\sim QuadratureRule	Tspeed::BaseMat, 17
Tspeed::QuadratureRule, 58	component
\sim ShapeFunction	Tspeed::MyMatMultiDim, 43, 44
Tspeed::ShapeFunction, 64	Tspeed::MyMatMultiDimBlockDiag, 46
\sim TimeAdvance	
Tspeed::TimeAdvance, 67	detJ
\sim Triangle	Tspeed::Geo::Triangle, 71
Tspeed::Geo::Triangle, 71	Dirichlet
Topodandoon mangio, 7	Tspeed, 11
add	dot
Tspeed::Receivers, 62	Tspeed::Geo::Point, 52
add force	Dubiner
Tspeed::TimeAdvance, 67	Tspeed::Dubiner, 20
AlignedVecE	Dunavant
Tspeed::Mesh, 38	Tspeed::Dunavant, 22
AlignedVecP	Dunavant.cpp
Tspeed::Mesh, 38	dunavant_degree, 90
AlignedVecT	dunavant order num, 90
Tspeed::Mesh, 38	dunavant_rule, 90
all_edges	dunavant_rule_num, 91
un_0ug00	danavant_raio_nam, 🗸

dunavant_suborder, 91	dunavant_subrule_14, 77
dunavant_suborder_num, 91	dunavant_subrule_15, 77
dunavant_subrule, 91	dunavant_subrule_16, 77
dunavant_subrule_01, 91	dunavant_subrule_17, 77
dunavant_subrule_02, 91	dunavant_subrule_18, 77
dunavant_subrule_03, 91	dunavant_subrule_19, 77
dunavant_subrule_04, 91	dunavant_subrule_20, 77
dunavant_subrule_05, 91	file_name_inc, 77
dunavant_subrule_06, 91	i4_max, 78
dunavant_subrule_07, 91	i4_min, 78
dunavant_subrule_08, 91	i4_modp, 78
dunavant_subrule_09, 91	i4_wrap, 78
dunavant_subrule_10, 91	r8_huge, 78
dunavant_subrule_11, 91	r8_nint, 78
dunavant_subrule_12, 91	reference_to_physical_t3, 78
dunavant_subrule_13, 91	s_len_trim, 78
dunavant_subrule_14, 91	timestamp, 78
dunavant_subrule_15, 91	timestring, 78
dunavant_subrule_16, 91	triangle_area, 78
dunavant_subrule_17, 91	triangle_points_plot, 78
dunavant_subrule_18, 91	dunavant_degree
dunavant_subrule_19, 91	Dunavant.cpp, 90
dunavant_subrule_20, 91	Dunavant.hpp, 77
file_name_inc, 91	dunavant_order_num
i4_max, 91	Dunavant.cpp, 90
i4_min, 91	Dunavant.hpp, 77
i4_modp, 91	dunavant_rule
i4_wrap, 92	Dunavant.cpp, 90
r8_huge, 92	Dunavant.hpp, 77
r8_nint, 92	dunavant_rule_num
reference_to_physical_t3, 92	Dunavant.cpp, 91
s_len_trim, 92	Dunavant.hpp, 77
TIME_SIZE, 90	dunavant_suborder
timestamp, 92	Dunavant.cpp, 91
timestring, 92	Dunavant.hpp, 77
triangle_area, 92	dunavant_suborder_num
triangle_points_plot, 92	Dunavant.cpp, 91
Dunavant.hpp	Dunavant.hpp, 77
dunavant_degree, 77	dunavant_subrule
dunavant_order_num, 77	Dunavant.cpp, 91
dunavant_rule, 77	Dunavant.hpp, 77
dunavant_rule_num, 77	dunavant_subrule_01
dunavant_suborder, 77	Dunavant.cpp, 91
dunavant_suborder_num, 77	Dunavant.hpp, 77
dunavant_subrule, 77	dunavant_subrule_02
dunavant_subrule_01, 77	Dunavant.cpp, 91
dunavant_subrule_02, 77	Dunavant.hpp, 77
dunavant_subrule_03, 77	dunavant_subrule_03
dunavant_subrule_04, 77	Dunavant.cpp, 91
dunavant_subrule_05, 77	Dunavant.hpp, 77
dunavant_subrule_06, 77	dunavant_subrule_04
dunavant_subrule_07, 77	Dunavant.cpp, 91
dunavant_subrule_08, 77	Dunavant.hpp, 77
dunavant_subrule_09, 77	dunavant_subrule_05
dunavant_subrule_10, 77	Dunavant.cpp, 91
dunavant_subrule_11, 77	Dunavant.hpp, 77
dunavant_subrule_12, 77	dunavant_subrule_06
dunavant_subrule_13, 77	Dunavant.cpp, 91

Dunavant.hpp, 77	Entity
dunavant_subrule_07	Tspeed::Entity, 25
Dunavant.cpp, 91	eval
Dunavant.hpp, 77	Tspeed::Force, 33
dunavant_subrule_08	Tspeed::PointWiseForce, 56
Dunavant.cpp, 91	eval_receivers
Dunavant.hpp, 77	Tspeed::TimeAdvance, 67
dunavant_subrule_09	eweight
Dunavant.cpp, 91	Tspeed::QuadratureRule, 59
Dunavant.hpp, 77	Examples/src/Lamb.cpp, 75
dunavant_subrule_10	Examples/src/wedge.cpp, 75
Dunavant.cpp, 91	4
Dunavant.hpp, 77	f Tanasadu Timas Adusanas CO
dunavant_subrule_11	Tspeed::TimeAdvance, 69
Dunavant.cpp, 91	FESpace
Dunavant.hpp, 77	Tspeed::FESpace, 28
dunavant_subrule_12	FESpace_ptr
Dunavant.cpp, 91	Tspeed, 11
Dunavant.hpp, 77	field_out
dunavant_subrule_13	Tspeed::FESpace, 29
Dunavant.cpp, 91	file_name_inc
Dunavant.hpp, 77	Dunavant.cpp, 91
dunavant_subrule_14	Dunavant.hpp, 77
Dunavant.cpp, 91	first_step
Dunavant.hpp, 77	Tspeed::LeapFrog, 35
dunavant_subrule_15	Tspeed::TimeAdvance, 67
Dunavant.cpp, 91	fold
Dunavant.hpp, 77	Tspeed::TimeAdvance, 69
dunavant_subrule_16	foldold
Dunavant.cpp, 91	Tspeed::TimeAdvance, 69
Dunavant.hpp, 77	Force
dunavant_subrule_17	Tspeed::Force, 32
Dunavant.cpp, 91	Force_ptr
Dunavant.hpp, 77	Tspeed, 11
dunavant_subrule_18	
Dunavant.cpp, 91	g_edge
Dunavant.hpp, 77	Tspeed::FESpace, 29
dunavant_subrule_19	Gauss
Dunavant.cpp, 91	Tspeed::Gauss, 34
Dunavant.hpp, 77	gdl
dunavant_subrule_20	Tspeed::ShapeFunction, 63
Dunavant.cpp, 91	Geometry.hpp
Dunavant.hpp, 77	NVAL, 81
	get_uh
edg	Tspeed::TimeAdvance, 67
Tspeed::Geo::Triangle, 72	getA
Edge	Tspeed::Matrices, 36
Tspeed::Geo::Edge, 22, 23	getl
edge_n	Tspeed::Matrices, 36
Tspeed::QuadratureRule, 58	getS
edge_nodes	Tspeed::Matrices, 37
Tspeed::QuadratureRule, 59	getinvM
edge_weights	Tspeed::Matrices, 37
Tspeed::QuadratureRule, 59	grad
elem	Tspeed::FESpace, 29
Tspeed::BaseMat, 17	Tspeed::ShapeFunction, 64
Tspeed::PointWiseEntity, 54	
elements	i4_max
Tspeed::Mesh, 38, 39	Dunavant.cpp, 91

Dunavant.hpp, 78	lib/include/FESpace.hpp, 78
i4_min	lib/include/FESpace_imp.hpp, 79
Dunavant.cpp, 91	lib/include/Force.hpp, 79
Dunavant.hpp, 78	lib/include/Force_imp.hpp, 80
i4_modp	lib/include/Geometry.hpp, 80
Dunavant.cpp, 91	lib/include/Matrices imp.hpp, 81
Dunavant.hpp, 78	lib/include/Mesh.hpp, 82
i4_wrap	lib/include/MyMat.hpp, 83
Dunavant.cpp, 92	lib/include/QuadratureRule.hpp, 84
Dunavant.hpp, 78	lib/include/QuadratureRule imp.hpp, 84
ld	lib/include/Receivers.hpp, 85
Tspeed::Entity, 25	lib/include/Receivers_imp.hpp, 85
id	lib/include/ShapeFunctions.hpp, 86
	•
Tspeed::Entity, 25	lib/include/ShapeFunctions_imp.hpp, 87
initial_v	lib/include/TSPEED.hpp, 89
Tspeed::TimeAdvance, 69	lib/include/TimeAdvance.hpp, 87
inode	lib/include/TimeAdvance_imp.hpp, 88
Tspeed::QuadratureRule, 59	lib/src/Dunavant.cpp, 89
int_n	lib/src/Force.cpp, 92
Tspeed::QuadratureRule, 60	lib/src/Geometry.cpp, 92
int nodes	lib/src/Mesh.cpp, 93
Tspeed::QuadratureRule, 60	lib/src/MyMat.cpp, 93
int_weights	lib/src/Parameters.cpp, 94
Tspeed::QuadratureRule, 60	lib/src/Receivers.cpp, 95
Internal	lib/src/ShapeFunctions.cpp, 95
Tspeed, 11	lib/src/TimeAdvance.cpp, 95
intriangle	loc_rhs
_	
Tspeed::Geo::Triangle, 72	Tspeed::FESpace, 30
invJac	M add
Tspeed::Geo::Triangle, 72	Tspeed::PointWiseEntity, 54
inverse_transform	M bold
Tspeed::FESpace, 30	_
invmap	Tspeed::Entity, 26
Tspeed::Geo::Triangle, 72	M_bed_map
is_orthonormal	Tspeed::Mesh, 40
Tspeed::BoundaryAdapted, 19	M_c
Tspeed::Dubiner, 20	Tspeed::BaseMat, 18
Tspeed::ShapeFunction, 64	M_completed
is_running	Tspeed::TimeAdvance, 69
Tspeed::TimeAdvance, 67	M_dt
iweight	Tspeed::TimeAdvance, 69
Tspeed::QuadratureRule, 60	M_f
rspeedQuadraturer tule, 00	Tspeed::Force, 33
Jac	Tspeed::TimeAdvance, 69
Tspeed::Geo::Triangle, 72	M_grad
·	Tspeed::ShapeFunction, 65
jacobi_polynomial	M_id
Tspeed, 11	
10	Tspeed::Entity, 26
L2error	M_ie
Tspeed::FESpace, 30	Tspeed::PointWiseEntity, 55
Lamb.cpp	M_last_step
main, 75	Tspeed::TimeAdvance, 69
lambda	M_m
Tspeed::Parameters, 48	Tspeed::BaseMat, 18
LeapFrog	M_mat
Tspeed::LeapFrog, 35	Tspeed::TimeAdvance, 69
length	M_nc
Tspeed::Geo::Edge, 23	Tspeed::BaseMat, 18
lib/include/Dunavant.hpp, 76	M_ne
no morado banavantinpp, 10	m_no

Tspeed::TimeAdvance, 69	Mesh_ptr
M_nel	Tspeed, 11
Tspeed::PointWiseEntity, 55	mu
M_nln	Tspeed::Parameters, 48
Tspeed::BaseMat, 18	MyMat
Tspeed::TimeAdvance, 69	Tspeed::MyMat, 40, 41
M_node_1D	MyMatBlockDiag
Tspeed::QuadratureRule, 60	Tspeed::MyMatBlockDiag, 42
M_node_2D	MyMatMultiDim
Tspeed::QuadratureRule, 60	Tspeed::MyMatMultiDim, 43
M_nqn_1D	MyMatMultiDimBlockDiag
Tspeed::QuadratureRule, 60	Tspeed::MyMatMultiDimBlockDiag, 45
M_nqn_2D	ND/A1
Tspeed::QuadratureRule, 60	NVAL
M_nr	Geometry.hpp, 81
Tspeed::BaseMat, 18	ne
M_penalty	Tspeed::FESpace, 31
Tspeed::TimeAdvance, 69	Tspeed::Mesh, 39
M_phi	neigh
Tspeed::ShapeFunction, 65	Tspeed::Geo::Triangle, 73
M_r	neighedges
Tspeed::BaseMat, 18	Tspeed::Geo::Triangle, 73
M_recv	Neumann
Tspeed::TimeAdvance, 69	Tspeed, 11
M_recv_written	nin
Tspeed::TimeAdvance, 69	Tspeed::FESpace, 31
M_reg	norm
Tspeed::Entity, 26	Tspeed::Geo::Point, 50 normal
M_relp	
Tspeed::PointWiseEntity, 55	Tspeed::Geo::Edge, 23
M_shape	nqn1d Tspeed::Dunavant, 21
Tspeed::PointWiseEntity, 55	Tspeed::Gauss, 34
M_tmax	ngn2d
Tspeed::TimeAdvance, 69	Tspeed::QuadratureRule, 60
M_w_1D	Tspeed::Dunavant, 21
Tspeed::QuadratureRule, 61	Tspeed::Gauss, 34
M_w_2D	nr
Tspeed::QuadratureRule, 61	Tspeed::BaseMat, 17
main	Tspeed::MyMatMultiDimBlockDiag, 46
Lamb.cpp, 75	numVertices
main.cpp, 96	Tspeed::Geo::Triangle, 74
wedge.cpp, 75	roposaniason mangie, 7
main.cpp, 96	operator<<
main, 96	Tspeed::Geo, 14
map	operator*
Tspeed::Geo::Triangle, 73	Tspeed, 12
Mat	Tspeed::Geo, 13
Tspeed::Dunavant, 21	Tspeed::Geo::Point, 50, 52
Tspeed::Gauss, 34	Tspeed::MyMat, 41
Tspeed::QuadratureRule, 58	Tspeed::MyMatMultiDim, 44
mat_dot	Tspeed::MyMatMultiDimBlockDiag, 46
Tspeed, 11	operator+
Matrices	Tspeed, 12
Tspeed::Matrices, 36	Tspeed::Geo, 13
Mesh	Tspeed::Geo::Point, 52
Tspeed::Mesh, 38	Tspeed::MyMatMultiDim, 44
mesh	operator+=
Tspeed::FESpace, 30	Tspeed::MyMat, 41

operator-	set_collnd
Tspeed::Geo, 13, 14	Tspeed::BaseMat, 17
Tspeed::Geo::Point, 53	set_dt
operator=	Tspeed::TimeAdvance, 67
Tspeed::Geo::Edge, 23	set_initial_u
Tspeed::Geo::Point, 51	Tspeed::TimeAdvance, 68
Tspeed::Geo::Triangle, 73	set_initial_v
Tspeed::MyMat, 41	Tspeed::TimeAdvance, 68
Tspeed::MyMatBlockDiag, 42	set_penalty
Tspeed::MyMatMultiDim, 44	Tspeed::TimeAdvance, 68
Tspeed::MyMatMultiDimBlockDiag, 46	set_rowInd
13peedwywatiwatibiiiibiockbiag, 40	Tspeed::BaseMat, 17
Parameters	set_tmax
Tspeed::Parameters, 47	Tspeed::TimeAdvance, 68
phi	setNeigh
Tspeed::ShapeFunction, 64	_
Point	Tspeed::Geo::Triangle, 74
	setNeighedges
Tspeed::Geo::Point, 50	Tspeed::Geo::Triangle, 74
point	setblock
Tspeed::PointWiseEntity, 54	Tspeed::BaseMat, 17
PointWiseForce	setp
Tspeed::PointWiseForce, 56	Tspeed::Parameters, 48
points_out	shape
Tspeed::FESpace, 31	Tspeed::FESpace, 31
printNeigh	Tspeed::PointWiseEntity, 55
Tspeed::Geo::Triangle, 73	ShapeFunction
printallNeigh	Tspeed::ShapeFunction, 64
Tspeed::Mesh, 39	ShapeFunctions.cpp
pt	Arr, 95
Tspeed::Geo::Triangle, 73	size
Topocaaco mangio, 70	
	Tspeed::BaseMat, 18
quad	Tspeed::BaseMat, 18 Tspeed::PointWiseEntity, 55
quad Tspeed::FESpace, 31	Tspeed::BaseMat, 18 Tspeed::PointWiseEntity, 55 size_type
quad Tspeed::FESpace, 31 QuadratureRule	Tspeed::BaseMat, 18 Tspeed::PointWiseEntity, 55 size_type Tspeed::Mesh, 38
quad Tspeed::FESpace, 31	Tspeed::BaseMat, 18 Tspeed::PointWiseEntity, 55 size_type Tspeed::Mesh, 38 SpMat
quad Tspeed::FESpace, 31 QuadratureRule Tspeed::QuadratureRule, 58	Tspeed::BaseMat, 18 Tspeed::PointWiseEntity, 55 size_type Tspeed::Mesh, 38 SpMat Tspeed::Matrices, 36
quad Tspeed::FESpace, 31 QuadratureRule Tspeed::QuadratureRule, 58 r8_huge	Tspeed::BaseMat, 18 Tspeed::PointWiseEntity, 55 size_type Tspeed::Mesh, 38 SpMat Tspeed::Matrices, 36 stats
quad Tspeed::FESpace, 31 QuadratureRule Tspeed::QuadratureRule, 58 r8_huge Dunavant.cpp, 92	Tspeed::BaseMat, 18 Tspeed::PointWiseEntity, 55 size_type Tspeed::Mesh, 38 SpMat Tspeed::Matrices, 36 stats Tspeed::Mesh, 39
quad Tspeed::FESpace, 31 QuadratureRule Tspeed::QuadratureRule, 58 r8_huge Dunavant.cpp, 92 Dunavant.hpp, 78	Tspeed::BaseMat, 18 Tspeed::PointWiseEntity, 55 size_type Tspeed::Mesh, 38 SpMat Tspeed::Matrices, 36 stats Tspeed::Mesh, 39 step
quad Tspeed::FESpace, 31 QuadratureRule Tspeed::QuadratureRule, 58 r8_huge Dunavant.cpp, 92 Dunavant.hpp, 78 r8_nint	Tspeed::BaseMat, 18 Tspeed::PointWiseEntity, 55 size_type Tspeed::Mesh, 38 SpMat Tspeed::Matrices, 36 stats Tspeed::Mesh, 39 step Tspeed::LeapFrog, 35
quad Tspeed::FESpace, 31 QuadratureRule Tspeed::QuadratureRule, 58 r8_huge Dunavant.cpp, 92 Dunavant.hpp, 78 r8_nint Dunavant.cpp, 92	Tspeed::BaseMat, 18 Tspeed::PointWiseEntity, 55 size_type Tspeed::Mesh, 38 SpMat Tspeed::Matrices, 36 stats Tspeed::Mesh, 39 step Tspeed::LeapFrog, 35 Tspeed::TimeAdvance, 68
quad Tspeed::FESpace, 31 QuadratureRule Tspeed::QuadratureRule, 58 r8_huge Dunavant.cpp, 92 Dunavant.hpp, 78 r8_nint Dunavant.cpp, 92 Dunavant.hpp, 78	Tspeed::BaseMat, 18 Tspeed::PointWiseEntity, 55 size_type Tspeed::Mesh, 38 SpMat Tspeed::Matrices, 36 stats Tspeed::Mesh, 39 step Tspeed::LeapFrog, 35 Tspeed::TimeAdvance, 68 sumtranspose
quad Tspeed::FESpace, 31 QuadratureRule Tspeed::QuadratureRule, 58 r8_huge Dunavant.cpp, 92 Dunavant.hpp, 78 r8_nint Dunavant.cpp, 92 Dunavant.hpp, 78 Receivers	Tspeed::BaseMat, 18 Tspeed::PointWiseEntity, 55 size_type Tspeed::Mesh, 38 SpMat Tspeed::Matrices, 36 stats Tspeed::Mesh, 39 step Tspeed::LeapFrog, 35 Tspeed::TimeAdvance, 68 sumtranspose Tspeed::MyMat, 41
quad Tspeed::FESpace, 31 QuadratureRule Tspeed::QuadratureRule, 58 r8_huge Dunavant.cpp, 92 Dunavant.hpp, 78 r8_nint Dunavant.cpp, 92 Dunavant.hpp, 78 Receivers Tspeed::Receivers, 61, 62	Tspeed::BaseMat, 18 Tspeed::PointWiseEntity, 55 size_type Tspeed::Mesh, 38 SpMat Tspeed::Matrices, 36 stats Tspeed::Mesh, 39 step Tspeed::LeapFrog, 35 Tspeed::TimeAdvance, 68 sumtranspose
quad Tspeed::FESpace, 31 QuadratureRule Tspeed::QuadratureRule, 58 r8_huge Dunavant.cpp, 92 Dunavant.hpp, 78 r8_nint Dunavant.cpp, 92 Dunavant.hpp, 78 Receivers Tspeed::Receivers, 61, 62 reference_to_physical_t3	Tspeed::BaseMat, 18 Tspeed::PointWiseEntity, 55 size_type Tspeed::Mesh, 38 SpMat Tspeed::Matrices, 36 stats Tspeed::Mesh, 39 step Tspeed::LeapFrog, 35 Tspeed::TimeAdvance, 68 sumtranspose Tspeed::MyMat, 41
quad Tspeed::FESpace, 31 QuadratureRule Tspeed::QuadratureRule, 58 r8_huge Dunavant.cpp, 92 Dunavant.hpp, 78 r8_nint Dunavant.cpp, 92 Dunavant.hpp, 78 Receivers Tspeed::Receivers, 61, 62 reference_to_physical_t3 Dunavant.cpp, 92	Tspeed::BaseMat, 18 Tspeed::PointWiseEntity, 55 size_type Tspeed::Mesh, 38 SpMat Tspeed::Matrices, 36 stats Tspeed::Mesh, 39 step Tspeed::LeapFrog, 35 Tspeed::TimeAdvance, 68 sumtranspose Tspeed::MyMat, 41 symmetrize
quad Tspeed::FESpace, 31 QuadratureRule Tspeed::QuadratureRule, 58 r8_huge Dunavant.cpp, 92 Dunavant.hpp, 78 r8_nint Dunavant.cpp, 92 Dunavant.hpp, 78 Receivers Tspeed::Receivers, 61, 62 reference_to_physical_t3	Tspeed::BaseMat, 18 Tspeed::PointWiseEntity, 55 size_type Tspeed::Mesh, 38 SpMat Tspeed::Matrices, 36 stats Tspeed::Mesh, 39 step Tspeed::LeapFrog, 35 Tspeed::TimeAdvance, 68 sumtranspose Tspeed::MyMat, 41 symmetrize Tspeed::MyMat, 41 Tspeed::MyMat, 41 Tspeed::MyMat, 41
quad Tspeed::FESpace, 31 QuadratureRule Tspeed::QuadratureRule, 58 r8_huge Dunavant.cpp, 92 Dunavant.hpp, 78 r8_nint Dunavant.cpp, 92 Dunavant.hpp, 78 Receivers Tspeed::Receivers, 61, 62 reference_to_physical_t3 Dunavant.cpp, 92	Tspeed::BaseMat, 18 Tspeed::PointWiseEntity, 55 size_type Tspeed::Mesh, 38 SpMat Tspeed::Matrices, 36 stats Tspeed::Mesh, 39 step Tspeed::LeapFrog, 35 Tspeed::TimeAdvance, 68 sumtranspose Tspeed::MyMat, 41 symmetrize Tspeed::MyMat, 41
quad Tspeed::FESpace, 31 QuadratureRule Tspeed::QuadratureRule, 58 r8_huge Dunavant.cpp, 92 Dunavant.hpp, 78 r8_nint Dunavant.cpp, 92 Dunavant.hpp, 78 Receivers Tspeed::Receivers, 61, 62 reference_to_physical_t3 Dunavant.cpp, 92 Dunavant.hpp, 78	Tspeed::BaseMat, 18 Tspeed::PointWiseEntity, 55 size_type Tspeed::Mesh, 38 SpMat Tspeed::Matrices, 36 stats Tspeed::Mesh, 39 step Tspeed::LeapFrog, 35 Tspeed::TimeAdvance, 68 sumtranspose Tspeed::MyMat, 41 symmetrize Tspeed::MyMat, 41 Tspeed::MyMat, 41 Tspeed::MyMat, 41
quad Tspeed::FESpace, 31 QuadratureRule Tspeed::QuadratureRule, 58 r8_huge Dunavant.cpp, 92 Dunavant.hpp, 78 r8_nint Dunavant.cpp, 92 Dunavant.hpp, 78 Receivers Tspeed::Receivers, 61, 62 reference_to_physical_t3 Dunavant.pp, 78 reg	Tspeed::BaseMat, 18 Tspeed::PointWiseEntity, 55 size_type Tspeed::Mesh, 38 SpMat Tspeed::Matrices, 36 stats Tspeed::Mesh, 39 step Tspeed::LeapFrog, 35 Tspeed::TimeAdvance, 68 sumtranspose Tspeed::MyMat, 41 symmetrize Tspeed::MyMat, 41 Tspeed::MyMatMultiDim, 44 TIME_SIZE Dunavant.cpp, 90 TSPEED.hpp, 89
quad Tspeed::FESpace, 31 QuadratureRule Tspeed::QuadratureRule, 58 r8_huge Dunavant.cpp, 92 Dunavant.hpp, 78 r8_nint Dunavant.cpp, 92 Dunavant.hpp, 78 Receivers Tspeed::Receivers, 61, 62 reference_to_physical_t3 Dunavant.pp, 78 reg Tspeed::Entity, 25	Tspeed::BaseMat, 18 Tspeed::PointWiseEntity, 55 size_type Tspeed::Mesh, 38 SpMat Tspeed::Matrices, 36 stats Tspeed::Mesh, 39 step Tspeed::LeapFrog, 35 Tspeed::TimeAdvance, 68 sumtranspose Tspeed::MyMat, 41 symmetrize Tspeed::MyMat, 41 Tspeed::MyMatMultiDim, 44 TIME_SIZE Dunavant.cpp, 90
quad Tspeed::FESpace, 31 QuadratureRule Tspeed::QuadratureRule, 58 r8_huge Dunavant.cpp, 92 Dunavant.hpp, 78 r8_nint Dunavant.cpp, 92 Dunavant.hpp, 78 Receivers Tspeed::Receivers, 61, 62 reference_to_physical_t3 Dunavant.pp, 92 Dunavant.hpp, 78 reg Tspeed::Entity, 25 rho	Tspeed::BaseMat, 18 Tspeed::PointWiseEntity, 55 size_type Tspeed::Mesh, 38 SpMat Tspeed::Matrices, 36 stats Tspeed::Mesh, 39 step Tspeed::LeapFrog, 35 Tspeed::TimeAdvance, 68 sumtranspose Tspeed::MyMat, 41 symmetrize Tspeed::MyMat, 41 Tspeed::MyMatMultiDim, 44 TIME_SIZE Dunavant.cpp, 90 TSPEED.hpp, 89
quad Tspeed::FESpace, 31 QuadratureRule Tspeed::QuadratureRule, 58 r8_huge Dunavant.cpp, 92 Dunavant.hpp, 78 r8_nint Dunavant.cpp, 92 Dunavant.hpp, 78 Receivers Tspeed::Receivers, 61, 62 reference_to_physical_t3 Dunavant.cpp, 92 Dunavant.hpp, 78 reg Tspeed::Entity, 25 rho Tspeed::Parameters, 48 rowInd	Tspeed::BaseMat, 18 Tspeed::PointWiseEntity, 55 size_type Tspeed::Mesh, 38 SpMat Tspeed::Matrices, 36 stats Tspeed::Mesh, 39 step Tspeed::LeapFrog, 35 Tspeed::TimeAdvance, 68 sumtranspose Tspeed::MyMat, 41 symmetrize Tspeed::MyMat, 41 Tspeed::MyMatMultiDim, 44 TIME_SIZE Dunavant.cpp, 90 TSPEED.hpp, 89 TimeAdvance
quad Tspeed::FESpace, 31 QuadratureRule Tspeed::QuadratureRule, 58 r8_huge Dunavant.cpp, 92 Dunavant.hpp, 78 r8_nint Dunavant.cpp, 92 Dunavant.hpp, 78 Receivers Tspeed::Receivers, 61, 62 reference_to_physical_t3 Dunavant.cpp, 92 Dunavant.hpp, 78 reg Tspeed::Entity, 25 rho Tspeed::Parameters, 48	Tspeed::BaseMat, 18 Tspeed::PointWiseEntity, 55 size_type Tspeed::Mesh, 38 SpMat Tspeed::Matrices, 36 stats Tspeed::Mesh, 39 step Tspeed::LeapFrog, 35 Tspeed::TimeAdvance, 68 sumtranspose Tspeed::MyMat, 41 symmetrize Tspeed::MyMat, 41 Tspeed::MyMatMultiDim, 44 TIME_SIZE Dunavant.cpp, 90 TSPEED.hpp, 89 TimeAdvance Tspeed::TimeAdvance, 67
quad Tspeed::FESpace, 31 QuadratureRule Tspeed::QuadratureRule, 58 r8_huge Dunavant.cpp, 92 Dunavant.hpp, 78 r8_nint Dunavant.cpp, 92 Dunavant.hpp, 78 Receivers Tspeed::Receivers, 61, 62 reference_to_physical_t3 Dunavant.cpp, 92 Dunavant.hpp, 78 reg Tspeed::Entity, 25 rho Tspeed::Parameters, 48 rowInd Tspeed::BaseMat, 17	Tspeed::BaseMat, 18 Tspeed::PointWiseEntity, 55 size_type Tspeed::Mesh, 38 SpMat Tspeed::Matrices, 36 stats Tspeed::Mesh, 39 step Tspeed::LeapFrog, 35 Tspeed::TimeAdvance, 68 sumtranspose Tspeed::MyMat, 41 symmetrize Tspeed::MyMat, 41 Tspeed::MyMatMultiDim, 44 TIME_SIZE Dunavant.cpp, 90 TSPEED.hpp, 89 TimeAdvance Tspeed::TimeAdvance, 67 timestamp Dunavant.cpp, 92
quad Tspeed::FESpace, 31 QuadratureRule Tspeed::QuadratureRule, 58 r8_huge Dunavant.cpp, 92 Dunavant.hpp, 78 r8_nint Dunavant.cpp, 92 Dunavant.hpp, 78 Receivers Tspeed::Receivers, 61, 62 reference_to_physical_t3 Dunavant.cpp, 92 Dunavant.hpp, 78 reg Tspeed::Entity, 25 rho Tspeed::Parameters, 48 rowInd Tspeed::BaseMat, 17	Tspeed::BaseMat, 18 Tspeed::PointWiseEntity, 55 size_type Tspeed::Mesh, 38 SpMat Tspeed::Matrices, 36 stats Tspeed::Mesh, 39 step Tspeed::LeapFrog, 35 Tspeed::TimeAdvance, 68 sumtranspose Tspeed::MyMat, 41 symmetrize Tspeed::MyMat, 41 Tspeed::MyMatMultiDim, 44 TIME_SIZE Dunavant.cpp, 90 TSPEED.hpp, 89 TimeAdvance Tspeed::TimeAdvance, 67 timestamp Dunavant.cpp, 92 Dunavant.hpp, 78
quad Tspeed::FESpace, 31 QuadratureRule Tspeed::QuadratureRule, 58 r8_huge Dunavant.cpp, 92 Dunavant.hpp, 78 r8_nint Dunavant.cpp, 92 Dunavant.hpp, 78 Receivers Tspeed::Receivers, 61, 62 reference_to_physical_t3 Dunavant.cpp, 92 Dunavant.hpp, 78 reg Tspeed::Entity, 25 rho Tspeed::Parameters, 48 rowInd Tspeed::BaseMat, 17 s_len_trim Dunavant.cpp, 92	Tspeed::BaseMat, 18 Tspeed::PointWiseEntity, 55 size_type Tspeed::Mesh, 38 SpMat Tspeed::Matrices, 36 stats Tspeed::Mesh, 39 step Tspeed::LeapFrog, 35 Tspeed::TimeAdvance, 68 sumtranspose Tspeed::MyMat, 41 symmetrize Tspeed::MyMat, 41 Tspeed::MyMatMultiDim, 44 TIME_SIZE Dunavant.cpp, 90 TSPEED.hpp, 89 TimeAdvance Tspeed::TimeAdvance, 67 timestamp Dunavant.cpp, 92 Dunavant.hpp, 78 timestring
quad Tspeed::FESpace, 31 QuadratureRule Tspeed::QuadratureRule, 58 r8_huge Dunavant.cpp, 92 Dunavant.hpp, 78 r8_nint Dunavant.cpp, 92 Dunavant.hpp, 78 Receivers Tspeed::Receivers, 61, 62 reference_to_physical_t3 Dunavant.cpp, 92 Dunavant.hpp, 78 reg Tspeed::Entity, 25 rho Tspeed::Parameters, 48 rowInd Tspeed::BaseMat, 17 s_len_trim Dunavant.cpp, 92 Dunavant.hpp, 78	Tspeed::BaseMat, 18 Tspeed::PointWiseEntity, 55 size_type Tspeed::Mesh, 38 SpMat Tspeed::Matrices, 36 stats Tspeed::Mesh, 39 step Tspeed::LeapFrog, 35 Tspeed::TimeAdvance, 68 sumtranspose Tspeed::MyMat, 41 symmetrize Tspeed::MyMat, 41 Tspeed::MyMatMultiDim, 44 TIME_SIZE Dunavant.cpp, 90 TSPEED.hpp, 89 TimeAdvance Tspeed::TimeAdvance, 67 timestamp Dunavant.cpp, 92 Dunavant.pp, 78 timestring Dunavant.cpp, 92
quad Tspeed::FESpace, 31 QuadratureRule Tspeed::QuadratureRule, 58 r8_huge Dunavant.cpp, 92 Dunavant.hpp, 78 r8_nint Dunavant.cpp, 92 Dunavant.hpp, 78 Receivers Tspeed::Receivers, 61, 62 reference_to_physical_t3 Dunavant.cpp, 92 Dunavant.hpp, 78 reg Tspeed::Entity, 25 rho Tspeed::Parameters, 48 rowInd Tspeed::BaseMat, 17 s_len_trim Dunavant.cpp, 92	Tspeed::BaseMat, 18 Tspeed::PointWiseEntity, 55 size_type Tspeed::Mesh, 38 SpMat Tspeed::Matrices, 36 stats Tspeed::Mesh, 39 step Tspeed::LeapFrog, 35 Tspeed::TimeAdvance, 68 sumtranspose Tspeed::MyMat, 41 symmetrize Tspeed::MyMat, 41 Tspeed::MyMatMultiDim, 44 TIME_SIZE Dunavant.cpp, 90 TSPEED.hpp, 89 TimeAdvance Tspeed::TimeAdvance, 67 timestamp Dunavant.cpp, 92 Dunavant.hpp, 78 timestring

Tspeed::Geo::Point, 51	Tspeed::BoundaryAdapted< N >, 18
Triangle	Tspeed::Dubiner
Tspeed::Geo::Triangle, 71	\sim Dubiner, 20
triangle_area	Dubiner, 20
Dunavant.cpp, 92	Tspeed::Dubiner< N >, 19
Dunavant.hpp, 78	Tspeed::Dunavant
triangle_points_plot	Dunavant, 22
Dunavant.cpp, 92	Mat, 21
Dunavant.hpp, 78	Vec, 21
Tspeed, 9	Vec2, 21
Bc, 11	Tspeed::Dunavant< N >, 20
CTensorProduct, 11	Tspeed::Entity, 23
Dirichlet, 11	bcld, 25
FESpace_ptr, 11	Entity, 25
Force_ptr, 11	ld, 25
Internal, 11	id, 25
jacobi_polynomial, 11	M_bcld, 26
mat_dot, 11	M_id, 26
Mesh_ptr, 11	M_reg, 26
Neumann, 11	reg, 25
operator*, 12	unassignedBc, 26
operator+, 12	unassignedId, 26
Unassigned, 11	unassignedReg, 26
Tspeed::BoundaryAdapted	Tspeed::FESpace
is_orthonormal, 19	\sim FESpace, 28
Tspeed::Dubiner	b_edge, 28
is_orthonormal, 20	base_invmass, 28
Tspeed::Dunavant	base_mass, 28
nqn1d, 21	FESpace, 28
ngn2d, 21	field_out, 29
Tspeed::Gauss	g_edge, 29
ngn1d, 34	grad, 29
ngn2d, 34	inverse_transform, 30
Tspeed::ShapeFunction	L2error, 30
gdl, 63	loc_rhs, 30
is_orthonormal, 64	mesh, 30
Tspeed::BaseMat, 15	ne, <mark>31</mark>
∼BaseMat, 16	nln, 31
BaseMat, 16	points_out, 31
block, 16	quad, 31
collnd, 17	shape, 31
elem, 17	Tspeed::FESpace < N, Q, S >, 27
M_c, 18	Tspeed::Force, 31
M_m, 18	\sim Force, 32
M_nc, 18	eval, 33
M_nln, 18	Force, 32
M_nr, 18	M f, 33
M_r, 18	SPVec, 32
nr, 17	Vec, 32
rowlnd, 17	Tspeed::Gauss
set_collnd, 17	Gauss, 34
set_rowlnd, 17	Mat, 34
setblock, 17	Vec, 34
size, 18	Vec2, 34
vecMult, 18	Tspeed::Gauss< N >, 33
Tspeed::BoundaryAdapted	Tspeed::Geo, 12
~BoundaryAdapted, 19	operator<<, 14
BoundaryAdapted, 19	operator*, 13
	-1

amayatay. 10	Mach 00
operator+, 13	Mesh, 38
operator-, 13, 14	ne, 39
Tspeed::Geo::Edge, 22	printallNeigh, 39
~Edge, 23	size_type, 38
Edge, 22, 23	stats, 39
length, 23	Tspeed::MyMat, 40
normal, 23	~MyMat, 41
operator=, 23	MyMat, 40, 41
Tspeed::Geo::Point, 48	operator*, 41
~Point, 50	operator+=, 41
dot, 52	operator=, 41
norm, 50	sumtranspose, 41
operator*, 50, 52	symmetrize, 41
operator+, 52	Tspeed::MyMatBlockDiag, 41
operator-, 53	~MyMatBlockDiag, 42
operator=, 51	MyMatBlockDiag, 42
Point, 50	operator=, 42
toEig, 51	Tspeed::MyMatMultiDim
x, 51	∼MyMatMultiDim, 43
y, 51	component, 43, 44
Tspeed::Geo::Triangle, 70	MyMatMultiDim, 43
\sim Triangle, 71	operator*, 44
all_edges, 71	operator+, 44
all_pts, 71	operator=, 44
detJ, 71	symmetrize, 44
edg, 72	vecMult, 44
intriangle, 72	Tspeed::MyMatMultiDim< T >, 42
invJac, 72	Tspeed::MyMatMultiDimBlockDiag
invmap, 72	\sim MyMatMultiDimBlockDiag, 45
Jac, 72	component, 46
map, 73	MyMatMultiDimBlockDiag, 45
neigh, 73	nr, 46
neighedges, 73	operator*, 46
numVertices, 74	operator=, 46
operator=, 73	vecMult, 46
printNeigh, 73	Tspeed::MyMatMultiDimBlockDiag< T >, 45
pt, 73	Tspeed::Parameters, 47
setNeigh, 74	∼Parameters, 47
setNeighedges, 74	avg_p, 47
Triangle, 71	lambda, 48
Tspeed::LeapFrog, 34	mu, 48
first_step, 35	Parameters, 47
LeapFrog, 35	rho, 48
step, 35	setp, 48
Tspeed::Matrices, 35	Tspeed::PointWiseEntity, 53
getA, 36	~PointWiseEntity, 54
getl, 36	elem, 54
getS, 37	M_add, 54
getinvM, 37	M_ie, 55
Matrices, 36	M_nel, 55
SpMat, 36	M_relp, 55
Tspeed::Mesh, 37	M_shape, 55
~Mesh, 38	
	point, 54
AlignedVecE, 38	shape, 55
AlignedVecP, 38	size, 55
AlignedVecT, 38	Tspeed::PointWiseForce, 55
elements, 38, 39	~PointWiseForce, 56
M_bed_map, 40	eval, 56

PointWiseForce, 56	M_tmax, 69
Tspeed::QuadratureRule	set_dt, 67
\sim QuadratureRule, 58	set_initial_u, 68
edge_n, 58	set_initial_v, 68
edge_nodes, 59	set_penalty, 68
edge_weights, 59	set_tmax, 68
eweight, 59	step, 68
inode, 59	TimeAdvance, 67
int_n, 60	u, 68
int_nodes, 60	uh, 69
int_weights, 60	uhold, 69
iweight, 60	uholdold, 69
M_node_1D, 60	update_variables, 69
M_node_2D, 60	write_receivers, 69
M_nqn_1D, 60	
M_nqn_2D, 60	U T LT AL OO
M_w_1D, 61	Tspeed::TimeAdvance, 68
M_w_2D, 61	uh
Mat, 58	Tspeed::TimeAdvance, 69
nqn2d, 60	uhold
QuadratureRule, 58	Tspeed::TimeAdvance, 69
Vec, 58	uholdold
Vec2, 58	Tspeed::TimeAdvance, 69
Tspeed::QuadratureRule < N >, 57	Unassigned
Tspeed::Receivers, 61	Tspeed, 11
add, 62	unassignedBc
Receivers, 61, 62	Tspeed::Entity, 26
write, 62	unassignedId
Tspeed::ShapeFunction	Tspeed::Entity, 26
\sim ShapeFunction, 64	unassignedReg
grad, 64	Tspeed::Entity, 26
M_grad, 65	update_variables
M_phi, 65	Tspeed::TimeAdvance, 69
phi, 64	Vec
ShapeFunction, 64	Tspeed::Dunavant, 21
Tspeed::ShapeFunction $< N >$, 62	Tspeed::Force, 32
Tspeed::TimeAdvance, 65	Tspeed::Gauss, 34
\sim TimeAdvance, 67	Tspeed::QuadratureRule, 58
add_force, 67	Vec2
B, 69	Tspeed::Dunavant, 21
eval_receivers, 67	Tspeed::Gauss, 34
f, 69	Tspeed::QuadratureRule, 58
first_step, 67	vecMult
fold, 69	Tspeed::BaseMat, 18
foldold, 69	Tspeed::MyMatMultiDim, 44
get_uh, 67	Tspeed::MyMatMultiDimBlockDiag, 46
initial_v, 69	13pccamymatimatibimbiochbiag, 40
is_running, 67	wedge.cpp
M_completed, 69	main, 75
M_dt, 69	wedge_init_param, 75
M_f, 69	wedge_init_param
M_last_step, 69	wedge.cpp, 75
M_mat, 69	write
M_ne, 69	Tspeed::Receivers, 62
M_nln, 69	write receivers
M_penalty, 69	Tspeed::TimeAdvance, 69
M_recv, 69	i oposali i ilio lavalisti, oo
M_recv_written, 69	x
,	

Tspeed::Geo::Point, 51

У

Tspeed::Geo::Point, 51