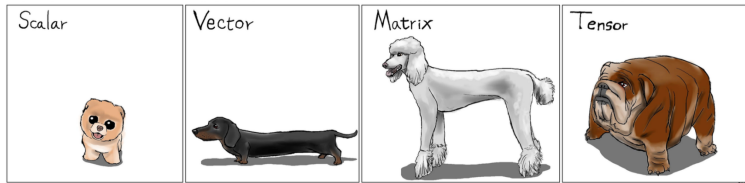


Tensor Data Analysis Overview

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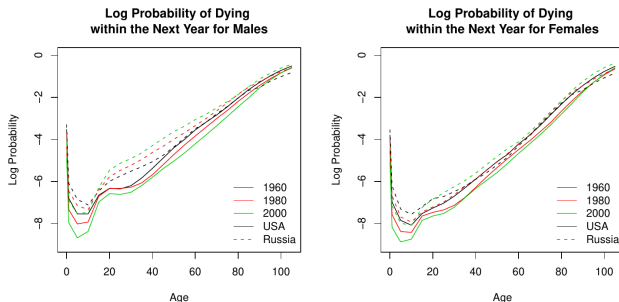
Outline

- 1 Tensors when the observations are scalars
- 2 Tensors with multivariate observations
 - Kronecker Separability for Higher Order Normality
- 3 Low-Rank Formats

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Human Mortality Database



Tensor form along different factors:

- 38 countries
- 23 age levels (0,1, then every 5 years)
- 9 time periods (1960-2000 every 5 years)
- 2 sexes

$39 \times 23 \times 9 \times 2$ array!

Factorial Designs

Cell means ANOVA: $y_{ijklm} = \mu_{ijkl} + e_{ijklm}$

- In STAT 500-510 deep interactions:

$$\begin{aligned}\mu_{ijkl} = & \alpha_i + \beta_j + \eta_k + \gamma_l + \alpha\beta_{ij} + \alpha\eta_{ik} + \alpha\gamma_{il} + \beta\eta_{jk} + \beta\gamma_{jl} + \eta\gamma_{kl} + \\ & (\alpha\beta\eta)_{ijk} + (\alpha\beta\gamma)_{ijl} + (\alpha\eta\gamma)_{ikl} + (\beta\eta\gamma)_{jkl} + (\alpha\beta\eta\gamma)_{ijkl}\end{aligned}$$

- we could do $\mu_{ijkl} = \langle \mathcal{X}_{ijkl}, \mathcal{B} \rangle$, where

$$\mathcal{X}_{i^*j^*k^*l^*} = \begin{cases} 1 & \text{if } (i, j, k, l) = (i^*, j^*, k^*, l^*) \\ 0 & \text{otherwise} \end{cases}$$

Then \mathcal{B} is an array that contains all the relevant means and deep interactions!

Tensor Regression

- Simple linear regression

$$y_i = \beta x_i + \epsilon_i, \quad \epsilon_i \stackrel{iid}{\sim} \mathcal{N}(0, \sigma^2)$$

- Multiple linear regression

$$y_i = \boldsymbol{\beta}' \mathbf{x}_i + \epsilon_i, \quad \epsilon_i \stackrel{iid}{\sim} \mathcal{N}(0, \sigma^2)$$

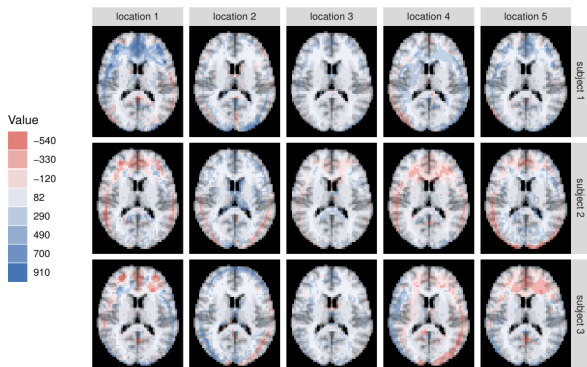
- Tensor regression

$$y_i = \langle \mathcal{B}, \mathcal{X}_i \rangle + \epsilon_i, \quad \epsilon_i \stackrel{iid}{\sim} \mathcal{N}(0, \sigma^2)$$

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Brain Imaging Data (Yamashita et.al 19)



tensor form along multiple factors and spatial dimensions!

- 9 subjects traveled to 12 imaging centers
- 3 repetitions of 240 time-steps each
- brain images of size $73 \times 73 \times 61$

$73 \times 73 \times 61 \times 240 \times 9 \times 12 \times 3$ array!

Multivariate Regression

- Multivariate Multiple Linear Regression

$$\mathbf{y}_i = B\mathbf{x}_i + \boldsymbol{\epsilon}_i, \quad \boldsymbol{\epsilon}_i \stackrel{iid}{\sim} \mathcal{N}_m(0, \Sigma),$$

- Matrix-variate Regression (Ding and Cook, 2018, JRSSB)

$$Y_i = B_1 X_i B_2^\top + E_i, \quad E_i \stackrel{iid}{\sim} \mathcal{N}_{m_1, m_2}(0, \Sigma_1, \Sigma_2),$$

- Multilinear Tensor Regression (Hoff, 2015, Ann. Appl. Stat)

$$\mathcal{Y}_i = \llbracket \mathcal{X}_i; B_1, \dots, B_p \rrbracket + \mathcal{E}_i, \quad \mathcal{E}_i \stackrel{iid}{\sim} \mathcal{N}_{m_1, \dots, m_p}(0, \Sigma_1, \dots, \Sigma_p),$$

The Matrix Normal Distribution

- S. N. Roy wrote its pdf in 1957
- A matrix follows a normal distribution if its vectorization follows a multivariate normal distribution
- Without any constraint on the covariance matrix, this leads to overfitting
- Kronecker separability is an intuitive constraint

Definition:

$$X \sim \mathcal{N}_{m_1, m_2} (M, \Sigma_1, \Sigma_2) \iff \text{vec}(X) \sim \mathcal{N}_{m_1 \times m_2} (\text{vec}(M), \Sigma_2 \otimes \Sigma_1)$$

dimensionality reduction:

$$[(m_1 \times m_2 + 1)(m_1 \times m_2)]/2 \rightarrow (m_1 + 1) \times m_1/2 + (m_2 + 1) \times m_2/2$$

The Tensor Normal Distribution

- A tensor follows a normal distribution if its vectorization follows a multivariate normal distribution
- The assumption of kronecker separability can be extended to higher order tensors
- Vectorization is usually defined in reverse lexicographic order to avoid an inconsistency with matrix vectorization

Definition:

$$\mathcal{X} \sim \mathcal{N}_{m_1, \dots, m_p} (\mathcal{M}, \Sigma_1, \dots, \Sigma_p)$$
$$\iff \text{vec}(\mathcal{X}) \sim \mathcal{N}_{m_1 \times \dots \times m_p} \left(\text{vec}(\mathcal{M}), \bigotimes_{i=1}^p \Sigma_i \right)$$

Comparisons between tensor normal distributions

- Bivariate normal distribution: $\mathbf{x} \sim \mathcal{N}_2(\boldsymbol{\mu}, \Sigma)$, $\Sigma[i, j] = \sigma_{ij}$

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \sim \mathcal{N}_2 \left(\begin{bmatrix} \mu_1 \\ \mu_2 \end{bmatrix}, \begin{bmatrix} \sigma_{11} & \sigma_{12} \\ \sigma_{21} & \sigma_{22} \end{bmatrix} \right)$$

- Matrix normal distribution: $X \sim \mathcal{N}_{3,2}(M, \Sigma_1, \Sigma)$, $\Sigma[i, j] = \sigma_{ij}^2$

$$\text{vec}(X) = \begin{bmatrix} \mathbf{x}_1 \\ \mathbf{x}_2 \end{bmatrix} \sim \mathcal{N}_{3 \times 2} \left(\begin{bmatrix} \boldsymbol{\mu}_1 \\ \boldsymbol{\mu}_2 \end{bmatrix}, \begin{bmatrix} \sigma_{11}\Sigma_1 & \sigma_{12}\Sigma_1 \\ \sigma_{21}\Sigma_1 & \sigma_{22}\Sigma_1 \end{bmatrix} \right).$$

- Third order tensor normal distribution: $\mathcal{X} \sim \mathcal{N}_{3,2,2}(\mathcal{M}, \Sigma_1, \Sigma_2, \Sigma)$

$$\begin{aligned} \text{vec}(\mathcal{X}) &= \begin{bmatrix} \text{vec } \mathcal{X}(:, :, 1) \\ \text{vec } \mathcal{X}(:, :, 2) \end{bmatrix} \\ &\sim \mathcal{N}_{3 \times 2 \times 2} \left(\begin{bmatrix} \text{vec } \mathcal{M}(:, :, 1) \\ \text{vec } \mathcal{M}(:, :, 2) \end{bmatrix}, \begin{bmatrix} \sigma_{11}\Sigma_2 \otimes \Sigma_1 & \sigma_{12}\Sigma_2 \otimes \Sigma_1 \\ \sigma_{21}\Sigma_2 \otimes \Sigma_1 & \sigma_{22}\Sigma_2 \otimes \Sigma_1 \end{bmatrix} \right). \end{aligned}$$

Back to Matrix-Variate Regression

$$Y_i = B_1 X_i B_2^\top + E_i, \quad E_i \stackrel{iid}{\sim} \mathcal{N}_{m_1, m_2}(0, \Sigma_1, \Sigma_2),$$

- MLE under fixed (B_2, Σ_2) :

Let $H_1 = \sum_{i=1}^n X_i B_2' \Sigma_2^{-1} B_2 X_i'$, then

$$\begin{cases} \hat{B}_1 = (\sum_{i=1}^n Y_i \Sigma_2^{-1} B_2 X_i') H_1^{-1} \\ \hat{\Sigma}_1 = \sum_{i=1}^n Y_i \Sigma_2^{-1} Y_i' - \hat{B}_1 H_1 \hat{B}_1' \end{cases}$$

- MLE under fixed (B_1, Σ_1) :

Let $H_2 = \sum_{i=1}^n X_i' B_1' \Sigma_1^{-1} B_1 X_i$, then

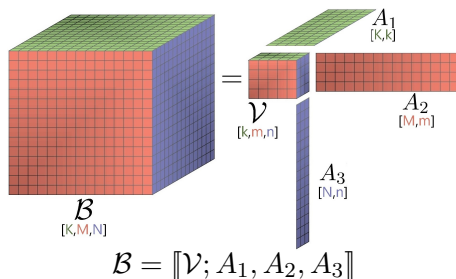
$$\begin{cases} \hat{B}_2 = (\sum_{i=1}^n Y_i' \Sigma_1^{-1} B_1 X_i) H_2^{-1} \\ \hat{\Sigma}_2 = \sum_{i=1}^n Y_i' \Sigma_1^{-1} Y_i - \hat{B}_2 H_2 \hat{B}_2' \end{cases}$$

- Block relaxation algorithm!!!
- You should avoid this model \rightarrow tensor on tensor regression!

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The Tucker (TK) Format

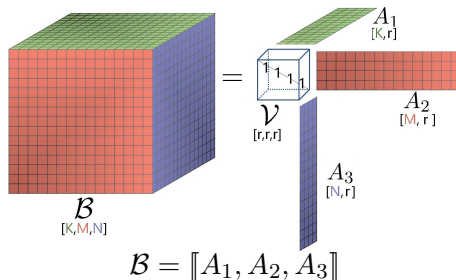


The diagram shows a large 3D tensor \mathcal{B} with dimensions $[K, M, N]$ being decomposed into a core tensor \mathcal{V} with dimensions $[k, m, n]$ and three factor matrices A_1 (dimensions $[K, k]$), A_2 (dimensions $[M, m]$), and A_3 (dimensions $[N, n]$). The equation $\mathcal{B} = [\mathcal{V}; A_1, A_2, A_3]$ is shown below the diagram.

$$\mathcal{B} = [\mathcal{V}; A_1, A_2, A_3]$$

- Unconstrained $\mathcal{B} \in \mathbb{R}^{15 \times 15 \times 15}$ has 3,375 parameters
- Constrained to a Tucker format of rank (3,4,5) leads to only 240

The Canonical (CP) format



- Special case when core \mathcal{V} is *diagonal*
- Unconstrained \mathcal{B} has 3,375 parameters
- Constrained to a CP format of rank 4 leads to only 180

The Tensor Ring (TR) Format

$$\begin{array}{c} \mathcal{B} \in \mathbb{R}^{4 \times 4 \times 4 \times 4} \\ \text{[K,L,M,N]} \end{array} = \begin{array}{c} \mathcal{A}_1 \quad \mathcal{A}_2 \\ [r_1, \text{K}, r_2] \quad [r_2, \text{L}, r_3] \\ \mathcal{A}_4 \quad \mathcal{A}_3 \\ [r_4, \text{N}, r_1] \quad [r_3, \text{M}, r_4] \end{array}$$

$$\mathcal{B} = \text{tr}(\mathcal{A}_1 \times^1 \mathcal{A}_2 \times^1 \mathcal{A}_3 \times^1 \mathcal{A}_4)$$

- Referred to matrix product state (MPS) in many-body physics
- Unconstrained \mathcal{B} has 256 parameters
- Constrained to a TR format of rank (2,2,2,2) leads to only 64

Tensor-on-Tensor Regression:

$$\begin{aligned}\mathcal{Y}_i &= \langle \mathcal{X}_i | \mathcal{B} \rangle + \mathcal{E}_i, \quad \mathcal{E}_i \stackrel{iid}{\sim} \mathcal{N}_{m_1, m_2, \dots, m_p}(0, \sigma^2 \Sigma_1, \Sigma_2, \dots, \Sigma_p), \\ \mathcal{X}_i &\in \mathbb{R}^{h_1 \times h_2 \times \dots \times h_l}, \quad \mathcal{Y}_i \in \mathbb{R}^{m_1 \times m_2 \times \dots \times m_p}, \\ \mathcal{B} &\in \mathbb{R}^{h_1 \times h_2 \times \dots \times h_l \times m_1 \times m_2 \times \dots \times m_p}.\end{aligned}$$

- Multilinear Tensor Regression is the case where \mathcal{B} has an OP format $\mathcal{B}_{OP} = \circ[[M_1, M_2, \dots, M_p]]$ because

$$\langle \mathcal{X}_i | \mathcal{B}_{OP} \rangle = [[\mathcal{X}_i; M_1, M_2, \dots, M_p]].$$

- You can instead do a CP, TR or TK format!