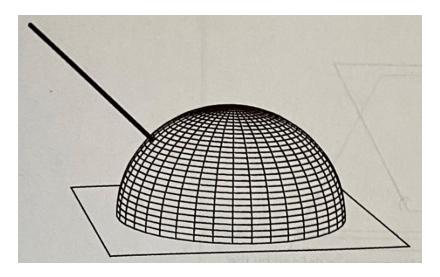
8 Reflection models

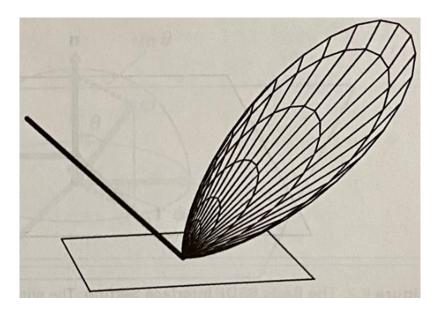
The <u>BRDF</u> describes light <u>reflection</u> at a surface, the BTDF describes light <u>transmission</u> at a surface, and the BSDF encompasses <u>both</u> of these effects described generally as <u>scattering</u>.

Categories of surface reflection (IMPORTANT: most surfaces exhibit a *mixture* of these 4 types):

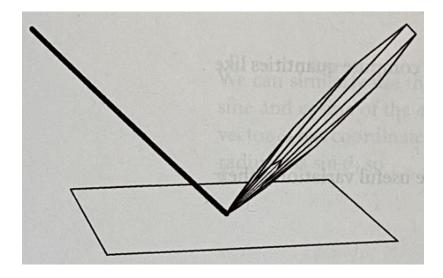
- Diffuse: light scatters equally in all directions. Matte paint, dull chalkboards, etc.



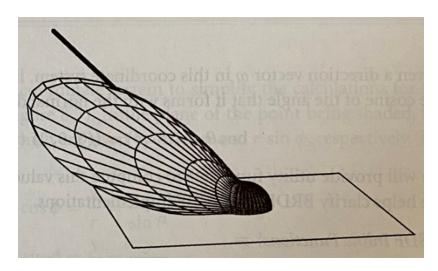
- *Glossy specular*: light scatters preferentially in a set of reflected directions (reflected direction as opposed to back in the incident direction). Plastic, high-gloss paint, etc.



- Perfect specular: light scatters in a single reflected direction. Mirrors, glass, etc.



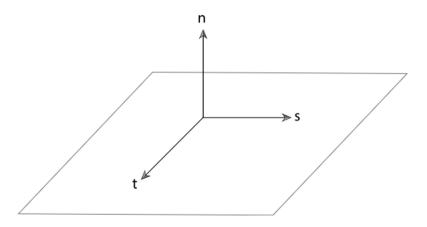
- Retro-reflective: light scatters primarily back along the incident direction. Velvet, the moon, etc.



Surface reflection can be further subcategorized as *isotropic* or *anisotropic*:

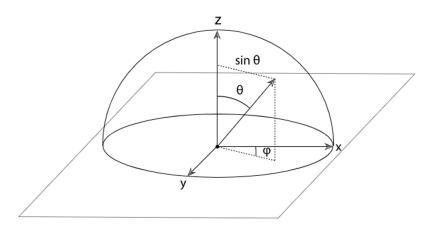
- *Isotropic:* if you rotate the surface about the normal at one point, the <u>reflectance distribution</u> <u>doesn't change</u>.
- *Anisotropic:* if you rotate the surface about the normal at one point, the <u>reflectance distribution</u> <u>changes</u>. Brush metal, compact disks, etc.

The <u>shading coordinate system</u>. <u>Orthonormal basis</u> vectors are 2 vectors tangent to the surface at a point and the normal.



s and t are aligned with x and y, and n with z. (World space x, y, and z? No. Orientation is such that n points up.)

The spherical coordinates of a direction vector ω are expressed relative to this orthonormal basis. (Note that for computing ϕ , ω is first projected to the xy (st) plane.)



The sine, cosine, and tangent of θ and ϕ are computed using various trigonometric and Pythagorean identities (note the triangles). An interesting thing to note is that the length of the projection of ω onto the xy plane is given by $\sin\theta$.

The ω vector in the shading coordinate system:

- Is a linear combination of $\{s, t, n\}$.
- Is normalized.
- Is outward facing, even if it is an incident direction vector.
- Is an incident one when it is in the same hemisphere as n. And n always points away from the object.

8.1 Basic interface

All categories of surfaces (according to how they reflect light) compute the BRDF (and BTDF) differently. But a <u>special</u> note must be made for <u>perfect specular surfaces</u>: their directional distribution is a <u>Dirac delta function</u>: only a single incident direction contributes to the reflected radiometric quantity in a given outgoing direction (that is to say that the outgoing direction determines the incident direction uniquely). In contrast, the BRDFs (and BTDF) of other surfaces map a given outgoing direction to multiple (or all) incident directions.

The BxDF is the abstract base class / interface of BRDFs and BTDFs. Among other things, it computes the spectral distribution (Spectrum) of a pair of outgoing and incident directions.

8.1.1 Reflectance

See <u>here</u>.

8.2 Specular reflection and transmission

TODO

8.3 Lambertian reflection

The <u>Lambertian model</u> models a <u>perfect diffuse</u> surface that scatters incident light equally in all directions. Not physically possible.

Its BxDF uses a <u>reflectance</u> (a distribution, a spectral distribution, Spectrum) that expresses the fraction of incident light that is scattered ("scattering" is a term that stands for "reflection" or "transmission") at each wavelength in the outgoing direction, which is <u>equal</u> for (or <u>constant</u> across) all outgoing directions in the hemisphere. (Is the rest of the incident energy absorbed?)

The Lambertian BRDF $f_r(p, \omega_i, \omega_o)$ is a constant spectral distribution commonly called the <u>diffuse color</u> c_{diff} or <u>albedo</u>.

Since the BRDF is constant across all outgoing directions, the Lambertian <u>directional-hemispherical</u> <u>reflectance</u> is constant too:

$$\begin{split} &\rho_{dh}(\omega_{i}) \\ &= \int\limits_{\Omega = H^{2}(n):\{\omega_{o}\}} f_{r}(p,\omega_{i},\omega_{o}) \left| \cos\theta_{o} \right| d\omega_{o} \\ &= f_{r}(p,\omega_{i},\omega_{o}) \int\limits_{\Omega = H^{2}(n):\{\omega_{o}\}} \left| \cos\theta_{o} \right| d\omega_{o} \\ &= f_{r}(p,\theta_{o},\phi_{o},\theta_{i},\phi_{i}) \int\limits_{\phi_{i}=0}^{2\pi} \int\limits_{\theta_{i}=0}^{\pi/2} \left| \cos\theta_{i} \right| \sin\theta_{i} d\theta_{i} d\phi_{i} \\ &= f_{r}(p,\theta_{o},\phi_{o},\theta_{i},\phi_{i}) \pi \\ &= \pi f_{r}(p,\omega_{i},\omega_{o}) \\ &= \pi c_{diff} \end{split}$$

The value of the double definite integral is π :

f(x,y)	cos(y)sin(y)	
dA	dydx 🗸	
x from	0 to 2pi	
y from	0 to pi/2	
Submit		
finite integral:		
inite integral.		More
$C2\pi$ C^{π}	$\sin(y) dy dx = \pi \approx 3.14159$	

*Wolfram Alpha	Get this widget	i 🛨 🗀

2 classes implement the Lambertian model: LambertianReflection is the BRDF and LambertianTransmission is the BTDF.

TODO: how does Lambertian transmission work? What materials exhibit diffuse transmission?