



# Algorithmical Geometry: Computation of Delaunay Triangulations Using a Divide-and-Conquer Algorithm

Markus Pawellek

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#### Outline

Related Work

Mathematical Preliminaries

Geometric Primitives

Quad-Edge Data Structure

Algorithm

Implementation Notes

Conclusions

Educational Problems:

Many Resources

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- Duality to Voronoi Diagrams

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- Multiple Algorithm Types: Incremental, Sweepline, Divide-and-Conquer

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- Multiple Algorithm Types: Incremental, Sweepline, Divide-and-Conquer
- Varying Data Structures

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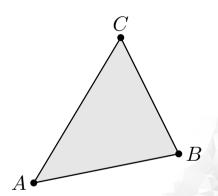
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# Mathematical Preliminaries

## Mathematical Preliminaries: Triangle and Circumcircle

#### **Triangle**

 $A,B,C\in\mathbb{R}^2$  affinely independent define vertices of a triangle.



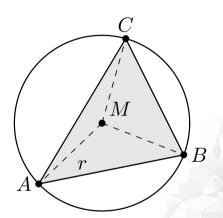
# Mathematical Preliminaries: Triangle and Circumcircle

#### **Triangle**

 $A,B,C\in\mathbb{R}^2$  affinely independent define vertices of a triangle.

#### Circumcircle

Circle that intersects with all vertices of the triangle.



# Mathematical Preliminaries: Point Set

#### **Point Set**

 $\mathcal{V} \subset \mathbb{R}^2$  finite,  $\#\mathcal{V} \geq 3$ , affinely span  $\mathbb{R}^2$ 

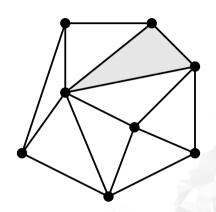
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Planar straight-line graph over  $\mathcal{V}$  such that its edges form a maximal subset of non-crossing edges.



# Mathematical Preliminaries: Delaunay Triangulation

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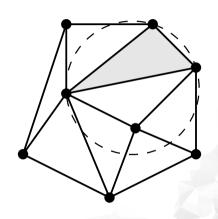
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Circumcircle of any triangle contains no other points of V.



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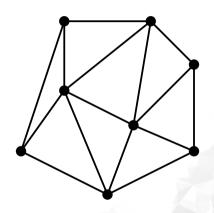
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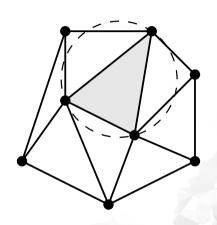
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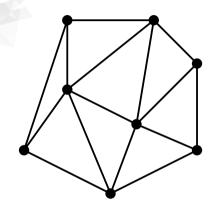
#### **Triangulation**

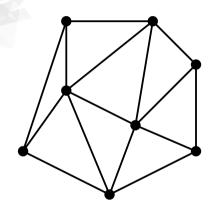
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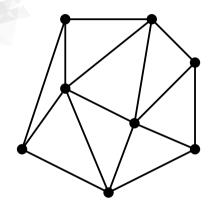
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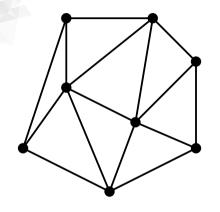




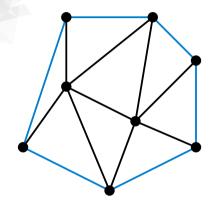
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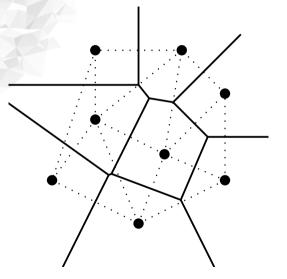
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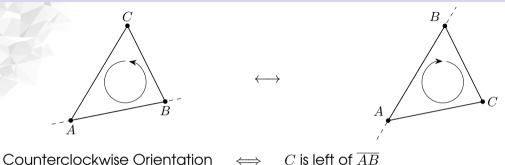
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- Dual of Voronoi diagram

# Geometric Primitives







Counterclockwise Orientation 
$$\iff$$
  $C$  is left of  $\overline{AB}$ 

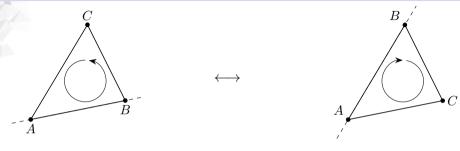
$$0 < \begin{vmatrix} A_x & A_y & 1 \\ B_x & B_y & 1 \\ C_x & C_y & 1 \end{vmatrix}$$



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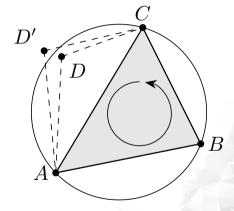
### Geometric Primitives: Triangle Orientation



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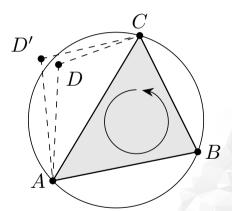
$$0 < \begin{vmatrix} A_x & A_y & 1 \\ B_x & B_y & 1 \\ C_x & C_y & 1 \end{vmatrix} = \begin{vmatrix} B_x - A_x & B_y - A_y \\ C_x - A_x & C_y - A_y \end{vmatrix} = \det \left( B - A - C - A \right)$$

### Geometric Primitives: Inside Circumcircle



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$$0 < \begin{vmatrix} A_x & A_y & A_x^2 + A_y^2 & 1 \\ B_x & B_y & B_x^2 + B_y^2 & 1 \\ C_x & C_y & C_x^2 + C_y^2 & 1 \\ D_x & D_y & D_x^2 + D_y^2 & 1 \end{vmatrix}$$



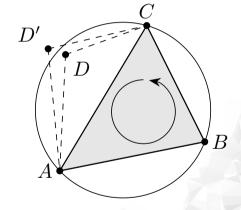
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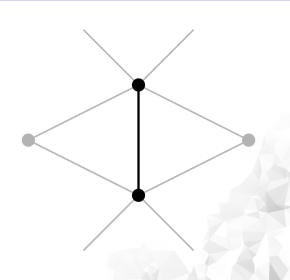
$$= \left\langle x, \operatorname{adj} \left( u \ v \right)^{\mathrm{T}} \begin{pmatrix} \|u\|^{2} \\ \|v\|^{2} \end{pmatrix} \right\rangle$$

$$- \det \left( u \ v \right) \|x\|^{2}$$

 $u \coloneqq B - A, \quad v \coloneqq C - A, \quad x \coloneqq D - A$ 

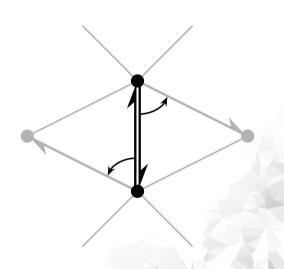


### Quad-Edge Data Structure

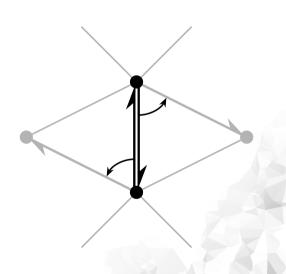


Edge-Based List-Like Data Structure for Storing Neighbor Information:

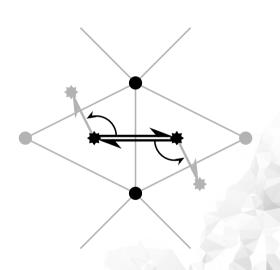
Directed edges for vertices



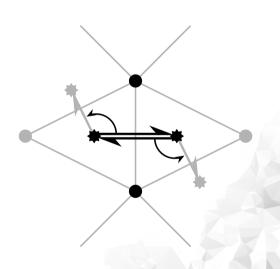
- Directed edges for vertices
- Pointer to ccw. next directed edge with same origin vertex



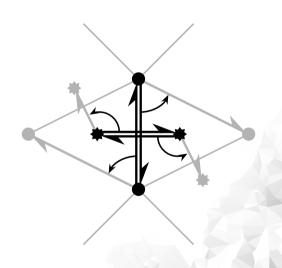
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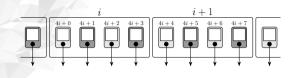
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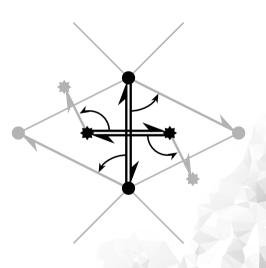
### Quad-Edge Data Structure: Implementation



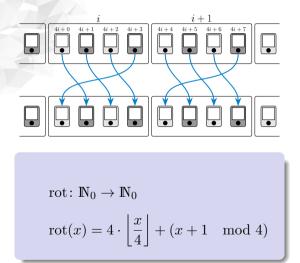
```
struct edge {
    size_t next;
    size_t data;
};

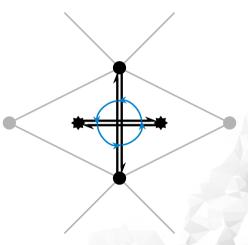
struct quad_edge {
    edge data[4];
};

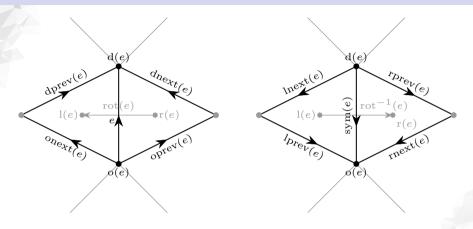
vector<vertex> vertices{};
vector<quad_edge> quad_edges{};
vector<size_t> free_edges{};
```

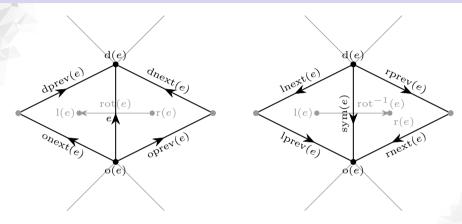


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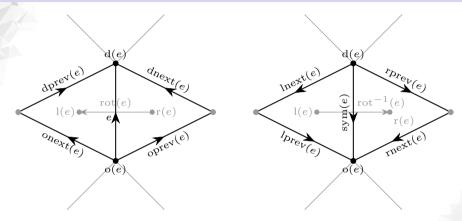




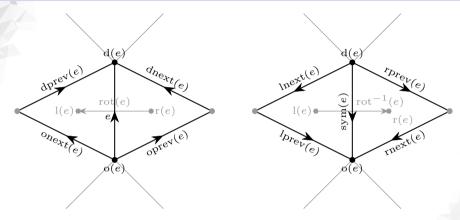




Create a new edge



- ► Create a new edge
- ▶ Delete existing edge



- Create a new edge
- Delete existing edge
- Connect points by a new edge

# Algorithm

### Triangulation Algorithm

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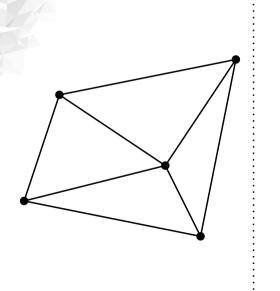
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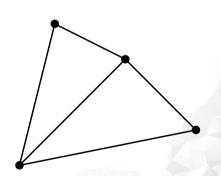
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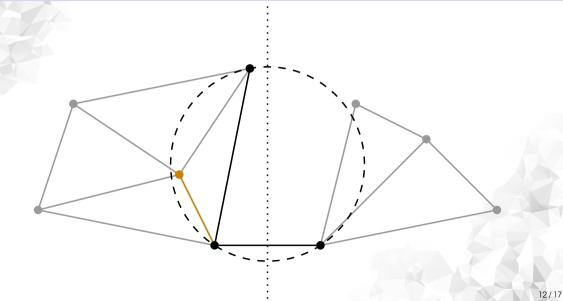
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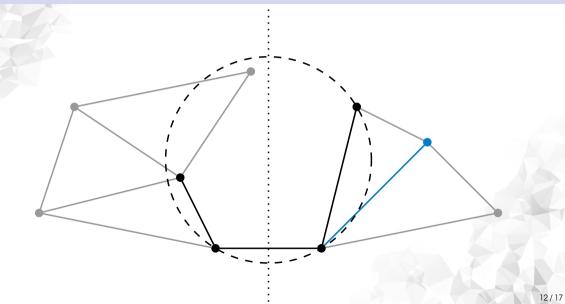
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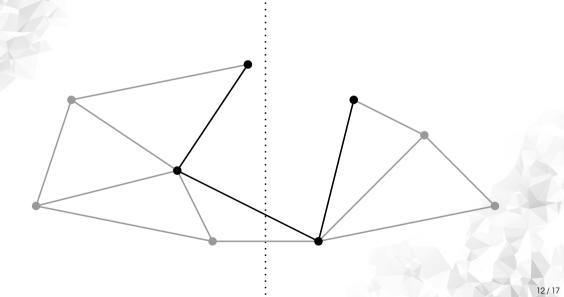
- 1. If point count is smaller than four, make edge or triangle and return.
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- 4. Merge left and right triangulations.

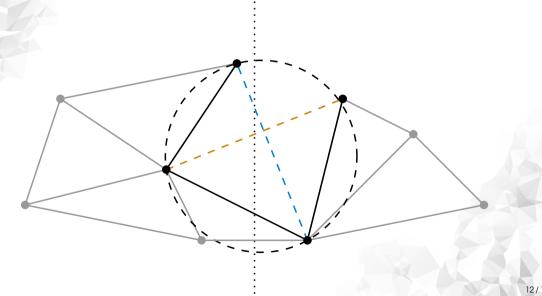






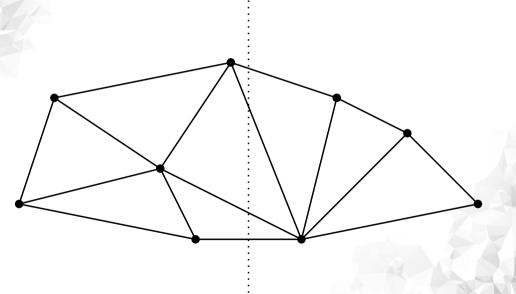






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$$T(n) = \mathcal{O}(n \log n)$$

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- Algorithm is correct

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- Divide-and-conquer variant seems to be most powerful and robust

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### **Future Work:**

Use triangular data structure instead of quad-edge data structure

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- Use triangular data structure instead of quad-edge data structure
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# Thank you for Your Attention!

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