

# Algorithmical Geometry: Computation of Delaunay Triangulations Using a Divide-and-Conquer Algorithm

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#### Outline

**Related Work** 

Mathematical Preliminaries

Geometric Primitives

**Quad-Edge Data Structure** 

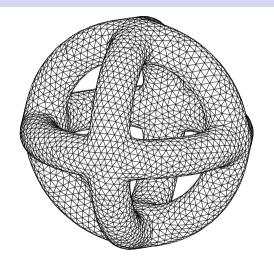
Algorithm

Implementation Notes

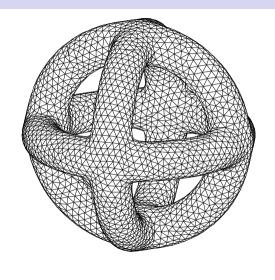
**Applications** 

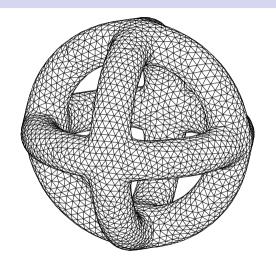
Conclusions





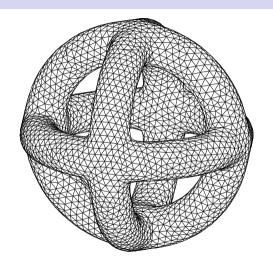
<sup>\*</sup>https://upload.wikimedia.org/wikipedia/commons/b/b8/Approx-3tori.svg, December 29, 2021



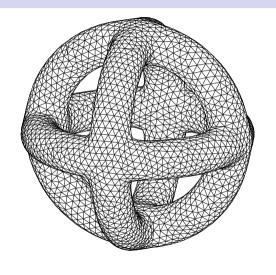


#### **Educational Problems:**

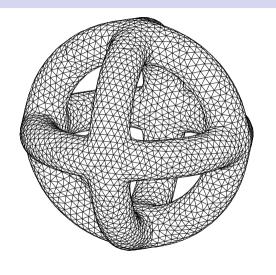
Many Resources



- Many Resources
- Duality to Voronoi Diagrams



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- Multiple Algorithm Types: Incremental, Sweepline, Divide-and-Conquer



- Many Resources
- Duality to Voronoi Diagrams
- Multiple Algorithm Types: Incremental, Sweepline, Divide-and-Conquer
- Varying Data Structures

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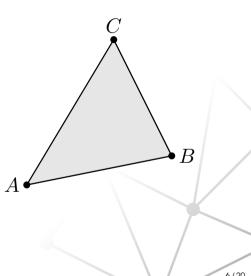
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# Mathematical Preliminaries

## Mathematical Preliminaries: Triangle and Circumcircle

#### **Triangle**

 $A, B, C \in \mathbb{R}^2$  affinely independent define vertices of a triangle.



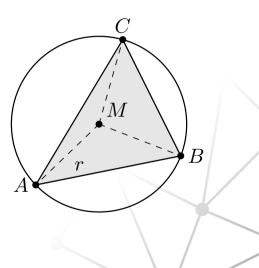
## Mathematical Preliminaries: Triangle and Circumcircle

#### **Triangle**

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#### Circumcircle

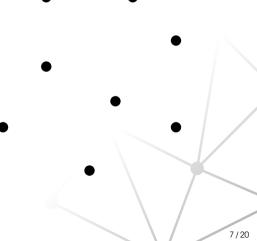
Circle that intersects with all vertices of the triangle.



# Mathematical Preliminaries: Point Set

### **Point Set**

 $\mathcal{V}\subset\mathbb{R}^2$  finite,  $\#\mathcal{V}\geq 3$ , affinely span  $\mathbb{R}^2$ 



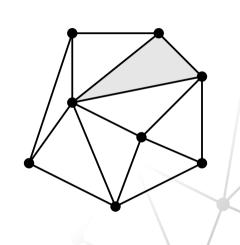
# Mathematical Preliminaries: Triangulation

#### **Point Set**

 $\mathcal{V} \subset \mathbb{R}^2$  finite,  $\#\mathcal{V} \geq 3$ , affinely span  $\mathbb{R}^2$ 

#### **Triangulation**

Planar straight-line graph over  $\mathcal{V}$  such that its edges form a maximal subset of non-crossing edges.



# Mathematical Preliminaries: Delaunay Triangulation

#### **Point Set**

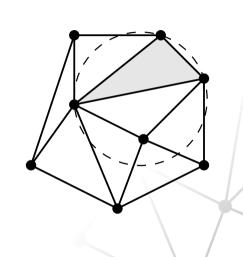
 $\mathcal{V} \subset \mathbb{R}^2$  finite,  $\#\mathcal{V} \geq 3$ , affinely span  $\mathbb{R}^2$ 

#### **Triangulation**

Planar straight-line graph over V such that its edges form a maximal subset of non-crossing edges.

#### **Delaunay Triangulation**

Circumcircle of any triangle contains no other points of V.



# Mathematical Preliminaries: Delaunay Triangulation

#### **Point Set**

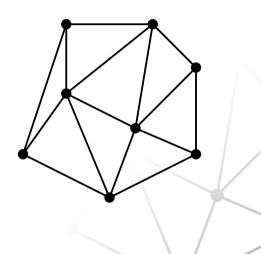
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# Mathematical Preliminaries: Delaunay Triangulation

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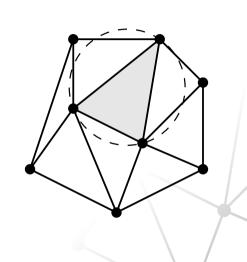
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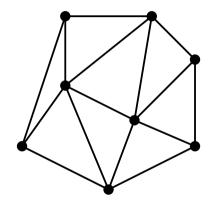
#### **Triangulation**

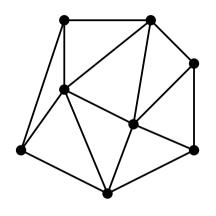
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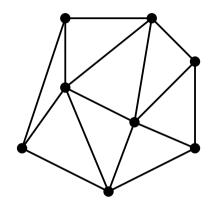
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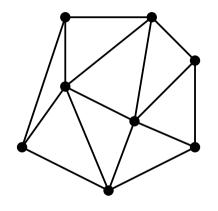




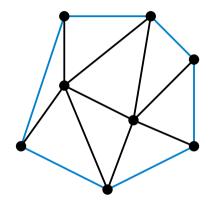
► Existence is guaranteed



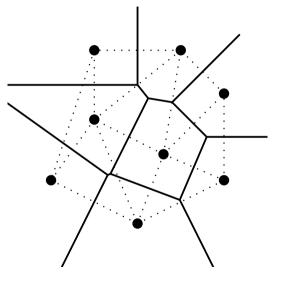
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- Unique if there are no four points that are cocircular
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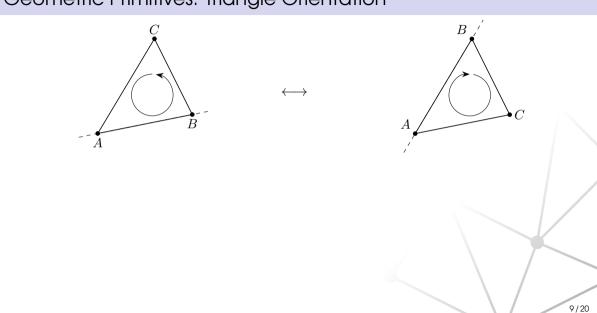


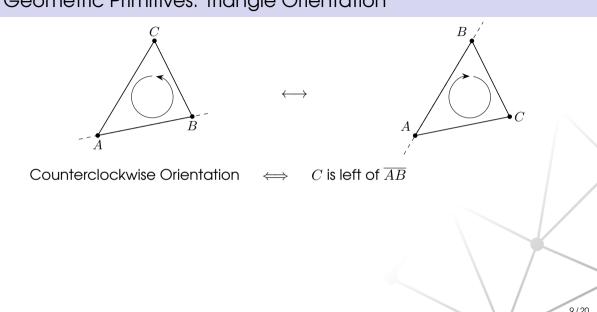
- Existence is guaranteed
- Unique if there are no four points that are cocircular
- Optimality: maximization of the minimum angle of all angles
- Convex hull is contained

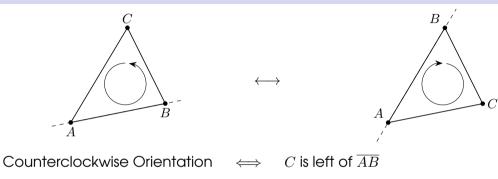


- Existence is guaranteed
- Unique if there are no four points that are cocircular
- Optimality: maximization of the minimum angle of all angles
- Convex hull is contained
- Dual of Voronoi diagram

# Geometric Primitives







$$0 < \begin{vmatrix} A_x & A_y & 1 \\ B_x & B_y & 1 \\ C_x & C_y & 1 \end{vmatrix}$$



Counterclockwise Orientation 
$$\iff$$
  $C$  is left of  $\overline{AB}$ 

$$0 < \begin{vmatrix} A_x & A_y & 1 \\ B_x & B_y & 1 \\ C_x & C_y & 1 \end{vmatrix} = \begin{vmatrix} B_x - A_x & B_y - A_y \\ C_x - A_x & C_y - A_y \end{vmatrix}$$

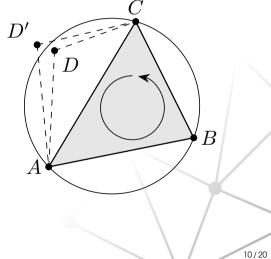
# Geometric Primitives: Triangle Orientation

$$\longleftrightarrow \qquad \longleftrightarrow \qquad A$$

Counterclockwise Orientation 
$$\iff$$
  $C$  is left of  $\overline{AB}$ 

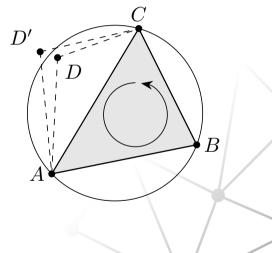
$$0 < \begin{vmatrix} A_x & A_y & 1 \\ B_x & B_y & 1 \\ C_x & C_y & 1 \end{vmatrix} = \begin{vmatrix} B_x - A_x & B_y - A_y \\ C_x - A_x & C_y - A_y \end{vmatrix} = \det \left( B - A - C - A \right)$$

# Geometric Primitives: Inside Circumcircle



#### Geometric Primitives: Inside Circumcircle

$$0 < \begin{vmatrix} A_x & A_y & A_x^2 + A_y^2 & 1 \\ B_x & B_y & B_x^2 + B_y^2 & 1 \\ C_x & C_y & C_x^2 + C_y^2 & 1 \\ D_x & D_y & D_x^2 + D_y^2 & 1 \end{vmatrix}$$



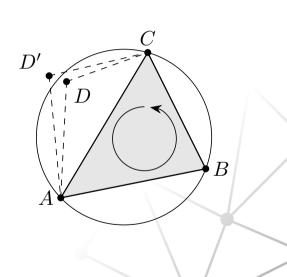
### Geometric Primitives: Inside Circumcircle

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$$= \left\langle x, \operatorname{adj} \left( u \ v \right)^{\mathrm{T}} \begin{pmatrix} \|u\|^2 \\ \|v\|^2 \end{pmatrix} \right\rangle$$

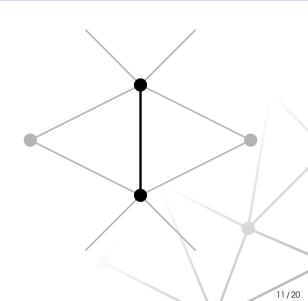
$$- \det \left( u \ v \right) \|x\|^2$$

$$u \coloneqq B - A, \quad v \coloneqq C - A, \quad x \coloneqq D - A$$



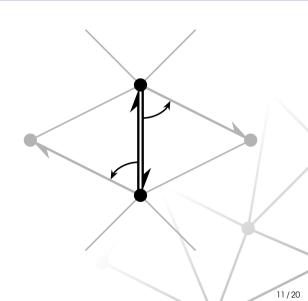
# Quad-Edge Data Structure

Edge-Based List-Like Data Structure for Storing Neighbor Information:



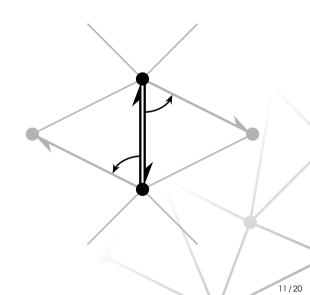
Edge-Based List-Like Data Structure for Storing Neighbor Information:

Directed edges for vertices



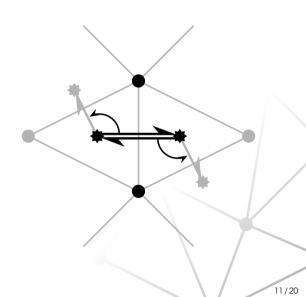
Edge-Based List-Like Data Structure for Storing Neighbor Information:

- Directed edges for vertices
- Pointer to ccw. next directed edge with same origin vertex



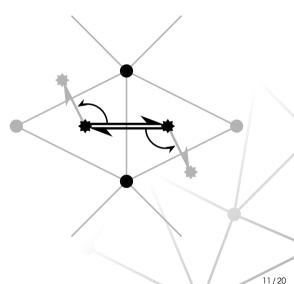
Edge-Based List-Like Data Structure for Storing Neighbor Information:

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- Directed dual edges for adjacent faces



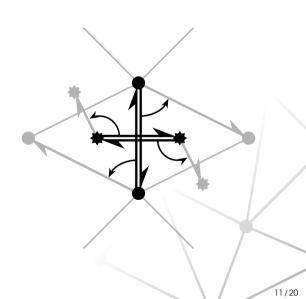
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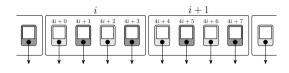


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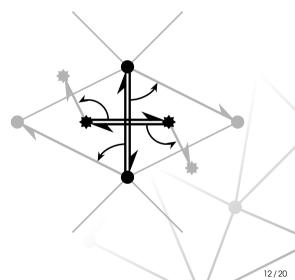
# Quad-Edge Data Structure: Implementation



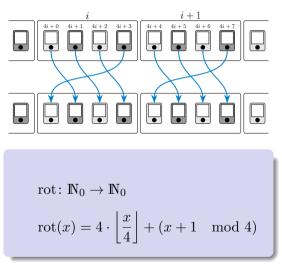
```
struct edge {
    size_t next;
    size_t data;
};

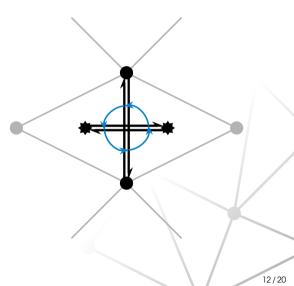
struct quad_edge {
    edge data[4];
};

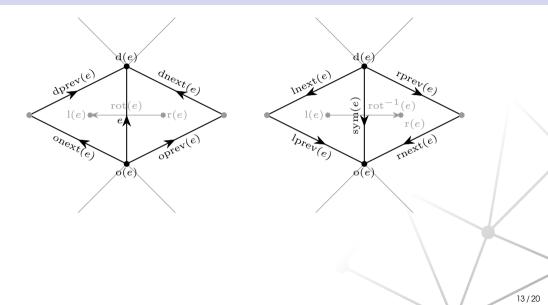
vector<vertex> vertices{};
vector<quad_edge> quad_edges{};
vector<size_t> free_edges{};
```

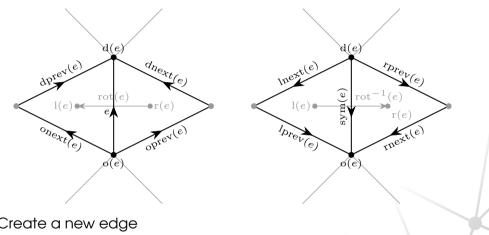


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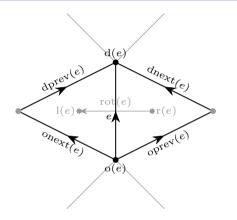




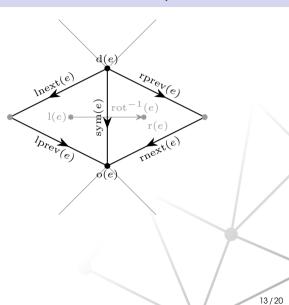


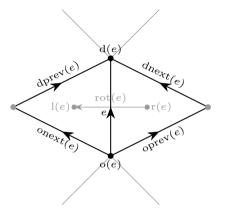


Create a new edge

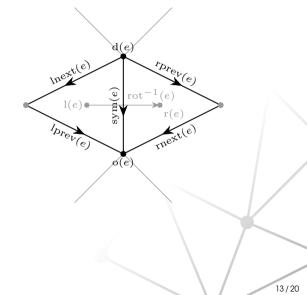


- Create a new edge
- ▶ Delete existing edge

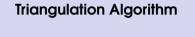




- Create a new edge
- Delete existing edge
- Connect points by a new edge



# Algorithm



#### Triangulation Algorithm

1. Sort the given point set by increasing  $\boldsymbol{x}$  coordinate.

#### **Triangulation Algorithm**

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#### **Subroutine: Triangulate**

1. If point count is smaller than four, make edge or triangle and return.

#### **Triangulation Algorithm**

- 1. Sort the given point set by increasing  $\boldsymbol{x}$  coordinate.
- 2. Triangulate sorted point set.

- 1. If point count is smaller than four, make edge or triangle and return.
- 2. Split point set into left and right half.

#### **Triangulation Algorithm**

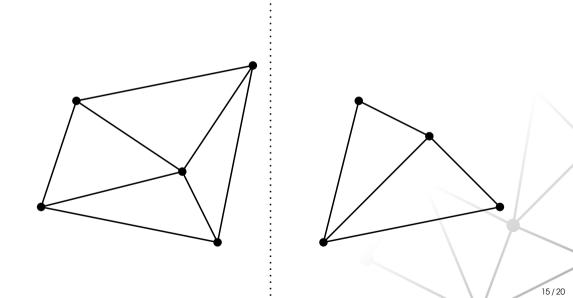
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#### **Triangulation Algorithm**

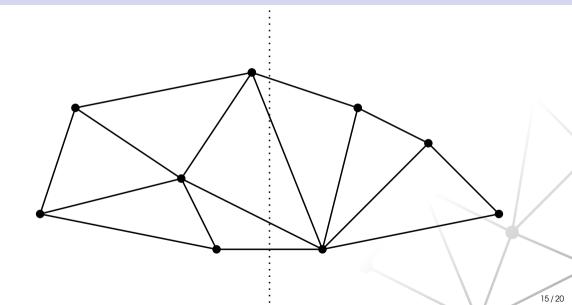
- 1. Sort the given point set by increasing x coordinate.
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- 1. If point count is smaller than four, make edge or triangle and return.
- 2. Split point set into left and right half.
- 3. Triangulate left and right half.
- 4. Merge left and right triangulations.



# Algorithm: Merge Triangulations Example 15/20

# Algorithm: Merge Triangulations Example





- ▶ linear complexity by using Euler's formula for planar graphs
- computation of lower common tangent
- circle test for adjacent edges
- circle test for cross edge

#### **Subroutine: Merge Triangulations**

1. Compute and add lower common tangent.

- linear complexity by using Euler's formula for planar graphs
- computation of lower common tangent
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- 1. Compute and add lower common tangent.
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  - 3.3 Make this cross edge the new baseline.
- linear complexity by using Euler's formula for planar graphs
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# Algorithm: Complexity

- Use master theorem
- Merge step is linear in point count

$$t(n) = 2t\left(\frac{n}{2}\right) + \mathcal{O}(n)$$

$$\mathcal{O}(n\log n)$$

#### Subroutine: Triangulate

- If point count is smaller than four, make edge or triangle and return.
- 2. Split point set into left and right half.
- 3. Triangulate left and right half.
- Merge left and right triangulations.

# Algorithm: Correctness

#### Proof by induction:

Show that for two given Delaunay triangulations  $\mathfrak{T}(\mathcal{L})$  and  $\mathfrak{T}(\mathcal{R})$  separated by a vertical line the merge subroutine generates a Delaunay triangulation  $\mathfrak{T}(\mathcal{L} \cup \mathcal{R})$ .

- ► For two Delaunay triangulations separated by a vertical line, it is enough to remove inner edges and insert cross edges.
- Common tangents are elements of the Delaunay triangulation.
- Removed edges are indeed not Delaunay.
- Insertion of cross edges generates new Delaunay triangle.
- There are no other edges that have to be removed.
- ▶ Theorem: Algorithm is correct.

# Implementation Notes

## Implementation Notes

- Geometric Primitives need exact computation and therefore arbitrary precision
- still no robust split, use Dwyer instead (no sorting, parallelization)
- triangular data structure increases speed but algorithm is more complicated
- Divide-and-conquer variant seems to be most powerful and robust

# Applications

# Conclusions

#### Conclusions

#### **Summary:**

- ▶ Delaunay triangulation can be generated by given divide-and-conquer algorithm in  $O(n \log n)$
- Data structure needs to store neighbor information

#### **Future Work:**

- Use triangular data structure instead of quad-edge data structure
- Use Dwyer's approach to make algorithm more robust
- Parallelization

# Thank you for Your Attention!

## References

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(1)	D. T. Lee and B. J. Schachter. "Two Algorithms for Constructing a Delaunay Triangulation". In: <i>International</i> <i>Journal of Computer and Information Sciences</i> 9 (1980), pp. 219–242. DOI: 10.1007/BF00977785.	(7)	D. F. Watson. "Computing the <i>n</i> -Dimensional Delaunay Tessellation with Application to Voronoi Polytopes". In: <i>The Computer Journal</i> 24 (1981), pp. 167–172. DOI: 10.1093/comjnl/24.2.167.
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