

## Lógicas modales

Carlos Areces & Raul Fervari

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## Part I

## Memory logics

### Changing the model

- The Modal Logic book says

A modal formula is a little automaton standing at some state in a relational structure, and only permitted to explore the structure by making journeys to neighbouring states.

- What about granting our automaton the additional power to **modify the model** during its exploratory trips?
- There may be many ways to modify a model (changing the domain, the edges, the valuation, ...)
- We want to restrict our attention to a specific way of modifying a model: **adding a memory** to the model, and **performing changes** on it

### Changing the model

- We are going to add a storage structure to standard Kripke models:

$$\mathcal{M} = \langle W, (R_r)_{r \in \text{rel}}, V \rangle$$



- There are many possible types of structures: a set, a list, a stack, ...
- We want to start with a very simple structure, so we are going to add a **set**  $S$  to the standard Kripke model:

#### Memory Kripke model

Given a set  $S \subseteq W$ , a memory Kripke model is

$$\mathcal{M} = \langle W, (R_r)_{r \in \text{rel}}, V, S \rangle$$

## Changing the model

We have to add suitable operators to manipulate the memory

- Since we are using a set  $S$  as the container, there are two “natural” operators to use:
  - An operator  $\textcircled{r}$  to *remember* the current point, storing it in  $S$ .
  - An operator  $\textcircled{k}$  to check membership of the current point, and find out whether it is *known*

### Some notation

Given  $\mathcal{M} = \langle W, (R_r)_{r \in \text{rel}}, V, S \rangle$ ,  $w \in W$ , we define

$$\mathcal{M}[w] = \langle W, (R_r)_{r \in \text{rel}}, V, S \cup \{w\} \rangle$$

Now, more formally

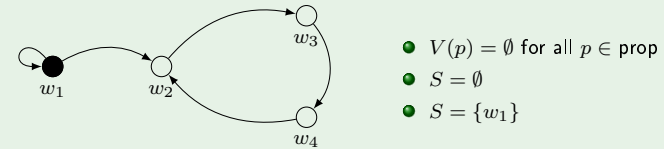
### Semantics of $\textcircled{r}$ and $\textcircled{k}$

$$\begin{aligned} \mathcal{M}, w \models \textcircled{r}\varphi & \text{ iff } \mathcal{M}[w], w \models \varphi \\ \mathcal{M}, w \models \textcircled{k} & \text{ iff } w \in S \end{aligned}$$

## Changing the model

Let's see the use of  $\textcircled{r}$  and  $\textcircled{k}$  with an example. Suppose we start with the following model:

### A model with an initially empty memory



- How can we check whether  $w_1$  has a successor different from itself?

$$\begin{aligned} \mathcal{M}, w_1 & \models \textcircled{r}\Diamond\neg\textcircled{k} \\ & \Updownarrow \\ \mathcal{M}[w_1], w_1 & \models \Diamond\neg\textcircled{k} \\ & \Updownarrow \\ \mathcal{M}[w_1], w_2 & \models \neg\textcircled{k} \quad \checkmark \end{aligned}$$

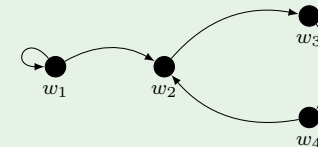
## Memory logics

- The idea of using operators that **change** the model is not new
- The family of languages with these characteristics are sometimes called **dynamic logics**
- For example:
  - Dynamic epistemic logics
  - Real time logics
  - Dynamic predicate logic
- Memory logics can be seen as dynamic languages that
  - Do not add any domain-specific behaviour in the evolution of the model
  - Analyze dynamic behaviour from a very simple perspective
  - Can be thought of as a ‘weak’ version of the standard  $\downarrow$  modal binder
- Can be combined with other modal and hybrid operators ( $A$ , nominals,  $@$ , etc.)

## Other operators

- We can think in other operators, that *delete* elements from the memory.
- In the previous example, the memory was initially empty, which was quite convenient

### A model where every point is memorized



- How can we check whether  $w_1$  has a successor different from itself?
- There doesn't seem to be a way...

## Other operators

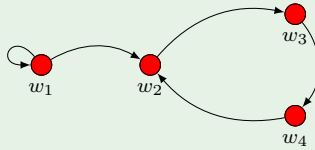
We can define an operator  $\textcircled{e}$  (for 'erase') that completely wipes out the memory

### Semantics of $\textcircled{e}$

$$\langle M, (R_r)_{r \in \text{rel}}, V, S \rangle, w \models \textcircled{e}\varphi \quad \text{iff} \quad \langle M, (R_r)_{r \in \text{rel}}, V, \emptyset \rangle, w \models \varphi$$

So now, in order to check in  $\mathcal{M}$  whether  $w_1$  has a successor different from itself

A model  $\mathcal{M}$ , where every point is memorized



we can evaluate

$$\mathcal{M}, w_1 \models \textcircled{e}(\textcircled{r}\Diamond \neg \textcircled{k}) \textcircled{r}\Diamond \neg \textcircled{k}$$

This formula works independently of the initial state of the memory

## Other ingredients

There are other "dimensions" we can take into consideration:

- Class of models: for example, it is quite natural to consider the class of models whose memory is initially empty
- Memorizing policies: we can try to impose some restrictions on the interplay between memory and modal operators
  - These restrictions are going to help us find decidable fragments
- Other memory operators and containers: are there other memory operators? What happens if we change a set by other type of structure?
  - We can define  $\textcircled{f}$ , a local version of  $\textcircled{e}$
  - We can try using a stack instead of a set as the memory container

## Other operators

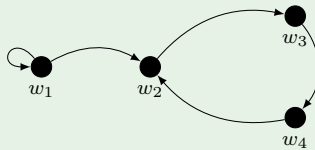
- We can also think in a 'local' version of  $\textcircled{e}$ , that only deletes the current point of evaluation.
- Let's consider then the operator  $\textcircled{f}$  (for 'forget')

### Semantics of $\textcircled{f}$

$$\langle M, (R_r)_{r \in \text{rel}}, S \rangle, w \models \textcircled{f}\varphi \quad \text{iff} \quad \langle M, (R_r)_{r \in \text{rel}}, S \setminus \{w\} \rangle, w \models \varphi$$

Again, if we want to check in  $\mathcal{M}$  whether  $w_1$  has a successor different from itself

A model  $\mathcal{M}$ , where every point is memorized



we can evaluate

$$\mathcal{M}, w_1 \models \textcircled{f}(\textcircled{r}\Diamond \textcircled{k}) \textcircled{k}$$

## Other ingredients: classes of models

Observe that when the memory of  $\mathcal{M}$  is initially empty,

$$\mathcal{M}, w \models \textcircled{r}\langle r \rangle \textcircled{k} \quad \text{iff} \quad w R_r w$$

But this formula is also true at

A model with a non-empty memory



Taking this into consideration, it is natural to consider memory logics restricted to

$$\mathcal{C}_\emptyset = \{ \mathcal{M} \mid \mathcal{M} = \langle W, (R_r)_{r \in \text{rel}}, V, \emptyset \rangle \}$$

the class of models with an empty memory.

## Other ingredients: memorizing policies

- Until now memory and modal operators were working 'in parallel'
- Restricting expressivity sometimes can be helpful to reduce computational cost
- We can try to impose some restrictions in the interplay between memory and modal operators

Let's define an operator where  $\langle r \rangle$  and  $\textcircled{r}$  act **at the same time**

### $\langle r \rangle$ and $\textcircled{r}$ working together

$$\mathcal{M}, w \models \langle\langle r \rangle\rangle \varphi \quad \text{iff} \quad \exists w' \in W, R_r(w, w') \text{ and } \mathcal{M}[w], w' \models \varphi.$$

We are going to see later that this operator helps us to find **decidable** memory fragments

## Notation

We are going to work with several memory logic fragments

### Notational convention

- We call  $\mathcal{ML}$  the basic modal logic, and  $\mathcal{HL}$  the extension of  $\mathcal{ML}$  with nominals
- When we add a set  $S$  and the operators  $\textcircled{r}$  and  $\textcircled{k}$  we add  $m$  as a superscript, e.g.  $\mathcal{ML}^m(\dots)$
- We add  $\emptyset$  as a subscript when we work with  $\mathcal{C}_\emptyset$  (otherwise is the class of all models), e.g.  $\mathcal{ML}_\emptyset^m(\dots)$
- Then we list the additional operators

For example

- $\mathcal{ML}_\emptyset^m(\langle r \rangle, \textcircled{e})$ : the modal memory logic with  $\textcircled{r}$ ,  $\textcircled{k}$ ,  $\textcircled{e}$  and the usual diamond  $\langle r \rangle$  over the class  $\mathcal{C}_\emptyset$
- $\mathcal{HL}^m(@, \langle r \rangle)$ : the hybrid memory logic with  $\textcircled{r}$ ,  $\textcircled{k}$ ,  $\langle r \rangle$ ,  $@$  over the class of all models

## Getting to know a logic

This is a new family of logics, and there are characteristics that are worth investigating

- Expressivity: What can we say with memory logics? Which is the relation between them and other well-known logics?
- Decidability: Which is the computational complexity of the different fragments? How much are memory operators adding to the basic modal logic?
- Interpolation: How they behave in term of Craig interpolation and Beth definability?
- Axiomatization: Do they have sound and complete axiomatic systems?
- Tableau systems: Can we adapt known tableau techniques to produce sound and complete tableau systems? Can we find terminating tableaux for the decidable memory fragments?

**Disclaimer:** we are not going to see all these topics during this talk

## Expressivity results

We compare the expressive power of the different fragments via the existence of *equivalence preserving translations*

$\mathcal{L}'$  is as least as expressive as  $\mathcal{L}$  ( $\mathcal{L} \leq \mathcal{L}'$ ) if there is a Tr such that

$$\mathcal{M}, w \models_{\mathcal{L}} \varphi \text{ iff } \mathcal{M}, w \models_{\mathcal{L}'} \text{Tr}(\varphi)$$

### Theorem

$$\mathcal{ML}_\emptyset^m(\langle r \rangle) < \mathcal{HL}(\downarrow).$$

To see that  $\mathcal{ML}_\emptyset^m(\langle r \rangle) \leq \mathcal{HL}(\downarrow)$  we define a translation Tr that maps formulas of  $\mathcal{ML}_\emptyset^m(\langle r \rangle)$  into sentences of  $\mathcal{HL}(\downarrow)$ .

- We use  $\downarrow$  to simulate  $\textcircled{r}$ .
- We use a finite set  $N$  to simulate that  $\textcircled{k}$  does not distinguish between different memorized states.

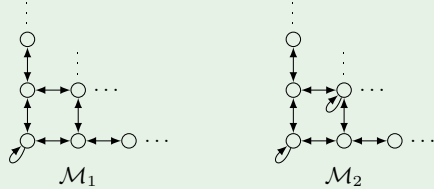
$$\begin{aligned} \text{Tr}_N(\textcircled{r}\varphi) &= \downarrow i. \text{Tr}_{N \cup \{i\}}(\varphi) \quad (\text{for } i \text{ a new nominal}) \\ \text{Tr}_N(\textcircled{k}\varphi) &= \bigvee_{i \in N} i \end{aligned}$$

## Expressivity results

How can we see that  $\mathcal{ML}_\emptyset^m(\langle r \rangle) \neq \mathcal{HL}(\downarrow)$ ? We need to show that there is *no possible* translation from  $\mathcal{HL}(\downarrow)$  to  $\mathcal{ML}_\emptyset^m(\langle r \rangle)$ ...

- We developed a notion of *bisimulation* for each fragment. Intuitively, two models are bisimilar for a logic  $\mathcal{L}$  when they cannot be distinguished by  $\mathcal{L}$ -formulas

$\mathcal{M}_1$  and  $\mathcal{M}_2$  are  $\mathcal{ML}_\emptyset^m(\langle r \rangle)$ -bisimilar



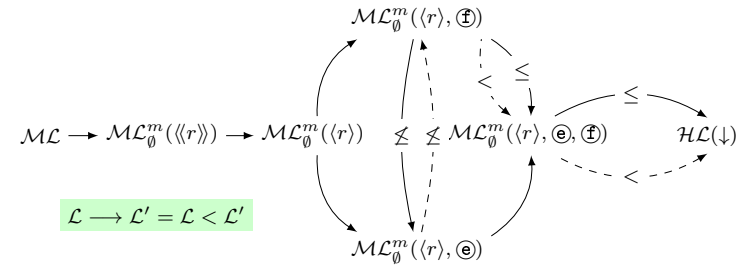
But there is a formula  $\varphi \in \mathcal{HL}(\downarrow)$  such that

$$\mathcal{M}_1, w \models_{\mathcal{HL}(\downarrow)} \varphi \text{ and } \mathcal{M}_2, v \not\models_{\mathcal{HL}(\downarrow)} \varphi$$

So a translation from  $\mathcal{HL}(\downarrow)$  to  $\mathcal{ML}_\emptyset^m(\langle r \rangle)$  cannot exist

## Expressivity results

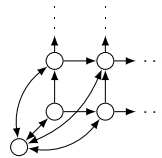
We establish in this way an “expressivity map” for many memory logic fragments:



- All the memory logic fragments are between the basic modal logic and the logic  $\mathcal{HL}(\downarrow)$  (and therefore below first order logic)

## Decidability results

- We have encoded the tiling problem for several memory fragments using a *spy point*: a point that sees every other point in the model



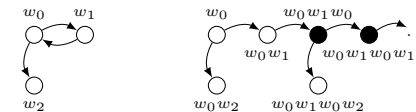
- Most of the memory logic fragments turned out to be undecidable
- We found decidable fragments restricting the interplay between  $\langle r \rangle$  and  $\textcircled{r}$ : we force them to act at the same time

$\langle r \rangle$  and  $\textcircled{r}$  working together

$$\mathcal{M}, w \models \langle r \rangle \varphi \text{ iff } \exists w' \in W, R_r(w, w') \text{ and } \mathcal{M}[w], w' \models \varphi.$$

## Decidability results

- We proved that some fragments are PSPACE-complete showing that they enjoy the bounded tree-model property: every satisfiable formula can be satisfied in a bounded tree
- We showed that there is a procedure to transform an arbitrary model into a tree-like model, preserving equivalence



- We also built a “decidability map” for the different memory fragments

PSPACE-complete	Undecidable
$\mathcal{ML}^m(\langle r \rangle)$	$\mathcal{ML}_\emptyset^m(\langle r \rangle), \mathcal{ML}^m(\langle r \rangle) + i$
$\mathcal{ML}^m(\langle r \rangle, \textcircled{r})$	$\mathcal{ML}^m(\langle r \rangle), \dots$

## Axiomatizations

- We characterized many memory logics fragments in terms of axiomatic systems *à la Hilbert*
- **Nominals** proved to be a very useful device to find sound and complete axiomatizations

### Axiomatization for $\mathcal{HL}^m(@, \langle r \rangle)$

All axioms and rules for  $\mathcal{HL}(@)$

+

$$\vdash @_i(\langle \mathbf{r} \rangle \varphi \leftrightarrow \varphi[\langle \mathbf{k} \rangle / (\langle \mathbf{k} \rangle \vee i)])$$

- We found sound and complete axiomatizations for all the *hybrid* memory fragments (and establish automatic completeness for pure extensions)
- We could provide axiomatizations for some cases even in the absence of nominals (i.e.,  $\mathcal{ML}^m(\langle\langle r \rangle\rangle)$  and  $\mathcal{ML}^m(\langle\langle r \rangle\rangle, \langle \mathbf{f} \rangle)$ )
- The tree-model property was a key feature to use when nominals were not present

## Tableau systems

- We presented a sound and complete tableau system for  $\mathcal{ML}^m(\langle r \rangle, @, \langle \mathbf{f} \rangle)$ ,  $\mathcal{ML}_\emptyset^m(\langle r \rangle, @, \langle \mathbf{f} \rangle)$ , and its sublanguages
- It is a *prefixed* tableau where we use prefixed formulas with the shape

$$\langle w, R, F \rangle^C : \varphi$$

- $w$ : point of evaluation
- $R$ : set of memorized labels
- $F$ : set of forgotten labels
- $C$ : either  $\mathcal{C}_\emptyset$  or the class of all models
- $\varphi$ : current formula
- The rules for propositional and modal operators are standard

## Tableau systems

- For example, the rule for  $\langle \mathbf{r} \rangle$  is quite straightforward

$$(\langle \mathbf{r} \rangle) \quad \frac{\langle w, R, F \rangle^C : \langle \mathbf{r} \rangle \varphi}{\langle w, R \cup \{w\}, F - \{w\} \rangle^C : \varphi}$$

- The rule for  $\langle \mathbf{k} \rangle$  (and for  $\neg \langle \mathbf{k} \rangle$ ) introduces an equivalence class

$$(\langle \mathbf{k} \rangle) \quad \frac{\langle w, \{v_1, \dots, v_k\}, F \rangle^C : \langle \mathbf{k} \rangle}{w \approx v_1 \mid \dots \mid w \approx v_k \mid \langle w, \emptyset, \emptyset \rangle^C : \langle \mathbf{k} \rangle}$$

$$(\text{repl}) \quad \frac{\langle w, R, F \rangle^C : \varphi \quad w \approx^* w'}{\langle w', R[w \mapsto w'], F[w \mapsto w'] \rangle^C : \varphi}$$

- Since this fragment is undecidable, the tableau is non-terminating
- We also provided a sound, complete and terminating tableau for the decidable fragments

## Open questions

- We left some missing links in the expressivity map. We would like to complete it.
- The decidable fragments we found are strictly more expressive than  $\mathcal{ML}$ , but still really close to it. Can we find more expressive but still decidable fragments? We have some ideas
  - Concrete domains: storing values, not points
  - Restricted classes of models
  - Weaker containers (or syntactic restrictions)
- Beth definability needs further research, we would like some general result
- We want to explore the relation between memory logics and other dynamic logics (DEL is a good candidate). This could also lead to decidable fragments
- Can we find suitable axiomatizations in the absence of nominals. We still don't have one for  $\mathcal{ML}^m(\langle r \rangle)$ !

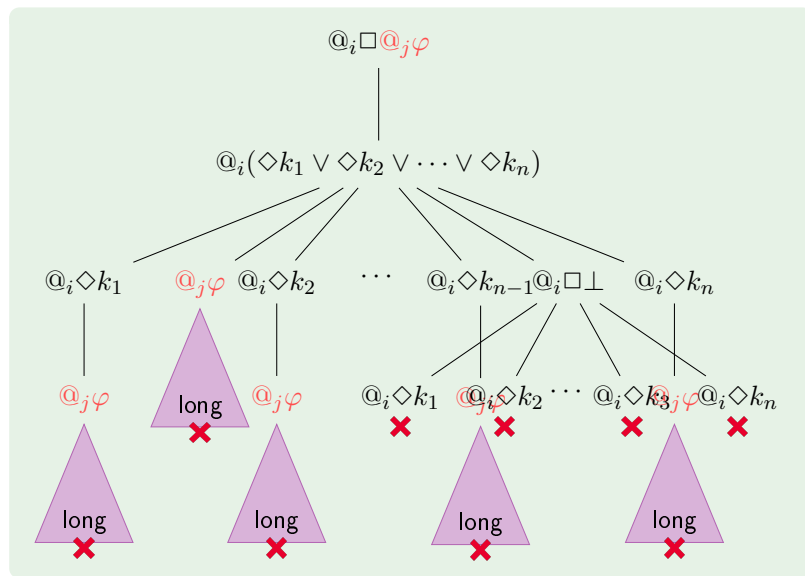
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- Areces, C., Figueira, D., Gorin, D., and Mera, S.. Tableaux and Model Checking for Memory Logics. In Automated Reasoning with Analytic Tableaux and Related Methods, pp. 47–61, Springer Berlin / Heidelberg, Oslo, Norway, 2009.

## Part III

## Coinduction, extractability, normal forms

### Global modalities should be “extracted”



### Globality ~ extractability?

Global modalities are extractable from other modalities...

$$\begin{array}{ll}
 [r]@_i\varphi \equiv [r]\perp \vee @_i\varphi & [r]A\varphi \equiv [r]\perp \vee A\varphi \\
 @_j@_i\varphi \equiv @_j\perp \vee @_i\varphi & @_jA\varphi \equiv @_j\perp \vee A\varphi \\
 A@_i\varphi \equiv A\perp \vee @_i\varphi & AA\varphi \equiv A\perp \vee A\varphi \\
 \vdots & \vdots
 \end{array}$$

... but some modalities are more equal than others

$$\begin{array}{l}
 \downarrow i.@_i\varphi \not\equiv \downarrow i.\perp \vee @_i\varphi \\
 \textcircled{r}A\varphi \not\equiv \textcircled{r}\perp \vee A\varphi
 \end{array}$$

## Coinductive models – a unifying framework

The class of all (rooted) Kripke models with domain  $W$

- $\text{Kripke}_W \stackrel{\text{def}}{=} \text{all the tuples } \langle W, w_0, V, R \rangle \text{ such that}$ 
  - $w_0 \in W$
  - $V(p) \subseteq W$
  - $R(r, w) \subseteq W$
- $\langle W, w, V, R \rangle \models [r]\varphi$  iff  $\langle W, v, V, R \rangle \models \varphi, \forall v \in R(r, w)$
- Many modal operators can be defined as classes of models

The class of all *coinductive models* with domain  $W$

- $\text{Mods}_W \stackrel{\text{def}}{=} \text{all the tuples } \langle W, w_0, V, R \rangle \text{ such that}$ 
  - $w_0 \in W$
  - $V(p) \subseteq W$
  - $R(r, w) \subseteq \text{Mods}_W \leftarrow \text{coinductive definition!}$
- $\langle W, w, V, R \rangle \models [r]\varphi$  iff  $\mathcal{M} \models \varphi, \forall \mathcal{M} \in R(r, w)$
- More modal operators can be defined as classes of models

## Defining Conditions

Defining condition

$$\mathcal{P}_A(\mathcal{M}) \iff R^{\mathcal{M}}(A, w) = \{\langle v, |\mathcal{M}|, V^{\mathcal{M}}, R^{\mathcal{M}} \rangle \mid v \in |\mathcal{M}|\}$$

Defining condition

$$\mathcal{P}_{@_i}(\mathcal{M}) \iff R^{\mathcal{M}}(@_i, w) = \{\langle v, |\mathcal{M}|, V^{\mathcal{M}}, R^{\mathcal{M}} \rangle \mid v \in V(i)\}, i \in \text{Nom}$$

$$\mathcal{P}_{\downarrow i}(\mathcal{M}) \iff R^{\mathcal{M}}(\downarrow i, w) = \{\langle w, |\mathcal{M}|, V^{\mathcal{M}}[i \mapsto \{w\}], R^{\mathcal{M}} \rangle\}, i \in \text{Nom}$$

$$\mathcal{P}_{\text{Nom}}(\mathcal{M}) \iff V^{\mathcal{M}}(i) \text{ is a singleton, } \forall i \in \text{Nom}$$

Defining condition

$$\mathcal{P}_{\oplus}(\mathcal{M}) \iff R^{\mathcal{M}}(\oplus, w) = \{\langle w, |\mathcal{M}|, V^{\mathcal{M}}[\oplus \mapsto V^{\mathcal{M}}(\oplus) \cup \{w\}], R^{\mathcal{M}} \rangle\}$$

$$\mathcal{P}_{\ominus}(\mathcal{M}) \iff R^{\mathcal{M}}(\ominus, w) = \{\langle w, |\mathcal{M}|, V^{\mathcal{M}}[\ominus \mapsto V^{\mathcal{M}}(\ominus) \setminus \{w\}], R^{\mathcal{M}} \rangle\}$$

$$\mathcal{P}_{\emptyset}(\mathcal{M}) \iff R^{\mathcal{M}}(\emptyset, w) = \{\langle w, |\mathcal{M}|, V^{\mathcal{M}}[\emptyset \mapsto \emptyset], R^{\mathcal{M}} \rangle\}$$

## Some initial results using the coinductive framework

- The basic modal logic is complete wrt coinductive models
- *Bisimulations*: one size fits all
- General conditions that guarantee extractability
- Extractability is preserved when new operators are added

## References

- Areces, C. and Gorín, D.. Coinductive models and normal forms for modal logics (or how we learned to stop worrying and love coinduction). Journal of Applied Logic, 8(4):305–318, Elsevier, 2010.



## Logical methods in the generation de referring expressions

$Dom\ M$

- (logical) content determination  $\approx$  description problem

## Motivation: Modal logics in the GRE

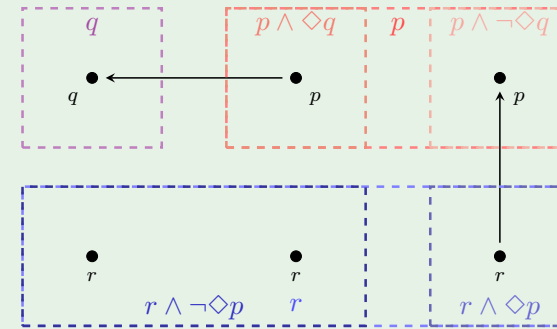
Areces, Koller & Striegnitz (2008)

- We propose modal logics for content determination:
  - $\mathcal{ML}$  – the basic modal language  $(\neg, \wedge, \Diamond)$
  - $\mathcal{EL}$  – the existential positive fragment of  $\mathcal{ML}$   $(\wedge, \Diamond)$
- *Rationale:*
  - Good expressive power
  - Simple surface realization algorithms
  - Relatively low computational complexity for inference tasks
- In particular, we show that:
 

*“The modal description problem needs polynomial time”*

## The modal description problem in polynomial time

A variation of Tarjan's bisimulation contraction algorithm

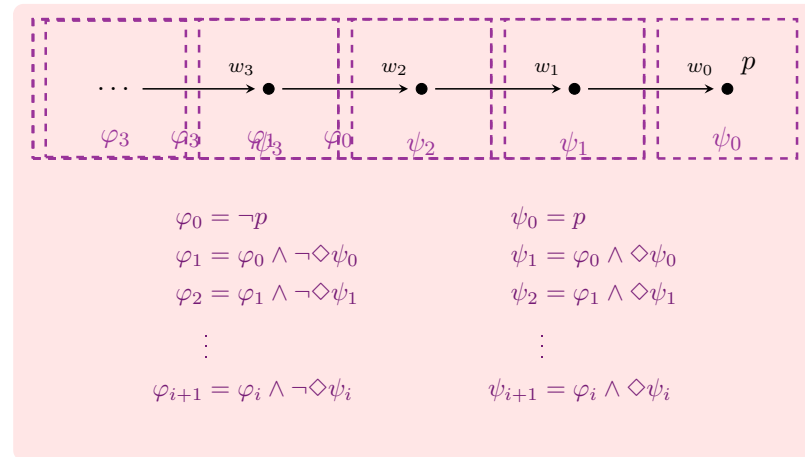


- Tarjan's algorithm runs in polynomial time
- Hence, the modal description problem is polynomial
- But this is **assuming that  $\wedge$  takes constant time!**

## The modal description problem in polynomial time for DAG representation!

- This algorithm produces a formula represented as a DAG
- The size of the DAG is polynomial in the size of the model
- Surface realization step doesn't exploit DAG representation
  - Most probably can't be done anyway
- Is the *tree* representation of this formula also polynomial?
- If not, “modal content determination” can't be said to take polynomial time

## The modal description problem in polynomial time also for tree representation?



- Each  $\psi_i$  is description for  $w_i$  with size exponential in  $i$
- Observe that  $w_i$  admits a linear description:  $\underbrace{\Diamond \Diamond \dots \Diamond}_i p$

## Where do we go from here?

- The example shows that this algorithm is not polynomial
- Can we *fix* it?
- Can we find *another* one that is indeed polynomial?
- We show that **no such algorithm exists!**

## Bounds for the separation / description problems

Basic modal language  $\mathcal{ML}$

### Theorem (Lower bound)

*Any upper bound for the size of a solution for the separation or description problem for  $\mathcal{ML}$  is at least exponential.*

### Corollary

No polynomial time algorithm exists that solves the description or separation problem returning the formula as a tree.

### Theorem (Upper bound)

*If  $\varphi \in \mathcal{ML}$  is a minimum description for  $v$  in  $\mathcal{M} = \langle W, R, V \rangle$ , then  $|\varphi| \in O(2^{\frac{1}{2}|W|^2} \cdot |V|)$ .*