Modal Logics as Fragments of Classical Logic

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What we want to cover

- ► Kripke models vs. first-order models
- ► Translations into FOL
- ► Transfer results
- ► Optimize Translations
- Beyond FOL

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Relevant Bibliography

- ► Chapter 2 of "Modal Logic," Blackburn, de Rijke & Venema. Look for the section 'Standard Translation' (Seccion 2.4).
- ► "Tree-Based Heuristics in Modal Theorem Proving," Areces, Gennari, Heguiabehere and de Rijke.
- ▶ "Unsorted Functional Translations," Areces and Gorín.

Kripke models vs. First-order models

Kripke models

- ightharpoonup A non-empy domain W
- ▶ One or more $R_i \subseteq W \times W$
- ► A valuation function $V : PROP \rightarrow 2^W$

First-order model

- ► A non-empy domain \mathcal{D}
- ► For each predicate *P* of arity *n*, a

$$P^{\mathcal{I}} \subseteq \underbrace{\mathcal{D} \times \ldots \times \mathcal{D}}_{n}$$

► It is easy to see that there is a one-to-one correspondence between the two.

Model correspondence

► Formally, a Kripke model

$$\mathcal{M} = \langle W, \{R_i\}_{i \in \text{MOD}}, V \rangle$$

defined over the signature $\mathcal{S} = \langle PROP, MOD \rangle$ corresponds to a first-oder model

$$\mathcal{I}^{\mathcal{M}} = \langle W, \cdot^{\mathcal{I}^{\mathcal{M}}}
angle$$

over the (first-order) signature $S' = \{P_i \mid i \in PROP \cup MOD\}$ (P_i is unary if $i \in PROP$; binary if $i \in MOD$) where

$$P_i^{\mathcal{I}^{\mathcal{M}}} = \left\{ egin{array}{ll} V(i) & ext{si } i \in ext{PROP} \ R_i & ext{si } i \in ext{MOD} \end{array}
ight.$$

 \triangleright S' is call the first-order correspondence language.

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The standard translation

$$\begin{array}{lll} \mathcal{M},w\models p & \text{iff} & w\in V(p) \\ \mathcal{M},w\models \neg\varphi & \text{iff} & \mathcal{M},w\not\models\varphi \\ \mathcal{M},w\models\varphi\wedge\psi & \text{iff} & \mathcal{M},w\models\varphi\ y\ \mathcal{M},w\models\psi \\ \mathcal{M},w\models\langle R\rangle\varphi & \text{iff} & \exists w'\in W\ \text{tq}\ R(w,w')\ y\ \mathcal{M},w'\models\varphi \\ \end{array}$$

$$\begin{array}{lll} \mathsf{ST}_x(p) & \equiv & P_p(x) \\ \mathsf{ST}_x(\neg\varphi) & \equiv & \neg \mathsf{ST}_x(\varphi) \\ \mathsf{ST}_x(\varphi \wedge \psi) & \equiv & \mathsf{ST}_x(\varphi) \wedge \mathsf{ST}_x(\psi) \\ \mathsf{ST}_x(\langle R \rangle \varphi) & \equiv & \exists y. (R(x,y) \wedge \mathsf{ST}_y(\varphi)) \end{array}$$

Formula correspondence

- ► We can also define a correspondence between formulas of the two languages.
- ▶ We can define it as a translation between the two languages.
- ► If the original formula and its translation are equivalent, then the original logic can be expressed by the target logic.

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ST, the standard translation

- ▶ $ST_x(\varphi)$ maps each formula φ , to a formula in FOL with exactly one free variable x
- ► This free variable will be instantiated by the point of evaluation of a modal formula (remember the "internal perspective)

Theorem

For any formula φ in the basic modal logic, any model \mathcal{M} , any w in the domain of \mathcal{M} an any assignment g,

$$\mathcal{M}, w \models \varphi \text{ iff } \mathcal{M}, g[x \mapsto w] \models ST_x(\varphi)$$

Proof.

Easy, by induction on φ .

Formula correspondence. From FOL to modal

- ▶ It is easy to see that ST is injective, but not surjective.
 - ► E.g., notice that each quantifier comes with a guard.
- ► Can we give a similar translation from FOL to the basic modal logic?
 - ► Let's have a look at the semantics

$$\begin{array}{lll} \mathcal{I}, g \models P(x_1, \dots, x_n) & \text{iff} & (g(x_1), \dots, g(x_n)) \in P^{\mathcal{I}} \\ \mathcal{I}, g \models \neg \varphi & \text{iff} & \mathcal{I}, g \not\models \varphi \\ \mathcal{I}, g \models \varphi \wedge \psi & \text{iff} & \mathcal{I}, g \models \varphi \text{ y } \mathcal{I}, g \models \psi \\ \mathcal{I}, g \models \exists x. \varphi & \text{iff} & \text{exists } w \text{ s.t. } \mathcal{I}, g[x \mapsto w] \models \varphi \\ \end{array}$$

- ▶ Looks difficult, but how do we prove there is no translation.
- ▶ We will see how later.

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(What is compactness? ← notice the big parenthesis

Theorem (FOL is Compact)

- a) If $\Gamma \models \varphi$, then for some finite $\Gamma_0 \subseteq \Gamma$, $\Gamma_0 \models \varphi$.
- b) If every finite subset Γ_0 of Γ is satisfiable, then Γ is.
- c) If Γ is unsatisfiable, then some finite $\Gamma_0 \subseteq \Gamma$ is.
 - ► Compactness is nice because it ensures:
 - ► Reasoning in a compact logic always involves a finite number of premises.
 - ▶ It is a tool to prove (non constructive) model existence . . .
 - ▶ ... and non-existence also.

Transference results

- ► The ST let us import results from FOL.
- ▶ We will discuss two examples:
 - 1. Compactness
 - 2. Löwenheim-Skolem

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Compactness in action!

► Consider the following formulas:

$$\begin{aligned} \mathsf{AtLeast}_2 &:= \exists x_1, x_2 \ . \ x_1 \neq x_2 \\ \mathsf{AtLeast}_3 &:= \exists x_1, x_2, x_3 \ . \ x_1 \neq x_2 \land x_1 \neq x_3 \land x_2 \neq x_3 \\ &\vdots \\ \mathsf{AtLeast}_n &:= \exists x_1, \dots, x_n \ . \bigwedge_{i \neq j} x_i \neq x_j \end{aligned}$$

- ▶ How should a model \mathcal{I} be so that $\mathcal{I} \models \mathsf{AtLeast}_n$?
- ▶ And $\mathcal{I} \models \mathsf{AtLeast}_n \land \neg \mathsf{AtLeast}_{n+1}$?

Compactness in action!

Question: Can FOL define finiteness? I.e., is there a formula φ s.t. $\mathcal{I} \models \varphi$ iff \mathcal{I} is a finite model?

- ▶ It if exist, we could just show it explicitly...
- ▶ If it does not exist, how do we prove it?
 - 1. Suppose there is a φ as requested, and let

$$\Gamma := \{\varphi\} \cup \bigcup_{i=2}^{\infty} \{\mathsf{AtLeast}_i\}$$

- 2. Every finite Γ_0 , subset of Γ , is satisfiable...
- 3. By compactness Γ is satisfiable, but it is not.
- 4. The contradiction comes from assuming the existence of φ

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To think about...) \leftarrow and we close the parenthesis!

- ▶ We just show that certain things cannot be expressed in FOL.
- ▶ We could move to higher-order logics...
- ► ... at the price of losing nice meta-logic properties (e.g., compacidad) which makes them hard to use.
- ► Then, what gives?
- ► That's life. Chose your logic.
- ► There will always be compromises between expressivity, good meta-logical properties, easy of use, computational complexity, etc.

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Back to BML: Compactness Transference

Theorem (Compactness for the Basic Modal Logic)

If every finite set of Γ *is satisfiable, then* Γ *is.*

Proof.

1. Define, for each set of formulas Δ ,

$$\mathsf{ST}_x(\Delta) := \{ \mathsf{ST}_x(\varphi) \mid \varphi \in \Delta \}$$

- 2. Let Γ_0 be a finite subset of Γ ; we know that $\mathsf{ST}_x(\Gamma_0)$ is satisfiable iff Γ_0 is
- 3. Then if every finite Γ_0 is satisfiable, every $\mathsf{ST}_x(\Gamma_0)$ is; and by FOL compactness, $\mathsf{ST}_x(\Gamma)$ is satisfiable
- 4. By then Γ is satisfiable.

(Löwenheim-Skolem ← another parenthesis...

Theorem (Löwenheim-Skolem)

If Γ is a satisfiable set of FOL formulas, then Γ is satisfiable in a countable model.

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(Infinite cardinals for dummies)

- ▶ There are as many natural numbers as odd numbers.
- ► There are as many natural numbers as rationals.
- ▶ But there are more real numbers than natural numbers (Cantor diagonal)
- ► I.e., there are "infinites bigger than others" (sometimes it is tricky to order them)
- ▶ If C is a set then, 2^C has always strictly more elements than C. Hence, there are always bigger infinites.

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Löwenheim-Skolem) ← and we close the last parenthesis...

Theorem (Löwenheim-Skolem)

If Γ is a satisfiable set of FOL formulas, then Γ is satisfiable in a countable model.

Corollary:

No formula of FO can define uncountable.

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Modal Löwenheim-Skolem

Theorem (Löwenheim-Skolem for BML)

If Γ is a satisfiable set of BML formulas, then Γ is satisfiable in a countable model.

Proof.

We proceed as with compacity:

- 1. If Γ is satisfiable, then $ST_x(\Gamma)$ is.
- 2. By L\u00fcenheim-Skolem for FOL, there is countable \mathcal{I} and assignment g, s.t. $\mathcal{I}, g \models \mathsf{ST}_x(\Gamma)$
- 3. But then, $\mathcal{I}, g(x) \models \Gamma$

Another application of ST: Theorem proving

- ► A prover is a program that
 - takes an input a formula
 - upon termination, it says if the formula is valid or not
- ► Building provers is difficult
- ▶ Luckily there are good provers for FOL
- ▶ Using ST, we obtain "free" a prover for BML

$$\varphi \Longrightarrow \forall x.\mathsf{ST}_x(\varphi) \Longrightarrow \boxed{\mathsf{FOL}\;\mathsf{prover}} \Longrightarrow \mathsf{Answer}$$

A better ST...

▶ Let us have a closer look at ST

$$\begin{array}{lll} \mathsf{ST}_x(p) & \equiv & P_p(x) \\ \mathsf{ST}_x(\neg\varphi) & \equiv & \neg \mathsf{ST}_x(\varphi) \\ \mathsf{ST}_x(\varphi \wedge \psi) & \equiv & \mathsf{ST}_x(\varphi) \wedge \mathsf{ST}_x(\psi) \\ \mathsf{ST}_x(\langle m \rangle \varphi) & \equiv & \exists y \; . \; P_m(x,y) \wedge \mathsf{ST}_y(\varphi) \end{array}$$

▶ In ST_x , y is a new variable.

$$\begin{array}{lll} \mathsf{ST}_y(\langle m\rangle\varphi) & \equiv & \exists z \, . \, P_m(y,z) \wedge \mathsf{ST}_z(\varphi) \\ \mathsf{ST}_z(\langle m\rangle\varphi) & \equiv & \exists w \, . \, P_m(y,w) \wedge \mathsf{ST}_w(\varphi) \\ & \vdots & & \vdots \end{array}$$

- ▶ But, *x* does not appear in $ST_y(\varphi)$ (neither free nor bound)
- ▶ We could re-use it:

$$\mathsf{ST}_{\mathsf{y}}(\langle m \rangle \varphi) \equiv \exists x . P_m(y, x) \land \mathsf{ST}_x(\varphi)$$

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But first...¿decidability of what?

Definition: Usually, we say that a logic is decidable if the problem of determining the validity of its formulas is decidable. (For FOL, we can interchange validity and satisfiability.)

Theorem

FOL is not decidable.

Proof.

(Idea) Given a Turing machine ${\mathcal T}$, we can write a FOL formula $\varphi_{\mathcal T}$ such that

 $\triangleright \varphi_{\mathcal{T}}$ is satisfiable iff \mathcal{T} terminates on all inputs.

(See, e.g., 'Mathematical Logic', Ebbinghaus, Flum y Thomas)

... Why?

In this way ST uses only two variables. Useful?

- 1. First, it shows there is more than one translation. Some might be better than others.
- 2. More important, the 2-variable translation will let us transfer a decidability (actually complexity) result.

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More transference: Decidability of BML

Theorem

The fragment defined as the set of all formulas of FOL with only two variables (FOL2) is decidable.

Proof.

Leap of faith. The original proof is by Scott, 1962 ('A decision method for validity of sentences in two variables') for FO2 without equality. The result with equality is by Mortimer, 1975 ('On languages with two variables')

Theorem

BML is decidable.

Proof.

Given φ , we use ST using only two variables and use the decision method for FOL2 with $\forall x.ST_x(\varphi)$ as input.

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Decidability and expressive power

▶ We had a pending question:

Is there a translation from FOL into BML?

- ► And now we have the answer: No.
- ▶ If such a translation exists, then FOL would be decidable.
- ► This result uses decidability to meassure expressivity
- ► It is not "constructive" (it does not tell us what it is exactly that which cannot be expressed)
- ► A new question:

Is there a translation from FOL2 into BML?

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Going beyond BML

Example (cont.)

3. $\mathcal{M}, w \models \langle \pi \rangle \varphi$ iff exists v s.t. $(w, v) \in \overline{\pi}$ and $\mathcal{M}, v \models \varphi$

Where

$$\begin{array}{cccc} \overline{a} & := & R_a \\ \overline{\pi_1 \cup \pi_2} & := & \overline{\pi_1} \cup \overline{\pi_2} \\ \overline{\pi_1; \pi_2} & := & \overline{\pi_1} \circ \overline{\pi_2} \\ \overline{\pi^*} & := & \overline{\pi}^* \end{array}$$

► It would be enough to show TR s.t.

$$\mathcal{I}, g \models \mathsf{TR}_{\pi}(x, y) \ \text{sii} \ (g(x), g(y)) \in \overline{\pi}$$

because then

$$\mathsf{ST}_{\mathsf{x}}(\langle \pi \rangle \varphi) := \exists \mathsf{y} . \mathsf{TR}_{\pi}(\mathsf{x}, \mathsf{y}) \wedge \mathsf{ST}_{\mathsf{y}}(\varphi)$$

Going beyond BML

► It is easy to extend ST to other modal logics and obtain similar transference results

Example

1.
$$\mathcal{M}, w \models \mathsf{E}\varphi$$
 iff exists v s.t. $\mathcal{M}, v \models \varphi$

$$\mathsf{ST}_x(\mathsf{E}\varphi) \equiv \exists y.\mathsf{ST}_y(\varphi)$$

$$\mathsf{ST}_y(\mathsf{E}\varphi) \equiv \exists y.\mathsf{ST}_y(\varphi)$$

2.
$$\mathcal{M}, w \models \langle m \rangle^{-1} \varphi$$
 iff exists v s.t. $R_m v w$ y $\mathcal{M}, v \models \varphi$ $\mathsf{ST}_x(\langle m \rangle^{-1} \varphi) \equiv \exists y. R_m(y, x) \land \mathsf{ST}_y(\varphi)$ $\mathsf{ST}_v(\langle m \rangle^{-1} \varphi) \equiv \exists x. R_m(x, y) \land \mathsf{ST}_x(\varphi)$

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Translating PDL relations

$$\mathsf{TR}_a(x,y) := P_a(x,y)$$

$$\mathsf{TR}_{\pi_1 \cup \pi_2}(x, y) := \mathsf{TR}_{\pi_1}(x, y) \vee \mathsf{TR}_{\pi_2}(x, y)$$

$$\mathsf{TR}_{\pi_1:\pi_2}(x,y) := \exists z . \mathsf{TR}_{\pi_1}(x,z) \wedge \mathsf{TR}_{\pi_2}(z,y)$$

$$\mathsf{TR}_{\pi^*}(x, y) := \mathsf{Well}, \text{ not into FOL we wont.}..$$

Transitive closure

• Let Γ be the following (infinite) set of formulas

$$\langle \pi^* \rangle \neg p$$

$$p$$

$$[\pi] p$$

$$[\pi][\pi] p$$

$$[\pi][\pi][\pi] p$$

$$\vdots$$

- ▶ Each finite Γ_0 , subset of Γ , is satisfiable
- ▶ But Γ is not
- ► I.e., PDL is not compact
- ▶ Hence, we won't be able to obtain a translation into FOL.
- ▶ Note: we just discover something concrete that cannot be expressed by FOL: the transitive closure of a relation.

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To close

We saw that...

- ▶ BML is a (proper) fragment of FOL, and other modal logics are
- ► there is always a balance between expressive power, complexity, good behavior, etc.
- ▶ modal logics are not restricted to FOL
 - ▶ (PDL is a decidable fragment of second-order logic.)

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