

Lógicas modales

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1er Cuatrimestre 2017
Córdoba, Argentina

Part I

Memory logics

Changing the model

- The Modal Logic book says

A modal formula is a little automaton standing at some state in a relational structure, and only permitted to explore the structure by making journeys to neighbouring states.

- What about granting our automaton the additional power to **modify the model** during its exploratory trips?
- There may be many ways to modify a model (changing the domain, the edges, the valuation, ...)
- We want to restrict our attention to a specific way of modifying a model: **adding a memory** to the model, and **performing changes** on it

Changing the model

- We are going to add a storage structure to standard Kripke models:

$$\mathcal{M} = (W, (R_r)_{r \in \text{rel}}, V) \quad + \quad \text{USB drive icon}$$

- There are many possible types of structures: a set, a list, a stack, ...
- We want to start with a very simple structure, so we are going to add a set S to the standard Kripke model:

Memory Kripke model

Given a set $S \subseteq W$, a memory Kripke model is

$$\mathcal{M} = (W, (R_r)_{r \in \text{rel}}, V, S)$$

Changing the model

We have to add suitable operators to manipulate the memory

- Since we are using a set S as the container, there are two "natural" operators to use:
 - An operator \oplus to *remember* the current point, storing it in S .
 - An operator \otimes to check membership of the current point, and find out whether it is *known*

Some notation

Given $\mathcal{M} = (W, (R_r)_{r \in \text{rel}}, V, S)$, $w \in W$, we define

$$\mathcal{M}[w] = (W, (R_r)_{r \in \text{rel}}, V, S \cup \{w\})$$

Now, more formally

Semantics of \oplus and \otimes

$$\begin{aligned} \mathcal{M}, w \models \oplus \varphi & \text{ iff } \mathcal{M}[w], w \models \varphi \\ \mathcal{M}, w \models \otimes & \text{ iff } w \in S \end{aligned}$$

Changing the model

Let's see the use of \oplus and \otimes with an example. Suppose we start with the following model:

A model with an initially empty memory



- How can we check whether w_1 has a successor different from itself?

$$\mathcal{M}, w_1 \models \oplus \Diamond \neg \otimes$$

$$\Downarrow$$

$$\mathcal{M}[w_1], w_1 \models \Diamond \neg \otimes$$

$$\Downarrow$$

$$\mathcal{M}[w_1], w_2 \models \neg \otimes \quad \checkmark$$

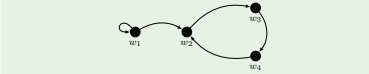
Memory logics

- The idea of using operators that **change** the model is not new
- The family of languages with these characteristics are sometimes called **dynamic logics**
- For example:
 - Dynamic epistemic logics
 - Real time logics
 - Dynamic predicate logic
- Memory logics can be seen as dynamic languages that
 - Do not add any domain-specific behaviour in the evolution of the model
 - Analyze dynamic behaviour from a very simple perspective
 - Can be thought of as a 'weak' version of the standard \downarrow modal binder
- Can be combined with other modal and hybrid operators (Δ , nominals, \otimes , etc.)

Other operators

- We can think in other operators, that *delete* elements from the memory.
- In the previous example, the memory was initially empty, which was quite convenient

A model where every point is memorized



- How can we check whether w_1 has a successor different from itself?
- There doesn't seem to be a way...

Other operators

We can define an operator \oplus (for 'erase') that completely wipes out the memory

Semantics of \oplus

$$\langle M, (R_r)_{r \in \text{rel}}, V, S \rangle, w \models \oplus \varphi \text{ iff } \langle M, (R_r)_{r \in \text{rel}}, V, \emptyset \rangle, w \models \varphi$$

So now, in order to check in \mathcal{M} whether w_1 has a successor different from itself

A model \mathcal{M} , where every point is memorized



we can evaluate

$$\mathcal{M}, w_1 \models \oplus \oplus \oplus \Diamond \neg \oplus \Diamond \Diamond \neg \oplus$$

This formula works independently of the initial state of the memory

Other operators

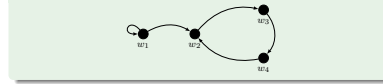
- We can also think in a 'local' version of \oplus , that only deletes the current point of evaluation.
- Let's consider then the operator \oplus (for 'forget')

Semantics of \oplus

$$\langle M, (R_r)_{r \in \text{rel}}, S \rangle, w \models \oplus \varphi \text{ iff } \langle M, (R_r)_{r \in \text{rel}}, S \setminus \{w\} \rangle, w \models \varphi$$

Again, if we want to check in \mathcal{M} whether w_1 has a successor different from itself

A model \mathcal{M} , where every point is memorized



we can evaluate

$$\mathcal{M}, w_1 \models \oplus \Diamond \Diamond \oplus$$

Other ingredients

There are other "dimensions" we can take into consideration:

- Class of models: for example, it is quite natural to consider the class of models whose memory is initially empty
- Memorizing policies: we can try to impose some restrictions on the interplay between memory and modal operators
 - These restrictions are going to help us find decidable fragments
- Other memory operators and containers: are there other memory operators? What happens if we change a set by other type of structure?
 - We can define \oplus , a local version of \oplus
 - We can try using a stack instead of a set as the memory container

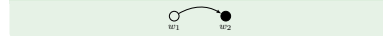
Other ingredients: classes of models

Observe that when the memory of \mathcal{M} is initially empty,

$$\mathcal{M}, w \models \Diamond(r) \oplus \text{ iff } w R_r w$$

But this formula is also true at

A model with a non-empty memory



Taking this into consideration, it is natural to consider memory logics restricted to

$$\mathcal{C}_0 = \{\mathcal{M} \mid \mathcal{M} = \langle W, (R_r)_{r \in \text{rel}}, V, \emptyset \rangle\}$$

the class of models with an empty memory.

Other ingredients: memorizing policies

- Until now memory and modal operators were working 'in parallel'
- Restricting expressivity sometimes can be helpful to reduce computational cost
- We can try to impose some restrictions in the interplay between memory and modal operators

Let's define an operator where $\langle r \rangle$ and \oplus act at the same time

$\langle r \rangle$ and \oplus working together

$$\mathcal{M}, w \models \langle r \rangle \varphi \text{ iff } \exists w' \in W, R_r(w, w') \text{ and } \mathcal{M}[w], w' \models \varphi.$$

We are going to see later that this operator helps us to find decidable memory fragments

Notation

We are going to work with several memory logic fragments

Notational convention

- We call \mathcal{ML} the basic modal logic, and \mathcal{HL} the extension of \mathcal{ML} with nominals
- When we add a set S and the operators \oplus and \oplus we add m as a superscript, e.g. $\mathcal{ML}^m(\dots)$
- We add \emptyset as a subscript when we work with \mathcal{C}_0 (otherwise is the class of all models), e.g. $\mathcal{ML}_{\emptyset}^m(\dots)$
- Then we list the additional operators

For example

- $\mathcal{ML}_{\emptyset}^m(\langle r \rangle, \oplus)$: the modal memory logic with \oplus , \oplus , \oplus and the usual diamond $\langle r \rangle$ over the class \mathcal{C}_0
- $\mathcal{HL}_{\emptyset}^m(\oplus, \langle r \rangle)$: the hybrid memory logic with \oplus , \oplus , $\langle r \rangle$, \oplus over the class of all models

Getting to know a logic

This is a new family of logics, and there are characteristics that are worth investigating

- Expressivity: What can we say with memory logics? Which is the relation between them and other well-known logics?
- Decidability: Which is the computational complexity of the different fragments? How much are memory operators adding to the basic modal logic?
- Interpolation: How they behave in term of Craig interpolation and Beth definability?
- Axiomatization: Do they have sound and complete axiomatic systems?
- Tableau systems: Can we adapt known tableau techniques to produce sound and complete tableau systems? Can we find terminating tableaux for the decidable memory fragments?

Disclaimer: we are not going to see all these topics during this talk

Expressivity results

We compare the expressive power of the different fragments via the existence of *equivalence preserving translations*

\mathcal{L}' is at least as expressive as \mathcal{L} ($\mathcal{L} \leq \mathcal{L}'$) if there is a Tr such that

$$\mathcal{M}, w \models_{\mathcal{L}} \varphi \text{ iff } \mathcal{M}, w \models_{\mathcal{L}'} \text{Tr}(\varphi)$$

Theorem

$$\mathcal{ML}_{\emptyset}^m(\langle r \rangle) < \mathcal{HL}(\downarrow).$$

To see that $\mathcal{ML}_{\emptyset}^m(\langle r \rangle) \leq \mathcal{HL}(\downarrow)$ we define a translation Tr that maps formulas of $\mathcal{ML}_{\emptyset}^m(\langle r \rangle)$ into sentences of $\mathcal{HL}(\downarrow)$.

- We use \downarrow to simulate \oplus .
- We use a finite set N to simulate that \oplus does not distinguish between different memorized states.

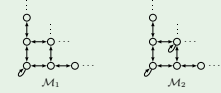
$$\begin{aligned} \text{Tr}_N(\oplus \varphi) &= \downarrow i. \text{Tr}_{N \cup \{i\}}(\varphi) \quad (\text{for } i \text{ a new nominal}) \\ \text{Tr}_N(\oplus) &= \bigvee_{i \in N} i \end{aligned}$$

Expressivity results

How can we see that $\mathcal{ML}_0^m(\langle r \rangle) \neq \mathcal{HL}(\downarrow)$? We need to show that there is *no possible* translation from $\mathcal{HL}(\downarrow)$ to $\mathcal{ML}_0^m(\langle r \rangle)$...

- We developed a notion of *bisimulation* for each fragment. Intuitively, two models are bisimilar for a logic \mathcal{L} when they cannot be distinguished by \mathcal{L} -formulas

\mathcal{M}_1 and \mathcal{M}_2 are $\mathcal{ML}_0^m(\langle r \rangle)$ -bisimilar



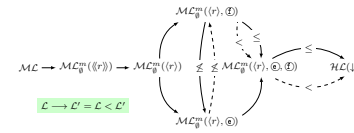
But there is a formula $\varphi \in \mathcal{HL}(\downarrow)$ such that

$$\mathcal{M}_1, w \models_{\mathcal{HL}(\downarrow)} \varphi \text{ and } \mathcal{M}_2, v \not\models_{\mathcal{HL}(\downarrow)} \varphi$$

So a translation from $\mathcal{HL}(\downarrow)$ to $\mathcal{ML}_0^m(\langle r \rangle)$ cannot exist

Expressivity results

We establish in this way an "expressivity map" for many memory logic fragments:



- All the memory logic fragments are between the basic modal logic and the logic $\mathcal{HL}(\downarrow)$ (and therefore below first order logic)

Decidability results

- We have encoded the tiling problem for several memory fragments using a *spy point*: a point that sees every other point in the model



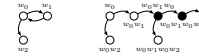
- Most of the memory logic fragments turned out to be undecidable
- We found decidable fragments restricting the interplay between $\langle r \rangle$ and \oplus : we force them to act at the same time

$\langle r \rangle$ and \oplus working together

$$\mathcal{M}, w \models \langle r \rangle \varphi \text{ iff } \exists w' \in W, R_r(w, w') \text{ and } \mathcal{M}[w], w' \models \varphi.$$

Decidability results

- We proved that some fragments are PSPACE-complete showing that they enjoy the bounded tree-model property: every satisfiable formula can be satisfied in a bounded tree
- We showed that there is a procedure to transform an arbitrary model into a tree-like model, preserving equivalence



- We also built a "decidability map" for the different memory fragments

PSPACE-complete	Undecidable
$\mathcal{ML}^m(\langle r \rangle)$	$\mathcal{ML}^m(\langle r \rangle, \oplus, \&)$
$\mathcal{ML}^m(\langle r \rangle, \&)$	$\mathcal{ML}^m(\langle r \rangle, \oplus, \&) + i$
	$\mathcal{ML}^m(\langle r \rangle, \dots)$

Axiomatizations

- We characterized many memory logics fragments in terms of axiomatic systems *à la Hilbert*
- **Nominals** proved to be a very useful device to find sound and complete axiomatizations

Axiomatization for $\mathcal{HL}^m(\&, \langle r \rangle)$

All axioms and rules for $\mathcal{HL}(\&)$
+
 $\vdash \&_i(\&)\varphi \leftrightarrow \varphi[\&/(\& \vee i)]$

- We found sound and complete axiomatizations for all the *hybrid* memory fragments (and establish automatic completeness for pure extensions)
- We could provide axiomatizations for some cases even in the absence of nominals (i.e., $\mathcal{ML}^m(\langle r \rangle)$ and $\mathcal{ML}^m(\langle r \rangle, \&)$)
- The tree-model property was a key feature to use when nominals were not present

Tableau systems

- We presented a sound and complete tableau system for $\mathcal{ML}^m(\langle r \rangle, \&, \oplus)$, $\mathcal{ML}^m(\langle r \rangle, \&, \oplus)$, and its sublanguages
- It is a *prefixed* tableau where we use prefixed formulas with the shape

$$\langle w, R, F \rangle^C : \varphi$$

- w : point of evaluation
- R : set of memorized labels
- F : set of forgotten labels
- C : either $C_\&$ or the class of all models
- φ : current formula

- The rules for propositional and modal operators are standard

Tableau systems

- For example, the rule for \oplus is quite straightforward

$$(\oplus) \frac{(w, R, F)^C : \&\varphi}{(w, R \cup \{w\}, F - \{w\})^C : \varphi}$$

- The rule for $\&$ (and for $\neg\&$) introduces an equivalence class

$$(\&) \frac{\{w, \{v_1, \dots, v_k\}, F\}^C : \&}{w \approx v_1 \mid \dots \mid w \approx v_k \mid \{w, \emptyset, \emptyset\}^C : \&}$$

$$(\neg\&) \frac{(w, R, F)^C : \varphi}{(w', R[w \leftrightarrow w'], F[w \leftrightarrow w'])^C : \varphi}$$

- Since this fragment is undecidable, the tableau is non-terminating
- We also provided a sound, complete and terminating tableau for the decidable fragments

Open questions

- We left some missing links in the expressivity map. We would like to complete it.
- The decidable fragments we found are strictly more expressive than \mathcal{ML} , but still really close to it. Can we find more expressive but still decidable fragments? We have some ideas
 - Concrete domains: storing values, not points
 - Restricted classes of models
 - Weaker containers (or syntactic restrictions)
- Both definability needs further research, we would like some general result
- We want to explore the relation between memory logics and other dynamic logics (DEL is a good candidate). This could also lead to decidable fragments
- Can we find suitable axiomatizations in the absence of nominals. We still don't have one for $\mathcal{ML}^m(\langle r \rangle)$

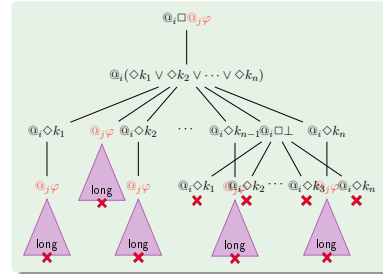
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Part III

Coinduction, extractability, normal forms

Global modalities should be “extracted”



Globality ~ extractability?

Global modalities are extractable from other modalities...

$$\begin{aligned} [r] \Box_i \varphi &\equiv [r] \perp \vee \Box_i \varphi & [r] \Box_i \varphi &\equiv [r] \perp \vee \Box_i \varphi \\ \Box_j \Box_i \varphi &\equiv \Box_j \perp \vee \Box_i \varphi & \Box_j \Box_i \varphi &\equiv \Box_j \perp \vee \Box_i \varphi \\ \Box \Box_i \varphi &\equiv \Box \perp \vee \Box_i \varphi & \Box \Box_i \varphi &\equiv \Box \perp \vee \Box_i \varphi \end{aligned}$$

... but some modalities are more equal than others

$$\begin{aligned} \Box_i \Box_j \varphi &\neq \Box_j \Box_i \varphi \\ \Box \Box_i \varphi &\neq \Box_i \Box \varphi \end{aligned}$$

Coinductive models – a unifying framework

The class of all (rooted) Kripke models with domain W

- $\text{Kripke}_W \stackrel{\text{def}}{=} \text{all the tuples } (W, w_0, V, R) \text{ such that}$
 - $w_0 \in W$
 - $V(p) \subseteq W$
 - $R(r, w) \subseteq W$
- $\langle W, w, V, R \rangle \models [r] \varphi$ iff $\langle W, v, V, R \rangle \models \varphi, \forall v \in R(r, w)$
- Many modal operators can be defined as classes of models

The class of all coinductive models with domain W

- $\text{Mod}_W \stackrel{\text{def}}{=} \text{all the tuples } (W, w_0, V, R) \text{ such that}$
 - $w_0 \in W$
 - $V(p) \subseteq W$
 - $R(r, w) \subseteq \text{Mod}_W \leftarrow \text{coinductive definition!}$
- $\langle W, w, V, R \rangle \models [r] \varphi$ iff $\mathcal{M} \models \varphi, \forall \mathcal{M} \in R(r, w)$
- More modal operators can be defined as classes of models

Defining Conditions

$$\text{Defining condition} \\ \mathcal{P}_A(\mathcal{M}) \iff R^M(A, w) = \{(v, [\mathcal{M}], V^M, R^M) \mid v \in [\mathcal{M}]\}$$

$$\begin{aligned} \text{Defining condition} \\ \mathcal{P}_{\Box_i}(\mathcal{M}) &\iff R^M(\Box_i, w) = \{(v, [\mathcal{M}], V^M, R^M) \mid v \in V(i)\}, i \in \text{Nom} \\ \mathcal{P}_{\Box}(\mathcal{M}) &\iff R^M(\Box, w) = \{(w, [\mathcal{M}], V^M[i \mapsto \{w\}], R^M)\}, i \in \text{Nom} \\ \mathcal{P}_{\text{Nom}}(\mathcal{M}) &\iff V^M(i) \text{ is a singleton, } \forall i \in \text{Nom} \end{aligned}$$

$$\begin{aligned} \text{Defining condition} \\ \mathcal{P}_{\Box}(\mathcal{M}) &\iff R^M(\Box, w) = \{(w, [\mathcal{M}], V^M(\Box) \mapsto V^M(\Box) \cup \{w\}], R^M)\} \\ \mathcal{P}_{\Box}(\mathcal{M}) &\iff R^M(\Box, w) = \{(w, [\mathcal{M}], V^M(\Box) \mapsto V^M(\Box) \setminus \{w\}], R^M)\} \\ \mathcal{P}_{\Box}(\mathcal{M}) &\iff R^M(\Box, w) = \{(w, [\mathcal{M}], V^M(\Box) \mapsto \emptyset), R^M)\} \end{aligned}$$

Some initial results using the coinductive framework

- The basic modal logic is complete wrt coinductive models
- *Bisimulations*: one size fits all
- General conditions that guarantee extractability
- Extractability is preserved when new operators are added

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Part IV

Logical methods in the generation of referring expressions

Separations and descriptions



- Let \mathcal{M} be a Kripke model
- And let $\emptyset \neq C, D \subset \text{Dom } \mathcal{M}$
- For any formula φ , we say that:
 - φ *separates* C and D in \mathcal{M} iff

$$\mathcal{M}, C \models \varphi \text{ and } \mathcal{M}, D \not\models \varphi$$
- Similarly, for $w \in \text{Dom } \mathcal{M}$ we say:
 - φ *describes* w in \mathcal{M} iff

$$\mathcal{M}, w \models \varphi \text{ and } \mathcal{M}, v \not\models \varphi \forall v \neq w$$
- Description is a form of separation
- φ could be of any suitable logic

Separation and description problems

The separation problem

Given a finite model \mathcal{M} and sets $C, D \subset \text{Dom } \mathcal{M}$, find a φ that separates C and D , if possible.

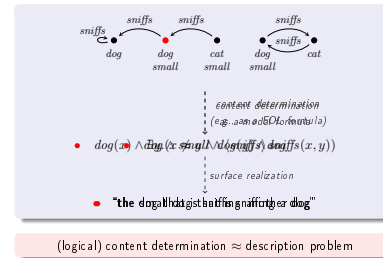
The description problem

Given a finite model \mathcal{M} and a world $w \in \text{Dom } \mathcal{M}$, find a φ that describes w , if possible.

- They can be seen as another kind of inference task
- But they didn't receive much attention so far
- We are interested in their computational properties

Motivation: Generation of Referring Expressions

An application of logics in Natural Language Generation



Motivation: Modal logics in the GRE

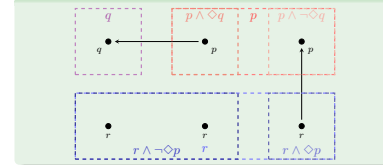
Areces, Koller & Striegnitz (2008)

- We propose modal logics for content determination:
 - \mathcal{ML} – the basic modal language (\neg, \wedge, \diamond)
 - \mathcal{EL} – the existential positive fragment of \mathcal{ML} (\wedge, \diamond)
- Rationale:
 - Good expressive power
 - Simple surface realization algorithms
 - Relatively low computational complexity for inference tasks
- In particular, we show that:

"The modal description problem needs polynomial time"

The modal description problem in polynomial time

A variation of Tarjan's bisimulation contraction algorithm

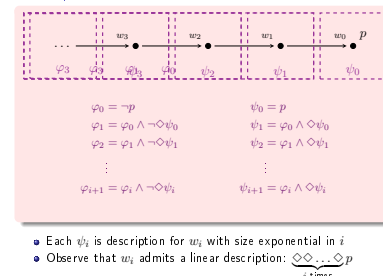


- Tarjan's algorithm runs in polynomial time
- Hence, the modal description problem is polynomial
- But this is assuming that \wedge takes constant time!

The modal description problem in polynomial time for DAG representation!

- This algorithm produces a formula represented as a DAG
- The size of the DAG is polynomial in the size of the model
- Surface realization step doesn't exploit DAG representation
 - Most probably can't be done anyway
- Is the *tree* representation of this formula also polynomial?
- If not, "modal content determination" can't be said to take polynomial time

The modal description problem in polynomial time also for tree representation?



Where do we go from here?

- The example shows that this algorithm is not polynomial
- Can we *fix* it?
- Can we find *another* one that is indeed polynomial?
- We show that **no such algorithm exists!**

Bounds for the separation / description problems

Basic modal language \mathcal{ML}

Theorem (Lower bound)

Any upper bound for the size of a solution for the separation or description problem for \mathcal{ML} is at least exponential.

Corollary

No polynomial time algorithm exists that solves the description or separation problem returning the formula as a tree.

Theorem (Upper bound)

If $\varphi \in \mathcal{ML}$ is a minimum description for v in $\mathcal{M} = \langle W, R, V \rangle$, then $|\varphi| \in O(2^{\frac{1}{2}|W|^2} \cdot |V|)$.