# Hybrid Logics Undecidability and infinite models

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### What we cover in this lecture

- ► Today we will see some examples of modal logics which are undecidable.
- ▶ We will show some techniques used to prove undecidability, and other related properties.

- ▶ We already discussed it would be interesting to have dynamic naming, or "variables" in addition to nominals.
- ▶ Suposse we can create names "on the fly". Introduce the  $\downarrow x$ , that names the current state x.
- ▶  $\downarrow x$  names the current evaluation point, and let us refer to it in the rest of the formula. E.g.,  $\downarrow x. \diamondsuit x$  characterizes reflexive points.

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To the signature of the basic modal logic add an infinite enumerable set of variables VAR.

Syntax of  $\mathcal{HL}(\downarrow)$ 

$$\varphi ::= x \mid p \mid \neg \varphi \mid \varphi \wedge \psi \mid \langle r \rangle \varphi \mid \downarrow x. \varphi$$

where  $p \in PROP$ ,  $r \in REL$ ,  $x \in VAR$ .

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▶ Given a model  $\mathcal{M} = \langle W, \{R_i\}, V \rangle$  and an assignament g define:

### $\mathcal{HL}(\downarrow)$ Semantics:

$$\mathcal{M}, g, w \models x$$
 iff  $g(x) = w$   
 $\mathcal{M}, g, w \models \downarrow x. \varphi$  iff  $\mathcal{M}, g_w^x, w \models \varphi$  where  $g_w^x$  is identical to  $g$  except  $g_w^x(x) = w$ .

- We saw that the basic modal logic (and other extensions) have the finite model property
- ► This is useful for proving decidability (knowing also a bound for the model size)
- ▶ We will see that  $\mathcal{HL}(\downarrow)$  is able to force an infinite model
- ▶ By itself, this does not prove undecidability, but it paves the way

- ▶ Write a formula which says that there is a non empty set *B* whose elements constitute a strict partial order. That is:
  - ► Irreflexive
  - ► Transitive
- And where every element has a successor

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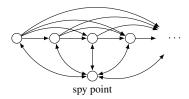
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Each s-successor has an edge towards s (Back)  $\downarrow s.([r] \neg s \land \langle r \rangle \top \land [r] \langle r \rangle s)$ 

Each *s*-successor has an edge towards *s* (*Back*)  $\downarrow s.([r] \neg s \land \langle r \rangle \top \land [r] \langle r \rangle s)$ 

The s-successors in two steps are s-successors in one step

$$(Spy) \qquad \downarrow s.([r][r](\neg s \to (\downarrow x.\langle r \rangle (s \land \langle r \rangle x))))$$

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Let  $\varphi$  be the formula  $Back \wedge Spy \wedge Irr \wedge Succ \wedge Tran$ 

#### Theorem

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We have to check also that  $\varphi$  does have models.

#### Theorem

There exists  $\mathcal{M}, g, w$  s.t.  $\mathcal{M}, g, w \models \varphi$ .

**Proof.** Let *B* be an infinite set of elements and *w* an element such that  $w \notin B$ . Let *R* be the smallest relation such that

- R defines an strict partial order over B
- ▶ wRb and bRw for every element  $b \in B$

$$\mathcal{M} = \langle B \cup \{w\}, R, V \rangle$$
 verifies  $\mathcal{M}, g, w \models \varphi$  (for any V and g).

### Undecidability

- ▶ How do we prove that a logic is undecidable?
- ▶ If we want to prove it in a direct way, we must write a formula that codifies arbitrary executions in a Turing machine
- ► The tiling problem, which has been proved to be undecidable, will be useful for the modal case

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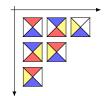
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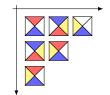


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- ▶ The tiling problem in  $\mathbb{N} \times \mathbb{N}$  is known to be undecidable
- ▶ Given a set of types of tiles  $\mathcal{T}$ , we want to write a formula  $\varphi_{\mathcal{T}}$  such that  $\varphi_{\mathcal{T}}$  is satisfiable iff there exists a tiling for  $\mathcal{T}$

▶ We will use again a spy point



► (Notice, codifying the tiling problem does not imply forcing an infinite model, why?)

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- Suppose that we also have a modality  $\langle o \rangle$  that we use to move from the spy point into every tile
- And we have as well modalities  $\langle u \rangle$  and  $\langle r \rangle$  in order to move up from a tile and to the right of a tile respectively.



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Finally, there is a tile in each point of the grid and all the colors coincide:

Each point has a single type of tile (Unique) 
$$[o] \left( \bigvee_{1 \leq i \leq n} t_i \wedge \bigwedge_{1 \leq i < j \leq n} (t_i \rightarrow \neg t_j) \right)$$

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Each tile has an adjacent tile above which is appropriately colored

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Let

$$\varphi_T = \downarrow s.(Back \land Empty \land Spy \land Grid \land Func \land Conf \land Unique \land Vert \land Horiz)$$

#### Theorem

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Let T be a set of tile types. Then  $\varphi_T$  is satisfiable iff there is a T-tiling of  $\mathbb{N} \times \mathbb{N}$ .

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(⇒) Suppose that  $\mathcal{M}, w \models \varphi_T$ . By construction,  $\mathcal{M}$  represents a tiling in  $\mathbb{N} \times \mathbb{N}$ .

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- (⇐) Suppose that  $f: \mathbb{N} \times \mathbb{N} \to T$  is a tiling in  $\mathbb{N} \times \mathbb{N}$ . We define the model  $\mathcal{M} = \langle W, \{R_o, R_u, R_r\}, V \rangle$ :
  - $W = \mathbb{N} \times \mathbb{N} \cup \{w\}$
  - $ightharpoonup R_o = \{(w, v), (v, w) \mid v \in \mathbb{N} \times \mathbb{N}\}$
  - ►  $R_u = \{(x, y), (x, y + 1) \mid x, y \in \mathbb{N}\}$
  - ►  $R_r = \{(x, y), (x + 1, y) \mid x, y \in \mathbb{N}\}$
  - $V(t_i) = \{x \mid x \in \mathbb{N} \times \mathbb{N}, f(x) = T_i\}$

It is not hard to see that  $\mathcal{M}, w \models \varphi_T$ 

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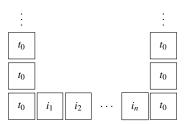
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  - ► The "two person corridor tiling" is EXPTIME-complete

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- ► The game starts with the referee putting tiles as follows



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  - ▶ Otherwise (if no player can make a valid move,  $t_{s+1}$  is not in the column 1, or the game goes on infinitely) Duplicator wins
- ► The problem of detecting if Spoiler has a winning strategy is known to be EXPTIME-complete.

- Using the "two person corridor tiling" one can prove that PDL is EXPTIME-hard, codifying the tree of possible moves between Spoiler y Duplicator.
- Also, it can be used to prove that K + A is EXPTIME-hard.