Modal Logics as Fragments of Classical Logic

Carlos Areces carlos.areces@gmail.com

Spring Term 2018 Stanford

What we want to cover

- Kripke models vs. first-order models
- ► Translations into FOL
- Transfer results
- Optimize Translations
- Beyond FOL

Relevant Bibliography

- ► Chapter 2 of "Modal Logic," Blackburn, de Rijke & Venema. Look for the section 'Standard Translation' (Seccion 2.4).
- "Tree-Based Heuristics in Modal Theorem Proving," Areces, Gennari, Heguiabehere and de Rijke.
- "Unsorted Functional Translations," Areces and Gorín.

Kripke models

First-order model

Kripke models

► A non-empy domain *W*

First-order model

ightharpoonup A non-empy domain \mathcal{D}

Kripke models

- ightharpoonup A non-empy domain W
- ▶ One or more $R_i \subseteq W \times W$

First-order model

- ▶ A non-empy domain \mathcal{D}
- ▶ For each predicate *P* of arity *n*, a

$$P^{\mathcal{I}} \subseteq \underbrace{\mathcal{D} \times \ldots \times \mathcal{D}}_{n}$$

Kripke models

- ► A non-empy domain *W*
- ▶ One or more $R_i \subseteq W \times W$
- A valuation function $V: PROP \rightarrow 2^W$

First-order model

- ightharpoonup A non-empy domain \mathcal{D}
- ► For each predicate *P* of arity *n*, a

$$P^{\mathcal{I}} \subseteq \underbrace{\mathcal{D} \times \ldots \times \mathcal{D}}_{n}$$

Kripke models

- ► A non-empy domain *W*
- ▶ One or more $R_i \subseteq W \times W$
- A valuation function $V \cdot PROP \rightarrow 2^W$

First-order model

- ightharpoonup A non-empy domain \mathcal{D}
- ▶ For each predicate *P* of arity *n*, a

$$P^{\mathcal{I}} \subseteq \underbrace{\mathcal{D} \times \ldots \times \mathcal{D}}_{n}$$

► It is easy to see that there is a one-to-one correspondence between the two.

Model correspondence

► Formally, a Kripke model

$$\mathcal{M} = \langle W, \{R_i\}_{i \in MOD}, V \rangle$$

defined over the signature $S = \langle PROP, MOD \rangle$ corresponds to a first-oder model

$$\mathcal{I}^{\mathcal{M}} = \langle W, \cdot^{\mathcal{I}^{\mathcal{M}}} \rangle$$

over the (first-order) signature $S' = \{P_i \mid i \in PROP \cup MOD\}$ (P_i is unary if $i \in PROP$; binary if $i \in MOD$) where

$$P_i^{\mathcal{I}^{\mathcal{M}}} = \left\{ egin{array}{ll} V(i) & ext{si } i \in ext{PROP} \\ R_i & ext{si } i \in ext{MOD} \end{array}
ight.$$

 \triangleright S' is call the first-order correspondence language.

Formula correspondence

▶ We can also define a correspondence between formulas of the two languages.

Formula correspondence

- We can also define a correspondence between formulas of the two languages.
- ▶ We can define it as a translation between the two languages.

Formula correspondence

- We can also define a correspondence between formulas of the two languages.
- ▶ We can define it as a translation between the two languages.
- ▶ If the original formula and its translation are equivalent, then the original logic can be expressed by the target logic.

$$\mathcal{M}, w \models p \qquad \text{iff} \qquad w \in V(p)$$

$$\mathcal{M}, w \models \neg \varphi \qquad \text{iff} \qquad \mathcal{M}, w \not\models \varphi$$

$$\mathcal{M}, w \models \varphi \land \psi \qquad \text{iff} \qquad \mathcal{M}, w \models \varphi \text{ and } \mathcal{M}, w \models \psi$$

$$\mathcal{M}, w \models \langle m \rangle \varphi \qquad \text{iff} \qquad \text{exists } v \text{ s.t. } R_m w v \text{ and } \mathcal{M}, v \models \varphi$$

$$\mathcal{M}, w \models p \qquad \text{iff} \qquad w \in V(p)$$

$$\mathcal{M}, w \models \neg \varphi \qquad \text{iff} \qquad \mathcal{M}, w \not\models \varphi$$

$$\mathcal{M}, w \models \varphi \land \psi \qquad \text{iff} \qquad \mathcal{M}, w \models \varphi \text{ and } \mathcal{M}, w \models \psi$$

$$\mathcal{M}, w \models \langle m \rangle \varphi \qquad \text{iff} \qquad \text{exists } v \text{ s.t. } R_m w v \text{ and } \mathcal{M}, v \models \varphi$$

$$\mathcal{M}, w \models p & \text{iff} \quad w \in V(p) \\
\mathcal{M}, w \models \neg \varphi & \text{iff} \quad \mathcal{M}, w \not\models \varphi \\
\mathcal{M}, w \models \varphi \land \psi & \text{iff} \quad \mathcal{M}, w \models \varphi \text{ and } \mathcal{M}, w \models \psi \\
\mathcal{M}, w \models \langle m \rangle \varphi & \text{iff} \quad \exists v . R_m w v \land \mathcal{M}, v \models \varphi$$

$$\mathcal{M}, w \models p & \text{iff} \quad w \in V(p) \\
\mathcal{M}, w \models \neg \varphi & \text{iff} \quad \mathcal{M}, w \not\models \varphi \\
\mathcal{M}, w \models \varphi \land \psi & \text{iff} \quad \mathcal{M}, w \models \varphi \land \mathcal{M}, w \models \psi \\
\mathcal{M}, w \models \langle m \rangle \varphi & \text{iff} \quad \exists v . R_m w v \land \mathcal{M}, v \models \varphi$$

$$\mathcal{M}, w \models p & \text{iff} \quad w \in V(p) \\
\mathcal{M}, w \models \neg \varphi & \text{iff} \quad \neg \mathcal{M}, w \models \varphi \\
\mathcal{M}, w \models \varphi \land \psi & \text{iff} \quad \mathcal{M}, w \models \varphi \land \mathcal{M}, w \models \psi \\
\mathcal{M}, w \models \langle m \rangle \varphi & \text{iff} \quad \exists v . R_m w v \land \mathcal{M}, v \models \varphi$$

$$\mathcal{M}, w \models p & \text{iff} \quad w \in V(p) \\
\mathcal{M}, w \models \neg \varphi & \text{iff} \quad \neg \mathcal{M}, w \models \varphi \\
\mathcal{M}, w \models \varphi \land \psi & \text{iff} \quad \mathcal{M}, w \models \varphi \land \mathcal{M}, w \models \psi \\
\mathcal{M}, w \models \langle m \rangle \varphi & \text{iff} \quad \exists v . R_m w v \land \mathcal{M}, v \models \varphi$$

- 1. Rewrite "english" in "logic"...
- 2. Remember the equivalence between models ...

$$\mathcal{M}, w \models p & \text{iff} \quad w \in V(p) \\
\mathcal{M}, w \models \neg \varphi & \text{iff} \quad \neg \mathcal{M}, w \models \varphi \\
\mathcal{M}, w \models \varphi \land \psi & \text{iff} \quad \mathcal{M}, w \models \varphi \land \mathcal{M}, w \models \psi \\
\mathcal{M}, w \models \langle m \rangle \varphi & \text{iff} \quad \exists v . P_m(w, v) \land \mathcal{M}, v \models \varphi$$

- 1. Rewrite "english" in "logic"...
- 2. Remember the equivalence between models . . .

$$\mathcal{M}, w \models p \qquad \text{iff} \quad P_p(w)$$

$$\mathcal{M}, w \models \neg \varphi \qquad \text{iff} \quad \neg \mathcal{M}, w \models \varphi$$

$$\mathcal{M}, w \models \varphi \land \psi \quad \text{iff} \quad \mathcal{M}, w \models \varphi \land \mathcal{M}, w \models \psi$$

$$\mathcal{M}, w \models \langle m \rangle \varphi \quad \text{iff} \quad \exists v . P_m(w, v) \land \mathcal{M}, v \models \varphi$$

- 1. Rewrite "english" in "logic"...
- 2. Remember the equivalence between models . . .

$$\mathcal{M}, w \models p \qquad \text{iff} \quad P_p(w)$$

$$\mathcal{M}, w \models \neg \varphi \qquad \text{iff} \quad \neg \mathcal{M}, w \models \varphi$$

$$\mathcal{M}, w \models \varphi \land \psi \quad \text{iff} \quad \mathcal{M}, w \models \varphi \land \mathcal{M}, w \models \psi$$

$$\mathcal{M}, w \models \langle m \rangle \varphi \quad \text{iff} \quad \exists v . P_m(w, v) \land \mathcal{M}, v \models \varphi$$

- 1. Rewrite "english" in "logic"...
- 2. Remember the equivalence between models ...
- 3. *v* and *w* are elements in the model, we represent them as variables...

$$\mathcal{M}, x \models p & \text{iff} \quad P_p(x) \\
\mathcal{M}, x \models \neg \varphi & \text{iff} \quad \neg \mathcal{M}, x \models \varphi \\
\mathcal{M}, x \models \varphi \land \psi & \text{iff} \quad \mathcal{M}, x \models \varphi \land \mathcal{M}, x \models \psi \\
\mathcal{M}, x \models \langle m \rangle \varphi & \text{iff} \quad \exists y . P_m(x, y) \land \mathcal{M}, y \models \varphi$$

- 1. Rewrite "english" in "logic"...
- 2. Remember the equivalence between models ...
- 3. *v* and *w* are elements in the model, we represent them as variables...

$$\mathcal{M}, x \models p & \text{iff} \quad P_p(x) \\
\mathcal{M}, x \models \neg \varphi & \text{iff} \quad \neg \mathcal{M}, x \models \varphi \\
\mathcal{M}, x \models \varphi \land \psi & \text{iff} \quad \mathcal{M}, x \models \varphi \land \mathcal{M}, x \models \psi \\
\mathcal{M}, x \models \langle m \rangle \varphi & \text{iff} \quad \exists y . P_m(x, y) \land \mathcal{M}, y \models \varphi$$

- 1. Rewrite "english" in "logic"...
- 2. Remember the equivalence between models ...
- 3. *v* and *w* are elements in the model, we represent them as variables...
- 4. Done!

$$\begin{array}{lll} \operatorname{Trad}_x(p) & \equiv & P_p(x) \\ \operatorname{Trad}_x(\neg\varphi) & \equiv & \neg \operatorname{Trad}_x(\varphi) \\ \operatorname{Trad}_x(\varphi \wedge \psi) & \equiv & \operatorname{Trad}_x(\varphi) \wedge \operatorname{Trad}_x(\psi) \\ \operatorname{Trad}_x(\langle m \rangle \varphi) & \equiv & \exists y \; . \; P_m(x, \; y) \wedge \operatorname{Trad}_y(\varphi) \end{array}$$

- 1. Rewrite "english" in "logic"...
- 2. Remember the equivalence between models ...
- 3. *v* and *w* are elements in the model, we represent them as variables...
- 4. Done!
- 5. This is the standard translation into FOL

$$\begin{array}{lll} \mathsf{ST}_{x}(p) & \equiv & P_{p}(x) \\ \mathsf{ST}_{x}(\neg\varphi) & \equiv & \neg \mathsf{ST}_{x}(\varphi) \\ \mathsf{ST}_{x}(\varphi \wedge \psi) & \equiv & \mathsf{ST}_{x}(\varphi) \wedge \mathsf{ST}_{x}(\psi) \\ \mathsf{ST}_{x}(\langle m \rangle \varphi) & \equiv & \exists y \; . \; P_{m}(x, \; y) \wedge \mathsf{ST}_{y}(\varphi) \end{array}$$

- 1. Rewrite "english" in "logic"...
- 2. Remember the equivalence between models ...
- 3. *v* and *w* are elements in the model, we represent them as variables...
- 4. Done!
- 5. This is the standard translation into FOL

- ▶ $ST_x(\varphi)$ maps each formula φ , to a formula in FOL with exactly one free variable x
- ► This free variable will be instantiated by the point of evaluation of a modal formula (remember the "internal perspective)

- ▶ $ST_x(\varphi)$ maps each formula φ , to a formula in FOL with exactly one free variable x
- ► This free variable will be instantiated by the point of evaluation of a modal formula (remember the "internal perspective)

Theorem

For any formula φ in the basic modal logic, any model \mathcal{M} , any w in the domain of \mathcal{M} an any assignment g,

$$\mathcal{M}, w \models \varphi \text{ iff } \mathcal{M}, g[x \mapsto w] \models ST_x(\varphi)$$

- ▶ $ST_x(\varphi)$ maps each formula φ , to a formula in FOL with exactly one free variable x
- ► This free variable will be instantiated by the point of evaluation of a modal formula (remember the "internal perspective)

Theorem

For any formula φ in the basic modal logic, any model \mathcal{M} , any w in the domain of \mathcal{M} an any assignment g,

$$\mathcal{M}, w \models \varphi \text{ iff } \mathcal{M}, g[x \mapsto w] \models ST_x(\varphi)$$

Proof.

Easy, by induction on φ .

- ▶ It is easy to see that ST is injective, but not surjective.
 - ► E.g., notice that each quantifier comes with a guard.

- ▶ It is easy to see that ST is injective, but not surjective.
 - ▶ E.g., notice that each quantifier comes with a guard.
- Can we give a similar translation from FOL to the basic modal logic?

- ▶ It is easy to see that ST is injective, but not surjective.
 - ► E.g., notice that each quantifier comes with a guard.
- Can we give a similar translation from FOL to the basic modal logic?
 - Let's have a look at the semantics

$$\mathcal{I}, g \models P(x_1, \dots, x_n) \quad \text{iff} \quad (g(x_1), \dots, g(x_n)) \in P^{\mathcal{I}} \\
\mathcal{I}, g \models \neg \varphi \quad \qquad \text{iff} \quad \mathcal{I}, g \not\models \varphi \\
\mathcal{I}, g \models \varphi \land \psi \quad \qquad \text{iff} \quad \mathcal{I}, g \models \varphi \text{ y } \mathcal{I}, g \models \psi \\
\mathcal{I}, g \models \exists x. \varphi \quad \qquad \text{iff} \quad \text{exists } w \text{ s.t. } \mathcal{I}, g[x \mapsto w] \models \varphi$$

- ▶ It is easy to see that ST is injective, but not surjective.
 - ► E.g., notice that each quantifier comes with a guard.
- Can we give a similar translation from FOL to the basic modal logic?
 - Let's have a look at the semantics

$$\mathcal{I}, g \models P(x_1, \dots, x_n) & \text{iff} \quad (g(x_1), \dots, g(x_n)) \in P^{\mathcal{I}} \\
\mathcal{I}, g \models \neg \varphi & \text{iff} \quad \mathcal{I}, g \not\models \varphi \\
\mathcal{I}, g \models \varphi \land \psi & \text{iff} \quad \mathcal{I}, g \models \varphi \text{ y } \mathcal{I}, g \models \psi \\
\mathcal{I}, g \models \exists x. \varphi & \text{iff} \quad \text{exists } w \text{ s.t. } \mathcal{I}, g[x \mapsto w] \models \varphi$$

▶ Looks difficult, but how do we prove there is no translation.

- ▶ It is easy to see that ST is injective, but not surjective.
 - ▶ E.g., notice that each quantifier comes with a guard.
- Can we give a similar translation from FOL to the basic modal logic?
 - Let's have a look at the semantics

$$\begin{array}{lll} \mathcal{I}, g \models P(x_1, \dots, x_n) & \text{iff} & (g(x_1), \dots, g(x_n)) \in P^{\mathcal{I}} \\ \mathcal{I}, g \models \neg \varphi & \text{iff} & \mathcal{I}, g \not\models \varphi \\ \mathcal{I}, g \models \varphi \wedge \psi & \text{iff} & \mathcal{I}, g \models \varphi \text{ y } \mathcal{I}, g \models \psi \\ \mathcal{I}, g \models \exists x. \varphi & \text{iff} & \text{exists } w \text{ s.t. } \mathcal{I}, g[x \mapsto w] \models \varphi \end{array}$$

- ▶ Looks difficult, but how do we prove there is no translation.
- ▶ We will see how later.

Transference results

- ▶ The ST let us import results from FOL.
- ▶ We will discuss two examples:
 - 1. Compactness
 - 2. Löwenheim-Skolem

(What is compactness? ← notice the big parenthesis Theorem (FOL is Compact)

a) If $\Gamma \models \varphi$, then for some finite $\Gamma_0 \subseteq \Gamma$, $\Gamma_0 \models \varphi$.

(What is compactness? ← notice the big parenthesis Theorem (FOL is Compact)

- a) If $\Gamma \models \varphi$, then for some finite $\Gamma_0 \subseteq \Gamma$, $\Gamma_0 \models \varphi$.
- b) If every finite subset Γ_0 of Γ is satisfiable, then Γ is.

(What is compactness? ← notice the big parenthesis Theorem (FOL is Compact)

- a) If $\Gamma \models \varphi$, then for some finite $\Gamma_0 \subseteq \Gamma$, $\Gamma_0 \models \varphi$.
- b) If every finite subset Γ_0 of Γ is satisfiable, then Γ is.
- c) If Γ is unsatisfiable, then some finite $\Gamma_0 \subseteq \Gamma$ is.

Theorem (FOL is Compact)

- a) If $\Gamma \models \varphi$, then for some finite $\Gamma_0 \subseteq \Gamma$, $\Gamma_0 \models \varphi$.
- b) If every finite subset Γ_0 of Γ is satisfiable, then Γ is.
- c) If Γ is unsatisfiable, then some finite $\Gamma_0 \subseteq \Gamma$ is.
 - ► Compactness is nice because it ensures:
 - Reasoning in a compact logic always involves a finite number of premises.
 - ▶ It is a tool to prove (non constructive) model existence ...
 - ... and non-existence also.

Theorem (FOL is Compact)

- a) If $\Gamma \models \varphi$, then for some finite $\Gamma_0 \subseteq \Gamma$, $\Gamma_0 \models \varphi$.
- b) If every finite subset Γ_0 of Γ is satisfiable, then Γ is.
- c) If Γ is unsatisfiable, then some finite $\Gamma_0 \subseteq \Gamma$ is.

Proof.

▶ a), b) y c) are equivalent (¡Exercise!)

Theorem (FOL is Compact)

- a) If $\Gamma \models \varphi$, then for some finite $\Gamma_0 \subseteq \Gamma$, $\Gamma_0 \models \varphi$.
- b) If every finite subset Γ_0 of Γ is satisfiable, then Γ is.
- c) If Γ is unsatisfiable, then some finite $\Gamma_0 \subseteq \Gamma$ is.

- ► a), b) y c) are equivalent (¡Exercise!)
- ► "Proof" of a) (assuming completeness):

- Theorem (FOL is Compact)
- a) If $\Gamma \models \varphi$, then for some finite $\Gamma_0 \subseteq \Gamma$, $\Gamma_0 \models \varphi$.
- b) If every finite subset Γ_0 of Γ is satisfiable, then Γ is.
- c) If Γ is unsatisfiable, then some finite $\Gamma_0 \subseteq \Gamma$ is.

- ► a), b) y c) are equivalent (¡Exercise!)
- ► "Proof" of a) (assuming completeness):
 - 1. $\Gamma \models \varphi$ then $\Gamma \vdash \varphi$ (strong completeness)

(What is compactness? ← notice the big parenthesis Theorem (FOL is Compact)

- a) If $\Gamma \models \varphi$, then for some finite $\Gamma_0 \subseteq \Gamma$, $\Gamma_0 \models \varphi$.
- b) If every finite subset Γ_0 of Γ is satisfiable, then Γ is.
- c) If Γ is unsatisfiable, then some finite $\Gamma_0 \subseteq \Gamma$ is.

- ► a), b) y c) are equivalent (¡Exercise!)
- ► "Proof" of a) (assuming completeness):
 - 1. $\Gamma \models \varphi$ then $\Gamma \vdash \varphi$ (strong completeness)
 - 2. But any proof of $\Gamma \vdash \varphi$ (by definition) is finite

Theorem (FOL is Compact)

- a) If $\Gamma \models \varphi$, then for some finite $\Gamma_0 \subseteq \Gamma$, $\Gamma_0 \models \varphi$.
- b) If every finite subset Γ_0 of Γ is satisfiable, then Γ is.
- c) If Γ is unsatisfiable, then some finite $\Gamma_0 \subseteq \Gamma$ is.

- ▶ a), b) y c) are equivalent (¡Exercise!)
- ► "Proof" of a) (assuming completeness):
 - 1. $\Gamma \models \varphi$ then $\Gamma \vdash \varphi$ (strong completeness)
 - 2. But any proof of $\Gamma \vdash \varphi$ (by definition) is finite
 - 3. Hence, only a finite set of formulas (Γ_0) from Γ appears in the proof

Theorem (FOL is Compact)

- a) If $\Gamma \models \varphi$, then for some finite $\Gamma_0 \subseteq \Gamma$, $\Gamma_0 \models \varphi$.
- b) If every finite subset Γ_0 of Γ is satisfiable, then Γ is.
- c) If Γ is unsatisfiable, then some finite $\Gamma_0 \subseteq \Gamma$ is.

- ▶ a), b) y c) are equivalent (¡Exercise!)
- ► "Proof" of a) (assuming completeness):
 - 1. $\Gamma \models \varphi$ then $\Gamma \vdash \varphi$ (strong completeness)
 - 2. But any proof of $\Gamma \vdash \varphi$ (by definition) is finite
 - 3. Hence, only a finite set of formulas (Γ_0) from Γ appears in the proof
 - 4. Hence $\Gamma_0 \vdash \varphi$ and $\Gamma_0 \models \varphi$

Theorem (FOL is Compact)

- a) If $\Gamma \models \varphi$, then for some finite $\Gamma_0 \subseteq \Gamma$, $\Gamma_0 \models \varphi$.
- b) If every finite subset Γ_0 of Γ is satisfiable, then Γ is.
- c) If Γ is unsatisfiable, then some finite $\Gamma_0 \subseteq \Gamma$ is.

- ▶ a), b) y c) are equivalent (¡Exercise!)
- ► "Proof" of a) (assuming completeness):
 - 1. $\Gamma \models \varphi$ then $\Gamma \vdash \varphi$ (strong completeness)
 - 2. But any proof of $\Gamma \vdash \varphi$ (by definition) is finite
 - 3. Hence, only a finite set of formulas (Γ_0) from Γ appears in the proof
 - 4. Hence $\Gamma_0 \vdash \varphi$ and $\Gamma_0 \models \varphi$
- ▶ Of course, proving strong completeness is the hard part.

Consider the following formulas:

$$\begin{aligned} \mathsf{AtLeast}_2 &:= \exists x_1, x_2 \,.\, x_1 \neq x_2 \\ \mathsf{AtLeast}_3 &:= \exists x_1, x_2, x_3 \,.\, x_1 \neq x_2 \land x_1 \neq x_3 \land x_2 \neq x_3 \\ &\vdots \\ \mathsf{AtLeast}_n &:= \exists x_1, \dots, x_n \,.\, \bigwedge_{i \neq i} x_i \neq x_j \end{aligned}$$

▶ How should a model \mathcal{I} be so that $\mathcal{I} \models \mathsf{AtLeast}_n$?

Consider the following formulas:

$$\begin{aligned} \mathsf{AtLeast}_2 &:= \exists x_1, x_2 \ . \ x_1 \neq x_2 \\ \mathsf{AtLeast}_3 &:= \exists x_1, x_2, x_3 \ . \ x_1 \neq x_2 \land x_1 \neq x_3 \land x_2 \neq x_3 \\ & \vdots \\ \mathsf{AtLeast}_n &:= \exists x_1, \dots, x_n \ . \ \bigwedge_{i \neq j} x_i \neq x_j \end{aligned}$$

- ▶ How should a model \mathcal{I} be so that $\mathcal{I} \models \mathsf{AtLeast}_n$?
- ▶ And $\mathcal{I} \models \mathsf{AtLeast}_n \land \neg \mathsf{AtLeast}_{n+1}$?

Question: Can FOL define finiteness? I.e., is there a formula φ s.t. $\mathcal{I} \models \varphi$ iff \mathcal{I} is a finite model?

Question: Can FOL define finiteness? I.e., is there a formula φ s.t.

 $\mathcal{I} \models \varphi \text{ iff } \mathcal{I} \text{ is a finite model?}$

- ▶ It if exist, we could just show it explicitly...
- ▶ If it does not exist, how do we prove it?

Question: Can FOL define finiteness? I.e., is there a formula φ s.t.

 $\mathcal{I} \models \varphi \text{ iff } \mathcal{I} \text{ is a finite model?}$

- ▶ It if exist, we could just show it explicitly...
- ▶ If it does not exist, how do we prove it?
 - 1. Suppose there is a φ as requested, and let

$$\Gamma := \{\varphi\} \cup \bigcup_{i=2}^{\infty} \{\mathsf{AtLeast}_i\}$$

Question: Can FOL define finiteness? I.e., is there a formula φ s.t.

 $\mathcal{I} \models \varphi \text{ iff } \mathcal{I} \text{ is a finite model?}$

- ▶ It if exist, we could just show it explicitly...
- ▶ If it does not exist, how do we prove it?
 - 1. Suppose there is a φ as requested, and let

$$\Gamma := \{\varphi\} \cup \bigcup_{i=2}^{\infty} \{\mathsf{AtLeast}_i\}$$

2. Every finite Γ_0 , subset of Γ , is satisfiable...

Question: Can FOL define finiteness? I.e., is there a formula φ s.t.

 $\mathcal{I} \models \varphi \text{ iff } \mathcal{I} \text{ is a finite model?}$

- ▶ It if exist, we could just show it explicitly...
- ▶ If it does not exist, how do we prove it?
 - 1. Suppose there is a φ as requested, and let

$$\Gamma := \{\varphi\} \cup \bigcup_{i=2}^{\infty} \{\mathsf{AtLeast}_i\}$$

- 2. Every finite Γ_0 , subset of Γ , is satisfiable...
- 3. By compactness Γ is satisfiable, but it is not.

Question: Can FOL define finiteness? I.e., is there a formula φ s.t.

 $\mathcal{I} \models \varphi \text{ iff } \mathcal{I} \text{ is a finite model?}$

- ▶ It if exist, we could just show it explicitly...
- ▶ If it does not exist, how do we prove it?
 - 1. Suppose there is a φ as requested, and let

$$\Gamma := \{\varphi\} \cup \bigcup_{i=2}^{\infty} \{\mathsf{AtLeast}_i\}$$

- 2. Every finite Γ_0 , subset of Γ , is satisfiable...
- 3. By compactness Γ is satisfiable, but it is not.
- 4. The contradiction comes from assuming the existence of φ

▶ We just show that certain things cannot be expressed in FOL.

- ▶ We just show that certain things cannot be expressed in FOL.
- ▶ We could move to higher-order logics...

- ▶ We just show that certain things cannot be expressed in FOL.
- ▶ We could move to higher-order logics...
- ... at the price of losing nice meta-logic properties (e.g., compacidad) which makes them hard to use.

- ▶ We just show that certain things cannot be expressed in FOL.
- ▶ We could move to higher-order logics...
- ... at the price of losing nice meta-logic properties (e.g., compacidad) which makes them hard to use.
- ► Then, what gives?

- ▶ We just show that certain things cannot be expressed in FOL.
- ▶ We could move to higher-order logics...
- ... at the price of losing nice meta-logic properties (e.g., compacidad) which makes them hard to use.
- ► Then, what gives?
- ► That's life. Chose your logic.

- ▶ We just show that certain things cannot be expressed in FOL.
- ▶ We could move to higher-order logics...
- ... at the price of losing nice meta-logic properties (e.g., compacidad) which makes them hard to use.
- ► Then, what gives?
- ► That's life. Chose your logic.
- ► There will always be compromises between expressivity, good meta-logical properties, easy of use, computational complexity, etc.

Theorem (Compactness for the Basic Modal Logic) *If every finite set of* Γ *is satisfiable, then* Γ *is.*

Theorem (Compactness for the Basic Modal Logic) *If every finite set of* Γ *is satisfiable, then* Γ *is.*

Proof.

1. Define, for each set of formulas Δ ,

$$\mathsf{ST}_{x}(\Delta) := \{\mathsf{ST}_{x}(\varphi) \mid \varphi \in \Delta\}$$

Theorem (Compactness for the Basic Modal Logic) *If every finite set of* Γ *is satisfiable, then* Γ *is.*

Proof.

1. Define, for each set of formulas Δ ,

$$\mathsf{ST}_x(\Delta) := \{\mathsf{ST}_x(\varphi) \mid \varphi \in \Delta\}$$

2. Let Γ_0 be a finite subset of Γ ; we know that $\mathsf{ST}_x(\Gamma_0)$ is satisfiable iff Γ_0 is

Theorem (Compactness for the Basic Modal Logic)

If every finite set of Γ *is satisfiable, then* Γ *is.*

Proof.

1. Define, for each set of formulas Δ ,

$$\mathsf{ST}_x(\Delta) := \{\mathsf{ST}_x(\varphi) \mid \varphi \in \Delta\}$$

- 2. Let Γ_0 be a finite subset of Γ ; we know that $\mathsf{ST}_x(\Gamma_0)$ is satisfiable iff Γ_0 is
- 3. Then if every finite Γ_0 is satisfiable, every $\mathsf{ST}_x(\Gamma_0)$ is; and by FOL compactness, $\mathsf{ST}_x(\Gamma)$ is satisfiable

Theorem (Compactness for the Basic Modal Logic)

If every finite set of Γ *is satisfiable, then* Γ *is.*

Proof.

1. Define, for each set of formulas Δ ,

$$\mathsf{ST}_x(\Delta) := \{\mathsf{ST}_x(\varphi) \mid \varphi \in \Delta\}$$

- 2. Let Γ_0 be a finite subset of Γ ; we know that $\mathsf{ST}_x(\Gamma_0)$ is satisfiable iff Γ_0 is
- 3. Then if every finite Γ_0 is satisfiable, every $\mathsf{ST}_x(\Gamma_0)$ is; and by FOL compactness, $\mathsf{ST}_x(\Gamma)$ is satisfiable
- 4. By then Γ is satisfiable.

(Löwenheim-Skolem \leftarrow another parenthesis...

Theorem (Löwenheim-Skolem)

If Γ is a satisfiable set of FOL formulas, then Γ is satisfiable in a countable model.

(Infinite cardinals for dummies)

- ▶ There are as many natural numbers as odd numbers.
- ► There are as many natural numbers as rationals.
- But there are more real numbers than natural numbers (Cantor diagonal)
- ► I.e., there are "infinites bigger than others" (sometimes it is tricky to order them)
- ▶ If C is a set then, 2^C has always strictly more elements than C.

(Infinite cardinals for dummies)

- ► There are as many natural numbers as odd numbers.
- ▶ There are as many natural numbers as rationals.
- But there are more real numbers than natural numbers (Cantor diagonal)
- ► I.e., there are "infinites bigger than others" (sometimes it is tricky to order them)
- ▶ If C is a set then, 2^C has always strictly more elements than C. Hence, there are always bigger infinites.

$L\ddot{o}wenheim-Skolem) \leftarrow and we close the last parenthesis...$

Theorem (Löwenheim-Skolem)

If Γ is a satisfiable set of FOL formulas, then Γ is satisfiable in a countable model.

$L\ddot{o}wenheim-Skolem) \leftarrow and we close the last parenthesis...$

Theorem (Löwenheim-Skolem)

If Γ is a satisfiable set of FOL formulas, then Γ is satisfiable in a countable model.

Corollary:

No formula of FO can define uncountable.

Modal Löwenheim-Skolem

Theorem (Löwenheim-Skolem for BML)

If Γ is a satisfiable set of BML formulas, then Γ is satisfiable in a countable model.

Modal Löwenheim-Skolem

Theorem (Löwenheim-Skolem for BML)

If Γ is a satisfiable set of BML formulas, then Γ is satisfiable in a countable model.

Proof.

We proceed as with compacity:

- 1. If Γ is satisfiable, then $ST_x(\Gamma)$ is.
- 2. By L\u00fcenheim-Skolem for FOL, there is countable \mathcal{I} and assignment g, s.t. $\mathcal{I}, g \models \mathsf{ST}_x(\Gamma)$
- 3. But then, $\mathcal{I}, g(x) \models \Gamma$

Another application of ST: Theorem proving

- ▶ A prover is a program that
 - takes an input a formula
 - upon termination, it says if the formula is valid or not
- ▶ Building provers is difficult
- ► Luckily there are good provers for FOL
- ▶ Using ST, we obtain "free" a prover for BML

$$\varphi \Longrightarrow \forall x.\mathsf{ST}_x(\varphi) \Longrightarrow \boxed{\mathsf{FOL}\;\mathsf{prover}} \Longrightarrow \mathsf{Answer}$$

A better ST...

Let us have a closer look at ST

$$\begin{array}{lll} \mathsf{ST}_x(p) & \equiv & P_p(x) \\ \mathsf{ST}_x(\neg\varphi) & \equiv & \neg \mathsf{ST}_x(\varphi) \\ \mathsf{ST}_x(\varphi \wedge \psi) & \equiv & \mathsf{ST}_x(\varphi) \wedge \mathsf{ST}_x(\psi) \\ \mathsf{ST}_x(\langle m \rangle \varphi) & \equiv & \exists y \, . \, P_m(x,y) \wedge \mathsf{ST}_y(\varphi) \end{array}$$

▶ In ST_x , y is a new variable.

$$\begin{array}{lcl} \mathsf{ST}_{\mathtt{y}}(\langle m \rangle \varphi) & \equiv & \exists z \; . \; P_{m}(\mathtt{y}, \mathtt{z}) \wedge \mathsf{ST}_{\mathtt{z}}(\varphi) \\ \mathsf{ST}_{\mathtt{z}}(\langle m \rangle \varphi) & \equiv & \exists w \; . \; P_{m}(\mathtt{y}, \mathtt{w}) \wedge \mathsf{ST}_{\mathtt{w}}(\varphi) \\ & \vdots & & \vdots \end{array}$$

A better ST...

Let us have a closer look at ST

$$\begin{array}{lll} \mathsf{ST}_x(p) & \equiv & P_p(x) \\ \mathsf{ST}_x(\neg\varphi) & \equiv & \neg \mathsf{ST}_x(\varphi) \\ \mathsf{ST}_x(\varphi \wedge \psi) & \equiv & \mathsf{ST}_x(\varphi) \wedge \mathsf{ST}_x(\psi) \\ \mathsf{ST}_x(\langle m \rangle \varphi) & \equiv & \exists y \, . \, P_m(x,y) \wedge \mathsf{ST}_y(\varphi) \end{array}$$

▶ In ST_x , y is a new variable.

$$\begin{array}{lcl} \mathsf{ST}_{y}(\langle m\rangle\varphi) & \equiv & \exists z \; . \; P_{m}(y,z) \land \mathsf{ST}_{z}(\varphi) \\ \mathsf{ST}_{z}(\langle m\rangle\varphi) & \equiv & \exists w \; . \; P_{m}(y,w) \land \mathsf{ST}_{w}(\varphi) \\ & \vdots & & \vdots \end{array}$$

▶ But, *x* does not appear in $ST_y(\varphi)$ (neither free nor bound)

A better ST...

Let us have a closer look at ST

$$\begin{array}{lll} \mathsf{ST}_x(p) & \equiv & P_p(x) \\ \mathsf{ST}_x(\neg\varphi) & \equiv & \neg \mathsf{ST}_x(\varphi) \\ \mathsf{ST}_x(\varphi \wedge \psi) & \equiv & \mathsf{ST}_x(\varphi) \wedge \mathsf{ST}_x(\psi) \\ \mathsf{ST}_x(\langle m \rangle \varphi) & \equiv & \exists y \ . \ P_m(x,y) \wedge \mathsf{ST}_y(\varphi) \end{array}$$

▶ In ST_x , y is a new variable.

$$\begin{array}{lcl} \mathsf{ST}_{\mathsf{y}}(\langle m\rangle\varphi) & \equiv & \exists z \; . \; P_m(y,z) \land \mathsf{ST}_z(\varphi) \\ \mathsf{ST}_z(\langle m\rangle\varphi) & \equiv & \exists w \; . \; P_m(y,w) \land \mathsf{ST}_w(\varphi) \\ & \vdots & & \vdots \end{array}$$

- ▶ But, *x* does not appear in $ST_y(\varphi)$ (neither free nor bound)
- ▶ We could re-use it:

$$\mathsf{ST}_{\mathsf{v}}(\langle m \rangle \varphi) \equiv \exists x . P_m(y, x) \land \mathsf{ST}_x(\varphi)$$

... Why?

In this way ST uses only two variables. Useful?

... Why?

In this way ST uses only two variables. Useful?

1. First, it shows there is more than one translation. Some might be better than others.

... Why?

In this way ST uses only two variables. Useful?

- 1. First, it shows there is more than one translation. Some might be better than others.
- 2. More important, the 2-variable translation will let us transfer a decidability (actually complexity) result.

Definition: Usually, we say that a logic is decidable if the problem of determining the validity of its formulas is decidable. (For FOL, we can interchange validity and satisfiability.)

Definition: Usually, we say that a logic is decidable if the problem of determining the validity of its formulas is decidable. (For FOL, we can interchange validity and satisfiability.)

Theorem

FOL is not decidable.

Definition: Usually, we say that a logic is decidable if the problem of determining the validity of its formulas is decidable. (For FOL, we can interchange validity and satisfiability.)

Theorem

FOL is not decidable.

Proof.

(Idea) Given a Turing machine \mathcal{T} , we can write a FOL formula $\varphi_{\mathcal{T}}$ such that

• $\varphi_{\mathcal{T}}$ is satisfiable iff \mathcal{T} terminates on all inputs.

(See, e.g., 'Mathematical Logic', Ebbinghaus, Flum y Thomas)

Definition: Usually, we say that a logic is decidable if the problem of determining the validity of its formulas is decidable. (For FOL, we can interchange validity and satisfiability.)

Theorem

FOL is not decidable.

Definition: Usually, we say that a logic is decidable if the problem of determining the validity of its formulas is decidable. (For FOL, we can interchange validity and satisfiability.)

Theorem

FOL is not decidable.

Just a moment! An the FOL provers?

ightharpoonup Complete axiomatization \Longrightarrow a tool to list all theorems

Definition: Usually, we say that a logic is decidable if the problem of determining the validity of its formulas is decidable. (For FOL, we can interchange validity and satisfiability.)

Theorem

FOL is not decidable.

- ightharpoonup Complete axiomatization \Longrightarrow a tool to list all theorems
- φ is valid \implies eventually φ is listed as a theorem $\sqrt{\ }$

Definition: Usually, we say that a logic is decidable if the problem of determining the validity of its formulas is decidable. (For FOL, we can interchange validity and satisfiability.)

Theorem

FOL is not decidable.

- ightharpoonup Complete axiomatization \Longrightarrow a tool to list all theorems
- φ is valid \Longrightarrow eventually φ is listed as a theorem $\sqrt{\ }$
- φ is a contradiction \Longrightarrow eventually $\neg \varphi$ is listed $\sqrt{\ }$

Definition: Usually, we say that a logic is decidable if the problem of determining the validity of its formulas is decidable. (For FOL, we can interchange validity and satisfiability.)

Theorem

FOL is not decidable.

- ightharpoonup Complete axiomatization \Longrightarrow a tool to list all theorems
- φ is valid \implies eventually φ is listed as a theorem $\sqrt{\ }$
- φ is a contradiction \Longrightarrow eventually $\neg \varphi$ is listed $\sqrt{\ }$
- ightharpoonup Otherwise \Longrightarrow we might have to wait forever \times

Definition: Usually, we say that a logic is decidable if the problem of determining the validity of its formulas is decidable. (For FOL, we can interchange validity and satisfiability.)

Theorem

FOL is not decidable.

- ightharpoonup Complete axiomatization \Longrightarrow a tool to list all theorems
- $\triangleright \varphi$ is valid \implies eventually φ is listed as a theorem $\sqrt{\ }$
- φ is a contradiction \Longrightarrow eventually $\neg \varphi$ is listed $\sqrt{\ }$
- ightharpoonup Otherwise \Longrightarrow we might have to wait forever \times
- ► This kind of problems are called semi-decidible.

Theorem

The fragment defined as the set of all formulas of FOL with only two variables (FOL2) is decidable.

Theorem

The fragment defined as the set of all formulas of FOL with only two variables (FOL2) is decidable.

Proof.

Leap of faith.

Theorem

The fragment defined as the set of all formulas of FOL with only two variables (FOL2) is decidable.

Proof.

Leap of faith. The original proof is by Scott, 1962 ('A decision method for validity of sentences in two variables') for FO2 without equality. The result with equality is by Mortimer, 1975 ('On languages with two variables')

Theorem

The fragment defined as the set of all formulas of FOL with only two variables (FOL2) is decidable.

Proof.

Leap of faith. The original proof is by Scott, 1962 ('A decision method for validity of sentences in two variables') for FO2 without equality. The result with equality is by Mortimer, 1975 ('On languages with two variables')

Theorem

BML is decidable.

Theorem

The fragment defined as the set of all formulas of FOL with only two variables (FOL2) is decidable.

Proof.

Leap of faith. The original proof is by Scott, 1962 ('A decision method for validity of sentences in two variables') for FO2 without equality. The result with equality is by Mortimer, 1975 ('On languages with two variables')

Theorem

BML is decidable.

Proof.

Given φ , we use ST using only two variables and use the decision method for FOL2 with $\forall x.ST_x(\varphi)$ as input.

▶ We had a pending question:

▶ We had a pending question:

Is there a translation from FOL into BML?

▶ And now we have the answer: No.

▶ We had a pending question:

- ▶ And now we have the answer: No.
- ▶ If such a translation exists, then FOL would be decidable.

▶ We had a pending question:

- ▶ And now we have the answer: No.
- ▶ If such a translation exists, then FOL would be decidable.
- ► This result uses decidability to meassure expressivity

▶ We had a pending question:

- ▶ And now we have the answer: No.
- ▶ If such a translation exists, then FOL would be decidable.
- This result uses decidability to meassure expressivity
- ▶ It is not "constructive" (it does not tell us what it is exactly that which cannot be expressed)

▶ We had a pending question:

Is there a translation from FOL into BML?

- ▶ And now we have the answer: No.
- ▶ If such a translation exists, then FOL would be decidable.
- ► This result uses decidability to meassure expressivity
- ▶ It is not "constructive" (it does not tell us what it is exactly that which cannot be expressed)
- ► A new question:

► It is easy to extend ST to other modal logics and obtain similar transference results

1.
$$\mathcal{M}, w \models \mathsf{E}\varphi$$
 iff exists v s.t. $\mathcal{M}, v \models \varphi$

2.
$$\mathcal{M}, w \models \langle m \rangle^{-1} \varphi$$
 iff exists v s.t. $R_m v w$ y $\mathcal{M}, v \models \varphi$

► It is easy to extend ST to other modal logics and obtain similar transference results

1.
$$\mathcal{M}, w \models \mathsf{E}\varphi$$
 iff exists v s.t. $\mathcal{M}, v \models \varphi$
$$\mathsf{ST}_x(\mathsf{E}\varphi) \equiv \exists y. \mathsf{ST}_y(\varphi)$$

2.
$$\mathcal{M}, w \models \langle m \rangle^{-1} \varphi$$
 iff exists v s.t. $R_m v w$ y $\mathcal{M}, v \models \varphi$

► It is easy to extend ST to other modal logics and obtain similar transference results

1.
$$\mathcal{M}, w \models \mathsf{E}\varphi$$
 iff exists v s.t. $\mathcal{M}, v \models \varphi$
$$\mathsf{ST}_x(\mathsf{E}\varphi) \equiv \exists x. \mathsf{ST}_x(\varphi)$$

2.
$$\mathcal{M}, w \models \langle m \rangle^{-1} \varphi$$
 iff exists v s.t. $R_m v w$ y $\mathcal{M}, v \models \varphi$

► It is easy to extend ST to other modal logics and obtain similar transference results

1.
$$\mathcal{M}, w \models \mathsf{E}\varphi$$
 iff exists v s.t. $\mathcal{M}, v \models \varphi$ $\mathsf{ST}_x(\mathsf{E}\varphi) \equiv \exists x.\mathsf{ST}_x(\varphi)$ $\mathsf{ST}_y(\mathsf{E}\varphi) \equiv \exists y.\mathsf{ST}_y(\varphi)$

2.
$$\mathcal{M}, w \models \langle m \rangle^{-1} \varphi$$
 iff exists v s.t. $R_m v w$ y $\mathcal{M}, v \models \varphi$

► It is easy to extend ST to other modal logics and obtain similar transference results

1.
$$\mathcal{M}, w \models \mathsf{E}\varphi$$
 iff exists v s.t. $\mathcal{M}, v \models \varphi$

$$\mathsf{ST}_x(\mathsf{E}\varphi) \equiv \exists x.\mathsf{ST}_x(\varphi)$$

$$\mathsf{ST}_y(\mathsf{E}\varphi) \equiv \exists y.\mathsf{ST}_y(\varphi)$$

2.
$$\mathcal{M}, w \models \langle m \rangle^{-1} \varphi$$
 iff exists v s.t. $R_m v w$ y $\mathcal{M}, v \models \varphi$ $\mathsf{ST}_x(\langle m \rangle^{-1} \varphi) \equiv \exists y. R_m(y, x) \land \mathsf{ST}_y(\varphi)$

► It is easy to extend ST to other modal logics and obtain similar transference results

1.
$$\mathcal{M}, w \models \mathsf{E}\varphi$$
 iff exists v s.t. $\mathcal{M}, v \models \varphi$ $\mathsf{ST}_x(\mathsf{E}\varphi) \equiv \exists x.\mathsf{ST}_x(\varphi)$ $\mathsf{ST}_y(\mathsf{E}\varphi) \equiv \exists y.\mathsf{ST}_y(\varphi)$

2.
$$\mathcal{M}, w \models \langle m \rangle^{-1} \varphi$$
 iff exists v s.t. $R_m v w$ y $\mathcal{M}, v \models \varphi$ $\mathsf{ST}_x(\langle m \rangle^{-1} \varphi) \equiv \exists y. R_m(y, x) \wedge \mathsf{ST}_y(\varphi)$ $\mathsf{ST}_y(\langle m \rangle^{-1} \varphi) \equiv \exists x. R_m(x, y) \wedge \mathsf{ST}_x(\varphi)$

Example (cont.)

3. $\mathcal{M}, w \models \langle \pi \rangle \varphi$ iff exists v s.t. $(w, v) \in \overline{\pi}$ and $\mathcal{M}, v \models \varphi$ Where

$$\begin{array}{cccc} \overline{a} & := & R_a \\ \overline{\pi_1 \cup \pi_2} & := & \overline{\pi_1} \cup \overline{\pi_2} \\ \overline{\pi_1; \underline{\pi_2}} & := & \overline{\pi_1} \circ \overline{\pi_2} \\ \overline{\pi^*} & := & \overline{\pi}^* \end{array}$$

Example (cont.)

3. $\mathcal{M}, w \models \langle \pi \rangle \varphi$ iff exists v s.t. $(w, v) \in \overline{\pi}$ and $\mathcal{M}, v \models \varphi$ Where

$$\begin{array}{cccc} \overline{a} & := & R_a \\ \overline{\pi_1 \cup \pi_2} & := & \overline{\pi_1} \cup \overline{\pi_2} \\ \overline{\pi_1; \underline{\pi_2}} & := & \overline{\pi_1} \circ \overline{\pi_2} \\ \overline{\pi^*} & := & \overline{\pi}^* \end{array}$$

► It would be enough to show TR s.t.

$$\mathcal{I}, g \models \mathsf{TR}_{\pi}(x, y) \text{ sii } (g(x), g(y)) \in \overline{\pi}$$

because then

$$\mathsf{ST}_x(\langle \pi \rangle \varphi) := \exists y \ . \ \mathsf{TR}_\pi(x,y) \land \mathsf{ST}_v(\varphi)$$

Translating PDL relations

$$TR_a(x, y)$$
 := $TR_{\pi_1 \cup \pi_2}(x, y)$:= $TR_{\pi_1; \pi_2}(x, y)$:= $TR_{\pi^*}(x, y)$:=

Translating PDL relations

$$\mathsf{TR}_{a}(x,y) := P_{a}(x,y)$$
 $\mathsf{TR}_{\pi_{1} \cup \pi_{2}}(x,y) :=$
 $\mathsf{TR}_{\pi_{1};\pi_{2}}(x,y) :=$
 $\mathsf{TR}_{\pi^{*}}(x,y) :=$

Translating PDL relations

$$\begin{array}{lll} \mathsf{TR}_{a}(x,y) & := & P_{a}(x,y) \\ \mathsf{TR}_{\pi_{1} \cup \pi_{2}}(x,y) & := & \mathsf{TR}_{\pi_{1}}(x,y) \vee \mathsf{TR}_{\pi_{2}}(x,y) \\ \mathsf{TR}_{\pi_{1};\pi_{2}}(x,y) & := & \\ \mathsf{TR}_{\pi^{*}}(x,y) & := & \end{array}$$

Translating PDL relations

$$\begin{array}{lll} \mathsf{TR}_{a}(x,y) & := & P_{a}(x,y) \\ \mathsf{TR}_{\pi_{1} \cup \pi_{2}}(x,y) & := & \mathsf{TR}_{\pi_{1}}(x,y) \vee \mathsf{TR}_{\pi_{2}}(x,y) \\ \mathsf{TR}_{\pi_{1};\pi_{2}}(x,y) & := & \exists z \, . \, \mathsf{TR}_{\pi_{1}}(x,z) \wedge \mathsf{TR}_{\pi_{2}}(z,y) \\ \mathsf{TR}_{\pi^{*}}(x,y) & := & \end{array}$$

Translating PDL relations

```
\begin{array}{lll} \mathsf{TR}_{a}(x,y) & := & P_{a}(x,y) \\ \mathsf{TR}_{\pi_{1} \cup \pi_{2}}(x,y) & := & \mathsf{TR}_{\pi_{1}}(x,y) \vee \mathsf{TR}_{\pi_{2}}(x,y) \\ \mathsf{TR}_{\pi_{1};\pi_{2}}(x,y) & := & \exists z \, . \, \mathsf{TR}_{\pi_{1}}(x,z) \wedge \mathsf{TR}_{\pi_{2}}(z,y) \\ \mathsf{TR}_{\pi^{*}}(x,y) & := & \mathsf{Well, not into FOL we wont...} \end{array}
```

$$\begin{array}{c} \langle \pi^* \rangle \neg p \\ p \\ [\pi] p \\ [\pi] [\pi] [\pi] p \\ [\pi] [\pi] [\pi] p \\ \vdots \end{array}$$

Let Γ be the following (infinite) set of formulas

$$\langle \pi^* \rangle \neg p \\ p \\ [\pi] p \\ [\pi] [\pi] p \\ [\pi] [\pi] [\pi] p \\ \vdots$$

▶ Each finite Γ_0 , subset of Γ , is satisfiable

$$\langle \pi^* \rangle \neg p \\ p \\ [\pi] p \\ [\pi] [\pi] p \\ [\pi] [\pi] [\pi] p \\ \vdots$$

- ▶ Each finite Γ_0 , subset of Γ , is satisfiable
- ▶ But Γ is not

$$\langle \pi^* \rangle \neg p \\ p \\ [\pi] p \\ [\pi] [\pi] p \\ [\pi] [\pi] [\pi] p \\ \vdots$$

- ▶ Each finite Γ_0 , subset of Γ , is satisfiable
- ▶ But Γ is not
- ▶ I.e., PDL is not compact

$$\langle \pi^* \rangle \neg p \\ p \\ [\pi] p \\ [\pi] [\pi] p \\ [\pi] [\pi] [\pi] p \\ \vdots$$

- ▶ Each finite Γ_0 , subset of Γ , is satisfiable
- But Γ is not
- ▶ I.e., PDL is not compact
- ▶ Hence, we won't be able to obtain a translation into FOL.

$$\langle \pi^* \rangle \neg p$$

$$p$$

$$[\pi] p$$

$$[\pi][\pi] p$$

$$[\pi][\pi][\pi] p$$

$$\vdots$$

- ▶ Each finite Γ_0 , subset of Γ , is satisfiable
- ▶ But Γ is not
- ▶ I.e., PDL is not compact
- ▶ Hence, we won't be able to obtain a translation into FOL.
- ▶ Note: we just discover something concrete that cannot be expressed by FOL: the transitive closure of a relation.

To close

We saw that...

▶ BML is a (proper) fragment of FOL, and other modal logics are too.

To close

We saw that...

- ▶ BML is a (proper) fragment of FOL, and other modal logics are too.
- there is always a balance between expressive power, complexity, good behavior, etc.

To close

We saw that...

- ▶ BML is a (proper) fragment of FOL, and other modal logics are too.
- there is always a balance between expressive power, complexity, good behavior, etc.
- modal logics are not restricted to FOL
 - ▶ (PDL is a decidable fragment of second-order logic.)