

Building Artificial Life and Multi-Agent simulations using the Breve engine

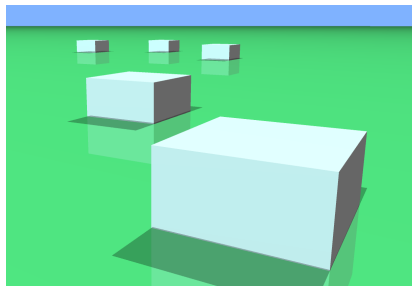
Wouter Bulten, Frank Dorssers & Robert-Jan Drenth

ACAIS: Life, June 6th 2013



Goal of today

Investigating and building multi-agent and artificial life simulations.



Overview

Introducing breve

Past projects

Basis of a simulation

Building a simulation

Adding complexity

What we are going to build



What is breve?

- ▶ Environment designed for simulation of realistic, 3D, multi-agent systems
- ▶ Created by Jon Klein (Hampshire College & Chalmers University)
- ▶ Autonomous agents



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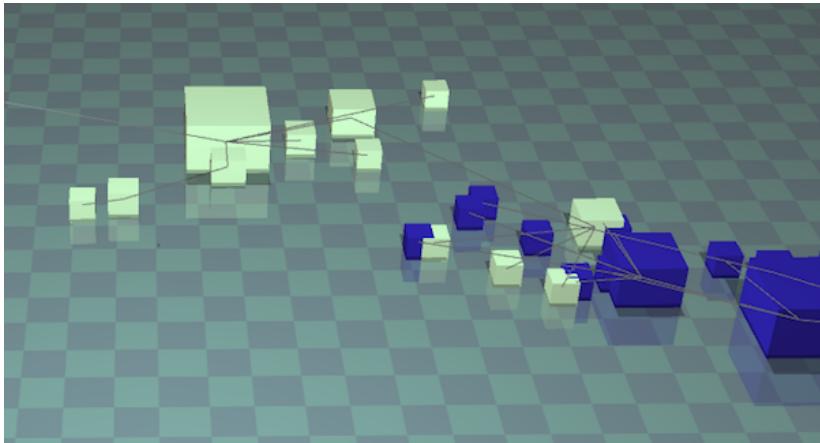
Types of simulation

- ▶ Multi-agent Simulations
- ▶ 3D spatial simulation
- ▶ Physical simulation

Why breve?

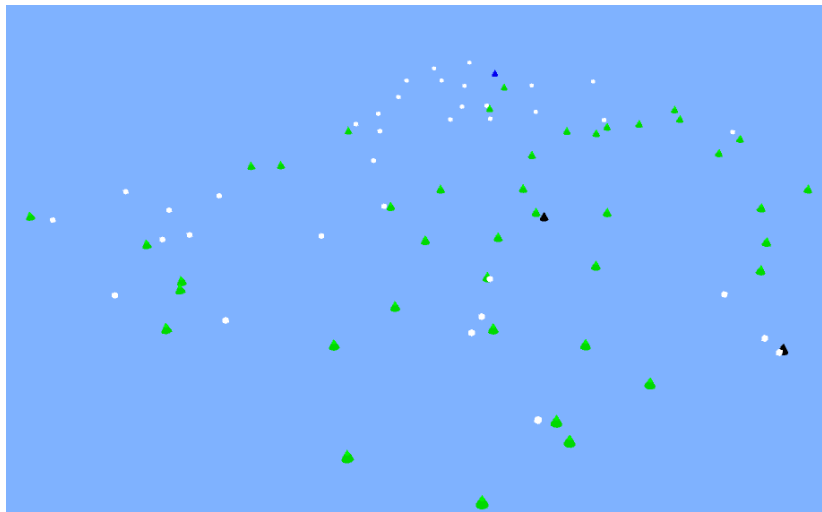
- ▶ Easy way to visualise a simulation (and to disable it)
- ▶ Framework
- ▶ Open Source / Free to use

The evolution of leadership



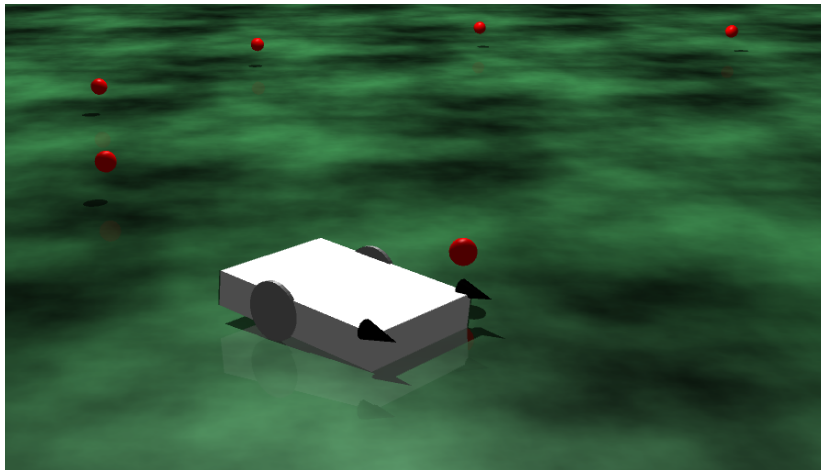
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Punishment Mechanisms and their Effect on Cooperation

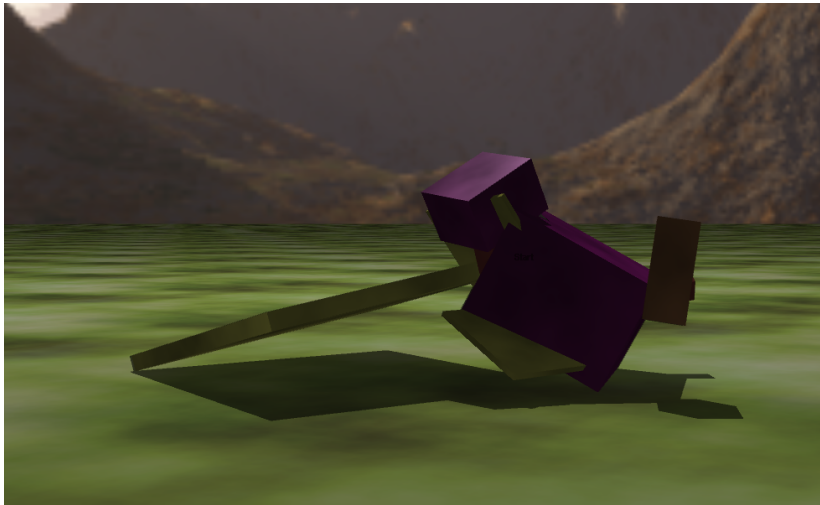


Mike Farjam, Pim Haselager & Ida Sprinkhuizen-Kuyper, BNAIC 2012

Braitenberg

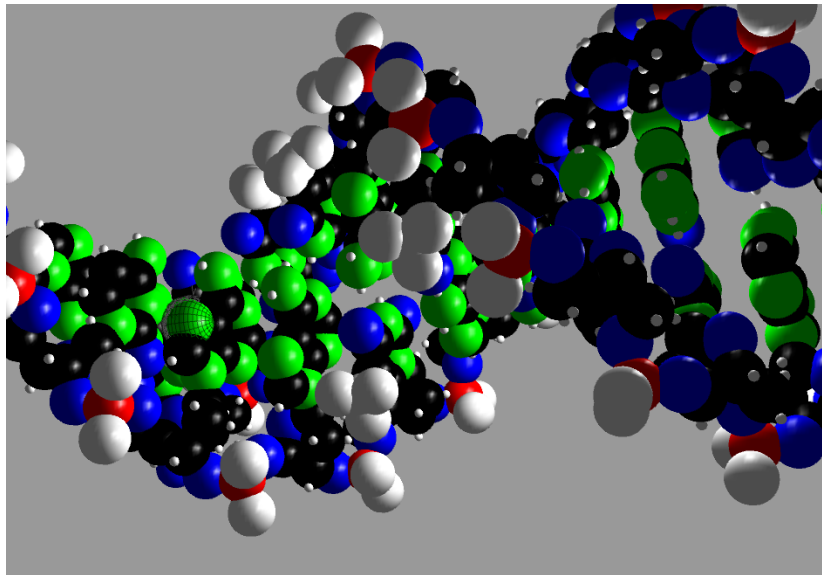


Virtual Creatures

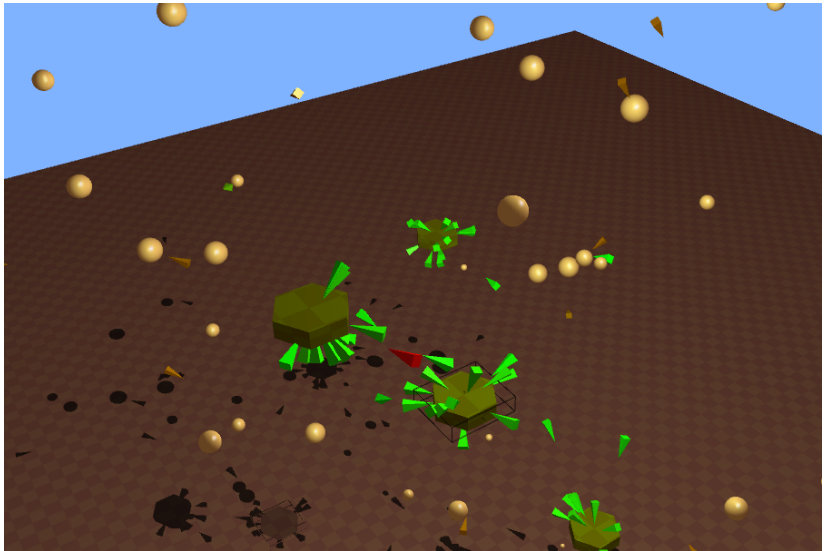


Evolving virtual creatures, Sims (1994)

Molecule



Sharing eco-system



Wouter Bulten, Pim Haselager & Ida Sprinkhuizen-Kuyper, BNAIC 2012

Basis of a simulation

Every simulation has the same building blocks:

1. Controller
2. Agents
3. Objects (floor, food, nests, etc.)

Building & running a simulation

- ▶ Build simulations in Steve or Python
- ▶ Run using the IDE or through command line

Steve

```
Mobile : Bird (aka Birds) {
```

```
+ to init:
```

```
...
```

```
+ to iterate:
```

```
...
```

```
}
```

Python

```
class Bird( breve.Mobile ):
```

```
    def __init__( self ):
```

```
        ...
```

```
    def iterate( self ):
```

```
        ...
```



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Adding complexity

- ▶ Communication between
 - ▶ agents (groups, leaders, followers)
 - ▶ simulations via a network
- ▶ Use physics
- ▶ Add evolution/genetics (own modules, link with JGap, or built-in engine Push)

What we are going to build

- ▶ 3D decentralised food gathering algorithm
- ▶ No communication between agents
- ▶ Goal: collect food and make piles
- ▶ Optional: two groups

