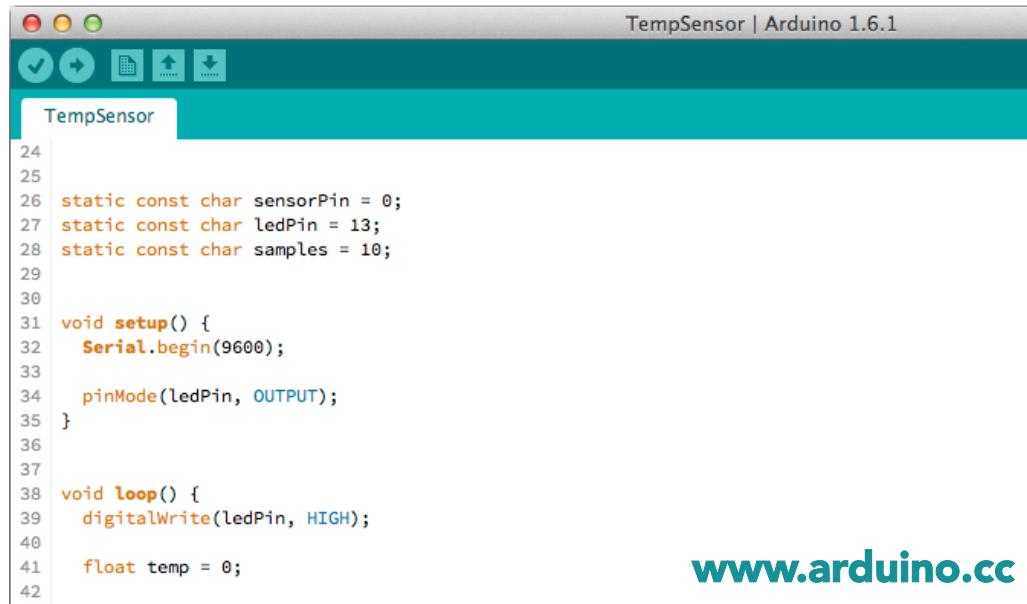


Electrónica Básica com o Arduino

...explicada por um informático

A Plataforma Arduino



```
TempSensor | Arduino 1.6.1

TempSensor

24
25
26 static const char sensorPin = 0;
27 static const char ledPin = 13;
28 static const char samples = 10;
29
30
31 void setup() {
32   Serial.begin(9600);
33
34   pinMode(ledPin, OUTPUT);
35 }
36
37
38 void loop() {
39   digitalWrite(ledPin, HIGH);
40
41   float temp = 0;
42 }
```

www.arduino.cc

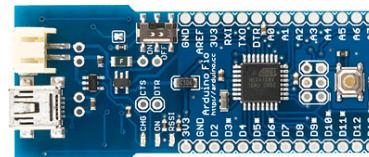
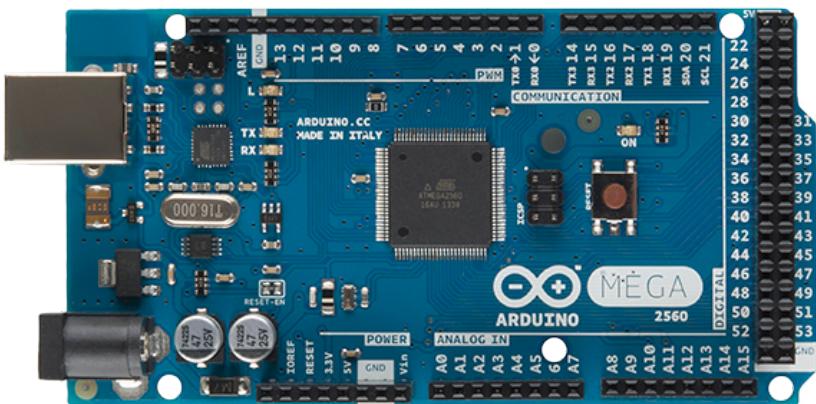
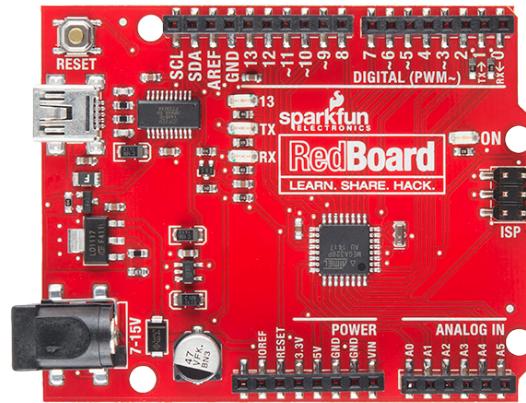
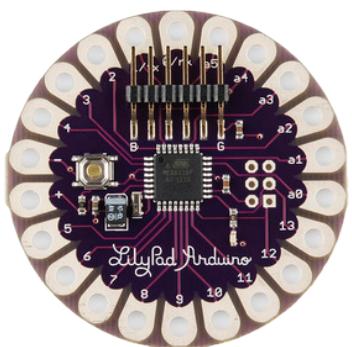
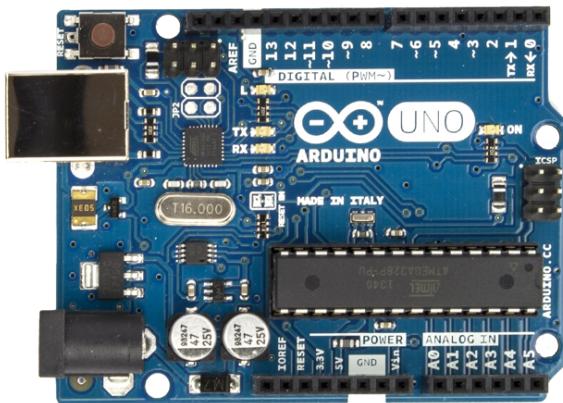


...10101010...

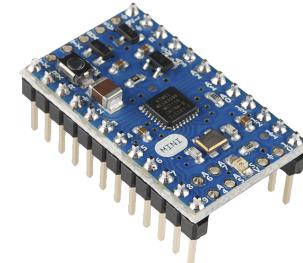


- Uma biblioteca de abstracção do *hardware*
- Um IDE simples em cima das ferramentas da GNU
- Circuitos de suporte ao microcontrolador
- Um *bootloader* para carregar programas

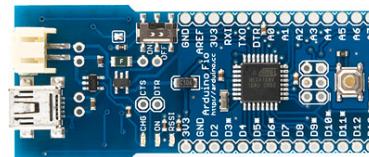
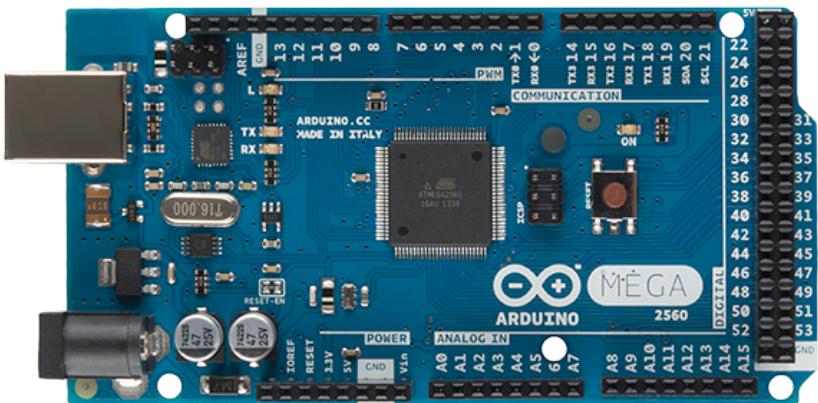
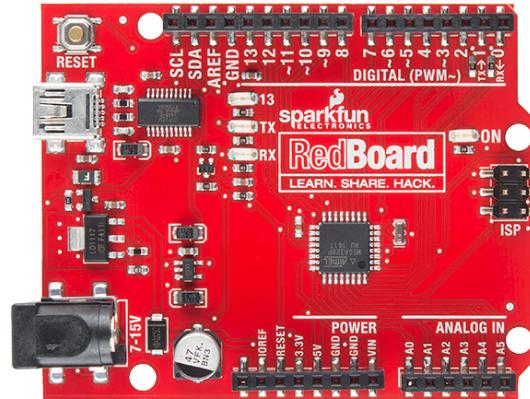
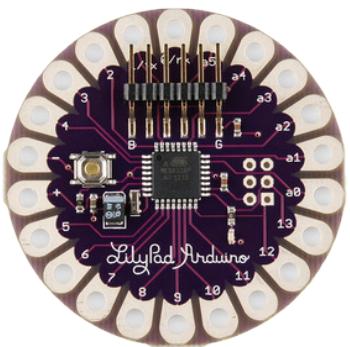
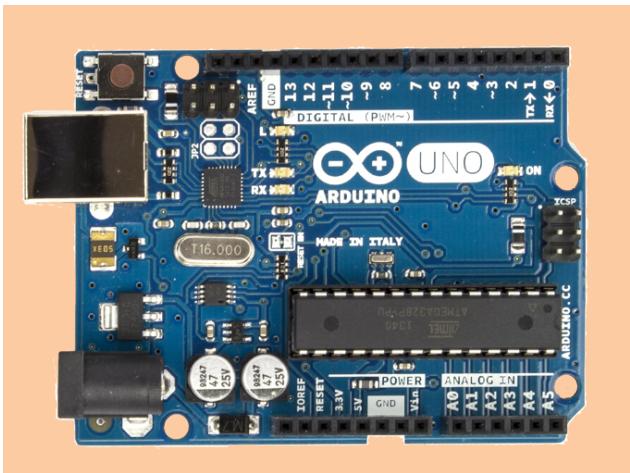
A Plataforma Arduino



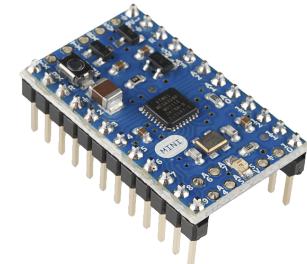
ATMEL AVR



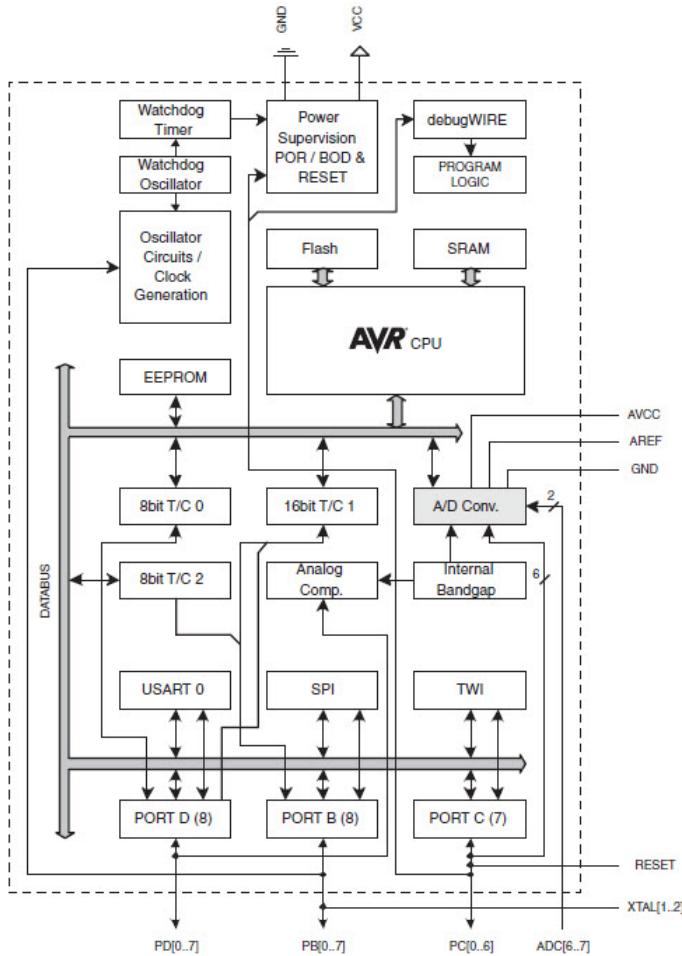
A Plataforma Arduino



AT&T **AVR**



Especificações (do Arduino Uno)



- ATmega328p (8-bit) @ 16 MHz
- 2 KB de RAM
- 32 KB de memória Flash (programas)
...mais 1 KB de EEPROM (estado persistente)
- 14 pinos de I/O digital
...6 deles com PWM disponível (8-bit)
...2 com suporte para *interrupts*
- 6 pinos de *input* analógico (10-bit)

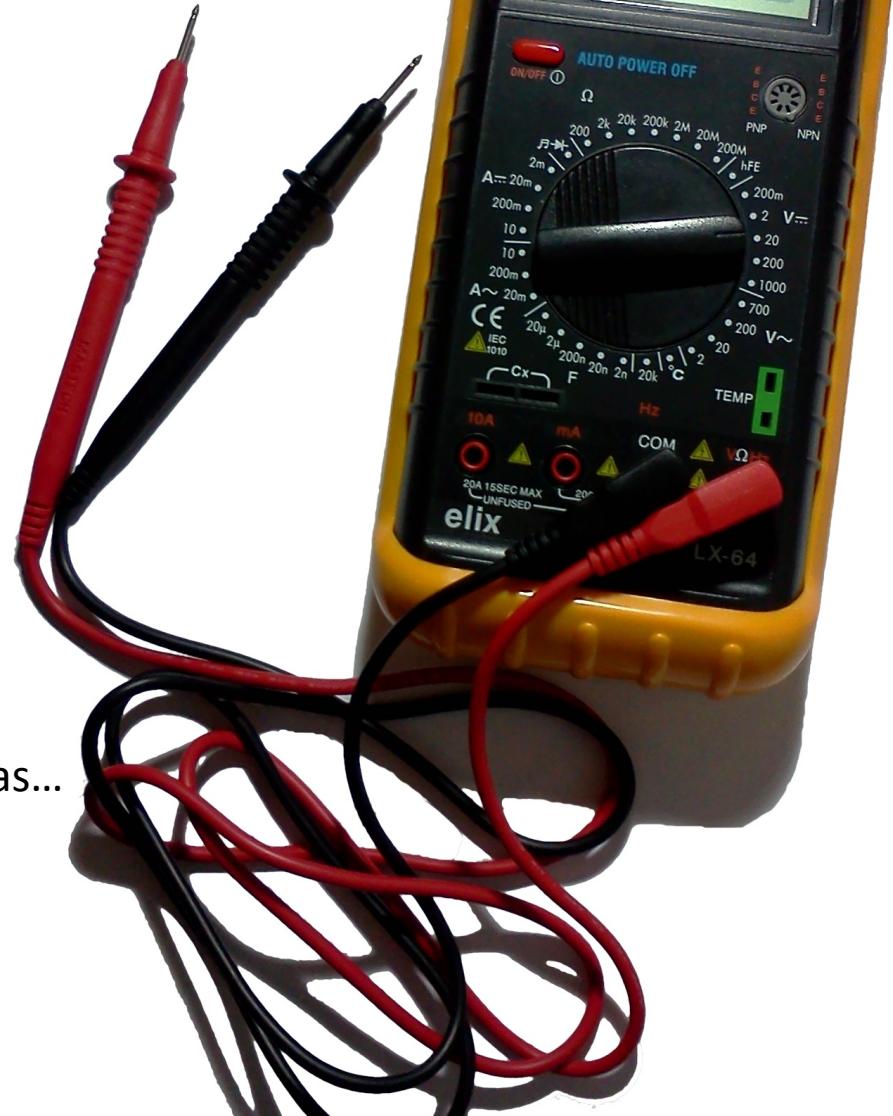
Especificações Eléctricas

- A placa funciona a **5 V**
- Fonte de alimentação entre **7** a **12 V**
 - ...que pode ir até 20 V, mas não se recomenda
- Cada pino de I/O aguenta **20 mA** (em segurança)
 - ...mas **evitem** mais de **100 mA** na soma de todos os pinos
 - ...e **nunca** lhes dêem mais de 5 V ou voltagens negativas
- O pino “5V” debita até cerca de **100 mA** (sem aquecer muito)
 - ...mas o pino V_{in} (voltagem de alimentação) aguenta até **1 A**



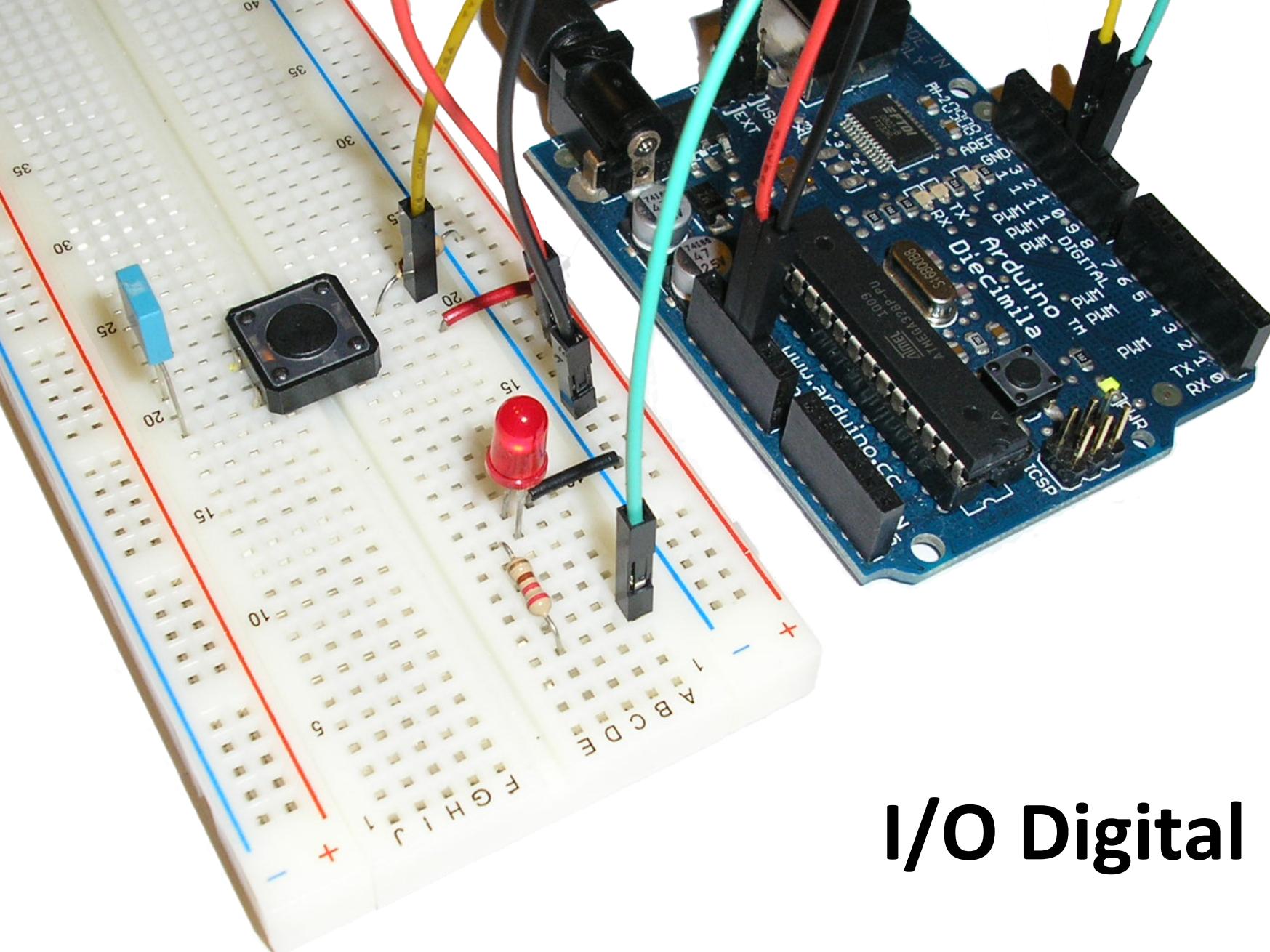
Arranjam um destes...

- Voltagem* (V_{dc} e V_{ac})
- Corrente (DC e AC)
- Resistência (Ω)
- Capacitância (F)
- Ganho de transístores (hFE)
- Teste de continuidade
- Temperatura ($^{\circ}C$)



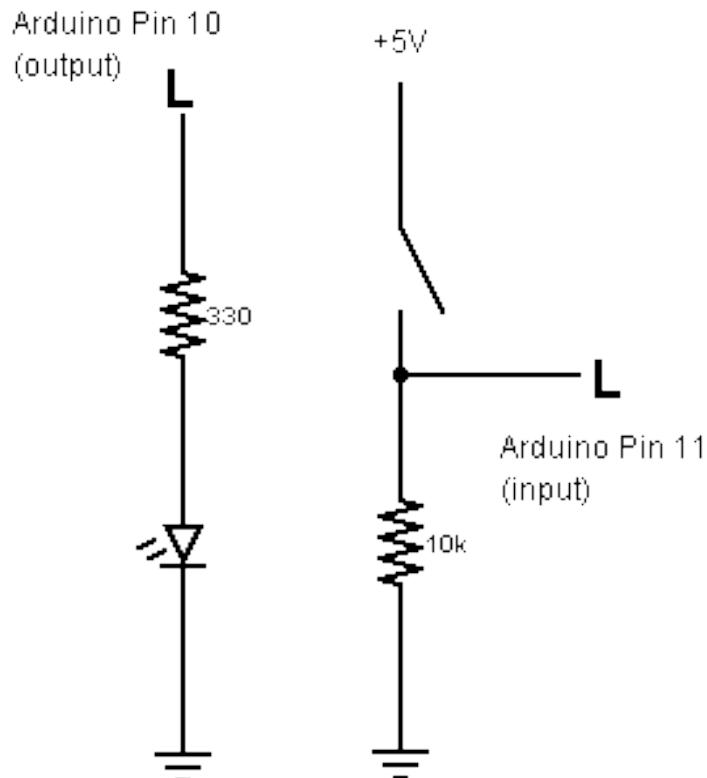
Qualquer marca serve, mas não sejam forretas...

*Mais correctamente: “Tensão Eléctrica”



I/O Digital

O Primeiro Circuito (I/O Digital)



```
// Alternar o estado de um LED pressionando um botão...

static const char led_pin = 10;
static const char button_pin = 11;

boolean led_state = LOW;
boolean last_button_state = LOW;

void setup() {
    pinMode(led_pin, OUTPUT);
    pinMode(button_pin, INPUT);
}

void loop() {
    boolean button_state = digitalRead(button_pin);

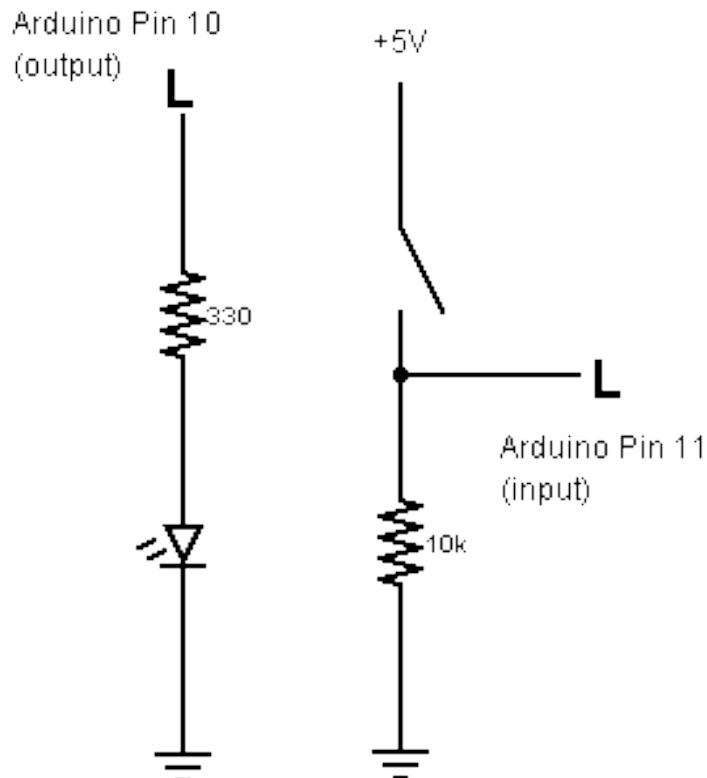
    if (button_state == HIGH && last_button_state == LOW) {
        led_state = !led_state;

        digitalWrite(led_pin, led_state);
    }

    last_button_state = button_state;
}
```

Binário: 988 bytes

O Primeiro Circuito (I/O Digital)



// Alternar o estado de um LED pressionando um botão...

```
static const char led_pin = 10;
static const char button_pin = 11;

boolean led_state = LOW;
boolean last_button_state = LOW;

void setup() {
    pinMode(led_pin, OUTPUT);
    pinMode(button_pin, INPUT);
}

void loop() {
    boolean button_state = digitalRead(button_pin);

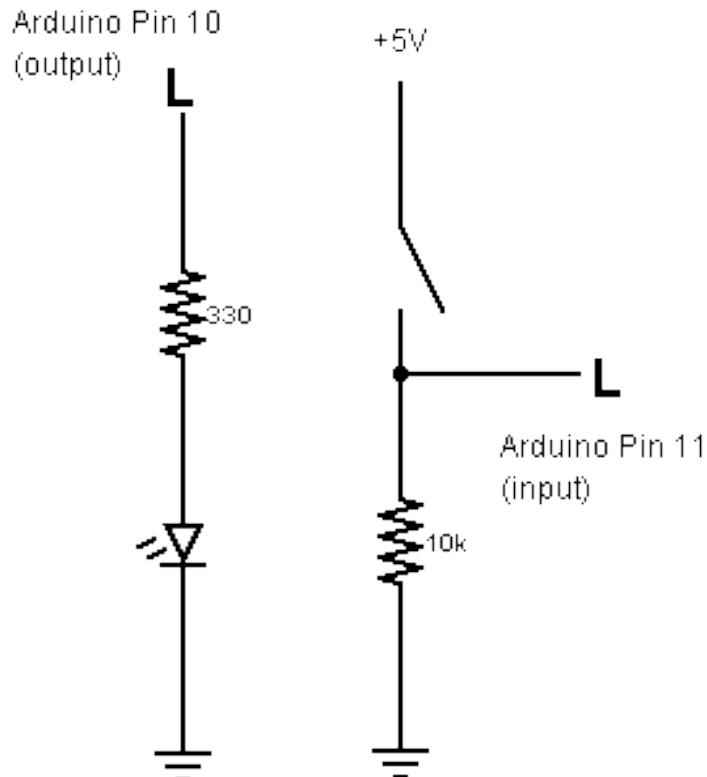
    if (button_state == HIGH && last_button_state == LOW) {
        led_state = !led_state;

        digitalWrite(led_pin, led_state);
    }

    last_button_state = button_state;
}
```

Binário: 988 bytes

O Primeiro Circuito (I/O Digital)



```
// Alternar o estado de um LED pressionando um botão...
```

```
static const char led_pin = 10;
static const char button_pin = 11;

boolean led_state = LOW;
boolean last_button_state = LOW;

void setup() {
    pinMode(led_pin, OUTPUT);
    pinMode(button_pin, INPUT);
}

void loop() {
    boolean button_state = digitalRead(button_pin);

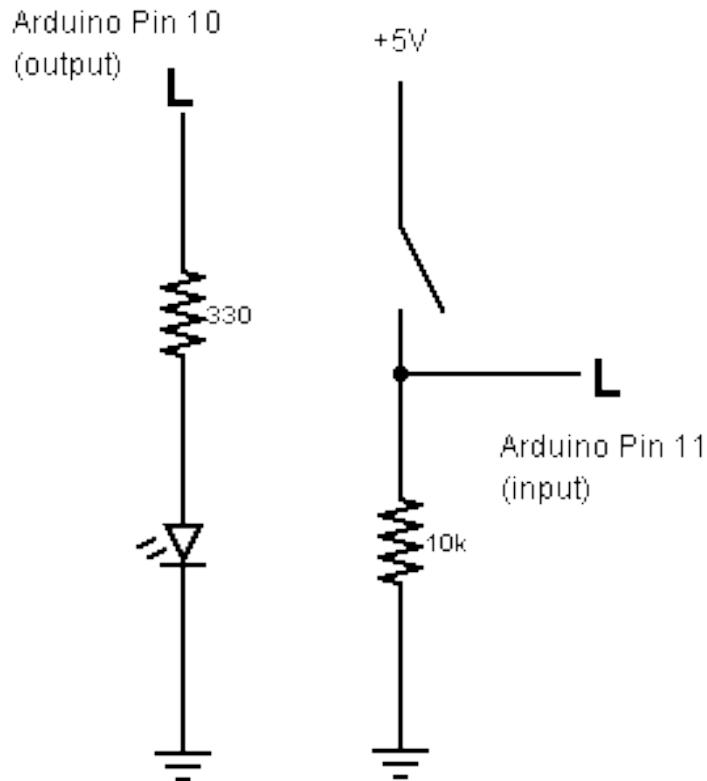
    if (button_state == HIGH && last_button_state == LOW) {
        led_state = !led_state;

        digitalWrite(led_pin, led_state);
    }

    last_button_state = button_state;
}
```

Binário: 988 bytes

O Primeiro Circuito (I/O Digital)



```
// Alternar o estado de um LED pressionando um botão...
```

```
static const char led_pin = 10;
static const char button_pin = 11;

boolean led_state = LOW;
boolean last_button_state = LOW;

void setup() {
    pinMode(led_pin, OUTPUT);
    pinMode(button_pin, INPUT);
}

void loop() {
    boolean button_state = digitalRead(button_pin);

    if (button_state == HIGH && last_button_state == LOW) {
        led_state = !led_state;

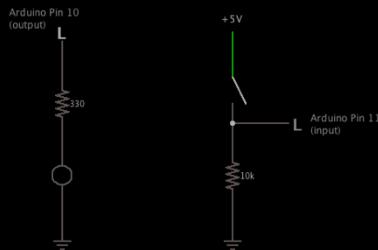
        digitalWrite(led_pin, led_state);
    }

    last_button_state = button_state;
}
```

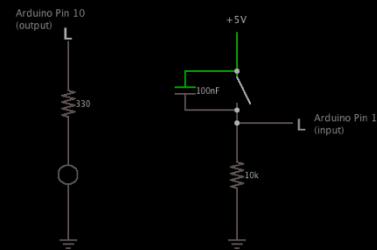
Binário: 988 bytes

Simulação

Simple Digital Input and Output



Simple Digital Input and Output (debounced)



This works because Arduino digital pins have input hysteresis (Schmitt-Trigger).

“Debouncing” com Condensadores



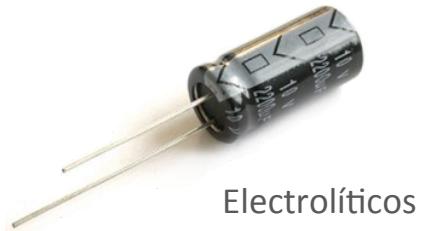
Poliéster



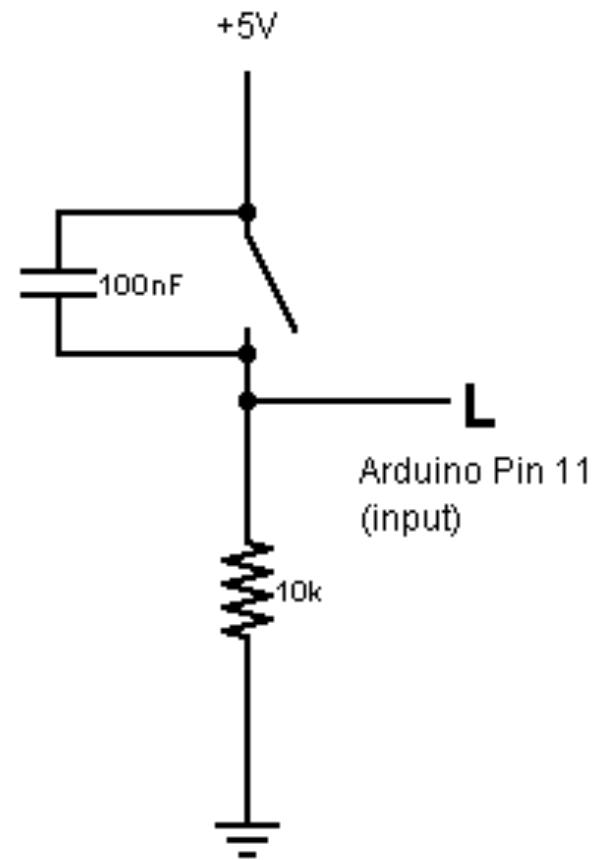
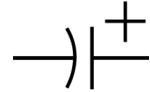
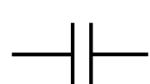
Tântalo



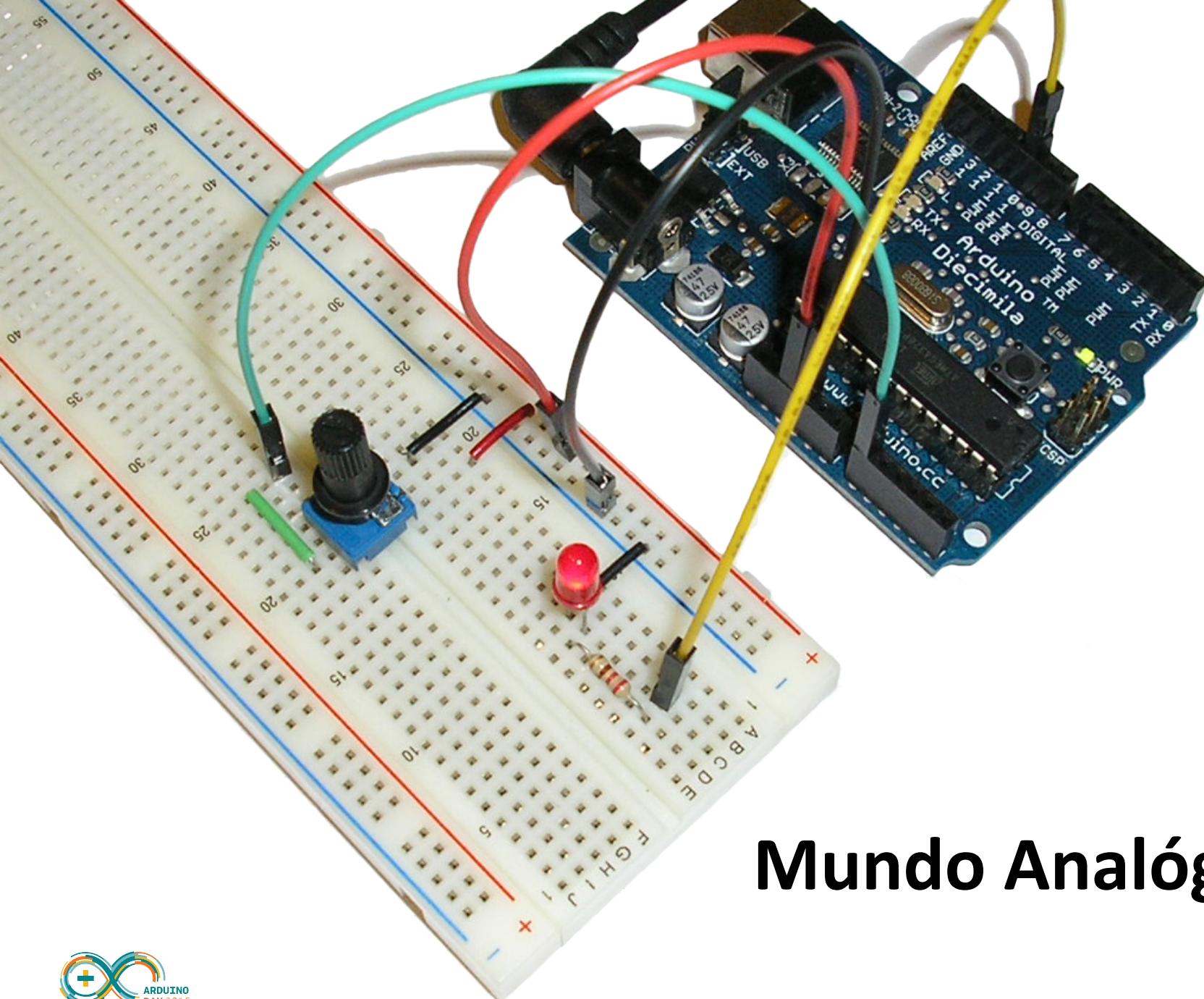
Cerâmicos



Electrolíticos

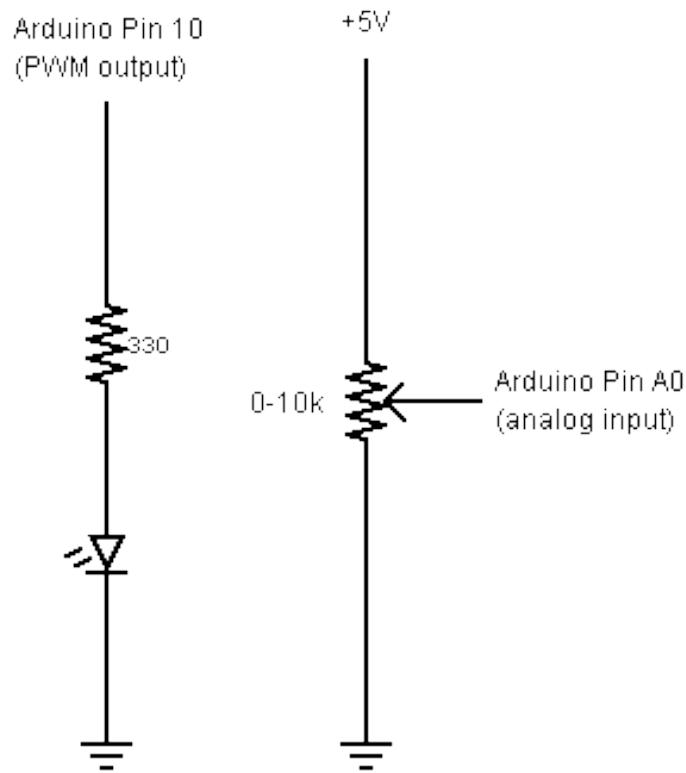


Isto funciona porque os pinos digitais do Arduino têm histerese (Schmitt-Trigger).



Mundo Analógico

Input Analógico e Output PWM*



```
// Controlar o brilho de um LED com um potenciômetro...

static const char led_pin = 10;
static const char pot_pin = A0;

void setup() {
    pinMode(led_pin, OUTPUT);
}

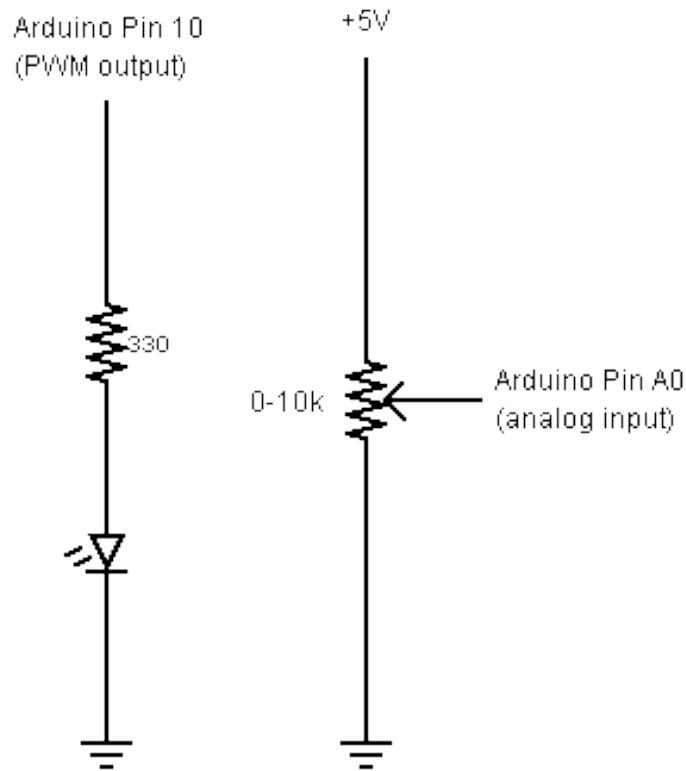
void loop() {
    short pot_value = analogRead(pot_pin);
    short brightness = map(pot_value, 0, 1023, 0, 255);

    analogWrite(led_pin, brightness);

    delay(10);
}
```

*Pulse-Width Modulation

Input Analógico e Output PWM*



```
// Controlar o brilho de um LED com um potenciômetro...
```

```
static const char led_pin = 10;
static const char pot_pin = A0;

void setup() {
    pinMode(led_pin, OUTPUT);
}

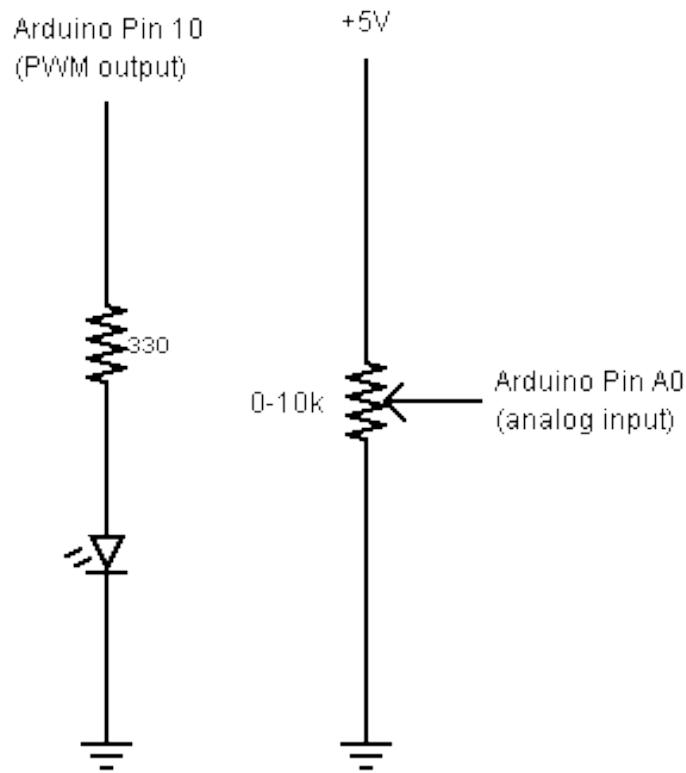
void loop() {
    short pot_value = analogRead(pot_pin);
    short brightness = map(pot_value, 0, 1023, 0, 255);

    analogWrite(led_pin, brightness);

    delay(10);
}
```

*Pulse-Width Modulation

Input Analógico e Output PWM*



```
// Controlar o brilho de um LED com um potenciômetro...
```

```
static const char led_pin = 10;
static const char pot_pin = A0;
```

```
void setup() {
    pinMode(led_pin, OUTPUT);
}
```

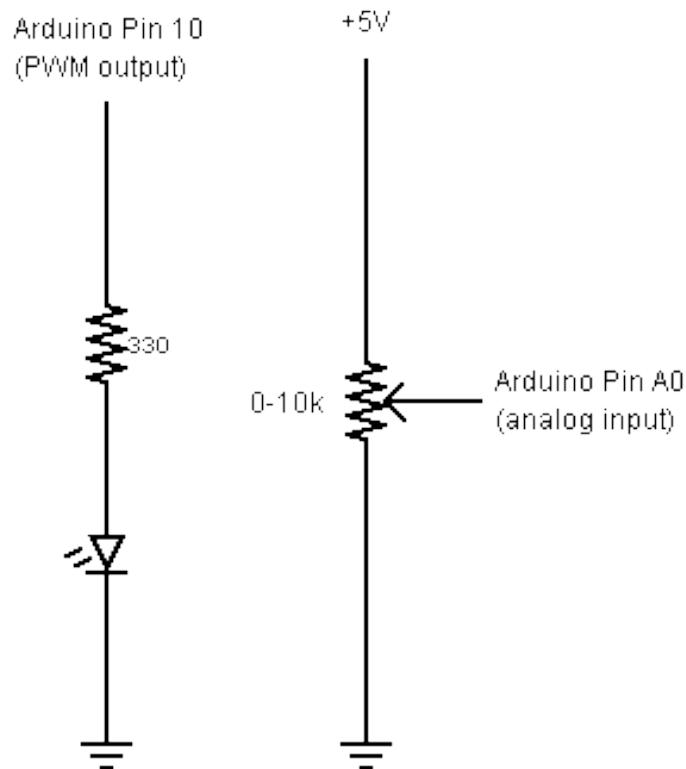
```
void loop() {
    short pot_value = analogRead(pot_pin);
    short brightness = map(pot_value, 0, 1023, 0, 255);

    analogWrite(led_pin, brightness);

    delay(10);
}
```

*Pulse-Width Modulation

Input Analógico e Output PWM*



```
// Controlar o brilho de um LED com um potenciômetro...

static const char led_pin = 10;
static const char pot_pin = A0;

void setup() {
    pinMode(led_pin, OUTPUT);
}

void loop() {
    short pot_value = analogRead(pot_pin);
    short brightness = map(pot_value, 0, 1023, 0, 255);

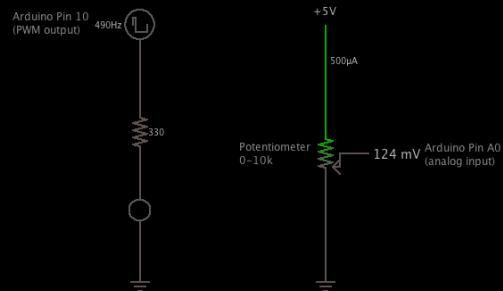
    analogWrite(led_pin, brightness);

    delay(10);
}
```

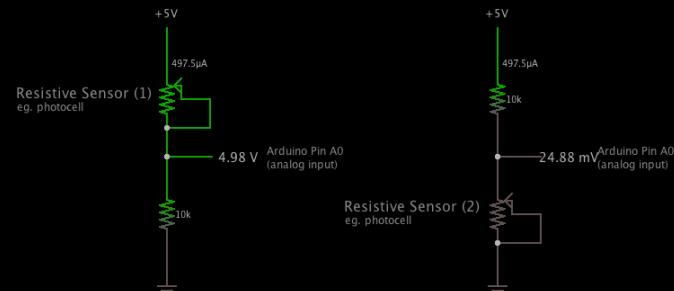
*Pulse-Width Modulation

Simulação

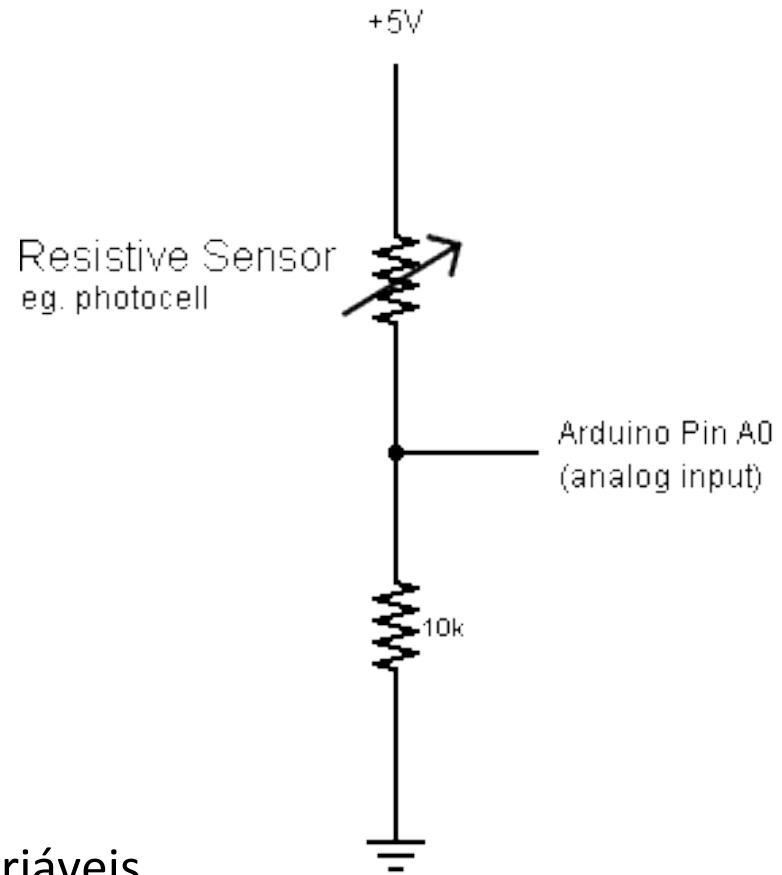
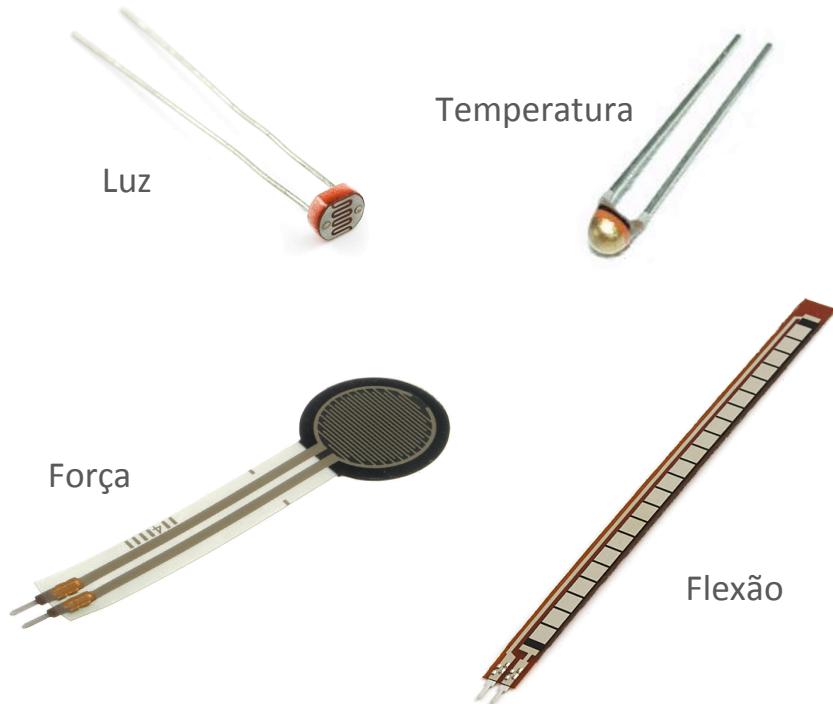
Simple Analog Input and Output



Resistive Analog Input (Voltage Divider)

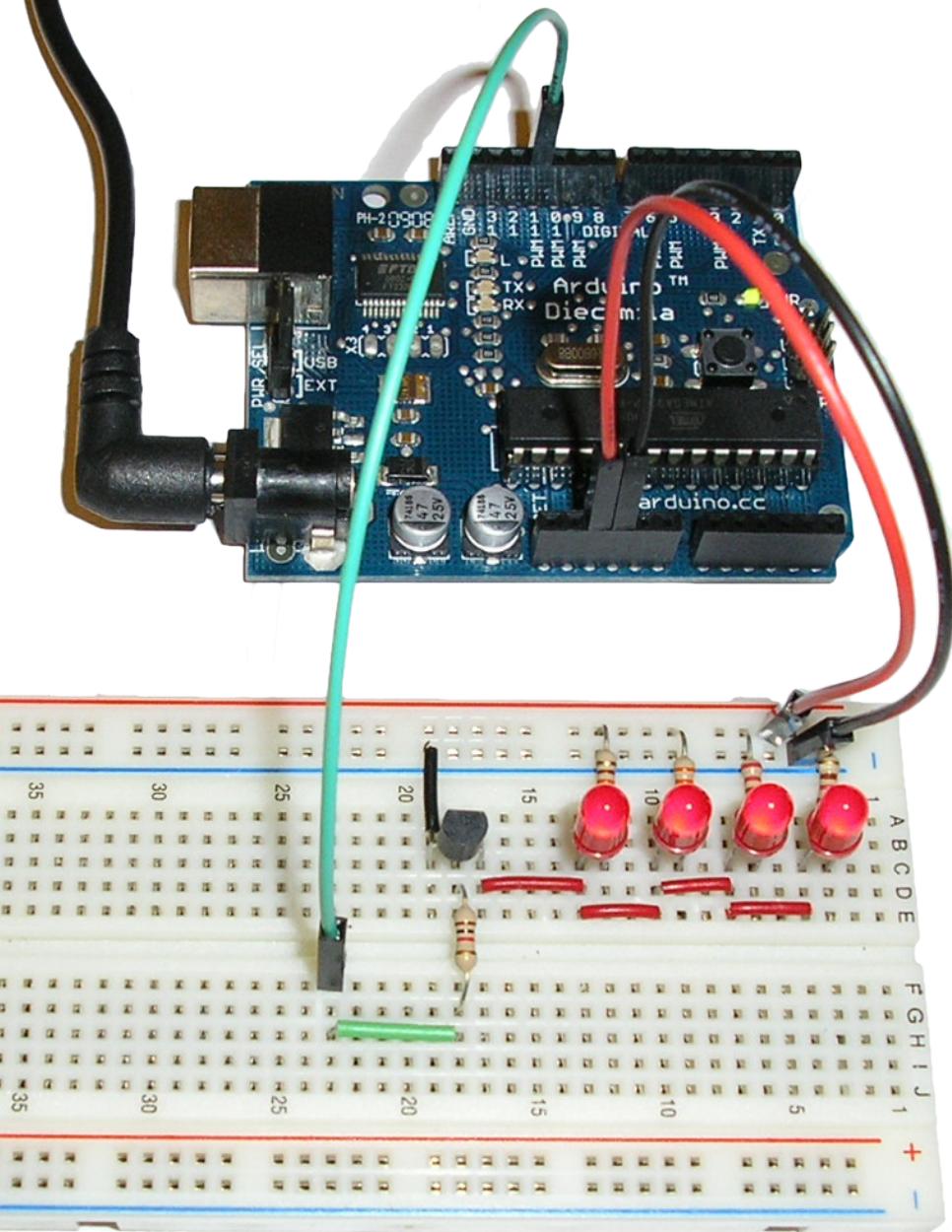


Input Analógico: Sensores Resistivos

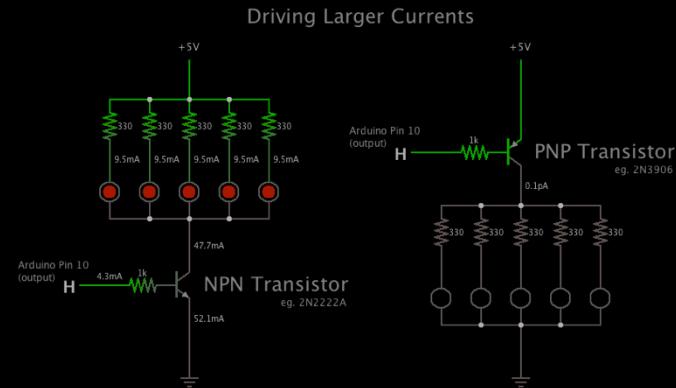


Muitos sensores são apenas resistências variáveis...

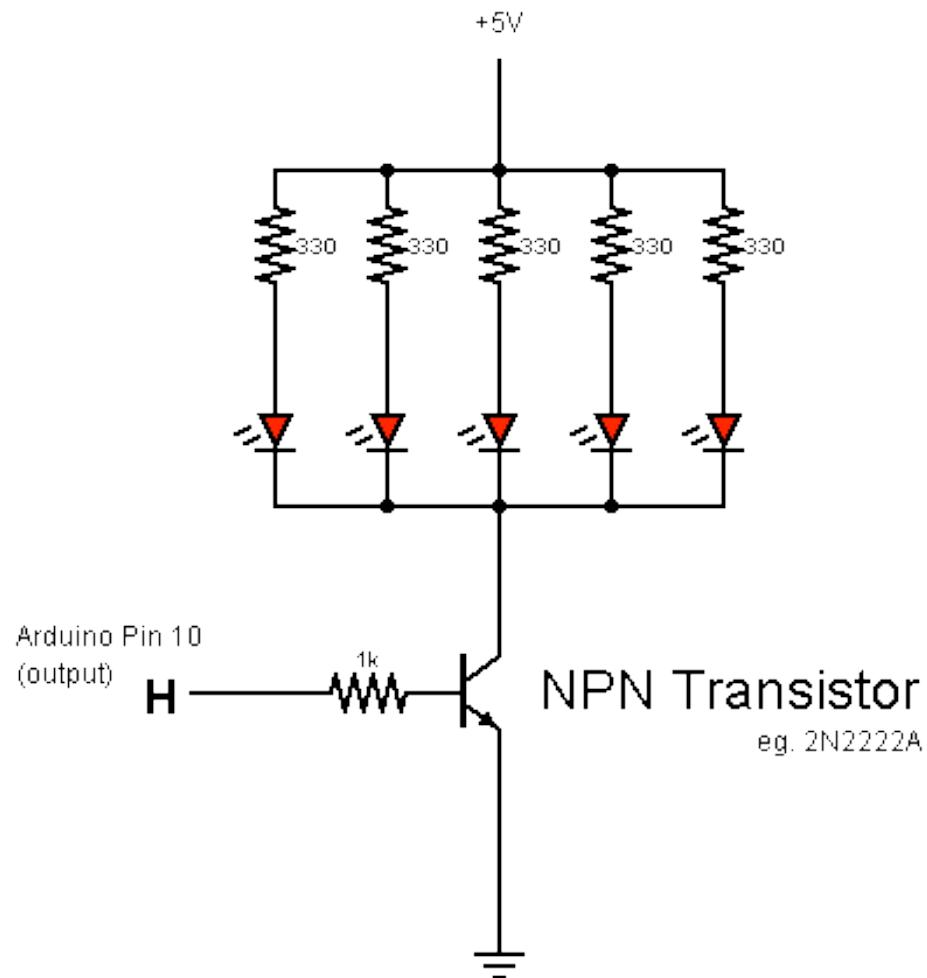
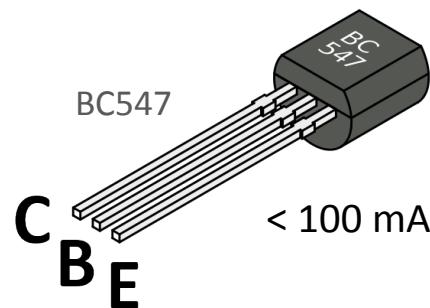
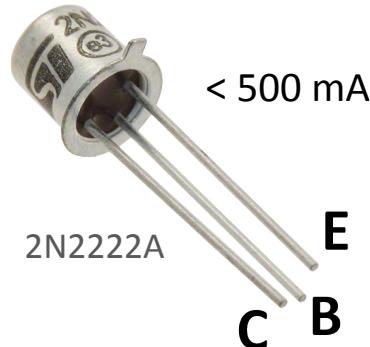
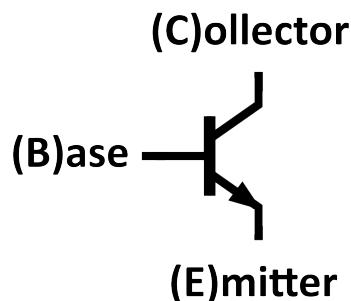
Mais Corrente



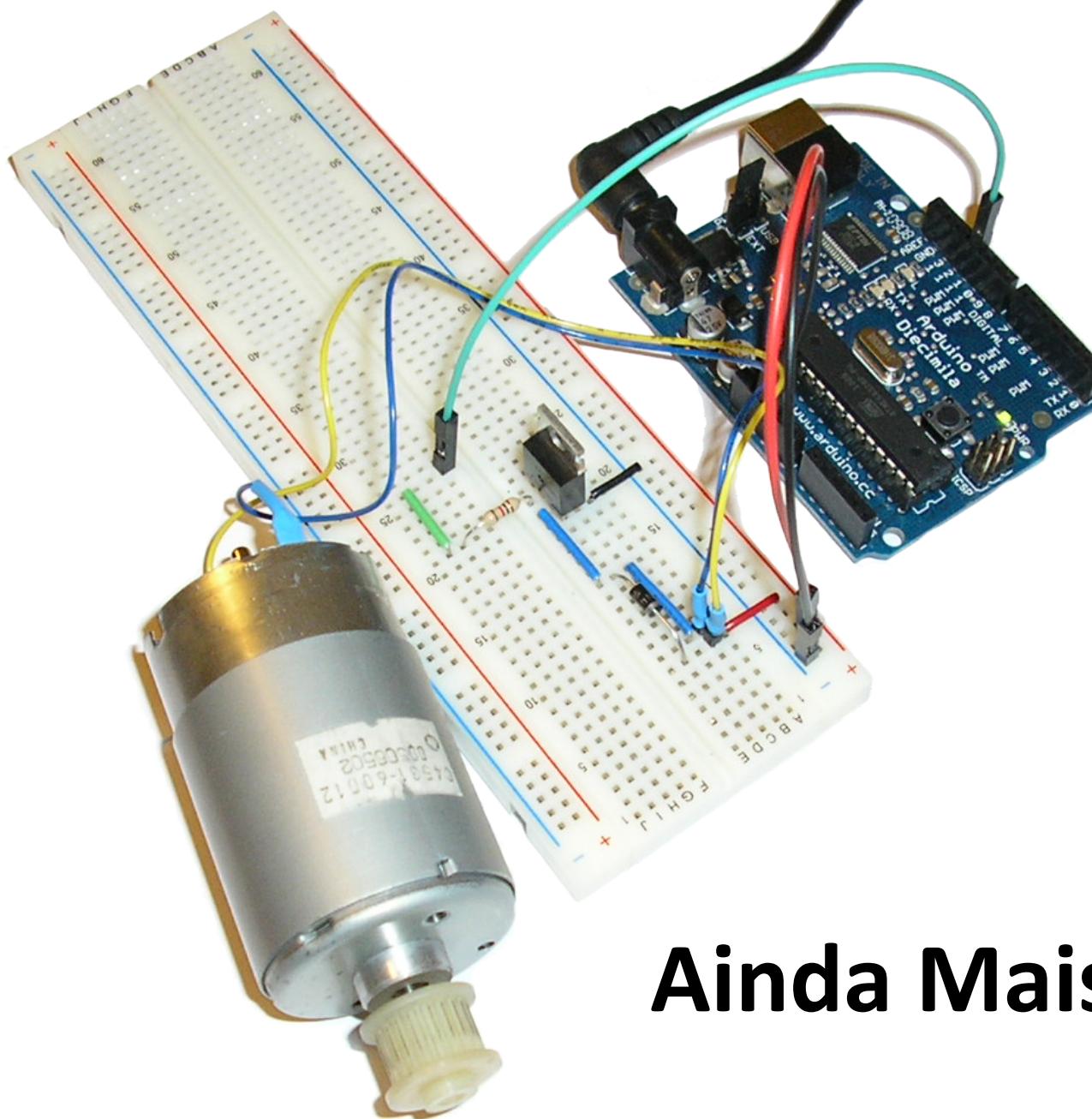
Simulação



Controlar Mais Corrente: BJTs*



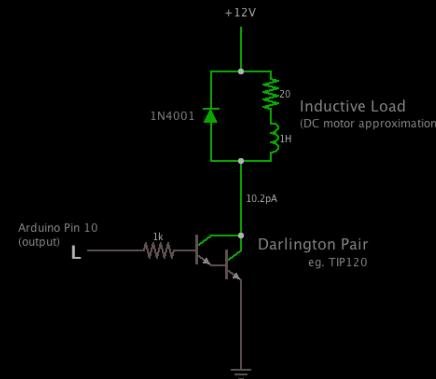
* Bipolar Junction Transistors (Transístores Bipolares)



Ainda Mais Corrente

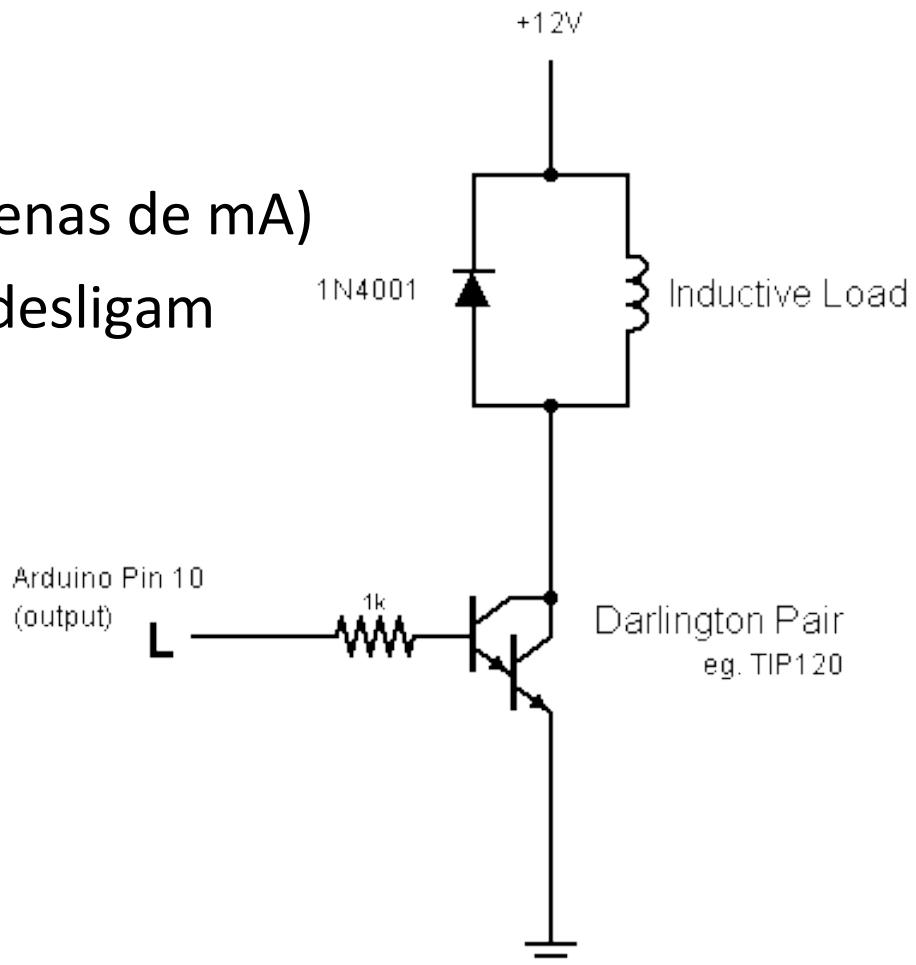
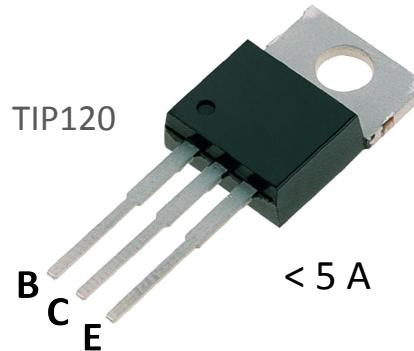
Simulação

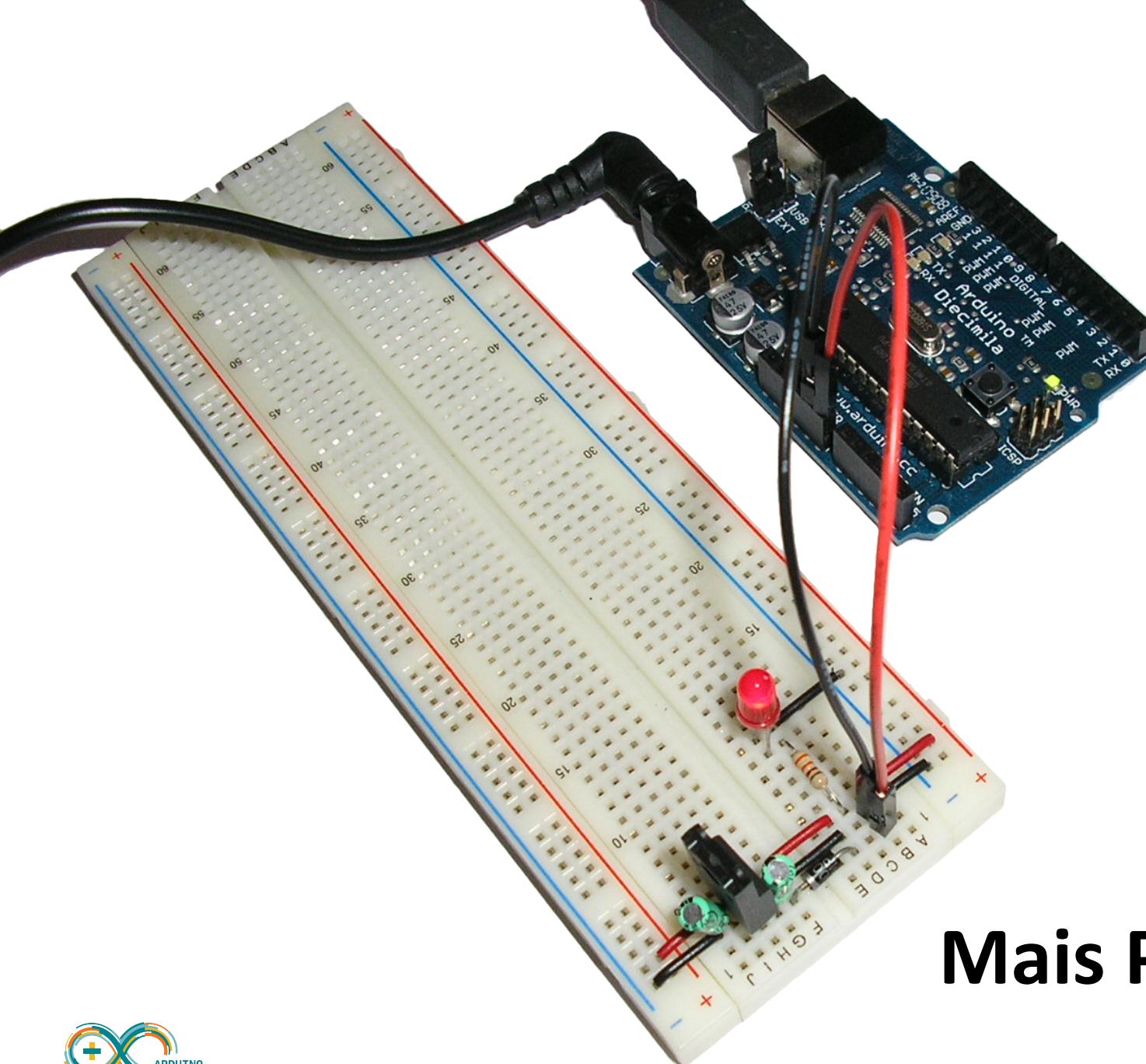
Driving Even Larger Currents (Darlington)



Cargas Indutivas

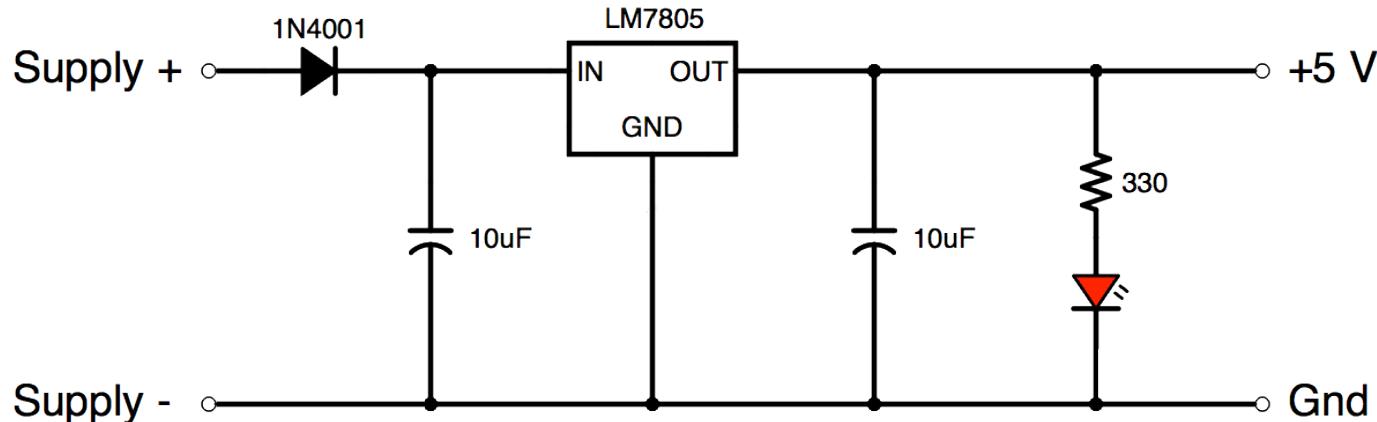
- Motores, solenóides, relés...
- Puxam muita corrente (centenas de mA)
- Causam “kickback” quando desligam



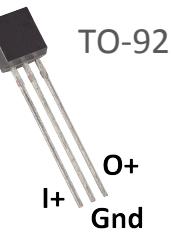


Mais Potência

Alimentação Regulada



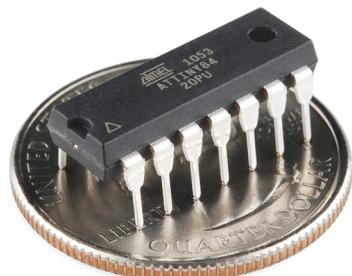
- 5 V (LM7805), 12 V (LM7812) e outras
- Voltagem de entrada até 35 V
- Máx. 100 mA (TO-92) ou 1 A (TO-220)
- Condensadores obrigatórios para funcionar correctamente



Microcontroladores Isolados



ATtiny85



ATtiny84

ATmega168
ATmega328p



Podem ser programados com o IDE do Arduino!

Precisam de um programador ISP, mas um Arduino a correr o *sketch* “ArduinoISP” é suficiente.

github.com/carlosefr/atmega – Configuração para microcontroladores ATmega sem componentes externos
highlowtech.org/?p=1695 – Configuração para microcontroladores ATtiny

Obrigado!

Questões?

PDF desta apresentação, simulações e código:
cloud.carlos-rodrigues.com/arduino-day/2015.zip

Carlos Rodrigues

cefrodrigues@gmail.com
twitter.com/carlosefrodrigues

