

Title

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Problem 3.3.1

A rotation $\varphi_1 + \varphi_2$ about the z -axis is carried out as two successive rotations φ_1 and φ_2 , each about the z -axis. Use the matrix representation of the rotations to derive the trigonometric identities

Solution

$$\begin{aligned}\cos(\varphi_1 + \varphi_2) &= \cos \varphi_1 \cos \varphi_2 - \sin \varphi_1 \sin \varphi_2 \\ \sin(\varphi_1 + \varphi_2) &= \sin \varphi_1 \cos \varphi_2 + \cos \varphi_1 \sin \varphi_2 \\ \begin{bmatrix} \cos(\varphi_1 + \varphi_2) \sin(\varphi_1 + \varphi_2) \\ -\sin(\varphi_1 + \varphi_2) \cos(\varphi_1 + \varphi_2) \end{bmatrix} &= \begin{bmatrix} \cos \varphi_2 \sin \varphi_2 \\ -\sin \varphi_2 \cos \varphi_2 \end{bmatrix} \begin{bmatrix} \cos \varphi_1 \sin \varphi_1 \\ -\sin \varphi_1 \cos \varphi_1 \end{bmatrix} \\ &= \begin{bmatrix} \cos \varphi_1 \cos \varphi_2 - \sin \varphi_1 \sin \varphi_2 & \sin \varphi_1 \cos \varphi_2 + \cos \varphi_1 \sin \varphi_2 \\ -\cos \varphi_1 \sin \varphi_2 - \sin \varphi_1 \cos \varphi_2 & -\sin \varphi_1 \sin \varphi_2 + \cos \varphi_1 \cos \varphi_2 \end{bmatrix}\end{aligned}$$

Problem 3.3.2

A corner reflector is formed by three mutually perpendicular reflecting surfaces. Show that a ray of light incident upon the corner (striking all three surfaces) is reflected back along a line parallel to the line of incidence. Hint. Consider the effect of a reflection on the components of a vector describing the direction of the light ray.

Solution Here we are asked to prove that the ray of light incident upon the corner reflector is reflected back along a line parallel to the line of incidence. So for this align the reflecting surfaces with xy , xz , and yz planes. If an incoming ray strikes the xy plane, the z component of its direction of propagation is reversed. A strike on the xz plane reverses its y component, and a strike on the yz plane reverses its x component.

Problem 3.3.3

Let x and y be column vectors. Under an orthogonal transformation S , they become $x' = Sx$ and $y' = Sy$. Show that $(x')^T y' = x^T y$, a result equivalent to the invariance of the dot product under a rotational transformation.

Solution It is given that S is orthogonal, if so its transpose is also its inverse. From this

$$(x')^T = (Sx)^T = x^T S^T = x^T S^{-1}$$

Then

$$(x')^T y' = x^T S^{-1} Sy = x^T y$$

Therefore $(x')^T y' = x^T y$

Problem 3.3.4

Given the orthogonal transformation matrix S and vectors \mathbf{a} and \mathbf{b} ,

$$S = \begin{bmatrix} 0.80 & 0.60 & 0.00 \\ -0.48 & 0.64 & 0.60 \\ 0.36 & -0.48 & 0.80 \end{bmatrix}, \quad \mathbf{a} = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \quad \mathbf{b} = \begin{bmatrix} 0 \\ 2 \\ -1 \end{bmatrix}$$

- Calculate $\det(S)$.
- Verify that $\mathbf{a} \cdot \mathbf{b}$ is invariant under application of \mathbf{S} to \mathbf{a} and \mathbf{b} .
- Determine what happens to $\mathbf{a} \times \mathbf{b}$ under application of \mathbf{S} to \mathbf{a} and \mathbf{b} . Is this what is expected?

Solution For (a) given

$$S = \begin{bmatrix} 0.80 & 0.60 & 0.00 \\ -0.48 & 0.64 & 0.60 \\ 0.36 & -0.48 & 0.80 \end{bmatrix}$$

$$\det(S) = \det \begin{bmatrix} 0.80 & 0.60 & 0.00 \\ -0.48 & 0.64 & 0.60 \\ 0.36 & -0.48 & 0.80 \end{bmatrix} = 1$$

Solution For (b) we show that $a \cdot b$ is invariant under application of \mathbf{S} to a and b .

$$\begin{aligned} \mathbf{a}' &= \mathbf{S}\mathbf{a} \\ &= \begin{bmatrix} 0.80 & 0.60 & 0.00 \\ -0.48 & 0.64 & 0.60 \\ 0.36 & -0.48 & 0.80 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \\ &= \begin{bmatrix} 0.80 \\ 0.12 \\ 1.16 \end{bmatrix} \end{aligned}$$

$$\begin{aligned} \mathbf{b}' &= \mathbf{S}\mathbf{b} \\ &= \begin{bmatrix} 0.80 & 0.60 & 0.00 \\ -0.48 & 0.64 & 0.60 \\ 0.36 & -0.48 & 0.80 \end{bmatrix} \begin{bmatrix} 0 \\ 2 \\ -1 \end{bmatrix} \\ &= \begin{bmatrix} 1.20 \\ 0.68 \\ -1.76 \end{bmatrix} \end{aligned}$$

$$a \cdot b = \begin{bmatrix} 1 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 2 \\ -1 \end{bmatrix} = -1$$

$$a' \cdot b' = \begin{bmatrix} 0.80 & 0.12 & 1.16 \end{bmatrix} \begin{bmatrix} 1.20 \\ 0.68 \\ -1.76 \end{bmatrix} = -1$$

Thus, $a \cdot b$ is invariant under application of \mathbf{S} to a and b .

Solution For (c) we find $\mathbf{a} \times \mathbf{b}$

$$\begin{aligned} \mathbf{a} \times \mathbf{b} &= \begin{vmatrix} i & j & k \\ 1 & 0 & 1 \\ 0 & 2 & -1 \end{vmatrix} = \begin{bmatrix} -2 \\ 1 \\ 2 \end{bmatrix} \\ \mathbf{S}(\mathbf{a} \times \mathbf{b}) &= \begin{bmatrix} 0.80 & 0.60 & 0.00 \\ -0.48 & 0.64 & 0.60 \\ 0.36 & -0.48 & 0.80 \end{bmatrix} \begin{bmatrix} -2 \\ 1 \\ 2 \end{bmatrix} \\ &= \begin{bmatrix} -1 \\ 2.8 \\ 0.4 \end{bmatrix} \end{aligned}$$

$$\mathbf{a}' \times \mathbf{b}' = \begin{vmatrix} i & j & k \\ 0.80 & 0.12 & 1.16 \\ 1.20 & 0.68 & -1.76 \end{vmatrix} = \begin{bmatrix} -1 \\ 2.8 \\ 0.4 \end{bmatrix}$$

Thus, $\mathbf{S}(\mathbf{a} \times \mathbf{b}) = \mathbf{a}' \times \mathbf{b}'$ and hence $\mathbf{a} \times \mathbf{b}$ is a vector.

Problem 3.3.5

Using \mathbf{a} and \mathbf{b} as defined in Exercise 3.3.5 but with

$$S = \begin{bmatrix} 0.60 & 0.00 & 0.80 \\ -0.64 & -0.60 & 0.48 \\ -0.48 & 0.80 & 0.36 \end{bmatrix} \quad \text{and} \quad \mathbf{c} = \begin{bmatrix} 2 \\ 1 \\ 3 \end{bmatrix}$$

(a) Calculate $\det(S)$.

(b) $\mathbf{a} \times \mathbf{b}$

(c) $(\mathbf{a} \times \mathbf{b}) \cdot \mathbf{c}$

(d) $\mathbf{a} \times (\mathbf{b} \times \mathbf{c})$

Solution For (a) Given that

$$S = \begin{bmatrix} 0.60 & 0.00 & 0.80 \\ -0.64 & -0.60 & 0.48 \\ -0.48 & 0.80 & 0.36 \end{bmatrix}$$

Then

$$\det(S) = \det \begin{bmatrix} 0.60 & 0.00 & 0.80 \\ -0.64 & -0.60 & 0.48 \\ -0.48 & 0.80 & 0.36 \end{bmatrix} = 1$$

Apply \mathbf{S} to \mathbf{a} , \mathbf{b} , and \mathbf{c} .

$$\mathbf{a}' = \mathbf{S}\mathbf{a}$$

$$\begin{aligned} &= \begin{bmatrix} 0.60 & 0.00 & 0.80 \\ -0.64 & -0.60 & 0.48 \\ -0.48 & 0.80 & 0.36 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \\ &= \begin{bmatrix} 1.40 \\ -0.16 \\ -0.12 \end{bmatrix} \end{aligned}$$

$$\mathbf{b}' = \mathbf{S}\mathbf{b}$$

$$\begin{aligned} &= \begin{bmatrix} 0.60 & 0.00 & 0.80 \\ -0.64 & -0.60 & 0.48 \\ -0.48 & 0.80 & 0.36 \end{bmatrix} \begin{bmatrix} 0 \\ 2 \\ -1 \end{bmatrix} \\ &= \begin{bmatrix} -0.80 \\ -1.68 \\ 1.24 \end{bmatrix} \end{aligned}$$

$$\mathbf{c}' = \mathbf{S}\mathbf{c}$$

$$\begin{aligned} &= \begin{bmatrix} 0.60 & 0.00 & 0.80 \\ -0.64 & -0.60 & 0.48 \\ -0.48 & 0.80 & 0.36 \end{bmatrix} \begin{bmatrix} 2 \\ 1 \\ 3 \end{bmatrix} \\ &= \begin{bmatrix} 3.60 \\ -0.44 \\ 0.92 \end{bmatrix} \end{aligned}$$

Now, we determine what happen to $\mathbf{a} \times \mathbf{b}$ under application of \mathbf{S} to \mathbf{a} , \mathbf{b} , \mathbf{c} .

Solution For (b)

$$(\mathbf{a} \times \mathbf{b}) = \begin{bmatrix} -2 \\ 1 \\ 2 \end{bmatrix}$$

$$\begin{aligned} \mathbf{S}(\mathbf{a} \times \mathbf{b}) &= \begin{bmatrix} 0.60 & 0.00 & 0.80 \\ -0.64 & -0.60 & 0.48 \\ -0.48 & 0.80 & 0.36 \end{bmatrix} \begin{bmatrix} -2 \\ 1 \\ 2 \end{bmatrix} \\ &= \begin{bmatrix} 0.40 \\ 1.64 \\ 2.48 \end{bmatrix} \end{aligned}$$

$$\mathbf{a}' \times \mathbf{b}' = \begin{vmatrix} i & j & k \\ 1.40 & -0.16 & -0.12 \\ -0.80 & -1.68 & 1.24 \end{vmatrix} = \begin{bmatrix} -0.40 \\ -1.64 \\ -2.48 \end{bmatrix}$$

Thus, $\mathbf{S}(\mathbf{a} \times \mathbf{b}) = \mathbf{a}' \times \mathbf{b}'$

Solution For (c) we determine what happen to $(\mathbf{a} \times \mathbf{b}) \cdot \mathbf{c}$ under application of \mathbf{S} to $\mathbf{a}, \mathbf{b}, \mathbf{c}$

$$(\mathbf{a} \times \mathbf{b}) \cdot \mathbf{c} = \begin{bmatrix} -2 & 1 & 2 \end{bmatrix} \cdot \begin{bmatrix} 2 \\ 1 \\ 3 \end{bmatrix} = -4 + 1 + 6 = 3$$

$$(\mathbf{a}' \times \mathbf{b}') \cdot \mathbf{c}' = \begin{bmatrix} -0.40 & -1.64 & -2.48 \end{bmatrix} \cdot \begin{bmatrix} 3.60 \\ -0.44 \\ 0.92 \end{bmatrix} = -3$$

Thus, $(\mathbf{a} \times \mathbf{b}) \cdot \mathbf{c} = -(\mathbf{a}' \times \mathbf{b}') \cdot \mathbf{c}'$

Solution For (d) We now determine what happen to $\mathbf{a} \times (\mathbf{b} \times \mathbf{c})$ under application of \mathbf{S} to $\mathbf{a}, \mathbf{b}, \mathbf{c}$.

$$\mathbf{a} \times (\mathbf{b} \times \mathbf{c}) = \begin{vmatrix} 1 & 0 & 1 \\ 0 & 2 & -1 \\ 2 & 1 & 3 \end{vmatrix} = \begin{bmatrix} 2 \\ 11 \\ -2 \end{bmatrix}$$

$$\mathbf{S}(\mathbf{a} \times (\mathbf{b} \times \mathbf{c})) = \begin{bmatrix} 0.60 & 0.00 & 0.80 \\ -0.64 & -0.60 & 0.48 \\ -0.48 & 0.80 & 0.36 \end{bmatrix} \begin{bmatrix} 2 \\ 11 \\ -2 \end{bmatrix} = \begin{bmatrix} -0.40 \\ -8.84 \\ 7.12 \end{bmatrix}$$

$$\mathbf{a}' \times (\mathbf{b}' \times \mathbf{c}') = \begin{vmatrix} 1.40 & -0.16 & -0.12 \\ -0.80 & -1.68 & 1.24 \\ 3.60 & -0.44 & 0.92 \end{vmatrix} = \begin{bmatrix} -0.40 \\ -8.84 \\ 7.12 \end{bmatrix}$$

Thus, $\mathbf{S}(\mathbf{a} \times (\mathbf{b} \times \mathbf{c})) = \mathbf{a}' \times (\mathbf{b}' \times \mathbf{c}')$