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Classifiers

- You are given a set of n samples, each with d features.
- Some samples belong to a certain class \mathcal{O} ; some do not.
- Example: sample are bank loans, features are income and age (d=2). Some are in class defaulted; some are not. Goal: Predict whether future borrowers will default based on their income and age.
- Represent each sample as a point in a d-dimensional space, called a <u>feature vector</u> (aka predictors, independent variables).
- Decision boundary: the boundary chosen by our classifier to separate \mathcal{O} from not \mathcal{O} .
- Some (not all) classifiers work by computing a <u>predictor function</u>: A function f(x) that maps sample point x to a scalar such that,

$$f(x) > 0 \text{ if } x \in class \mathcal{O}$$

 $f(x) \leq 0 \text{ if } x \notin class \mathcal{O}$

(aka decision function, or discriminant function).

• For these classifiers, the decision boundary is,

$$\{x \in \mathbb{R}^d : f(x) = 0\}$$

That is the set of all points where the prediction function is zero. Usually this set is a (d-1)-dimensional surface in \mathbb{R}^d .

- $\{x: f(x) = 0\}$ is also called an <u>isosurface</u> (aka isocontours) of f for the <u>isovalue</u> 0.
- Linear classifier: The decision boundary is a hyperplane. Usually uses a linear predictor function.
- Overfitting: when sinuous (having many curves and turns) decision boundary fits sample data so well that it doesn't classify future (test set) items well.

Math Review

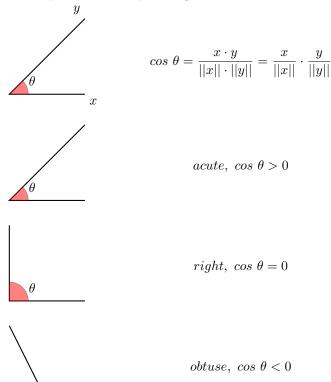
• <u>Vectors</u>:

$$x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} x_1 & x_2 & x_3 & x_4 & x_5 \end{bmatrix}^T$$

Think of x as a point in \mathbb{R}^d .

- Conventions (often, but not always):
 - Uppercase roman = matrix.
 - Lowercase roman = vector.
 - Greek = scalar.
 - Other scalars: n = number of samples, d = number of features or dimension of sample, i, j, and k = indices.

- Functions (often scalars): f(), s(), etc.
- Inner products (aka dot products)
 - $x \cdot y = x_1 y_1 + x_2 y_2 + \dots + x_d y_d$
 - Also written x^Ty .
 - Clearly, $f(x) = w \cdot x + \alpha$ is a linear function in x.
- Eucledian norms: $||x|| = \sqrt{x \cdot x} = \sqrt{x_1^2 + x_2^2 + \dots + x_d^2}$
 - -||x|| is the length (aka Eucledian length) of a vector x.
 - Given a vector x, $\frac{x}{||x||}$ is a unit vector (length 1).
 - "Normalize" a vector x: replace x with $\frac{x}{||x||}$.
- Use dot product to compute angles:



• Given a linear predictor function $f(x) = w \cdot x + \alpha$, decision boundary is

$$H = \{x: w \cdot x = -\alpha\}$$

- The set H is called a hyperplane (A line in 2D, a plane in 3D).
- Theorem: Let \vec{xy} be a vector that lies in H. Then $w \cdot (y x) = 0$. Proof: x and y lie on the hyperplane H. $\therefore w \cdot (y - x) = -\alpha - (-\alpha) = 0$.
- w is called the <u>normal vector</u> of H. w is normal (perpendicular) or orthogonal to H.
- If w is a unit vector, $w \cdot x + \alpha$ is called the <u>signed distance</u> from x to H i.e. its distance, but positive on one side of H; negative on the other. Moreover the distance from H to the origin is α . Hence $\alpha = 0$ if and only if H contains the origin.

- The coefficients in w, plus α are called <u>weights</u> or <u>regression coefficients</u>. Goal of many Machine Learning algorithms is to find what the weights should be.
- The input data is linearly separable if \exists a hyperplane that separates all samples $\in \mathcal{O}$ from all samples $\notin \mathcal{O}$.

Perceptron algorithm

- (Frank Rosenblatt, 1957) Slow, but correct for linearly separable samples. Uses a <u>numerical optimization</u> algorithm: gradient descent.
- Consider n sample vectors $x_1, x_2, \dots x_n$.
- For each sample, let

$$y_i = \begin{cases} 1 & \text{if } x_i \in \mathcal{O} \\ -1 & \text{if } x_i \notin \mathcal{O} \end{cases}$$

• Goal: find weights w such that

$$x_i \cdot w \ge 0$$
 if $y_i = 1$
 $x_i \cdot w \le 0$ if $y_i = -1$

- Equivalently: $y_i x_i \cdot w \geq 0$. Inequality is called a <u>constraint</u>.
- Idea: We define a <u>risk function</u> R that is positive if some constraint is violated. Then we use optimization to choose w that minimizes R.
- Define the loss function

$$L(y, y_i) = \begin{cases} 0 & \text{if } y_i y \ge 0\\ -y_i y & \text{otherwise} \end{cases}$$

• Define the <u>risk function</u> (aka objective function or <u>cost function</u>)

$$R(w) = \sum_{i=1}^{n} L(x_i \cdot w, y_i) = \sum_{i \in V} -y_i \cdot x_i \cdot w$$

where $x_i \cdot w$ is our prediction, y_i is the correct classification and v is the set of indices i for which $y_i x_i \cdot w < 0$.

- If w classifies X_1, \ldots, X_n correctly, then R(w) = 0. Otherwise, R(w) > 0; we want to find a better w.
- Goal: Solve this optimization problem; Find w that minimizes R(w).