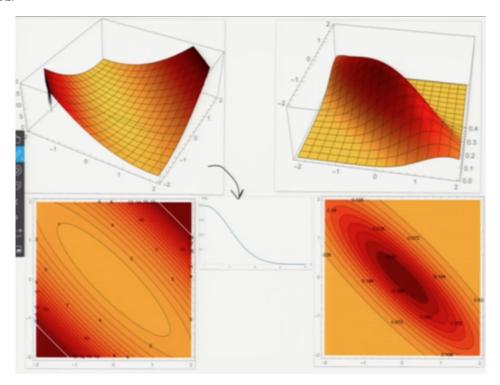
02/22/2016

Anisotropic Multivariate Gaussians

• $X \sim \mathcal{N}(\mu, \Sigma) \Leftarrow X$ is random d-vector with mean μ .

$$P(x) = \frac{1}{\sqrt{(2\pi)^d}\sqrt{|\Sigma|}} \exp(-\frac{1}{2}(x-\mu)^T \Sigma^{-1}(x-\mu))$$

- Σ is the dxd SPD <u>covariance matrix</u>
- Σ^{-1} is the dxd SPD precision matrix; serves as a metric tensor.
- Write P(x) = n(q(x)), where $q(x) = (x \mu)^T \Sigma^{-1}(x \mu)$. Note, $n : \mathbb{R} \to \mathbb{R}$, exponential, $q : \mathbb{R}^d \to \mathbb{R}$, quadratic.
- Principle: given $f: \mathbb{R} \to \mathbb{R}$, isosurfaces of f(q(x)) are same as q(x) (different isovalues), except that some might be "combined."



• Covariance:

$$Cov(X, Y) = E[(X - E[X])(Y - E[Y])^{T}]$$
$$= E[XY^{T}] - \mu_{x}\mu_{y}^{T}$$
$$Var(X) = Cov(X, X)$$

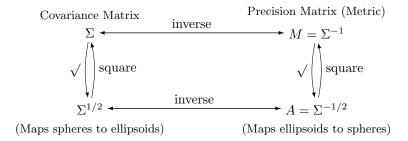
– For a Gaussian, one can show $Var(X) = \Sigma$. Hence,

$$\Sigma = \begin{bmatrix} \operatorname{Var}(X_1) & \operatorname{Cov}(X_1, X_2) & \dots & \operatorname{Cov}(X_1, X_d) \\ \operatorname{Cov}(X_2, X_1) & \operatorname{Var}(X_2) & \dots & \operatorname{Cov}(X_2, X_d) \\ \vdots & & \ddots & \vdots \\ \operatorname{Cov}(X_d, X_1) & \operatorname{Cov}(X_d, X_2) & \dots & \operatorname{Var}(X_d) \end{bmatrix}$$

- $-X_i, X_j \text{ independent} \Rightarrow \text{Cov}(X_i, X_j) = 0.$
- $Cov(X_i, X_j) = 0$ and they come from a joint normal distribution $\Rightarrow X_i, X_j$ independent.
- All features pairwise independent $\Rightarrow \Sigma$ is diagonal.

 Σ is diagonal \Leftrightarrow axis-aligned Gaussian; squared radii on the diagonal.

$$\Leftrightarrow P(x) = P(X_1)P(X_2)\dots P(X_d)$$

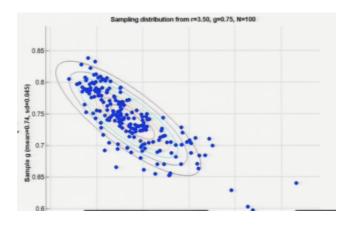


- Eigenvalues of $\Sigma^{1/2}$ are ellipsoid radii (standard deviations along the eigenvectors).
- Eigenvalues of Σ are variances along along eigenvectors.
- Diagonalizing $\Sigma = V\Lambda V^T$, $\Sigma^{\frac{1}{2}} = V\Lambda^{\frac{1}{2}}V^T$.

Maximum Likelihood estimation for anisotropic Gaussians

- Given samples x_1, \ldots, x_n and classes y_1, \ldots, y_n find the best-fit Gaussians.
- For QDA:

$$\hat{\Sigma_c} = \frac{1}{n_c} \sum_{i: y_i = c} (x_i - \mu_c) (x_i - \mu_c)^T \Leftarrow \text{conditional covariance for samples in class c}$$



- Priors π_c and means $\hat{\mu_c}$ same as before.
- $-\hat{\Sigma_c}$ is the positive semidefinite. If some zero eigenvalue, must eliminate the zero-variance dimension.
- For LDA:

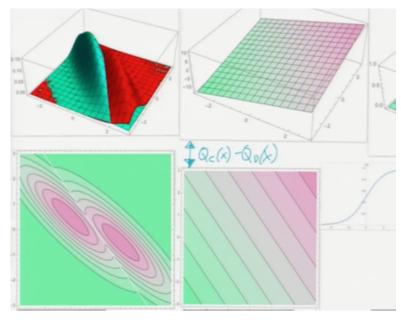
$$\hat{\Sigma} = \frac{1}{n} \sum_{c} \sum_{i:y_i = c} (x_i - \mu_c)(x_i - \mu_c)^T \iff \text{pooled within class covariance matrix}$$

• QDA:

- $-\pi_c, \mu_c, \Sigma_c$ may be different for each class c.
- Goal is to choose c that maximizes $P(X=x|Y=c)\pi_c$, which is equivalent to maximizing the quadratic discriminant function

$$Q_c(x) = \ln\left(\sqrt{(2\pi)^d}P(x)\pi_c\right)$$
$$= -\frac{1}{2}q_c(x) - \frac{1}{2}\ln|\Sigma_c| + \ln\pi_c$$

- 2 classes: Prediction function $Q_c(x) Q_d(x)$ is quadratic, but may be indefinite.
- Since the prediction function is quadratic \Rightarrow Bayes decision boundary is quadric.
- Posterior is $P(Y = c | X = x) = s(Q_c(x) Q_d(x))$ where $s(\cdot)$ is the logistic function.



• <u>LDA</u>:

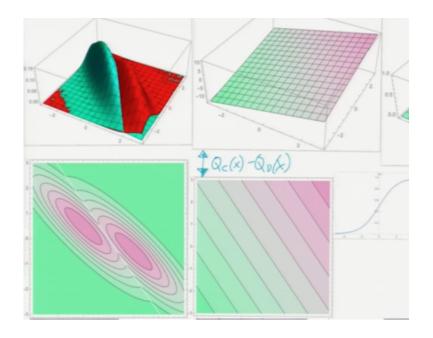
– Once Σ for all classes.

$$Q_c(x) - Q_d(x) = (\mu_c - \mu_d)^T \Sigma^{-1} x - \frac{\mu_c^T \Sigma^{-1} \mu_c - \mu_d^T \Sigma^{-1} \mu_d}{2} + \ln \pi_c - \ln \pi_d$$

- Choose class c that maximizes the <u>linear discriminant function</u>,

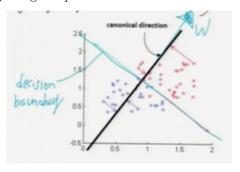
$$\mu^T \Sigma^{-1} x - \frac{1}{2} \mu_c^T \Sigma^{-1} \mu_c + \ln \pi_c$$

- 2 classes:
 - * Decision boundary is $w^Tx + \alpha = 0$
 - * Posterior is $P(Y = c|X = x) = s(w^T x + \alpha)$.



• Notes

- Changing prior π_c (or loss) is easy: if its LDA adjust $\alpha.$
- LDA is often interpreted as projecting samples onto the normal vector.



- For 2 classes,
 - * LDA has d+1 parameters (w, α) .
 - * QDA has $\frac{d(d+3)}{2} + 1$ parameters * \Rightarrow QDA more likely to overfit.

