CS 189: Introduction to Machine Learning - Discussion 5

- 1. Fun with Newton's method for root-finding
 - (a) Write down the iterative update equation of Newton's method for finding a root x: f(x) = 0 for a real-valued function f.
 - (b) Prove that if f(x) is a quadratic function $(f(x) = ax^2 + bx + c)$, then it only takes one iteration of Newton's Method to find the minimum/maximum.
- 2. Linearly Separable Data with Logistic Regression

Show (or explain) that for a linearly separable data set, the maximum likelihood solution for the logistic regression model is obtained by finding a vector β whose decision boundary $\beta^T x = 0$ separates the classes, and taking the magnitude of β to be infinity. **Note**: Remember that as mentioned in lecture, doing maximum-likelihood on logistic regression is same as minimizing cross-entropy loss (see lecture-6, slides-21,22). In lecture, we explored the cross-entropy loss-minimization perspective to logistic regression. This question will make you explore the likelihood perspective.

3. Linear Regression with Laplace prior

We saw in discussion 4 that there is a probabilistic interpretation of linear regression: $P(y|\mathbf{x}, \sigma^2) \sim \mathcal{N}(\mathbf{w^T}\mathbf{x}, \sigma^2)$. We extend this by assuming some prior distribution on parameters \mathbf{w} . Let us assume the prior is a Laplace distribution, so we have:

$$w_j \sim Laplace(0, t)$$
, i.e. $P(w_j) = \frac{1}{2t} e^{-|w_j|/t}$ and $P(\mathbf{w}) = \prod_{j=1}^D P(w_j) = (\frac{1}{2t})^D \cdot e^{-\frac{\sum |w_j|}{t}}$

Show it is equivalent to minimizing the following risk function, and find the value of the constant λ :

$$R(\mathbf{w}) = \sum_{i=1}^{n} (y^{(i)} - \mathbf{w}^T \mathbf{x}^{(i)})^2 + \lambda ||\mathbf{w}||_1, \text{ where } ||\mathbf{w}||_1 = \sum_{j=1}^{D} |w_j|$$

4. Review: Linear SVM in Higher Dimensional space (video)

Consider a data set, $X \in \mathbb{R}^{nxd}$.

Let $X_i \in \mathbb{R}^d$ be one data point, i.e. one row of X. We can create a quadratic feature vector X_i' from X_i by mapping the features:

$$x_1, x_2, ..., x_d$$
 to
$$x_1^2, x_2^2, ... x_d^2, \sqrt{2} x_1 x_2, ..., \sqrt{2} x_1 x_d, \sqrt{2} x_2 x_1, ..., \sqrt{2} x_2 x_d, ... \sqrt{2} x_{d_1} x_d.$$

For simplicity, lets consider the simple case where our data is initially two dimensional: A quadratic mapping takes x_1, x_2 to $x_1^2, x_2^2, \sqrt{2}x_1x_2$.

We can view these terms as a new feature vector, and fit a linear decision boundary in this higher, 3D space. The boundary will be linear in the features.

This can also be viewed as fitting a polynomial boundary in a (d+1) dimensional space.

The following video demonstrates this concept: https://www.youtube.com/watch?v=3liCbRZPrZA