

DD2425 - Robotics and Autonomous Systems

GROUP 6

December 13, 2014

Project Report



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Abstract

Abstract Abs

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1 Introduction

Introduction

2 Mechanical design

$$y = f(x) \tag{1}$$

Equation 1 shows that... Thrun $et\ al.\ [1]$ show that...

References

[1] S. Thrun, W. Burgard, and D. Fox. Probabilistic Robotics (Intelligent Robotics and Autonomous Agents). The MIT Press, 2005.