DD2425 - Robotics and Autonomous Systems

Group 6

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Project Report

Authors

Carlos Gálvez del Postigo
Mathias Lindblom
Tingyu Liu
Gundars Kalns

Abstract

Abstract Abstract

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Introduction

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$$y = f(x) \tag{1}$$

Equation 1 shows that...
Thrun *et al.*[1] show that...

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Motion control

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Conclusions

References

[1] S. Thrun, W. Burgard, and D. Fox. *Probabilistic Robotics (Intelligent Robotics and Autonomous Agents)*. The MIT Press, 2005.