

# DD2425 - Robotics and Autonomous Systems

#### GROUP 6

December 13, 2014

## **Project Report**



Carlos Gálvez del Postigo Mathias Lindblom Tingyu Liu Gundars Kalns



#### Abstract

Abstract Abs

## Contents

1	Introduction	<b>2</b>
2	Mechanical design	2

## 1 Introduction

My Introduction

# 2 Mechanical design

$$y = f(x) \tag{1}$$

Equation 1 shows that... Thrun  $et\ al.\ [1]$  show that...

## References

[1] S. Thrun, W. Burgard, and D. Fox. Probabilistic Robotics (Intelligent Robotics and Autonomous Agents). The MIT Press, 2005.