## APPROXIMATELY CONVEX FUNCTIONS

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In previous papers approximately linear functions [1] and approximately isometric transformations [2; 3; 4] have been studied. In both cases it was shown that the properties of linearity and isometry are "stable" in a certain sense. For example, it was proved that if a function f(x) satisfies the linear functional equation within an amount  $\epsilon$ , that is,  $|f(x+y)-f(x)-f(y)| \le \epsilon$ , then there exists an actual solution g(x) of the linear functional equation such that  $|g(x)-f(x)| \le \epsilon$ , where  $\epsilon$  is a given positive number.

In the present paper we discuss a similar problem for the property of convexity. We consider real-valued functions defined on subsets of n-dimensional Euclidean space  $E_n$ . A function f(x) defined on a convex subset S of  $E_n$  will be called  $\epsilon$ -convex if  $f(hx+(1-h)y) \leq hf(x)+(1-h)f(y)+\epsilon$ , for all x and y in S and for  $0 \leq h \leq 1$ . Here  $\epsilon$  is a fixed positive number. Our object is to show that to an  $\epsilon$ -convex function f(x) there corresponds a convex function g(x) such that  $|f(x)-g(x)| \leq k\epsilon$ , for some constant k. In order to prove this we need some results on  $\epsilon$ -convex functions and on approximating simplices given in the following four lemmas. The paper is self-contained.

LEMMA 1. Let f(x) be an  $\epsilon$ -convex function defined on an n-dimensional simplex  $S \subset E_n$ . Let the vertices of the simplex be  $p_0, p_1, \dots, p_n$ , then if  $x = \sum_{i=0}^{n} \alpha_i p_i$ ,  $\alpha_i > 0$ ,  $\sum_{i=0}^{n} \alpha_i = 1$  is any point of S, we have

(1) 
$$f(x) \leq \sum_{i=0}^{n} \alpha_{i} f(p_{i}) + 2k_{n} \epsilon,$$

where  $k_n = (n^2 + 3n)/(4n + 4)$ .

PROOF. We prove the inequality by induction on n. For n=1, (1) reduces to the statement of  $\epsilon$ -convexity, so it is true for n=1. We assume that (1) holds for n replaced by n-1, and prove it for n dimensions. The case in which some  $\alpha_i=1$  is trivial, for in this case  $x=p_i$ , so we may assume that  $\alpha_i<1$  for  $i=1, \dots, n+1$ . For convenience we may also assume that  $\alpha_n \ge \alpha_j$ ,  $j=0, \dots, n-1$ . Put  $h=1-\alpha_n$ ,  $a_j=\alpha_j/h$ ,  $j=0, \dots, n-1$ , and  $q=\sum_{j=0}^{n-1} a_j p_j$ . Then  $x=\sum_{j=0}^{n} \alpha_j p_j = hq + (1-h)p_n$ , and since f is  $\epsilon$ -convex,

(2) 
$$f(x) \leq hf(q) + (1-h)f(p_n) + \epsilon.$$

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¹ For a discussion of these and other related questions, see [6].

By the induction hypothesis,

(3) 
$$f(q) \leq \sum_{i=0}^{n-1} a_i f(p_i) + \frac{(n-1)(n+2)}{2n} \epsilon.$$

Substituting (3) into (2), we get

(4) 
$$f(x) \leq \sum_{i=0}^{n} \alpha_i f(p_i) + \left\{ 1 + \frac{h(n-1)(n+2)}{2n} \right\} \epsilon.$$

Since  $\alpha_n \ge \alpha_j$ ,  $j=0, \dots, n-1$ , the minimum value which  $\alpha_n$  can have is 1/(n+1), so the maximum value which h can have is 1-1/(n+1)=n/(n+1). Consequently an upper bound for the expression in brackets in inequality (4) is

$$1 + \frac{(n-1)(n+2)}{2(n+1)} = \frac{n^2 + 3n}{2n+2}.$$

Thus the lemma has been established.

LEMMA 2. Let f(x) be an  $\epsilon$ -convex function defined on an open convex set  $G \subset E_n$ . Then on each closed bounded subset B of G, f(x) is bounded.

PROOF. f is bounded from above, since B may be covered with a finite number of n-dimensional simplices, each contained in G, and f is bounded on each simplex by Lemma 1.

To prove that f is bounded from below on B, let B be covered with a finite number of closed spheres  $S_i$ , such that each  $S_i$  is contained in G. Let  $x_i$  be the center of  $S_i$ , and let  $x_i + y$  be any point of the sphere  $S_i$ . Then by  $\epsilon$ -convexity

$$f(x_i) \leq 2^{-1}f(x_i + y) + 2^{-1}f(x_i - y) + \epsilon$$

or

$$f(x_i + y) \ge 2f(x_i) - f(x_i - y) - 2\epsilon$$

Now  $x_i - y$  belongs to the sphere  $S_i$ , and since  $S_i$  is a closed subset of G,  $f(x_i - y)$  is bounded from above as  $x_i + y$  varies over  $S_i$ . Hence  $f(x_i + y)$  is bounded from below for  $x_i + y \in S_i$ , and it follows that f is bounded from below on B. The proof of the following two lemmas is left to the reader.

LEMMA 3. Let x lie in an n-dimensional simplex with vertices  $q_0, q_1, \dots, q_n$ , so that  $x = \sum_{i=0}^n \alpha_i q_i, \alpha_i \ge 0$ , and  $\sum_{i=0}^n \alpha_i = 1$ . Suppose also that we have n+1 sequences  $\{q_i^{(\nu)}\}$   $(i=0, \dots, n; \nu=1, 2, 3, \dots)$  of points such that  $q_i^{(\nu)} \rightarrow q_i$  as  $\nu \rightarrow \infty$ , and that for each  $\nu$ , x also lies in the n-dimensional simplex with vertices  $q_i^{(\nu)}$  so that

$$x = \sum_{i=0}^{n} \alpha_i^{(\nu)} q_i^{(\nu)},$$

where  $\alpha_i^{(\nu)} \geq 0$  and  $\sum_{i=0}^n \alpha_i^{(\nu)} = 1$ . Then as  $\nu \to \infty$ ,  $\alpha_i^{(\nu)} \to \alpha_i$ .

LEMMA 4. Suppose x is interior to an n-dimensional simplex in  $E_n$  whose vertices are  $q_0$ ,  $q_1$ ,  $\cdots$ ,  $q_n$ . Then if  $q_i^{(\nu)} \rightarrow q_i$  in  $E_n$  as  $\nu \rightarrow \infty$   $(i=0, \cdots, n)$ , x is also interior to the simplex  $S_n^{(\nu)}$  whose vertices are  $q_i^{(\nu)}$   $(i=0, \cdots, n)$ , for sufficiently large n.

THEOREM 1. Let f(x) be  $\epsilon$ -convex on an open convex set  $G \subset E_n$ , and let B be any closed bounded convex subset of G. Then there exists a convex function  $\phi(x)$  on B such that

$$|\phi(x) - f(x)| \leq k_n \epsilon,$$
 for  $x \in B$ ,

where  $k_n = (n^2 + 3n)/(4n + 4)$ .

PROOF. Let H be a bounded convex open subset of G such that  $B \subset H$ , and  $\overline{H} \subset G$ . Since B is a compact subset of the open convex set G, the existence of such an H is easily shown. Let K denote the convex hull of the closure of the graph of the function f(x) for  $x \in \overline{H}$ , so that K is a convex set in  $E_{n+1}$ .

Define, for  $x = (x_1, \dots, x_n) \in \overline{H}$ ,  $g(x) = \inf [y; (x_1, x_2, \dots, x_n, y) \in K]$ . Since f(x) is bounded on  $\overline{H}$  by Lemma 2, K is a compact set in  $E_{n+1}$  and g(x) is well defined on  $\overline{H}$ . It is easily seen that g(x) is a convex function, and that  $g(x) \leq f(x)$  for  $x \in H$ . Given a point  $x \in B$ , let p denote the point  $(x_1, x_2, \dots, x_n, g(x))$  in  $E_{n+1}$ . Now p evidently belongs to the boundary of K, and since K is closed, it also belongs to K. By a well known theorem, p lies on an p-dimensional simplex p whose vertices are points or limit points of the graph of p for p where p where p were in the interior of an p and p simplex with vertices in p would lie in the interior of p and not on its boundary.

There are three possible cases.

- (i) p is a point of the graph of f.
- (ii) p is a limit point of the graph of f.
- (iii) p is "interior" to some simplex S whose dimension is positive and less than or equal to m, and whose vertices are points or limit points of the graph of f.

In case (i), f(x) = g(x), and there is nothing to prove. In case (ii)

<sup>&</sup>lt;sup>2</sup> See [5, p. 9].

<sup>&</sup>lt;sup>3</sup> A point will be called "interior" to a simplex S of dimension r if it belongs to S but not to any face of lower dimension than r.

it is convenient to translate the axes so that the origin of coordinates lies at the point x so that x=0. Then by hypothesis there exists a sequence of distinct points  $x^{(\mu)} \in H \subset E_n$  tending to zero such that  $\lim_{\mu \to \infty} f(x^{(\mu)}) = g(0)$ . It is clear that an infinite number of these points must all lie in some one of the  $2^n$ -tants determined by the coordinate hyperplanes. For definiteness, let us assume the first  $2^n$ -tant contains an infinite number of these points. We denote them by  $x^{(\nu)}$ , so that all the coordinates of each  $x^{(\nu)}$  may be assumed to be non-negative. Now choose on each coordinate axis a point  $p_j$  whose jth coordinate is negative, the others being zero,  $j=1, 2, \cdots, n$ , such that  $p_j \in H$ . Consider the simplex  $S^{(\nu)}$  whose vertices are  $p_1, p_2, \cdots, p_n$  and  $x^{(\nu)}$ . Then the origin belongs to this simplex, and there exist  $\alpha_i^{(\nu)}$ ,  $i=1, \cdots, n+1$ , such that

(5) 
$$\sum_{i=1}^{n} \alpha_{i}^{(\nu)} p_{i} + \alpha_{n+1}^{(\nu)} x^{(\nu)} = 0,$$

where  $\alpha_j^{(\nu)} \ge 0$ ,  $\alpha_{n+1}^{(\nu)} > 0$ , and  $\sum_{i=1}^{n+1} \alpha_i^{(\nu)} = 1$ .

To prove this, let  $p_{jj}$  be the jth coordinate of the point  $p_j$  and let  $x_j^{(r)}$  be the jth coordinate of the point  $x^{(r)}$ . Then the "vector" equation (5) may be written in the form:

(6) 
$$\alpha_{j}^{(r)} p_{jj} + \alpha_{n+1}^{(r)} x_{j}^{(r)} = 0, \qquad j = 1, \dots, n,$$

where  $p_{jj} < 0$ , and  $x_j^{(\nu)} \ge 0$ . Since  $x_j^{(\nu)} \ne 0$ , at least one of the  $x_j^{(\nu)}$  must be positive. If  $x_j^{(\nu)} = 0$ , choose  $\alpha_j^{(\nu)} = \rho_j^{(\nu)} = 0$ . If  $x_j^{(\nu)} \ne 0$  equation (6) determines the ratio  $\rho_j^{(\nu)} = \alpha_j^{(\nu)}/\alpha_{n+1}^{(\nu)}$ , which in this case is evidently positive. The value of  $\alpha_{n+1}^{(\nu)}$  is then determined by the requirement that  $\sum_{i=1}^{n+1} \alpha_i^{(\nu)} = (1 + \sum_{j=1}^{n} \rho_j^{(\nu)})\alpha_{n+1}^{(\nu)} = 1$ . Thus relation (6) is established. By Lemma 1, it follows that

(7) 
$$f(0) \leq \sum_{i=1}^{n} \alpha_{i}^{(r)} f(p_{i}) + \alpha_{n+1}^{(r)} f(x^{(r)}) + 2k_{n}\epsilon.$$

Now as  $v \to \infty$ ,  $x^{(v)} \to 0$ . Hence by (6),  $\alpha_j^{(v)} \to 0$  for  $j = 1, \dots, n$ . It follows that  $\alpha_{n+1}^{(v)} \to 1$ . Since  $f(x^{(v)}) \to g(0)$ , we have  $f(0) \leq g(0) + 2k_n \epsilon$ , or  $f(x) \leq g(x) + 2k_n \epsilon$ .

We now turn to case (iii). Here p lies in the interior of an r-dimensional simplex  $S_r$   $(1 \le r \le n)$  whose vertices  $p_i$   $(i=0, 1, \dots, r)$  are points or limit points of the graph of f.

Let  $\pi$  be a supporting hyperplane of  $K \subset E_{n+1}$  through the point p. Now p is interior to at least one line segment  $S_1$  belonging to  $S_r$  and hence to K. Any such line segment  $S_1$  must lie in the hyperplane  $\pi$ , for otherwise  $S_1$  would pierce the hyperplane  $\pi$  at p so that part of  $S_1$  would lie on one side of  $\pi$  and part on the other, which is impossible since all of K lies on one side of  $\pi$ . It follows that  $S_r$ , and hence its vertices  $p_i$ , lies in  $\pi$ , and the  $p_i$  are boundary points of K.

This supporting hyperplane  $\pi$  cannot be perpendicular to  $E_n$ , for in this case  $\pi$  would project (orthogonally) into a hyperplane in  $E_n$  which would be a supporting hyperplane of the projection of the convex set K and which would contain the point x. Thus x would be on the boundary of the projection of K. But the projection of K includes the open set K which by hypothesis contains K, so K cannot lie on the boundary of K0 projection, and we have a contradiction.

Therefore the projection of  $S_r$  onto  $E_n$  is a simplex  $\Sigma_r$  of the same dimension r, and the interior of  $S_r$  projects into the interior of  $\Sigma_r$ , so that the point x which is the projection of p lies in the interior of  $\Sigma_r$ .

We use double subscripts to denote the coordinates of the vertices  $p_i$  of  $S_r$ , and we denote the projections of these vertices onto  $E_n$  by  $q_0, q_1, \dots, q_r$ . Then by hypothesis there exist sequences  $q_i^{(\nu)}$  such that  $p_{i,n+1} = \lim_{r \to \infty} f(q_i^{(\nu)})$ , where  $\lim_{r \to \infty} q_i^{(\nu)} = q_i$ , and  $q_0, \dots, q_r$  are the vertices of the r-dimensional simplex  $\Sigma_r \subset E_n$ , which contains the point x in its interior. Our object is to construct a simplex  $S_n^{(\nu)}$  of dimension n in  $E_n$  such that x is interior to  $S_n^{(\nu)}$ , and such that r of its vertices are points  $q_0^{(\nu)}, \dots, q_r^{(\nu)}$ . We can then apply Lemma 1 to this simplex and take the limit in the resulting inequality as  $r \to \infty$ .

Suppose first that r=n. In this case, x is interior to the n-dimensional simplex  $\Sigma_n \subset E_n$ , so that

$$x = \sum_{i=0}^{n} \alpha_i q_i, \qquad \alpha_i > 0, \qquad \sum_{i=0}^{n} \alpha_i = 1.$$

Since  $q_i^{(\nu)} \to q_i$  in  $E_n$  as  $\nu \to \infty$ , it follows by Lemma 4 that  $x = \sum_{i=0}^n \alpha_i^{(\nu)} q_i^{(\nu)}$ ,  $\alpha_i^{(\nu)} > 0$ ,  $\sum_{i=0}^n \alpha_i^{(\nu)} = 1$ . Hence by Lemma 3,  $\alpha_i^{(\nu)} \to \alpha_i$  as  $\nu \to \infty$ .

Now by Lemma 1, we have  $f(x) \leq \sum_{i=0}^{n} \alpha_i^{(\nu)} f(q_i^{(\nu)}) + 2k_n \epsilon$ . By taking limits as  $\nu \to \infty$  we get

$$f(x) \leq \sum_{i=0}^{n} \alpha_{i} p_{i,n+1} + 2k_{n} \epsilon = g(x) + 2k_{n} \epsilon.$$

Now let us suppose that  $1 \le r \le n$ . Let  $F_r$  be the r-dimensional flat containing  $\Sigma_r$ . Now if for all but a finite number of  $\nu$ 's, the  $q_i^{(\nu)}$ ,  $i=0, \dots, n; \nu=1, 2, 3, \dots$ , are contained in  $F_r$ , then  $q_i^{(\nu)} \rightarrow q_i$  in  $F_r$  and one has essentially case (iiia) with r replacing n, so the proof follows as before.

Next suppose that an infinity of points  $q_i^{(\nu)}$  for some i lie outside this flat. We may as well assume (by relabeling and suppressing a subsequence if necessary) that all of the  $q_0^{(\nu)}$  lie outside  $F_r$ .

Let us choose a new coordinate system with origin at  $q_0$  and with the first r axes belonging to  $F_r$ , so that the equations of  $F_r$  are  $z_j = 0$ , j = r + 1,  $\cdots$ , n. The last n - r coordinates  $q_{0,r+1}^{(\nu)}$ ,  $\cdots$ ,  $q_{0,n}^{(\nu)}$  of the point  $q_0^{(\nu)}$  cannot all be zero for any  $\nu$ . It follows that for some fixed j,  $q_{0,r+1}^{(\nu)} \neq 0$ , for all  $\nu$ . We may without loss of generality assume that  $q_{0,r+1}^{(\nu)} \neq 0$ , for all  $\nu$ . Now there must be an infinity of the numbers  $q_{0,r+1}^{(\nu)}$  which are either all positive or all negative, and by reversing the (r+1)st coordinate axis if necessary, we may assume that  $q_{0,r+1}^{(\nu)} > 0$  for all  $\nu$ .

Next, if r+1 < n, we consider  $q_{0,r+2}^{(r)}$ . If  $q_{0,r+2}^{(r)} = 0$  for all but a finite number of  $\nu$ 's, we rotate the  $z_{r+1}$  and  $z_{r+2}$  axes through an acute angle, keeping all of the other axes fixed, in such a way that after the rotation  $q_{0,r+1}^{(r)}$  will still be positive and  $q_{0,r+2}^{(r)}$  will become positive for all but a finite number of  $\nu$ 's.

On the other hand if  $q_{0,r+2}^{(r)} \neq 0$  for an infinite number of  $\nu$ 's, then for an infinite number of  $\nu$ 's, these numbers are all positive or all negative. By reversing the  $z_{r+2}$ -axis if necessary we have  $q_{0,r+2}^{(r)} > 0$  for an infinite number of  $\nu$ 's. Thus by suppressing a subsequence if necessary we can arrange matters so that  $q_{0,r+1}^{(r)} > 0$  and  $q_{0,r+2}^{(r)} > 0$  for all  $\nu$ .

If r+2 < n, we proceed in the same way, with r+1 replacing r, and so on. Thus, there will exist a coordinate system in  $E_n$  and sequences of points  $q_i^{(r)} \rightarrow q_i$   $(i=0, 1, \dots, r)$  such that the origin lies at the point  $q_0$ , and  $q_{i,j}=0$ ,  $q_{0,j}^{(r)}>0$  for  $j=r+1, \dots, n$ , where  $f(q_i^{(r)}) \rightarrow p_{i,n+1}$ ,  $x = \sum_{i=0}^r \alpha_i q_i$ ,  $g(x) = \sum_{i=0}^r \alpha_i p_{i,n+1}$ ,  $\sum_{i=0}^r \alpha_i = 1$ ,  $\alpha_i > 0$ .

Now let  $q_i$   $(i=r+1, \dots, n)$  be a point in H whose (r+1)st coordinate is a negative number and whose other coordinates are all zero. We now show that x is interior to the n-dimensional simplex whose vertices are  $q_0^{(r)}$ ,  $q_1$ ,  $q_2$ ,  $\cdots$ ,  $q_n$ , for sufficiently large  $\nu$ .

Thus we must show the existence of positive numbers  $\beta_i$   $(i=0,\dots,n)$  with  $\sum_{i=0}^{n} \beta_i = 1$  such that  $x = \sum_{i=0}^{r} \alpha_i q_i = \beta_0 q_0^{(r)} + \sum_{i=0}^{n} \beta_i q_i$ . That is, the  $\beta_i$  are to satisfy the following system of n+1 linear equations:

(8) 
$$\beta_{0}q_{0,j}^{(r)} + \sum_{i=0}^{r} \beta_{i}q_{i,j} = \sum_{i=0}^{r} \alpha_{i}q_{i,j} \qquad (j = 1, \dots, r),$$

$$\beta_{0}q_{0,j}^{(r)} + \beta_{j}q_{i,j} = 0 \qquad (j = r + 1, \dots, n),$$

$$\sum_{i=0}^{n+1} \beta_{i} = 1.$$

Since  $\alpha_i > 0$ ,  $\sum_{i=0}^{r} \alpha_i = 1$ , and  $q_{0,j}^{(r)} \rightarrow q_{0,j} = 0$ , it follows that for  $0 < \beta_0 < 1$  there will exist a  $\nu_0$ , independent of  $\beta_0$ , such that the first r equations of the system (8) have solutions for  $\beta_i$ ,  $i=1, \dots, r$ , which are between zero and one, whenever  $\nu \ge \nu_0$ . Since  $q_{i,j}$  and  $q_{0,j}^{(\nu)}$  are of opposite signs by construction for  $j=r+1, \dots, n$ , it is clear that the next n-r equations will also have solutions  $\beta_i$ ,  $j=r+1, \dots, n$ , which are between zero and one when  $\beta_0$  is, and when  $\nu$  is sufficiently large. With the help of the last equation all the  $\beta$ 's may be determined, with  $0 < \beta_i < 1$ ,  $i=0, \dots, n$ .

Next, for a given  $\nu$ , so large that x is interior to the simplex with vertices  $q_0^{\nu}$ ,  $q_1$ ,  $\cdots$ ,  $q_n$ , there will exist by Lemma 4 an index  $\mu = \mu(\nu)$  such that x is also interior to the simplex with vertices  $q_0^{\nu}$ ,  $q_1^{\mu}$ ,  $q_2^{\mu}$ ,  $\cdots$ ,  $q_r^{\mu}$ ,  $q_{r+1}$ ,  $\cdots$ ,  $q_n$ . Let one such index  $\mu$  be determined for each  $\nu$  and put  $\bar{q}_i^{\nu} = q_i^{\mu(\nu)}$ ,  $i = 1, \cdots, r$ . For convenience we also put  $\bar{q}_0^{\nu} = q_0^{\nu}$ . Then there exist  $\alpha_i > 0$ , i = 0,  $1, \cdots, n$ , such that  $\sum_{i=0}^{n} \alpha_i^{\nu} = 1$  and  $x = \sum_{i=0}^{r} \alpha_i q_i = \sum_{i=0}^{r} \alpha_i^{\nu} \bar{q}_i^{\nu} + \sum_{i=r+1}^{n} \alpha_i q_i$ . By Lemma 1 we have

$$f(x) \leq \sum_{i=0}^{r} \alpha_{i} f(\bar{q}_{i}) + \sum_{i=r+1}^{n} \alpha_{i} f(q_{i}) + 2k_{n} \epsilon.$$

Now as  $\nu \to \infty$ ,  $\bar{q}_i^{\nu} \to q_i$ ,  $f(\bar{q}_i^{\nu}) \to p_{i,n+1}$ , and, by Lemma 3, we know that  $\alpha_i^{\nu} \to \alpha_i$  for  $i = 0, 1, \dots, r$ , while  $\alpha_j^{\nu} \to 0$ ,  $j = r+1, \dots, n$ . Hence by letting  $\nu \to \infty$  in the last inequality we get

$$f(x) \leq \sum_{i=0}^{r} \alpha_{i} p_{i,n+1} + 2k_{n} \epsilon = g(x) + 2k_{n} \epsilon.$$

We have proved that for any point  $x \in B$ ,  $g(x) \le f(x) \le g(x) + 2k_n \epsilon$ , where g(x) is a convex function. Now define  $\phi(x) = g(x) + k_n \epsilon$ . Then  $\phi(x)$  is convex and

$$|\phi(x) - f(x)| \le k_n \epsilon$$
 for  $x \in B$ .

This completes the proof of theorem 1.

THEOREM 2. If f(x) is an  $\epsilon$ -convex function defined on a convex open subset of G of  $E_n$ , then there exists a convex function  $\phi(x)$  defined on G such that  $|f(x) - \phi(x)| \le k_n \epsilon$ .

PROOF. Let  $H_{\mathfrak{p}}, \nu = 1, 2, 3, \cdots$ , be a sequence of convex, compact subsets of G such that  $H_{\mathfrak{p}+1} \subset H_{\mathfrak{p}}$  and such that  $G = \bigcup_{\mathfrak{p}=1}^{\infty} H_{\mathfrak{p}}$  (the existence of such a sequence is easily demonstrated). Then by Theorem 1, there exists for each  $\nu$  a convex function  $\phi_{\mathfrak{p}}(x)$  on  $H_{\mathfrak{p}}$  such that  $|\phi_{\mathfrak{p}}(x) - f(x)| \leq k_{\mathfrak{p}} \epsilon$ , for  $x \in H_{\mathfrak{p}}$ . For each fixed positive integer  $\mu$ , the function f(x) is bounded on  $H_{\mu}$  by Lemma 2. Hence the sequence  $\{\phi_{\mathfrak{p}}(x)\}$  is defined and uniformly bounded on  $H_{\mu}$  for  $\nu \geq \mu$ . By a well

known selection theorem there exists a subsequence  $\{\phi_{1p}(x)\}$  of the  $\phi_r(x)$  which converges for all  $x \in H_1$ . Similarly there is a subsequence  $\{\phi_{2p}(x)\}$  of the  $\phi_{1p}(x)$  which is defined and convergent on  $H_2$ , and so on. Now consider the sequence  $\{\phi_{pp}(x)\}$ ,  $p=1, 2, 3, \cdots$ . For any given  $x \in G$ , there exists a positive integer m so that  $x \in H_m$ . Hence for  $p \ge m$ , the sequence  $\{\phi_{pp}(x)\}$  is defined and converges to a limit  $\phi(x)$ . Thus g(x) is defined, is convex, and satisfies the inequality  $|\phi(x) - f(x)| \le k_n \epsilon$  for  $x \in G$ .

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