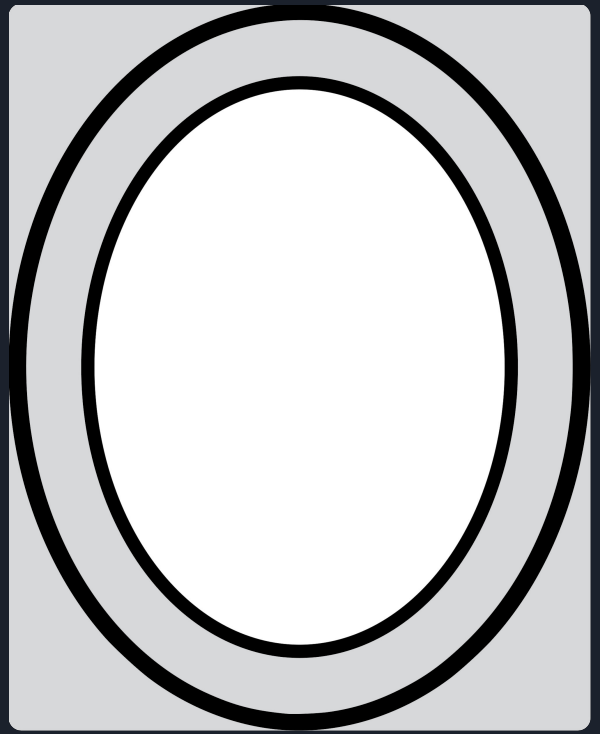
Práctica Final. Diseño de Controladores Borrosos y Neuroborrosos para un Robot Móvil

Ana Cortés Cercadillo
Carlos Javier Hellín Asensio

Parte 1. Control borroso. Entorno sin obstáculos.



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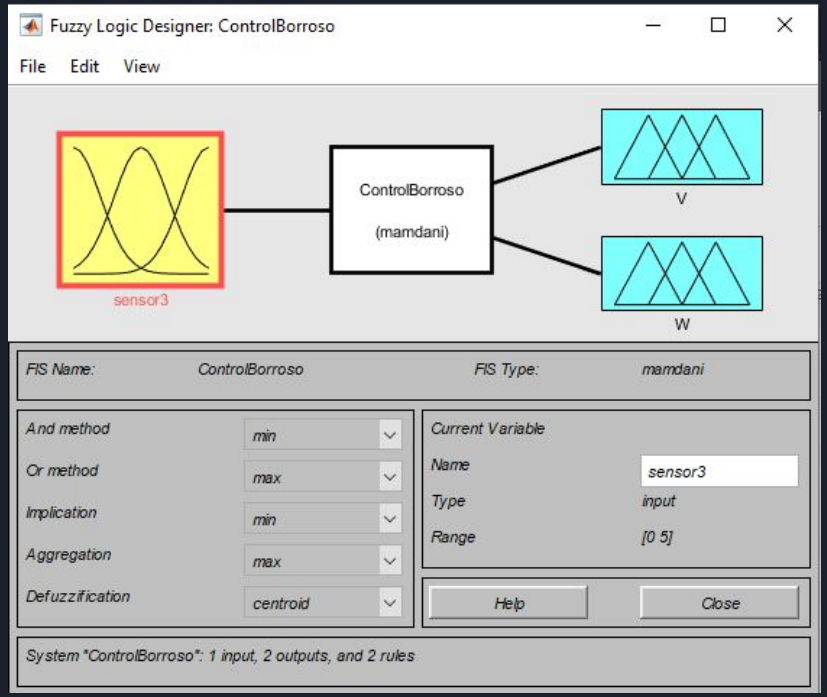

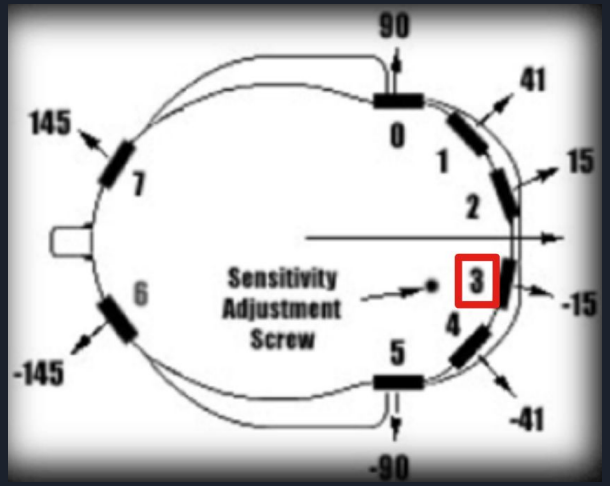

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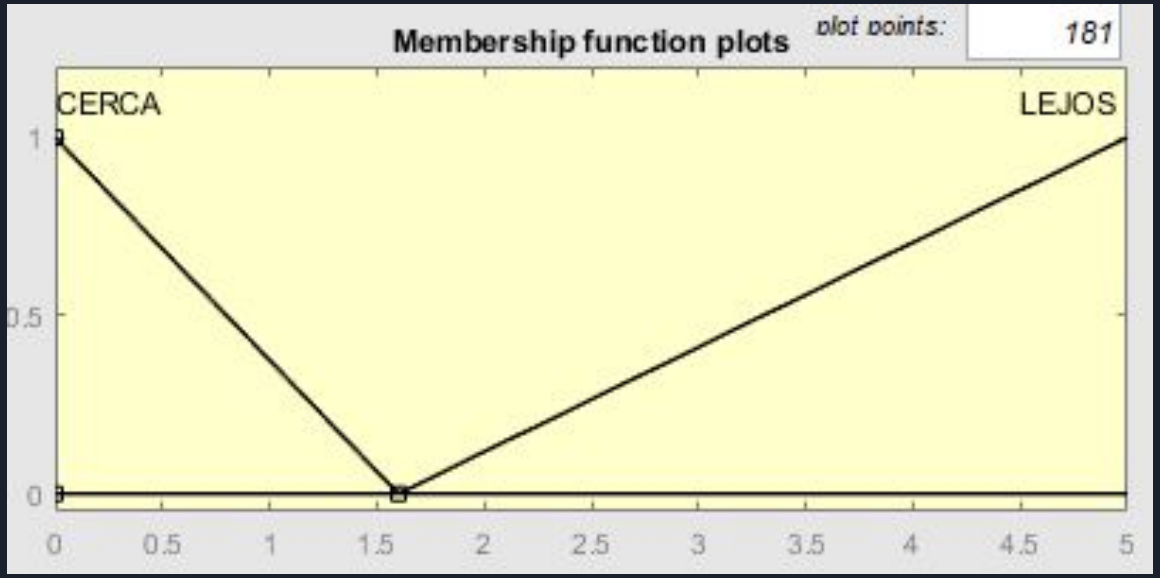
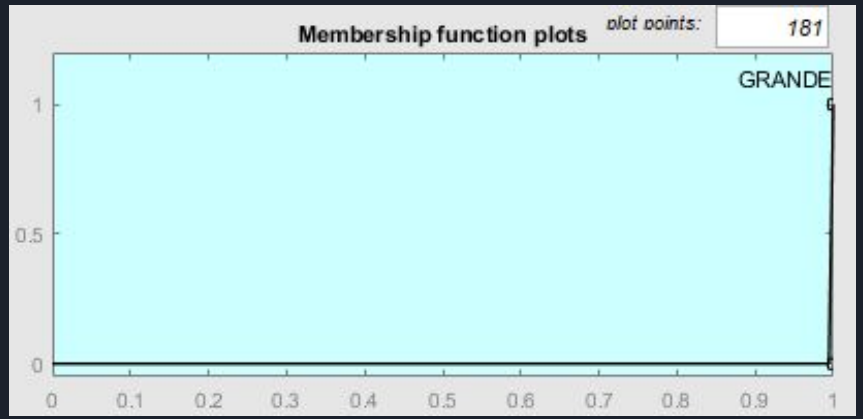
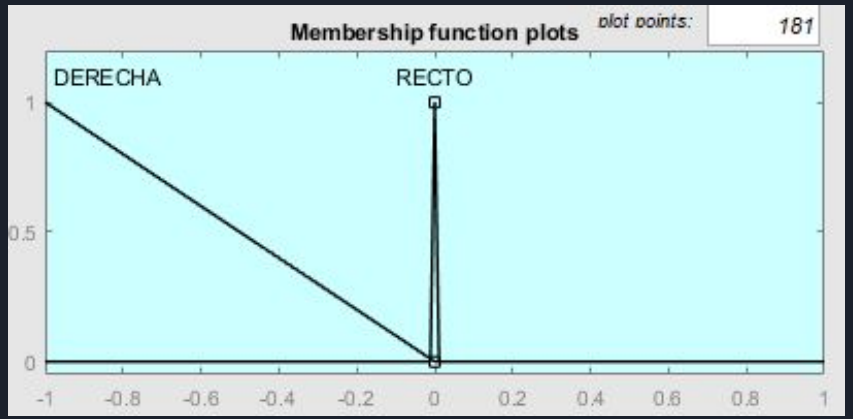


sensor3

Parte 1. Control borroso. Entorno sin obstáculos.



V



W

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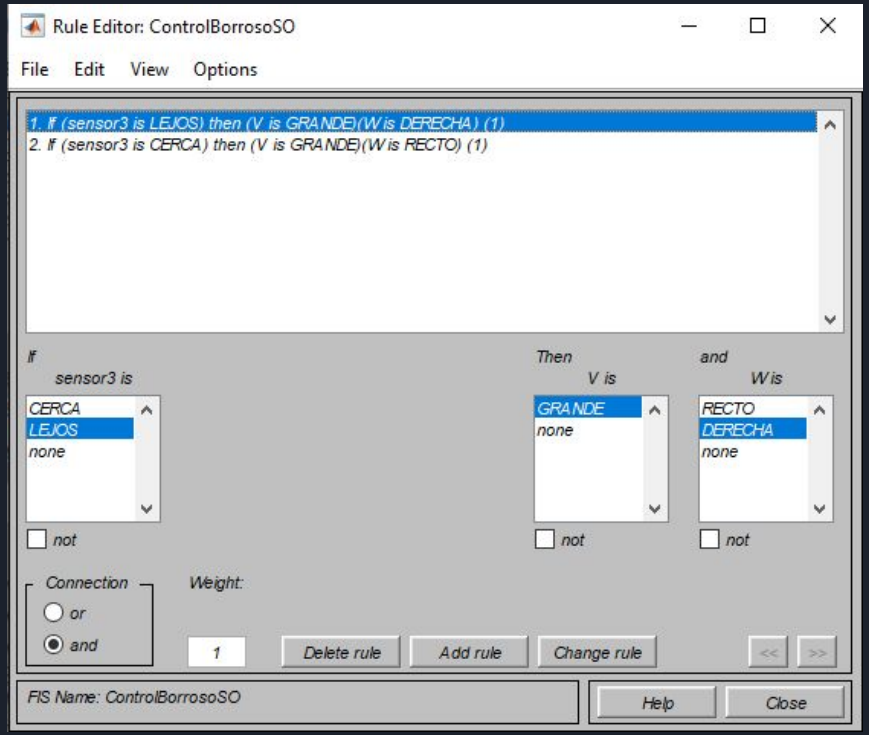

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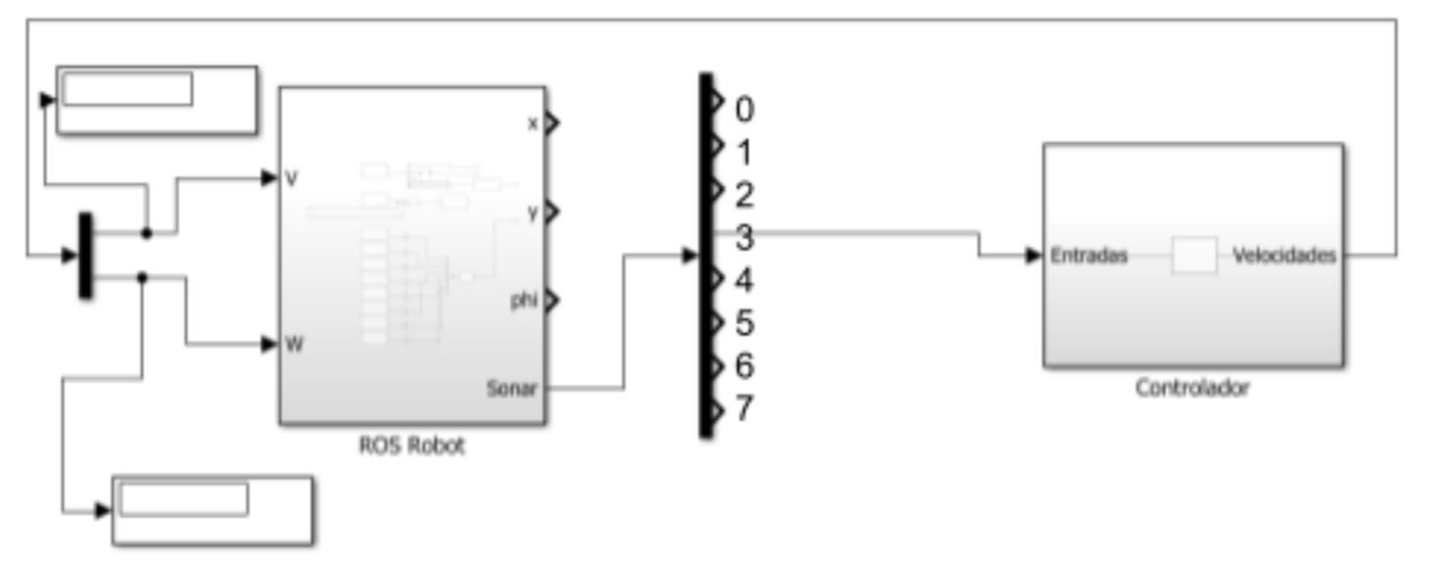

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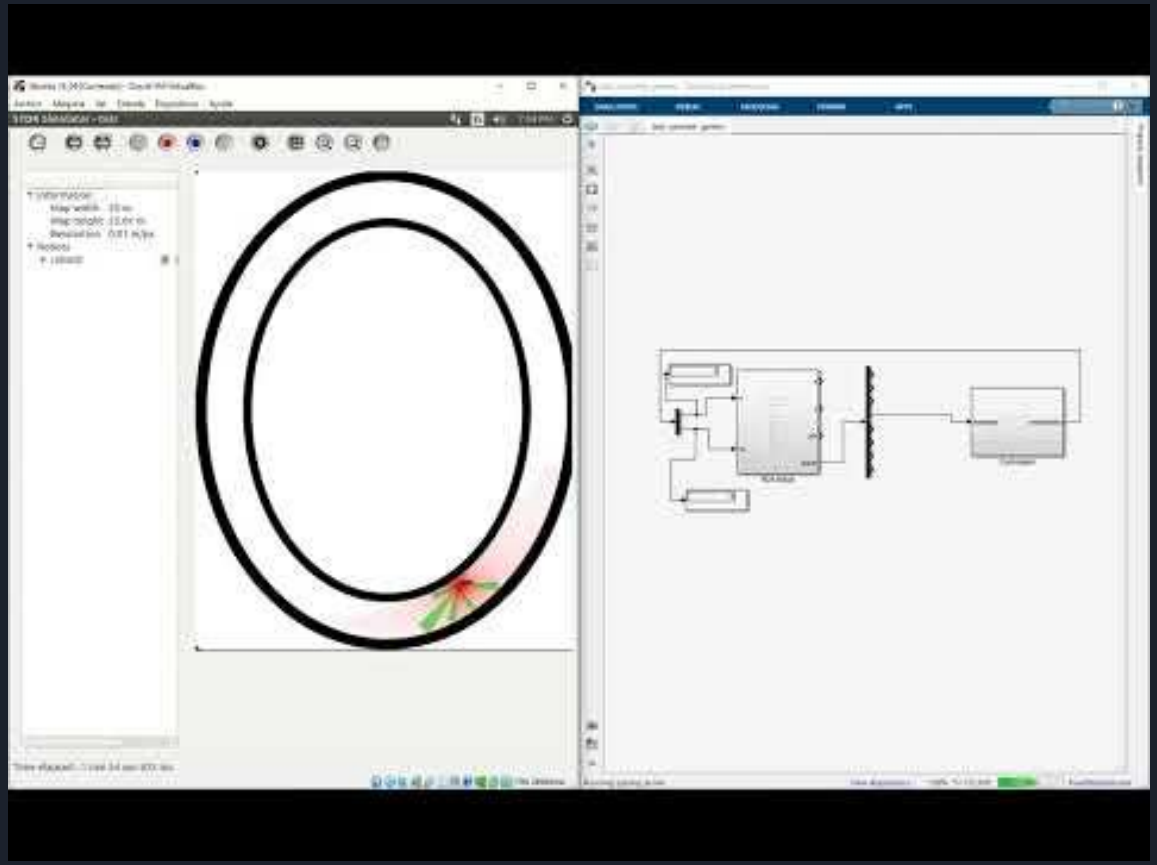

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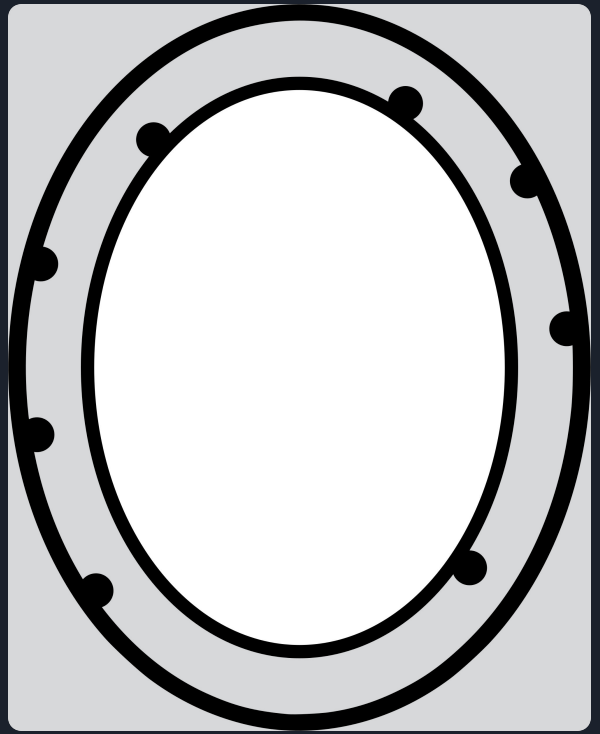

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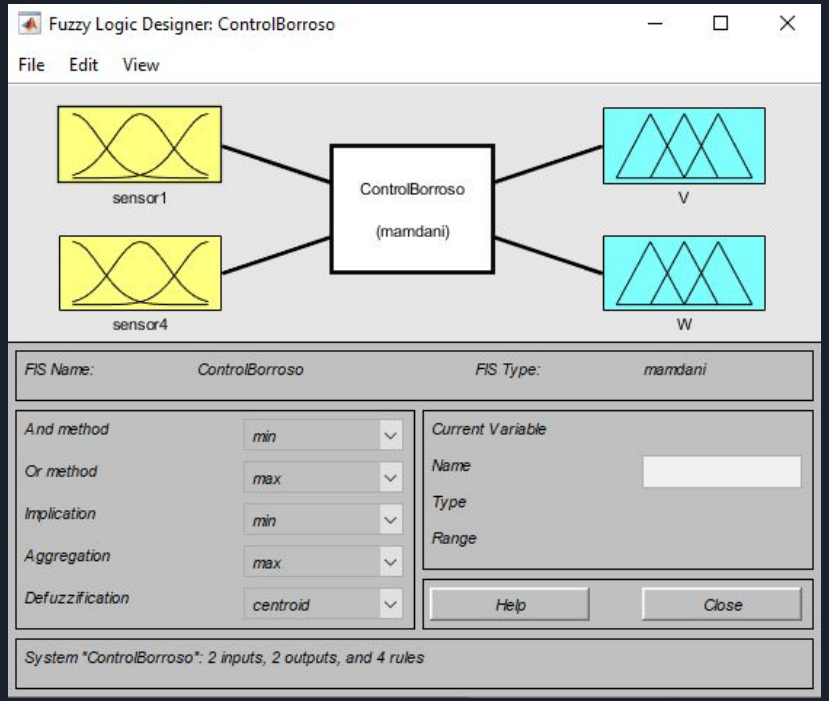

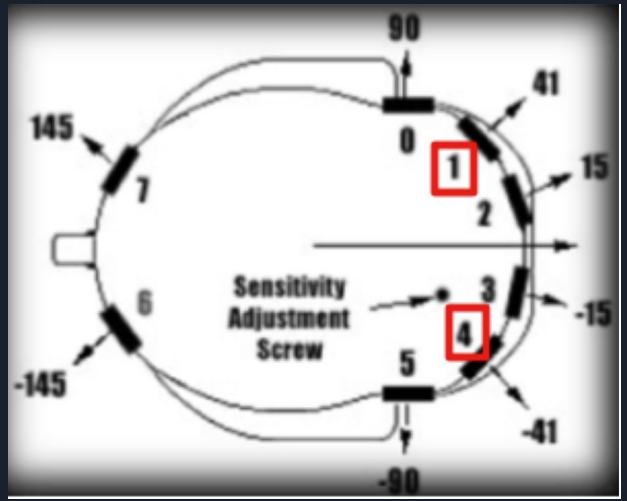

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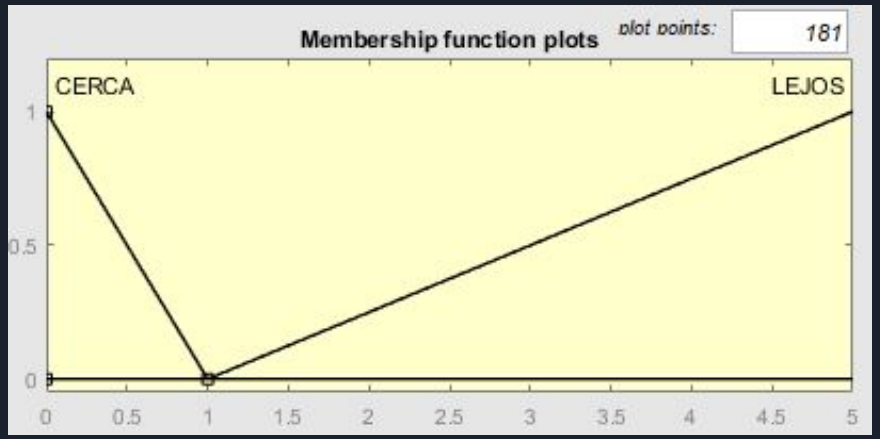
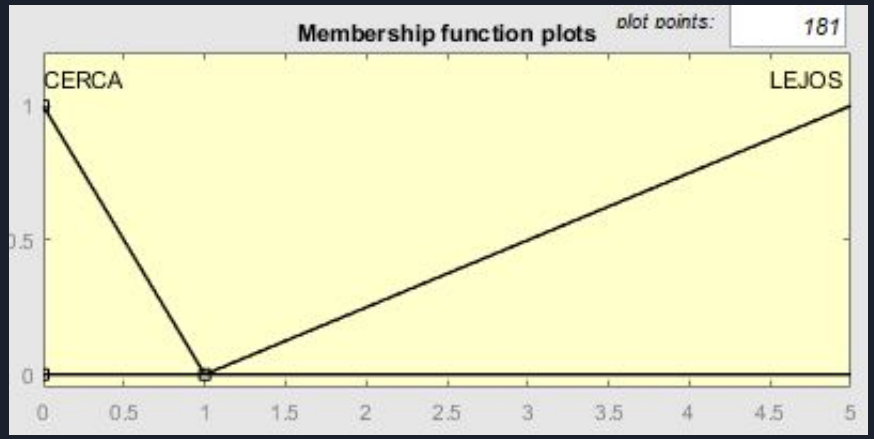
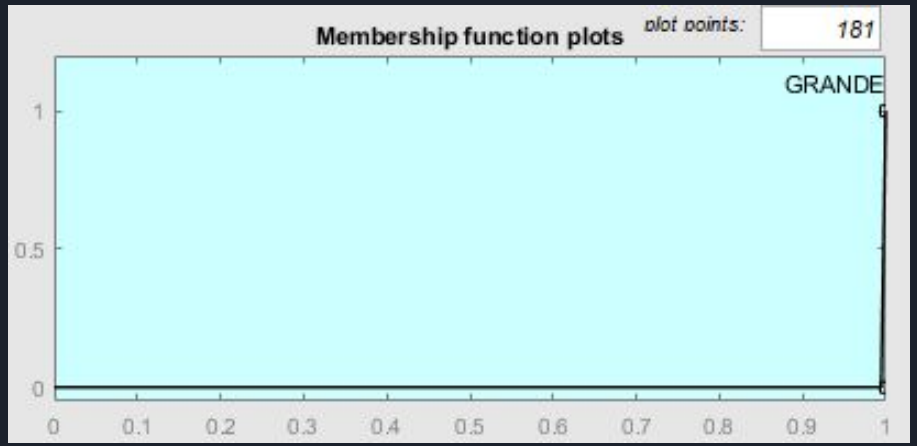


sensor1

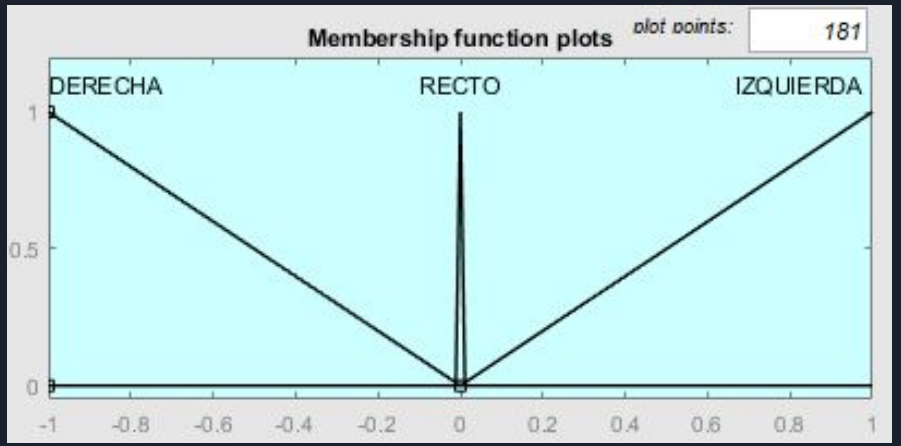


sensor4

Parte 1. Control borroso. Entorno con obstáculos.



V



W

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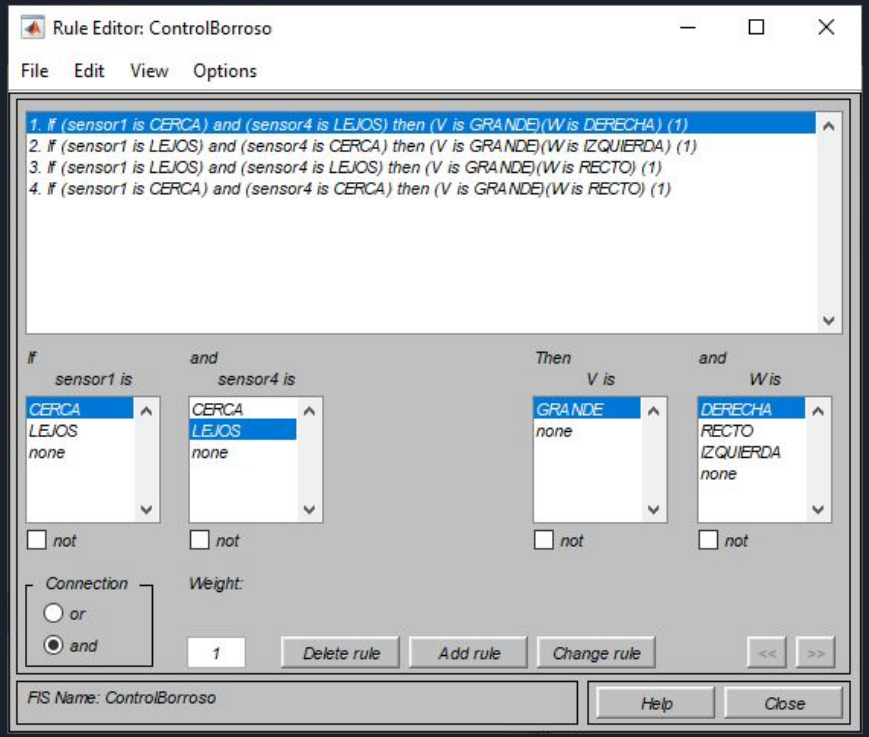

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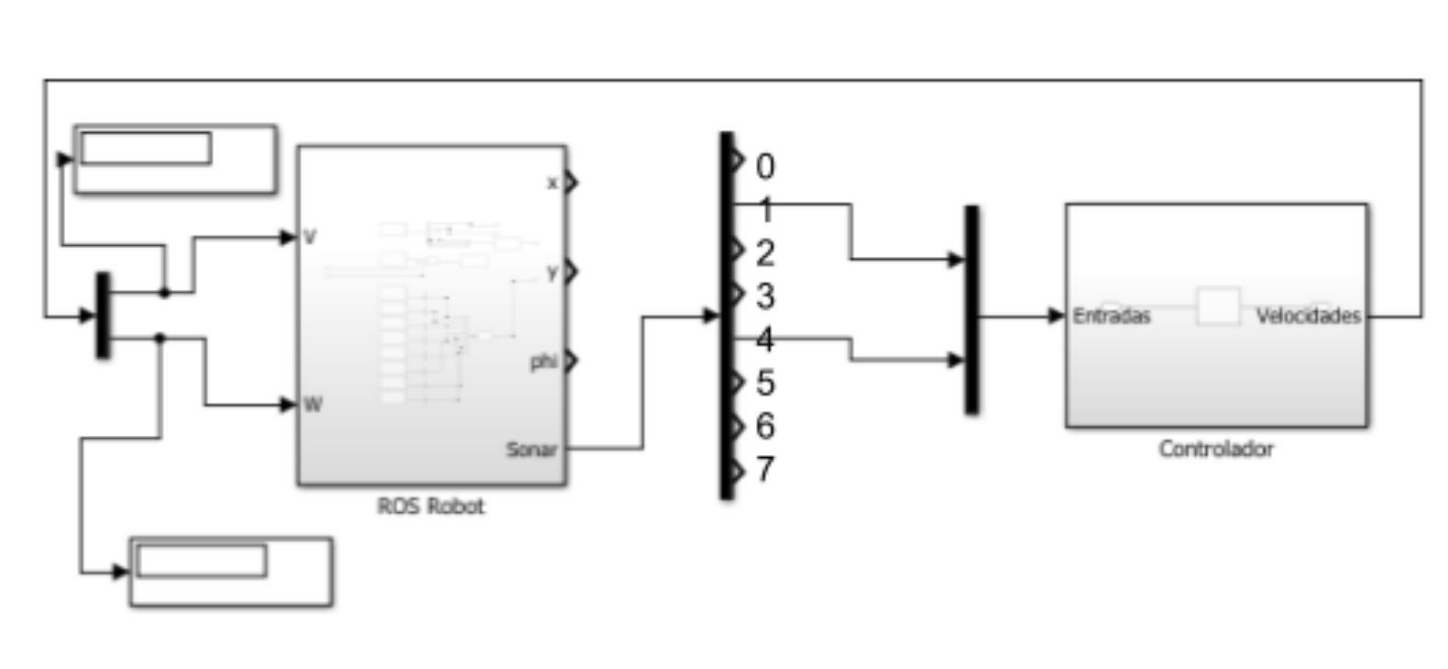

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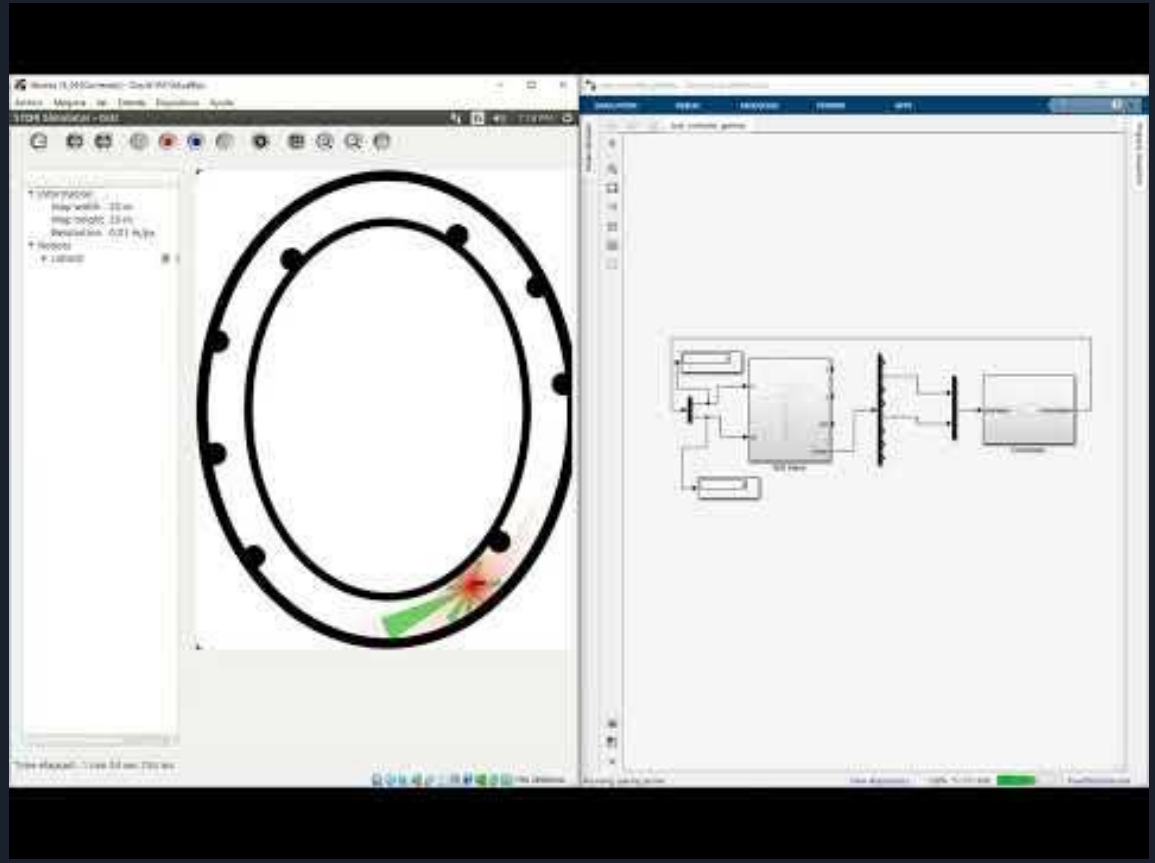


Parte 2. Controlador Neuroborroso. Entorno sin obstáculos.

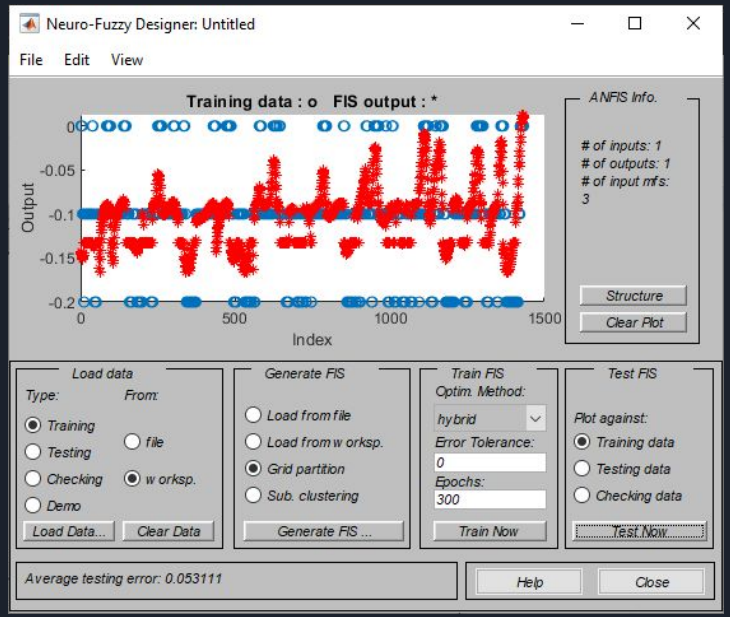
Train_angular.m

```
train_angular = training(:,[4,12])
indices = round(linspace(1,size(training,1),1500))
train_angular = train_angular(indices,:)
train_angular(isinf(train_angular)) = 5.0
train_angular = double(train_angular)
```

Train_lineal.m

```
train_lineal = training(:,[4,13])
indices = round(linspace(1,size(training,1),1500))
train_lineal = train_lineal(indices,:)
train_lineal(isinf(train_lineal)) = 5.0
train_lineal = double(train_lineal)
```

Parte 2. Controlador Neuroborroso. Entorno sin obstáculos.



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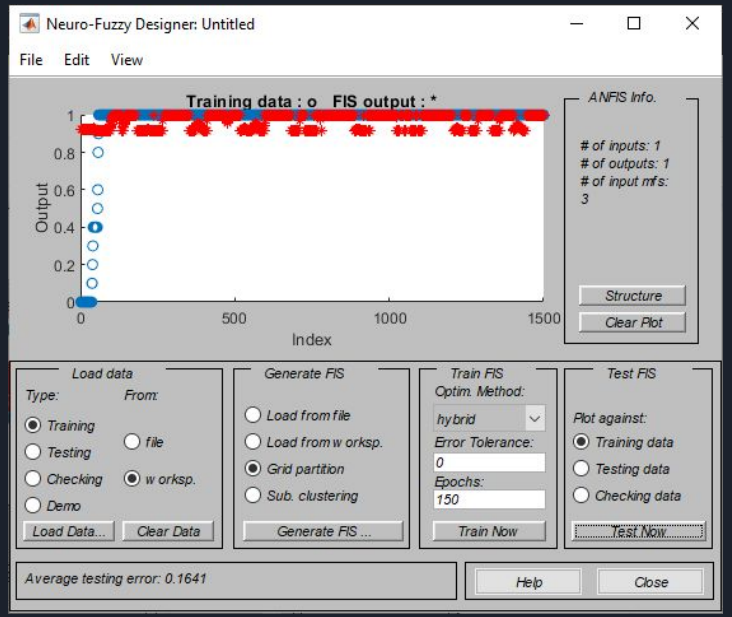

V

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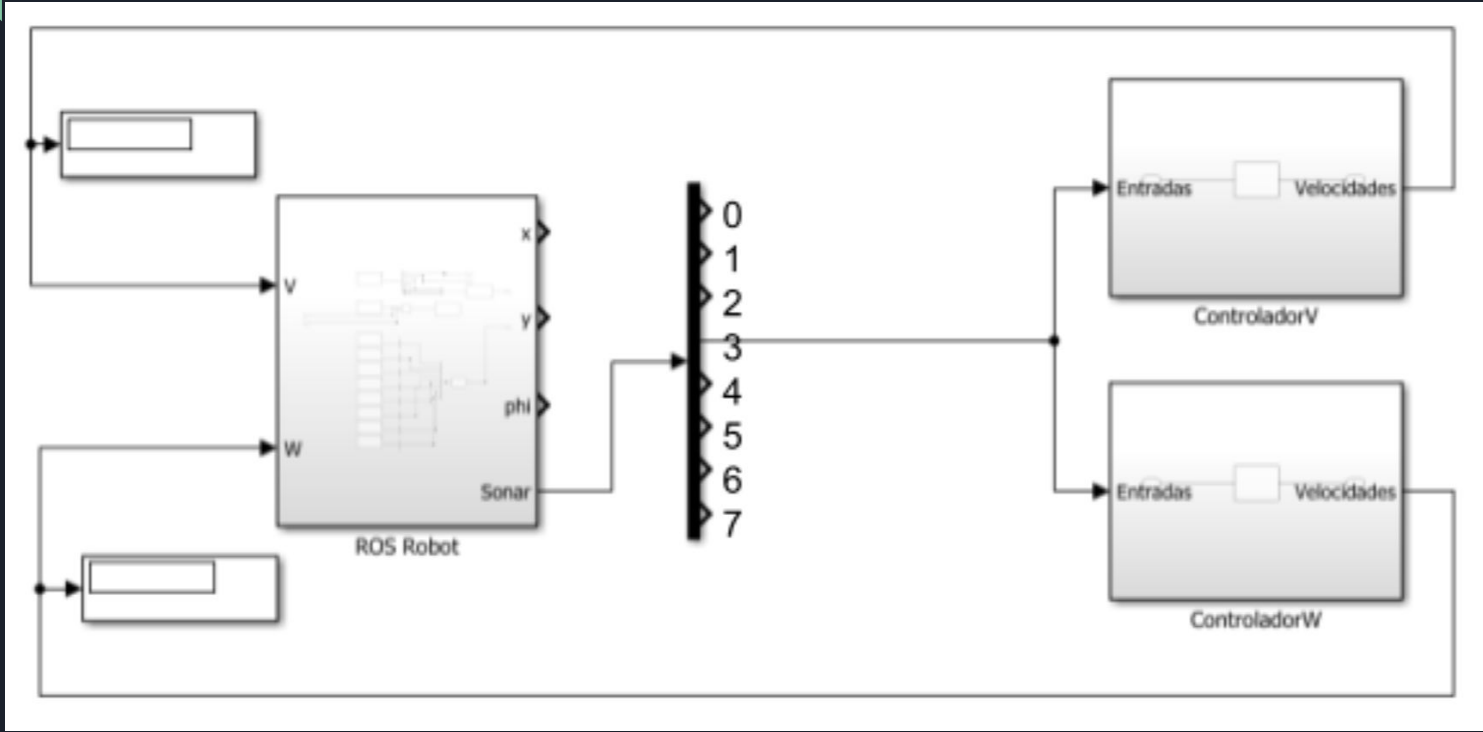

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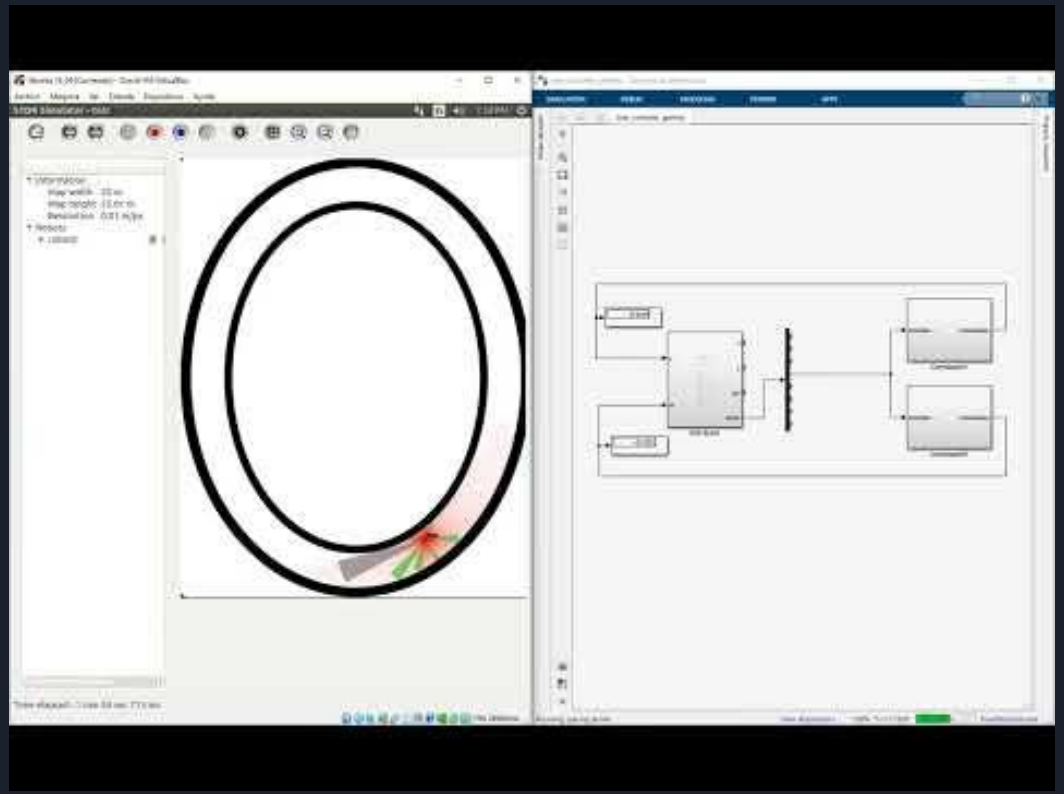


Parte 2. Controlador Neuroborroso. Entorno con obstáculos.

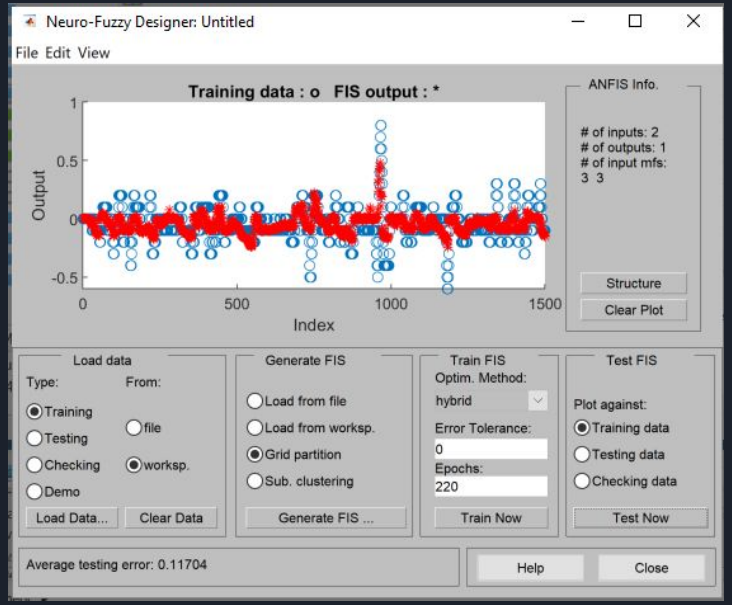
Train_angular.m

```
1 -    train_angular = training(:,[3,4,12])
2 -    indices = round(linspace(1,size(training,1),1500))
3 -    train_angular = train_angular(indices,:)
4 -    train_angular(isinf(train_angular)) = 5.0
5 -    train_angular = double(train_angular)
```

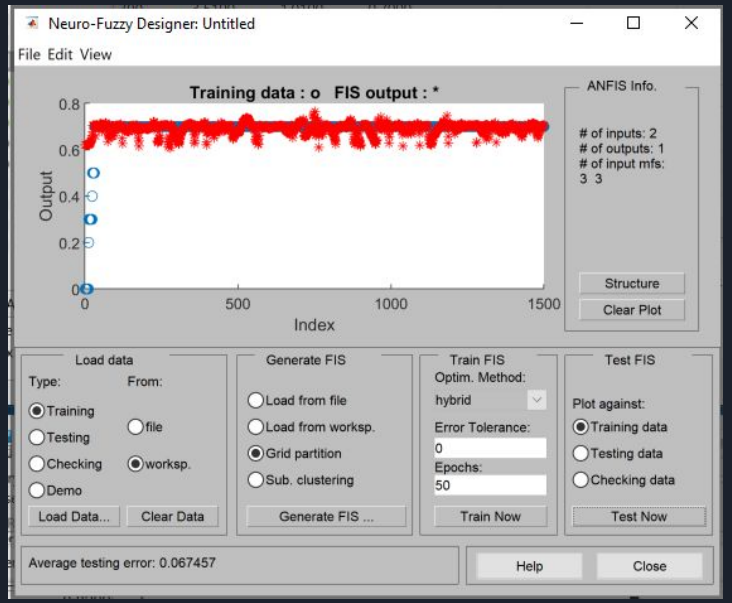
Train_lineal.m

```
1 -    train_lineal = training(:,[3,4,13])
2 -    indices = round(linspace(1,size(training,1),1500))
3 -    train_lineal = train_lineal(indices,:)
4 -    train_lineal(isinf(train_lineal)) = 5.0
5 -    train_lineal = double(train_lineal)
```

Parte 2. Controlador Neuroborroso. Entorno con obstáculos.



W



V

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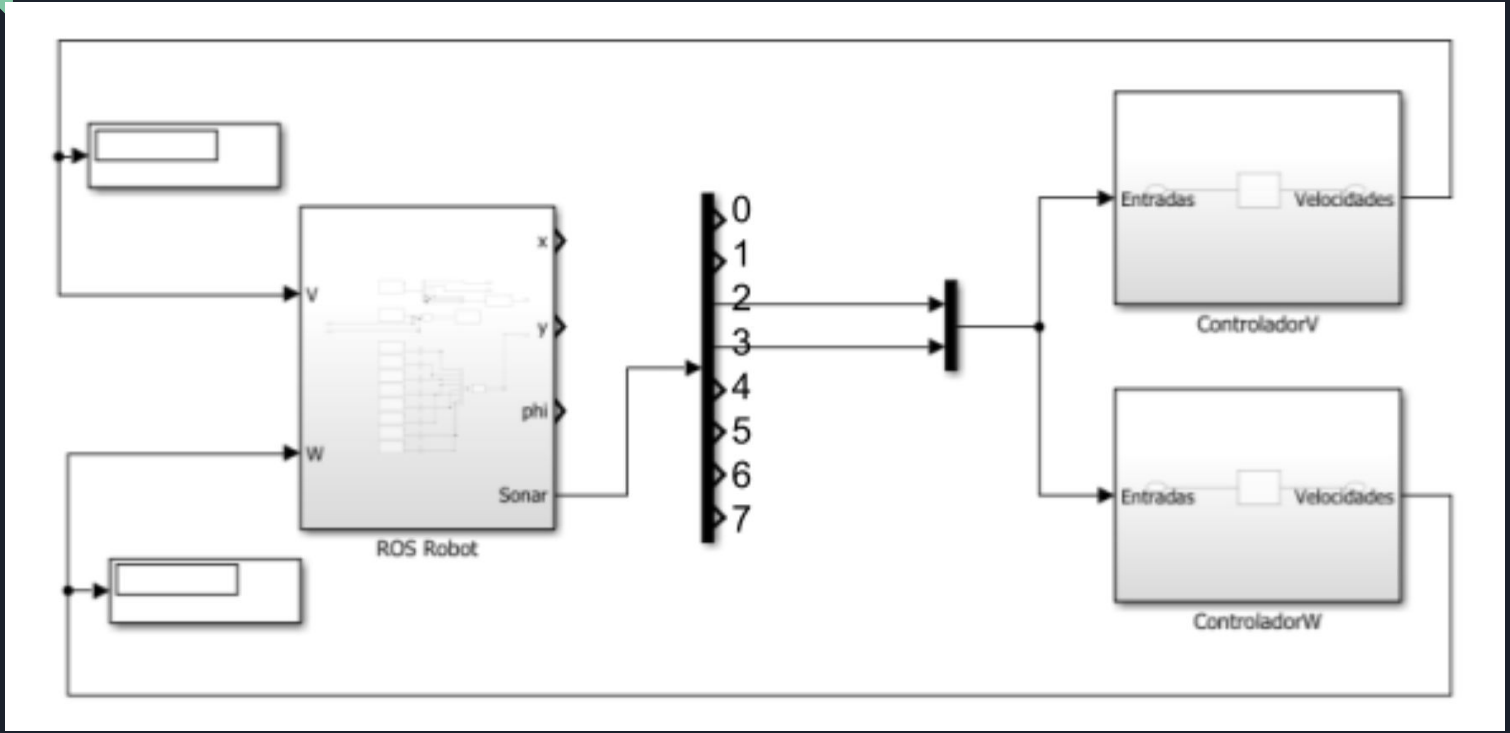

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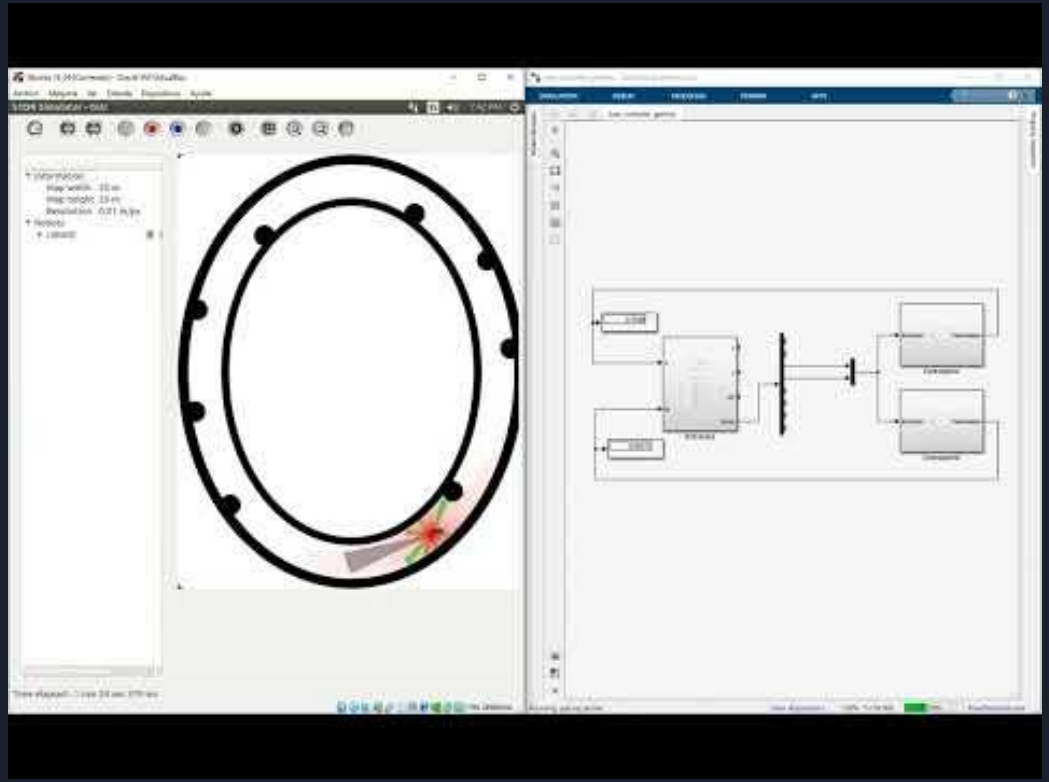

¡¡Gracias por todo!!