| Task name | Start date | End date | Duration (months) | 2016 | | 20 | | 2018 | | | | | | | | 2019 | | | | | |
|--|------------|----------|----------------------|-----------------|--|--------------------------|------------------------|--------------|--------------------------|---------------------|---------------|--------------------|--------------------|----------------------|------------------|-------------------|-----------------|---------------------|-------------------|------------|---------|
| | | | | 01 Sep | 01 Jan | 01 Apr | 01 Jul | 0. | 1 Oct | 01 Jan | | 01 Apr | 01 Jul | | 01 Oct | 01 Ja | an | 01 Apr | | 01 Jul | 01 Oct |
| | | | | Sep Oct Nov Dec | Jan Feb Mar | Apr May Jun | Jul Aug Se | p Oct I | Nov Dec Jai | n Feb Ma | ar Apr | May Jun | Jul Aug | Sep Oct | Nov Dec | Jan Feb | o Mar | Apr May | Jun Jul | Aug Sep | Oct Nov |
| → Doctoral Program in Informatics Engineering | | | | | | | | | | | | | | | | | | | | | |
| Human-robot cooperative assembly with semantic learning by demonstration | 01/10/16 | 01/10/19 | 36 | | Human-robot cooperative assembly with semantic learning by demonstration | | | | | | | | | | | | | | | | |
| 1 Use cases definition | 01/10/16 | 01/11/16 | 1 | Use cases defin | ition | | | | | | | | | | | | | | | | |
| 2 Review of state of the art | 01/11/16 | 01/12/16 | 1 | Review | of state of the art | | | | | | | | | | | | | | | | |
| 3 Evaluation and selection (| 01/12/16 | 01/02/17 | 2 | | Setup of testing | g platforms | | | | | | | | | | | | | | | |
| 4 Creation of perception and learning datasets | 01/02/17 | 01/04/17 | 2 | | | Creation of perception a | d learning datasets | | | | | | | | | | | | | | |
| 5 Definition of software architecture | 01/04/17 | 01/07/17 | 3 | | | | Definition of software | architecture | | | | | | | | | | | | | |
| 6 Knowledge / skill representation | 01/07/17 | 01/10/17 | 3 | | | | | Know led | ge / skill representatio | n | | | | | | | | | | | |
| 7 Extraction of assembly knowledge from Standard Operating Procedures | 01/10/17 | 01/01/18 | 3 | | | | | | Ex | traction of assembl | ly know ledge | from Standard O | perating Procedure | es | | | | | | | |
| 8 Assembly operations from structured knowledge / assembly skills | 01/01/18 | 01/04/18 | 3 | | | | | | | | Assemb | bly operations fro | om structured knov | v ledge / assembly s | kills | | | | | | |
| 9 Learning of new assembly operations from human demonstration | 01/04/18 | 01/09/18 | 5 | | | | | | | | | | | Learning of nev | assembly oper | ations from human | n demonstration | on | | | |
| 10 Immersive human-robot cooperation using projection mapping | 01/09/18 | 01/11/18 | 2 | | | | | | | | | | | | Immersive hu | man-robot coopera | ation using pr | ojection mapping | | | |
| 11 Validation of assembly system in industrial conditions | 01/11/18 | 01/03/19 | 4 | | | | | | | | | | | | | | Validat | ion of assembly sys | tem in industrial | conditions | |
| 12 Writing of articles and thesis | 01/03/19 | 01/10/19 | 7 | | | | | | | | | | | | | | | Writing of ar | ticles and the | sis | |
| | | | | | | | | | | | Milestone | - Assembly opera | ations from skills | | Milestone - Coop | erative assembly | | | | | |