

Time	<div>Session I</div> <div>Smart Sensors & Robotics</div> <div>Session Chair: Rui Sarmento</div>	
9.30 — 11.00 h	Rui Pinto	Robot Self-Localization Based on Sensor Fusion of GPS and iBeacons Measurements
	Valter Costa	Real-time Vision Techniques applied on Autonomous Driving
	Luís Neto	Optimizing Network Calls by Minimizing Variance in Data Availability Times
	Carlos Costa	Recognition of Banknotes in Multiple Perspectives Using Selective Feature Matching and Shape Analysis <div>Room B032</div>