Digital Communications

Digital Communications Problem Set

Team:

Finck BIG!

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Course: TDC1

Instructor: Glenn Berger

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Problem #1

Determine the impulse response h(t) corresponding to H(f).

a)
$$H(f) = \frac{1 - e^{-j2\pi f T}}{j \partial \pi f}$$

· To get to a point where the inverse transform can be taken, we first manipulate the equation into an Euler format:

$$H(f) = \frac{e^{-j\pi fT} \left[\frac{e^{j\pi fT} - e^{-j\pi fT}}{j^2} \right]}{known sine transform of the Euler equation!}$$

$$H(f) = e^{-j\pi fT} \times \frac{\sin(\pi fT)}{\pi f} \times \frac{T}{T}$$

$$\frac{\sin x}{x} = \sin(x)$$

$$\Rightarrow \text{ substitute!}$$

$$H(\omega) = \left[e^{-j\omega\frac{T}{2}}\right] T sinc\left(\frac{\omega T}{2}\right) \begin{cases} 0 & \text{x(t-t_0)} \iff \text{x(}\omega\text{)}e^{-j\omega t_0} \end{cases}$$

$$\text{(a)} rect\left(\frac{-7}{2}, \frac{7}{2}\right) \iff T sinc\left(\frac{\omega T}{2}\right)$$

:
$$H(\omega) \iff h(t) = rect(-T/2, T/2) \text{ shifted by } + T/2!$$

$$h(t) = u(t + T/2 - (T/2)) - u(t - T/2 - (T/2))$$

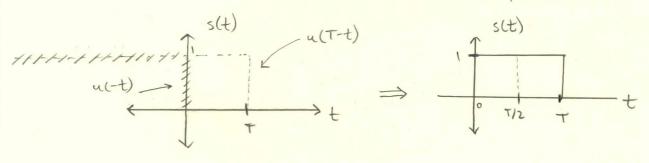
$$h(t) = u(t) - u(t - T)$$

b) To find the signal s(t), simply invert variables knowing the reflective relationship:

$$h(t) = s(T-t) \rightarrow s(t) = h(T-t)$$

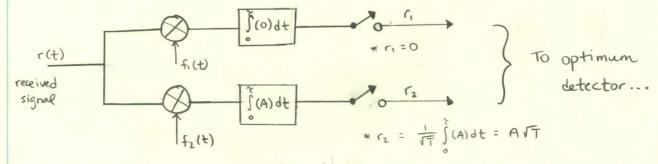
:
$$s(t) = u((T-t) + T/2 - (T/2)) - u((T-t) - T/2 - (T/2))$$

 $s(t) = u(T-t) - u(-t)$ Shift, Scale, Reflect.



Problem #2

- a) Determine block diagram of the demodulator and optimum detector...
- so (t) =0, 0 \left \(\pm T \) \ We first begin by deriving the s, (t) = A, 0 \left \(\pm T \) \ block diagram of the demodulator:



· the basis functions mimic a filter with the

*
$$f_m(t) = \begin{cases} \frac{1}{\sqrt{T}}, & 0 < range(t) < T \end{cases}$$
 of $m = 1, 2$
of otherwise $n = \#$ of dimensions $= 2$

· We are given that the power spectral density is $\frac{N_0}{2}$. Given the formula:

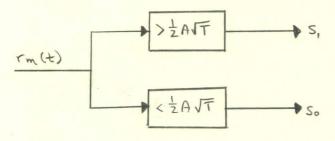
$$P(r|s_m) = \frac{1}{(\pi N_o)^{N/2}} \exp \left[-\sum_{k=1}^{N} \frac{(r_k - s_{mk})^2}{N_o} \right], \quad N=1 \text{ since we have}$$
one noise channel.

· Computing the p(rlsm) for each signal yields the following results:

$$p(r|s_0) = \frac{1}{\sqrt{\pi}N_0} e^{-\frac{r^2}{N_0}}$$

$$p(r|s_1) = \frac{1}{\sqrt{\pi}N_0} e^{-\frac{r^2}{N_0}} e^{-\frac{r^2}{N_0}}$$

- Since we know that these signals are equally probable and that $\Sigma(r_1+r_2) = AVT$, it must be the case that the probability = $\frac{1}{2}AVT$
- we can now construct our optimum detector diagram as follows:



Optimal threshold = 1 AVT

b) Given that the probabilities of error are the same, we can see that:

· Knowing that P(elsi) = _ op(rlsi) dr ... we substitute using probability expressions in part a).

 $P(e) = \frac{1}{2} \int P(r|s_0) + \frac{1}{2} \int P(r|s_1)$ These regions are opposite those of our optimum detector, indicating that these are errors. Substitute.

 $P(e) = \frac{1}{2} \int \frac{1}{\sqrt{\pi N_o}} e^{-\frac{r^2}{N_o}} dr + \frac{1}{2} \int \frac{1}{\sqrt{\pi N_o}} e^{-\frac{(r-A\sqrt{T})^2}{N_o}} dr$ when want to make these resemble gaussian PDF's.

Perform variable

Perform variable

 $\begin{array}{ll} \text{A} \rightarrow \text{Set } r = \frac{X}{\sqrt{\frac{2}{N_o}}} \\ \text{Then } dr = dx \left(\frac{1}{\sqrt{\frac{2}{N_o}}}\right) \end{array} \begin{array}{ll} \text{Rut lower bound in terms} \\ \text{of } x \text{; substitute bound for } r \text{ 8 solve for 8;} \\ \frac{1}{2} \text{A} \sqrt{1} = \frac{X}{\sqrt{\frac{2}{N_o}}} \Rightarrow x = \frac{1}{2} \text{A} \sqrt{1} \sqrt{\frac{2}{N_o}} \end{array}$

B \rightarrow Set $r = \frac{x}{\sqrt{2}} + A\sqrt{T}$ Rut upper bound in terms of x; substitute bound for r and solve for x:

Then $dr = dx \left(\frac{1}{\sqrt{2}} \right)$ $\frac{1}{2}A\sqrt{T} = \frac{x}{\sqrt{2}} - A\sqrt{T} \Rightarrow x = -\frac{1}{2}A\sqrt{T}\sqrt{\frac{2}{N_0}}$ Rewrite integral: P(e) = \frac{1}{2} \int_{\text{TINO}} e^{-\frac{x^2}{2}} dx + \frac{1}{2} \int_{\text{TINO}} e^{-\frac{x^2}{2}} dx

~ Through gaussian integration (WIKIPEDIA + NOTES), the expression simplifies:

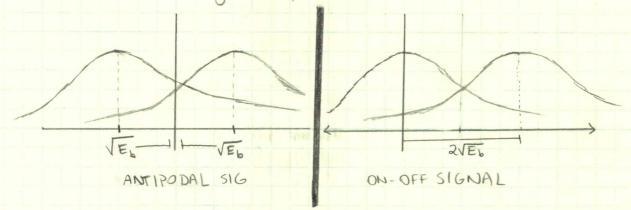
& $P(e) = Q \left[\frac{1}{2}\sqrt{\frac{2}{N_o}}A^{T}\right] \xrightarrow{\text{Also seen in slide 50 of notes}} P(e) = Q \left[\frac{1}{2}\sqrt{\frac{2}{N_o}}A^{T}\right] = Q \left[\sqrt{\frac{2}{2}}\sqrt{\frac{2}{N_o}}\right] = Q \left[\sqrt{\frac{2}{N_o}}\right] = Q \left[\sqrt{\frac{2}$

To write in terms of SNR, equate first and second expressions:

$$\frac{1}{2}\sqrt{\frac{2}{N_0}} \text{ AVT} = \sqrt{\text{SNR}_0} \implies \boxed{\text{SNR} = \frac{A^2T}{2N_0}}$$

3

Looking at the difference between the on-off switching and the antipodal signal representations:



⇒ As seen through the graphs & based on the calculated SNR, we see that on-off signaling requires 2× more energy to achieve the same error performance as antipodal signaling.

* on-OFF requires 2x more E than artipodal *



$$S_1(t) = \begin{cases} 1, & 0 \le t \le T \\ 0, & \text{otherwise} \end{cases}$$

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$$S_2(t) = -S_3(t) = \begin{cases} 1, & 0 \le t \le \frac{1}{2}T \end{cases}$$

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$$S_3(t) = \begin{cases} 1, & 0 \le t \le$$

3.)
A) since $s_2(t) = -s_3(t)$, the dimensionality will be z.

$$f_1(t) = \begin{cases} f & 0 \le t \le T \\ 0 & \text{otherwise} \end{cases}$$

$$f_1(t) = \begin{cases} f_1(t) = f_2(t) = -f_3(t) = f_3(t) = f_3(t)$$

$$m_1 = [IT, 0]$$

$$m_1 = [JT, 0]$$
 $m_2 = [0, JT]$ $m_3 = [0, -JT]$

$$m_{2}(0, \sqrt{T})$$
 $m_{1}(\sqrt{T}, 0)$
 $m_{3}(0, -\sqrt{T})$

3D) Given our orthonormal basis, our output will add noise components in both dimensions. The three outputs are:

$$(JT + n_1, n_2)$$

 $(n_1, JT + n_2)$
 $(n_1, -JT + n_2)$

$$\frac{R_{1}/R_{3} \text{ boundary}}{\int (JT + n_{1})^{2} + (n_{2})^{2}} = \int (n_{1})^{2} + (-JT + n_{2})^{2}$$

$$\int T + 2nJT + n_{1}^{2} + n_{2}^{2} = \int n_{1}^{2} + T - 2n_{2}JT + n_{2}^{2}$$

$$2n_{1}JT = -2n_{2}JT$$

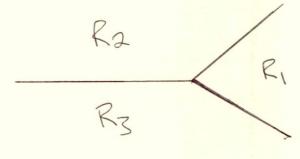
$$n_{1} = -n_{2}$$

$$(n_{1}, -n_{2})$$

Ra/Rz boundary

Since $s_2(t) = -s_3(t)$, R_2 and R_3 are on apposite sides of the y-axis,

3D) continued ...



This is a graph depicting the optimal decision regions.

 $R_1 \Rightarrow m_1$ $R_2 \Rightarrow m_2$ $R_3 \Rightarrow m_3$

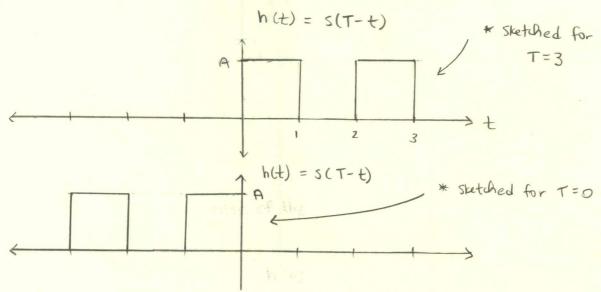
3e) R2 and R3 are each 3/8 of the total signal space.
R1 is 25% of the total space.

Each message (m, m2, m3) is equally probable and has 33 1/3 % chance of being received.

R₁ is most vulnerable to error because m₁ has an equal probability of being received and corresponds to the smallest region, R₁.

Problem #4

a) Sketch the impulse response of the matched filter to s(t).



b) Sketch output of matched filter to input s(t) over interval -2 4+8.

$$y(t) = s(t) * s(t) = \int_{0}^{t} s(\tau) s(\tau - t + \tau) d\tau$$

· Interval

$$t < 0 \rightarrow y(t) = 0$$

$$0 \le t < 1 \rightarrow \int_{0}^{t} A \times A dt = A^{2}t|_{0}^{t} = A^{2}t$$

$$1 \le t < 2 \rightarrow \int_{0}^{t} A \times A dt = A^{2}t|_{t-1}^{t} = A^{2}(1 - (t-1)) = A^{2}(2-t)$$

$$2 \le t < 3 \rightarrow \int_{0}^{t} A \times A dt + \int_{0}^{t-2} A \times A dt = A^{2}(t-2) + A^{2}(t-2) = 2A^{2}(t-2)$$

$$2 \le t < 4 \rightarrow \int_{0}^{t} A \times A dt + \int_{0}^{t} A \times A dt = A^{2}(3 - (t-1)) + A^{2}(1 - (t-3))$$

$$1 \le t < 4 \rightarrow \int_{0}^{t-2} A \times A dt = A^{2}(t-2(-2)) = A^{2}(t-4)$$

$$1 \le t < 6 \rightarrow y(t) = 0$$

$$1 \le t < 6 \rightarrow y(t) = 0$$

Putting together the piecewise and sketching yields:

$$g(t) = \begin{cases} 0, & t \neq 0 \\ A^{2}t, & 0 \leq t \neq 1 \\ A^{2}(2-t), & 1 \leq t \neq 2 \\ 2A^{2}(t-2), & 2 \leq t \neq 3 \\ 2A^{2}(4-t), & 3 \leq t \neq 4 \\ A^{2}(t-4), & 4 \leq t \leq 5 \\ A^{2}(b-t), & 5 \leq t \neq 6 \\ 0, & t \geq 6 \end{cases}$$

- c) Determine the variance of the noise at the output of the matched filter @ t = 3.
- → From slide 42 in the notes, we know that the variance of the noise is expressed by the following formula, @ t=T=3.

$$\sigma_{n_{T}}^{2} = \int_{0}^{\pi} \int_{0}^{\pi} E[n(r) n(t)] s(r) s(t) dt dr$$

$$= \frac{1}{2} N_{0} \int_{0}^{\pi} s^{2}(t) dt$$

$$= \frac{1}{2} N_{0} \int_{0}^{\pi} s^{2}(t) dt$$

$$\int_{0}^{\pi} A^{2} as seen in convolution$$

- d) Determine Pe as a function of A and No.
- * We know the following relationships: $\begin{cases} 0 \\ SNR_o = \frac{\lambda E_b}{N_o} = \frac{y_s^2(T)}{E[y_n^2(T)]} \end{cases}$

combining O & D, we see that :

$$P_{e} = Q(\sqrt{SNR_{o}}) = Q(\sqrt{\frac{y_{s}^{2}(T)}{E[y_{n}^{2}(T)]}}) \begin{cases} y_{s^{2}}(T) @ T = 3 = (2A^{2})^{2} = 4A^{4} \\ E[y_{n}^{2}(T) @ T = \sigma_{T=3}^{2} = N_{o}A^{2} \end{cases}$$

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$$= Q(\sqrt{SNR_{o}}) = Q(\sqrt{\frac{y_{s}^{2}(T)}{E[y_{n}^{2}(T)]}}) \begin{cases} y_{s}^{2}(T) @ T = 3 = (2A^{2})^{2} = 4A^{4} \\ P_{o}^{2}(T) @ T = \sigma_{T=3}^{2} = N_{o}A^{2} \end{cases}$$

$$P_{e} = Q\left(\sqrt{\frac{4A^{4}}{N_{o}A^{2}}}\right) = Q\left(\sqrt{\frac{4A^{2}}{N_{o}}}\right)$$