

ASD Assignment: 3D Game

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1 Initial Research

Among all the options for the ASD assignment, the simple 3D video game was chosen. The author found all of them of real interest, but two reasons led him to take that decision. The first one is his unfamiliarity with the CGI field; even though he counts with a quite solid basis in computer engineering, all the concepts such as shader, raytracer, renderer, flocking system, etc. are new for him. Thus, instead of a more specific project, it was thought that at the same time lectures give a more theoretical vision of computer graphics, a simple 3D game might be a good choice to get familiar with all of it and acquire a more global vision. And independently of the academic aims, the second reason was a quite well-formed idea of a 3D game in the author's mind.

By the time of starting the research, different videos of some 3D games were watched as well as reading the documentation of some libraries commonly used in the field of video game programming. Although Qt offers a very complete API, is more focused to the development of applications which need a powerful and friendly GUI. On the other hand, SDL offers functionalities more suitable referring to game programming. The SDL library [SDL 2.0, 2012] is completely compatible with 3D hardware acceleration via OpenGL, and provides a series of strong subsystems such as input events, threads, timers, audio, etc. Other of the main advantages of this library are that it supports the use of joysticks, which is really convenient in the world of videogames, it is cross-platform and completely open source.

Some other libraries were studied for their use as well. BulletPhysics [BulletPhysics, 2012] was thought in first instance as main physics engine to handle the collisions in the world of the game due to it is a full package which offers a wide range of collisions detection. In the same way, to implement the AI of the system, the author had in mind OpenSteer [OpenSteer, 2012], which offers steering behaviours for autonomous characters in game and animation. Finally, due to the simplicity of this project both libraries were rejected. Besides, using directly low level C++ to implement it, the approach of the used algorithms would be greater, so it would be a better chance to learn.

The final technologies chosen to implement the game were NGL, the graphic library of the NCCA, and SDL2 for handling the graphic context and user events. Later, SDL2_ttf would also be added for debugging purpose and because of some functionalities of rendering text are required at some points of the game play.

The main source of learning NGL was the ASD professor website [J. Macey's website, 2012] as well as his blog [J. Macey's blog, 2012]. Reading the demos' code and writing small programs was the process of understanding the concepts a progressing little by little. The same happened

with SDL, but extending it with all the other sources that might be found through the internet.

Parallel to this, other research was being carried out relative to the design of the game which, certainly, is completely independent of the technologies chosen to implement it. M. Sanchez provided to the author the contact of E. Anderson, an experienced teacher in game programming working at BU at the moment. He gently gave to the author an explanation of the typical game architecture, as well as provided some slides he often uses during his lectures.

At this point, the research material and documentation was enough to start with the design of the 3D game.

2 Initial Design

Currently, the most part of applications are designed using the paradigm of Object Orientation, due to the flexibility and scalability that design patterns offer, as well as it is widely belief as a very smart way of programming. But concerning to this project, it must be said that the execution of a game is normally a very secuencial flow.

All the games has a main loop with a similar estructure:

- reading the player input
- updating the world
- checking the collisions
- drawing the world
- adjusting FPS

So to design this execution flow, it was decided to count with a class *GameManager* which will be the centre of the system and will maintain the specific behaviour of this specific game. The rest of the modules which are surrounding this master class will purely have an object oriented design and will conform our game engine. See 1.

A game engine is a framework designed for the creation and development of video games. It might be thought as a group of predefined functions that offer to the game developper behaviour already programmed. Thus, all the different modules in this game should be part of a game engine, the most independent possible of this specific game, and that might be used in the future by other games of similar characteristics.

Once these concepts were clarified and the main structure was decided, the different modules had to be thought. One of the main worries of the author at the time of the design

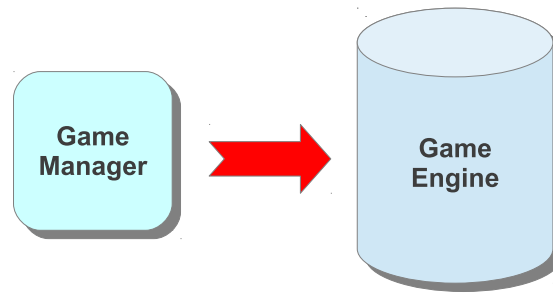


Figure 1: Game engine scheme

were the flexibility and the scalability, so a convenient idea was treat every module as an independent system which is in charge of certain responsibilities logically grouped and that could be unacoplated and used by any other client.

In order to model the world, a class *Object* was defined, which represents a simple object in the world and that mainly stores state information and some little behaviour for the interaction with other objects. This is the top of the hierarchy, and then some other classes with more specific state and behaviour might be defined. To store the objects of a concrete world there is a manager named *ObjectManager* which holds a list with all the objects and provides an interface with basic operations such as *addObject* or others more linked to this context.

The module in charge of updating the world is born in the class *Controller*, which provides a hierarchy of different autonomous behaviours (the AI of the game) as well as the controller defined by the user input. At first, this was thought as a strategy pattern, since the objects might have different strategies of movement but later, regarding the fact that is the controller the entity that moves an object and will have to modify its state, it was decided to use composition. So, in the same way, we count with a manager class that deals with all the controllers in order to give the client abstraction and to avoid they manage each one of them manually. The figure 2 shows this.

One of the critical points of computer games is the check of collisions among the objects moving around the world. In this approach, it was decided that the best option is that the responsibility of checking the collisions should be carried out by the holder of the objects but, using a physics engine object provided by the client. The *ObjectManager* just deals with a *PhysicsEngine* object which in this system is an abstract class and might be thought as an interface whose implementation depends on the specific physics engine used. In this way, this design provides a very high flexibility. See 3.

Concerning to the graphic module of this assignment, which is one of great importance

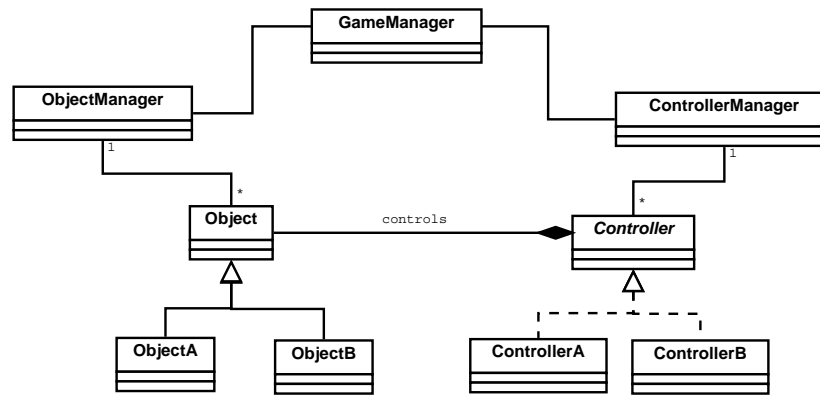


Figure 2: Controller-Object composition

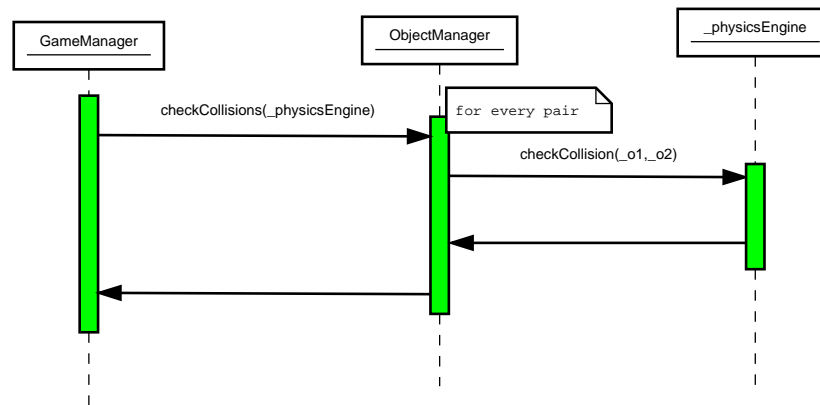


Figure 3: Sequence of the collisions check

taking into account the nature of this course itself, there is a class that is in charge of all the functionalities related with the drawing, which could not be named in other way that *Renderer*. The *Renderer* is the responsible of creating the graphic context and initialize everything needed for the rendering of the current scene of the game's world. It deals with the shaders and lights, and it is thought to be able to draw any 3D object over a background as well as 2D images or text. At the time the client asks for the render of the world, they should provide a reference to the world and its background, the camera from where the render should be processed and a simple flag to indicate a *debugMode*. As a design decision, the cameras are treated apart and independently to offer the user more transparency and versatility to visualize the scene. A *CameraManager* is added to the design as well to update all the positions of the different type of cameras according with a target, that is the main object of the world, the one the player is

controlling.

The design counts with a class which acts as a stock and stores all the sources needed for the execution of our game, such as meshes, textures, images, text, sound, etc. This is the *SourceManager*. The presence of managers is quite abundant in this system, the reason is that there will be a big amount of different objects during the runtime, and they can offer abstraction to the *GameManager* to deal with all of them. At first it was thought to make them singletons, but finally it was taken the option of just keeping one single instance of each manager.

Finally, in order to load our game world, a *Parser* is used to read from a describing scene file and some auxiliar functions used by the *GameManager* were grouped in a *Utilities* class.

A diagram of sequence is shown in 4 to illustrate how the main loop works and how the *GamaManager* interacts with the different modules.

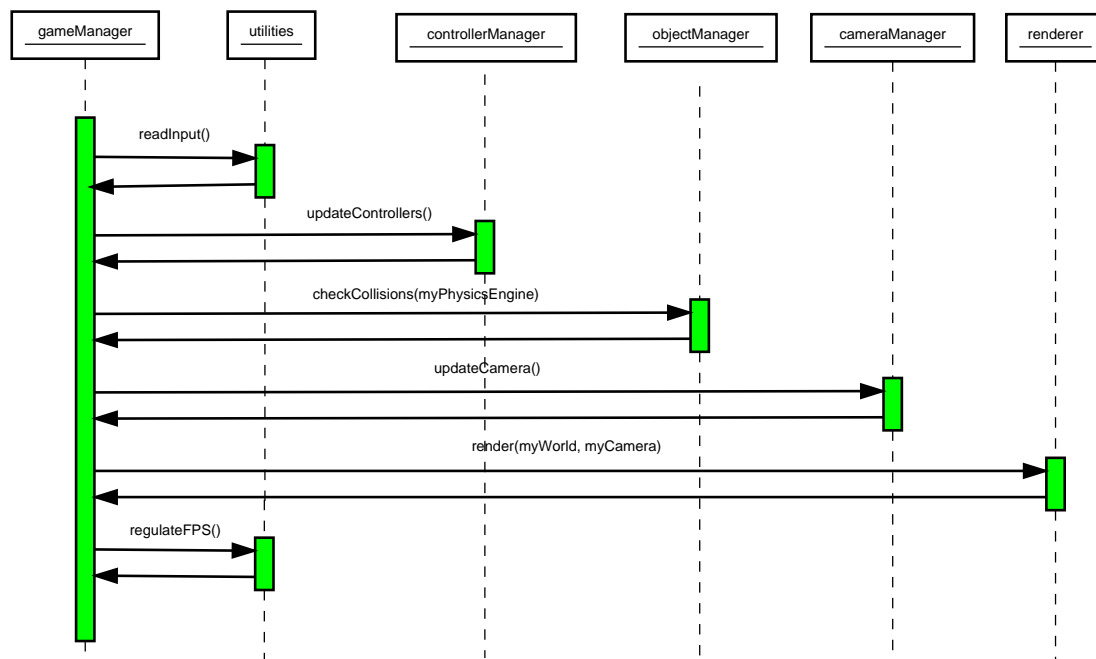


Figure 4: Sequence of the main loop

3 Proof of Context

The main aim of this first approach is the design, but a simple prototype is attached as a proof of context. The developer has a programming background in java an C, thus there is a period

of adaptation to C++ 11, so one of the main objects of this prototype is getting familiar to this technology.

This first version of the application shows the gameplay, rendered on a OpenGL context using NGL and SDL. So far it is single player and keyboard controlled, by this is tied to future modifications presented in the next section. The user will control an object which will be the main character of the world.

All the world is ambiented in the sea, so, in this context, the generic objects might perform roles such as obstacles on the sea, different types of boats or even marine fauna. The aim of the game is reaching the beach, which is at the end of the track where the main speedboat is advancing on. The main idea, which is not already implemented, is that the player might loose the game in two situations; if he loses all the load in his speedboat or if the police boats catch him. All of this is linked to the game story which is not relevant for this technical part.

It might be noticed that the AI is a very wide field to work when we are talking about boats moving on the sea, where a good understanding of physics plays a really important role. Some basic but different behaviours methods were implemented, thus the player might find boats which are crossing the sea track, which are coming towards the speedboat, etc.

The prototype can work so far with some test meshes and in two different debugging modes:

- mode 1: this is the primitives mode, where all the objects are rendered as primitives and the velocity vectors are drawn.
- mode 2: this is the collision mode, where the bounding spheres are rendered showing when a collision is produced.

It is possible to access to a specific debugging mode pressing the corresponding key number. For no debugging mode press 0.

The set of default cameras offered to the user for the rendering of the game scene is loaded at the initialization of the game. There is a circular queue of cameras which holds the typical cameras present on a video game, such as the camera from the back, up camera or first person camera. To iterate over this set of cameras the key *c* must be pressed. In addition, it was added a special camera, the back camera, which will be active while the player press *backspace*. The purpose of this camera for the real game is that it might be a useful feature when the police is chasing the player.

Other test functionalities have been added as well. It is possible to pause the game with the key *pause* or to interact with the window changing its size or converting it to fullscreen

mode.

4 Future work

This prototype compounds the main core of the game as it is thought to be formed by different modules the most independent possible. In this way, the application will acquire a flexible and scalable architecture profitable for reusability and expansibility.

After this first version, some reflexions were taken and some hints for future work and improvements on the system in the next term are these:

- Adding a Game State pattern to the design to manage the different states of the game, such as menu, story level, scores or gameplay.
- Adding the *Checkpoint* feature perhaps with a memento pattern.
- As it is a game about boats, it was considered a good idea to add particles systems to simulate the interaction of the motors or the hulls against the sea water.
- Improving the *physicsEngine* and the quality of the collision detection.
- Adding a subsystem of radio conversations. The player will be able to see on the screen radio conversations (rendering images or text) which in some situations might work as tutorial guide, information, story or a gag launched by some event in the gameplay. The first idea to design this is using an observer-observable pattern between the radio conversations and the objects, so every object can notify to a *ConversationManager* when a collision takes place.
- Adding a new controller to support the use of a joystick such as a play station joystick.
- Once the engine and technical part is finished, work on the visual impact of the game to make it attractive. Model good looking meshes and work on the appearance, thus it is a very important part of a 3D game.

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