



UiT Norges arktiske universitet

# DTE-2501 AI Methods and Applications

*Linear methods of classification and regression*

*Lecture 1/2 – Stochastic gradient descent*

Tatiana Kravets  
*Førsteamanuensis*

*Office: D2240*

*Email: [tatiana.kravets@uit.no](mailto:tatiana.kravets@uit.no)*

# Overview

I Linear model

II Numerical minimization

- a) Gradient descent
- b) Stochastic gradient
- c) Extensions and their comparison

# I Linear model

## Regression

- Training sample

$$X^l = (x_i, y_i)_{i=1}^l, x_i \in \mathbb{R}^n, y_i \in \mathbb{R}$$

- Linear model.  $\langle \cdot, \cdot \rangle$  is a scalar product

$$a(x, w) = \langle x, w \rangle = \sum_{j=1}^n w_j f_j(x), w \in \mathbb{R}^n$$

- Quadratic *loss function*

$$\varepsilon(a, y) = (a(x, w) - y(x))^2$$

- Training phase. Learning method is a *least squares method*.  $Q$  is an *empirical risk*

$$Q(w) = \sum_{i=1}^l (a(x_i, w) - y_i)^2 \rightarrow \min_w$$

- Testing phase. Test sample  $X^k = (\tilde{x}_i, \tilde{y}_i)_{i=1}^k$

$$\tilde{Q}(w) = \frac{1}{k} \sum_{i=1}^k (a(\tilde{x}_i, w) - \tilde{y}_i)^2$$

## Classification

- Training sample

$$X^l = (x_i, y_i)_{i=1}^l, x_i \in \mathbb{R}^n, y_i \in \{-1, +1\}$$

- Linear model

$$a(x, w) = \text{sign} \langle x, w \rangle = \text{sign} \sum_{j=1}^n w_j f_j(x)$$

- Binary loss function, or its *approximation*

$$\varepsilon(a, y) = [a(x, w)y(x) < 0] = [\langle x, w \rangle y < 0] \leq \varepsilon(\langle x, w \rangle y)$$

- Training phase. Learning method is a minimization of the empirical risk

$$Q(w) = \sum_{i=1}^l [a(x_i, w)y_i < 0] = \sum_{i=1}^l \varepsilon(\langle x_i, w \rangle y_i) \rightarrow \min_w$$

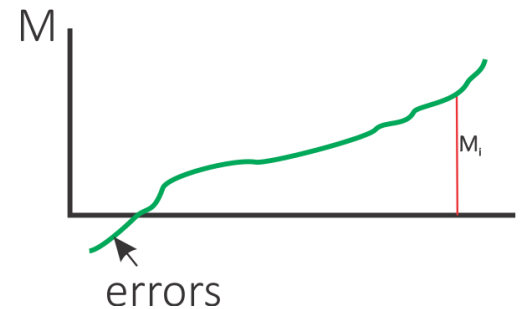
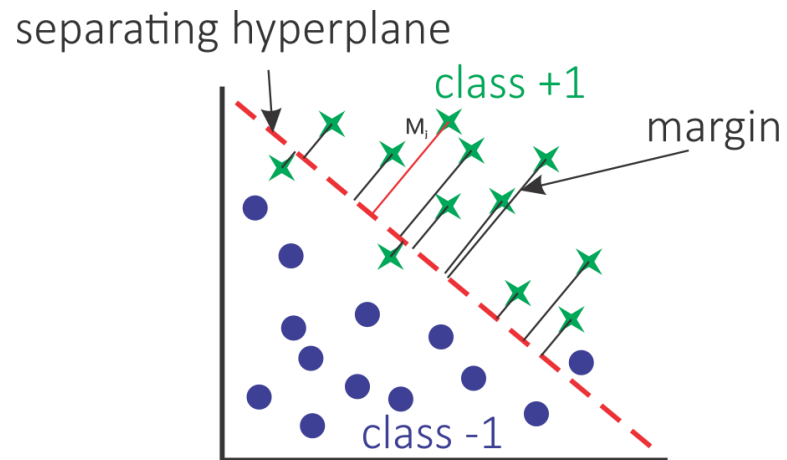
- Testing phase. Test sample  $X^k = (\tilde{x}_i, \tilde{y}_i)_{i=1}^k$

$$\tilde{Q}(w) = \frac{1}{k} \sum_{i=1}^k [\langle \tilde{x}_i, w \rangle \tilde{y}_i < 0]$$

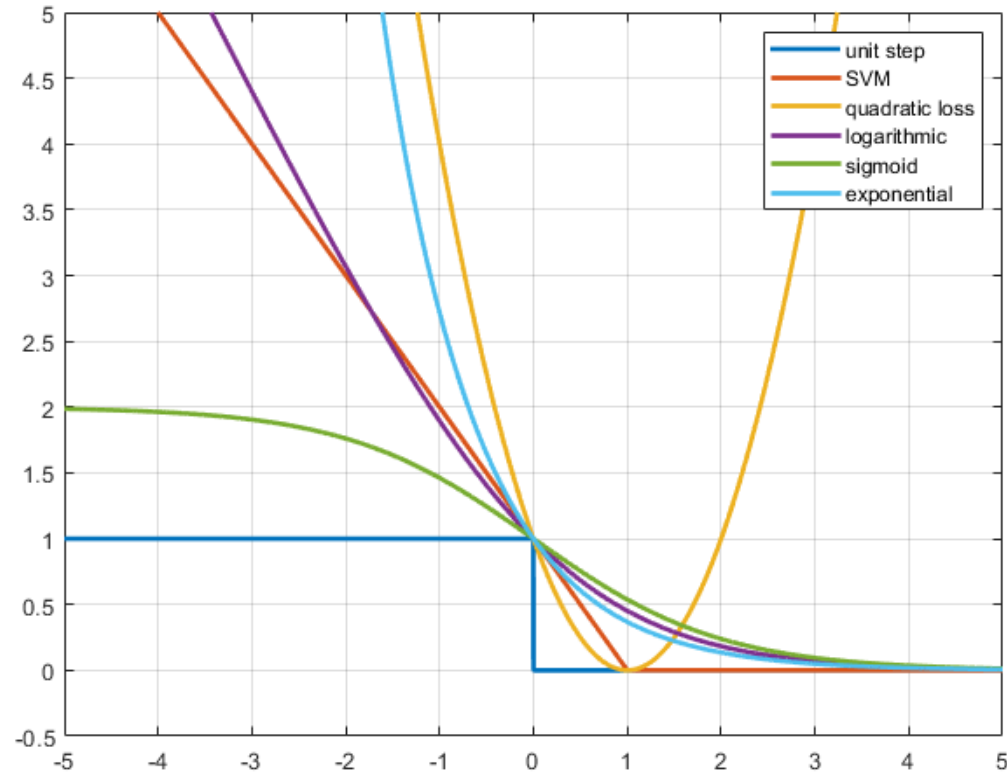
# Margin

Classifier  $a(x, w) = \text{sign}\langle x, w \rangle$

- $\langle x, w \rangle = 0$  is a separating hyperplane equation
- $M_i = \langle x_i, w \rangle y_i$  is a margin of the object  $x_i$
- $M_i < 0$  means an error of the algorithm  $a(x, w)$  on the object  $x_i$



# Continuous approximations of the threshold function



- $[M < 0]$  – the unit step (zero-one loss)
- $(1 - M)_+$  – piecewise linear (SVM)
- $(1 - M)^2$  – quadratic loss
- $\log_2(1 + e^{-M})$  – logarithmic
- $2(1 + e^M)^{-1}$  – sigmoid
- $e^{-M}$  – exponential

# II Numerical minimization

## Gradient descent

Empirical risk minimization

$$Q(w) = \sum_{i=1}^l \varepsilon_i(w) \rightarrow \min_w$$

Numerical minimization using a *gradient descent method*:

$w^{(0)}$  is an initial guess

$$w^{(t+1)} := w^{(t)} - h \cdot \nabla Q(w^{(t)}), \quad \nabla Q(w) = \left( \frac{\partial Q(w)}{\partial w_j} \right)_{j=0}^n$$

where  $h$  is a gradient step, which is also called a *learning rate*.

$$w^{(t+1)} := w^{(t)} - h \sum_{i=1}^l \nabla \varepsilon_i(w^{(t)})$$

# Stochastic gradient

**Input:** dataset  $X^l$ , learning rate  $h$ , parameter  $\lambda$

**Output:** weights  $w$

## Initialization

Set all the weights  $w_j, j = 0, \dots, n$  to small random numbers

Evaluate the objective function  $Q = \frac{1}{l} \sum_{i=1}^l \varepsilon_i(w)$

**do**

    pick randomly  $x_i$  from  $X^l$

    compute the loss function  $\varepsilon_i(w)$

    perform the gradient step  $w := w - h \nabla \varepsilon_i(w)$

    update the objective function  $Q := \lambda \varepsilon_i + (1 - \lambda)Q$

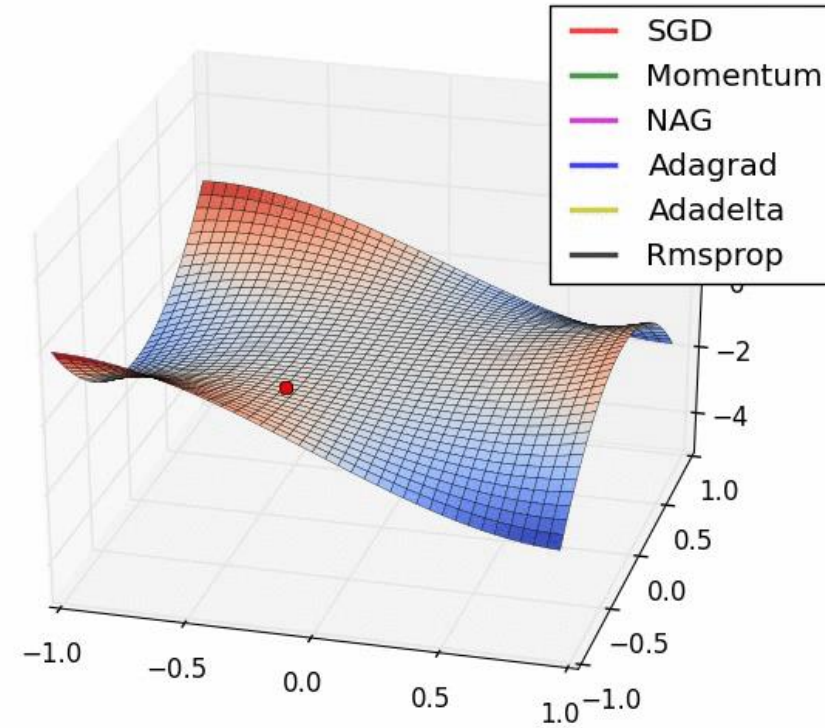
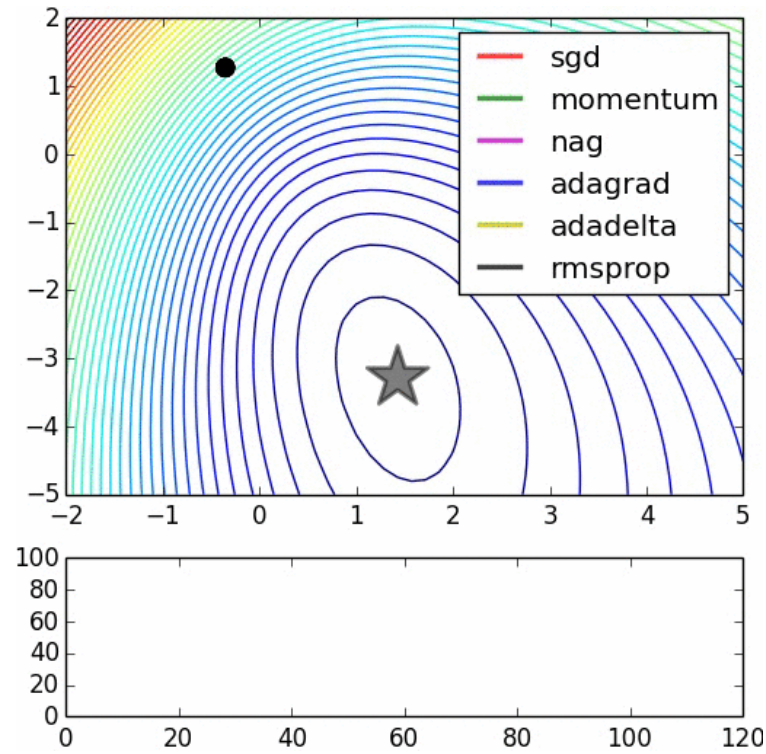
**until**  $Q$  and/or  $w$  converges

# Extensions

- **Stochastic average gradient (SAG)**  
The algorithm records an average of its parameter vector over time
- **Momentum**  
The algorithm updates the weights as a linear combination of the gradient and the previous update
- **RMSProp (running mean square propagation)**  
The learning rate is adapted for each of the parameters
- **AdaGrad (adaptive gradient)**  
The algorithm increases the learning rate for sparser parameters and decreases for ones that are less sparse
- etc...



# Comparison of optimization algorithms



Alec Radford's animation for optimization algorithms:

<http://www.denizyuret.com/2015/03/alec-radfords-animations-for.html>

### III Practical example

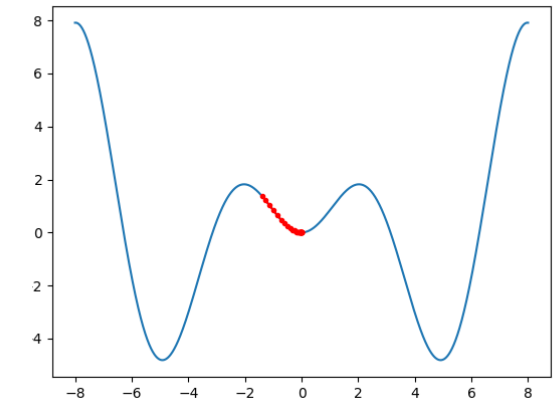
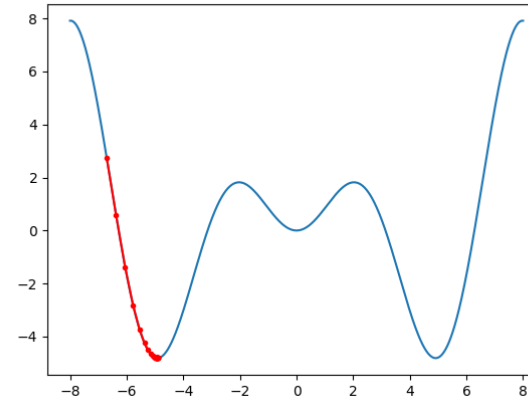
Objective function  $Q = x \sin x$  on  $[-8, 8]$

Derivative of the objective function  $Q' = \sin x + x \cos x$

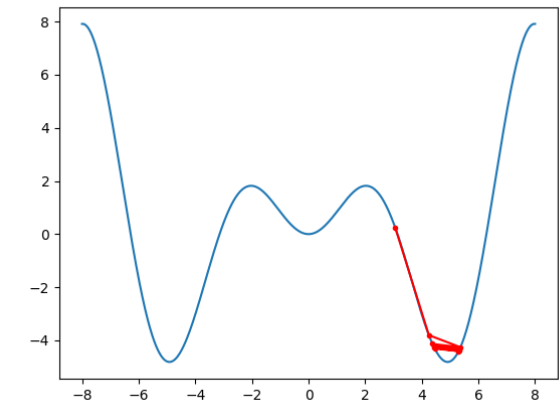
```
8 # objective function
9 def obj(x):
10     return x * sin(x)
11
12 # derivative of objective function
13 def derv(x):
14     return sin(x) + x * cos(x)
15
16 # gradient descent algorithm
17 def gradient_descent(objective, derivative, bounds, n_iter, step_size):
18     solution = bounds[:, 0] + rand(len(bounds)) * (bounds[:, 1] - bounds[:, 0])
19     for i in range(n_iter):
20         gradient = derivative(solution)
21         solution = solution - step_size * gradient
22         solution_eval = objective(solution)
23     return [solution, solution_eval]
24
25 bound = asarray([-8.0, 8.0])
26 n = 30
27 h = 0.1
28 sol, sol_eval = gradient_descent(obj, derv, bound, n, h)
```

Result:

Local minima depends on starting point



Not optimal step size ( $h = 0.4$ )



} random initialization

}  $x := x - hQ'(x)$