

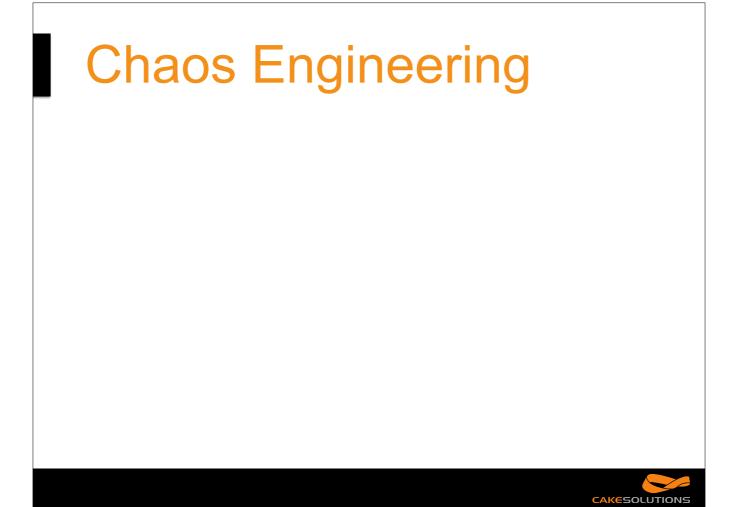
MANCHESTER LONDON NEW YORK

Using Chaos Engineering to Build Resilient Distributed Applications

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 Emphasises an empirical approach to testing and monitoring distributed systems



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- Typical Chaos Experiment
 - define views of a system (e.g. by monitoring a set of system or business metrics)
 - randomly inject faults (e.g. by killing containers or changing networking behaviour)



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- Infer weaknesses using deviations from expected or steady-state behaviour



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- Typical Chaos Experiment
 - define views of a system (e.g. by monitoring a set of system or business metrics)
 - randomly inject faults (e.g. by killing containers or changing networking behaviour)
- Infer weaknesses using deviations from expected or steady-state behaviour
- Potentially apply to production systems!





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- Cloud deployment involves dynamic environments
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 - deployment typically uses unverified processes
- · Potential for unanticipated failure is highly likely
 - it doesn't matter how the code was produced!
 - embrace and test for failure!



docker-compose-testkit



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- Open-source Scala library (under development)
 - (optionally) deploys, orchestrates and instruments Docker container code
 - agnostic of deployment environment
 - composable behaviour properties
 - reusable Chaos experiments easily defined



templates



templates

- Specify Docker image instrumentation layers
 - injects code and resources into image
- Specify library code for using instrumentation
 - code needs to use side effects
 - maintain a functional core using extensible effects (i.e. Eff)
 - sensor events represented using Monix Observables

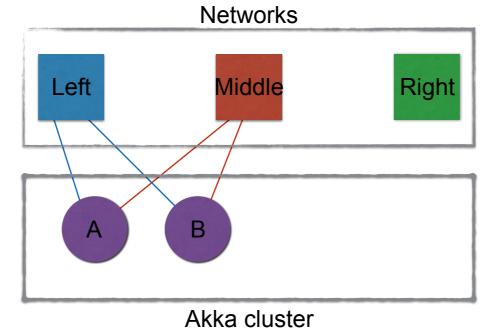




Networks

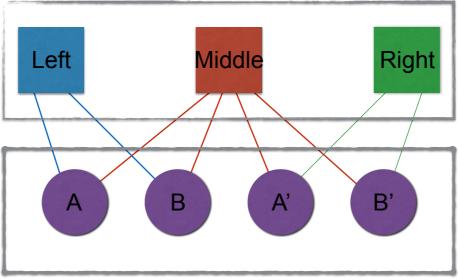








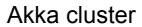
Networks



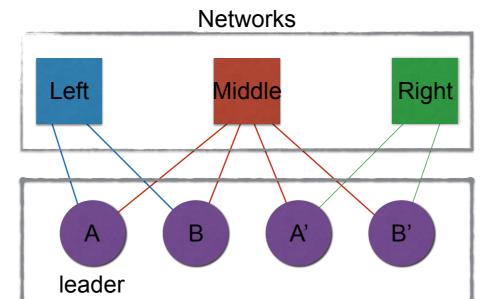




Left Middle Right A B A' B'







Akka cluster

Auto-downing Enabled!!



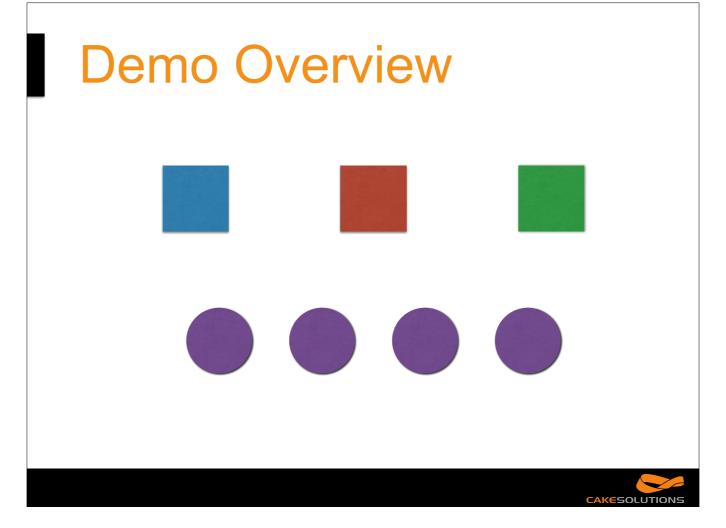




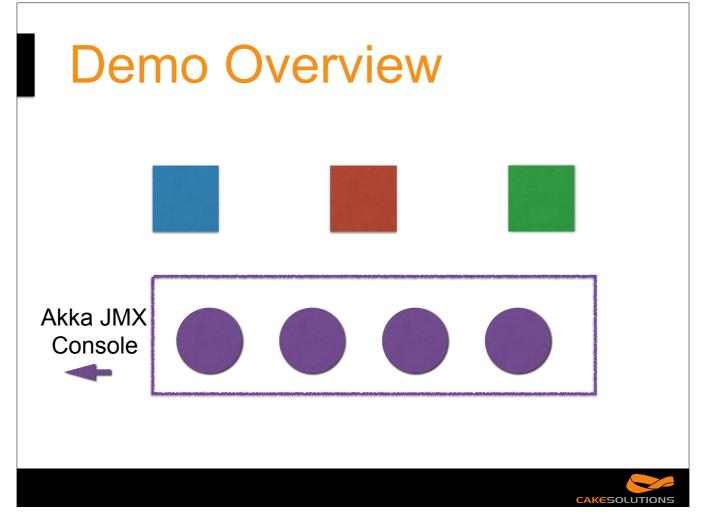




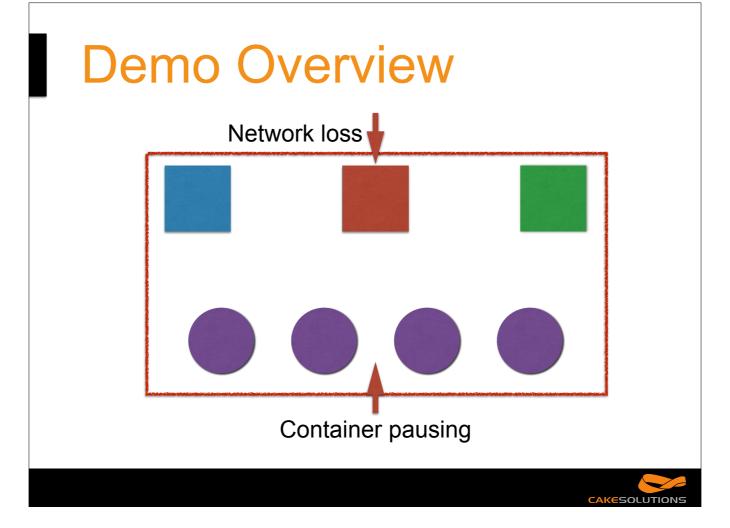




Point out our framework is capable of far more fault injection than this! Necessary to perform some coding to define this instrumentation layer. Docker-compose templating is used here!



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Chaos Experiment





Chaos Experiment





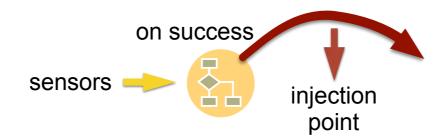
Chaos Experiment

on success



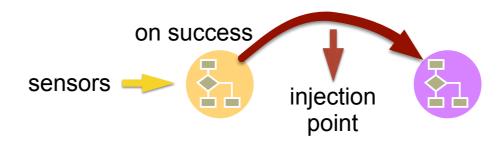
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 - when we successfully detect behaviour





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 Chaining such relations allows the fault injection search space to be described



```
def experiment[M: _jvm: _network: ..](implicit ..): Eff[M, Notify] =
   for {
        yield Accept()
```



```
def experiment[M: _jvm: _network: ..](implicit ..): Eff[M, Notify] =
   for {
     obs1 <- ???
     ..
} yield Accept()</pre>
```



```
def experiment[M: _jvm: _network: ..](implicit ..): Eff[M, Notify] =
   for {
     obs1 <- ???
     ...
     _ <- jvmGC(JvmGCStart)(rightA)
     _ = note("A' JVM GC pause starts")
     obs2 <- ???
     ...
} yield Accept()</pre>
```









Monitor State



Observed Event





```
Demo Overview
def experiment[M: _jvm: _network: ..](implicit ..): Eff[M, Notify] =
  for {
```

} yield Accept()





```
def experiment[M: _jvm: _network: ..](implicit ..): Eff[M, Notify] =
    for {
        obs1 <- jmx(inCluster(leftA, leftB, rightA, rightB))(leftA)
        _ <- check(isAccepting(obs1))
        _ = note("cluster formed, is stable and A an available leader")
        ..
        obs2 <- jmx(unreachable(rightA))(leftA)
        _ <- check(isAccepting(obs2))
        _ = note("A' is unreachable")
        ..
}</pre>
```



```
def experiment[M: _jvm: _network: ..](implicit ..): Eff[M, Notify] =
    for {
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        obs2 <- jmx(unreachable(rightA))(leftA)
        _ <- check(isAccepting(obs2))
        _ = note("A' is unreachable")
        ..
        obs3 <- jmx(inCluster(leftA, leftB, rightA, rightB))(leftA)
        _ <- check(isAccepting(obs3))
        _ = note("cluster stabilised with A' as a member")
        ..
} yield Accept()</pre>
```



```
def experiment[M: _jvm: _network: ..](implicit ..): Eff[M, Notify] =
 for {
    obs1 <- jmx(inCluster(leftA, leftB, rightA, rightB))(leftA)</pre>
    _ <- check(isAccepting(obs1))</pre>
    _ = note("cluster formed, is stable and A an available leader")
    obs2 <- jmx(unreachable(rightA))(leftA)</pre>
    _ <- check(isAccepting(obs2))</pre>
    _ = note("A' is unreachable")
    obs3 <- jmx(inCluster(leftA, leftB, rightA, rightB))(leftA)</pre>
    _ <- check(isAccepting(obs3))</pre>
    _ = note("cluster stabilised with A' as a member")
    obs4 <- jmx(inCluster(leftA, leftB))(leftA)</pre>
              && jmx(inCluster(leftA, leftB))(leftB)
              && jmx(inCluster(rightA))(rightA)
              && jmx(inCluster(rightB))(rightB)
    _ <- check(isAccepting(obs4))</pre>
    _ = note("cluster split brains into 3 clusters: A & B; A'; B'")
  } yield Accept()
```





```
type Model = Fx.fx5[JmxAction, NetworkAction, ..]
```



```
val cluster = Map(
  leftA -> compose.service(leftA).docker.head,
  leftB -> compose.service(leftB).docker.head,
  rightA -> compose.service(rightA).docker.head,
  rightB -> compose.service(rightB).docker.head
)
```



experiment[Model].runJvm(cluster).runNetwork...



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docker events --filter type=container sbt clean "dockerComposeTests/testOnly *AutoDownSplitBrainDockerTest"

Development Use Cases



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 Can we use instrumentation to investigate difficult to observe issues?



Development Use Cases

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- For example:
 - directly observe and extract networking evidence
 - observe impact of resource starved Docker containers
 - e.g. low memory or small thread pools



Development Use Case: Networking



Development Use Case: Networking

- Networking issues
 - instrument container with *iptables*
 - use runtime monitors to validate received/sent network traffic expectations
 - capture PCAP data as a side effect of monitoring for offline examination



Development Use Case: Container Resource Stress



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 Use LIB_PRELOAD "trick" to load application code via libfiu



Development Use Case: Container Resource Stress

- Use LIB_PRELOAD "trick" to load application code via libfiu
- libfiu Fault Injection in Userspace
 - DSL allows system calls to return with an error code
 - every time or randomly specified
 - reliably simulate container memory, CPU or thread resourcing issues
 - often very difficult to detect!



Development Use Case: JVM



Development Use Case: Modify JVM class loaders to instrument runtime application

code



Development Use Case: JVM

- Modify JVM class loaders to instrument runtime application code
- Byteman
 - rule based instrumentation DSL
 - event-condition-action (ECA) rules
 - operates at the the Java (not bytecode) level
 - enables principled experiments to guide investigation into difficult to observe issues
 - exceptions that get swallowed
 - validate expected data and control flows
 - etc.



Next Steps



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- Failure control plane
 - sidecar failure control node per Docker container
 - failure agent within each container
 - lower Dockerfile impact



Next Steps

- · Failure control plane
 - sidecar failure control node per Docker container
 - failure agent within each container
 - lower Dockerfile impact
- Describe how we may automatically generate Chaos experiments from models
 - observational models
 - models based on static analysis
 - models built using domain expertise





- Taken steady state behavioural specifications and developed a composable DSL for experiments
 - by relating data injection traces to observed system behaviour



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- Applied techniques to a range of fault-injection scenarios



- Taken steady state behavioural specifications and developed a composable DSL for experiments
 - by relating data injection traces to observed system behaviour
- Applied techniques to a range of fault-injection scenarios
- Shown how these techniques can be used within debugging scenarios



References

- https://github.com/carlpulley/ docker-compose-testkit /tree/ scala-sphere-2017
- Chaos Engineering by A.Basiri, N.Behnam, R.de Rooij, L.Hochstein, L.Kosewski, J.Reynolds and C.Rosenthal
- Freer monads, more extensible effects by O.Kiselyov and H.Ishii
- eff https://github.com/atnos-org/eff
- libfiu https://blitiri.com.ar/p/libfiu/
- Byteman http://byteman.jboss.org/



