University of Magdeburg School of Computer Science



Bachelor Thesis

Mixed-reality Simulation of Quadcopter-Swarms

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List of Acronyms

ASIL Automotive Security Integrity Level

E/E Elektrisch/Elektronisch EHF Element Hiding Factor

FCM Factor-Criteria-Metrics

GQM Goal Question Metric

LBC Loose Block Cohesion LCC Loose Class Cohesion

MDA Model Driven Architecture

MOOD Metrics for Object Oriented Design

NOE Number of Elements

OMG Object Management Group

PES Porsche Engineering Services GmbH

PHG Produkthaftungsgesetz

SysML Systems Modeling Language

TBC Tight Block Cohesion TCC Tight Class Cohesion

TeSiKo Technisches Sicherheitskonzept

UML Unified Modeling Language

1. Introduction

1.1 Motivation

[project context of this work]
[who needs the results]
[what are the problems to be solved?]
[what are existing solutions, what's different in this approach, what is the improvement]

1.2 Problem Statement

 $[\mathit{what}\ \mathit{are}\ \mathit{the}\ \mathit{goals}]\ [\mathit{how}\ \mathit{are}\ \mathit{we}\ \mathit{going}\ \mathit{to}\ \mathit{reach}\ \mathit{this}\ \mathit{goals}]\ [\mathit{what}\ \mathit{is}\ \mathit{to}\ \mathit{be}\ \mathit{done}]$

1.3 Outline

[short description of the sections]

2. Theory

2.1 Quadcopter Modelling

```
[fundamental physics]
[particle simulation]
```

2.2 Vrep

```
[connecting visual representation and physical model]
[simulation structure (lua scripts, scene structure]
[lua module structure]
[external interface (signals)]
```

2.3 Communication/Ivy-Bus

3. Implementation

3.1 Simulation Environment

```
[finken parameter estimation]
[controller tuning]
[simulation parameters]
[script structure]
```

3.2 Communication Link

```
[link in Vrep (signals]
```

- 3.3 [fancy name]
- 3.4 Quadcopter

4. Evaluation

 $[how\ realisitc\ is\ the\ simulation?]\ [which\ properties\ can\ be\ modelled\ well,\ which\ can't?]$

4.1 Speed

 $[communication\ delay]\ [vrep\ simulation\ speed]$

4.2 Accuracy

[error]

4.3

Stability

4.4 usability

5. Conclusion

5.1

[do the results show that it works?]

5.2 Future Work

Bibliography

