

The purpose of this notebook is to elucidate the two parts of projection and minimization.

Projection is analytical, whereas minimization is numerical and employs the Nminimize function.

INSTRUCTIONS: Run common_funs.nb, ES_FindSymGroups.nb, BC_ChooseTmat.nb, then this notebook
contact: Carl Tape (ctape@alaska.edu)

In[1246]:=

```
WantDetails = "WantDetails";
```

In[1247]:=

```
PaxesForLattice =  
  Paxes[True, True, True, id, {0, 0, 0}, 1.35, 1, .17, .009, "Gray", ArrowColor];
```

choose a Tmat from BC_ChooseTmat.nb or define your own here
(This is the BB basis for Tmat; if you want Voigt, you can define C and then use TmatofCmat().)

In[1248]:=

```
Tmat = TmatIgel;
```

KEY FUNCTION: this will maximize (NMaximize) instead of minimize (NMinimize)
After running this function, $\{\theta_0, \sigma_0, \phi_0\}$ can be used to find the U associated with the maximum.

In[1249]:=

```
GetTempAnd $\theta_0\sigma_0\phi_0$ Max[Tmat_,  $\Sigma$ ] := (Clear[ $\theta$ ,  $\sigma$ ,  $\phi$ ];  
  temp[Tmat,  $\Sigma$ ] = NMaximize[{DistToVzofU[Tmat, UsHat[{ $\theta$ ,  $\sigma$ ,  $\phi$ }],  $\Sigma$ ],  
     $0 \leq \theta \leq 2\pi \&\& -\pi \leq \sigma \leq \pi \&\& 0 \leq \phi \leq \pi$ }, { $\theta$ ,  $\sigma$ ,  $\phi$ }, Method  $\rightarrow$  "RandomSearch";  
  { $\theta_0$ ,  $\sigma_0$ ,  $\phi_0$ } = ({ $\theta$ ,  $\sigma$ ,  $\phi$ } /. temp[Tmat,  $\Sigma$ ][[2]]);  
  If[MemberQ[{XISO, MONO},  $\Sigma$ ],  $\sigma_0 = 0$ ];) (* optional *)
```

Example elastic map

In[1250]:=

```
PrintVoigt[Tmat]  
TISO = ProjToVSigOfU[Tmat, id, ISO];
```

The $[T]_{BB}$ matrix is
$$\begin{pmatrix} 10. & 0.7 & 1.05 & 5.2 & -3.92598 & -3.10269 \\ 0.7 & 8. & -2. & -0.2 & -0.46188 & 0.326599 \\ 1.05 & -2. & 6. & -0.45 & -0.190526 & 0.318434 \\ 5.2 & -0.2 & -0.45 & 5.5 & 0 & -1.22474 \\ -3.92598 & -0.46188 & -0.190526 & 0 & 5.5 & 2.12132 \\ -3.10269 & 0.326599 & 0.318434 & -1.22474 & 2.12132 & 13. \end{pmatrix}$$

The eigenvalues are: $\{17.7924, 10.1797, 9.22349, 5.83219, 4.30288, 0.669364\}$

The Voigt matrix is
$$\begin{pmatrix} 10. & 3.5 & 2.5 & -5. & 0.1 & 0.3 \\ 3.5 & 8. & 1.5 & 0.2 & -0.1 & -0.15 \\ 2.5 & 1.5 & 6. & 1. & 0.4 & 0.24 \\ -5. & 0.2 & 1. & 5. & 0.35 & 0.525 \\ 0.1 & -0.1 & 0.4 & 0.35 & 4. & -1. \\ 0.3 & -0.15 & 0.24 & 0.525 & -1. & 3. \end{pmatrix}$$

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$\mathcal{V}_{ISO}(U) = \mathcal{V}_{ISO}(I)$, independent of U , so the function U
 $\rightarrow d(T, \mathcal{V}_{ISO}(U)) = d(T, \mathcal{T}_{ISO})$ is constant.

$d(T, \mathcal{T}_{ISO}) = 12.0102$ (Distance from T to \mathcal{T}_{ISO})

$\beta_{ISO}^{\square T} = 0.533 = 30.55^\circ$ (Angle between T and \mathcal{T}_{ISO})

$$P(T, \mathcal{V}_{ISO}(I)) = \begin{pmatrix} 7. & 0. & 0. & 0. & 0. & 0. \\ 0. & 7. & 0. & 0. & 0. & 0. \\ 0. & 0. & 7. & 0. & 0. & 0. \\ 0. & 0. & 0. & 7. & 0. & 0. \\ 0. & 0. & 0. & 0. & 7. & 0. \\ 0. & 0. & 0. & 0. & 0. & 13. \end{pmatrix}$$

(The closest elastic map to T having symmetry ISO)

Lamé parameters for $P(T, \mathcal{V}_{ISO}(I))$ are $\lambda = 2$.

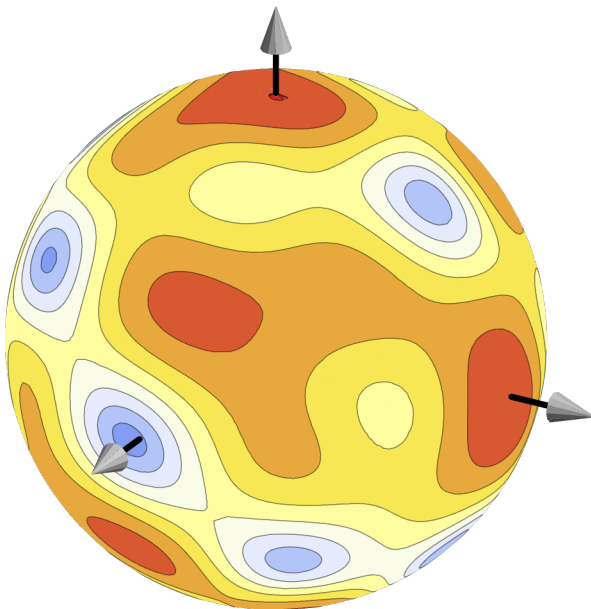
and $\mu = 3.5$, bulk modulus $\kappa = 4.33333$, Poisson ratio = 0.181818

plot the (TRIV) map as a sphere

```
In[1252]:=
MatrixNote[Tmat]
Show[{cpMONO[Tmat, contoursMONO[Tmat], MaxForScaling[Tmat],
      plotpoints, contourstyle], Graphics3D[PaxesForLattice]}, options]

Out[1252]=
T is Igel

Out[1253]=
```



Closest to MONO maps

```
In[1254]:=
OutputFor[Tmat, MONO]
```

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NMinimize = {1.77381, { $\theta \rightarrow 6.2378$, $\sigma \rightarrow -1.04197$, $\phi \rightarrow 1.58615$ }}

(minimizing the function $(\theta, \sigma, \phi) \rightarrow d(T, \mathcal{V}_{\text{MONO}}(U))$, $U = \hat{U}_S(\theta, \sigma, \phi)$)

(($\theta_0, \sigma_0, \phi_0$) in degrees are {357.4, 0., 90.9})

$$U_0 = \hat{U}_S(\theta_0, \sigma_0, \phi_0) = \begin{pmatrix} -0.0153358 & 0.0453676 & 0.998853 \\ 0.000696467 & 0.99897 & -0.0453622 \\ -0.999882 & 0 & -0.0153516 \end{pmatrix} \quad (\text{A})$$

MONO-minimizer for T. It minimizes the function $U \rightarrow d(T, \mathcal{V}_{\text{MONO}}(U))$

$\beta_{\text{MONO}}^T = 0.075 = 4.31^\circ$ (Angle between T and $\mathcal{T}_{\text{MONO}}$)

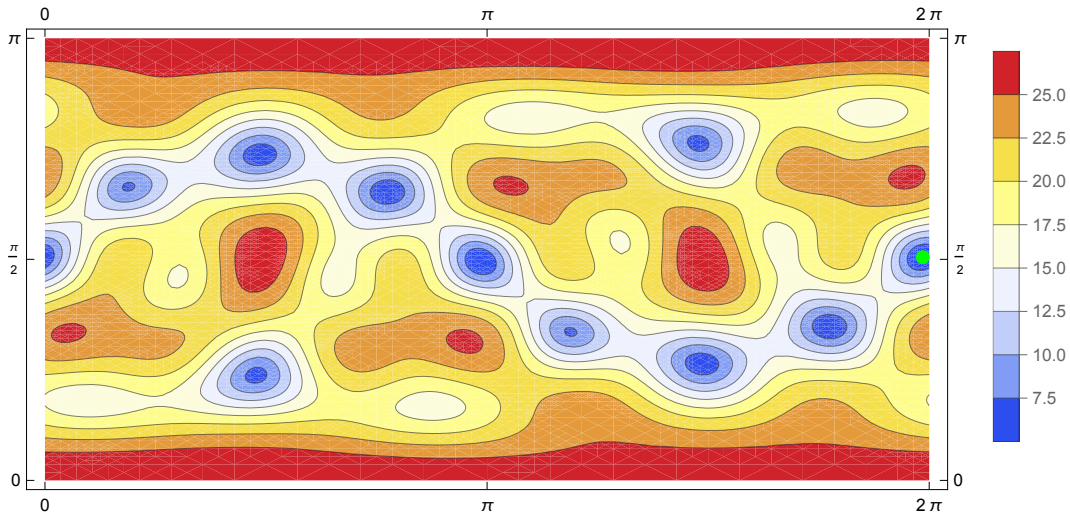
$\mathcal{V}_{\text{MONO}}(U_0)$ contains a closest map to T in $\mathcal{T}_{\text{MONO}}$

$d(T, \mathcal{T}_{\text{MONO}}) = 1.774$ (Distance from T to $\mathcal{T}_{\text{MONO}}$)

Does the green point look like a correct

GLOBAL minimum? If not, the minimization has failed.

Uniqueness (or not) of the closest MONO map is usually obvious from the contour plot.



$$P(T, \mathcal{V}_{\text{MONO}}(U_0)) = \begin{pmatrix} 10.0483 & 0.312292 & 0.626973 & 5.21023 & -3.95328 & -3.07084 \\ 0.312292 & 7.96402 & -1.96673 & 0.37924 & -0.115108 & -0.213739 \\ 0.626973 & -1.96673 & 6.07884 & 0.0499996 & -0.114125 & -0.15424 \\ 5.21023 & 0.37924 & 0.0499996 & 5.39035 & 0.00319104 & -1.17338 \\ -3.95328 & -0.115108 & -0.114125 & 0.00319104 & 5.5185 & 2.10692 \\ -3.07084 & -0.213739 & -0.15424 & -1.17338 & 2.10692 & 13. \end{pmatrix}$$

(a closest elastic map to T having symmetry at least MONO)

plot the closest MONO map as a sphere

In[1255]:=

TMONO = Closest[Tmat, MONO];

UMONO = UT[TMONO, MONO];

OutputFor[TMONO, MONO]

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NMinimize = {7.6283 × 10⁻⁷, {θ → 6.2378, σ → -3.12923, φ → 1.58615}}

(minimizing the function (θ, σ, φ) → d(T, V_{MONO}(U)), U = Ũ_S(θ, σ, φ))

((θ₀, σ₀, φ₀) in degrees are {357.4, 0., 90.9})

$$U_0 = \hat{U}_S(\theta_0, \sigma_0, \phi_0) = \begin{pmatrix} -0.0153358 & 0.0453676 & 0.998853 \\ 0.000696467 & 0.99897 & -0.0453623 \\ -0.999882 & 0 & -0.0153516 \end{pmatrix} \quad (A)$$

MONO-minimizer for T. It minimizes the function U → d(T, V_{MONO}(U))

β_{MONO}^T = 0 (Angle between T and T_{MONO}. The initial β_{MONO}^T = 3.24 × 10⁻⁸

is here chopped to zero, since the chop threshold is set at 0.01°)

Since β_{MONO}^T = 0, T is assigned symmetry at least MONO.

V_{MONO}(U₀) contains T

d(T, T_{MONO}) = 7.6 × 10⁻⁷ (Distance from T to T_{MONO})

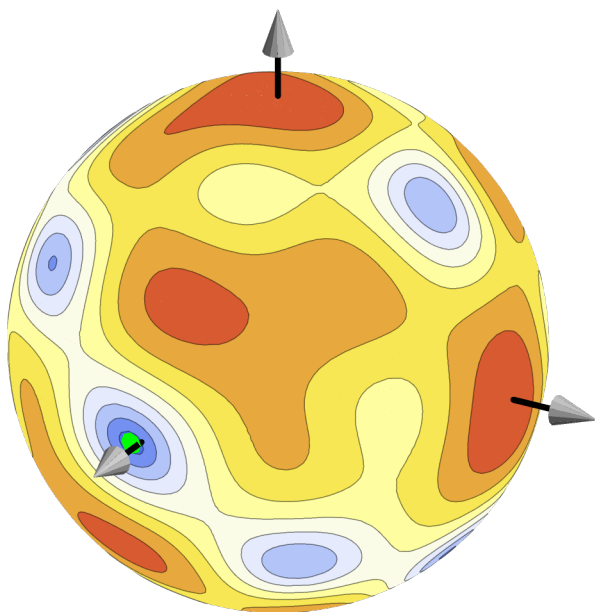
$$T_{\text{MONO}} = [\overline{U_0}]^T [T] [\overline{U_0}] = \begin{pmatrix} 6.06321 & 2.00189 & 0 & 0 & 0 & 0 \\ 2.00189 & 7.94231 & 0 & 0 & 0 & 0 \\ 0 & 0 & 10.0733 & 0.802002 & -6.52726 & 3.07774 \\ 0 & 0 & 0.802002 & 5.48337 & -0.0517244 & 1.23396 \\ 0 & 0 & -6.52726 & -0.0517244 & 5.43786 & -2.07855 \\ 0 & 0 & 3.07774 & 1.23396 & -2.07855 & 13. \end{pmatrix}$$

(Should be a MONO-ref matrix for T. If not, consider decreasing ChopT.)

In[1258]:=

```
TwoFold = Graphics3D[
  TwoFoldGraphics[MONO, UMONO, 1.25 AngRadDisk, 3 ShiftToEye, eye, tkns, Green]];
Show[
  {cpMONO[TMONO, contoursMONO[Tmat], MaxForScaling[Tmat], plotpoints, contourstyle],
   TwoFold, Graphics3D[PaxesForLattice]}, options]
```

Out[1259]=



check

In[1260]:=

```
UforNM1 = UMONO;
TMONOx = ProjToVSigOfU[Tmat, UforNM1, MONO];
AngleMatrix[Tmat, TMONO] / Degree
AngleMatrix[Tmat, TMONOx] / Degree
AngleMatrix[TMONO, TMONOx] / Degree
```

Out[1262]=

4.30551

Out[1263]=

4.30551

Out[1264]=

 1.47878×10^{-6}

What would our closest-to-MONO map look like for the default U (=Identity)?

```

In[1265]:=
  UforNM1 = id;
  TMON0x = ProjToVSigOfU[Tmat, UforNM1, MON0];
  AngleMatrix[Tmat, TMON0] / Degree
  AngleMatrix[Tmat, TMON0x] / Degree
  AngleMatrix[TMON0, TMON0x] / Degree

Out[1267]=
  4.30551

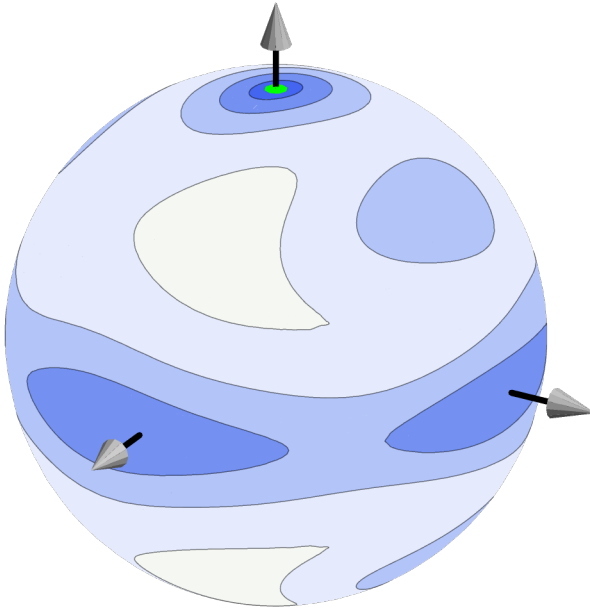
Out[1268]=
  27.0034

Out[1269]=
  27.0269

In[1270]:=
  TwoFold = Graphics3D[
    TwoFoldGraphics[MON0, UforNM1, 1.25 AngRadDisk, 3 ShiftToEye, eye, tkns, Green]];
  Show[
    {cpMON0[TMON0x, contoursMON0[Tmat], MaxForScaling[Tmat], plotpoints, contourstyle],
     TwoFold, Graphics3D[PaxesForLattice]}, options]

Out[1271]=

```



Among the projected MONO maps, which one is **farthest** from our target map?
 Since \mathcal{V}_{ISO} is contained in every $\mathcal{V}_{\Sigma}(U)$ and since your TMON0x is in

$\mathcal{V}_{\text{MONO}}(\text{UMONOmax})$, then all ISO maps are at least as far from Tmat as is TMONOx.

To get a truly (i.e., non ISO) MONO map that is farther from Tmat than TMONOx, write TMONOx in the form $\text{TMONOx} = U \mathcal{T}_{\text{MONO}} U^T$, where $\mathcal{T}_{\text{MONO}}$ is a MONO ref matrix. (You already have U.) Then change a couple of entries of $\mathcal{T}_{\text{MONO}}$, but keeping it a MONO ref matrix. The new $U \mathcal{T}_{\text{MONO}} U^T$ will be farther from Tmat (since TMONOx was a projection).

In[1272]:=

```
GetTempAnd000000Max[Tmat, MONO]
```

In[1273]:=

```
UMONOmax = UsHat[{00, 00, 00}];
TMONOx = ProjToVSigOfU[Tmat, UMONOmax, MONO];
AngleMatrix[Tmat, TMONO] / Degree
AngleMatrix[Tmat, TMONOx] / Degree
AngleMatrix[TMONO, TMONOx] / Degree
```

Out[1275]=

```
4.30551
```

Out[1276]=

```
27.0575
```

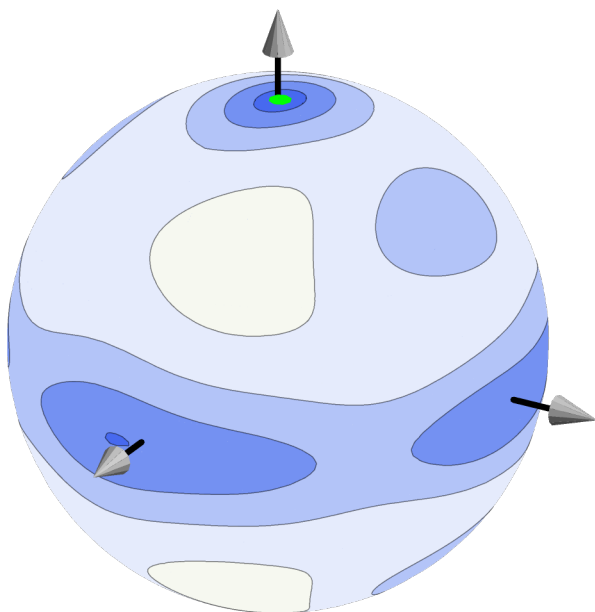
Out[1277]=

```
27.0448
```


In[1278]:=

```
TwoFold = Graphics3D[
  TwoFoldGraphics[MONO, UMONOmax, 1.25 AngRadDisk, 3 ShiftToEye, eye, tkns, Green]];
Show[
  {cpMONO[TMONOx, contoursMONO[Tmat], MaxForScaling[Tmat], plotpoints, contourstyle],
   TwoFold, Graphics3D[PaxesForLattice]}, options]
```

Out[1279]=

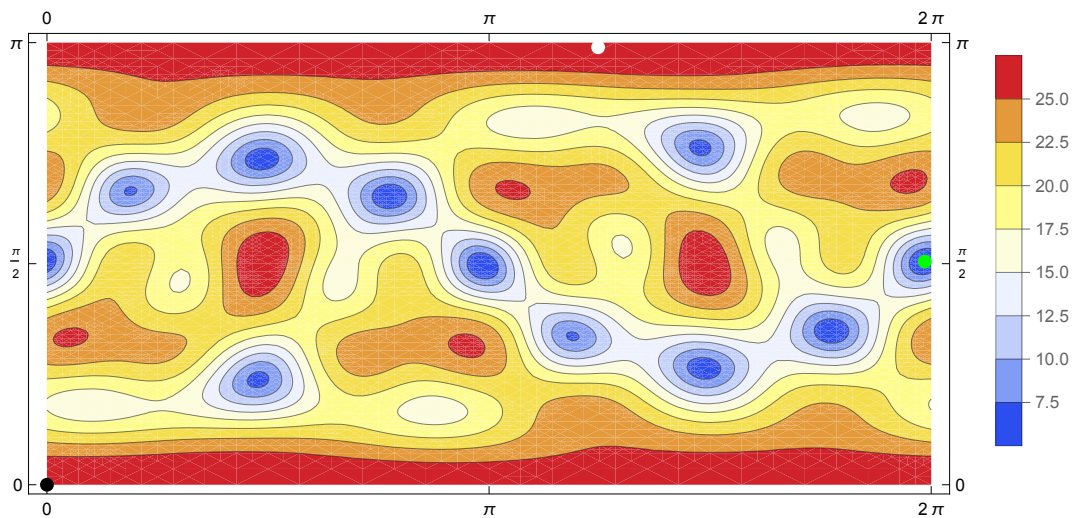


replot the map, but with the $U=Id$ and $U=U_{max}$ points added

In[1280]:=

```
Show[{ContourPlot[Alpha[Tmat, { $\theta$ ,  $\phi$ }, MON0] / Degree,
  { $\theta$ , 0, 2  $\pi$ }, { $\phi$ , 0,  $\pi$ }, Contours  $\rightarrow$  Automatic,
  ColorFunction  $\rightarrow$  (ColorData["TemperatureMap"]), PlotLegends  $\rightarrow$  Automatic],
Graphics[
  {PointSize[.015], {Green, Point[TPxyz0to2pi[UT[Tmat, MON0].{0, 0, 1}]]}},
Graphics[{PointSize[.015], {White, Point[TPxyz0to2pi[UMON0max.{0, 0, 1}]]}},
Graphics[{PointSize[.015], {Black, Point[{0, 0}]}]}]
}, FrameTicks  $\rightarrow$  {Range[0, 2  $\pi$ ,  $\pi$ ], Range[0,  $\pi$ ,  $\pi/2$ ]},
AspectRatio  $\rightarrow$  Automatic, PlotRange  $\rightarrow$  All, ImageSize  $\rightarrow$  500]
```

Out[1280]=



Closest to XISO maps

In[1281]:=

```
OutputFor[Tmat, XISO]
```

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NMinimize = {6.50485, { $\theta \rightarrow 1.50483$, $\sigma \rightarrow 3.07695$, $\phi \rightarrow 0.714334$ }}

(minimizing the function $(\theta, \sigma, \phi) \rightarrow d(T, \mathcal{V}_{\text{XISO}}(U))$, $U = \hat{U}_S(\theta, \sigma, \phi)$)

(($\theta_0, \sigma_0, \phi_0$) in degrees are {86.2, 0., 40.9})

$$U_0 = \hat{U}_S(\theta_0, \sigma_0, \phi_0) = \begin{pmatrix} 0.0498003 & -0.997825 & 0.0431815 \\ 0.753887 & 0.0659144 & 0.65369 \\ -0.655115 & 0 & 0.75553 \end{pmatrix} \quad (\text{A XISO})$$

-minimizer for T. It minimizes the function $U \rightarrow d(T, \mathcal{V}_{\text{XISO}}(U))$

$\beta_{\text{XISO}}^T = 0.279 = 15.98^\circ$ (Angle between T and $\mathcal{T}_{\text{XISO}}$)

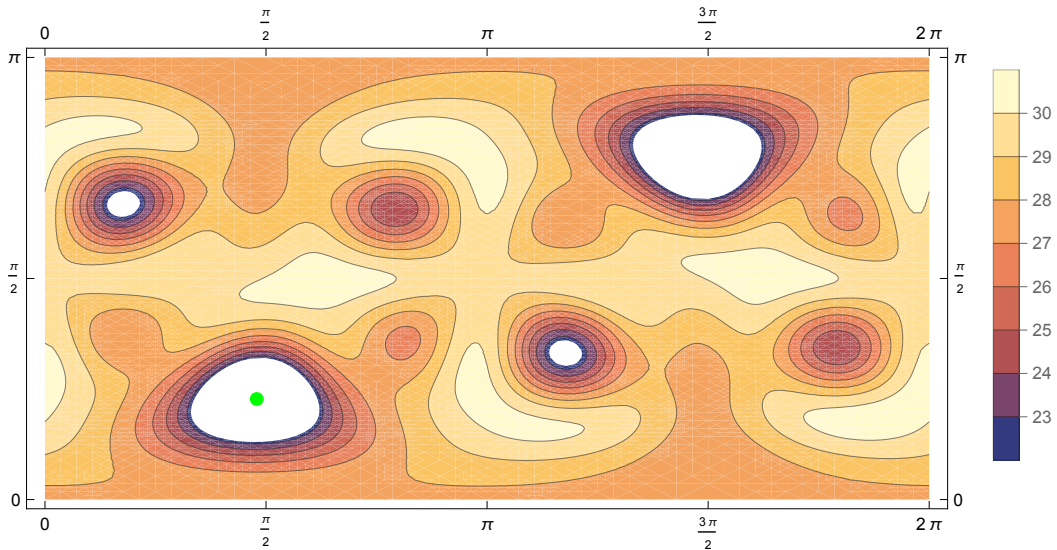
$\mathcal{V}_{\text{XISO}}(U_0)$ contains a closest map to T in $\mathcal{T}_{\text{XISO}}$

$d(T, \mathcal{T}_{\text{XISO}}) = 6.505$ (Distance from T to $\mathcal{T}_{\text{XISO}}$)

Does the green point look like a correct

GLOBAL minimum? If not, the minimization has failed.

Uniqueness (or not) of the closest XISO map is usually obvious from the contour plot.



$$P(T, \mathcal{V}_{\text{XISO}}(U_0)) = \begin{pmatrix} 12.0284 & 0.456493 & 0.397549 & 3.07421 & -2.91164 & -3.27377 \\ 0.456493 & 5.14803 & 0.181413 & 0.182489 & -0.192338 & -0.216259 \\ 0.397549 & 0.181413 & 5.09532 & 0.166797 & -0.150986 & -0.187109 \\ 3.07421 & 0.182489 & 0.166797 & 6.33018 & -1.13784 & -1.41006 \\ -2.91164 & -0.192338 & -0.150986 & -1.13784 & 6.39812 & 1.36334 \\ -3.27377 & -0.216259 & -0.187109 & -1.41006 & 1.36334 & 13. \end{pmatrix}$$

(a closest elastic map to T having symmetry at least XISO)

plot the closest XISO map as a sphere

In[1282]:=

TXISO = Closest[Tmat, XISO];

UXISO = UT[Tmat, XISO];

OutputFor[TXISO, XISO]

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NMinimize = {6.03787 × 10⁻⁹, {θ → 1.50483, σ → 1.41779, ϕ → 0.714334}}

(minimizing the function (θ, σ, ϕ) → d(T, V_{XISO}(U)), U = Ũ_S(θ, σ, ϕ))

((θ₀, σ₀, ϕ₀) in degrees are {86.2, 0., 40.9})

$$U_0 = \hat{U}_S(\theta_0, \sigma_0, \phi_0) = \begin{pmatrix} 0.0498003 & -0.997825 & 0.0431815 \\ 0.753887 & 0.0659144 & 0.65369 \\ -0.655115 & 0 & 0.75553 \end{pmatrix} \quad (\text{A XISO})$$

-minimizer for T. It minimizes the function U → d(T, V_{XISO}(U))

β_{XISO}^T = 0 (Angle between T and T_{XISO}. The initial β_{XISO}^T = 2.66 × 10⁻¹⁰

is here chopped to zero, since the chop threshold is set at 0.01°)

Since β_{XISO}^T = 0, T is assigned symmetry at least XISO.

V_{XISO}(U₀) contains T

d(T, T_{XISO}) = 6. × 10⁻⁹ (Distance from T to T_{XISO})

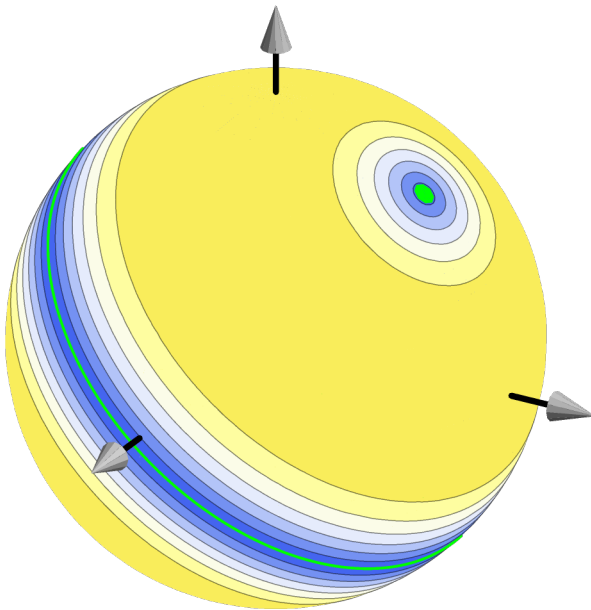
$$T_{XISO} = [\overline{U_0}]^T [T] [\overline{U_0}] = \begin{pmatrix} 5.25329 & 0 & 0 & 0 & 0 & 0 \\ 0 & 5.25329 & 0 & 0 & 0 & 0 \\ 0 & 0 & 4.93777 & 0 & 0 & 0 \\ 0 & 0 & 0 & 4.93777 & 0 & 0 \\ 0 & 0 & 0 & 0 & 14.6179 & 3.82705 \\ 0 & 0 & 0 & 0 & 3.82705 & 13. \end{pmatrix}$$

(Should be a XISO-ref matrix for T. If not, consider decreasing ChopT.)

In[1285]:=

```
TwoFold = Graphics3D[
  TwoFoldGraphics[XISO, UXISO, 1.25 AngRadDisk, 3 ShiftToEye, eye, tkns, Green]];
Show[
  {cpMONO[TXISO, contoursMONO[Tmat], MaxForScaling[Tmat], plotpoints, contourstyle],
   TwoFold, Graphics3D[PaxesForLattice]}, options]
```

Out[1286]=



check

In[1287]:=

```
UforNM1 = UXISO;
TXISOx = ProjToVSigOfU[Tmat, UforNM1, XISO];
AngleMatrix[Tmat, TXISO] / Degree
AngleMatrix[Tmat, TXISOx] / Degree
AngleMatrix[TXISO, TXISOx] / Degree
```

Out[1289]=

15.9806

Out[1290]=

15.9806

Out[1291]=

0.

What would our closest-to-XISO map look like for the default U (=Identity)?

```

In[1292]:=
  UforNM1 = id;
  TXISOx = ProjToVSigOfU[Tmat, UforNM1, XISO];
  AngleMatrix[Tmat, TXISO] / Degree
  AngleMatrix[Tmat, TXISOx] / Degree
  AngleMatrix[TXISO, TXISOx] / Degree

Out[1294]=
  15.9806

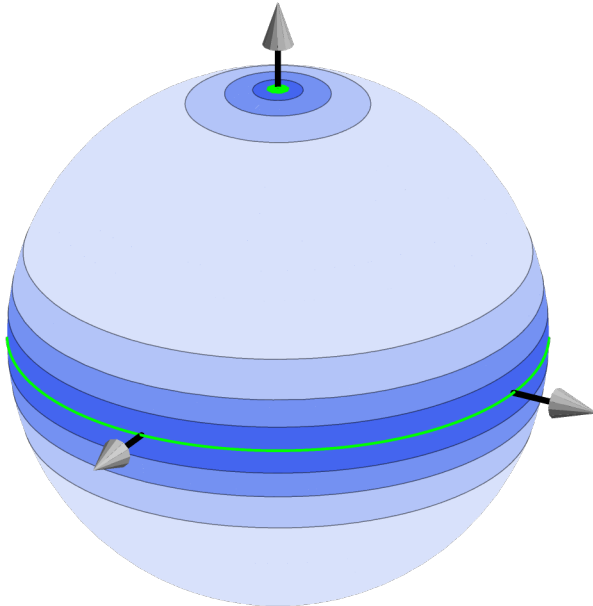
Out[1295]=
  27.855

Out[1296]=
  24.9357

In[1297]:=
  TwoFold = Graphics3D[
    TwoFoldGraphics[XISO, UforNM1, 1.25 AngRadDisk, 3 ShiftToEye, eye, tkns, Green]];
  Show[
    {cpMONO[TXISOx, contoursMONO[Tmat], MaxForScaling[Tmat], plotpoints, contourstyle],
     TwoFold, Graphics3D[PaxesForLattice]}, options]

Out[1298]=

```



Let's how far from ISO it is.

In[1299]:=

AngleMatrix[TXISOx, TISO] / Degree

Out[1299]=

13.0875

In[1300]:=

PrintVoigt[TXISOx]

The $[T]_{BB}$ matrix is
$$\begin{pmatrix} 9. & 0 & 0 & 0 & 0 & 0 \\ 0 & 9. & 0 & 0 & 0 & 0 \\ 0 & 0 & 5.75 & 0 & 0 & 0 \\ 0 & 0 & 0 & 5.75 & 0 & 0 \\ 0 & 0 & 0 & 0 & 5.5 & 2.12132 \\ 0 & 0 & 0 & 0 & 2.12132 & 13. \end{pmatrix}$$

The eigenvalues are: {13.5584, 9., 9., 5.75, 5.75, 4.94158}

The Voigt matrix is
$$\begin{pmatrix} 9.125 & 3.375 & 2. & 0 & 0 & 0 \\ 3.375 & 9.125 & 2. & 0 & 0 & 0 \\ 2. & 2. & 6. & 0 & 0 & 0 \\ 0 & 0 & 0 & 4.5 & 0 & 0 \\ 0 & 0 & 0 & 0 & 4.5 & 0 \\ 0 & 0 & 0 & 0 & 0 & 2.875 \end{pmatrix}$$

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$\mathcal{V}_{ISO}(U) = \mathcal{V}_{ISO}(I)$, independent of U , so the function U

$\rightarrow d(T, \mathcal{V}_{ISO}(U)) = d(T, \mathcal{T}_{ISO})$ is constant.

$d(T, \mathcal{T}_{ISO}) = 4.73022$ (Distance from T to \mathcal{T}_{ISO})

$\beta_{ISO}^{\square T} = 0.228 = 13.09^\circ$ (Angle between T and \mathcal{T}_{ISO})

$P(T, \mathcal{V}_{ISO}(I)) = \begin{pmatrix} 7. & 0. & 0. & 0. & 0. & 0. \\ 0. & 7. & 0. & 0. & 0. & 0. \\ 0. & 0. & 7. & 0. & 0. & 0. \\ 0. & 0. & 0. & 7. & 0. & 0. \\ 0. & 0. & 0. & 0. & 7. & 0. \\ 0. & 0. & 0. & 0. & 0. & 13. \end{pmatrix}$

(The closest elastic map to T having symmetry ISO)

Lamé parameters for $P(T, \mathcal{V}_{ISO}(I))$ are $\lambda = 2$.

and $\mu = 3.5$, bulk modulus $\kappa = 4.33333$, Poisson ratio = 0.181818

Among the projected XISO maps, which one is farthest from our target map?

In[1301]:=

GetTempAnd000000Max[Tmat, XISO]

In[1302]:=

```

UXISOmax = UsHat[{θ0, σ0, φ0}];
TXISOx = ProjToVSigOfU[Tmat, UXISOmax, XISO];
AngleMatrix[Tmat, TXISO] / Degree
AngleMatrix[Tmat, TXISOx] / Degree
AngleMatrix[TXISO, TXISOx] / Degree

```

Out[1304]=

15.9806

Out[1305]=

30.5468

Out[1306]=

26.3551

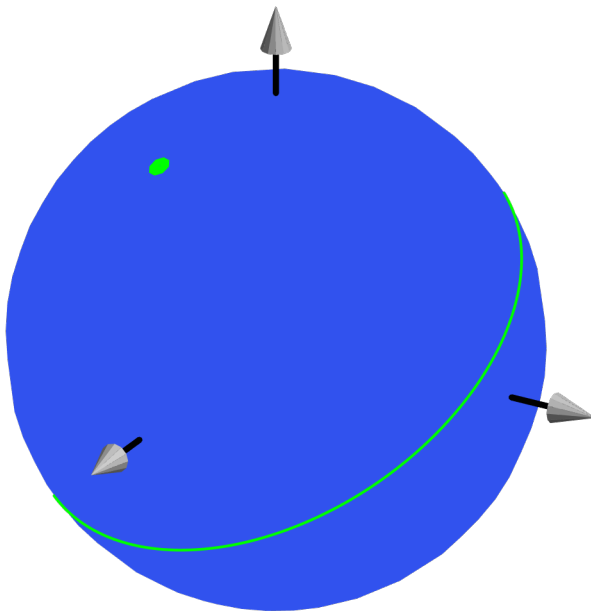
In[1307]:=

```

TwoFold = Graphics3D[
  TwoFoldGraphics[XISO, UXISOmax, 1.25 AngRadDisk, 3 ShiftToEye, eye, tkns, Green]];
Show[
  {cpMONO[TXISOx, contoursMONO[Tmat], MaxForScaling[Tmat], plotpoints, contourstyle],
   TwoFold, Graphics3D[PaxesForLattice]}, options]

```

Out[1308]=



That looks ISO on this color scale. Let's how far from ISO it is.

In[1309]:=

```
AngleMatrix[TXISOx, TISO] / Degree
```

Out[1309]=

0.597797

In[1310]:=

PrintVoigt[TXISOx]The [T]_{BB} matrix is

$$\begin{pmatrix} 7.01821 & 0.00448765 & 0.0418971 & -0.0240439 & -0.00134566 & -0.0399718 \\ 0.00448765 & 7.01005 & -0.0111118 & -0.0375894 & 0.00304252 & 0.0903755 \\ 0.0418971 & -0.0111118 & 6.96894 & -0.0021221 & -0.0209194 & -0.0228677 \\ -0.0240439 & -0.0375894 & -0.0021221 & 6.96935 & -0.0190231 & -0.0207948 \\ -0.00134566 & 0.00304252 & -0.0209194 & -0.0190231 & 7.03345 & -0.0733601 \\ -0.0399718 & 0.0903755 & -0.0228677 & -0.0207948 & -0.0733601 & 13. \end{pmatrix}$$

The eigenvalues are: {13.0027, 7.05164, 7.05164, 7.01436, 6.93983, 6.93983}

The Voigt matrix is

$$\begin{pmatrix} 8.98363 & 1.98632 & 2.00365 & -0.0046849 & 0.0565687 & -0.0143136 \\ 1.98632 & 8.92771 & 2.00864 & -0.0287288 & 0.0189792 & -0.0164357 \\ 2.00365 & 2.00864 & 9.09146 & -0.0155415 & 0.0351391 & 0.00274212 \\ -0.0046849 & -0.0287288 & -0.0155415 & 3.5091 & 0.00224383 & 0.0209485 \\ 0.0565687 & 0.0189792 & 0.0351391 & 0.00224383 & 3.50502 & -0.00555589 \\ -0.0143136 & -0.0164357 & 0.00274212 & 0.0209485 & -0.00555589 & 3.48447 \end{pmatrix}$$

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 $\mathcal{V}_{\text{ISO}}(U) = \mathcal{V}_{\text{ISO}}(I)$, independent of U, so the function U $\rightarrow d(T, \mathcal{V}_{\text{ISO}}(U)) = d(T, \mathcal{T}_{\text{ISO}})$ is constant. $d(T, \mathcal{T}_{\text{ISO}}) = 0.212298$ (Distance from T to \mathcal{T}_{ISO}) $\beta_{\text{ISO}}^{\square T} = 0.0104 = 0.6^\circ$ (Angle between T and \mathcal{T}_{ISO})

$$P(T, \mathcal{V}_{\text{ISO}}(I)) = \begin{pmatrix} 7. & 0. & 0. & 0. & 0. & 0. \\ 0. & 7. & 0. & 0. & 0. & 0. \\ 0. & 0. & 7. & 0. & 0. & 0. \\ 0. & 0. & 0. & 7. & 0. & 0. \\ 0. & 0. & 0. & 0. & 7. & 0. \\ 0. & 0. & 0. & 0. & 0. & 13. \end{pmatrix}$$

(The closest elastic map to T having symmetry ISO)

Lamé parameters for $P(T, \mathcal{V}_{\text{ISO}}(I))$ are $\lambda = 2$.and $\mu = 3.5$, bulk modulus $\kappa = 4.33333$, Poisson ratio = 0.181818

replot the map, but with the $U=Id$ (red) and $U=U_{max}$ (blue) points added ($U = U_{min}$ in green)

In[1311]:=

```
Show[ContourPlot[Alpha[Tmat, {θ, φ}, XIS0] / Degree, {θ, 0, 2 π}, {φ, 0, π},
  Contours → Automatic, ColorFunction → (ColorData["M10DefaultDensityGradient"]),
  PlotLegends → Automatic],
Graphics[
  {PointSize[.015], {Green, Point[TPxyz0to2pi[UT[Tmat, XIS0].{0, 0, 1}]]}},
Graphics[{PointSize[.015], {Blue, Point[TPxyz0to2pi[UXIS0max.{0, 0, 1}]]}},
(* Graphics[{PointSize[.015], {Red, Point[TPxyz0to2pi[UforNM1.{0, 0, 1}]]}} *)
Graphics[{PointSize[.015], {Red, Point[{0, 0}]]}}
], FrameTicks → {Range[0, 2 π, π], Range[0, π, π / 2]},
AspectRatio → Automatic, PlotRange → All, ImageSize → 500]
```

Out[1311]=

