# TDDD38/726G82 - Advanced programming in C++

Templates III

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- 1 Dependent Names
- 2 More on Templates
- 3 SFINAE



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### **Dependent Names**

```
struct X
{
  using foo = int;
};
struct Y
{
  static void foo() { }
};

template <typename T>
struct Z
{
  void foo()
  {
  T::foo; // what does this refer to?
  }
};
```



**Dependent Names** 

T:: foo can refer to these things:

- A type
- A function
- A variable

All of which are names that depend on T.



**Dependent Names** 

- The compiler can have a hard time to distinguish between these uses;
- To specify that it is a type use the typename keyword;
- If it is a member, then use it as normal.



### **Dependent Names**

```
template <typename T>
struct Z
 void foo()
    // foo should be a type
    typename T::foo x{};
   // or
    // foo is a function (or a variable)
    T::foo();
   // or
    // foo is a variable (or a function)
    T::foo;
};
```



- Dependent names
- Non-dependent names



- Dependent names
  - Is bound at instantiation
  - Name lookup occurs when the template argument is known
  - For member functions in class templates, this is a dependent name
- Non-dependent names



- Dependent names
- Non-dependent names
  - Is bound at definition
  - Name lookup occurs as normal
  - Note: if the meaning of a non-dependent name has changed between definition and instatiation, the program is ill-formed



```
struct Type { };
template <typename T>
void foo()
{
    // dependent name
    typename T::type x{};

    // non-dependent name
    Type t{};
}
```



### III-formed program

```
struct Type;
template <typename T>
struct Foo
{
    // Type is incomplete during definition
    Type x;
};

// Type is still incomplete during instantiation
Foo<int> foo;

// Doesn't matter that we define Type here
// the instantiation above is ill-formed
struct Type { };
```



III-formed program

# The worst part?



III-formed program

The compiler isn't required to report this as an error



Ill-formed program

Fortunately, most compilers do!



### III-formed program

```
test.cpp:7:8: error: field 'x' has incomplete type 'Type'
Type x;
^
test.cpp:1:8: note: forward declaration of 'struct Type'
struct Type;
^^~~
```



### typename

```
template <typename T>
class Cls
  struct Inner
    T x;
    T::value type val;
public:
 static Inner create_inner();
};
template <typename T>
Cls<T>::Inner Cls<T>::create inner()
 T x{};
 T::value type val;
 return {x, val};
```



### typename

```
template <typename T>
class Cls
  struct Inner
    T x;
    typename T::value_type val;
public:
 static Inner create_inner();
};
template <typename T>
typename Cls<T>::Inner Cls<T>::create_inner()
 T x{};
 typename T::value_type val{};
 return {x, val};
```



### **Ambiguity**

```
template <int N> struct S1
{
  template <int M> struct S2
    static int foo() { return M; }
 };
template <int N>
int bar()
{
  return S1<N>::S2<N>::foo();
```



Which way should the compiler interpret this?

```
template <int N> struct S1
{
   static int const S2{};
};
```

```
S1<N>::S2<N>::foo()
```

```
template <int N> struct S1
{
  template <int M> struct S2
  {
    static int foo() { return M; }
  };
};
```

```
S1<N>::S2<N>::foo()
```



Which way should the compiler interpret this?

```
template <int N> struct S1
{
   static int const S2{};
};
```

```
(S1<N>::S2)<(N>::foo())
```

```
template <int N> struct S1
{
  template <int M> struct S2
  {
    static int foo() { return M; }
  };
};
```

```
(S1<N>)::(S2<N>)::(f00())
```



Which way should the compiler interpret this?

```
template <int N> struct S1
{
   static int const S2{};
};
```

```
S2 < (N > foo())
```

```
template <int N> struct S1
{
  template <int M> struct S2
  {
    static int foo() { return M; }
  };
};
```

```
S2<N>::foo()
```



### But what about this?

```
template <int N> struct S1
 template <int M> struct S2
    static int foo() { return M; }
 };
};
template <> struct S1<1>
 static int const S2{};
};
int foo() { return 1; }
template <int N>
int bar()
 // only works if N = 1 (the specialization)
 return S1<N>::S2<N>::foo();
```



### But what about this?

```
template <int N> struct S1
 template <int M> struct S2
    static int foo() { return M; }
 };
};
template <> struct S1<1>
 static int const S2{};
};
int foo() { return 1; }
template <int N>
int bar()
 // works for the general case but not for N = 1
 return S1<N>::template S2<N>::foo();
```



### Dependent names of templates

- If a name depends on a template (as was the case with S1<N>::S2<N>) the compiler cannot assume that the dependent name is a template
- Therefore the only reasonable interpretation must be that the second < is a comparison</li>
- unless we specify it as a template by adding template before the dependent name
- This is true for all operators which can access names;
   ->, . and ::



What type of entities must A, B and C be?

```
template <typename T>
void bar()
{
  typename T::A a;
  T::B;
  T::C();
}
```



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Template parameters

There are three kinds of template parameters:

- type template parameters
- non-type template parameters
- template template parameters



- What if we want to take a template as a parameter?
- That is, a class template that has not been instantiated?
- It is not possible with the two types we have seen so far, type or non-type template parameters
- This is where template template parameters come in!



```
template<template <typename > typename T>
struct Wrap_Int
{
    T<int> wrapper;
};

template <typename T>
struct X
{
    T data;
};

int main()
{
    Wrap_Int<X> x;
}
```



- Here Wrap\_Int takes X as a template parameter
- X is passed to Wrap\_Int as a class template
- Inside Wrap\_Int, X will then be instantiated with int
- You can think of it as a "template parameters that takes the name of another template"



```
template <typename T, typename U>
struct Y { };
int main()
{
    // does not work, Y takes 2 template parameters
    Wrap_Int<Y> y;

    // does not work, int is not a template
    Wrap_Int<int> z;
}
```



### A more concrete example



### A more concrete example

- C is template that takes two template parameters
- T and U are two arbitrary types
- The parameter c is of type C<T, U>
- We instantiate operator<< with:</li>
  - T = int
  - U = allocator<int>
  - C = vector
- Thus we get vector<int, allocator<int>>



A problem appears on the horizon!

```
int main()
{
  map<int, int> m{{1,2},{3,4},{5,6}};
  cout << m << endl;
}</pre>
```

- This won't work
- std::map takes three template parameters



### Variadic Templates to the rescue!

```
template <template <typename, typename...> typename C,
          typename... Ts>
ostream& operator<<(ostream& os, C<Ts...> const& c)
 for (auto const& e : c)
   os << e << ' ';
 return os;
int main()
 vector<int> v{1,2,3,4};
 map<int, int> m{{1,2},{3,4},{5,6}};
 cout << v << endl;
 // we would need a operator<< for pair<T, U> as well
 cout << m << endl;
```



And now for something completely different...





```
void fun1(int&& x);
template <typename T>
void fun2(T&& x);
int main()
  int x{};
  fun1(5); // works
```



```
void fun1(int&& x);
template <typename T>
void fun2(T&& x);
int main()
  int x{};
  fun1(5); // works
  fun1(x); // doesn't work
```



```
void fun1(int&& x);
template <typename T>
void fun2(T&& x);
int main()
  int x{};
  fun2(5); // works
```



```
void fun1(int&& x);
template <typename T>
void fun2(T&& x);
int main()
  int x{};
  fun2(5); // works
  fun2(x); // works?!
```



**Forwarding References** 

#### T&& denotes:

- a non-const rvalue reference to T
- except if it is a parameter to a function template, where
   T is a template parameter to that function template
- then it denotes a forwarding reference



```
template <typename T>
void foo(T&&);

// generated functions:
```

```
int main()
{
   int x{};
   int const y{};

   foo(5);
   foo(x);
   foo(y);
}
```



```
template <typename T>
void foo(T&&);

// generated functions:
void foo(int&&);

foo(5);
foo(x);
foo(y);
}
```



```
template <typename T>
void foo(T&&);

// generated functions:
void foo(int&&);

void foo(int&);

too(5);
foo(x);
foo(y);
}
```



```
template <typename T>
void foo(T&&);

// generated functions:
void foo(int&&);

void foo(int&);

void foo(int const&);

int main()
{
   int x{};
   int const y{};

   foo(5);
   foo(x);
   foo(y);
}
```



```
template <typename T>
void foo(T&&);

// generated functions:
void foo(int&&);

void foo(int&);

void foo(int const&);
```

```
int main()
{
   int x{};
   int const y{};

   foo(5);
   foo(x);
   foo(y);
}
```



- A forwarding reference can collapse into to any type of reference
- Parameters that are forwarding references will bind to the exact reference that is passed
- Each type of reference passed into the forwarding reference will generate a specific overload



```
template <typename... Ts>
vector<T> store(Ts... list)
{
  vector<T> vec {list...};
  return vec;
}
```



Problems with store

- Every parameter in list is passed by value
- Then they are copied into vec



Problems with store

- Every parameter in list is passed by value
- Then they are copied into vec
- This will cause every parameter passed into the function to be copied twice



Problems with store

- Every parameter in list is passed by value
- Then they are copied into vec
- This will cause every parameter passed into the function to be copied twice
- But we have move-semantics; we should leverage it whenever possible



```
template <typename... Ts>
vector<T> store(Ts&&... list)
{
  vector<T> vec {list...};
  return vec;
}
```



- When we write Ts&&... we apply a pattern on Ts
- This pattern will bind every type in Ts to a forwarding reference
- Thus generating a function which takes every parameter as they are
- But we are not yet using move semantics, because we will still copy everything into vec
- This happens becuase all of these parameters are xvalues, meaning they die at the end of this scope.



```
#include <utility> // std::forward
template <typename... Ts>
vector<T> store(Ts&&... list)
{
  vector<T> vec {std::forward<Ts>(list)...};
  return vec;
}
```



#### std::forward

- std::forward is a function template define in <utility>
- it takes a parameter of arbitrary type T and passes it as the correct type of reference
- this is necessary since binding an rvalue into an rvalue reference will give it a name
- therefore the rvalue itself has become an Ivalue
- std::forward is a way to "turn it back"



Forwarding References & auto

```
int main()
{
  int x{};

  // will become int&&
  auto&& y{5};

  // will become int&
  auto&& z{x};
}
```



What will be printed?

```
void fun(int&) { cout << 1; }
void fun(int const&) { cout << 2; }
void fun(int&&) { cout << 3; }

template <typename T>
void fun2(T&& t) { fun(t); }

int main() {
   int x{};
   int const y{};
   fun2(1);
   fun2(x);
   fun2(y);
}
```



What about now?

```
void fun(int&) { cout << 1; }
void fun(int const&) { cout << 2; }
void fun(int&&) { cout << 3; }

template <typename T>
void fun2(T&& t) { fun(std::forward<T>(t)); }

int main() {
   int x{};
   int const y{};
   fun2(1);
   fun2(x);
   fun2(y);
}
```



Alias Template

### In C++11 alias templates were introduced

```
template <typename T>
using array = std::vector<T>;
```

A template alias refers to a set of template types.



Variable Templates

#### In C++14 variable templates were introduced

```
template <int N>
bool positive {N > 0};

cout << positive<3> << endl;
cout << positive<-1> << endl;</pre>
```



Variable Templates

- A variable template defines a set of variables
- Must be free variables or static member variables
- I.e. data members in a class-type cannot be templated.



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#### Suppose the following:

```
template <typename T, int N>
int size(T const (&arr)[N])
{
   return N;
}

template <typename T>
typename T::size_type size(T const& t)
{
   return t.size();
}
```



How should the compiler handle this case?

When we pass an array of type int(&)[N] into size the compiler will:

- 1. examine each size candidate to see if they fit
- 2. notice that both function templates take one argument
- notice that the second version have return type typename T::size\_type



How should the compiler handle this case?

When we pass an array of type int(&)[N] into size the compiler will:

- see that int(&)[N] is of non-class type, so it cannot have members
- 5. conclude that the second version is invalid

But the first version matches, so should the compiler actually report an error regarding the second version?



The best acronym

# Substitution Failure Is Not An Error



#### Excuse me, what?

- During instantiation of templates the compiler will substitue the template parameters with an actual type or value
- This substitution can fail for many reasons
- If it does fail, it is not consider an error
- Instead the compiler will move on and try to find another match elsewhere



So it is just a special case? Why should I care?

Somebody realized, in the distant time of the 90's that this can be exploited for some awesome things!



#### Controlling the substitution failures



Controlling the substitution failures

- There are 4 overloads of size, numbered #1 to #4
- #1 will fail for all cases where T does not have a type named size\_type (i.e. non-container types)
- #2 will only match arrays (not due to SFINAE)



Controlling the substitution failures

- Nontype template parameters can be pointers
- so if T is a pointer it can be a template parameter
- In #3 we take a nontype template parameter of type T and have nullptr as default-value
- This will fail if T is not a pointer, since nullptr can only be assigned to pointers



#### Controlling the substitution failures

- #4 is a so called variadic function
- variadic functions are a relic from C
- has been made obselete by variadic templates
- a variadic function will only be called if there are no other matching functions
- I.e. it has the lowest priority during overload resolution
- Due to this, it is perfect as a sink



Trigger failure with a bool condition

```
template <bool, typename T = void>
struct enable_if
{
};

template <typename T>
    struct enable_if<true, T>
    {
      using type = T;
};

template <bool N, typename T = void>
    using enable_if_t = typename enable_if<N, T>::type;
```



#### We need to go deeper!

```
template <int N>
enable_if_t<(N >= 0) && (N % 2 == 0)> check()
  cout << "Even!" << endl;
template <int N, typename = enable_if_t<(N >= 0) && (N % 2 == 1)>>
void check()
  cout << "Odd!" << endl:
template <int N>
void check(enable_if_t<(N < 0)> = {})
  cout << "Negative" << endl;
check<0>():
check<3>();
check<-57>();
```



#### Nice SFINAE with C++11

```
// if t has a member size()
template <typename T>
auto size(T const& t) -> decltype(t.size())
{
    return t.size();
}
// if t is a pointer
template <typename T>
auto size(T const& t) -> decltype(*t, -1)
{
    return -1;
}
```

```
// if T is an array
template <typename T, size_t N>
auto size(T const (&)[N])
{
   return N;
}

// sink
int size(...)
{
   return 1;
}
```



...What?

# Let's take it step by step:

- Trailing return type
- decltype
- comma-operator
- Expression SFINAE



Trailing return type

```
auto foo(int x) -> int
{
   return x;
}
```

```
int foo(int x)
{
  return x;
}
```

decltype



#### decltype

- decltype is a specifier that collapses to a type
- decltype(...) will deduce the type of the supplied expression
- decltype((...)) will deduce the type and value category of the supplied expression and return an appropriate reference



the comma-operator

```
char sign{(1, 1.0, 'a')};
bool flag{(cout << 1, true)};</pre>
```



#### the comma-operator

- C++ has an operator called the *comma-operator*
- It takes a comma-separated list of expressions
- evaluates all of the expressions
- · and return the final one
- ... never use it for evil (nor when you are lazy)!



#### **Expression SFINAE**

```
// only match types which can be
// incremented (and default initialized)
template <typename T>
decltype(T{}++) inc(T& t)
{
  return t++;
}
```



#### **Expression SFINAE**

- if a template declaration uses decltype
- every expression in the decltype declaration will trigger a substitution failue if they are invalid
- this is called expression SFINAE



#### Putting it all together!

```
// if t has a member size()
template <typename T>
auto size(T const& t) -> decltype(t.size())
{
    return t.size();
}
// if t is a pointer
template <typename T>
auto size(T const& t) -> decltype(*t, -1)
{
    return -1;
}
```

```
// if T is an array
template <typename T, size_t N>
auto size(T const (&)[N])
{
    return N;
}

// sink
int size(...)
{
    return 1;
}
```



#### What will be printed?

```
template <typename T>
enable_if_t<(sizeof(T) < 4), int> foo(T&&)
{ return 1; }
template <typename T, T = nullptr>
int foo(T&&)
{ return 2; }
template <typename T>
auto foo(T&& t) -> decltype(t.size(), 3)
{ return 3; }
int main()
  vector<int> v{};
  short int s{};
  cout << foo(s)
       << foo(nullptr)
       << foo(v);
```



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