Paper Review - Auto-FuzzyJoin: Auto-Program Fuzzy Similarity Joins Without Labelled Examples

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Fuzzy-join (or similarity join)

		Right Table		
id	Isem		id	Isem
l1	Peppi Azzopardi	K	r1	Karmnu Vassallo
l2	Annetto Depasquale		r2	Ġużeppi Azzopardi
l3	Karmenu Vassallo		r3	Annetto De Pasquale

Left Table Left Table				Right Table				
L-id	L-name	L-director	L-description				R-director	R-description
l1	Carrie	Brian De Palma	Carrie White is shy and outcast	← →	r1	Carrie	Brian DePalma	This classic horror movie based
12	Vibes	Ken Kwapis	Psychics hired to find lost temple		r2	Vibes	Ken Kwapis	Two hapless psychics unwittingly

- Fuzzy join takes two tables as inputs and identifies record pairs that refer to the same entity.
- As an example, I1 and r2 refer to the same person.
- The concept can be extended to records with multiple fields or attributes.

Fuzzy-join configuration







- Fuzzy-join has been integrated into many commercial applications
- These systems are often difficult to use due to the large number of configuration parameters.
- The extension in Microsoft Excel has 19 options that span across 3 dialog boxes.
 - 11 are binary, thus resulting in 2048 possible configuration scenarios.
 - 8 continuous, such as thresholds and biases.
- In order to execute quality Fuzzy-joins, these configurations require careful user setup to achieve high-quality results.

Theoretical foundation: fuzzy join mapping

Given a **reference table** L and a table R containing records that may be **imprecise** or noisy, a **fuzzy join mapping** J establishes approximate matches between them.

- J connects elements of R to similar elements in L based on a chosen **similarity measure** (e.g., Levenshtein distance, cosine similarity, Jaccard similarity).
- Each record $r \in R$ is mapped to at most one record $l \in L$, or **no match at all** (denoted by \bot).
- The join is many-to-one because multiple records in R can be associated with the same record in L, but each r ∈ R has only one possible match.

Formally:

$$J:R \rightarrow L \cup \bot$$

Theoretical foundation: fuzzy join configuration space

A fuzzy join f compares two strings, r and I, by computing a distance score that reflects their similarity. The computation of this score is governed by a variety of parameters, forming a **parameter space**.

Each unique combination of these parameters defines a specific join function $f \in \mathcal{F}$, where \mathcal{F} is the space of all possible join functions.

Prerpocessing - Lowercase - Remove - punctuation - Stemming - ... - Token Weights - uniform weight - IDF weight - IDF weight - ... - ... - ...

Example: fuzzy join distance score computation

Join Function: f = (L, SP, EW, JD)

- · L: Lower-casing (Preprocessing)
- SP: Space Tokenization
- EW: Equal Weights
- JD: Jaccard Distance

Inputs:

- I = "2012 tigers lsu baseball team"
- r = "2012 lsu baseball team"

Tokenization (SP):

- I → {2012, tigers, Isu, baseball, team}
- r → {2012, lsu, baseball, team}

Jaccard Distance:

- $A \cap B = \{2012, lsu, baseball, team\} \rightarrow |A \cap B| = 4$
- $A \cup B = \{2012, tigers, lsu, baseball, team\} \rightarrow |A \cup B| = 5$
- Jaccard Similarity = $\frac{4}{5}$ = 0.8
- Jaccard Distance = 1 0.8 = 0.2

Result: f(I, r) = 0.2

Theoretical foundation: threshold and join configuration

- Once the distance f(I, r) is computed:
 - It is compared to a threshold compared to a threshold θ to decide whether to join the string pair I
 and r.
 - lower θ gives stricter matches
 - If $f(I, r) \le \theta$, the pair is considered a match.
- Together, the function f and the threshold θ define what the authors call a **join configuration**:

$$C = \langle f, \theta \rangle$$

- This configuration encapsulates both:
 - How distance is computed.
 - When two strings are considered similar enough to be joined.

A join configuration C is a 2-tuple $C = \langle f, \theta \rangle$, where $f \in \mathcal{F}$ is a join function, and θ is a threshold. We use $\mathcal{S} = \{ \langle f, \theta \rangle \mid f \in \mathcal{F}, \theta \in \mathbb{R} \}$ to denote the space of join configurations.

Theoretical foundation: fuzzy join mapping

Given two tables L and R , a join configuration $C \in \mathcal{S}$ induces a **fuzzy join mapping** J_C , defined as:

$$J_C(r) = \underset{l \in L, \ f(l,r) \leq \theta}{\arg \min} f(l,r), \ \forall r \in R$$

That is

- For each record $r \in R$, find $l \in L$ that minimizes the distance f(l, r), only if that distance is less than or equal to the threshold θ .
- If no such $l \in L$ exists such that $f(l,r) \leq \theta$, then $J_C(r)$ is maps to \bot i.e., no match for that record.

Theoretical foundation: the problem with single join configurations

Real-world data can exhibit multiple types of variations simultaneously, such as:

- Typos
- Missing tokens
- Extraneous information

As a result, relying on a **single join configuration** often fails to capture all valid matches, particularly when high **recall** is required.

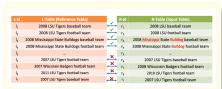
To handle this diversity, the algorithm uses a **set of join configurations**:

$$U = \{C_1, C_2, \ldots, C_K\}$$

Instead of relying on a single configuration, the system computes join results from each one.

This approach allows the system to:

- Accommodate diverse types of variations.
- Improve overall recall by combining multiple perspectives on similarity (different parametrizations that are sensitive to different types of noise).



- A Jaccard distance with threshold 0.2 works well for pairs like (*l*₁, *r*₁), which differ by only one or two tokens.
- However, for pairs like (I₃, r₃) with spelling variations, Jaccard similarity is not enough:
 - Jaccard distance ≈ 0.5 → too high to match under the 0.2 threshold
 - A more suitable metric is Edit
 Distance, which can better align such
 pairs.

Theoretical foundation: fuzzy join via multiple configurations

• To handle this diversity, the algorithm uses a set of join configurations:

$$U = \{C_1, C_2, \ldots, C_K\}$$

- Instead of relying on a single configuration, the system computes join results from each.
- This approach allows the system to:
 - Accommodate diverse types of variations.
 - Improve overall recall by combining multiple perspectives on similarity.

Given L and R, a set of join configurations $U = \{C_1, C_2, \dots, C_K\}$ induces a **fuzzy join mapping** J_U , defined as:

$$J_U(r) = \bigcup_{C_i \in U} J_{C_i}(r), \ \forall r \in R$$

This means that the overall result of the fuzzy join using configuration set U is the **union** of results from all individual configurations $C_i \in U$.

Each configuration $C_i \in U$ is designed to capture a **specific type of string variation** (e.g., typos, missing tokens, extra tokens).

Two records are considered **joined by the set** U **if and only if** they are joined by **at least one** configuration $C_i \in U$.

- Each configuration contributes high-quality joins targeted at particular data challenges.
- The overall join is more robust and comprehensive.

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Theoretical foundation: evaluating join quality; Precision

Given two tables R and L, and a space of join configurations S, the objective is to find a subset $U \subseteq S$ that produces good fuzzy join results. Let:

- J_U be the fuzzy join mapping induced by configuration set U
- J_G be the **ground truth** join mapping the ideal join result

Precision measures how many of the predicted joins are correct:

$$\mathsf{precision}(U) = \frac{\underbrace{\left|\left\{r \in R \mid J_U(r) \neq \emptyset, \ J_U(r) = J_G(r)\right\}\right|}_{\mathsf{True\ Positives\ (TP)}}}{\underbrace{\left|\left\{r \in R \mid J_U(r) \neq \emptyset\right\}\right|}_{\mathsf{TP}\ + \ \mathsf{FP}\ (\mathsf{all\ predicted\ ioins)}}$$

- Numerator (TP): Records where a join was predicted and it matched the ground truth.
- Denominator (TP + FP): All records where a join was predicted (correct or not).
- Only records with a prediction (i.e., $J_U(r) \neq \emptyset$) are evaluated in this precision formula.



Theoretical foundation: evaluating join quality; Recall

Recall measures how many of the correct (ground truth) joins were successfully predicted:

$$\mathsf{recall}(U) = \underbrace{|\{r \in R \mid J_U(r) \neq \emptyset, \ J_U(r) = J_G(r)\}|}_{\mathsf{True \ Positives \ (TP)}}$$

- This is the absolute count of True Positives, i.e., records for which:
 - A join was predicted $(J_U(r) \neq \emptyset)$, and
 - It matches the ground truth $(J_U(r) = J_G(r))$

False Negatives (FN) — cases where a correct join was missed — are defined as:

$$FN = |\{r \in R \mid J_G(r) \neq \emptyset, J_U(r) = \emptyset\}|$$

Note: The denominator TP + FN is constant across all U for a fixed dataset, so it is omitted in comparisons.

Theoretical foundation: Estimating precision without labels

Traditional precision metrics require a labeled ground truth to evaluate the quality of predicted joins.

Auto-FuzzyJoin introduces an unsupervised method to estimate join precision, without labeled data.

- Uses a local geometric heuristic: the number of L records within a 2d-ball around a matched reference point I
- Fewer neighbors imply higher confidence in the match (i.e., higher estimated precision)
- This estimation is:
 - Data-driven: only needs L and R
 - Model-independent: works with any join function f
 - Efficient: avoids costly labeling efforts

This idea enables precision-aware optimization without needing ground truth labels.

Theoretical foundation: estimating Precision/Recall for a single join configuration

Given:

- A single join configuration $C = \langle f, \theta \rangle$
- Two tables:
 - L: reference table
 - R: query table

Assumption: Complete Reference Table L

- L is assumed to contain all possible true matches for records in R.
- Ensures that for each $r \in R$, there exists a correct match $l \in L$.
- Simplifies analysis by reducing the chance of missing true positives due to an incomplete reference.

Geometric View of the Distance Function f

- Join function f embeds records into a metric space.
- Records are conceptually modelled as points on a unit grid.
- Each $l \in L$ is surrounded by **close variants** (differing by a token, character, etc.).
- The distance between each I and the surrounding r's is exploited by θ to compute join pairs.

Analogy: Stars and Planets

- Reference records $l \in L$ are like stars on a grid.
- Query records $r \in R$ are like **planets** that orbit these stars.
- Identifying the best join $J_C(r)$ is like determining which star a planet orbits.

Theoretical foundation: safe joins and the geometry of fuzzy matching

Safe Joins with a Complete L

- Define the **grid width** w: typical distance between a record I and its closest neighbors in L.
- A join is considered safe if the distance d = f(l, r) satisfies:

$$d<\frac{w}{2}$$

This guarantees that r lies closer to its true match I than to any other reference point.

Why This Matters:

- Ensures high precision avoiding false positives caused by ambiguous joins.
- Avoids joining r to an incorrect l' that lies at a similar distance.

Analogy: Stars and Planets

- A planet that lies equidistant between two stars (at $\frac{w}{2}$ each) cannot be confidently claimed by either.
- In fuzzy joining, such cases are inherently ambiguous and risky to resolve.



Theoretical foundation: estimating join precision (local heuristic)

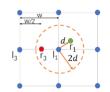
Given a query record $r \in R$ and its closest match $l \in L$, with distance d = f(l, r), we can estimate how **precise** this join is — i.e., how likely it is that (l, r) is a **correct match**.

- The more candidate records in *L* that are close to *r*, the less confident we are about any one being the true match.
- So we count how many other records
 l' ∈ L fall within the 2d-ball centered at l:

$$precision(l, r) = \underbrace{\frac{1}{\lfloor \{l' \in L \mid f(l, l') \le 2f(l, r)\} \rfloor}}_{\text{TP} + \text{FP (local competitors)}}$$

- A small 2*d*-ball → high precision (few competitors).
- A large 2d-ball → low precision (many competitors).

This provides a data-driven estimate of join quality without needing ground truth.



- To estimate the quality of joining r₁, we first find its nearest neighbor in L, which we'll call l₁.
- Compute the distance: $d = f(l_1, r_1)$.
- Draw a ball of radius 2d centered at l_1 .
 - If no other L records fall in the ball → high confidence.
- In this case, the 2*d*-ball contains only *l*₁:

$$\mathsf{precision}(\mathit{l}_1,\mathit{r}_1) = \frac{1}{1} = 1$$

High confidence join.

Theoretical foundation: When L is incomplete

Problem: When L is incomplete (i.e., some records are missing):

- Missing records in L result in missing stars in the grid.
- A record r may join to the wrong I, causing false positives and reducing precision.
- Example: If r₂ should match with l₂ (but l₂ is missing), it might instead match l₁ using d = f(r₂, l₁).

Note:

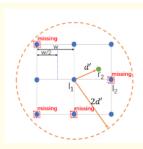
 Even if some records in L are missing, safe decisions can still be made.

Precision estimation:

- r₂ should match l₂ (missing), so l₁ becomes the fallback.
- The 2d'-ball around l₁ contains 5 records.
- Precision:

$$precision(I_1, r_2) = \frac{1}{5}$$

• ⇒ Low confidence join



- r_2 should join with l_2 , but l_2 is missing
- I₁ becomes the closest available record
- Compute distance $d' = f(I_1, r_2)$
- Draw a 2d'-ball around l_1
 - If the ball includes many other L records $\rightarrow d'$ is too lax
 - Join becomes unreliable

Theoretical foundation: Estimating Precision and Recall for a configuration

A configuration $C = \langle f, \theta \rangle$ includes:

- A join function f
- A threshold θ
- 1. Local precision for a join

$$precision(r, C) = \frac{1}{|\{l' \in L \mid f(l, l') \leq 2f(l, r)\}|}$$

- J_C(r) = I: join match for r ∈ R
- Denominator = number of plausible alternatives
- 2. Expected true positives

$$TP(C) = \sum_{r \in R, J_C(r) \neq \emptyset} precision(r, C)$$

3. Expected false positives

$$FP(C) = \sum_{r \in R, J_C(r) \neq \emptyset} (1 - \operatorname{precision}(r, C))$$

4. Overall Precision and Recall

$$precision(C) = \frac{TP(C)}{TP(C) + FP(C)}$$
 $recall(C) = TP(C)$

Note: Recall is estimated absolutely since ground truth is unavailable.



Understanding TP and FP contributions

True Positives (TP) and False Positives (FP) are calculated from the estimated precision of each join:

- If a configuration joins a record r with high estimated precision \rightarrow contributes more to TP
- If a join has low estimated precision → contributes more to FP

Formula Review:

$$TP(C) = \sum_{r \in R, J_C(r) \neq \emptyset} \mathsf{precision}(r, C)$$

$$FP(C) = \sum_{r \in R, J_C(r) \neq \emptyset} (1 - \mathsf{precision}(r, C))$$

Implication:

- Adding a configuration to *U* increases recall (more joins)
- But can hurt precision if added joins are unreliable
- Greedy selection prefers configurations that give more TP per unit FP

Example: Precision and Recall estimation

Setup: Assume 3 records in R, joined to L using configuration $C = \langle f, \theta \rangle$.

Join Results:

- $J_C(r_1) = I_1$, $f(I_1, r_1) = 0.1$, 5 plausible matches \Rightarrow precision $(r_1, C) = \frac{1}{5} = 0.20$
- $J_C(r_2) = l_2$, $f(l_2, r_2) = 0.05$, 2 plausible matches \Rightarrow precision $(r_2, C) = \frac{1}{2} = 0.50$
- $J_C(r_3) = I_3$, $f(I_3, r_3) = 0.2$, 4 plausible matches \Rightarrow precision $(r_3, C) = \frac{1}{4} = 0.25$

Estimated TP and FP:

$$TP(C) = 0.20 + 0.50 + 0.25 = 0.95$$

 $FP(C) = (1 - 0.20) + (1 - 0.50) + (1 - 0.25) = 2.05$

Estimated Precision and Recall:

$$\mathsf{precision}(\mathit{C}) = \frac{0.95}{0.95 + 2.05} = \frac{0.95}{3.00} \approx 0.317$$

$$recall(C) = TP(C) = 0.95$$

Note: This example assumes no ground truth; hence recall is based on expected TP count.



Theoretical foundation: Precision and Recall for a set of configurations

Let $U = \{C_1, C_2, \dots, C_K\}$ be a set of configurations.

Case 1: No Conflicts in U

• Each record $r \in R$ is matched by at most one configuration:

$$\forall r \in R, \quad |J_U(r)| \leq 1$$

• Then:

$$TP(U) = \sum_{C \in U} TP(C), \quad FP(U) = \sum_{C \in U} FP(C)$$

Case 2: Conflicting Assignments in U

- Multiple configurations suggest different joins for the same r
- Resolve conflicts by:
 - **1** Compare precision scores: precision (r, C_i) vs. precision (r, C_j)
 - 2 Choose the match with higher precision
 - **3** Assign that join to $J_U(r)$
 - 4 Recompute TP(U) and FP(U)

Final Estimates:

$$precision(U) = \frac{TP(U)}{TP(U) + FP(U)}$$
 $recall(U) = TP(U)$



Example: resolving conflicting joins from multiple configurations

Context: Two configurations propose different joins for the same record $r \in R$ using different string similarity methods.

Configurations:

- $C_1 = \langle f_1, \theta_1 \rangle$, where f_1 uses Jaccard distance over space-tokenized lowercase strings with equal weights.
- $C_2 = \langle f_2, \theta_2 \rangle$, where f_2 uses Cosine similarity over character trigrams with TF-IDF weighting.

Join Proposals for r:

- C_1 : $J_{C_1}(r) = I_1$ with precision $(r, C_1) = \frac{1}{4} = 0.25$
- C_2 : $J_{C_2}(r) = I_2$ with precision $(r, C_2) = \frac{1}{2} = 0.50$

Conflict Resolution Strategy:

Compare estimated precision:

$$precision(r, C_1) = 0.25 < precision(r, C_2) = 0.50$$

2 Assign $J_U(r) = I_2$ (higher-confidence match from C_2)

Effect:

- TP(U) and FP(U) incorporate only the winning match.
- · Competing matches are discarded.



Auto-FuzzyJoin Algorithm: single column case

Recall-Maximizing Fuzzy Join (RM-FJ) is **NP-hard**. Use a **greedy approximation algorithm** called AutoFJ.

Objective:

• Maximize recall TP(U) subject to maintaining precision(U) $\geq \tau$

Greedy Strategy:

- Select configurations that:
 - Increase true positives (recall)
 - Minimize false positives (preserve precision)
- Guided by the Profit Metric:

$$profit(U) = \frac{TP(U)}{FP(U)}$$

Blocking Heuristic:

- To reduce the number of comparisons, apply 3-gram blocking.
- Each string is decomposed into overlapping sequences of 3 characters (3-grams).
- Only record pairs that share at least one common 3-gram are considered for joining.
- . This blocks out obviously dissimilar pairs and speeds up computation.
- Applied to both L-L and L-R candidate pairs:

 $LL, LR \leftarrow$ generate candidate pairs using 3-gram overlap

Algorithm 1 AUTOFJ for single column

15: return U

```
Require: Tables L and R, precision target \tau, search space S
1: LL, LR \leftarrow apply blocking with L - L and L - R

 LR ← Learn negative-rules from LL and apply rules on LR (Alg. 2)

3: Compute distance with different join functions f \in S

    Pre-compute precision estimation for each configuration C ∈ S

5: U ← Ø
 6: while S \ U ≠ Ø do
       max profit \leftarrow 0
       for all C \in S \setminus U do
           if profit(U \cup \{C\}) > max profit then
              C^* \leftarrow C, max_profit \leftarrow profit (U \cup \{C\})
       if precision(U \cup \{C^*\}) > \tau then
12:
           U \leftarrow U \cup \{C^*\}
13:
       else
           break
```

Problem formulation and complexity

Goal: Identify a set of join configurations $U \subseteq \mathcal{S}$ such that:

- Maximizes recall: TP(U)
- Satisfies precision constraint: precision(U) $\geq \tau$

Formal problem definition: Recall-maximizing fuzzy join (RM-FJ)

Given reference table L, query table R, and configuration space \mathcal{S} , find a subset $U\subseteq\mathcal{S}$ to:

$$\max_{U \subseteq S} TP(U) \quad \text{subject to} \quad \text{precision}(U) \ge \tau$$

Computational Complexity:

- The RM-FJ problem is shown to be NP-hard.
- ullet Exact search over all subsets of ${\mathcal S}$ is computationally infeasible.
- Justifies use of greedy approximation (AutoFJ).

Blocking for efficient candidate generation

Motivation:

- Naively comparing every $r \in R$ with every $l \in L$ is computationally expensive.
- We use a blocking technique to generate a smaller candidate set for similarity evaluation.

Technique: 3-Gram Blocking

- Each string is decomposed into overlapping substrings of 3 characters (3-grams).
- Only consider (r, l) pairs that share at least one common 3-gram.
- Applied on both L-L (for negative rule learning) and L-R (for actual join candidates).

Impact:

- · Reduces the number of unnecessary comparisons.
- Increases efficiency without significant recall loss.

1. 3-Gram blocking using TF-IDF

LL, LR \leftarrow apply 3-gram blocking on L-L and L-R

```
Reference Table L: \begin{array}{ccc} I_1 & \text{"john smith"} \\ I_2 & \text{"jane smythe"} \\ I_3 & \text{"alice johnson"} \end{array}
```

Query Record r_1 : "jon smyth"

Step 1: Preprocessing (P)

- Lowercasing (already lowercase)
- Add padding for 3-grams: e.g., "john smith" \rightarrow "##john#smith##"

Step 2: Tokenization (T)

- r₁: ##j, #jo, jon, on# , n#s, #sm, smy, myt, yth, th#, h##
- I1, I2: similar 3-gram sequences

Step 3: Token Weighting (W)

- Use TF-IDF to emphasize rare, meaningful trigrams (e.g., smy, yth)
- r₁-l₂: High score(rare overlapping trigrams), r₁-l₁: Medium (more common overlap), r₁-l₃: Zero (no shared trigrams)

Blocking Result:

• Only compare r_1 with l_1 , $l_2 \rightarrow$ prune l_3

2. Optimization - filtering with negative rules

 $LR \leftarrow Learn negative-rules from LL and apply rules on LR (Alg. 2)$

Assumption: Although 3-gram blocking may have pruned l3, we assume here it was retained due to weak overlap, allowing us to illustrate negative-rule filtering.

Goal: Use obvious non-matches in L-L to learn rules that help filter unlikely L-R pairs before costly distance computations.

Step 1: Generate LL — Self-Join on L using 3-gram blocking

Pair	Shared 3-grams	Interpretation
l_1 vs l_2	sm, smy, th	Possibly similar
I_1 vs I_3	jo, on	Clearly different
12 vs 13	Weak overlap	Probably different

Learn Negative Rule:

"If 3-gram overlap < 2, treat as a non-match."

Overlap Apply Rule? r1. /1 ~ 4 Nο Step 2: Apply Rule on LR Candidate Pairs ~ 5 Nο ~ 1 Yes r1. 12

Effect: Filter out clearly irrelevant pairs early — no need to compute Jaccard or Edit Distance!

Pair

Keep?

Yes

Yes

Nο

3. Compute distances - apply join functions

Compute distance with different join functions $f\in\mathcal{S}$ Pre-compute precision estimation for each configuration $\mathcal{C}\in\mathcal{S}$

Once candidate pairs are identified (via blocking and optional negative rules), we compute the actual similarity using multiple join functions $f \in \mathcal{S}$.

Each join function is defined by:

- Preprocessing (e.g., lowercasing, punctuation removal)
- Tokenization (e.g., char 3-grams, word tokens)
- Token weights (e.g., TF-IDF)
- Distance function (e.g., Jaccard, Cosine, Edit)

	r (query)	I (reference)
Example Candidate Pairs (after blocking):	"jon smyth"	"john smith"
	"jon smyth"	"jane smythe"

	Function f	Tokenizer	Distance	Description
Join Functions in \mathcal{S} :	f_1	char 3-grams	Jaccard	Overlap in token sets
Join Functions in 3:	f_2	char 3-grams	Cosine (TF-IDF)	Weighted similarity
	f_3	raw string	Levenshtein	Edit distance
	Pair	fı fo	s,	

	Pair	f_1	f_2	f_3
Computed Scores:	jon vs john	0.4	0.5	2
	jon vs jane	0.6	0.7	3

Note: Distances may follow different scales — lower often means more similar.

4. Start of greedy algorithm

$$\texttt{Initialize:} \quad \textit{U} \leftarrow \emptyset$$

 ${\it U}$ will hold the selected join configurations:

$$C = \langle f, \theta \rangle$$

Each configuration includes:

- A join function $f \in \mathcal{F}$ (defined by P, T, W, D)
- A distance threshold θ (max allowed distance for a match)

Goal:

- Select a subset $U \subseteq \mathcal{S}$ from all candidate configurations
- Maximize recall: TP(U)
- Maintain precision: precision(U) $\geq \tau$

	Config C	Description
Example: Precomputed configuration set <i>S</i>	$C_1 = \langle f_1, 0.37 \rangle$ $C_2 = \langle f_2, 0.42 \rangle$ $C_3 = \langle f_3, 2 \rangle$	Jaccard distance with $\theta=0.37$ Cosine distance with $\theta=0.42$ Edit distance with $\theta=2$
	, ,	

These θ values were selected based on prior precision–recall evaluation for each f .



5. Main greedy loop

Main Loop: while $S \setminus U \neq \emptyset$ do

We continue as long as there are still unused configurations to consider.

Notation:

- S: full set of candidate configurations, each $C = \langle f, \theta \rangle$
- U: set of selected configurations
- $S \setminus U$: unused configurations

At each iteration:

- **1** Evaluate each $C \in S \setminus U$
- 2 Compute profit: how many true positives vs. false positives it contributes
- **3** Select the best configuration C^*

$$U \leftarrow U \cup \{C^*\}$$

Example state:

- $S = \{ \langle f_1, 0.37 \rangle, \langle f_2, 0.42 \rangle, \langle f_3, 2 \rangle \}$
- U = ∅

Loop continues while there are remaining candidates and precision can be preserved.

6. Find most promising configuration (profit heuristic)

$$\begin{aligned} & \max_\text{profit} \; \leftarrow \; 0 \\ & \text{for all} \quad C \in S \setminus U \quad \text{do} \\ & \text{if} \quad & \text{profit}(U \cup \{C\}) > \max_\text{profit} \; \text{then} \\ & \quad & \quad & C^* \; \leftarrow \; C, \; \max_\text{profit} \; \leftarrow \; \text{profit}(U \cup \{C\}) \end{aligned}$$

Profit Formula:

$$\operatorname{profit}(U \cup \{C\}) = \frac{TP(U \cup \{C\})}{FP(U \cup \{C\})}$$

	Config C	TP	FP	Profit = TP / FP		
Evamala	C_1	4	2	2.0		
Example:	C_2	5	5	1.0		
	$\overline{C_3}$	3	1	3.0		
After evaluation: $C^* = C_3$, max_profit = 3.0						

Heuristic: choose the configuration that gives the most recall "bang" per unit of precision "risk."



7. Precision constraint check & termination

Check: if
$$precision(U \cup \{C^*\}) > \tau$$
 then $U \leftarrow Ucup\{C^*\}$

After selecting the best candidate C^* (based on profit), we must verify that adding it to U preserves minimum required precision τ .

- If precision passes: add C* to U
- · Else: break no remaining configs will satisfy the constraint

Example 1 (Pass):
$$\frac{\text{Config}}{C_3}$$
 TP FP Profit Precision τ 3.0 0.75 0.7

 \Rightarrow Precision $> \tau \rightarrow$ Accept $\rightarrow U \leftarrow \{C_3\}$

Example 2 (Fail & Break):
$$\frac{\text{Config}}{C_3}$$
 $\frac{\text{TP}}{3}$ $\frac{\text{FP}}{3}$ $\frac{\text{Profit}}{3}$ $\frac{\text{Precision}}{3}$ $\frac{\tau}{3}$

 \Rightarrow Precision < au o Reject o Stop Loop

Greedy termination: If best config can't meet τ , no others will.



8. Return final join plan

Return: U

The greedy loop terminates when:

- $S \setminus U = \emptyset$ (all configs evaluated), or
- The best candidate fails the precision constraint

The algorithm returns U: a set of selected configurations:

- Each $C = \langle f, \theta \rangle$
- Maximizes recall while keeping precision(U) $> \tau$

Each configuration in U defines:

- A join function f (e.g., Jaccard, Cosine, Edit Distance)
- A threshold θ used to accept matches

Example Output:

• $U = \{ \langle f_2 = \mathsf{Cosine}, \theta = 0.5 \rangle, \langle f_3 = \mathsf{Edit}, \theta = 2 \rangle \}$

These are used to perform the final fuzzy similarity join.



Example: Selecting the best match

1. Input Setup:

- Query record: r₁ = "jon smyth"
- Reference table: $L = \{"john smith", "jane smythe", "alice johnson"\}$
- After blocking: candidates for r_1 are l_1 and l_2

	Join Function f	θ	$f(r_1, I_1)$	$f(r_1, I_2)$	Matches?
2. Distance Results:	Jaccard (3-grams)	0.4	0.5	0.3	l_2 only
2. Distance Results.	Cosine (TF-IDF)	0.5	0.6	0.4	I_2 only
	Edit Distance	2.0	2	3	l_1 only

3. Final Configuration Set *U*:

- $U = \{ \langle f_2 = \text{Cosine}, \ \theta = 0.5 \rangle, \ \langle f_3 = \text{Edit}, \ \theta = 2 \rangle \}$
- Under Cosine: $r_1 \mapsto l_2$
- Under Edit Distance: $r_1 \mapsto l_1$

4. Conflict Resolution: Local Precision

$$precision(r, C) = \frac{1}{|\{l' \in L | f(l, l') \le 2f(l, r)\}|}$$

Config C	Match	f(I,r)	2 <i>d</i> -ball size	Precision
C ₂ (Cosine)	l ₂	0.4	5	1/5 = 0.2
C_3 (Edit)	I_1	2	2	1/2 = 0.5

Result: "jon smyth" is matched to "john smith" (Edit Distance), since it has higher estimated precision (0.5 > 0.2).