Paper Review - Auto-FuzzyJoin: Auto-Program Fuzzy Similarity Joins Without Labelled Examples

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Fuzzy-join (or similarity join)

| | Left Table | | Right Table |
|----|--------------------|-------------|---------------------|
| id | Isem | id | Isem |
| l1 | Peppi Azzopardi 🔸 | r1 | Karmnu Vassallo |
| ι2 | Annetto Depasquale | ≯ r2 | Ġużeppi Azzopardi |
| l3 | Karmenu Vassallo | r3 | Annetto De Pasquale |

| Left Table | | | | | Right Table | | | |
|------------|--------|----------------|------------------------------------|--|-------------|--------|---------------|----------------------------------|
| L-id | L-name | L-director | L-description | | R-id | R-name | R-director | R-description |
| l1 | Carrie | Brian De Palma | Carrie White is shy and outcast < | | → r1 | Carrie | Brian DePalma | This classic horror movie based |
| l2 | Vibes | Ken Kwapis | Psychics hired to find lost temple | | r2 | Vibes | Ken Kwapis | Two hapless psychics unwittingly |

- Fuzzy join takes two tables as inputs and identifies record pairs that refer to the same entity.
- As an example, I1 and r2 refer to the same person.
- The concept can be extended to records with multiple fields or attributes.

Fuzzy-join configuration







- Fuzzy-join has been integrated into many commercial applications
- These systems are often difficult to use due to the large number of configuration parameters.
- The extension in Microsoft Excel has 19 options that span across 3 dialog boxes.
 - 11 are binary, thus resulting in 2048 possible configuration scenarios.
 - 8 continuous, such as thresholds and biases.
- In order to execute quality Fuzzy-joins, these configurations require careful user setup to achieve high-quality results.

Theoretical foundation: fuzzy join mapping

Given a **reference table** L and a table R containing records that may be **imprecise** or noisy, a **fuzzy join mapping** J establishes approximate matches between them.

- J connects elements of R to similar elements in L based on a chosen **similarity measure** (e.g., Levenshtein distance, cosine similarity, Jaccard similarity).
- Each record $r \in R$ is mapped to at most one record $l \in L$, or **no match at all** (denoted by \bot).
- The join is many-to-one because multiple records in R can be associated with the same record in L, but each r ∈ R has only one possible match.

Formally:

$$J:R \rightarrow L \cup \bot$$

Theoretical foundation: fuzzy join configuration space

A fuzzy join f compares two strings, r and I, by computing a distance score that reflects their similarity. The computation of this score is governed by a variety of parameters, forming a **parameter space**.

Each unique combination of these parameters defines a specific join function $f \in \mathcal{F}$, where \mathcal{F} is the space of all possible join functions.

Prerpocessing Tokenization Token Weights Distance function Lowercase Remove punctuation Stemming In the property of the property of

Example: fuzzy join distance score computation

Join Function: f = (L, SP, EW, JD)

- · L: Lower-casing (Preprocessing)
- SP: Space Tokenization
- EW: Equal Weights
- JD: Jaccard Distance

Inputs:

- / = "2012 tigers lsu baseball team"
- r = "2012 lsu baseball team"

Tokenization (SP):

- I → {2012, tigers, Isu, baseball, team}
- r → {2012, lsu, baseball, team}

Jaccard Distance:

- A ∩ B = {2012, Isu, baseball, team} → |A ∩ B| = 4
- $A \cup B = \{2012, tigers, lsu, baseball, team\} \rightarrow |A \cup B| = 5$
- Jaccard Similarity = $\frac{4}{5}$ = 0.8
- Jaccard Distance = 1 0.8 = 0.2

Result: f(I, r) = 0.2

Theoretical foundation: threshold and join configuration

- Once the distance f(I, r) is computed:
 - It is compared to a threshold compared to a threshold θ to decide whether to join the string pair I
 and r.
 - lower θ gives stricter matches
 - If $f(I, r) \le \theta$, the pair is considered a match.
- Together, the function f and the threshold θ define what the authors call a **join configuration**:

$$C = \langle f, \theta \rangle$$

- This configuration encapsulates both:
 - · How distance is computed.
 - When two strings are considered similar enough to be joined.

A join configuration C is a 2-tuple $C = \langle f, \theta \rangle$, where $f \in \mathcal{F}$ is a join function, and θ is a threshold. We use $\mathcal{S} = \{ \langle f, \theta \rangle \mid f \in \mathcal{F}, \theta \in \mathbb{R} \}$ to denote the space of join configurations.

Theoretical foundation: fuzzy join mapping

Given two tables L and R , a join configuration $C \in \mathcal{S}$ induces a fuzzy join mapping J_C , defined as:

$$J_C(r) = \underset{l \in L, \ f(l,r) \le \theta}{\arg \min} f(l,r), \ \forall r \in R$$

That is

- For each record $r \in R$, find $l \in L$ that minimizes the distance f(l, r), only if that distance is less than or equal to the threshold θ .
- If no such $l \in L$ exists such that $f(l,r) \leq \theta$, then $J_C(r)$ is maps to \bot i.e., no match for that record.

Theoretical foundation: the problem with single join configurations

Real-world data can exhibit multiple types of variations simultaneously, such as:

- Typos
- Missing tokens
- Extraneous information

As a result, relying on a **single join configuration** often fails to capture all valid matches, particularly when high **recall** is required.

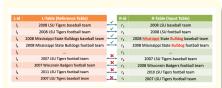
To handle this diversity, the algorithm uses a **set of join configurations**:

$$U = \{C_1, C_2, \ldots, C_K\}$$

Instead of relying on a single configuration, the system computes join results from each one.

This approach allows the system to:

- Accommodate diverse types of variations.
- Improve overall recall by combining multiple perspectives on similarity (different parametrizations that are sensitive to different types of noise).



- A Jaccard distance with threshold 0.2 works well for pairs like (*l*₁, *r*₁), which differ by only one or two tokens.
- However, for pairs like (I₃, r₃) with spelling variations, Jaccard similarity is not enough:
 - Jaccard distance ≈ 0.5 → too high to match under the 0.2 threshold
 - A more suitable metric is Edit
 Distance, which can better align such
 pairs.

Theoretical foundation: fuzzy join via multiple configurations

• To handle diversity, the algorithm uses a **set of join configurations**:

$$U = \{C_1, C_2, \ldots, C_K\}$$

• Instead of relying on a single configuration, the system computes join results from each.

Given L and R, a set of join configurations $U = \{C_1, C_2, \dots, C_K\}$ induces a **fuzzy join mapping** J_U , defined as:

$$J_U(r) = \bigcup_{C_i \in U} J_{C_i}(r), \ \forall r \in R$$

This means that the overall result of the fuzzy join using configuration set U is the **union** of results from all individual configurations $C_i \in U$.

Each configuration $C_i \in U$ is designed to capture a **specific type of string variation** (e.g., typos, missing tokens, extra tokens).

Two records are considered joined by the set U if and only if they are joined by at least one configuration $C_i \in U$.

- Each configuration contributes high-quality joins targeted at particular data challenges.
- The overall join is more robust and comprehensive.



Theoretical foundation: evaluating join quality; Precision

Given two tables R and L, and a space of join configurations S, the objective is to find a subset $U \subseteq S$ that produces good fuzzy join results. Let:

- J_U be the fuzzy join mapping induced by configuration set U
- J_G be the **ground truth** join mapping the ideal join result

Precision measures how many of the predicted joins are correct:

$$\mathsf{precision}(U) = \frac{\underbrace{\left|\left\{r \in R \mid J_U(r) \neq \emptyset, \ J_U(r) = J_G(r)\right\}\right|}_{\mathsf{True\ Positives\ (TP)}}}{\underbrace{\left|\left\{r \in R \mid J_U(r) \neq \emptyset\right\}\right|}_{\mathsf{TP}\ + \ \mathsf{FP}\ (\mathsf{all\ predicted\ ioins)}}$$

- Numerator (TP): Records where a join was predicted and it matched the ground truth.
- Denominator (TP + FP): All records where a join was predicted (correct or not).
- Only records with a prediction (i.e., $J_U(r) \neq \emptyset$) are evaluated in this precision formula.



Theoretical foundation: evaluating join quality; Recall

Recall measures how many of the correct (ground truth) joins were successfully predicted:

$$\mathsf{recall}(U) = \underbrace{|\{r \in R \mid J_U(r) \neq \emptyset, \ J_U(r) = J_G(r)\}|}_{\mathsf{True \ Positives \ (TP)}}$$

- This is the absolute count of True Positives, i.e., records for which:
 - A join was predicted $(J_U(r) \neq \emptyset)$, and
 - It matches the ground truth $(J_U(r) = J_G(r))$

False Negatives (FN) — cases where a correct join was missed — are defined as:

$$\mathsf{FN} = |\{r \in R \mid J_{\mathsf{G}}(r) \neq \emptyset, \ J_{\mathsf{U}}(r) = \emptyset\}|$$

Note: The denominator TP + FN is constant across all U for a fixed dataset, so it is omitted in comparisons.

Theoretical foundation: Estimating precision without labels

Traditional precision metrics require a labeled ground truth to evaluate the quality of predicted joins.

Auto-FuzzyJoin introduces an unsupervised method to estimate join precision, without labeled data.

- Uses a local geometric heuristic: the number of L records within a 2d-ball around a matched reference point I
- Fewer neighbors imply higher confidence in the match (i.e., higher estimated precision)
- This estimation is:
 - Data-driven: only needs L and R
 - Model-independent: works with any join function f
 - Efficient: avoids costly labeling efforts

This idea enables precision-aware optimization without needing ground truth labels.

Theoretical foundation: estimating Precision/Recall for a single join configuration

Given:

- A single join configuration $C = \langle f, \theta \rangle$
- Two tables:
 - L: reference table
 - R: query table

Assumption: Complete Reference Table L

- L is assumed to contain all possible true matches for records in R, that is for each r∈ R, there exists a
 correct match l∈ L.
- This simplifies analysis by reducing the chance of missing true positives due to an incomplete reference.

Geometric View of the Distance Function f

- Join function f embeds records into a metric space.
- Records are conceptually modelled as points on a unit grid.
- Each $l \in L$ is surrounded by **close variants** (differing by a token, character, etc.).
- The distance between each I and the surrounding r's is exploited by θ to compute join pairs.

Analogy: Stars and Planets

- Reference records $I \in L$ are like stars on a grid.
- Query records $r \in R$ are like **planets** that orbit these stars.
- Identifying the best join $J_C(r)$ is like determining which star a planet orbits.

Theoretical foundation: safe joins and the geometry of fuzzy matching

Safe Joins with a Complete L

- Define the **grid width** w: typical distance between a record I and its closest neighbors in L.
- A join is considered safe if the distance d = f(I, r) satisfies:

$$d<\frac{w}{2}$$

• This guarantees that r lies closer to its true match I than to any other reference point.

Why This Matters:

- Ensures high precision avoiding false positives caused by ambiguous joins.
- Avoids joining r to an incorrect I' that lies at a similar distance.

Analogy: Stars and Planets

- A planet that lies equidistant between two stars (at $\frac{w}{2}$ each) cannot be confidently claimed by either.
- In fuzzy joining, such cases are inherently ambiguous and risky to resolve.

Theoretical foundation: estimating join precision (local heuristic)

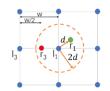
Given a query record $r \in R$ and its closest match $l \in L$, with distance d = f(l, r), we can estimate how **precise** this join is — i.e., how likely it is that (l, r) is a **correct match**.

- The more candidate records in *L* that are close to *r*, the less confident we are about any one being the true match.
- So we count how many other records
 l' ∈ L fall within the 2d-ball centered at l:

$$precision(l, r) = \underbrace{\frac{1}{\lfloor \{l' \in L \mid f(l, l') \le 2f(l, r)\} \rfloor}}_{\text{TP} + \text{FP (local competitors)}}$$

- A small 2d-ball → high precision (few competitors).
- A large 2d-ball → low precision (many competitors).

This provides a data-driven estimate of join quality without needing ground truth.



- To estimate the quality of joining r₁, we first find its nearest neighbor in L, which we'll call l₁.
- Compute the distance: $d = f(l_1, r_1)$.
- Draw a ball of radius 2d centered at l_1 .
 - If no other L records fall in the ball → high confidence.
- In this case, the 2*d*-ball contains only I_1 :

$$\mathsf{precision}(\mathit{I}_1,\mathit{r}_1) = \frac{1}{1} = 1$$

High confidence join.

Theoretical foundation: When L is incomplete

Problem: When L is incomplete (i.e., some records are missing):

- Missing records in L result in missing stars in the grid.
- A record r may join to the wrong I, causing false positives and reducing precision.
- Example: If r₂ should match with l₂ (but l₂ is missing), it might instead match l₁ using d = f(r₂, l₁).

Note:

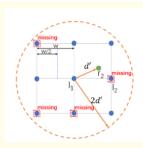
 Even if some records in L are missing, safe decisions can still be made.

Precision estimation:

- r₂ should match l₂ (missing), so l₁ becomes the fallback.
- The 2d'-ball around l₁ contains 5 records.
- Precision:

$$precision(I_1, r_2) = \frac{1}{5}$$

• ⇒ Low confidence ioin



- r_2 should join with l_2 , but l_2 is missing
- I1 becomes the closest available record
- Compute distance $d' = f(I_1, r_2)$
- Draw a 2d'-ball around l_1
 - If the ball includes many other L records $\rightarrow d'$ is too lax
 - Join becomes unreliable

Theoretical foundation: Estimating Precision and Recall for a configuration

A configuration $C = \langle f, \theta \rangle$ includes:

- A join function f
- A threshold θ
- 1. Local precision for a join

$$\mathsf{precision}(r,\,\mathcal{C}) = \frac{1}{|\{\mathit{I'} \in \mathit{L} \mid \mathit{f}(\mathit{I},\,\mathit{I'}) \leq 2\mathit{f}(\mathit{I},\,r)\}|}$$

- J_C(r) = I: join match for r ∈ R
- Denominator = number of plausible alternatives
- 2. Expected true positives

$$TP(C) = \sum_{r \in R, J_C(r) \neq \emptyset} precision(r, C)$$

3. Expected false positives

$$FP(C) = \sum_{r \in R, J_C(r) \neq \emptyset} (1 - \operatorname{precision}(r, C))$$

4. Overall Precision and Recall

$$\mathsf{precision}(\mathcal{C}) = \frac{\mathit{TP}(\mathcal{C})}{\mathit{TP}(\mathcal{C}) + \mathit{FP}(\mathcal{C})} \qquad \mathsf{recall}(\mathcal{C}) = \mathit{TP}(\mathcal{C})$$

Note: Recall is estimated absolutely since ground truth is unavailable.



Understanding TP and FP contributions

True Positives (TP) and False Positives (FP) are calculated from the estimated precision of each join:

- If a configuration joins a record r with high estimated precision \rightarrow contributes more to TP
- If a join has low estimated precision → contributes more to FP

Formula Review:

$$TP(C) = \sum_{r \in R, J_C(r) \neq \emptyset} \mathsf{precision}(r, C)$$

$$FP(C) = \sum_{r \in R, J_C(r) \neq \emptyset} (1 - \mathsf{precision}(r, C))$$

Implication:

- Adding a configuration to *U* increases recall (more joins)
- But can hurt precision if added joins are unreliable
- Greedy selection prefers configurations that give more TP per unit FP

Example: Precision and Recall estimation

Setup: Assume 3 records in R, joined to L using configuration $C = \langle f, \theta \rangle$.

Join Results:

- $J_C(r_1) = I_1$, $f(I_1, r_1) = 0.1$, 5 plausible matches \Rightarrow precision $(r_1, C) = \frac{1}{5} = 0.20$
- $J_C(r_2) = l_2$, $f(l_2, r_2) = 0.05$, 2 plausible matches \Rightarrow precision $(r_2, C) = \frac{1}{2} = 0.50$
- $J_C(r_3) = I_3$, $f(I_3, r_3) = 0.2$, 4 plausible matches \Rightarrow precision $(r_3, C) = \frac{1}{4} = 0.25$

Estimated TP and FP:

$$TP(C) = 0.20 + 0.50 + 0.25 = 0.95$$

 $FP(C) = (1 - 0.20) + (1 - 0.50) + (1 - 0.25) = 2.05$

Estimated Precision and Recall:

$$precision(C) = \frac{0.95}{0.95 + 2.05} = \frac{0.95}{3.00} \approx 0.317$$

$$recall(C) = TP(C) = 0.95$$

Note: This example assumes no ground truth; hence recall is based on expected TP count.



Theoretical foundation: Precision and Recall for a set of configurations

Let $U = \{C_1, C_2, \dots, C_K\}$ be a set of configurations.

Case 1: No Conflicts in U

• Each record $r \in R$ is matched by at most one configuration:

$$\forall r \in R$$
, $|J_U(r)| \leq 1$

• Then:

$$TP(U) = \sum_{C \in U} TP(C), \quad FP(U) = \sum_{C \in U} FP(C)$$

Case 2: Conflicting Assignments in U

- Multiple configurations suggest different joins for the same r
- Resolve conflicts by:
 - **1** Compare precision scores: precision (r, C_i) vs. precision (r, C_j)
 - 2 Choose the match with higher precision
 - **3** Assign that join to $J_U(r)$
 - \bigcirc Recompute TP(U) and FP(U)

Final Estimates:

$$precision(U) = \frac{TP(U)}{TP(U) + FP(U)}$$
 $recall(U) = TP(U)$



Example: resolving conflicting joins from multiple configurations

Context: Two configurations propose different joins for the same record $r \in R$ using different string similarity methods.

Configurations:

- $C_1 = \langle f_1, \theta_1 \rangle$, where f_1 uses Jaccard distance over space-tokenized lowercase strings with equal weights.
- $C_2 = \langle f_2, \theta_2 \rangle$, where f_2 uses Cosine similarity over character trigrams with TF-IDF weighting.

Join Proposals for r:

- C_1 : $J_{C_1}(r) = I_1$ with precision $(r, C_1) = \frac{1}{4} = 0.25$
- C_2 : $J_{C_2}(r) = I_2$ with precision $(r, C_2) = \frac{1}{2} = 0.50$

Conflict Resolution Strategy:

Compare estimated precision:

$$precision(r, C_1) = 0.25 < precision(r, C_2) = 0.50$$

2 Assign $J_U(r) = I_2$ (higher-confidence match from C_2)

Effect:

- TP(U) and FP(U) incorporate only the winning match.
- · Competing matches are discarded.



From theory to implementation

Before diving into the implementation of AutoFJ for the single-column case, let us briefly revisit the key theoretical ideas that drive the algorithm.

- A fuzzy join configuration is defined by a join function and a threshold $C = \langle f, \theta \rangle$, where f captures how similarity is computed, and θ determines when two strings are similar enough to join.
- Multiple such configurations are explored in order to maximize recall while satisfying a user-defined precision constraint \(\tau\).
- Precision is estimated without labeled data using a geometric heuristic based on how isolated a match is
 in the reference table L.
- The algorithm selects an optimal set of configurations $\mathcal{U} \subseteq \mathcal{F} \times \Theta$ through a greedy strategy that maximizes true positives while minimizing false positives.

Auto-FuzzyJoin Algorithm: single column case

Recall-Maximizing Fuzzy Join (RM-FJ) is **NP-hard**. Use a **greedy approximation algorithm** called AutoFJ.

Objective:

• Maximize recall TP(U) subject to maintaining precision(U) $\geq \tau$

Greedy Strategy:

- Select configurations that:
 - Increase true positives (recall)
 - Minimize false positives (preserve precision)
- Guided by the Profit Metric:

$$profit(U) = \frac{TP(U)}{FP(U)}$$

Blocking Heuristic:

- . To reduce the number of comparisons, apply 3-gram blocking.
- Each string is decomposed into overlapping sequences of 3 characters (3-grams).
- Only record pairs that share at least one common 3-gram are considered for joining.
- This blocks out obviously dissimilar pairs and speeds up computation.
- Applied to both L-L and L-R candidate pairs:

LL, LR ← generate candidate pairs using 3-gram overlap

Algorithm 1 AUTOFJ for single column

15: return U

```
Require: Tables L and R, precision target \tau, search space S
1: LL, LR \leftarrow apply blocking with L - L and L - R

    LR ← Learn negative-rules from LL and apply rules on LR (Alg. 2)

3: Compute distance with different join functions f \in S

    Pre-compute precision estimation for each configuration C ∈ S.

5: U ← Ø
 6: while S \ U ≠ Ø do
       max \ profit \leftarrow 0
       for all C \in S \setminus U do
           if profit(U \cup \{C\}) > max \ profit then
              C^* \leftarrow C, max profit \leftarrow profit (U \cup \{C\})
10:
       if precision(U \cup \{C^*\}) > \tau then
12-
           U \leftarrow U \cup \{C^*\}
13:
       else
           break
```

Problem formulation and complexity

Goal: Identify a set of join configurations $U \subseteq S$ such that:

- Maximizes recall: TP(U)
- Satisfies precision constraint: precision(U) $\geq au$

Formal problem definition: Recall-maximizing fuzzy join (RM-FJ)

Given reference table L, query table R, and configuration space S, find a subset $U \subseteq S$ to:

$$\max_{U \subseteq S} TP(U) \quad \text{subject to} \quad \text{precision}(U) \ge \tau$$

Computational Complexity:

- The RM-FJ problem is shown to be NP-hard.
- ullet Exact search over all subsets of ${\mathcal S}$ is computationally infeasible.
- Justifies use of greedy approximation (AutoFJ).

Blocking for efficient candidate generation

Motivation:

- Naively comparing every $r \in R$ with every $l \in L$ is computationally expensive.
- We use a **blocking** technique to generate a smaller candidate set for similarity evaluation.

Technique: 3-Gram Blocking

- Each string is decomposed into overlapping substrings of 3 characters (3-grams).
- Only consider (r, l) pairs that share at least one common 3-gram.
- Applied on both L-L (for negative rule learning) and L-R (for actual join candidates).

Impact:

- · Reduces the number of unnecessary comparisons.
- Increases efficiency without significant recall loss.

1. 3-Gram blocking using TF-IDF

LL. LR \leftarrow apply 3-gram blocking on L-L and L-R

This step implements the blocking stage described in the theoretical framework. The goal is to reduce the number of candidate pairs from $L \times R$ by quickly eliminating obviously dissimilar records. Blocking uses 3-gram tokenization and TF-IDF weighting to prioritize pairs that share meaningful substrings. Only pairs that pass this filter proceed to the more expensive distance computation phase.

```
"john smith"
Reference Table L:
                  b "jane smythe"
                       "alice iohnson"
Query Record r1: "ion smyth"
```

Step 1: Preprocessing (P)

- Lowercasing (already lowercase)
- Add padding for 3-grams: e.g., "john smith" → "##john#smith##"

Step 2: Tokenization (T)

- r₁: ##j, #jo, jon, on#, n#s, #sm, smy, myt, yth, th#, h##
- l_1 , l_2 : similar 3-gram sequences

Step 3: Token Weighting (W)

- Use TF-IDF to emphasize rare, meaningful trigrams (e.g., smy, yth)
- r_1-l_2 : High score(rare overlapping trigrams), r_1-l_1 : Medium (more common overlap), r_1-l_3 : Zero (no shared trigrams)

Blocking Result:

 Only compare r₁ with l₁, l₂ → prune l₃ Carmel Gafa

The next step corresponds to the theoretical concept of $negative\ rule\ learning$, where patterns of dissimilarity within the reference table L are used to eliminate poor candidate matches before computing distances. These rules are designed to catch non-matching pairs that may appear similar due to superficial token overlap but are semantically distinct. Filtering based on these learned rules improves both computational efficiency and overall precision.

2. Optimization - filtering with negative rules

 $LR \leftarrow Learn negative$ -rules from LL and apply rules on LR (Alg. 2)

Assumption: Although 3-gram blocking may have pruned l₃, we assume here it was retained due to weak overlap, allowing us to illustrate negative-rule filtering.

Goal: Use obvious non-matches in L-L to learn rules that help filter unlikely L-R pairs before costly distance computations.

Step 1: Generate LL — Self-Join on L using 3-gram blocking

| Pair | Shared 3-grams | Interpretation |
|----------------|----------------|--------------------|
| l_1 vs l_2 | sm, smy, th | Possibly similar |
| I_1 vs I_3 | jo, on | Clearly different |
| I_2 vs I_3 | Weak overlap | Probably different |

Learn Negative Rule:

"If 3-gram overlap \leq 2, treat as a non-match."

| | ı an | Overrap | Apply Rule: | rrech: |
|------------------------------------------|------------|----------|-------------|--------|
| Step 2: Apply Rule on LR Candidate Pairs | r_1, l_1 | \sim 4 | No | Yes |
| Step 2. Apply Rule on LA Candidate Fairs | r_1, l_2 | ~ 5 | No | Yes |
| | r. la | ~. 1 | Vec | No |

Effect: Filter out clearly irrelevant pairs early — no need to compute Jaccard or Edit Distance!

The next step directly implements the fuzzy join function f(l,r) as defined in the theoretical framework. Each join function is composed of a preprocessing step P, a tokenization strategy T, a token weighting scheme W, and a distance metric D. The full join function is expressed as:

$$f(I,r) = D(W(T(P(I))), W(T(P(r))))$$

Multiple such functions are evaluated in parallel, each capturing different notions of similarity. The results will later be used to select the most effective join configurations under precision constraints.

3. Compute distances - apply join functions

Compute distance with different join functions $f \in \mathcal{S}$ Pre-compute precision estimation for each configuration $\mathcal{C} \in \mathcal{S}$

Once candidate pairs are identified (via blocking and optional negative rules), we compute the actual similarity using multiple join functions $f \in \mathcal{S}$.

Each join function is defined by:

- Preprocessing (e.g., lowercasing, punctuation removal)
- Tokenization (e.g., char 3-grams, word tokens)
- Token weights (e.g., TF-IDF)
- Distance function (e.g., Jaccard, Cosine, Edit)

| | r (query) | I (reference) |
|-------------------------------------------|-------------|---------------|
| Example Candidate Pairs (after blocking): | "jon smyth" | "john smith" |
| | "jon smyth" | "jane smythe" |

| | Function f | Tokenizer | Distance | Description |
|-----------------------------------|--------------|--------------|-----------------|-----------------------|
| Join Functions in \mathcal{S} : | f_1 | char 3-grams | Jaccard | Overlap in token sets |
| Join Functions in 3. | f_2 | char 3-grams | Cosine (TF-IDF) | Weighted similarity |
| | f_3 | raw string | Levenshtein | Edit distance |
| | Pair | fı fo | f ₃ | |

| | Pair | f_1 | f_2 | f_3 |
|------------------|-------------|-------|-------|-------|
| Computed Scores: | jon vs john | 0.4 | 0.5 | 2 |
| | jon vs jane | 0.6 | 0.7 | 3 |

Note: Distances may follow different scales — lower often means more similar.

The next step implements the core optimization loop of AutoFJ, which is guided by the objective of maximizing recall while ensuring the estimated precision remains above a threshold τ . The goal is to identify a subset of join configurations $\mathcal{U} \subseteq \mathcal{F} \times \Theta$ that collectively yield the most high-quality joins. A greedy approximation is used due to the NP-hardness of the problem, incrementally adding the most profitable configuration C that increases true positives without violating the precision constraint.

4. Start of greedy algorithm

Initialize:
$$U \leftarrow \emptyset$$

 ${\it U}$ will hold the selected join configurations:

$$C = \langle f, \theta \rangle$$

Each configuration includes:

- A join function $f \in \mathcal{F}$ (defined by P, T, W, D)
- A distance threshold θ (max allowed distance for a match)

Goal:

- Select a subset $U \subseteq \mathcal{S}$ from all candidate configurations
- Maximize recall: TP(U)
- Maintain precision: precision(U) $\geq \tau$

| | Config C | Description |
|--------------------------------------------------------|----------------------------------------------------------------------------------------------------|------------------------------------------------------------------------------------------------------------|
| Example: Precomputed configuration set <i>S</i> | $C_1 = \langle f_1, 0.37 \rangle$ $C_2 = \langle f_2, 0.42 \rangle$ $C_3 = \langle f_3, 2 \rangle$ | Jaccard distance with $\theta=0.37$ Cosine distance with $\theta=0.42$ Edit distance with $\theta=2$ |

These θ values were selected based on prior precision–recall evaluation for each f.



5. Main greedy loop

Main Loop: while $S \setminus U \neq \emptyset$ do

We continue as long as there are still unused configurations to consider.

Notation:

- S: full set of candidate configurations, each $C = \langle f, \theta \rangle$
- U: set of selected configurations
- S \ U: unused configurations

At each iteration:

- Evaluate each $C \in S \setminus U$
- @ Compute profit: how many true positives vs. false positives it contributes
- **3** Select the best configuration C^*

$$U \leftarrow U \cup \{C^*\}$$

Example state:

- $S = \{ \langle f_1, 0.37 \rangle, \langle f_2, 0.42 \rangle, \langle f_3, 2 \rangle \}$
- U = ∅

Loop continues while there are remaining candidates and precision can be preserved.

6. Find most promising configuration (profit heuristic)

Profit Formula:

$$\operatorname{profit}(U \cup \{C\}) = \frac{TP(U \cup \{C\})}{FP(U \cup \{C\})}$$

| | Config C | TP | FP | Profit = TP / FP | | | |
|--------------------------------------------------|------------------|----|----|------------------|--|--|--|
| Example: | C_1 | 4 | 2 | 2.0 | | | |
| Example. | C_1 C_2 | 5 | 5 | 1.0 | | | |
| | $\overline{C_3}$ | 3 | 1 | 3.0 | | | |
| After evaluation: $C^* = C_3$, max_profit = 3.0 | | | | | | | |

Heuristic: choose the configuration that gives the most recall "bang" per unit of precision "risk."



7. Precision constraint check & termination

Check: if
$$precision(U \cup \{C^*\}) > \tau$$
 then $U \leftarrow Ucup\{C^*\}$

After selecting the best candidate C^* (based on profit), we must verify that adding it to U preserves minimum required precision τ .

- If precision passes: add C* to U
- · Else: break no remaining configs will satisfy the constraint

Example 1 (Pass):
$$\frac{\text{Config}}{C_3}$$
 $\frac{\text{TP}}{3}$ $\frac{\text{FP}}{1}$ $\frac{\text{Profit}}{3}$ $\frac{\text{Precision}}{3}$ $\frac{\tau}{3}$

$$\Rightarrow$$
 Precision $> \tau \rightarrow$ Accept $\rightarrow U \leftarrow \{C_3\}$

Example 2 (Fail & Break):
$$\frac{\text{Config}}{C_3}$$
 $\frac{\text{TP}}{3}$ $\frac{\text{FP}}{3}$ $\frac{\text{Profit}}{3}$ $\frac{\text{Precision}}{3}$ $\frac{\tau}{3}$

$$\Rightarrow$$
 Precision $< \tau \rightarrow$ Reject \rightarrow Stop Loop

Greedy termination: If best config can't meet τ , no others will.



8. Return final join plan

Return: U

The greedy loop terminates when:

- $S \setminus U = \emptyset$ (all configs evaluated), or
- The best candidate fails the precision constraint

The algorithm returns U: a set of selected configurations:

- Each $C = \langle f, \theta \rangle$
- Maximizes recall while keeping precision(U) $> \tau$

Each configuration in U defines:

- A join function f (e.g., Jaccard, Cosine, Edit Distance)
- A threshold θ used to accept matches

Example Output:

• $U = \{ \langle f_2 = \mathsf{Cosine}, \theta = 0.5 \rangle, \langle f_3 = \mathsf{Edit}, \theta = 2 \rangle \}$

These are used to perform the final fuzzy similarity join.



Example: Selecting the best match

1. Input Setup:

- Query record: $r_1 = "jon smyth"$
- Reference table: $L = \{"john smith", "jane smythe", "alice johnson"\}$
- After blocking: candidates for r_1 are l_1 and l_2

| | Join Function f | θ | $f(r_1, I_1)$ | $f(r_1, I_2)$ | Matches? |
|----------------------|-------------------|----------|---------------|---------------|---------------------|
| 2. Distance Results: | Jaccard (3-grams) | 0.4 | 0.5 | 0.3 | l ₂ only |
| | Cosine (TF-IDF) | 0.5 | 0.6 | 0.4 | l_2 only |
| | Edit Distance | 2.0 | 2 | 3 | I_1 only |

3. Final Configuration Set *U*:

- $U = \{ \langle f_2 = \text{Cosine}, \ \theta = 0.5 \rangle, \ \langle f_3 = \text{Edit}, \ \theta = 2 \rangle \}$
- Under Cosine: $r_1 \mapsto l_2$
- Under Edit Distance: $r_1 \mapsto l_1$

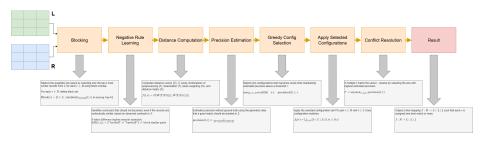
4. Conflict Resolution: Local Precision

$$precision(r, C) = \frac{1}{|\{l' \in L | f(l, l') \le 2f(l, r)\}|}$$

| [6. 6-1. (5. 72-1. (5. 77)] | | | | | | | | | |
|-----------------------------|-------------------------|-----------------------|---------|-----------------------|-----------|--|--|--|--|
| | Config C | Match | f(I, r) | 2 <i>d</i> -ball size | Precision | | | | |
| | C ₂ (Cosine) | <i>l</i> ₂ | 0.4 | 5 | 1/5 = 0.2 | | | | |
| | C_3 (Edit) | I_1 | 2 | 2 | 1/2 = 0.5 | | | | |

Result: "jon smyth" is matched to "john smith" (Edit Distance), since it has higher estimated precision (0.5 > 0.2).

AutoFJ pipeline



AutoFJ Architecture

AutoFJ Codebase Structure

```
autofi/
|-- 50-single-column-datasets.md
                                            # Documentation describing benchmark datasets
|-- autofi.pv
                                            # Main driver script for AutoFJ
|-- datasets.pv
                                            # Loads and preprocesses datasets
|-- negative_rule.py
                                            # Learns rules to prevent false matches
|-- utils.pv
                                            # General-purpose utility functions
|-- benchmark/
                                            # Contains all test datasets and benchmarks
l-- blocker/
                                            # Blocking component
    |-- autofj_blocker.py
                                            # AutoFJ-specific record blocking
    |-- blocker.py
                                            # General blocking logic
-- optimizer/
                                            # Greedy optimization logic
    -- autofj_multi_column_greedy_algorithm.py
                                                  # Multi-column join optimizer
    |-- autofj_single_column_greedy_algorithm.py # Single-column join optimizer
 -- join function space/
                                            # Parameter space for join functions
    |-- autofj_join_function_space.py
                                            # Constructs and manages the join function space
    |-- options.py
                                            # Parameter definitions
    |-- join_function/
                                            # Join function components
        |-- autofj_join_function.py
                                            # Encapsulates join logic
        |-- distance_function.py
                                            # Implements distance metrics
        |-- join_function.py
                                            # Computes scores for matching
        |-- preprocessor.py
                                            # Text cleaning and normalization
        |-- tokenizer.py
                                           # Tokenization strategies
        |-- token_weight.py
                                           # Token weighting methods
```

Step 1: Start - Input Tables L and R

Function

Loads the reference table L and the noisy table R, possibly applying minimal preprocessing.

Implementation

autofj/datasets.py

Uses standard file loading and DataFrame operations to ingest raw datasets. It may include optional utilities to split or format tables.

Step 2: Blocking

Function

Reduces the number of comparisons by pruning unlikely matches based on token similarity.

Implementation

autofj/blocker/autofj_blocker.py
autofj/blocker/blocker.py

Main entry point for blocking.

Constructs token sets using 3-gram decomposition, computes TF-IDF scores for each token, and retrieves candidate pairs via cosine similarity. Function block_LL_and_L_R() returns top-k most similar candidates from L for each $r \in R$ based on TF-IDF weighted token overlap.

Step 3: Negative Rule Learning

Function

Learns simple rules to eliminate false matches based on exclusive tokens (e.g., $2007 \neq 2008$) learned from intra-L variation.

Implementation

```
learn_negative_rules(...) identifies discriminative tokens from record pairs in L differing by only one word.

apply_negative_rules(...) removes candidate (I, r) pairs from L × R if they violate these rules.
```

Step 4: Distance Computation

Function

Computes similarity scores using various join function configurations $\langle P, T, W, D \rangle$.

Implementation

autofj/join_function_space/autofj_join_function_space.py — Iterates over all valid combinations of preprocessing (lowercase, strip punctuation), tokenization (space or 3-gram), weighting (equal or TF-IDF), and distances (Jaccard, Cosine, Edit).

Each component is modularized:

preprocessor.py e.g., lowercase, remove punctuation tokenizer.py whitespace or n-gram based splitting token_weight.py arw or IDF weighting lactance_function.py Jaccard, Edit, Cosine

Scores are stored in a large matrix for all candidate (I, r) pairs under all functions.

Step 5: Precision Estimation

Function

Estimates the reliability of each predicted join (I, r) using a geometric heuristic based on L.

Implementation

autofj/autofj.py - estimate_precision(...) checks how "isolated" I is in the embedding space: the fewer $I' \in L$ within a 2-ball of I, the higher the confidence.

This is a key innovation: it enables precision estimation without ground truth by assuming L has no duplicates.

Step 6: Greedy Configuration Selection

Function

Selects join configurations that maximize recall while meeting a minimum precision threshold au.

Implementation

autofj/optimizer/autofj_single_column_greedy_algorithm.py - Implements a greedy loop where each candidate configuration $C = \langle f, \theta \rangle$ is scored using a profit function: TP(C)/FP(C). Configuration C^* is added to $\mathcal U$ only if the precision of $\mathcal U \cup \{C^*\}$ remains $> \tau$.

Step 7: Apply Selected Configurations

Function

Applies all configurations in \mathcal{U} to generate potential matches for each $r \in R$.

Implementation

autofj/autofj.py

Applies each $\langle f,\theta\rangle\in\mathcal{U}$ to the blocked pairs. If multiple I satisfy $f(I,r)\leq\theta$, they are retained for conflict resolution.

Step 8: Conflict Resolution

Function

If multiple $l \in L$ match a single $r \in R$, pick the one with highest estimated precision.

Implementation

autofj/autofj.py

Function get_final_join_result(...) evaluates local precision of each match using the 2-ball heuristic. The *I* with the lowest neighborhood density is chosen.

Step 9: Output - Final Join Result

Function

Returns the final mapping $J:R \to L \cup \{\bot\}$ where each r is assigned the best matching I or none at all.

Implementation

autofj.py Wraps the full join pipeline from blocking to conflict resolution and outputs the join set. Can be extended to include score thresholds, logs, and exporting joins.

Testing

Possible improvements