

ICS5110 Assignment

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Abstract—This study investigates the COMPAS dataset, a widely used risk assessment tool in the U.S. criminal justice system, to evaluate the accuracy, fairness, and ethical implications of predictive machine learning models. We apply logistic regression, k-nearest neighbors (KNN), and neural networks to predict recidivism and compare their performance against the COMPAS scoring system. The study includes extensive data preprocessing, feature engineering, and dimensionality reduction techniques such as PCA to optimize model performance. Evaluation metrics, including accuracy, precision, recall, and ROC AUC, reveal that some techniques outperform COMPAS in classification accuracy but we also raise concerns about potential overfitting. Finally, we deploy a web-based interface using the Gradio framework to interactively demonstrate model predictions.

Index Terms—Machine Learning, Recidivism Prediction, COMPAS, Logistic Regression, KNN, Neural Networks.

I. INTRODUCTION

This exercise explores the well-known COMPAS dataset using several machine learning techniques, where we will also examine the ethical implications of predictive risk assessment models. In this study, we will apply techniques discussed in ICS5110, such as imputation and encoding, to assist in data preparation. Additionally, we trained a neural network, logistic regressor, and k-nearest neighbours model on the dataset to predict whether a person is likely to recidivate within two years.

The selected dataset is particularly interesting because, in addition to the **two_year_recid** label—which indicates whether an individual has reoffended within two years of an initial charge, it also includes the COMPAS **decile_score**, a risk rating predicting the likelihood of recidivism. This allows us to compare our findings with the COMPAS system and analyze the nuances of applying different techniques.

A. History of the COMPAS tool

The COMPAS (Correctional Offender Management Profiling for Alternative Sanctions)[1] dataset and tool have a controversial history rooted in its use for assessing the likelihood of recidivism among criminal defendants. Developed by Northpointe, COMPAS gained widespread adoption in the U.S. judicial system for pretrial risk assessments and sentencing decisions. This tool is helpful in various stages of the criminal justice process, including bail, sentencing, and parole decisions.

However, in 2016, an investigative report by ProPublica[7] revealed significant racial biases in the tool's predictions. The report found that COMPAS disproportionately labelled Black defendants as high risk for reoffending while underestimating the risk for white defendants, even when both groups had

similar criminal histories. This revelation sparked a broader debate about using algorithmic tools in criminal justice and their transparency and fairness.

The COMPAS tool has not been directly the subject of lawsuits, but its use in judicial decisions has led to legal challenges. For instance, in *State v. Loomis* (2016)[3], the Wisconsin Supreme Court upheld using COMPAS in sentencing. However, judges must be informed about its limitations, particularly its proprietary nature and potential biases. The case highlighted the broader tension between the utility of predictive algorithms and their application's need for accountability and fairness.

B. The COMPAS dataset

The dataset that originates from the COMPAS tool is widely used in criminology and machine learning studies.

The dataset contains attributes such as demographic information, prior charges, juvenile records, and risk scores, including the widely analysed decile score, which categorises individuals into ten different risk groups.

The decile score is a critical feature, assigning a numerical value to an individual's likelihood of reoffending. Other important features include the number of prior offences **priors_count** and the type of offence **c_charge_degree**, provide context for these predictions. At the same time, the label **two_year_recid** indicates whether an individual reoffended within two years of their COMPAS assessment.

While the dataset has been instrumental in research aimed at understanding and improving risk prediction models, it has also been the subject of extensive scrutiny due to its implications for fairness and equity in the justice system. A couple of thoughts resulting from this scrutiny include:

- Multiple studies, including the influential ProPublica investigation in 2016[7], have highlighted racial disparities in the COMPAS predictions. African-American defendants were found to be nearly twice as likely as Caucasian defendants to be labelled as high-risk for recidivism but not reoffend. Conversely, Caucasian defendants were more likely to be classified as low-risk but later reoffend, raising concerns about systemic bias embedded in the algorithm, which could exacerbate existing inequalities in the justice system.
- The COMPAS tool operates as a proprietary black-box model, meaning its internal workings and feature weights are not disclosed to the public or even to the defendants it evaluates. This lack of transparency prevents meaningful

scrutiny and accountability, leaving users unable to fully understand or challenge the tool's predictions.

- The COMPAS algorithm relies on historical criminal justice data, which may reflect social and systemic biases. For example, law enforcement practices that can result in sentencing disparities can all influence the patterns observed in the data. Using such data as input, the COMPAS tool risks perpetuating these biases into an electronic tool.
- Some features in the COMPAS dataset, such as age and criminal history, are static and cannot change over time, as this data is based on the date of the COMPAS assessment. We can argue that these features in risk predictions without considering the period after the COMPAS assessment undermines the potential for individuals to reform and leads to insensible punitive outcomes.
- The ethical implications of using predictive algorithms in high-stakes decisions, such as sentencing and parole, constitute a significant area of concern. The potential for false positives can lead to unjustly harsher treatment, while false negatives can impact public safety.
- The dataset available for research purposes is a reduced version of the original COMPAS data, with several features anonymised or removed. Missing important data introduces limitations for academic studies aiming to replicate or validate the findings from real-world COMPAS applications.

The criticism of the COMPAS tool emphasises the challenges of deploying machine learning systems in sensitive domains like justice. These challenges are not unique to COMPAS but highlight broader issues in applying algorithmic decision-making tools in socially important contexts. They highlight the need for transparency, fairness-aware modelling techniques, and careful ethical evaluations when designing and implementing such tools.

C. Objectives of this work

The objective of this project is to assess the accuracy and fairness of predictive models compared to the COMPAS system. In this investigation, we will:

- Analyse the COMPAS dataset and its predictions.
- Prepare the dataset for machine learning through cleaning, transformation, and feature engineering.
- Train and evaluate a neural network, a logistic regressor and use a k-nearest neighbour to obtain our recidivism risk.
- Investigate potential biases and ethical implications in predictions.

II. BACKGROUND

In this section, we will review the key techniques employed in this study, providing an explanation of their principles to establish a solid foundation for the work presented.

A. Machine learning technique - Neural network

Neural networks[2] are machine learning models inspired by biological neural networks. They comprise layers of interconnected nodes (neurons) that transform input data into meaningful outputs through weights and activation functions. Neural networks are widely used for classification, regression, and generative modelling tasks. This section will look at the important aspects related to neural networks.

1) *The perceptron*: A perceptron is a basic architecture that consists of a layer of input nodes that is fully connected with an output node and, therefore, does not have any hidden nodes. Perceptrons can only represent linearly separable functions and are used only for binary classification.

The building blocks of a perceptron are the following:

- The perceptron takes several input features that each represent an aspect of the input data.
- Each input feature differently influences the output through a weight parameter. Weights are optimized during the training process.
- A bias is utilized to make input-independent adjustments to the weighted inputs. Bias values are also optimized during training.
- The weighted inputs are summed together, including the bias; this can be expressed as:

$$z = \sum_{i=1}^n w_i x_i + b \quad (1)$$

- The weighted sum is passed through a Heaviside step activation function that maps the weighted sum to a binary output, such that:

$$f(z) = \begin{cases} 0 & \text{if } z < \theta \\ 1 & \text{if } z \geq \theta \end{cases}$$

- The output of the perceptron that results from the activation function can then be used to classify the inputs.

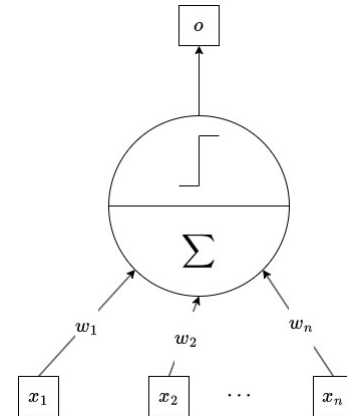


Fig. 1: The perceptron

A simple learning algorithm fits a perceptron to any linearly separable set.

2) *Multilayer perceptron*: The neural network architecture we use in this work are multilayer perceptrons. A multilayer perceptron is made up of fully connected layers. It contains an input layer, a number of hidden layers, and an output layer. This structure allows us to model more complex relationships when compared to the simpler perceptron.

The building blocks of a perceptron are the following:

- Each input feature is connected directly to an input neuron to forward the features into the network.
- One or more hidden layers, each having a designated number of nodes, follow. These layers transform the feature information at each level.
- Finally, an output layer consisting of one node (if the task is regression or binary classification) or more nodes (if the task is multi-class classification) gives us the result of the network.

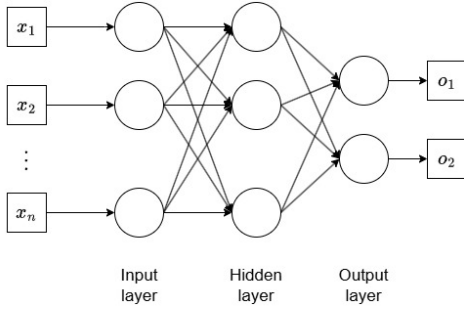


Fig. 2: A multilayer perceptron with a single hidden layer

I. Forward propagation involves feeding feature information to the input layer, passing it through all hidden layers, and finally to the output layer to generate a predicted output. A linear transformation followed by a non-linear activation generates the output for every node at each layer. Forward propagation is comprised of the following steps:

- a) For each neuron in layer j , the weighted sum of its inputs is calculated as:

$$z_j = \sum_{i=1}^{n_j} w_{ij}^{(j)} x_i^{(j-1)} + b_j \quad (2)$$

Where:

$x_i^{(j-1)}$ Input from the i^{th} neuron of the previous layer $j - 1$.

$w_{ij}^{(j)}$ Weight connecting the i^{th} neuron of layer $j - 1$ to the current neuron in layer j .

b_j Bias term for the neuron in layer j .

z_j Result of the linear transformation at the current neuron in layer j .

n_j Number of inputs (or neurons) in the previous layer $j - 1$.

- b) The result of the weighted sum, z_j , is passed through a non-linear activation function:

$$a_j = f(z_j)$$

This introduces non-linearity to the model. A list of some common activation functions can be seen in the Table I.

Function	Equation	Diagram
Sigmoid	$\sigma(x) = \frac{1}{1+e^{-x}}$	
Tanh	$\tanh(x)$	
Leaky Relu	$\max(0.2x, x)$	
Relu	$\max(0, x)$	

TABLE I: Activation Functions

II. The predicted output is compared to the actual output using a loss function to compute the loss. A loss function measures the difference between the actual target values and the model's predicted results. For a single prediction:

$$\mathcal{L}(\hat{y}, y) = f(\hat{y}, y)$$

Where:

\hat{y} Predicted value.

y Actual value.

f Specific loss function formula.

The cost function aggregates the loss over the entire dataset:

$$\frac{1}{m} \sum_{i=1}^m \mathcal{L}(\hat{y}_i, y_i)$$

Two examples of cost functions are the following:

- Mean Squared Error (MSE):

$$\text{MSE} = \frac{\sum_{i=1}^n (\hat{y}^{(i)} - y^{(i)})^2}{n} \quad (3)$$

- Binary Cross-Entropy: Commonly used for binary classification problems:

$$L = -\frac{1}{N} \sum_{i=1}^N [y_i \log(\hat{y}_i) + (1 - y_i) \log(1 - \hat{y}_i)] \quad (4)$$

Where:

- L The average loss (cost) across all N samples in the dataset.
- y_i The true label for the i^{th} sample, where $y_i \in \{0, 1\}$.
- \hat{y}_i Predicted probability for $y_i = 1$.
- $1 - \hat{y}_i$ Predicted probability for $y_i = 0$.
- \log The natural logarithm.

III. Backpropagation is the process by which the network's weights and biases are adjusted to minimize loss. The loss is propagated backwards from the output layer to the input layer. At each step, the gradient of the loss with respect to the parameters determines the adjustment. The following steps make up the backpropagation phase:

- a) The gradient of the loss with respect to each weight and bias in every node is calculated, starting from the output layer and moving backwards to the input layer.
- b) The gradient for any layer builds on the gradient of the subsequent (later) layers using the chain rule of differentiation.
- c) The network's parameters for any node are adjusted in the direction opposite to the respective gradient using optimization algorithms like stochastic gradient descent (SGD) or variants such as the Adam optimizer.

3) *Stochastic gradient descent*: Stochastic gradient descent is an optimization algorithm that optimizes the parameters Θ of the network, to minimize the loss

$$\Theta = \arg \min_{\Theta} \frac{1}{N} \sum_{i=1}^n l(x_i, \Theta)$$

Where:

- $x_{1,2,\dots,N}$ The training set.
- $l(x_i, \Theta)$ The loss for a given data point x_i .
- N The number of examples in the dataset.

The loss, z is a supervision signal that guides any modifications that should take place on the parameters[10]. The stochastic gradient descent method of such modification is as follows:

$$\theta^i \leftarrow \theta^i - \eta \frac{\partial z}{\partial \theta^i}$$

where i represents the layer index η is the learning rate $\frac{\partial z}{\partial \theta^i}$ is the gradient of the loss z with respect to parameter θ^i

The parameters are updated iteratively, as follows:

$$\theta_{t+1}^i = \theta_t^i - \eta \frac{\partial z}{\partial \theta_t^i}$$

There are a few considerations that are important to note about stochastic gradient descent.

The learning rate affects the step size for each update, that is how much the parameters are adjusted in the direction of the gradient. A large learning rate might result in overshooting and even divergence, whereas a small learning rate leads to more stable convergence, albeit slower

The parameters are updated for every sample or for a small batch of samples, unlike traditional gradient descent that computes that gradients for the entire dataset. This approach leads to faster updates but is also prone to more noise in the optimization process.

4) *Momentum*: Momentum is a technique used in training neural networks to accelerate optimization. This accelerated optimization is achieved by considering also the values of previous gradients for each parameter. Momentum can, in this way, mitigate oscillations in the optimization path and speed up learning[11].

Momentum acts on the update rule of gradient descent by adding a portion of the update from the previous step to the current step. This approach allows the optimizer to maintain a directional memory, or velocity, effectively smoothing out updates and reducing oscillations.

Momentum is commonly integrated with optimization algorithms like stochastic gradient descent and is a key component of advanced optimizers like Adam optimizer in Section II-A6.

The momentum update rule is given by[6]:

$$v_t^i = \beta v_{t-1}^i + (1 - \beta) \frac{\partial z}{\partial \theta_t^i} \quad (5)$$

$$\theta_{t+1}^i = \theta_t^i - \eta v_t^i \quad (6)$$

Where:

- v_t^i The velocity term at step t for the parameters at index i .
- β The momentum coefficient (e.g., 0.9), controlling how much of the previous velocity to retain.
- $\frac{\partial z}{\partial \theta_t^i}$ The gradient of the loss function z with respect to parameters θ^i at step t .
- η The learning rate.
- θ_t^i The parameters at layer index i at step t .

A typical value is $\beta = 0.9$, which retains 90% of the previous velocity. Smaller values result in less "memory" of past updates.

5) *RMSProp*: Root Mean Square Propagation (RMSProp)[6] is an adaptive learning rate optimization algorithm designed to improve the training of neural networks. Its main function is to address challenges such as inconsistent or large gradient magnitudes. RMSProp helps stabilize convergence during optimization due to its effectiveness in dealing with noisy gradients.

RMSProp adjusts the learning rate for each parameter based on the average of recent squared gradients. In this way, the optimizer adapts to the scale of the gradients, preventing large updates that could destabilize training.

The algorithm is similar to momentum, but here it introduces a running average of squared gradients to normalize parameter updates.

The RMSProp update rule is given by:

$$S_t^i = \beta S_{t-1}^i + (1 - \beta) \left(\frac{\partial z}{\partial \theta_t^i} \right)^2 \quad (7)$$

Where:

- S_t^i Exponentially weighted moving average of squared gradients at step t for the parameters at layer index i .
- β Decay rate for the moving average (commonly set to 0.9).
- $\frac{\partial z}{\partial \theta_t^i}$ Gradient of the loss function z with respect to parameters θ_t^i at step t and layer index i .

The parameters are updated using a learning rate scaled by the square root of S_t^i (with a small value ϵ added for numerical stability):

$$\theta_{t+1}^i = \theta_t^i - \frac{\eta}{\sqrt{S_t^i + \epsilon}} \left(\frac{\partial z}{\partial \theta_t^i} \right) \quad (8)$$

Where:

- η Global learning rate, which is set to 0.001 in most frameworks.
- ϵ Small constant (e.g., 10^{-8}) to prevent division by zero.

RMSProp is a widely used optimizer that forms the foundation for more advanced methods such as adam optimizer that is discussed in detail in Section II-A6. It is especially effective in training deep neural networks where gradient magnitudes can vary significantly.

6) *Adam optimizer*: The Adam Optimizer (Adaptive Moment Estimation)[6] is a widely used optimization algorithm for training deep learning models. It combines the benefits of momentum and rmsprop to provide an efficient, robust, and adaptable optimizer. Adam is particularly effective for problems with sparse gradients and non-stationary objectives.

Adam optimizer had a number of hyper parameters:

- Learning Rate α : 0.001
- First Moment Decay Rate β_1 : 0.9
- Second Moment Decay Rate β_2 : 0.999
- Numerical Stability Term ϵ : $1e-8$

The Adam-optimizer update rule is given by the following steps:

- I. First, calculate the first moment estimate, or the Momentum that we discussed in Section II-A4, which is the exponentially weighted moving average of the gradients. This is done to smooth gradient updates over time by including past gradients and thus maintaining a directional memory:

$$m_t^i = \beta_1 m_{t-1}^i + (1 - \beta_1) \frac{\partial z}{\partial \theta_t^i}$$

- II. Calculate the second moment estimate, which is the basic idea of RMSProp that we discussed in Section II-A5, to track the exponentially weighted variance of gradients:

$$v_t^i = \beta_2 v_{t-1}^i + (1 - \beta_2) \left(\frac{\partial z}{\partial \theta_t^i} \right)^2$$

- III. Correct these results for initialization bias:

$$\hat{m}_t^i = \frac{m_t^i}{1 - \beta_1^t}$$

$$\hat{v}_t^i = \frac{v_t^i}{1 - \beta_2^t}$$

- IV. Update the parameters using the corrected estimates:

$$\theta_{t+1}^i = \theta_t^i - \frac{\alpha \hat{m}_t^i}{\sqrt{\hat{v}_t^i + \epsilon}}$$

7) *Batch normalization*: Batch normalization is used to control the statistics of the activations in the neural networks. It is commonly used in neural network architectures, and it is usually found after layers that have multiplications, like linear or convolutional layers

If we consider a hidden state neural net node

We have basically a pre-activation value, that is the result of

$$z = \left(\sum_{i=1}^n x_i w_i \right) + b$$

That is fed into a non-linear element such as ReLU or tanh.

- We do not want the pre-activation to be very small as the tanh activation will not effectively activate.
- We also do not want these values to be too large, as the tanh will become saturated.
- Furthermore, we want these values to be roughly Gaussian, that is, with a mean of 0 and a standard deviation of 1.

Sergey Ioffe and Christian Szegedy propose batch-normalization [4] to take the hidden states and normalize them to be Gaussian.

Input: Values of x over a mini-batch: $\mathcal{B} = \{x_1 \dots x_m\}$; Parameters to be learned: γ, β	
Output: $\{y_i = \text{BN}_{\gamma, \beta}(x_i)\}$	
$\mu_{\mathcal{B}} \leftarrow \frac{1}{m} \sum_{i=1}^m x_i$	// mini-batch mean
$\sigma_{\mathcal{B}}^2 \leftarrow \frac{1}{m} \sum_{i=1}^m (x_i - \mu_{\mathcal{B}})^2$	// mini-batch variance
$\hat{x}_i \leftarrow \frac{x_i - \mu_{\mathcal{B}}}{\sqrt{\sigma_{\mathcal{B}}^2 + \epsilon}}$	// normalize
$y_i \leftarrow \gamma \hat{x}_i + \beta \equiv \text{BN}_{\gamma, \beta}(x_i)$	// scale and shift

Algorithm 1: Batch Normalization Transform, applied to activation x over a mini-batch.

Fig. 3: Batch normalization algorithm, from [4]

There are two ways whereby batch normalization can be implemented:

- Pre-activation normalization, where batch-normalization is carried out before the activation function is applied.
- Post-activation normalization, where batch-normalization is carried out after the activation function is applied.

The original paper specified pre-activation normalization, however studies have shown that post-activation batch normalization will give superior results.

8) *Regularization*: Regularization are techniques used to prevent overfitting in machine learning. This is achieved by adding a penalty term to the loss function, that discourage the model from assigning larger weights to features.

L1 regularization or Lasso Regularization adds the sum of the absolute values of the weights to the loss function:

$$\mathcal{L}_{L1} = \mathcal{L} + \lambda \sum_{i=1}^n |w_i| \quad (9)$$

Where:

\mathcal{L} The original loss function (e.g., cost-function-mean-square-error, cost-function-cross-entropy).

λ The regularization strength, a hyperparameter.

w_i The weight of the i^{th} node.

L1 regularization drives some weights to zero, thus encouraging sparsity in the network. Since L1 penalizes large weights, it promotes simpler networks with improved generalization.

L2 or Ridge regularization adds the sum of the squared values of the weights to the loss function:

$$\mathcal{L}_{L2} = \mathcal{L} + \lambda \sum_{i=1}^n w_i^2 \quad (10)$$

Where:

\mathcal{L} The original loss function (e.g., cost-function-mean-square-error, cost-function-cross-entropy).

λ The regularization strength, a hyperparameter.

w_i The weight of the i^{th} node.

L2 penalizes large weights but does not drive them to zero but shrinks them closer to zero. It hence promotes smoother solutions and avoids sharp changes in parameter values.

B. Machine learning technique - Logistic regression

Logistic regression[2] is a machine learning algorithm commonly used for binary classification tasks.

Given a feature vector $X \in \mathbb{R}^{n_x}$, the goal of logistic regression is to predict the probability \hat{y} that a binary output variable y takes the value 1, given X , that is $\hat{y} = P(y = 1|X)$, $0 \leq y \leq 1$. For example, in the case of image classification,

logistic regression can be used to predict the probability that an image contains a cat.

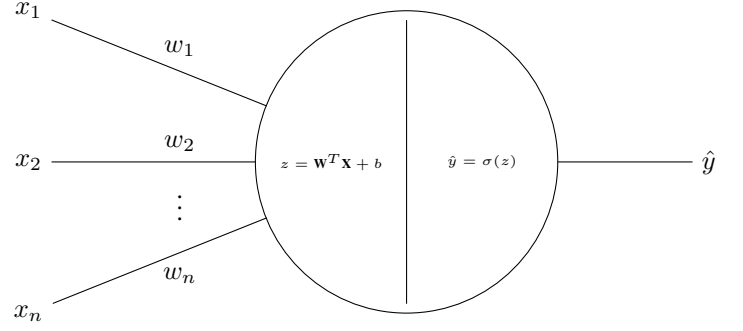


Fig. 4: A logistic regression model

Logistic regression can be visualized as the model shown in Figure 4. It consists of several main components:

- Inputs. The input vector to the model $\mathbf{X} \in \mathbb{R}^{n_x}$.
- Parameters. A weight vector $\mathbf{W} \in \mathbb{R}^{n_x}$ and a bias term $b \in \mathbb{R}$. These will form the coefficients of a linear equation that gives the log odds ratio.
- Pre-activation result: The result is obtained by multiplying the transpose of the weights with the inputs and then adding the bias.

$$z = \mathbf{W}^T \mathbf{X} + b = \begin{bmatrix} w_1 & w_2 & \dots & w_n \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} + b \quad (11)$$

- Sigmoid function. A function as shown in Figure 5, $\sigma(z) = \frac{1}{1+e^{-z}}$, which maps any real number z to the range $(0, 1)$. This function is used to ensure that the predicted probability \hat{y} is always between 0 and 1.

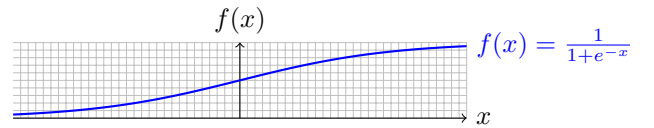


Fig. 5: Sigmoid activation function

- Output. The predicted probability \hat{y} is computed as $\hat{y} = \sigma(z) = \sigma(\mathbf{W}^T \mathbf{X} + b)$.

A term that is often encountered in this scenario is the log-odds ratio or logit. Logistic regression models the probability $P(y = 1 | X)$, of the binary dependent variable Y given the predictor variables $\mathbf{X} = \{x_1, x_2, \dots, x_n\}$. The goal is to find a relationship between $P(y = 1)$, and the predictors \mathbf{X} .

The probability is modelled using the sigmoid function:

$$P(y = 1 | X) = \frac{1}{1 + e^{-\eta}}$$

Where: $\eta = b + w_1x_1 + w_2x_2 + \dots + w_nx_n$ is the linear regression function

The odds of $y = 1$ are defined as the ratio of the probability of success to the probability of failure:

$$\text{Odds} = \frac{P(y = 1)}{1 - P(y = 1)}$$

Taking the natural logarithm of the odds gives the [log-odds-ratio]] or logit:

$$\text{Log-Odds} = \ln \left(\frac{P(y = 1)}{1 - P(y = 1)} \right)$$

From the sigmoid function, we can derive the relationship between the probability and the log-odds-ratio:

$$P(y = 1) = \frac{1}{1 + e^{-\eta}}$$

$$1 - P(y = 1) = 1 - \frac{1}{1 + e^{-\eta}} = \frac{e^{-\eta}}{1 + e^{-\eta}}$$

The odds, therefore, are

$$\text{Odds} = \frac{P(y = 1)}{1 - P(y = 1)} = \frac{\frac{1}{1 + e^{-\eta}}}{\frac{e^{-\eta}}{1 + e^{-\eta}}} = e^{\eta}$$

Taking the natural logarithm of both sides gives the log-odds:

$$\ln \left(\frac{P(y = 1)}{1 - P(y = 1)} \right) = \eta$$

Substituting $\eta = b + w_1x_1 + w_2x_2 + \dots + w_nx_n$

$$\ln \left(\frac{P(y = 1)}{1 - P(y = 1)} \right) = \eta = b + w_1x_1 + w_2x_2 + \dots + w_nx_n \quad (12)$$

We conclude this overview of logistic regression by looking at how they work and learn. The weight vector \mathbf{W} and the bias term b are learned from a labelled training set by minimizing a suitable loss function using techniques such as gradient descent or its variants. Once trained, the logistic regression model can be used to predict the probability of the binary output variable for new input examples.

The feedforward process for logistic regression can be described as follows:

- 1) Compute z as the dot product of the weight vector \mathbf{W} and the input features, plus the bias term b , transforming the input features into a single scalar z that represents the log-odds of the output being $y = 1$:

$$z = \mathbf{W}^T \mathbf{X} + b \quad (13)$$

- 2) Pass z through the sigmoid function to map the log-odds z to a probability $\hat{y} = P(y = 1 | X)$, ensuring the output is between 0 and 1:

$$\hat{y} = \sigma(z) = \frac{1}{1 + e^{-z}} \quad (14)$$

- 3) During training, we define the loss function \mathcal{L} as the negative log-likelihood of the predicted output given the true label:

$$\mathcal{L} = -(y \ln(\hat{y}) + (1 - y) \ln(1 - \hat{y})) \quad (15)$$

For a trained system, we compare \hat{y} to a threshold to convert the probabilistic output into the final binary classification.

We now look at **feedback process** for logistic regression. To optimize the weight vector \mathbf{W} , we compute the derivatives of the loss function with respect to each weight and the bias term and use these derivatives to update the weights in the opposite direction of the gradient, that is gradient descent.

To compute the derivatives, we use the chain rule:

$$\frac{\partial \mathcal{L}}{\partial w_i} = \frac{\partial \mathcal{L}}{\partial \hat{y}} \cdot \frac{\partial \hat{y}}{\partial z} \cdot \frac{\partial z}{\partial w_i}$$

and

$$\frac{\partial \mathcal{L}}{\partial b} = \frac{\partial \mathcal{L}}{\partial \hat{y}} \cdot \frac{\partial \hat{y}}{\partial z} \cdot \frac{\partial z}{\partial b}$$

We can then use these derivatives to update the weights as follows:

$$w_i \leftarrow w_i - \alpha \frac{\partial \mathcal{L}}{\partial w_i} \quad (16)$$

and

$$b \leftarrow b - \alpha \frac{\partial \mathcal{L}}{\partial b} \quad (17)$$

Where α is the learning rate, which controls the step size of the updates. By iteratively performing these updates on a training set, we can find the optimal weight vector \mathbf{W} that minimizes the loss function on the training set.

To calculate the derivatives, let us begin by computing the derivative of the loss function with respect to the predicted output \hat{y} :

$$\frac{\partial \mathcal{L}}{\partial \hat{y}} = \frac{\partial}{\partial \hat{y}} (-(y \ln(\hat{y}) + (1 - y) \ln(1 - \hat{y})))$$

since

$$\frac{d(\ln(x))}{dx} = \frac{1}{x}$$

we get:

$$\frac{\partial \mathcal{L}}{\partial \hat{y}} = - \left(\frac{y}{\hat{y}} - \frac{1 - y}{1 - \hat{y}} \right)$$

The derivative of the predicted output \hat{y} with respect to z is solved using the quotient rule, that is

$$\frac{d}{dx} \left(\frac{f(x)}{g(x)} \right) = \frac{f'(x)g(x) - g'(x)f(x)}{g^2(x)}$$

So, if we let

$f(z) = 1$	$f'(z) = 0$
$g(z) = 1 + e^{-z}$	$g'(z) = -e^{-z}$

$$\begin{aligned}
\frac{\partial \hat{y}}{\partial z} &= \frac{\partial}{\partial z} \left(\frac{1}{1 + e^{-z}} \right) \\
&= \frac{e^{-z}}{(1 + e^{-z})^2} \\
&= \frac{1}{(1 + e^{-z})} \frac{e^{-z}}{(1 + e^{-z})} \\
&= \frac{1}{(1 + e^{-z})} \frac{1 + e^{-z} - 1}{1 + e^{-z}} \\
&= \frac{1}{(1 + e^{-z})} \left(\frac{1 + e^{-z}}{1 + e^{-z}} - \frac{1}{1 + e^{-z}} \right) \\
&= \hat{y}(1 - \hat{y})
\end{aligned}$$

The derivative of z with respect to w_i :

$$\begin{aligned}
\frac{\partial z}{\partial w_i} &= \frac{\partial}{\partial w_i} \mathbf{W}^T \mathbf{X} + b \\
&= \frac{\partial}{\partial w_i} (w_1 x_1 + \dots + w_i x_i + \dots + w_n x_n + b) \\
&= x_i
\end{aligned} \tag{18}$$

Similarly,

$$\begin{aligned}
\frac{\partial z}{\partial b} &= \frac{\partial}{\partial b} \mathbf{W}^T \mathbf{X} + b \\
&= \frac{\partial}{\partial b} (w_1 x_1 + \dots + w_i x_i + \dots + w_n x_n + b) \\
&= 1
\end{aligned} \tag{19}$$

Therefore

$$\begin{aligned}
\frac{\partial \mathcal{L}}{\partial w_i} &= \frac{\partial \mathcal{L}}{\partial \hat{y}} \cdot \frac{\partial \hat{y}}{\partial z} \cdot \frac{\partial z}{\partial w_i} \\
&= - \left(\frac{y}{\hat{y}} - \frac{1-y}{1-\hat{y}} \right) \cdot \hat{y}(1-\hat{y}) \cdot x_i \\
&= - \left(\frac{-y(1-\hat{y}) + (1-y)\hat{y}}{\hat{y}(1-\hat{y})} \right) \cdot \hat{y}(1-\hat{y}) \cdot x_i \\
&= [(1-y)\hat{y} - y(1-\hat{y})] x_i \\
&= [\hat{y} - y\hat{y} - y + y\hat{y}] x_i
\end{aligned}$$

$$\frac{\partial \mathcal{L}}{\partial w_i} = (\hat{y} - y) x_i \tag{20}$$

and similarly

$$\frac{\partial \mathcal{L}}{\partial b} = (\hat{y} - y) \tag{21}$$

C. Machine learning technique - K-nearest neighbours algorithm

K-nearest neighbours[2] is simple yet robust for datasets with well-structured local relationships. It is particularly effective for non-linear decision boundaries and finds applications in anomaly detection, pattern recognition, and recommendation systems.

The k-nearest neighbours algorithm is non-parametric, that is, it does not make assumptions about the underlying distribution or functional form of the data; instance-based, that is, it does not explicitly learn a model during a training phase, but it relies on the raw training data to make predictions at query time, unlike parametric models, which "learn" a set of fixed parameters (e.g., coefficients in linear regression) during training, learning method used for classification and regression tasks. It predicts the output of a query point based on the labels or values of its k -nearest neighbours in feature space.

KNN does not assume a specific functional form for the data. Instead, it relies on the local structure of the dataset. For a given query point x , the algorithm uses a distance metric to identify its k -nearest neighbours and infers the prediction by aggregating their outcomes. Typical distance metrics include:

1) Euclidean Distance

$$d(x, x') = \sqrt{\sum_{i=1}^n (x_i - x'_i)^2}$$

2) Manhattan Distance

$$d(x, x') = \sum_{i=1}^n |x_i - x'_i|$$

3) Minkowski Distance. Note that for $p = 2$, this reduces to the Euclidean distance; for $p = 1$, it becomes the Manhattan distance.

$$d(x, x') = \left(\sum_{i=1}^n |x_i - x'_i|^p \right)^{1/p}$$

In classification tasks, the predicted class \hat{y} for a query point x is determined by majority voting among its k -nearest neighbours. If we let $N_k(x)$ represent the set of the k -nearest neighbours, the predicted class is given by:

$$\hat{y} = \operatorname{argmax}_c \sum_{x' \in N_k(x)} \mathbb{I}(y(x') = c)$$

Where:

- argmax_c Identifies the class c with the highest count among the neighbours.
- $\mathbb{I}(\cdot)$ The indicator function, which equals 1 if $y(x') = c$, and 0 otherwise.

The parameter k determines the number of neighbours considered.

- A small k (e.g., $k = 1$) makes the model sensitive to noise, as predictions rely heavily on individual points.

- A large k smooths the decision boundary but may lead to underfitting.

Finding the optimal value for k is one of the main challenges in the k -nearest neighbour. Cross-validation is typically employed to find a value using the following procedure:

- 1) Iterate Over Candidate Values of k
 - Choose a range of potential k values, for example, $k = 1, 2, \dots, 20$.
- 2) Evaluate Performance for Each k
 - For each k , use K -fold cross-validation:
 - Train the KNN model using $K - 1$ folds.
 - Validate it on the remaining fold.
 - Compute the average performance metric across all K folds.
- 3) Select k with the Best Performance
 - After evaluating all k values, choose the k that maximizes the performance metric (e.g., accuracy) or minimizes the error.

The k -nearest neighbour algorithm is, therefore, as follows;

1) *Input:*

- Dataset: $D = \{(x_1, y_1), (x_2, y_2), \dots, (x_N, y_N)\}$, where x_i is the feature vector, and y_i is the corresponding label or value.
- Query point: x_{query} , the data point for which the prediction is required.
- Number of neighbours: k , the number of nearest neighbours to consider.
- Distance metric: $d(x, x')$ (e.g., Euclidean distance).

2) *Steps:*

- 1) Calculate Distance. For the query point x_{query} , compute the distance to every point x_i in the dataset D using the chosen distance metric. For Euclidean distance:

$$d(x_{query}, x_i) = \sqrt{\sum_{j=1}^n (x_{query_j} - x_{i_j})^2},$$

$$\forall i \in \{1, 2, \dots, N\}.$$

- 2) Sort Neighbours. Rank all data points x_i in D by their distance to x_{query} in ascending order. Let this sorted set be D_{sorted} .
- 3) Select k -Nearest Neighbours. Extract the top k data points from D_{sorted} . Denote this set as $N_k(x_{query})$.
- 4) Aggregate Neighbours' Outputs.
 - For **classification**: Perform majority voting among the labels y_i of the k -nearest neighbours:

$$\hat{y} = \operatorname{argmax}_c \sum_{x_i \in N_k(x_{query})} \mathbb{I}(y_i = c),$$

where $\mathbb{I}(y_i = c)$ is an indicator function that equals 1 if $y_i = c$, and 0 otherwise.

- 5) **Output Prediction:** Return \hat{y} as the predicted label (for classification) or value (for regression) for x_{query} .

3) *Output:* The predicted label or value \hat{y} for the query point x_{query} .

D. Feature scaling

Feature scaling[2] is an important data transformation process. It is a very important aspect of many machine learning algorithms including logistic regression, support vector machines and neural networks, as, the performance of such algorithms is adversely impacted when the numerical features have different scales. The two methods to transform features on the same scale are normalization and rescaling.

During normalization or rescaling, values are scaled and shifted so that they are mapped onto the $[0, 1]$ interval. This is achieved by applying the following transformation;

$$x_{normalized} = \frac{x - x_{min}}{x_{max} - x_{min}}$$

Normalization is also sometimes referred to as min-max scaling.

Standardization is particularly suited for algorithms that assume Gaussian distributions, like linear regression and logistic regression. It is achieved by first subtracting values from the mean so that the mean of the normalized values is zero, and then dividing by the standard deviation so that the variance of the normalized distribution is one. Thus;

$$x_{standardized} = \frac{x - \mu}{\sigma}$$

Unlike normalization, the range of standardization is not fixed, and this can sometimes be an issue if a value in the $[0, 1]$ interval is expected. Standardization is however more resilient to the effect of outliers.

Tree based machine learning models, like decision trees and random forests do not normally require feature scaling.

E. Cross-validation

Cross-validation[2] is a technique that can be applied to any ML algorithm that is aimed to reduce overfitting by estimating how well each hypothesis generalizes to unseen data. In practice, a portion of the data is reserved for this purpose.

The K -fold cross validation technique splits the dataset into k folds, training that model on $k - 1$ folds and testing on the remaining one. The test fold is rotated and the process is repeated so that each fold will act as the test set once. Metrics like mean square error are averaged across folds, ensuring a robust estimate.

Therefore, if for example, we split the data into 10 folds, so that each fold will have $n/10$ records, we train the model on 9 folds and test on the remaining one. We then rotate the test fold and repeat this process 10 times. The final performance metric is computed as the mean of the metrics across the 10 folds.

In stratified K -fold cross validation, the folds have the same proportion of the classes as in the original dataset.

Other types of cross validation include Leave one out cross-validation, where each data point is used as a test set once.

F. Principal Component Analysis (PCA)

Principal Component Analysis[9] is a statistical method for dimensionality reduction that transforms high-dimensional data into a lower-dimensional space while maintaining as much variance as possible. It achieves this by identifying directions in the data, called principal components, which maximize the variance. PCA is widely used in data compression, noise reduction, and visualization applications.

PCA relies on variance, which measures data spread, and covariance, which shows how features change together. It transforms the data into a new coordinate system defined by the eigenvectors of the covariance matrix, ordered by their corresponding eigenvalues. These eigenvalues quantify the variance captured by each principal component.

The following steps are carried out in order to determine the principal components of a dataset:

Given a dataset X with n samples and d features, represented as an $n \times d$ matrix:

$$X = \begin{bmatrix} x_{11} & x_{12} & \cdots & x_{1d} \\ x_{21} & x_{22} & \cdots & x_{2d} \\ \vdots & \vdots & \ddots & \vdots \\ x_{n1} & x_{n2} & \cdots & x_{nd} \end{bmatrix}$$

- We start by centring the data. Centering ensures the dataset is zero-centred by subtracting the mean of each feature:

$$X_{\text{centered}} = X - \mu$$

where μ is the mean vector:

$$\mu = \frac{1}{n} \sum_{i=1}^n X_i$$

- We then compute the covariance matrix Σ which is calculated as:

$$\Sigma = \frac{1}{n-1} X_{\text{centered}}^T X_{\text{centered}}$$

- And then solve the eigenvalue equation for the covariance matrix:

$$\Sigma v = \lambda v$$

where:

λ : Eigenvalue (variance explained by the principal component).

v : Eigenvector (direction of the principal component).

- We sort the eigenvalues in descending order and select the top k eigenvectors to obtain the principal components:

$$V_k = [v_1, v_2, \dots, v_k]$$

- We then transform the data into the new k -dimensional space:

$$X_{\text{reduced}} = X_{\text{centered}} V_k$$

- The explained variance ratio quantifies the proportion of variance retained by each principal component:

$$\text{Explained Variance Ratio} = \frac{\lambda_i}{\sum_{j=1}^d \lambda_j}$$

where λ_i is the eigenvalue of the i -th principal component.

G. Feature Selection

Feature selection identifies and retains the most relevant features in a dataset to improve model performance and reduce complexity. It involves reducing the dimensionality of the original problem by selecting a subset of features. For example:

Original problem (with n dimensions): \longrightarrow Reduced problem (with $k < n$ dimensions):

In feature selection, k features are selected out of N to minimize the learner error. This process can be mathematically represented as:

$$\begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_N \end{bmatrix} \xrightarrow{\text{Feature Selection}} \begin{bmatrix} x_{i_1} \\ x_{i_2} \\ \vdots \\ x_{i_k} \end{bmatrix}$$

Feature selection is essential for several reasons:

- Curse of Dimensionality. High-dimensional datasets often lead to models requiring more data and computation and are prone to poor generalization.
- Overfitting. Excessive features can cause a model to fit noise in the data, leading to overfitting.
- Visualization. Reduced dimensionality makes it possible to visualize data in two or three dimensions.

Filter-based feature selection is a method that selects features based on statistical measures of their relevance to the target variable, independently of any machine learning model.

Filter-based feature selection has two primary aims:

- 1) Select features that are independent of each other, ensuring that each feature contributes new information.
- 2) Select features that are highly dependent on the target variable, avoiding features that do not improve model performance.

Types of filter-based feature selection methods include:

- For small numbers of features:
 - Use scatterplots to visually assess relationships between features and the target variable.

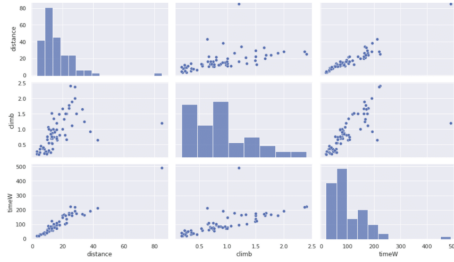


Fig. 6: Scatter plot analysis of a simple dataset with few features. Taken from lecture notes by Dr. Konstantinos Makantasis.

- For analyzing relationships:
 - Use Pearson correlation to measure the linear correlation between features and the target variable. The Pearson correlation is a normalized version of covariance[8] and measures the degree of linear correlation between two variables.

$$r = \frac{\sigma_{xy}}{\sigma_x \sigma_y} = \frac{\sum (X_i - \bar{X})(Y_i - \bar{Y})}{\sqrt{\sum (X_i - \bar{X})^2 \sum (Y_i - \bar{Y})^2}}$$

where:

X_i, Y_i : The individual data points.

\bar{X}, \bar{Y} : The means of the variables X and Y .

r is unitless, meaning it has no associated units of measurement.

H. Measurement

Quantitative measurements[5] numerically represent attributes and are fundamental for evaluating machine learning models by providing an objective means to assess the model's performance. We can analyse the model's effectiveness by comparing model predictions to actual outcomes. Appropriate selection and reporting of measurement methods, including their reliability, validity, and potential biases, are essential to ensure accurate interpretation and meaningful results. This section will look at the measurements used in this study.

The function used in machine learning and statistical modelling to quantify the difference between the predicted outputs of a model and the actual target values is called the loss function. It serves as a measure of the model's performance, guiding the optimisation process to improve predictions.

For a single prediction:

$$\text{Loss}(\hat{y}, y) = f(\hat{y}, y)$$

Where:

\hat{y} : Predicted value.

y : Actual value.

f : Specific loss function formula

The aggregation of the loss function across the entire dataset is called the cost function so that;

$$\text{Cost}(\hat{y}, y) = \frac{1}{N} \sum_{i=1}^N \mathcal{L}(\hat{y}_i, y_i)$$

In the problem we are considering, we will try to predict whether a person will recidivate given information about his or her previous criminal history is a binary classifier problem. A binary classifier is a function that can be applied to features X such as $(x_1, x_2, x_3, \dots, x_n)$ and maps them to an output Y , where $Y \in \{0, 1\}$. It is a supervised learning technique; therefore, a test set is extracted from the available data to validate the model before being deployed in production.

$$f(x_1, x_2, x_3, \dots, x_n) = Y \in \{0, 1\}$$

The function will return a value between 0 and 1; therefore, a threshold value is operated to classify the result as true or false. The model will subsequently classify predictions as true or false according to the threshold value.

For the classification problem that we have in hand, we will primarily use the log-likelihood cost function defined as:

$$\mathcal{L}_{\text{log-likelihood}} = - \sum_{i=1}^N [y_i \ln(\hat{y}_i) + (1 - y_i) \ln(1 - \hat{y}_i)]$$

Negative log-likelihood focuses on the distance between the labels y_i and the predicted probabilities \hat{y}_i . If we consider a sample where:

- y_i is one and \hat{y}_i is close to 1: $y_i \ln(\hat{y}_i)$ is close to zero, while $(1 - y_i) \ln(1 - \hat{y}_i)$ is zero, so that the resultant loss is close to zero.
- y_i is 1 and \hat{y}_i is far from 1: $y_i \ln(\hat{y}_i)$ is large, while $(1 - y_i) \ln(1 - \hat{y}_i)$ is zero so that the resultant loss is large.
- y_i is zero and \hat{y}_i is close to 0: $y_i \ln(\hat{y}_i)$ is zero, while $(1 - y_i) \ln(1 - \hat{y}_i)$ is also close to zero so that the resultant loss is close to zero.
- y_i is zero and \hat{y}_i is far from 0: $y_i \ln(\hat{y}_i)$ is zero, while $(1 - y_i) \ln(1 - \hat{y}_i)$ is large so that the resultant loss is large.

In this scenario, we can obtain four kinds of results:

The number of samples that are TP, TN, FP or FN can be organised in what is known as a confusion matrix, that is shown in Figure 7. This tool makes it easy to perform calculations that determine the validity of the model at hand.

Prediction	Classif	Outcome	Description
1	1	True Positive (TP)	The model correctly predicted the positive class.
1	0	False Positive (FP)	The model incorrectly predicted the positive class (a false alarm).
0	1	False Negative (FN)	The model incorrectly predicted the negative class (a miss).
0	0	True Negative (TN)	The model correctly predicted the negative class.

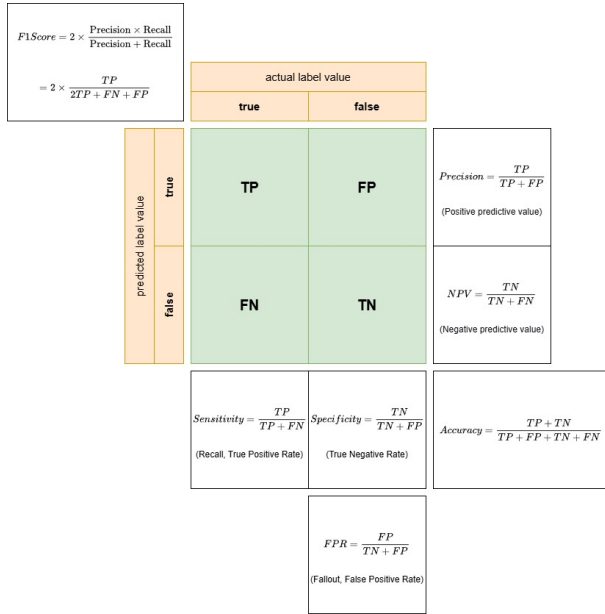


Fig. 7: Confusion matrix and associated equations

There are several key performance metrics derived from the confusion matrix, each offering a different perspective on evaluating the effectiveness of a binary classification model.

The **accuracy** of a model is a straightforward measure that evaluates the proportion of correct predictions (both True Positives and True Negatives) out of the total number of predictions. It can be mathematically defined as:

$$\text{Accuracy} = \frac{TP + TN}{TP + FP + TN + FN}$$

for a dataset,

$$\text{Accuracy} = \frac{1}{N} \sum_{i=1}^N 1(\hat{y}_i = y_i)$$

Precision answers the question: "Out of all the observations predicted to be positive, how many were positive?" In other words, it measures the model's ability to avoid false positives.

$$\text{Precision} = \frac{TP}{TP + FP}$$

Recall or **sensitivity** measures the model's ability to correctly identify positive cases. It answers the question: "Out of all the actual positive instances, how many did the model correctly identify as positive?"

$$\text{Recall} = \frac{TP}{TP + FN}$$

Specificity measures the model's ability to identify negative cases correctly. It answers the question: "Out of all the actual negative instances, how many did the model correctly identify as negative?"

The formula for specificity is:

$$\text{Specificity} = \frac{TN}{TN + FP}$$

The F1-score is the harmonic mean of [precision](model-performance-precision) and [recall](model-performance-recall). It provides a single metric that balances precision and recall, which is useful when there is an uneven class distribution or when false positives and false negatives are important.

The formula for the F1 score is:

$$F1 = 2 \times \frac{\text{Precision} \times \text{Recall}}{\text{Precision} + \text{Recall}}$$

$$= 2 \times \frac{TP}{2TP + FN + FP}$$

In imbalanced datasets, computing separate F1-scores for the minority and majority classes is important because a single overall F1-score can mask poor performance on the minority class. While the majority class may achieve a high F1-score due to its dominance, the minority class often suffers from low recall, leading to a much lower F1-score. Thus, the F1-score for the majority class (negative class) is:

$$F1_{\text{majority}} = 2 \times \frac{TN}{2TN + FN + FP}$$

The macro F1-score calculates the F1-score for each class separately and then takes the average, giving equal weight to both classes regardless of class imbalance.

$$F1_{\text{macro}} = \frac{F1_{\text{minority}} + F1_{\text{majority}}}{2}$$

The weighted F1-score takes class imbalance into account by weighting the F1-score of each class according to its support (i.e., the number of instances in that class). It is computed as:

$$F1_{\text{weighted}} = \frac{N_{\text{minority}} \cdot F1_{\text{minority}} + N_{\text{majority}} \cdot F1_{\text{majority}}}{N_{\text{total}}}$$

As can be seen in Figure 8, the Receiver Operator Characteristic (ROC) curve is plotted by varying the decision threshold of the classifier and plotting the corresponding values of FPR (on the x-axis) and sensitivity or TPR (on the y-axis). Each point on the ROC curve represents a (FPR, TPR) pair for a particular threshold value.

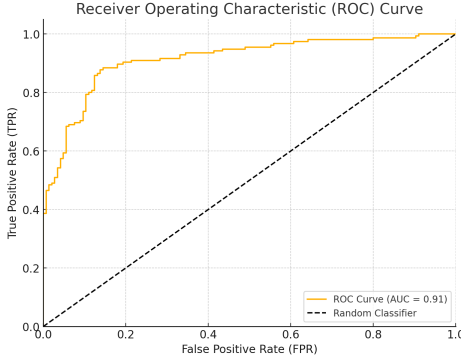


Fig. 8: ROC curve

The Area Under the ROC Curve (AUC) is a key indicator of model performance. The value of the AUC ranges from 0 to 1:

- A perfect classifier has an AUC of 1, indicating it achieves a TPR of 1 while keeping the FPR at 0.
- A model with an AUC of 0.5 performs no better than random guessing.
- Higher AUC values indicate better overall performance.

The goal of a classifier is to maximise the TPR (correctly predicting positive instances) while minimising the FPR (incorrectly classifying negative instances as positive). Ideally, the ROC curve should approach the top-left corner of the plot, indicating a high TPR with a low FPR.

In summary, the ROC curve helps to visualise and compare the trade-offs between true positives and false positives across different thresholds, and the AUC provides a single number summarising the model's ability to discriminate between positive and negative classes.

III. DATA PREPARATION

The COMPAS dataset used in this study is publicly available through ProPublica's GitHub repository[7]. This repository contains the dataset and other assets used by ProPublica to investigate the biases present in the COMPAS risk assessment tool.

The file chosen for this analysis is **compas-scores-two-years.csv**, as it provides the cleanest and most relevant data for general recidivism prediction. This CSV file contains the key data required for our study, including several attributes related to demographics, criminal history, COMPAS risk scores, and the two-year recidivism outcomes that are important for exploring the predictive capabilities and the ethical implications of machine learning models in the context of recidivism prediction.

The dataset includes important information about individuals. Following an initial analysis, a list of the key fields in the dataset is below.

- Personal Information, includes attributes such as **age**, **race**, **age_category**, etc.
- Case and Event-Related Details are the fields prefixed with **c_** that provide a timeline and details of a person's interactions with the criminal justice system.
- Violence Risk Assessment are the fields prefixed with **v_** and are associated with the violence risk assessment in COMPAS. This dimension predicts violent recidivism risk.
- Case-Level Details for Violent Recidivism are the fields prefixed with **vr_**. These fields provide additional details specific to violent recidivism events.
- Juvenile Criminal Record are the fields prefixed with **juv_**. These fields capture information about an individual's juvenile criminal record, which is a key predictor of future adult criminal behaviour.
- Previous Charges and Severity can be deduced from fields such as **priors_count** and **juv_** fields.
- Additional fields, including **r_charge_**, **r_offense_**, **vr_** fields, **c_charge_degree**, and **c_charge_desc**, provide a broader perspective on criminal history and severity.
- Two-Year Recidivism, or the **two_year_recid** field in the COMPAS dataset, indicates whether an individual reoffended (recidivated) within two years of their initial assessment or release. This field is critical for evaluating the predictive accuracy of the COMPAS risk assessment tool.
- Decile Score is a standardized risk score in the COMPAS dataset. It categorizes an individual's likelihood of recidivism into ten equal groups (deciles) where 1 is the lowest risk, and 10 is the highest risk. Each decile represents approximately 10% of the sample when applied to a norm group.

A. Preparing the data for further analysis and training

Before we can perform any analysis or apply machine learning techniques, it is important to pre-process and prepare the dataset so that we can handle missing values, encode categorical features, and split the data into training, testing, and validation sets. This step will produce a clean dataset for building accurate and unbiased models. The following steps outline the procedures to prepare the dataset for further analysis and training.

B. Initial look at data and missing values handling

The dataset has 7214 instances over 53 columns. The COMPAS system risk factor is the field **decile_score**, but the dataset also contains information about whether or not the person recidivated through the label **two_year_recid**.

The first step in this data analysis step was removing the features irrelevant to this exercise or with over 50% missing records. We removed all the COMPAS-administrative

labels and additional recidivism information apart from **two_year_recid**, narrowing the dataset to 17 fields.

The difference between **c_jail_in** and **c_jail_out** was calculated into a new field, **days_in_jail** and the difference between **in_custody** and **out_custody**, in a new field, **days_in_custody**. We subsequently removed the features containing date information from the dataset, together with **days_in_custody**, as it contained no information. At this stage, the dataset contains thirteen features: eight numerical, four categorical, and one descriptive. It also contains two labels, **decile_score**, which we will treat as the leading label in this exercise and **two_year_recid**, which we are keeping to compare the prediction power of our models to the original one.

C. Imputation of missing data

While examining the resultant dataset, we noticed that **days_b_screening_arrest** has 6907 values that are not null. Whilst it is possible to eliminate the rows that contain the null values at this stage, we replaced the missing values using a KNN imputation technique by grouping the numeric values of this dataset so that we can calculate the missing values. We checked this process by plotting the distribution of **days_b_screening_arrest** before and after imputation to see if any variations occurred.

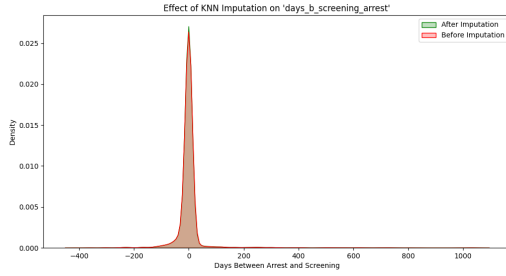


Fig. 9

At this stage, the dataset contains four categorical features that need encoding for machine learning algorithms. This section will focus on converting them into a numerical format using two encoding techniques. The categorical features and their values are listed below:

Feature	Description	Unique Values
sex	Gender of the individual	Male Female
race	Race of the individual	African-American Caucasian Hispanic Asian Native American Other
age_cat	Age category	Less than 25 25 - 45 Greater than 45
c_charge_degree	Degree of the criminal charge	F (Felony) M (Misdemeanor)

The following transformations are applied:

- One-Hot Encoding on **sex**, **race**, and **c_charge_degree**, transforming them into binary columns.
- Ordinal Encoding on **age_cat**. This encoding technique was preferred over one-hot in this case as it preserves order, thus respecting the inherent ranking of the category.

The original categorical columns were retained in the dataset for future use in the analysis steps.

D. Splitting the data into train, test and dev

A stratified shuffle split technique is preferred to create the train, test, and dev datasets whilst ensuring that the splits are proportional by **race**. In the first split, 80% Train and 20% Test are created, whilst in the Second split, The 20% Test is further divided into 10% Test and 10% Dev.

IV. DATA EXPLORATION AND VISUALISATION

Here we will examine the dataset in more detail to understand the patterns, distributions, and relationships. In this exercise, we will use more of the visual tools available through several Python libraries to identify potential biases, explore correlations between variables, and uncover insights that may influence the outcomes of predictive models.

A. Demographic analysis

We begin this analysis by segmenting the dataset based by race and gender.

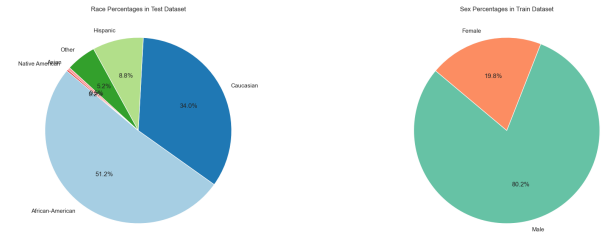


Fig. 10: Race and Sex breakdown for the dataset.

By examining the racial composition of the dataset, we observe the following:

- Over half of the test dataset is composed of African-American individuals, suggesting that the dataset may be imbalanced, with a disproportionate representation of one racial group.
- Asians and Native Americans each makeup only 0.2% of the dataset; this underrepresentation might raise some concerns as it may lead to challenges in statistical analysis or machine learning models. Such concerns include the lack of reliability or significance for these groups due to insufficient data.

Figure 10 also shows our dataset's male/female split, with females comprising only 13.8%. It is, therefore, evident that the female group is underrepresented, which can lead to biased models as models may overfit male patterns and underperform

on females and misleading conclusions as insights derived might generalise poorly for the female subgroup.

B. Age distribution analysis

We used a boxplot to illustrate the age patterns across racial groups, helping to identify central values, spread, and any anomalies.

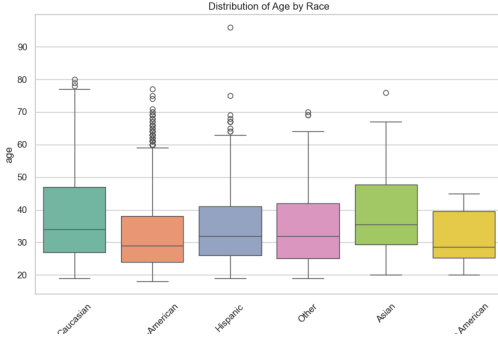


Fig. 11

Race	Median Age	Distribution Description
African-American	≈30 years	Concentrated in the 20–40 range, with a relatively narrow spread. We notice outliers above 60 years, indicating fewer older individuals.
Caucasian	≈40 years	Broader age range, from 20 to 70+ years. We notice more older individuals (upper outliers), making this group appear older on average.
Hispanic	≈30–35 years	Moderately broad spread, with most individuals between 20 and 50 years.
Asian	≈30 years	Narrow distribution, concentrated between 25 and 40 years. No outliers.
Native American	≈33 years	Very tight distribution, with all ages clustered closely around the median (little variability). It is important to note that this group accounts for a tiny portion of the population.
Other	≈35–40 years	Similar to Caucasians but with slightly fewer older individuals. The IQR shows a widespread.

C. Analysing distributions

Next, we plotted the distributions of all the features in our dataset; this is depicted in Figure 12. From these histograms, we notice

- The age distribution shows a right-skewed pattern, with most individuals falling in the younger age ranges (20–40 years).
- There is a significant over-representation of certain racial groups, particularly African Americans, which could indicate potential biases in the dataset's sampling.
- Most individuals have zero juvenile felony counts, zero juvenile misdemeanour counts, and no recorded "other" juvenile offences, with each distribution rapidly declining for higher counts.

- A large proportion of individuals have a low number of prior offences, but there is a long tail indicating some individuals have a significant number of priors.
- Most individuals have relatively short jail durations, with a few experiencing significantly longer durations.
- The distribution of days between screening and arrest is clustered around zero, with few extreme outliers on both ends.
- The decile scores appear relatively evenly distributed, but slight patterns suggest clustering at specific score levels (e.g., lower decile scores are slightly more frequent).
- Two-year recidivism plot shows a near-equal distribution, indicating a balanced dataset for recidivism outcomes.

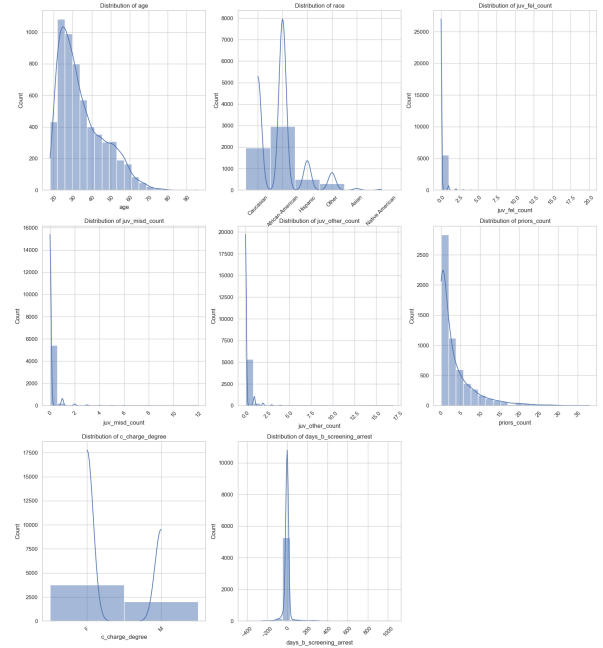


Fig. 12

D. Correlation analysis

The correlation matrix heatmap shown in Figure 13 was created to gather more insights and identify the areas of high correlation. This plot raises a number of interesting observations, namely:

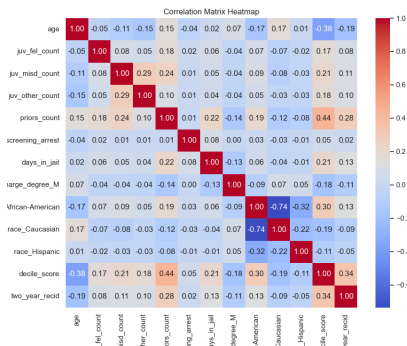


Fig. 13: Correlation matrix heatmap.

- Individuals with more prior offences tend to have higher risk scores, hence prior criminal behaviour is a key factor in risk assessment models. The number of prior offences also correlates positively with recidivism so it is true; individuals with more prior offences tend to re-offend more often.
- Older individuals tend to have lower risk scores, that is age may be inversely related to the risk of recidivism, with younger individuals being assessed as higher risk. In addition, older individuals are also less likely to recidivate, supporting this general trend.
- Individuals with higher risk scores are often recidivate within two years, suggesting that the risk score (**decile_score**) is a predictor, to a certain extent, of recidivism.
- A correlation of 0.30 indicates that being African-American is moderately associated with higher decile scores, raising potential concerns about racial bias in the scoring system. At the same time, Caucasian individuals correlate -0.19 and, therefore, are less likely to receive higher risk scores.
- The time spent in jail has only a small positive relationship with the likelihood of re-offending within two years
- Juvenile felony, misdemeanour, and other counts are positively correlated, indicating that individuals with one type of juvenile record will often have other types.

Figure 14 is a pair plot created to substantiate these observations further to show the relationships among the selected numerical features, with the recidivism outcome (**two_year_recid**) as the hue.

- **age** vs **priors_count**. Younger individuals tend to have fewer prior offences, but the prior count is scattered as age increases, showing that younger offenders tend to continue having problems with the judicial system.
- **age** vs **decile_score**. Older individuals tend to have lower decile scores. Younger individuals are associated with higher scores.
- **priors_count** vs **decile_score**. Positive trend: Higher priors count leads to higher decile scores, suggesting a strong correlation, indicating the tendency for offenders to be viewed as a risk community



Fig. 14: Pair plot for important features

- The distribution of **decile_score**. Two-year recidivists tend to cluster at higher decile scores (6–10 range). Non-recidivists are spread more evenly across scores.

E. Analysis of decile score relationship with race

The COMPAS dataset has been extensively discussed in recent years regarding the fairness of the scores assigned to individuals, especially considering the race component. Although the tool does not use race as one of the features in decile score prediction, there are concerns that race can be associated indirectly with other features. In this section, we will look at the data from the race point of view to see what patterns we can deduce from the dataset.

As a first step, we create a boxplot to compare the distribution of **decile_score** across different racial groups.

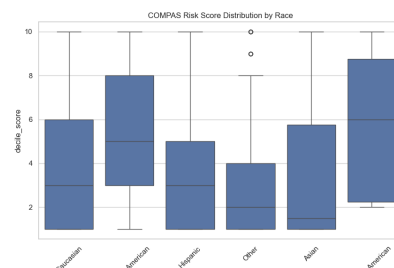


Fig. 15: Risk score distribution by race.

From this plot, we notice that African Americans have higher median scores and broader distributions, which suggests a potential bias in the COMPAS scoring system. In addition, Hispanics, Asians, and Other groups scored lower on average, which may indicate differences in the risk assessment process or underlying data inputs.

We then investigated the correlation of **decile_score** with **two_year_recid** by race:

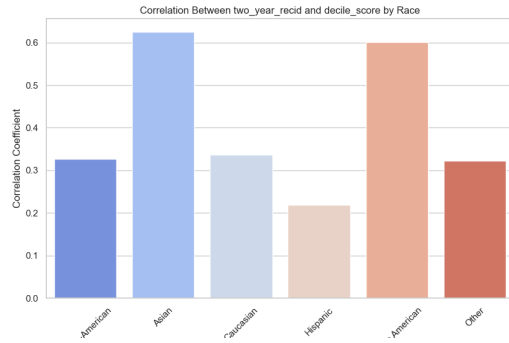


Fig. 16: Correlation of **decile_score** with **two_year_recid** by race

- Asians and Native Americans show the highest correlations, indicating that, for these groups, COMPAS scores align more closely with observed recidivism outcomes. However, it is important to remember that these groups comprise a tiny percentage of the population.
- African-Americans, Caucasians, and Others have moderate correlations, so COMPAS scores are only somewhat predictive for these groups but not as strongly as for Asians or Native Americans.
- The correlation between **two_year_recid** and **decile_score** for Hispanics is 0.22, the lowest among the groups, suggesting that for Hispanic individuals, the COMPAS scores are less predictive of actual recidivism outcomes than other racial groups. The low correlation for the Hispanic group is an area of concern because if the COMPAS scores do not accurately predict recidivism for this ethnicity, this could mean that the scoring system may overestimate or underestimate their actual risk, which could lead to misclassification of individuals, leading to potential unfair treatment, for example, harsher parole conditions or sentencing, or allowing more criminals on the streets.

The distribution of **decile_score** for Hispanic individuals was then compared with that of other racial groups using kernel density plots (KDE).

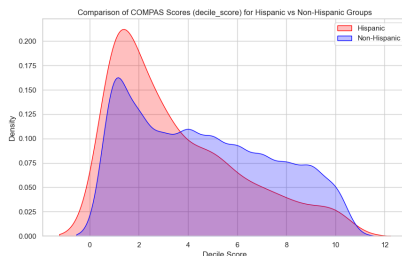
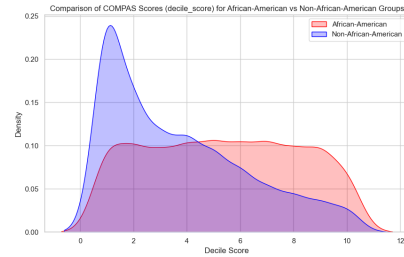


Fig. 17: Risk score distribution for Hispanics compared with the risk score distribution of the dataset.

The plots show that the peak density for Hispanic individuals occurs at a lower score of around 2. In contrast, non-Hispanic individuals have a flatter distribution extending to



H

Fig. 18: Risk score distribution for African-American compared with the risk score distribution of the dataset.

higher scores, albeit peaking in the same region, suggesting that Hispanic individuals are more likely to receive lower COMPAS scores than other individuals.

One has to note that we have previously seen that Hispanic individuals account for 8.8% of the population, which is significantly smaller compared to African-American and Caucasian groups. Although by any means not conclusive, these aspects raise questions about how risk scores are calibrated for underrepresented groups.

1) Analysis of the African-American sector: We created another density plot to compare the distribution of risk scores between African-American individuals and non-African-American individuals.

Here, we notice that African Americans are more likely to receive risk scores in the higher decile range, exceeding a value of six, than non-African Americans, suggesting that the COMPAS tool systematically assigns higher risk scores to African Americans. As noticed previously, non-African-American individuals show a strong peak at around a score of 2, with fewer individuals in this group receiving scores in the higher ranges.

This disparity in score distributions raises concerns about potential bias in the COMPAS scoring system. African Americans appear to be disproportionately classified as higher risk, a factor which could impact downstream decisions such as sentencing or parole.

F. Robustness of **decile_score**

As a final analysis, we compare **decile_score** with **two_year_recid** to see how many high-risk individuals receded and how many individuals categorised as low-risk did not. This metric is very powerful, as it assesses the validity of the predicted risk metric. Throughout this study, we will also use this test to validate our predicted scores for the machine learning models.

An important decision in this exercise is the selection of the decile score threshold that will dictate that values above it are more likely to recidivate and those below it not. In order to do this, we compared the decile score and two-year record for multiple thresholds. We examined the number of true negatives (the individuals with a decile score lower than the threshold and did not recidivate), true positives (those with a decile score higher or equal than the threshold and did recidivate) and false

positives and negatives. We then used these results to calculate the sensitivity, specificity, precision and accuracy:

Threshold	Sensitivity	Specificity	Precision	Accuracy
4	0.628659	0.670551	0.60941	0.651707
5	0.521186	0.766299	0.645823	0.656039
6	0.411017	0.83811	0.674889	0.645989
7	0.3047	0.897323	0.708147	0.63074
8	0.196071	0.938268	0.721986	0.604401

TABLE II: Performance Metrics for Different Decile Score Thresholds

Following this procedure, a threshold of 5 was decided to provide the best balance of these metrics. With this threshold, the total accuracy and precision are moderate, indicating that while the model performs reasonably well overall, there is room for improvement. We notice a low sensitivity compared to specificity; the model is better at identifying non-recidivists than recidivists.

The metrics for each racial group were then calculated with this threshold;

- The Caucasian group has a relatively high specificity but low sensitivity, indicating the COMPAS model more effectively avoids false positives but struggles to identify true positives.
- The African-American group shows higher sensitivity but lower specificity compared to Caucasians. This suggests the model identifies more recidivists among African Americans but at the cost of more false positives.
- The Hispanic group has low sensitivity, meaning the model struggles significantly to identify true positives in this group. Precision is also the lowest, indicating a high false-positive rate.

The significant disparity in sensitivity and specificity across racial groups highlights potential fairness issues in the model's predictions. For example, the model disproportionately favours Caucasians and Asians in terms of specificity while penalizing African-Americans with higher false-positive rates.

V. EXPERIMENTS

We start this investigation by explaining very shortly the project structure for this exercise. Unlike analysis where notebooks were used, Python files were used to create the models, tune them and carry out experiments.

- A **utils** area contains all the scripts necessary to download the dataset, split it in train and test datasets, define the feature engineering module and create the preprocessing pipeline. As most of these scripts manipulate the dataset, their result is ultimately saved in a **data** folder.
- A **models** area contains the definition of the k-nearest neighbour, logistic regressor and neural network. In all three model definitions, an initial step is to try and access a 'best parameters' file that contains the result of an optimization step that is described later on in this list. The model is combined with the preprocessor to create the particular model pipeline.

- An **experiments** area contains all the experiments that are carried out as part of this exercise. It contains three types of modules:

- 1) A script is designed to evaluate the performance of a machine learning pipeline on test data. It computes and reports key metrics, including accuracy, ROC AUC, F1-scores for both classes, precision, overall accuracy, and weighted average F1. The evaluation includes generating and saving a classification report, a confusion matrix image, and an ROC curve graph. Results are saved in the **results** folder.
- 2) **Experiment** scripts for each of the three machine learning methods that is used for training, evaluating, and saving a model pipeline. It loads the training and test datasets, fits the specified model pipeline on the training data, evaluates its performance on the test data using the functions explain previously, and saves the trained pipeline to a file.
- 3) **Optimization** scripts that tunes the machine learning model pipelines using grid search with cross-validation. After completing the grid search, each script saves the best parameters and corresponding cross-validation accuracy. It also exports the full results of the grid search as a CSV file. This process is carried out to select the optimal model hyperparameters.

A. Preparing data for machine learning

Building on the insights derived from the previous section, the next step involved the creation of the pipeline to transform the raw dataset into a format optimized for machine learning models.

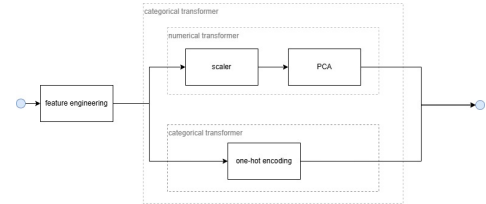


Fig. 19: The data transformation pipeline for this project.

The pipeline created for this application is shown in Figure 19. It is based on the `Pipeline` functionality provided by the Scikit-learn library, integrating feature engineering and transformations for both numerical and categorical data. The pipeline consists of the following components:

- **Feature Engineering:** The pipeline begins with a feature engineering unit where raw features are processed to derive new attributes and filter out irrelevant ones. This step prepares the dataset for subsequent transformations. Feature engineering is based on the Python's `pandas` library. The transformation logic was encapsulated in a reusable function, `feature_engineering`, which was wrapped in a `FunctionTransformer` to integrate it into the machine learning pipeline.

The primary objective of the feature engineering step is to:

- Retain only the most relevant features for recidivism prediction.
- Derive new features to enhance the dataset’s predictive capacity.
- Remove unnecessary or redundant columns to reduce noise and complexity.

Following the analysis phase, a subset of the dataset’s features was identified as relevant for training and subsequent analysis. These include demographic attributes (e.g., age, race, sex), prior criminal history (`priors_count`), juvenile offense counts (`juv_fel_count`, `juv_misd_count`, `juv_other_count`), and timestamps related to jail custody (`c_jail_in`, `c_jail_out`) and general custody (`in_custody`, `out_custody`). Features such as names and IDs were excluded to avoid introducing irrelevant or sensitive information into the analysis.

We decided to keep the `race` feature so that we can use it to analyse the results obtained by the machine learning models, but it will be removed from the features set at a later stage.

Two new features were created to capture time-based patterns:

- **days_in_jail**: Calculated as the absolute difference in days between the `c_jail_in` and `c_jail_out` timestamps. This feature provides insight into the duration of incarceration for a given charge.
- **days_in_custody**: Calculated as the absolute difference in days between the `in_custody` and `out_custody` timestamps. This feature reflects the total time an individual spent in custody.

These features offer information about the extent of an individual’s interaction with the criminal justice system, which may correlate with recidivism likelihood. As the originating features had frequent nulls, zeros were imputed where the calculation did not result into a number. The final processed dataset contains the following columns:

- **Demographic Features**: `sex`, `age`, `race`.
- **Juvenile Offense Counts**: `juv_fel_count`, `juv_misd_count`, `juv_other_count`.
- **Criminal History**: `priors_count`.
- **Derived Features**: `days_in_jail`, `days_in_custody`.

This feature engineering process resulted in a clean and concise dataset, ready for use in machine learning pipelines. By deriving meaningful features and eliminating irrelevant data, the preprocessing step set a strong foundation for building predictive models.

- **Numerical transformer:**

- **Scaler**: Numerical features are standardized or normal-

ized to ensure they are on a similar scale. This step is critical for distance-based algorithms and gradient-based optimization.

- **PCA (Principal Component Analysis)**: After scaling, dimensionality reduction is applied to numerical features to eliminate redundancy and reduce the complexity of the data. PCA retains the most important components that explain the majority of variance in the data.

- **Categorical Transformer:**

- **One-Hot Encoding**: Categorical variables are transformed into numerical format using one-hot encoding. This technique creates binary columns for each category, ensuring compatibility with machine learning models.

- **Integration of Transformations**: The outputs from the *numerical transformer* and *categorical transformer* are combined into a unified dataset using the Scikit-learn pipeline framework. This ensures that the transformations are consistently applied to both training and testing datasets, improving reproducibility and minimizing data leakage.

This pipeline structure allows for the independent processing of numerical and categorical features, enabling specialized transformations for each type of data. The modular design, powered by Scikit-learn’s `Pipeline` and `ColumnTransformer`, ensures flexibility and reusability, making it adaptable to various datasets and machine learning workflows. By incorporating scaling, PCA, and encoding, the pipeline ensures the dataset is well-prepared, reducing potential biases or inefficiencies during model training.

This approach represents an effective preprocessing strategy for heterogeneous datasets and highlights the importance of tailored transformations for achieving robust model performance.

1) Logistic regression experiments: Logistic regression results demonstrate that the model achieved a test accuracy of approximately 69.5%, and a ROC AUC of 0.74 as can be seen in Figure 20, outperforming the baseline COMPAS results in several key areas. The logistic regression model demonstrated better overall accuracy compared to COMPAS and a higher ROC AUC, and therefore improved discriminatory power in separating the two classes. Furthermore, the F1-score for the minority class was significantly higher, reflecting a better balance between precision and recall, particularly for the harder-to-predict positive class.

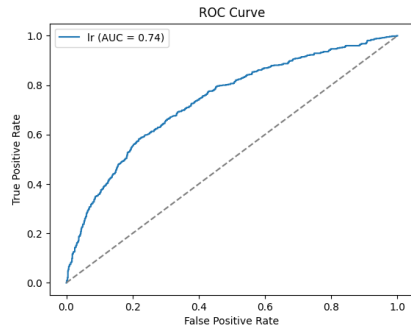


Fig. 20: Receiver operator characteristic plot for logistic regression model

Examining the confusion matrix shown in Figure 21 we can see that the logistic regression model's improvements. The tuned model identified fewer false positives and false negatives relative to the COMPAS predictions, suggesting that logistic regression was more effective at minimizing classification errors across both classes. The tuned model demonstrated better precision and recall for class 1 (minority), whereas COMPAS appears to struggle more with recall, as it has a larger number of false negatives. This is a significant improvement as false negatives correspond to the people that has a high decile score but did not have further encounters with the legal system.

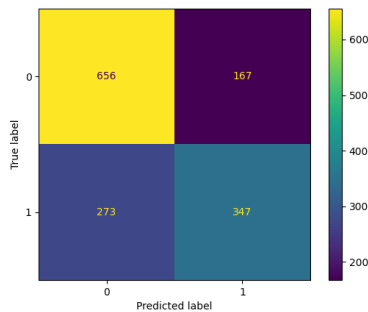


Fig. 21: Confusion matrix for logistic regression model

The `class_weight='balanced'` parameter in Scikit-learn's `LogisticRegression` adjusts the weights of the classes to be inversely proportional to their frequencies in the training data, hence attempting to address class imbalance. By assigning higher importance to the minority class 1, this parameter ensures that the model does not disproportionately favour the majority class 0. As a result, the recall for class 1 improved to 0.67 compared to previous configurations, indicating that the model is better at correctly identifying instances of the minority class. However, this improvement came at a slight cost to precision for both classes, as the model now predicts class 1 more frequently, leading to a lower overall accuracy (67.71%).

With the balanced weights, the model's improved recall for the minority class, that is the individuals who will reoffend,

may lead to better proactive interventions. However, the trade-off is an increase in false positives, which could mean incorrectly labelling individuals as high risk. This could unfairly subject some individuals to harsher penalties

This result is a clear indicator of the ethical and societal implications of optimizing machine learning models, especially for imbalanced datasets like this one.

2) *K-nearest neighbour experiments*: The KNN model outperformed both logistic regression and COMPAS, achieving a test accuracy of 73.46% and a ROC AUC of 0.80. With an F1-score of 0.66 for the minority class, KNN demonstrated a better balance between precision and recall, improving classification fairness. Its strong discrimination ability (AUC = 0.80) suggests that KNN is more effective in distinguishing between recidivists and non-recidivists.

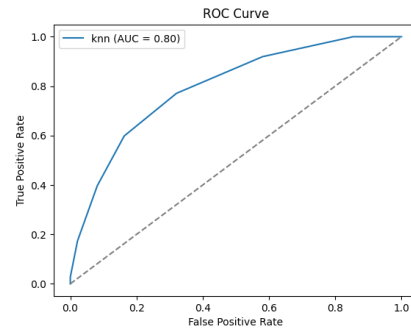


Fig. 22: Receiver operator characteristic plot for k-nearest neighbour model

Compared to logistic regression, the confusion matrix for kNN, shown in Figure 23 shows fewer false positives and a higher number of true positives. This suggests that kNN is better at minimizing classification errors for the majority class while still improving recall for the minority class. Compared to COMPAS, kNN drastically reduces false negatives and false positives, making it a significantly more balanced and fair model for this classification task.

In practical terms, the improved performance of kNN translates to more accurate predictions, particularly for identifying individuals at higher risk. This could lead to better decision-making, reducing the likelihood of unfairly labeling low-risk individuals as high risk while improving the identification of true high-risk cases.

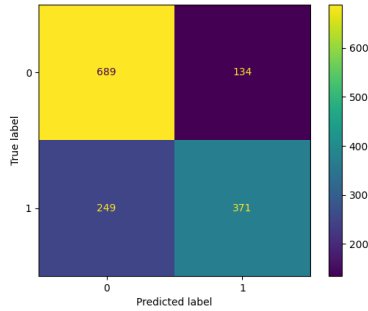


Fig. 23: Confusion matrix for k-nearest neighbour model

The KNN model with `weights='distance'` achieved an AUC of 0.9991, suggesting extreme overfitting. While precision and recall were near-perfect, the model likely memorized the training data rather than learning generalizable patterns. This raises fairness concerns, as overfitting could amplify dataset biases. Future work should explore regularization techniques to improve model robustness.

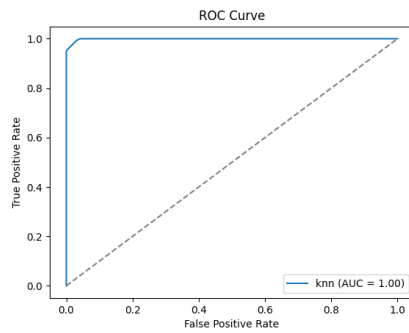


Fig. 24: Receiver operator characteristic plot for k-nearest neighbour model with weights parameter set to distance. This is probably the result of overfitting.

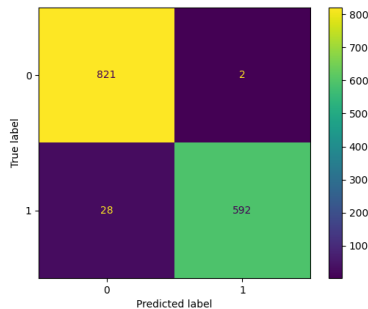


Fig. 25: Confusion matrix for k-nearest neighbour model with weights parameter set to distance. This is probably the result of overfitting.

3) *Neural network experiments:* The neural network implemented in exercise consists of an input layer, followed by two fully connected hidden layers. The first hidden layer contains 128 neurons, and the second contains 64 neurons, each followed by batch normalization and a ReLU activation function. The output layer consists of 2 neurons with a softmax activation function. The model is trained using the cross-entropy loss function, optimized with the Adam optimizer, and employs a mini-batch training strategy with a default batch size of 32 and 20 epochs.

The neural network achieved a test accuracy of 70% and an AUC of 0.75, demonstrating moderate classification performance. While recall for the minority class improved (0.69), the model still exhibited a higher misclassification rate compared to KNN. The confusion matrix revealed 242 false positives and 191 false negatives, indicating room for further optimization.

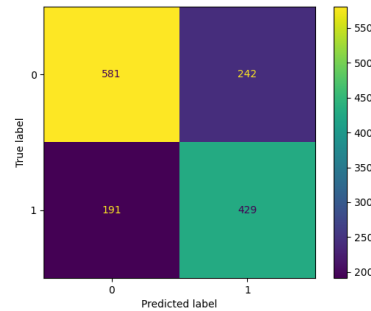


Fig. 26: Confusion matrix for neural network model.

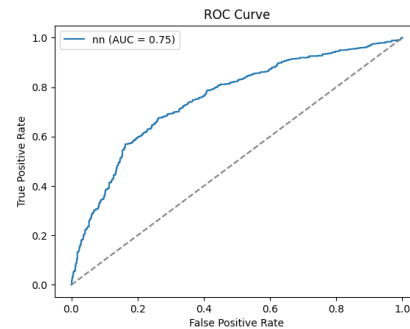


Fig. 27: Receiver operator characteristic plot for neural network model.

Changing the loss function to mean squared error caused some differences in how the network performs. While the overall accuracy stayed the same, the model became better at identifying instances of the minority class but less precise when predicting the majority class. This happens because MSE treats errors more evenly, which helps the model focus on reducing overall mistakes rather than just making the most confident predictions.

By using MSE, the model seems to make fairer predictions across both classes, improving recall for the minority class.

However, this comes with a trade-off; we may not be as confident in its predictions. Choosing MSE or another loss function depends on what matters most for the task—whether it’s catching as many minority cases as possible or making highly confident predictions.

4) *Final comments on experiments:* Table III summarizes the performance metrics across the different techniques.

Technique	F1-Score Class 0 Class 1	Precision (Class 1)	Overall Accuracy	Weighted Avg F1-Score
lr	0.75 0.61	0.68	0.70	0.68
lr balanced	0.71 0.64	0.61	0.68	0.67
knn	0.78 0.66	0.73	0.73	0.72
knn distance	0.98 0.98	1.00	0.98	0.98
nn	0.76 0.62	0.66	0.70	0.69
nn mse	0.72 0.68	0.63	0.70	0.70

TABLE III: Performance Metrics for Classification Techniques

The k-Nearest Neighbors (knn) model performed better than logistic regression in both overall accuracy and weighted F1-score, with a significant improvement in capturing minority class instances. The use of distance-based weights (knn distance) led to exceptional performance, with near-perfect metrics across all evaluation categories. However, this result indicates overfitting and should be carefully validated on more data.

The neural network (nn) achieved comparable performance to logistic regression, with a slight improvement in recall for the minority class. Changing the loss function to mean squared error (nn mse) resulted in a better balance between precision and recall for both classes, leading to a slight improvement in the weighted F1-score compared to the cross-entropy loss variant. This suggests that MSE as a loss function can encourage fairer predictions across classes in certain scenarios.

Overall, knn outperformed lr and nn models in most metrics, with nn mse demonstrating improved balance compared to nn. However, the extremely high metrics of knn distance should be interpreted with caution, as they may not generalize well to unseen data. The choice of model and loss function should depend on the specific application and the importance of precision, recall, and generalization.

VI. ETHICAL REVIEW

This subject has been already discussed into some details in Section IV where we have shown how the COMPAS model affects the different race groups and genders. In this study we have also investigated the robustness of the COMPAS decile score when compared to actual two year recidivism rate. In Section V we had the opportunity to see how different loss functions and model parameters affect the metrics that are obtained. The dataset examined in this study is particularly significant, as its findings have real-world implications that

directly impact individuals and their families. False negatives and false positives mean that potentially dangerous individuals are put on the streets and others might receive an unjustly harsh treatment.

The analysis of the data, model performance, and insights generated raises several ethical concerns and societal implications that warrant careful evaluation. First, the dataset used for training likely reflects inherent biases from historical or systemic inequalities, particularly in domains such as recidivism prediction. If the dataset is biased, models trained on it, regardless of their performance metrics, may inadvertently perpetuate or amplify these biases. For instance, minority groups may face disproportionately higher false positive or false negative rates, which could lead to unjust outcomes such as harsher treatment or denied opportunities.

The insights generated by these models also need to be critically examined. While models like knn distance demonstrated near-perfect performance on the test set, such high metrics often indicate overfitting, meaning the model may not generalize well to new or unseen data. Overfitting, combined with biased data, could result in overly confident predictions that fail to account for the complexities of real-world cases. This raises questions about the trustworthiness of these insights, especially in high-stakes decisions that affect individuals’ lives.

From a societal perspective, the implications of deploying these models are profound. A model with high false positive rates for the minority class (e.g., labeling individuals as high risk when they are not) can lead to unfair treatment, reinforcing discrimination and systemic inequities. Conversely, high false negative rates (e.g., failing to identify high-risk individuals) could pose public safety concerns. These outcomes highlight the importance of balancing precision and recall while ensuring fairness and transparency in predictions.

To mitigate these ethical risks, several measures are necessary. Regular bias audits should be conducted on the dataset and model outputs to identify and address disparities. Additionally, stakeholders must be involved in the development process to ensure that the models align with societal values and legal standards. Explainability techniques should also be employed to make model predictions more interpretable, allowing decision-makers to understand the rationale behind predictions. Finally, models should be rigorously tested on diverse and representative datasets to ensure robustness and fairness across different demographic groups.

In summary, while the results demonstrate strong technical performance, the ethical considerations of bias, fairness, and societal impact must remain at the forefront. Developing and deploying machine learning models in sensitive domains requires a careful balance between accuracy and equity, with continuous efforts to ensure accountability and mitigate harm.

VII. WEB PORTAL DEPLOYMENT

As a final step, the models created in this project were exposed using the Gradio framework, which exposes web forms using HTTP tunnelling.

We first abstracted the consumption of the models by setting up a production area in our project and creating a consumption API for each model, which, when given a single example, will return the result from the model. Although not used, we also created functionality to submit multiple lines and get a response for each in return.

We then created a Gradio application that creates a simple form to allow the user to input the data for the example, submit it, and view the results from the three models. Gradio also gives the functionality to save the results in a file.



Fig. 28: The Gradio application running in VSCode.

We tested the application locally to ensure proper functionality. Gradio also exposes the form through a remote URL that uses tunnelling to consume the app that is running locally. This URL was captured and used in a simple HTML file from GitHub as a GitHub page.

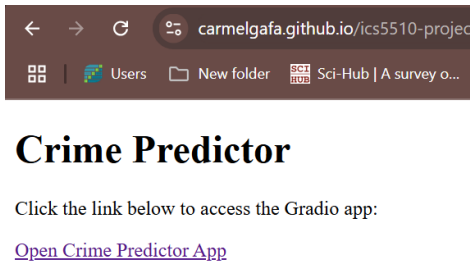


Fig. 29: GitHub page to access the Gradio app. URL: <https://carmelgafa.github.io/ics5510-project/>

It is important to note that Gradio’s remote URL and tunnel remain active for only 72 hours, emphasizing that this setup is intended solely as a demonstration of the system’s capabilities rather than as a production-ready solution.

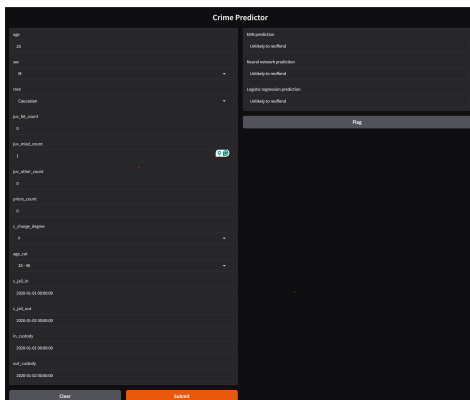


Fig. 30: Gradio app form showing the results from the three ML models.

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