# 1st IAA-CSIC Severo Ochoa School on Statistics, Data Mining, and Machine Learning







#### Parametric modeling of time series: Gap-filling application

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# PLATO IAA-CSIC Science Team



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## Outline

- Introduction
- The interpolation problem
- Parametric modeling: ARMA
- MARA
- Conclusions

### Software

- git pull
- Jupyter notebooks
- Python software:

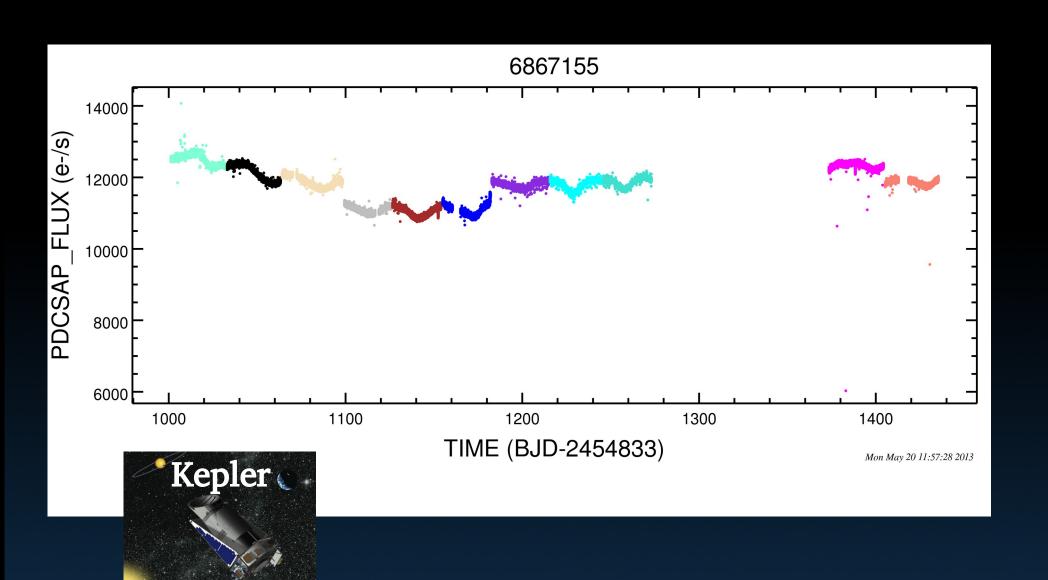
pip install numpy scipy astropy statsmodels matplotlib pandas ipython

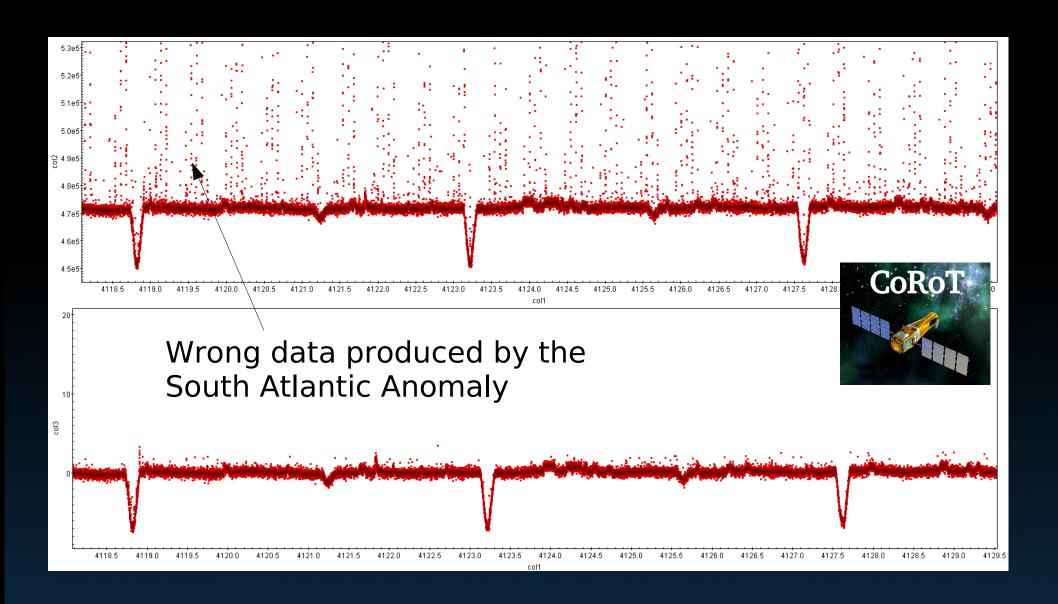
### Introduction

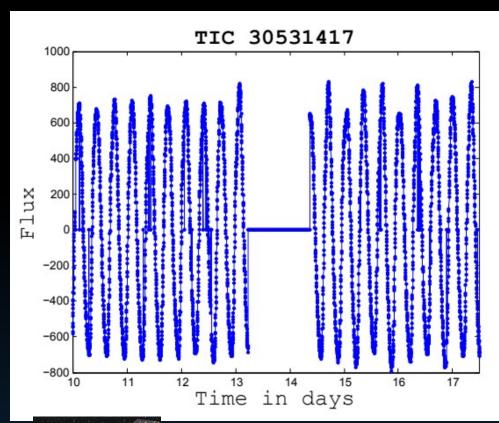
Interpolation is a very usual problem in data analysis:

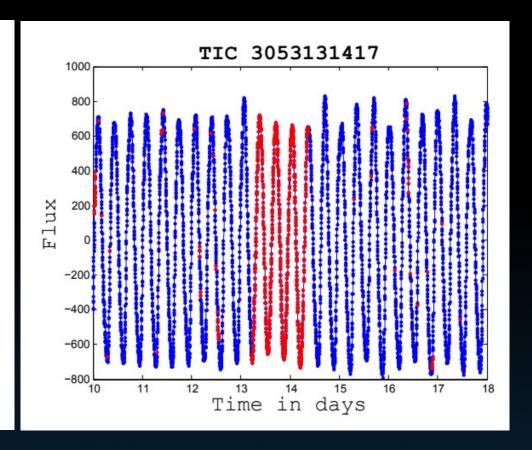
Gaps ↔ Irregular sampling ↔ Outliers

Signal Identification ↔ Data Modeling ↔ Interpolation ↔ Compression ↔ Noise Filtering ↔ ...



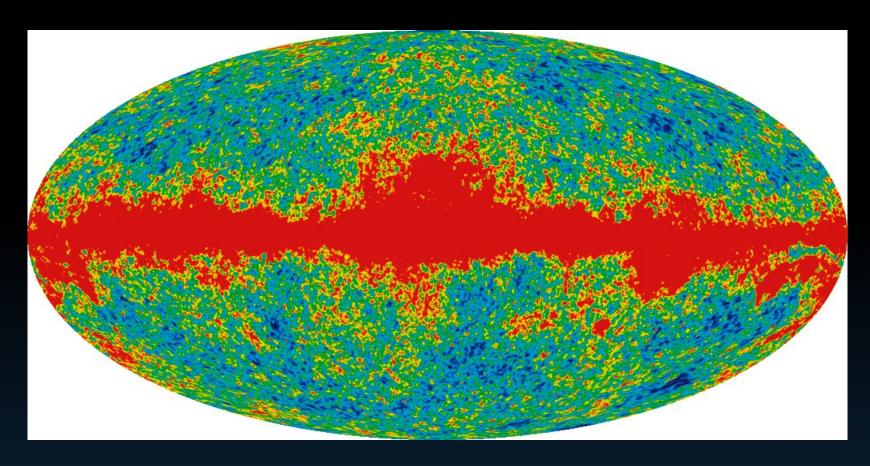








TESS 2-minute cadence data



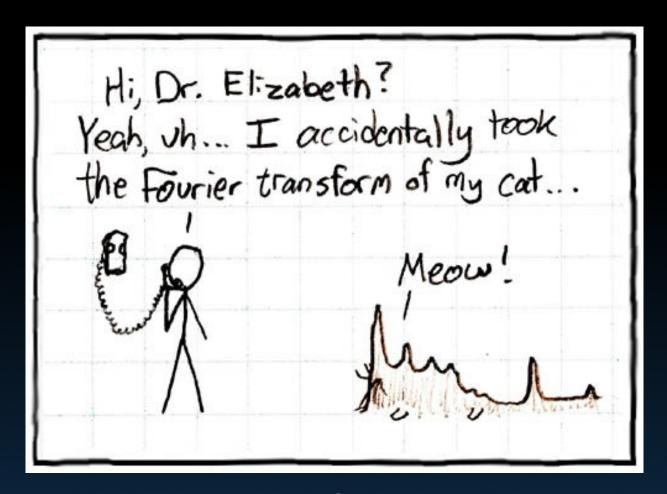
WMAP full-sky map in Ka band. The red band is microwave emission from our Galaxy.

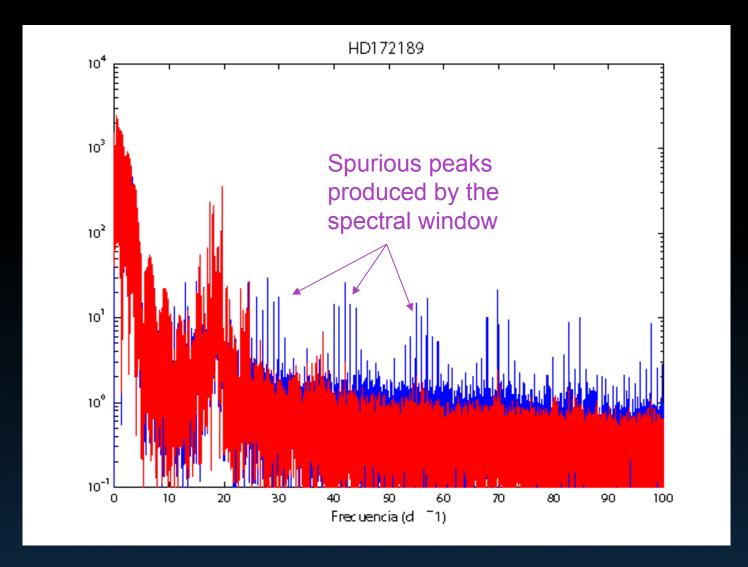
#### Why it is necessary to interpolate?

Why are gaps a problem?

Can't we just analyze the chunks of data that don't have gaps?

#### **FOURIER**





### Spectral Window

#### FOURIER ANALYSIS WITH UNEQUALLY-SPACED DATA\*

#### T. J. DEEMING

Dept. of Astronomy, The University of Texas at Austin, Tex., U.S.A.

(Received 22 March; in revised form 11 November, 1974)

$$w_T(t) = \begin{cases} 1; & (-T/2 \le t \le T/2) \\ 0; & \text{otherwise} \end{cases}$$

$$w_N(t) = \sum_{k=1}^{N} \delta(t - t_k).$$
Data windows

Transform

Discrete and Finite Fourier 
$$F_{T,N}(v) = \int_{-\infty}^{+\infty} w_{T,N}(t) f(t) e^{i2\pi v t} dt$$
,  $F_{T,N}(v) = F(v) * W_{T,N}(v)$ , Transform

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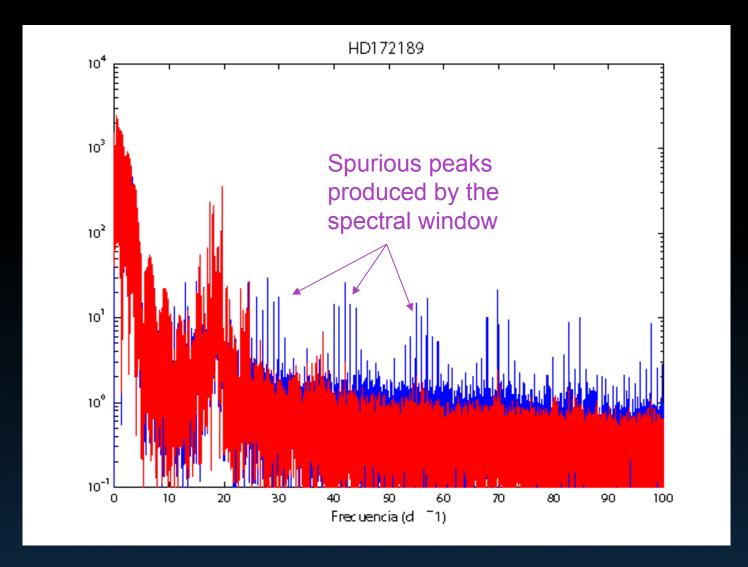
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$$W_N(v) = \sum_{k=1}^N e^{i2\pi v t_k} = \delta_N(v).$$

Spectral Window **Function** 



So how do we interpolate in the gaps?

# Interpolation - inpainting techniques



Ecce Homo, Sanctuary of Mercy church in Borja, Spain.

## Interpolation - inpainting techniques



Left panel is the original from Elías García Martínez. Right panel shows restoration attempt from Cecilia Giménez.

# A gap-filling method aimed to be <u>information preserving</u>



**Unbiased** 



Non-closed form expression, fitting functions that can be analytic or not.

# Interpolation

#### Univariate interpolation

## scipy.interpolate

interp1d(x, y[, kind, axis, copy, ...])

BarycentricInterpolator(xi[, yi, axis])

KroghInterpolator(xi, yi[, axis])

barycentric\_interpolate(xi, yi, x[, axis])

krogh\_interpolate(xi, yi, x[, der, axis])

pchip\_interpolate(xi, yi, x[, der, axis])

CubicHermiteSpline(x, y, dydx[, axis, ...])

PchipInterpolator(x, y[, axis, extrapolate])

Akima1DInterpolator(x, y[, axis])

CubicSpline(x, y[, axis, bc\_type, extrapolate])

PPoly(c, x[, extrapolate, axis])

BPoly(c, x[, extrapolate, axis])

Interpolate a 1-D function.

The interpolating polynomial for a set of points

Interpolating polynomial for a set of points.

Convenience function for polynomial interpolation.

Convenience function for polynomial interpolation.

Convenience function for pchip interpolation.

Piecewise-cubic interpolator matching values and first derivatives.

PCHIP 1-d monotonic cubic interpolation.

Akima interpolator

Cubic spline data interpolator.

Piecewise polynomial in terms of coefficients and breakpoints

Piecewise polynomial in terms of coefficients and breakpoints.

#### 1-D Splines

**BSpline**(t, c, k[, extrapolate, axis])

Univariate spline in the B-spline basis.

make\_interp\_spline(x, y[, k, t, bc\_type, ...])

Compute the (coefficients of) interpolating B-spline.

make\_lsq\_spline(x, y, t[, k, w, axis, ...])

Compute the (coefficients of) an LSQ B-spline.

#### Additional tools

lagrange(x, w)

approximate\_taylor\_polynomial(f, x, degree, ...)

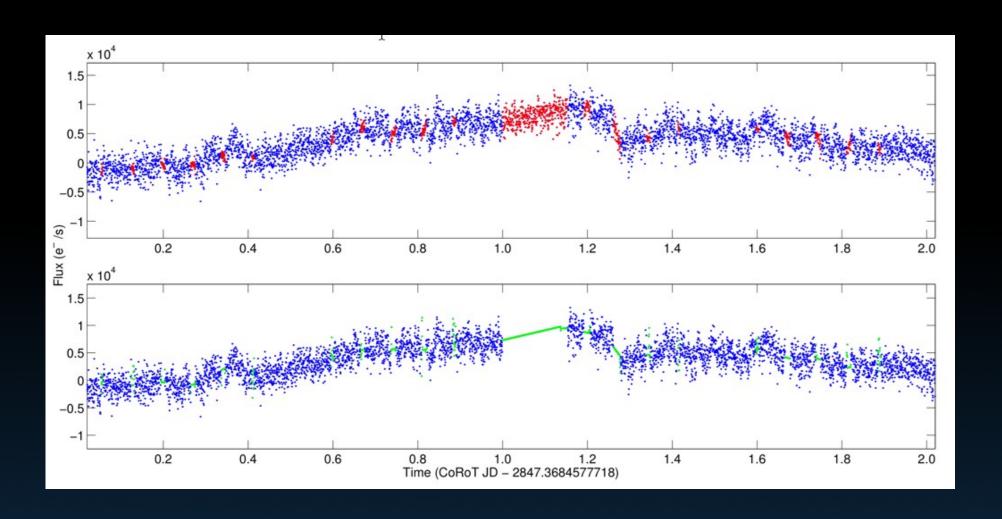
pade(an, m[, n])

Return a Lagrange interpolating polynomial.

Estimate the Taylor polynomial of f at x by polynomial fitting.

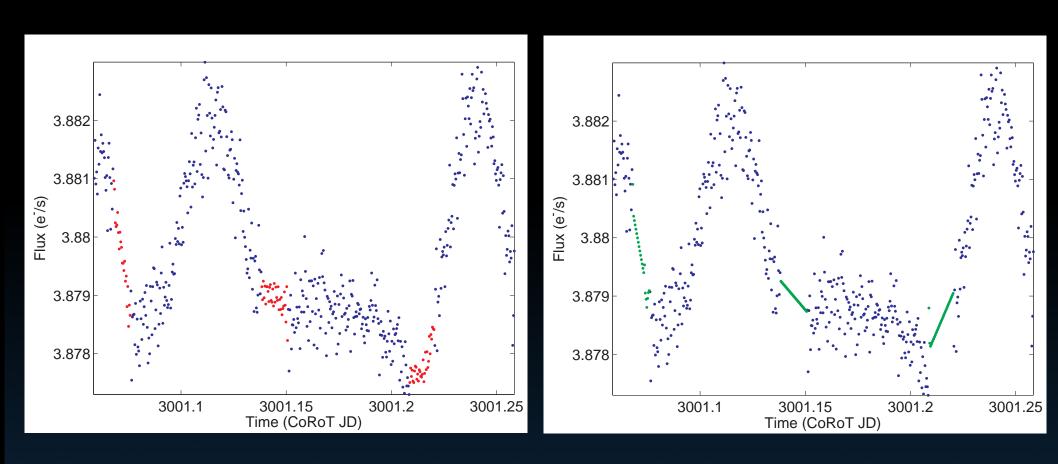
Return Pade approximation to a polynomial as the ratio of two polynomials.

# Interpolation: linear

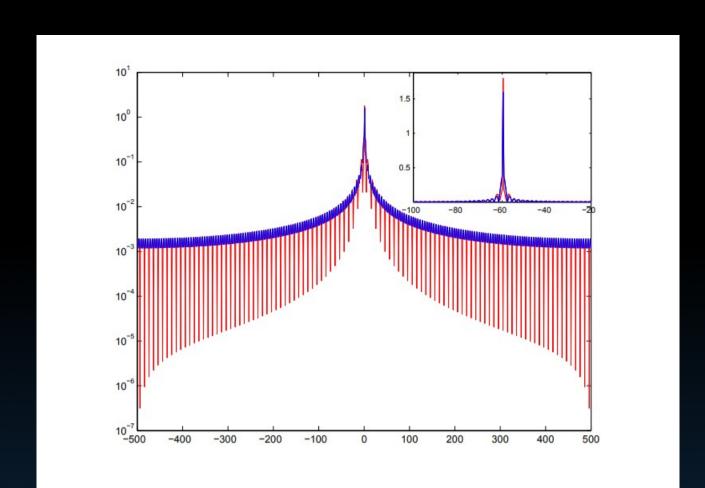


HD49933 − solar-like star with periods ~ min

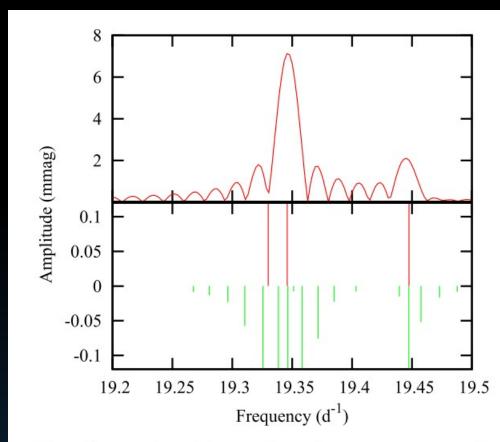
## Interpolation: linear



HD 48784 – Delta Scuti star with periods ~ hr



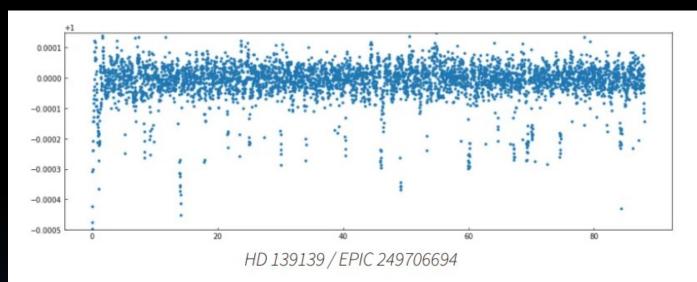
**Fig. A.1.** Spectral response function in log scale associated to gapped data (in blue) and linearly interpolated data (in red). See the inset for a zoom of the central peak in linear scale.



**Figure 4.** Schematic periodogram of known frequency components (with positive amplitudes) and extracted components (negative amplitudes) in a simulation.

- Although the signal has just 3 frequencies, numerous frequencies of relatively high amplitudes are required by the non-linear least squares algorithm to fit the signal.
- Even though the difference between simulated and extracted f1 is only 0.0007 d<sup>-1</sup> many fictitious components appear as a result of the insufficient quality of the fitting.

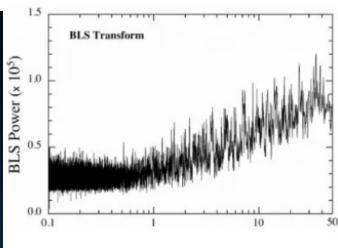
### Ultra-precise data analysis



The Random Transiter Star

In the era of ultra-precise data from satellites we are going to need ultra-precise data analysis to understand what we observe

**Information-preserving interpolation** 



# A gap-filling <u>information</u> <u>preserving</u> method



**Unbiased** 



Non-closed form expression, fitting functions that can be analytic or not.



**ARMA** interpolation (MIARMA)

# Go to: www.menti.com use the code: 97012

And answer this anonymous poll:

How familiar are you with ARIMA?

# ARIMA DANTZA ESKOLA



The class of autoregressive (AR) processes, and its extensions, autoregressive moving-average (ARMA) processes, are dense in the class of Gaussian linear processes.

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#### Wold Decomposition Theorem (Wold 1938)

"Any stationary random process can be decomposed into the sum of a purely random process and a linearly deterministic process, and further that the random part is a moving average, i.e. the convolution of a fixed, causal, invertible filter with an uncorrelated noise process."

AR 
$$x_t = \sum_{k=1}^p \alpha_k x_{t-k} + a_t$$
 Purely Autoregressive

MA 
$$x_t = -\sum_{k=1}^q b_k n_{t-k} \rightarrow X = B*N$$
 Moving Average

ARMA 
$$x_t = \sum_{k=1}^p lpha_k x_{t-k} - \sum_{k=1}^q b_k n_{t-k} + a_t$$
 Mixed AR + MA

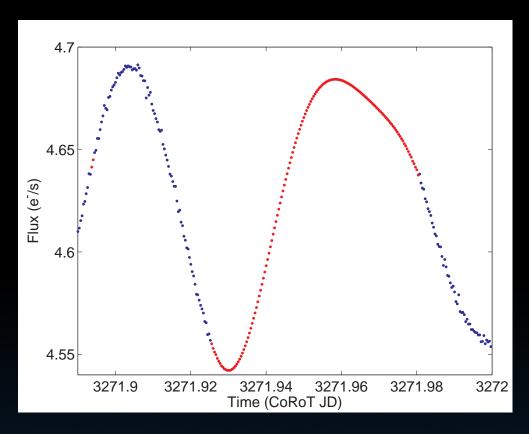
More information: Feigelson, Eric D., Babu, Jogesh G.,

Caceres, Gabriel A., 2018, Frontiers in Physics, 6, 80

Go to Jupyter Notebook and load:

ARMA\_pred1.ipynb

#### ARMA models fits deterministic signal too



e.g. a stochastically excited damped harmonic oscillation is described by an AR process of second order, i.e., p = 2 (Honerkamp, 2002)

$$x(t) = a_1 x(t - 1) + a_2 x(t - 2) + \eta(t)$$

This is the discretized version of the stochastic second order differential equation for the stochastically excited damped harmonic oscillation

$$\ddot{x}(t) = -\gamma \dot{x}(t) + \omega^2 \dot{x}(t) + \eta(t)$$

Roth, M., Zhugzhda, Yu D., 2010, Astronomy Letters, 36, 1

#### ARMA models fits deterministic signal too

#### Exercise 1

Make a simulated signal with just one harmonic component and try to fit an ARMA model to it. e.g.

```
nobs = 250
f1 = 0.1
t = np.arange(nobs)
yh = np.sin(2*np.pi*f1*t)
noise = np.random.normal(0,1,nobs)
```

Then plot it as in ARMA\_pred1.ipynb

#### ARMA models fits deterministic signal too

#### **Hints:**

Use some start params for the model fitting to converge:

```
model.fit(trend='nc', disp=-1, start_params=[1, 0])
```

• If you still have convergence problems and you want to force it to go through, you can try transparams=False

```
model.fit(trend='nc', disp=-1, start_params=[1, 0], transparams=False)
```

AR 
$$x_t = \sum_{k=1}^p lpha_k x_{t-k} + a_t$$
 Purely Autoregressive

MA 
$$x_t = -\sum_{k=1}^q b_k n_{t-k}$$
 Moving Average

ARMA 
$$x_t = \sum_{k=1}^p lpha_k x_{t-k} - \sum_{k=1}^q b_k n_{t-k} + a_t$$
 Mixed AR + MA

# How can we determine the orders p and q?

Go to Jupyter Notebook and load:

ARMA\_pred2.ipynb

#### Exercise 2

Continue the previous example and try to fit other models in order to find the optimal one.

#### For more on this, check:

Time Series Analysis: Forecasting and Control (Wiley Series in Probability and Statistics) 5th Edition

by George E. P. Box, Gwilym M. Jenkins, Gregory C. Reinsel, Greta M. Ljung

#### CRITERION FOR SELECTION OF THE ORDER (P,Q)

An ungapped data segment is modelled. Iteration through p, q

• Given the k model, its Akaike coefficient is obtained  $(AIC_k)$ 

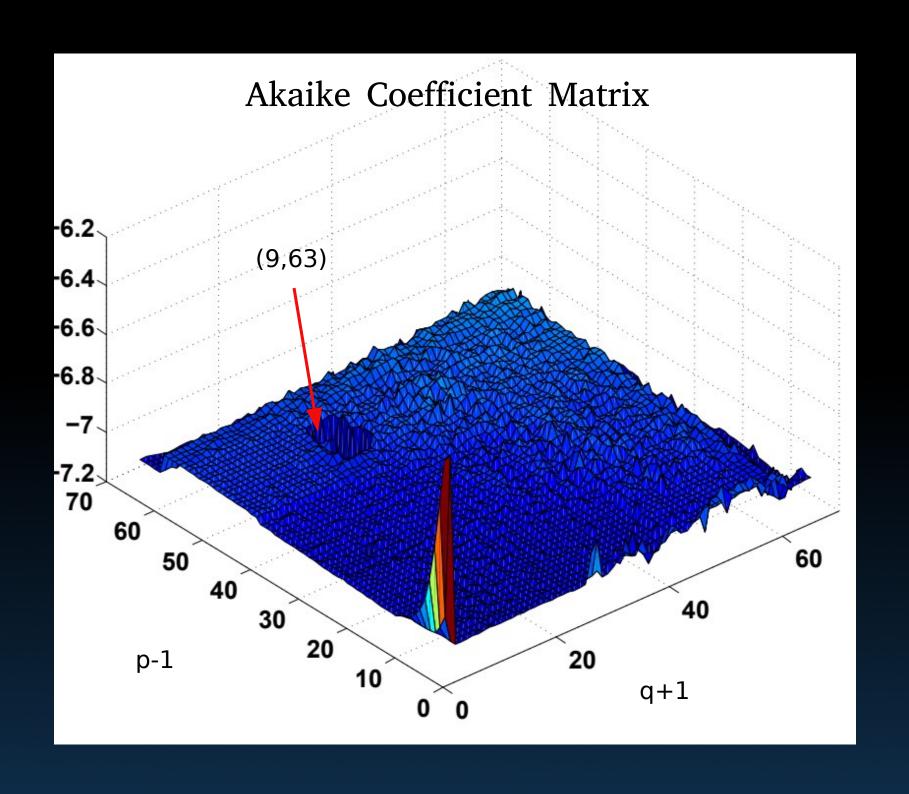
$$AIC_k = N.\log(V) + 2(p+q)$$

N = length of the data segment,

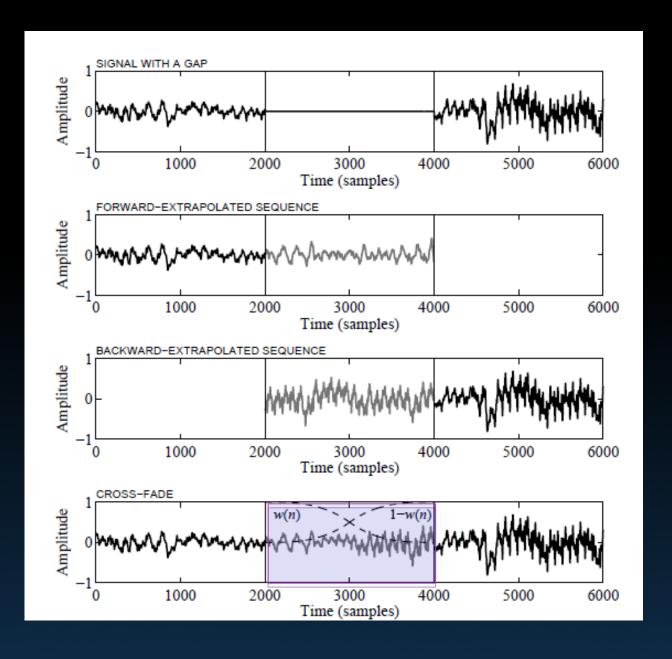
V = mean quadratic error of prediction

• Akaike criterion: the optimal model has min  $AIC_k$ 

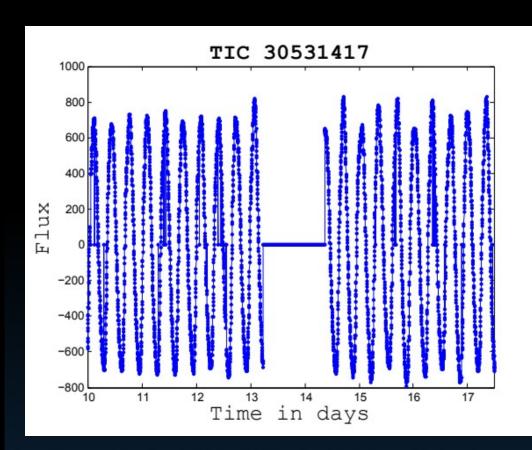
 Maximum Entropy Principle: guarantees that it is the best model that we can find with the information available.

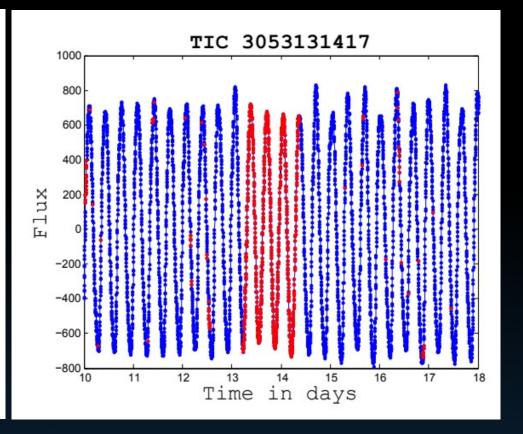


# MIARMA



# MIARMA















#### Extension of the original algorithm:

- \* Nonstationary processes with ARIMA,
- \* Continuous time processes: CARMA, CARIMA
- \* Fractional integrated processes: ARFIMA, CARFIMA
- \* Fractal analysis with ARFIMA processes
- \* Multidimensional interpolation
- \* Parallelization of the computations

• • •

# Module of AR Algorithms (MARA)



#### Lessons to take home

- Interpolation might be strictly necessary in order to perform ultra-precise data analysis and solve current challenges in astrophysics.
- Any data processing technique should be aimed to preserve the original information according to the scientific method.
- Use non-analytic models when you don't have any prior information about the signal.
- If you know that your data is stochastic or non-analytic don't use analytic models for fitting/interpolating.
- Remember that ARMA can represent deterministic signals too.
- And finally, if you like the interpolations I've shown you here ask me about MARA.

# "Music is the silence between the notes." - Claude Debussy

Thank you for your attention!