ML Cheat Sheet

1 Math Prerequisites

1.1 Derivatives

- $\partial(\mathbf{XY}) = (\partial \mathbf{X})\mathbf{Y} + \mathbf{X}(\partial \mathbf{Y})$
- $\frac{\partial \mathbf{f}(\mathbf{g}(\mathbf{u}(\mathbf{x})))}{\partial \mathbf{x}} = \frac{\partial \mathbf{u}(\mathbf{x})}{\partial \mathbf{x}} \frac{\partial \mathbf{g}(\mathbf{u})}{\partial \mathbf{u}} \frac{\partial \mathbf{f}(\mathbf{g})}{\partial \mathbf{g}}$
- $\frac{\partial \mathbf{x}^T \mathbf{a}}{\partial \mathbf{x}} = \frac{\partial \mathbf{a}^T \mathbf{x}}{\partial \mathbf{x}} = \mathbf{a}$
- $\frac{\partial \mathbf{a}^T \mathbf{X} \mathbf{b}}{\partial \mathbf{X}} = \mathbf{a}\mathbf{b}^T$
- $\frac{\partial \mathbf{a}^T \mathbf{X}^T \mathbf{b}}{\partial \mathbf{X}} = \mathbf{b}\mathbf{a}^T$
- $\frac{\partial \mathbf{X}}{\partial X_{ij}} = \mathbf{J}^{ij}$, J^{ij} is the single entry matrix
- $\frac{\partial \mathbf{b}^T \mathbf{X}^T \mathbf{X} \mathbf{c}}{\partial \mathbf{X}} = \mathbf{X}\left(\mathbf{b}\mathbf{c}^T + \mathbf{c}\mathbf{b}^T\right)$
- $\frac{\partial \mathbf{x}^T \mathbf{B} \mathbf{x}}{\partial \mathbf{x}} = \left(\mathbf{B} + \mathbf{B}^T\right)\mathbf{x}$
- $\frac{\partial}{\partial \mathbf{x}}(\mathbf{x} - \mathbf{A}\mathbf{s})^T \mathbf{W} (\mathbf{x} - \mathbf{A}\mathbf{s}) = 2\mathbf{W}(\mathbf{x} - \mathbf{A}\mathbf{s})$
- $\frac{\partial}{\partial \mathbf{X}} \|\mathbf{X}\|_F^2 = \frac{\partial}{\partial \mathbf{X}} \operatorname{Tr}\left(\mathbf{X}\mathbf{X}^H\right) = 2\mathbf{X}$

1.2 Linear Algebra

- **positive definite** (pd) if $\mathbf{a}^T \mathbf{V} \mathbf{a} > 0$
- $(\mathbf{x} - \mathbf{b})^T (\mathbf{x} - \mathbf{b}) = \|\mathbf{x} - \mathbf{b}\|_2^2$
- $\|\mathbf{X}\|_F = \|\mathbf{X}^T\|_F$

1.3 Distributions

Valid distribution $p(x) > 0$, $\forall x$ and $\sum p(x) = 1$
Model is identifiable iff $\theta_1 = \theta_2 \rightarrow P_{\theta_1} = P_{\theta_2}$

- **Gaussian** (Not convex):
  $\mathcal{N}(x|\mu, \sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{(x-\mu)^2}{2\sigma^2}\right)$
  $\mathcal{N}(x|\mu, \Sigma^2) = \frac{\exp(-\frac{1}{2}(x-\mu)^T \Sigma^{-1}(x-\mu))}{\sqrt{(2\pi)^D det(\Sigma)}}$
- **Poisson**: P(k events in interval) $= e^{-\lambda} \frac{\lambda^k}{k!}$
- **Bernoulli**: $p(y|\mu) = \mu^y (1-\mu)^{1-y}$

1.4 Convexity

A function $f(x)$ is convex if

- for any $\mathbf{x}_1, \mathbf{x}_2 \in \mathbf{X}$ and $0 \leq \lambda \leq 1$, we have : $f(\lambda \mathbf{x}_1 + (1-\lambda)\mathbf{x}_2) \leq \lambda f(\mathbf{x}_1) + (1-\lambda) f(\mathbf{x}_2)$
- it is a sum of convex functions
- composition of convex and linear functions
- $f(x) = g(h(x))$, g,h are convex, g increasing
- the Hessian $\mathbf{H}$ is positive semi-definite

1.5 Others

- Production of independent variables:
  $\operatorname{Var}(xy) = \mathbb{E}(x^2)\,\mathbb{E}(y^2) - [\mathbb{E}(x)]^2 [\mathbb{E}(y)]^2$
- Covariance matrix of a data vector $\mathbf{x}$
  $$\boldsymbol{\Sigma} = \frac{1}{N} \sum_{n=1}^{N} (\mathbf{x}_n - \mathbb{E}(\mathbf{x}))(\mathbf{x}_n - \mathbb{E}(\mathbf{x}))^T$$
- Multi-class $\mathbf{x}$
  $$p(\mathbf{y}|\mathbf{X}, \beta) = \prod^{N} p(\mathbf{y}_n|\mathbf{x}_n, \beta) = \prod^{K} \prod^{N} [p(\mathbf{y}_n = k|\mathbf{x}_n, \beta)]^{\tilde{y}_{nk}}$$

2 Cost functions

Mean square error (MSE):

$$MSE(\boldsymbol{w}) = \frac{1}{N} \sum_{n=1}^{N} (y_n - f(\mathbf{x}_n))^2$$

- MSE is **strictly convex** thus it has only one global minumum value.
- MSE is very prone to outliers.

Mean Absolute Error (MAE):

$$MAE = \frac{1}{N} \sum_{n=1}^{N} |y_n - f(\mathbf{x}_n)|$$

- MAE is more robust to outliers than MSE.

Huber loss

$$Huber = \begin{cases} \frac{1}{2} z^2 & , |z| \leq \delta \\ \delta |z| - \frac{1}{2}\delta^2 & , |z| > \delta \end{cases}$$

- Huber loss is convex, differentiable, and also robust to outliers but hard to set δ.

Tukey's bisquare loss

$$L(z) = \begin{cases} z(\delta^2 - z^2)^2 & , |z| < \delta \\ 0 & , |z| \geq \delta \end{cases}$$

Non-convex, non-diff., but robust to outliers.
Hinge loss:
$[1 - y_n f(\mathbf{x}_n)]_+ = \max(0, 1 - y_n f(\mathbf{x}_n))$
Logistic loss: $\log(1 - \exp(y_n f(\mathbf{x}_n)))$

3 Linear Regression

- Model that assume linear relationship
  $$\mathbf{y}_n \approx f(\mathbf{x}_n) := \mathbf{w}_0 + \mathbf{w}_1 \mathbf{x}_{n1} + \ldots = \mathbf{w}_0 + \mathbf{x}_n^T \mathbf{w} \approx \tilde{\mathbf{x}}_n^T \mathbf{w}$$
  ,where $\tilde{x}$ contains offset comp.
- $D > N$ problem: task is underdetermined.

4 Optimization

- Local minimum:
  $L(w^*) \leq L(w)\ \forall w : \|w - w^*\| < \epsilon$
- Global minimum: $L(w^*) \leq L(w)\ \forall w$

4.1 Grid search

- Compute the cost over a grid of V points. Exponential Complexity $\mathcal{O}(|V|^D)$, D is the dimension. Hard to find a good range of values. No guarantee to converge.

4.2 GD - Gradient Descent (Batch)

- GD uses only first-order information and takes steps in the opposite direction of the gradient
- Given cost function $\mathcal{L}(\mathbf{w})$ we want to find $\mathbf{w}$
  $$\mathbf{w} = \arg\min_{\mathbf{w}} \mathcal{L}(\mathbf{w})$$
- Take steps in the opposite direction of the gradient
  $$\mathbf{w}^{(t+1)} \leftarrow \mathbf{w}^{(t)} - \gamma \boldsymbol{\nabla} \mathcal{L}(\mathbf{w}^{(t)})$$
- With γ too big, method might diverge. With γ too small, convergence is slow.
- Very sensitive to ill-conditioning $\Rightarrow$ always normalize features $\Rightarrow$ allow different directions to converge at same speed.

4.3 SGD - Stochastic Gradient Descent

SGD update rule (only n-th training example):

$$\mathbf{w}^{(t+1)} \leftarrow \mathbf{w}^{(t)} - \gamma \boldsymbol{\nabla} \mathcal{L}_n(\mathbf{w}^{(t)})$$

Idea: Cheap but unbiased estimate of grad.

$$\mathbb{E}[\boldsymbol{\nabla} \mathcal{L}_n(\mathbf{w})] = \boldsymbol{\nabla}(\mathbf{w})$$

Robbins-Monroe condition:

- $\gamma^{(t)} : \sum_{t=1}^{\infty} \gamma^{(t)} = \infty; \sum_{t=1}^{\infty} (\gamma^{(t)})^2 < \infty$
- e.g. $\gamma^{(t)} = 1/(t+1)^r, r \in (0.5, 1)$

4.4 Mini-batch SGD

Update direction ($B \subseteq [N]$):

$$\mathbf{g}^{(t)} := \frac{1}{|B|} \sum_{n \in B} \boldsymbol{\nabla} \mathcal{L}_n(\mathbf{w}^{(t)})$$

Update rule : $\mathbf{w}^{(t+1)} \leftarrow \mathbf{w}^{(t)} - \gamma \mathbf{g}^{(t)}$

4.5 Gradients for MSE

- We define the error vector $\mathbf{e}$:
  $$\mathbf{e} := \mathbf{y} - \mathbf{X}\mathbf{w}$$
- and MSE as follows:
  $$\mathcal{L}(\mathbf{w}) = \frac{1}{2N} \sum_{n=1}^{N} (\mathbf{y}_n - \tilde{\mathbf{x}}_n^T \mathbf{w})^2 = \frac{1}{2N} \mathbf{e}^T \mathbf{e}$$
- then the gradient is given by
  $$\boldsymbol{\nabla} \mathcal{L}(\mathbf{w}) = -\frac{1}{N} \mathbf{X}^T \mathbf{e}$$
- Optimality conditions:
  1. *necessary*: gradient equal zero: $\frac{d\mathcal{L}(\mathbf{w}^*)}{d\mathbf{w}} = 0$
  2. *sufficient*: Hessian matrix is positive definite: $\mathbf{H}(\mathbf{w}^*) = \frac{d^2 \mathcal{L}(\mathbf{w}^*)}{d\mathbf{w} d\mathbf{w}^T} = \frac{1}{N} X^T X$

4.6 Subgradients (Non-Smooth OPT)

A vector $\mathbf{g} \in \mathbb{R}^D$ s.t.

$$\mathcal{L}(\mathbf{u}) \geq \mathcal{L}(\mathbf{w}) + \mathbf{g}^T(\mathbf{u} - \mathbf{w}) \quad \forall \mathbf{u} \in \mathbb{R}^D$$

is the subgradient to $\mathcal{L}$ at $\mathbf{w}$. If $\mathcal{L}$ is differentiable at $\mathbf{w}$, we have $\mathbf{g} = \boldsymbol{\nabla} \mathcal{L}(\mathbf{w})$

4.7 Constrained Optimization

Find solution $\min \mathcal{L}(\mathbf{w})$ s.t. $\mathbf{w} \in \mathcal{C}$

- Add proj. onto $\mathcal{C}$ after each step:
  $$P_{\mathcal{C}}(\mathbf{w}') = \arg\min |\mathbf{v} - \mathbf{w}'|, \mathbf{v} \in \mathcal{C}$$
  $$\mathbf{w}^{(t+1)} = P_{\mathcal{C}}[\mathbf{w}^{(t)} - \gamma \nabla \mathcal{L}(\mathbf{w}^{(t)})]$$
- Use penalty functions
  - $\min \mathcal{L}(\mathbf{w}) + I_{\mathcal{C}}, I_{\mathcal{C}} = 0$ if $\mathbf{w} \in \mathcal{C}$, ow $+\infty$
  - $\min \mathcal{L}(\mathbf{w}) + \lambda |\mathbf{A}\mathbf{w} - \mathbf{b}|$
- Stopping criteria when $\mathcal{L}(\mathbf{w})$ close to 0

4.8 Complexities for MSE/MAE per iteration

- GD=$\mathcal{O}(ND)$
- MB-GD=$\mathcal{O}(BD)$
- SGD=$\mathcal{O}(D)$

5 Least Squares

- Use the first optimality conditions:
  $$\boldsymbol{\nabla} L(\mathbf{w}^*) = 0 \Rightarrow \mathbf{X}^T \mathbf{e} = \mathbf{X}^T(\mathbf{y} - \mathbf{X}\mathbf{w}) = 0$$
- When $\mathbf{X}^T \mathbf{X}$ is invertible, we have the closed-form expression
  $$\mathbf{w}^* = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}$$
- thus we can predict values for a new $\mathbf{x}_m$
  $$\mathbf{y}_m := \mathbf{x}_\mathbf{m}^\mathbf{T} \mathbf{w}^* = \mathbf{x}_\mathbf{m}^\mathbf{T} (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}$$
- The **Gram matrix** $\mathbf{X}^T \mathbf{X}$ is pd and is also invertible iff $\mathbf{X}$ has full column rank.
- *Complexity*: $O(ND^2 + D^3) \equiv O(ND^2)$
- $\mathbf{X}$ can be rank deficient when $D > N$ or when the comlumns $\bar{\mathbf{x}}_d$ are nearly collinear. $\Rightarrow$ matrix is ill-conditioned.
- Can still solve using a linear system solver using normal equations:
  $$\mathbf{X}^\top \mathbf{X} \mathbf{w} = \mathbf{X}^\top \mathbf{y}$$

6 Maximum Likelihood (MLE)

- Let define the noise $\epsilon_n \sim \mathcal{N}(0, \sigma^2)$.
  $$\rightarrow \mathbf{y}_n = \mathbf{x}_n^T \mathbf{w} + \epsilon_n$$
- Another way of expressing this:
  $$p(\mathbf{y}|\mathbf{X}, \mathbf{w}) = \prod_{n=1}^{N} p(\mathbf{y}_n|\mathbf{x}_n, \mathbf{w}) = \prod_{n=1}^{N} \mathcal{N}(\mathbf{y}_n|\mathbf{x}_n^T \mathbf{w}, \sigma^2)$$
  which defines the likelihood of observing $\mathbf{y}$ given $\mathbf{X}$ and $\boldsymbol{w}$
- Define cost with log-likelihood
  $$\mathcal{L}_{MLE}(\boldsymbol{w}) = \log p(\mathbf{y}|\mathbf{X}, \mathbf{w}) = -\frac{1}{2\sigma^2} \sum_{n=1}^{N} (\mathbf{y}_n - \mathbf{x}_n^T \mathbf{w})^2 + cnst$$
- Maximum likelihood estimator (MLE) gives another way to design cost functions
  $$\operatorname*{argmin}_{\mathbf{w}} \mathcal{L}_{MSE}(\mathbf{w}) = \operatorname*{argmax}_{\mathbf{w}} \mathcal{L}_{MLE}(\mathbf{w})$$
- MLE can also be interpreted as finding the model under which the observed data is most likely to have been generated from.
- $\mathbf{w}_{\text{MLE}} \rightarrow \mathbf{w}_{\text{true}}$ for large amount of data

7 Ridge Regression and LASSO

- Add **regularization term**
  $$\min_{\mathbf{w}} \mathcal{L}(\mathbf{w}) + \Omega(\mathbf{w})$$
- This corresponds to MAP estimate with prior on weights.
- L_2-Reg. (Ridge): $\Omega(\mathbf{w}) = \lambda \|\mathbf{w}\|_2^2$
- $\rightarrow$ small values of $\mathbf{w}_i$, not sparse
- $\rightarrow \mathbf{w}^\star = (\mathbf{X}^T \mathbf{X} + \lambda' \mathbf{I})^{-1} \mathbf{X}^T \mathbf{y}$ with $\lambda' = 2N\lambda$
- $\rightarrow (\mathbf{X}^T \mathbf{X} + \lambda' \mathbf{I})^{-1}$ exists (lifted eigenvalues)
- L_1-Reg. (Lasso): $\Omega(\mathbf{w}) = \lambda \|\mathbf{w}\|_1$
- $\rightarrow$ sparsity of weight vector
- $\rightarrow$ implicit model selection
- **Maximum-a-posteriori (MAP)**
- (i) Posterior prob. $\propto$ Likelihood $\times$ Prior prob
  $$p(\mathbf{y}|\mathbf{X}\mathbf{w}) = \prod^{N} \mathcal{N}(\mathbf{y}_n|\mathbf{x}_n^T \mathbf{w}, \sigma_n^2)$$
  $$p(\mathbf{w}) = \mathcal{N}(\mathbf{w}|0, \sigma_0^2 \mathbf{I}_D)$$
  $$\text{then} \rightarrow \mathbf{w}^\star = \operatorname*{argmax}_{\mathbf{w}} p(\mathbf{y}|\mathbf{X}\mathbf{w}) \cdot p(\mathbf{w})$$
  $$\mathbf{w}^\star = \operatorname*{argmin}_{\mathbf{w}} \sum^{N} \frac{1}{2\sigma_n^2} (\mathbf{y}_n - \mathbf{x}^T \mathbf{w})^2 + \frac{1}{2\sigma_0^2} \|\mathbf{w}\|^2$$

8 Bias-Variance decomposition

- **Simple** (e.g. large λ) $\rightarrow$ large bias but low variance
- **Complex** (e.g. small λ) $\rightarrow$ low bias but large variance
- The expected squared loss between true model and learned model is a sum of three non-negative terms:
  $\mathbb{E}_S[(f(x) + \epsilon - f_S(x))^2] = Var[\epsilon] + \text{bias} + \text{variance}$:
  - **Bias** $= (f(x) - \mathbb{E}_{S'}[f_{S'}(x)])^2$: Difference between actual value and expected prediction.
  - **Variance** $= \mathbb{E}_S[(\mathbb{E}_{S'}[f_{S'}(x)] - f_S(x))^2]$: variance of predictions between training sets.
- All terms are lower bounds for the error.
- Cannot do better than $Var[\epsilon]$.

9 Logistic Regression

- **Classification** relates input variables $\mathbf{x}$ to discrete output variable $\mathbf{y}$
- **Binary classifier**: we use $y = 0$ for $\mathbf{C}_1$ and $\mathbf{y} = 1$ for $\mathbf{C}_2$.
- Can use least-squares to predict $\hat{y}_*$
  $$\hat{y} = \begin{cases} \mathbf{C}_1 & \hat{y}_* < 0.5 \\ \mathbf{C}_2 & \hat{y}_* \geq 0.5 \end{cases}$$
- **Logistic function**
  $$\sigma(x) = \frac{\exp(x)}{1 + \exp(x)}$$
  $$p(\mathbf{y}_n = \mathbf{C}_1|\mathbf{x}_n) = \sigma(\mathbf{x}^T \mathbf{w})$$
  $$p(\mathbf{y}_n = \mathbf{C}_2|\mathbf{x}_n) = 1 - \sigma(\mathbf{x}^T \mathbf{w})$$
- The probabilistic model:
  $$p(\mathbf{y}|\mathbf{X}, \mathbf{w}) = \prod_{n=1}^{N} \sigma(\mathbf{x}_n^T \mathbf{w})^{\mathbf{y}_n} (1 - \sigma(\mathbf{x}_n^T \mathbf{w}))^{1 - \mathbf{y}_n}$$
- The negative log-likelihood (w.r.t. MLE):
  $$\mathcal{L}(\mathbf{w}) = -\sum_{n=1}^{N} \mathbf{y}_n \ln \sigma(\mathbf{x}_n^T \mathbf{w}) + (1 - \mathbf{y}_n) \ln(1 - \sigma(\mathbf{x}_n^T \mathbf{w}))$$
  $$= \sum_{n=1}^{N} \ln[1 + \exp(\mathbf{x}_n^T \mathbf{w})] - \mathbf{y}_n \mathbf{x}_n^T \mathbf{w}$$
- We can use the fact that
  $$\frac{d}{dz} \ln(1 + \exp(z)) = \sigma(z)$$
- Gradient of the log-likelihood
  $$\mathbf{g} = \boldsymbol{\nabla} \mathcal{L}(\mathbf{w}) = \sum_{n=1}^{N} \mathbf{x}_n (\sigma(\mathbf{x}_n^T \mathbf{w}) - \mathbf{y}_n) = \mathbf{X}^T [\sigma(\mathbf{X}\mathbf{w}) - \mathbf{y}]$$
- The neg. log-likelihood $-\mathcal{L}_{mle}(\boldsymbol{w})$ is convex
- **Hessian** of the neg. log-likelihood
  - We know that
    $$\frac{d\sigma(t)}{dt} = \sigma(t)(1 - \sigma(t))$$
- Hessian is the derivative of the gradient
  $$\mathbf{H}(\mathbf{w}) = \frac{d\mathbf{g}(\mathbf{w})}{d\mathbf{w}^T} = \sum_{n=1}^{N} \frac{d}{d\mathbf{w}^T} \mathbf{x}_n \sigma(\mathbf{x}_n^T \mathbf{w}) = \sum_{n=1}^{N} \mathbf{x}_n \mathbf{x}_n^T \sigma(\mathbf{x}_n^T \mathbf{w})(1 - \sigma(\mathbf{x}_n^T \mathbf{w})) = \tilde{\mathbf{X}}^T \mathbf{S} \tilde{\mathbf{X}}$$
  where $\mathbf{S}$ is a $N \times N$ diagonal matrix with diagonals
  $$S_{nn} = \sigma(\mathbf{x}_n^T \mathbf{w})(1 - \sigma(\mathbf{x}_n^T \mathbf{w}))$$
- The neg. log-likelihood is not strictly convex. ????
- **Newton's Method**
  - Uses second-order information and takes steps in the direction that minimizes a quadratic approximation (Taylor)
    $$\mathcal{L}(\mathbf{w}) = \mathcal{L}(\mathbf{w}^{(k)}) + \nabla \mathcal{L}_k^T (\mathbf{w} - \mathbf{w}^{(k)}) + (\mathbf{w} - \mathbf{w}^{(k)})^T \mathbf{H}_k (\mathbf{w} - \mathbf{w}^{(k)})$$
    and it's minimum is at
    $$\mathbf{w}^{k+1} = \mathbf{w}^{(k)} - \gamma_k \mathbf{H}_k^{-1} \nabla \mathcal{L}_k$$
  - Complexity: $O((ND^2 + D^3)I)$
- **Regularized Logistic Regression**
  - If data is linearly separable, there is no best weight vector $\Rightarrow$ optimisation does not stop.
  - $\rightarrow$ use penalty term.
  $$\operatorname*{argmin}_{\mathbf{w}} - \sum_{n=1}^{N} \ln p(\mathbf{y}_n|\mathbf{x}_n^T \mathbf{w}) + \frac{\lambda}{2} \|\mathbf{w}\|^2$$

10 Exponential family distribution & Generalized Linear Model

- Exponential family distribution
  $$p(\mathbf{y}|\boldsymbol{\eta}) = h(y) \exp(\boldsymbol{\eta}^T \boldsymbol{\phi}(\mathbf{y}) - A(\boldsymbol{\eta}))$$
- For proper normalisation ($\int p = 1$):
  $$A(\boldsymbol{\eta}) = \ln[\int_y h(y) \exp(\boldsymbol{\eta}^T \boldsymbol{\phi}(\mathbf{y}))]$$
- **Bernoulli** distribution example
  $$\rightarrow \exp(\log(\frac{\mu}{1-\mu})y + \log(1 - \mu)))$$
  (i) there is a relationship between η and μ through the **link function**
  $$\eta = \log(\frac{\mu}{1-\mu}) \leftrightarrow \mu = \frac{e^\eta}{1 + e^\eta}$$
  (ii) Note that μ is the mean parameter of y
  (iii) Relationship between the mean $\boldsymbol{\mu}$ and $\boldsymbol{\eta}$ is defined using a link function g
  $$\boldsymbol{\eta} = \mathbf{g}(\boldsymbol{\mu}) \Leftrightarrow \boldsymbol{\mu} = \mathbf{g}^{-1}(\boldsymbol{\eta})$$
- **Gaussian** distribution example
  $$\exp((\frac{\mu}{\sigma^2}, \frac{-1}{2\sigma^2})(y, y^2)^T - \frac{\mu^2}{2\sigma^2} - \frac{1}{2}\ln(2\pi\sigma^2))$$
  (i) link function
  $$\eta = (\eta_1 = \mu/\sigma^2, \eta_2 = -1/(2\sigma^2))^T$$
  $$\mu = -\eta_1/(2\eta_2) \; ; \; \sigma^2 = -1/(2\eta_2)$$
- First and second derivatives of $A(\eta)$ are related to the mean and the variance
  $$\frac{dA(\eta)}{d\eta} = \mathbb{E}[\boldsymbol{\phi}(\eta)], \quad \frac{d^2 A(\eta)}{d\eta^2} = \operatorname{Var}[\boldsymbol{\phi}(\eta)]$$
- $A(\eta)$ is convex
- The generalized maximum likelihood cost to minimize is
  $$\min_{\mathbf{w}} \mathcal{L}(\mathbf{w}) = -\sum_{n=1}^{N} \log(p(\mathbf{y}_n|\mathbf{x}_n^T \mathbf{w}))$$
  where $p(\mathbf{y}_n|\mathbf{x}_n^T \mathbf{w})$ is an exponential family distribution
- We obtain the solution
  $$\frac{d\mathcal{L}}{d\mathbf{w}} = \mathbf{X}^T [\mathbf{g}^{-1}(\mathbf{X}\mathbf{w}) - \boldsymbol{\phi}(\mathbf{y})]$$

11 k-Nearest Neighbor (k-NN)

- Performs best in low dimensions.
- Assumes close points have similar values
- The k-NN regressor:
$$f(\mathbf{x}) = \frac{1}{k}\sum_{\mathbf{x}_n \in nbh_k(\mathbf{x})} \mathbf{y}_n$$
- The k-NN classifier:
$$f(\mathbf{x}) = modus x_n | \mathbf{x}_n \in nbh_k(\mathbf{x})$$
- Large k → smoothing over large area
- Small k → averaging over small area
- **Curse of dimensionality**:
  a) As dimensionality grows fixed-size training set covers dwindling fraction of input space ⇒ If we want to consider fixed fraction α of points and increase dimension, we need to explore almost whole range in each dimension.
  b) In high dimensions, points are far from each other ⇒ choice of NN becomes essentially random. Need radius
  $$r = \sqrt[d]{(1 - \frac{1}{\sqrt[N]{2}})}$$
  to have at least one data point in r^d rectangle with $p \geq \frac{1}{2}$.
- **NN performance**:
  - Optimal classifier: $f_*(x) = \mathbb{1}\mathbb{P}[y = 1|x] > \frac{1}{2}$
  - $\mathbb{E}_S[L(f_S)] \leq 2L(f_*) + 4c\sqrt{d}N^{\frac{-1}{1+d}}$

12 Support Vector Machine

- Assume $y_n \in \{-1, 1\}$
- SVM optimizes the following cost
$$\mathcal{L}(\mathbf{w}) = \min_{\mathbf{w}} \sum_{n=1}^{N} [1 - \mathbf{y}_n x_n^T \mathbf{w}]_+ + \frac{\lambda}{2}\|\mathbf{w}\|^2$$
- Can be optimised using subgradient descent.
- **Case: Linear separability:** We get a seperating hyperplane, no point in the margin and w, s.t margin is maximised ($2/\|w\|$).
- This is called hard-margin compared to soft-margin formulation.
- **Duality**:
  - Hard to minimize $g(\mathbf{w})$ so we define
  $$\mathcal{L}(\mathbf{w}) = \max_{\boldsymbol{\alpha}} G(\mathbf{w}, \boldsymbol{\alpha})$$
  - we use the property that
  $$[\mathbf{v}_n]_+ = \max(0, \mathbf{v}_n) = \max_{\alpha_n \in [0,1]} \alpha_n \mathbf{v}_n$$
  - We can rewrite the problem as
  $$\min_{\mathbf{w}} \max_{\alpha} \sum_{n=1}^{N} \alpha_n (1 - \mathbf{y}_n \boldsymbol{\phi}_n^T \mathbf{w}) + \frac{\lambda}{2}\|\mathbf{w}\|_2^2$$
  - This is differentiable, convex in $\boldsymbol{w}$ and concave in $\boldsymbol{\alpha}$
  - **Minimax theorem**:
  $$\min_{\mathbf{w}} \max_{\boldsymbol{\alpha}} G(\mathbf{w}, \boldsymbol{\alpha}) = \max_{\boldsymbol{\alpha}} \min_{\mathbf{w}} G(\mathbf{w}, \boldsymbol{\alpha})$$
  because G is convex in $\mathbf{w}$ and concave in $\boldsymbol{\alpha}$.
  - Derivative w.r.t. $\mathbf{w}$:
  $$\nabla_{\mathbf{w}} G(\mathbf{w}, \boldsymbol{\alpha}) = -\sum_{n=1}^{N} \alpha_n \mathbf{y}_n \mathbf{x}_n + \lambda \mathbf{w}$$
  - Equating this to 0, we get:
  $$\mathbf{w}(\boldsymbol{\alpha}) = \frac{1}{\lambda}\sum_{n=1}^{N} \alpha_n \mathbf{y}_n \mathbf{x}_n = \frac{1}{\lambda}\mathbf{X}^T \mathbf{Y}\boldsymbol{\alpha}$$
  $$\mathbf{Y} := \text{diag}(\boldsymbol{y})$$
  - Plugging $\mathbf{w}^*$ back in the dual problem
  $$\max_{\boldsymbol{\alpha} \in [0,1]^N} \boldsymbol{\alpha}^T \mathbf{1} - \frac{1}{2\lambda}\boldsymbol{\alpha}^T \mathbf{Y}\mathbf{X}\mathbf{X}^T \mathbf{Y}\boldsymbol{\alpha}$$
  - Data only enters as $\mathbf{K} = \mathbf{X}^T \boldsymbol{X}$.
- **Non support vector**: Example that lies on the correct side, outside margin $\boldsymbol{\alpha}_n = 0$
- **Essen. support vector**: Example that lies on the margin $\boldsymbol{\alpha}_n \in (0, 1)$
- **Bound support vector**: Example that lies strictly inside the margin or wrong side $\boldsymbol{\alpha}_n = 1$
- Use Coordinates Descent to find $\boldsymbol{\alpha}$. Update one coordinate (argmin) at the time and others constant.

13 Kernel Ridge Regression

- The following is true for ridge regression
$$\mathbf{w}^* = (\mathbf{X}^T\mathbf{X} + \lambda\mathbf{I}_D)^{-1}\mathbf{X}^T\mathbf{y} \ , (1)$$
$$= \mathbf{X}^T(\mathbf{X}\mathbf{X}^T + \lambda\mathbf{I}_N)^{-1}\mathbf{y} = \mathbf{X}^T\boldsymbol{\alpha}^* \ , (2)$$
- Complexity of computing $\mathbf{w}$: (1) $O(D^2N + D^3)$, (2) $O(DN^2 + N^3)$
- Thus we have $\mathbf{w}^* = \mathbf{X}^T\boldsymbol{\alpha}^*$, with $\mathbf{w}^* \in \mathbb{R}^D$ and $\boldsymbol{\alpha}^* \in \mathbb{R}^N$
- The representer theorem allows us to write an equivalent optimization problem in terms of $\boldsymbol{\alpha}$.
$$\boldsymbol{\alpha} = \underset{\boldsymbol{\alpha}}{\text{argmax}} \left(-\frac{1}{2}\boldsymbol{\alpha}^T(\mathbf{X}^T\mathbf{X} + \lambda\mathbf{I}_N)\boldsymbol{\alpha} + \boldsymbol{\alpha}^T\mathbf{y}\right)$$
- $\mathbf{K} = \mathbf{X}\mathbf{X}^T$ is called the **kernel matrix** or **Gram matrix**.
- If $\mathbf{K}$ is positive definite and symmetric, then it's called a **Mercer Kernel**.
- $\mathbf{K}_{i,j} = k(\mathbf{x}_i, \mathbf{x}_j)$
- If the kernel is Mercer, then there exists a function $\boldsymbol{\phi}(\mathbf{x})$ s.t.
$$k(\mathbf{x}, \mathbf{x}') = \boldsymbol{\phi}(\mathbf{x})^T\boldsymbol{\phi}(\mathbf{x}')$$
- **Kernel trick**:
  - compute dot-product in $\mathbb{R}^m$ while remaining in $\mathbb{R}^n$
  - Replace $\langle\mathbf{x}, \mathbf{x}'\rangle$ with $k(\mathbf{x}, \mathbf{x}')$.
- **Common Kernel**
  - $x \in \mathbb{R}, k(\mathbf{x}, \mathbf{x}') = (xx')^2 \Rightarrow \phi(x) = x^2$
  - Radial Basis function kernel (RBF)
  $$k(\mathbf{x}, \mathbf{x}') = \exp(-\frac{1}{2}(\mathbf{x} - \mathbf{x}')^T(\mathbf{x} - \mathbf{x}'))$$
- Thus we get
$$\mathbf{y} = \mathbf{w}^T\mathbf{x} = \sum_{i=1}^{K} \alpha_i \mathbf{x}_i^T\mathbf{x} = \sum_{i=1}^{K} \alpha_i k(\mathbf{x}, \mathbf{x}_i)$$

14 Unsupervised

Learn pattern without labels.

- **word2vec**: map every word to a vector $w_i \in \mathbb{R}^K$, K large, that captures its semantics.
- **Topic model**: Documents consist of collections of topics
  - topic = probability distribution over words
  - use clustering to pick out respresentative topics

15 K-means

$$\min_{\mathbf{z}, \boldsymbol{\mu}} \mathcal{L}(\mathbf{z}, \boldsymbol{\mu}) = \sum_{k=1}^{K}\sum_{n=1}^{N} z_{nk}||\mathbf{x}_n - \boldsymbol{\mu}_k||_2^2$$

such that $z_{nk} \in \{0, 1\}$ and $\sum_{k=1}^{K} z_{nk} = 1$

- K-means algorithm (Coordinate Descent): Initialize $\boldsymbol{\mu}_k$, then iterate
  1. For all n, compute $\mathbf{z}_n$ given $\boldsymbol{\mu}$
  $$z_{nk} = \begin{cases} 1 & \text{if } k = \text{argmin}_j ||\mathbf{x}_n - \boldsymbol{\mu}||_2^2 \\ 0 & \text{otherwise} \end{cases}$$
  2. For all k, compute μ_k given $\mathbf{z}$
  $$\boldsymbol{\mu}_k = \frac{\sum_{n=1}^{N} z_{nk}\mathbf{x}_n}{\sum_{n=1}^{N} z_{nk}}$$
- A good initialization procedure is to choose the prototypes to be equal to a random subset of K data points.
- Probabilistic model
$$p(\mathbf{z}, \boldsymbol{\mu}) = \prod_{n=1}^{N}\prod_{k=1}^{K} [\mathcal{N}(\mathbf{x}_n|\boldsymbol{\mu}_k, \mathbf{I})]^{z_{nk}}$$
$$-\log p(\mathbf{x}_n|\mu, z) = \sum_{n=1}^{N}\sum_{k=1}^{K} \frac{1}{2}\|\mathbf{x}_n - \mu_k\|^2\mathbf{z}_{nk} + c'$$
- K-means as a Matrix Factorization
$$\min_{\mathbf{z}, \boldsymbol{\mu}} \mathcal{L}(\mathbf{z}, \boldsymbol{\mu}) = ||\mathbf{X} - \mathbf{M}\mathbf{Z}^T||^2_{\text{Frob}}$$
- Computation can be heavy, each example can belong to only on cluster and clusters have to be spherical.

16 Gaussian Mixture Models

- Clusters can be elliptical using a full covariance matrix instead of isotropic covariance.
$$p(\mathbf{X}|\boldsymbol{\mu}, \boldsymbol{\Sigma}, \mathbf{z}) = \prod_{n=1}^{N}\prod_{k=1}^{K} [\mathcal{N}(\mathbf{x}_n|\boldsymbol{\mu}_k, \Sigma_k)]^{z_{nk}}$$
- **Soft-clustering**: Points can belong to several cluster by defining z_n to be a random variable.
$$p(z_n = k) = \pi_k \text{ where } \pi_k > 0, \forall k, \sum_{k=1}^{K} \pi_k = 1$$
- Joint distribution of Gaussian mixture model
$$p(\mathbf{X}, \mathbf{z}|\boldsymbol{\mu}, \boldsymbol{\Sigma}, \boldsymbol{\pi}) = \prod_{n=1}^{N} p(\mathbf{x}_n|\mathbf{r}_n, \boldsymbol{\mu}, \boldsymbol{\Sigma})p(\mathbf{z}_n|\boldsymbol{\pi})$$
$$= \prod_{n=1}^{N}\prod_{k=1}^{K} [(\mathcal{N}(\mathbf{x}_n|\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k))^{z_{nk}}] \prod_{k=1}^{K} [\pi_k]^{z_{nk}}$$
- z_n are called *latent* unobserved variables
- Unknown parameters are given by $\boldsymbol{\theta} = \{\boldsymbol{\mu}, \boldsymbol{\Sigma}, \boldsymbol{\pi}\}$
- We get the **marginal likelihood** by marginalizing z_n out from the likelihood
$$p(\mathbf{x}_n|\boldsymbol{\theta}) = \sum_{k=1}^{K} p(\mathbf{x}_n, z_n = k|\boldsymbol{\theta})$$
$$= \sum_{k=1}^{K} p(z_n = k|\boldsymbol{\theta})p(\mathbf{x}_n|z_n = k, \boldsymbol{\theta})$$
$$= \sum_{k=1}^{K} \pi_k\mathcal{N}(\mathbf{x}_n|\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)$$
- Without a latent variable model, number of parameters grow at rate $O(N)$
- After marginalization, the growth is reduced to $O(D^2K)$
- To get maximum likelihood estimate of $\boldsymbol{\theta}$, we maximize
$$\max_{\boldsymbol{\theta}} \sum_{n=1}^{N} \log \sum_{k=1}^{K} \pi_k\mathcal{N}(\mathbf{x}_n|\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)$$

17 Expectation Maximization Algorithm

- *[ALGORITHM]* Start with $\boldsymbol{\theta}^{(1)}$ and iterate
  1. *Expectation step*: Compute a lower bound to the cost such that it is tight at the previous $\boldsymbol{\theta}^{(t)}$ with equality when,
  $$q_{kn} = \frac{\pi_k\mathcal{N}(\mathbf{x}_n|\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)}{\sum_{k=1}^{K} \pi_k\mathcal{N}(\mathbf{x}_n|\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)}$$
  2. *Maximization step*: Update $\boldsymbol{\theta}$
  $$\boldsymbol{\theta}^{(t+1)} = \underset{\boldsymbol{\theta}}{\text{argmax}} \mathcal{L}(\boldsymbol{\theta}, \boldsymbol{\theta}^{(t)})$$
  $$\boldsymbol{\mu}_k^{(t+1)} = \frac{\sum_{n=1}^{N} \gamma^{(i)}(r_{nk})\mathbf{x}_n}{\sum_{n=1}^{N} q_{kn}^{(t)}}$$
  $$\boldsymbol{\Sigma}_k^{(t+1)} = \frac{\sum_{n=1}^{N} q_{kn}^{(t)}(\mathbf{x}_n - \boldsymbol{\mu}_k^{(t+1)})(\mathbf{x}_n - \boldsymbol{\mu}_k^{(t+1)})^T}{\sum_{n=1}^{N} q_{kn}^{(t)}}$$
  $$\pi_k^{(t+1)} = \frac{1}{N}\sum_{n=1}^{N} q_{kn}^{(t)}$$
- If covariance is diagonal → K-means.
- $q_{nk}^{(t)} = p(z_n = k|x_n, \theta^{(t)})$ posterior of z_n

18 Matrix factorization

- Find $\mathbf{X} \approx \mathbf{W}\mathbf{Z}^\top$
  - $\mathbf{X}$ is $D \times N$ (e.g movies × user)
  - $\mathbf{Z}$ a $N \times K$, $\mathbf{W}$ a $D \times K$ matrix
  $$\mathcal{L}(\mathbf{W}, \mathbf{Z}) = \frac{1}{2}\sum_{(d,n)\in\Omega} [x_{dn} - (\mathbf{W}\mathbf{Z}^T)_{dn}]^2 + \frac{\lambda_w}{2}\|\mathbf{W}\|^2_{\text{Frob}} + \frac{\lambda_z}{2}\|\mathbf{Z}\|^2_{\text{Frob}}$$
- **SGD**: For one fixed element (d, n) we derive entry (d', k) of $\mathbf{W}$ (if $d = d'$ oth. 0):
$$\frac{\partial}{\partial w_{d',k}} f_{d,n}(\mathbf{W}, \mathbf{Z}) = -[x_{dn} - (\mathbf{W}\mathbf{Z}^T)_{dn}]z_{nk}$$
And of $\mathbf{Z}$ (if $n = n'$ oth. 0):
$$\frac{\partial}{\partial z_{n',k}} f_{d,n}(\mathbf{W}, \mathbf{Z}) = -[x_{dn} - (\mathbf{W}\mathbf{Z}^T)_{dn}]w_{nk}$$
updates:
$$\mathbf{W}^{t+1} = \mathbf{W}^t - \gamma\nabla_w f_{d,n}(\mathbf{W}^t, \mathbf{Z}^t)$$
$$\mathbf{Z}^{t+1} = \mathbf{W}^t - \gamma\nabla_z f_{d,n}(\mathbf{W}^t, \mathbf{Z}^t)$$
- We can use coordinate descent algorithm, by first minimizing w.r.t. $\mathbf{Z}$ given $\mathbf{W}$ and then minimizing $\mathbf{W}$ given $\mathbf{Z}$. This is called **Alternating least-squares (ALS)**:
$$\mathbf{Z}^T \leftarrow (\mathbf{W}^T\mathbf{W} + \lambda_z\mathbf{I}_K)^{-1}\mathbf{W}^T\mathbf{X}$$
$$\mathbf{W}^T \leftarrow (\mathbf{Z}^T\mathbf{Z} + \lambda_w\mathbf{I}_K)^{-1}\mathbf{Z}^T\mathbf{X}^T$$
- *Complexity*: $O(DNK^2 + NK^3) \to O(DNK^2)$???

19 Text Representation

20 Singular Value Decomposition

- Matrix factorization method
$$\mathbf{X} = \mathbf{U}\mathbf{S}\mathbf{V}^T$$
  - $\mathbf{U}$ orthonormal $D \times D$, $\mathbf{V}$ orthonormal $N \times N$
  - $\mathbf{S}$ contains (non-negative) singular values in diagonal in descending order: $D \times N$
  - Columns of $\mathbf{U}$ and $\mathbf{V}$ are the left and right **singular vectors**.
- **Truncated SVD**: Take the matrix $\mathbf{S}^{(K)}$ with the K first diagonal elements non zero. Then, best rank-K approx:
$$\mathbf{X} \approx \mathbf{X}_K = \mathbf{U}\mathbf{S}^{(K)}\mathbf{V}^T$$

21 Principal Component Analysis

- dimensionality reduction and decorrelation $\|\mathbf{X} - \hat{\mathbf{X}}\|_F^2 \geq \|\mathbf{X} - \mathbf{U}_k\mathbf{U}_k^\top\mathbf{X}\|_F^2 = \sum_{i>K} s_i^2$
- If the data has zero mean
$$\boldsymbol{\Sigma} = \frac{1}{N}\mathbf{X}\mathbf{X}^T \Rightarrow \mathbf{X}\mathbf{X}^T = \mathbf{U}\mathbf{S}^2\mathbf{U}^T$$
$$\Rightarrow \mathbf{U}^T\mathbf{X}\mathbf{X}^T\mathbf{U} = \mathbf{U}^T\mathbf{U}\mathbf{S}^2\mathbf{U}^T\mathbf{U} = \mathbf{S}^2$$
- Thus the columns of matrix $\mathbf{U}$ are called the **principal components** and they decorrelate the covariance matrix.
- Not invariant under scalings → normalize $\mathbf{X}$
- Can compute U and S efficiently via $EVD(\mathbf{X}\mathbf{X}^\top)$ or $EVD(\mathbf{X}^\top\mathbf{X})$

22 Neural Net

- $x_j^{(l)} = \phi\left(\sum_i w_{i,j}^{(l)} x_i^{(l-1)} + b_j^{(l)}\right)$.
- NN with one hidden layer and sigmoid-like activation function can approximate any sufficiently smooth function on a bounded domain in average ($\leq \frac{(2Cr)^2}{n}$) and point-wise
- Cost function:
$$\mathcal{L} = \frac{1}{N}\sum_{n=1}^{N}\left(y_n - f^{(L+1)} \circ \ldots \circ f^{(1)}(\boldsymbol{x}_n^{(0)})\right)^2$$
We can use SGD to minimize the cost function.

22.1 Backpropagation Algorithm

- *Forward pass*: Compute $\boldsymbol{z}^{(l)} = \left(\boldsymbol{W}^{(l)}\right)^T\boldsymbol{x}^{(l-1)} + \boldsymbol{b}^{(l)}$ with $\boldsymbol{x}^{(0)} = \boldsymbol{x}_n$ and $\boldsymbol{x}^{(l)} = \phi(\boldsymbol{z}^{(l)})$.
- *Backward pass*: Set $\delta^{(L+1)} = -2(y_n - \boldsymbol{x}^{(L+1)})\phi'(z^{(L+1)})$ (if squared loss). Then compute
$$\delta_j^{(l)} = \frac{\partial\mathcal{L}_n}{\partial z_j^{(l)}} = \sum_k \frac{\partial\mathcal{L}_n}{\partial z_k^{(l+1)}}\frac{\partial z_k^{(l+1)}}{\partial z_j^{(l)}} = \sum_k \delta_k^{(l+1)}\boldsymbol{W}_{j,k}^{(l+1)}\phi'(z_j^{(l)})$$
- *Final Computation*:
$$\frac{\partial\mathcal{L}_n}{\partial w_{i,j}^{(l)}} = \sum_k \frac{\partial\mathcal{L}_n}{\partial z_k^{(l)}}\frac{\partial z_k^{(l)}}{\partial w_{i,j}^{(l)}} = \frac{\partial\mathcal{L}_n}{\partial z_j^{(l)}}\frac{\partial z_j^{(l)}}{\partial w_{i,j}^{(l)}} = \delta_j^{(l)}\boldsymbol{x}_i^{(l-1)}$$
$$\frac{\partial\mathcal{L}_n}{\partial b_j^{(l)}} = \sum_k \frac{\partial\mathcal{L}_n}{\partial z_k^{(l)}}\frac{\partial z_k^{(l)}}{\partial b_j^{(l)}} = \frac{\partial\mathcal{L}_n}{\partial z_j^{(l)}}\frac{\partial z_j^{(l)}}{\partial b_j^{(l)}} = \delta_j^{(l)} \cdot 1 = \delta_j^{(l)}$$

22.2 Activation Functions

Sigmoid $\phi(x) = \frac{1}{1+e^{-x}}$ Positive, bounded.
$\phi'(x) \simeq 0$ for large $|x|$ ⇒ Learning slow.

Tanh $\tanh(x) = \frac{e^x - e^{-x}}{e^x + e^{-x}} = \phi(2x) - 1/2$.
Balanced, bounded. Learning slow too.

ReLU $(x)_+ = \max 0, x$ Positive, unbounded. Derivate = 1 if $x > 0$, 0 if $x < 0$

Leaky ReLU $f(x) = \max \alpha x, x$ Remove 0 derivative.

Maxout $f(x) = max\boldsymbol{x}^T\boldsymbol{w}_1 + b_1, \ldots, \boldsymbol{x}^T\boldsymbol{w}_k + b_k$ (Generalization of ReLU)

22.3 Convolutional NN

Sparse connections and *weights sharing*: reduce complexity. (e.g. pixels in pictures only depend on neighbours)

22.4 Reg, Data Augmentation and Dropout

- Regularization term: $\frac{1}{2}\sum_{l=1}^{L+1}\mu^{(l)}||W^{(l)}||_F^2$
- Weight decay is $\Theta[t](1 - \eta\mu)$ in:
$$\Theta[t+1] = \Theta[t] + \eta(\nabla\mathcal{L} + \mu\Theta[t])$$
- Data Augm.: e.g. shift or rotation of pics
- Dropout: avoid overfit. Drop nodes randomly. (Then average multiple drop-NN or divide by dropout rate.)

23 Bayes Net

- Graph example: $p(x, y, z) = p(y|x)p(z|x)p(x)$: $(y \leftarrow x \rightarrow z)$
- **D-Separation** X and Y are D-separated by Z if every path from $x \in X$ to $y \in Y$ is blocked by Z. (→ independent)
- **Blocked Path** contains a variable that
  - is in Z and is **head-to-tail** or **tail-to-tail**
  - the node is **head-to-head** and neither the node nor any of its descendants are in Z.
- **Markov Blanket** (which blocks node A from the rest of the net) contains:
  - parents of A
  - children of A
  - parents of children of A