

/home/aryalohia/CMR /24a/driverless/driverless _ws/src/point_to_pixel/src /coloring/coloring.cpp

/home/aryalohia/CMR
/24a/driverless/driverless
_ws/src/point_to_pixel/src
/ros_node/point_to_pixel_node.hpp

/home/aryalohia/CMR /24a/driverless/driverless _ws/src/point_to_pixel/src /ros_node/point_to_pixel_node.cpp