

# Second model

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## Geometry

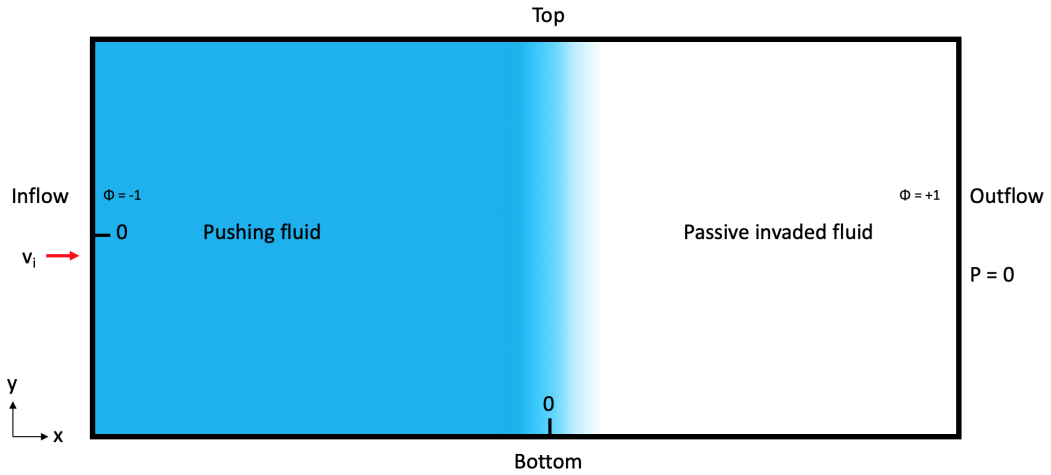


Figure 1: Geometry of the system

## Simplifications

In this first model, we set  $k = 0$  and  $\alpha = 0$ . The 'growth' of the fluid is due to an inflow on the left of the space.

## Equations

$$\begin{aligned}\vec{\nabla} p + \phi \vec{\nabla} \mu &= -\beta \theta_c(\phi) \vec{v} \\ \vec{\nabla} \cdot \vec{v} &= 0 \\ \frac{\partial \phi}{\partial t} + (\vec{v} \cdot \vec{\nabla}) \phi &= M \nabla^2 \mu \\ \mu &= \frac{\kappa}{\xi^2} (\phi^3 - \phi) - \kappa \nabla^2 \phi\end{aligned}$$

## Parameters

- $\beta$  passive friction of the fluid on the left (pushing)
- $\theta(\phi) = \frac{1}{2}[(1 - \phi) + (1 + \phi)\theta]$  linear continuous dimensionless friction coefficient (linear from [1–3] but no justification)
- $\theta = \frac{\beta'}{\beta}$  friction ratio, has to be  $> 1$  (less viscous invading more viscous)
- $M$  is the mobility of the phase (here taken as a constant [2, 4], can be  $M(\phi) \sim 1 - \phi^2$  [1, 3])
- $\kappa$  is the mixing energy
- $\xi$  is the width of the interface

## Initial conditions

For the phase

$$\begin{aligned}\phi(\vec{r}, t = 0) &= \phi_0(x) = \tanh\left(\frac{x}{\sqrt{2}\xi}\right) \\ \mu(\vec{r}, t = 0) &= 0\end{aligned}$$

For the flow

$$\begin{aligned}\vec{v}(\vec{r}, t = 0) &= v_i \hat{x} \\ p(\vec{r}, t = 0) &= P_{in}\left(\frac{1}{2} - \frac{x}{L}\right) \quad (L \text{ length of the box})\end{aligned}$$

## Boundary conditions

For the phase

$$\begin{aligned}\vec{\nabla}\phi(\vec{r}, t) \cdot \vec{n} &= 0 \text{ on } \partial\Omega_{t/b} \\ \vec{\nabla}\mu(\vec{r}, t) \cdot \vec{n} &= 0 \text{ on } \partial\Omega_{t/b} \\ \phi &= -1 \text{ on } \partial\Omega_{left} \\ \phi &= +1 \text{ on } \partial\Omega_{right} \\ \mu &= 0 \text{ on } \partial\Omega_{left/right}\end{aligned}$$

For the flow

$$\begin{aligned}\vec{v}(\vec{r}, t) &= v_i \hat{x} \text{ on } \partial\Omega_{left} \\ p(\vec{r}, t) &= 0 \text{ on } \partial\Omega_{right} \\ \vec{v} \cdot \vec{n} &= 0 \text{ on } \partial\Omega_{top/bottom} \\ \vec{\nabla}p \cdot \vec{n} &= 0 \text{ on } \partial\Omega_{top/bottom}\end{aligned}$$

## Dimensionless

### New dimensionless parameters

- $l = \sqrt{\frac{\gamma}{\beta v_i}}$
- $\tau = \frac{l}{v_i}$
- $p^* = \beta l v_i$
- $\mu^* = \frac{\kappa}{\xi^2}$
- $\theta = \frac{\beta'}{\beta}$
- and we have  $\gamma = \frac{2\sqrt{2}}{3} \frac{\kappa}{\xi}$

### Dimensionless equations

For the flow

$$\vec{\nabla} p + \frac{\mu^*}{\beta l v_i} \phi \vec{\nabla} \mu = -\theta_c(\phi) \vec{v}$$
$$\vec{\nabla} \cdot \vec{v} = 0$$

For the phase

$$\frac{\partial \phi}{\partial t} + \vec{v} \cdot \vec{\nabla} \phi = \frac{M \mu^*}{l_v i} \nabla^2 \mu$$
$$\mu = \phi^3 - \phi - \frac{\xi^2}{l^2} \nabla^2 \phi$$

### Dimensionless numbers

#### Cahn number

We introduce the Cahn number [1, 2, 5, 6]  $K = \frac{\xi}{l}$

#### Capillary number [2, 5]

$$\frac{\mu^*}{\beta v_i l} = \frac{\kappa}{\xi^2 \beta v_i l} = \frac{3}{2\sqrt{2}} \frac{\gamma}{\xi \beta l v_i}$$

Capillary number  $Ca = \frac{viscous}{surf.tension}$

$$Ca = \frac{2\sqrt{2}}{3} \frac{\xi \beta l v_i}{\gamma} = \frac{2\sqrt{2}}{3} \frac{\xi}{l} \frac{\beta l^2 v_i}{\gamma}$$

We introduce the natural capillary number for a sharp interface [2]  $Ca^* = \frac{\beta l^2 v_i}{\gamma}$

$$Ca = \frac{2\sqrt{2}}{3} K Ca^*$$

With our choice of  $l$ , we notice that  $Ca^* = 1$  and then  $Ca = \frac{2\sqrt{2}}{3} K$

**Péclet number [1–3, 6, 7]**

$$\frac{M\mu^*}{lv_i} = \frac{M\kappa}{\xi^2} \frac{1}{lv_i}$$

- $D = \frac{M\kappa}{\xi^2}$  has the dimension of a diffusion coefficient for the phase
- Péclet number  $Pe = \frac{advection}{diffusion}$

$$Pe = \frac{v_i l}{D} = \frac{v_i l}{M\kappa/\xi^2}$$

**Dimensionless equations with dimensionless numbers**

For the flow

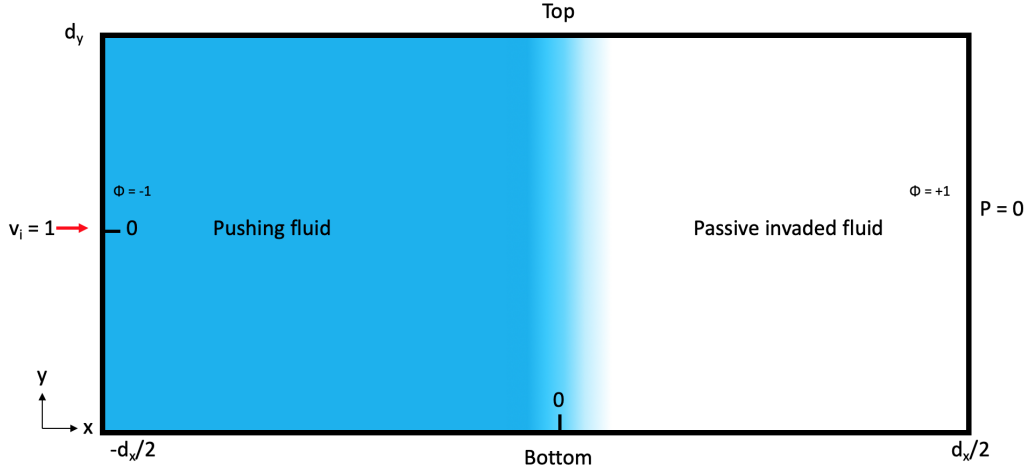
$$\begin{aligned} \vec{\nabla} p + \frac{1}{C_a} \phi \vec{\nabla} \mu &= -\theta(\phi) \vec{v} \\ \vec{\nabla} \cdot \vec{v} &= 0 \end{aligned}$$

For the phase

$$\begin{aligned} \frac{\partial \phi}{\partial t} + \vec{v} \cdot \vec{\nabla} \phi &= \frac{1}{Pe} \nabla^2 \mu \\ \mu &= \phi^3 - \phi - K^2 \nabla^2 \phi \end{aligned}$$

# Summary of the dimensionless problem

## Geometry



**Figure 2:** Geometry of the system

## Initial conditions

For the phase

$$\phi(\vec{r}, t = 0) = \phi_0(x) = \tanh\left(\frac{x}{\sqrt{2}K}\right)$$

$$\mu(\vec{r}, t = 0) = 0$$

For the flow

$$\vec{v}(\vec{r}, t = 0) = 1 \cdot \hat{x}$$

$$p(\vec{r}, t = 0) = \frac{d_x}{2} - x$$

## Boundary conditions

For the phase

$$\vec{\nabla}\phi(\vec{r}, t) \cdot \vec{n} = 0 \text{ on } \partial\Omega_{t/b}$$

$$\vec{\nabla}\mu(\vec{r}, t) \cdot \vec{n} = 0 \text{ on } \partial\Omega_{t/b}$$

$$\phi = -1 \text{ on } \partial\Omega_{left}$$

$$\phi = +1 \text{ on } \partial\Omega_{right}$$

$$\mu = 0 \text{ on } \partial\Omega_{left/right}$$

**For the flow**

$$\begin{aligned}\vec{v}(\vec{r}, t) &= 1 \cdot \hat{x} \text{ on } \partial\Omega_{left} \\ p(\vec{r}, t) &= 0 \text{ on } \partial\Omega_{right} \\ \vec{v} \cdot \vec{n} &= 0 \text{ on } \partial\Omega_{top/bottom} \\ \vec{\nabla} p \cdot \vec{n} &= 0 \text{ on } \partial\Omega_{top/bottom}\end{aligned}$$

## Dimensionless equations

$$\begin{aligned}\vec{\nabla} p + \frac{1}{Ca} \phi \vec{\nabla} \mu &= -\theta(\phi) \vec{v} \\ \vec{\nabla} \cdot \vec{v} &= 0 \\ \frac{\partial \phi}{\partial t} + \vec{v} \cdot \vec{\nabla} \phi &= \frac{1}{Pe} \nabla^2 \mu \\ \mu &= \phi^3 - \phi - K^2 \nabla^2 \phi\end{aligned}$$

## Numerical values

### Physics

#### Péclet number

In order to ensure 'instantaneous' local equilibrium/to converge like the sharp interface, we need  $\frac{1}{Pe}$  to be as small as possible [1, 2, 8]. Take  $Pe = O(1/K)$ .

#### Capillary number

$Ca = \frac{2\sqrt{2}}{3} K Ca^*$  with  $Ca^* = 1$  in our case (choice of  $l$ )

## Computing values

#### Mesh size element

Smallest mesh size element  $h = 0.1 - 0.2$  from [8], but we will try smaller ones in order to have a good resolution of the interface

#### Cahn number

From [2, 8, 9] we need  $0.5h \leq \xi/l \leq 2h$  Meaning  $K \sim 0.05 - 0.4$

#### Initial perturbation [2, 7]

We initiate the phase with a regular perturbation  $\phi(t=0) = th(\frac{x+\delta x}{\sqrt{2K}})$  with  $\delta x = h_0 \sin(ky)$  and  $\lambda = 2\pi/k$

- To fall into the linear phase, we need  $h_0/\lambda \ll 1$  (in practice,  $h_0/\lambda = 0.01 - 0.06$ )

- The wave disturbance must not see the interface width  $h_0/K \gg 1$  (in practice,  $h_0/K = 10 - 40$ )

This means that we have to change the value of  $\phi$  and  $\mu$  in the initial conditions.

- If  $|x| > a * h_0$ , we have  $\mu = 0$  and  $\phi = \tanh(\frac{x}{\sqrt{2K}})$
- If  $|x| \leq a * h_0$ , we have  $\phi = \tanh(\frac{x+\delta x}{\sqrt{2K}})$  with  $\delta x = h_0 \sin(\frac{2\pi}{\lambda} y)$ , then we need to have

$$\mu = \frac{K\delta x}{\sqrt{2}} \left(\frac{2\pi}{\lambda}\right)^2 (1 - \phi^2) + \left(h_0 \frac{2\pi}{\lambda} \cos\left(\frac{2\pi}{\lambda} y\right)\right)^2 \phi (1 - \phi^2)$$

In practice, we choose  $1 < a < 2$

## New values

From [2], and CFL condition

- $h = \frac{1}{2^n}$  with  $n = 6, 7, 8$
- $K = O(h^k)$  with  $0 < k < 1$  (try  $K = 10h$ )
- $\Delta t \leq h^2 Pe/2$
- $\Delta t \leq h/v_i$

## Comparison with theory

We call  $\sigma(q)$  the growth rate of the fingers, with  $q$  the wave number of the fingers. According to the theory, we have:

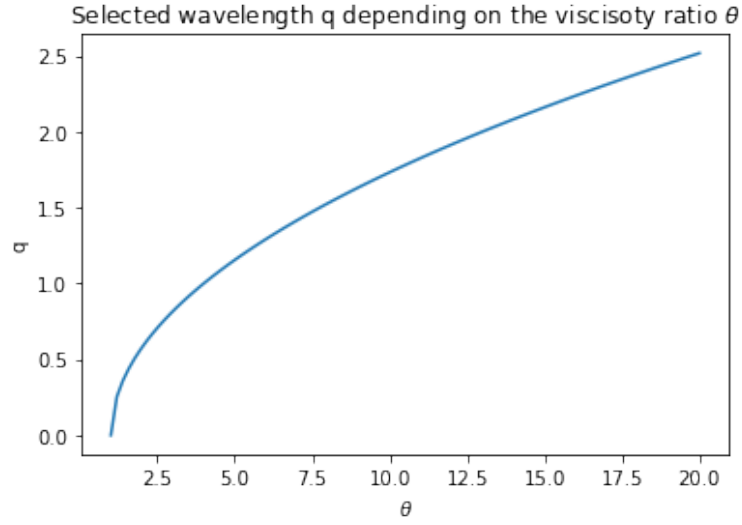
$$\sigma(q) = \frac{\theta - 1 - q^2}{\theta + 1} q$$

The wave number that will be selected and that we should see is the one with the fastest growing fingers, meaning the biggest  $\sigma$ .

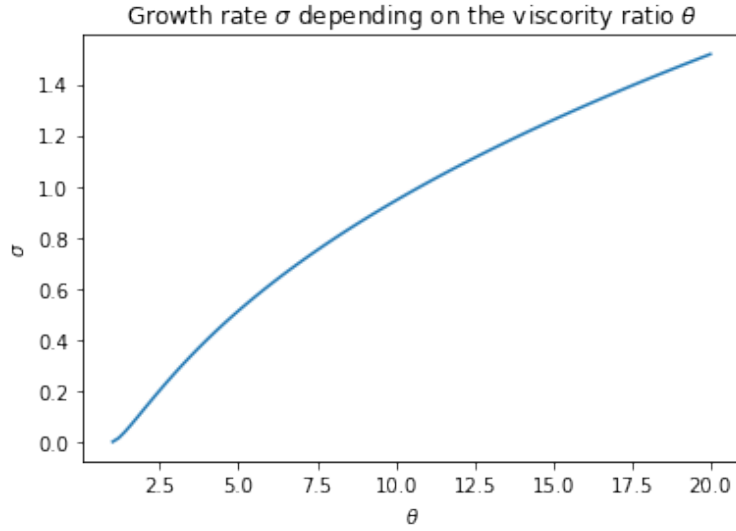
$$\begin{aligned} \frac{\partial \sigma(q)}{\partial q} &= \frac{\theta - 1}{\theta + 1} - \frac{3q^2}{\theta + 1} = 0 \\ \Leftrightarrow q_{chosen} &= \sqrt{\frac{\theta - 1}{3}} \\ \Leftrightarrow \sigma_{chosen} &= \frac{\theta - 1}{\theta + 1} \sqrt{\frac{\theta - 1}{3}} - \left(\frac{\theta - 1}{3}\right)^{3/2} \frac{1}{\theta + 1} \end{aligned}$$

Initially, the interface is  $H = \delta x_0$ , with time it will be  $H(t) = \delta x_0 + \delta h(t)$  and with  $\delta h(t) \propto \exp(\sigma_{chosen} t) \Leftrightarrow \ln(\delta h(t)) \propto \sigma_{chosen} t$ .

To begin with, we choose  $k = 2\pi/\lambda = q_{chosen}$  to make sure the fingers are growing, and then we will choose different  $q$  to see if we can get the appropriate  $q_{chosen}$  after some time.



**Figure 3:** Wave length depending on the viscosity



**Figure 4:** Growth rate depending on the viscosity

## Variational problem

### Solving the flow

Test functions  $\vec{v}_t \in L(\mathbb{R}^2) \rightarrow L(\mathbb{R}^2)$  and  $p_t \in L(\mathbb{R}) \rightarrow L(\mathbb{R})$

$$\begin{aligned} \vec{\nabla} p + \theta_c(\phi) \vec{v} &= -\frac{1}{Ca} \phi \vec{\nabla} \mu \\ \Rightarrow \int_{\Omega} \vec{\nabla} p \cdot \vec{v}_t + \theta_c(\phi) \vec{v} \cdot \vec{v}_t &= \int_{\Omega} -\frac{1}{Ca} \phi \vec{\nabla} \mu \cdot \vec{v}_t \\ \vec{\nabla} \cdot \vec{v} &= 0 \\ \Rightarrow \int_{\Omega} p_t \vec{\nabla} \cdot \vec{v} &= 0 \end{aligned}$$



$$\begin{aligned}
& \int_{\Omega} \theta_c(\phi) \vec{v} \cdot \vec{v}_t + \vec{\nabla} p \cdot \vec{v}_t + p_t \vec{\nabla} \cdot \vec{v} = - \int_{\Omega} \frac{1}{Ca} \phi \vec{\nabla} \mu \cdot \vec{v}_t \\
& \Leftrightarrow \int_{\Omega} \theta_c(\phi) \vec{v} \cdot \vec{v}_t + \vec{\nabla} p \cdot \vec{v}_t - \vec{\nabla} p_t \cdot \vec{v} + \int_{\partial\Omega} p_t \vec{v} \cdot \vec{n} dS = - \int_{\Omega} \frac{1}{Ca} \phi \vec{\nabla} \mu \cdot \vec{v}_t \\
& \int_{\partial\Omega} p_t \vec{v} \cdot \vec{n} dS = \int_{\partial\Omega_{in}} p_t \vec{v} \cdot \vec{n} dS + \int_{\partial\Omega_{out}} p_t \vec{v} \cdot \vec{n} dS + \int_{\partial\Omega_{top/bot}} p_t \vec{v} \cdot \vec{n} dS \\
& = \int_{\partial\Omega_{in}} p_t \vec{v} \cdot \vec{n} dS \\
& = \int_{\partial\Omega_{in}} -p_t dS
\end{aligned}$$

Because

- $p_{out}$  is know so  $p_t = 0$  on  $\partial\Omega_{out}$
- $\vec{v} \cdot \vec{n} = 0$  on  $\partial\Omega_{top/bot}$
- $\vec{v} \cdot \vec{n} = -1$  on  $\partial\Omega_{in}$  and because the normal goes outward

Then

$$\begin{aligned}
& \int_{\Omega} \theta_c(\phi) \vec{v} \cdot \vec{v}_t + \vec{\nabla} p \cdot \vec{v}_t - \vec{\nabla} p_t \cdot \vec{v} = - \int_{\Omega} \frac{1}{Ca} \phi \vec{\nabla} \mu \cdot \vec{v}_t + \int_{\partial\Omega_{in}} p_t dS \\
& \Leftrightarrow a((\vec{v}, p), (\vec{v}_t, p_t)) = L((\vec{v}_t, p_t))
\end{aligned}$$

## Solving the phase

Test functions  $\phi_t \in L(\mathbb{R}) \rightarrow L(\mathbb{R})$  and  $\mu_t \in L(\mathbb{R}) \rightarrow L(\mathbb{R})$ .

$$\begin{aligned}
& \frac{\partial \phi}{\partial t} + \vec{v} \cdot \vec{\nabla} \phi - \frac{1}{Pe} \nabla^2 \mu = 0 \\
& \Rightarrow \int_{\Omega} \frac{\partial \phi}{\partial t} \phi_t + \phi_t \vec{v} \cdot \vec{\nabla} \phi - \frac{1}{Pe} \phi_t \nabla^2 \mu = 0 \\
& \Leftrightarrow \int_{\Omega} \frac{\partial \phi}{\partial t} \phi_t + \phi_t \vec{v} \cdot \vec{\nabla} \phi + \frac{1}{Pe} \vec{\nabla} \mu \cdot \vec{\nabla} \phi_t = 0
\end{aligned}$$

Because  $\int_{\partial\Omega} \phi_t \vec{\nabla} \mu \cdot \vec{n} dS = 0$

- $\vec{\nabla} \mu \cdot \vec{n} = 0$  on  $\partial\Omega_{t/b}$
- $\phi$  is know on  $\partial\Omega_{left/right}$  so  $\phi_t = 0$  on  $\partial\Omega_{left/right}$

$$\begin{aligned}
& \mu - (\phi^3 - \phi) + K^2 \nabla^2 \phi = 0 \\
& \Rightarrow \int_{\Omega} \mu \mu_t - (\phi^3 - \phi) \mu_t + K^2 \mu_t \nabla^2 \phi = 0 \\
& \Leftrightarrow \int_{\Omega} \mu \mu_t - (\phi^3 - \phi) \mu_t - K^2 \vec{\nabla} \phi \cdot \vec{\nabla} \mu_t = 0
\end{aligned}$$

Because  $\int_{\partial\Omega} \mu_t \vec{\nabla} \phi \cdot \vec{n} dS = 0$

- $\vec{\nabla}\phi \cdot \vec{n} = 0$  on  $\partial\Omega_{t/b}$
- $\mu$  is known on  $\partial\Omega_{left/right}$  so  $\mu_t = 0$  on  $\partial\Omega_{left/right}$

## Time-Discretization

We now discretize the time:  $dt = t_{n+1} - t_n$  and apply an implicit time scheme  $\frac{\phi^{n+1} - \phi^n}{dt} = f(\phi^{n+1}, \mu^{n+1})$ :

$$\begin{aligned} \int_{\Omega} \frac{\partial\phi}{\partial t} \phi_t + \phi_t \vec{v} \cdot \vec{\nabla}\phi + \frac{1}{Pe} \vec{\nabla}\mu \cdot \vec{\nabla}\phi_t &= 0 \\ \Leftrightarrow \int_{\Omega} \frac{\phi^{n+1} - \phi^n}{dt} \phi_t + \phi_t \vec{v}^n \cdot \vec{\nabla}\phi^{n+1} + \frac{1}{Pe} \vec{\nabla}\mu^{n+1} \cdot \vec{\nabla}\phi_t &= 0 \end{aligned}$$

We first initiate  $\phi$  and  $\mu$ , and give  $\vec{v}$  an initial value of 1.

Then, if we know the values of  $\phi^n$ ,  $\mu^n$ ,  $\vec{v}^n$  and  $p^n$ , we first solve the phase and the chemical potential:

$$\begin{aligned} \int_{\Omega} \frac{\phi^{n+1} - \phi^n}{dt} \phi_t + \phi_t \vec{v}^n \cdot \vec{\nabla}\phi^{n+1} + \frac{1}{Pe} \vec{\nabla}\mu^{n+1} \cdot \vec{\nabla}\phi_t &= 0 \\ \int_{\Omega} \mu^{n+1} \mu_t - ((\phi^{n+1})^3 - \phi^{n+1}) \mu_t - K^2 \vec{\nabla}\phi^{n+1} \cdot \vec{\nabla}\mu_t &= 0 \end{aligned}$$

We now know  $\phi^{n+1}$  and  $\mu^{n+1}$ , and then use these values to update the velocity and the pressure:

$$\int_{\Omega} \theta_c(\phi^{n+1}) \vec{v}^{n+1} \cdot \vec{v}_t + \vec{\nabla}p^{n+1} \cdot \vec{v}_t - \vec{\nabla}p_t \cdot \vec{v}^{n+1} = - \int_{\Omega} \frac{1}{Ca} \phi^{n+1} \vec{\nabla}\mu^{n+1} \cdot \vec{v}_t + \int_{\partial\Omega_{in}} p_t dS$$

## Current solver

Currently : solve the flow with a Krylov solver with MUMP.

Solve the 2 equations for the phase together with a Newton solver (non linear).

## Dimensions

- $\beta = 10^{15} - 10^{16} Pa.s.m^{-2}$
- $\gamma = 10^{-3} - 10^{-2} Pa.m$
- $v_i = 10^{-8} - 10^{-6} m/s$  (we choose it to be a bit bigger than normal cell migration speed)
- For  $\beta = 10^{15}$ ,  $\gamma = 10^{-3}$  and  $v_i = 10^{-8}$  we have  $l = 10^{-5} m = 10 \mu m$
- The typical size of an epithelial cell would be  $10 \mu m$

We ideally want to try in boxes of (dimensionless) dimensions (100 x 100) - (200 x 200) to hope and see something.

## References

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