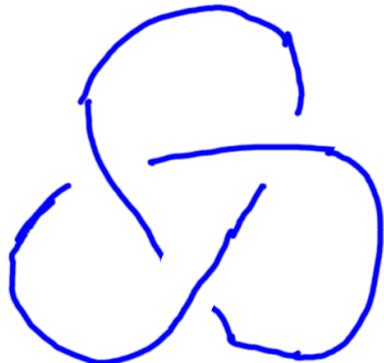


Invariants of knots and links

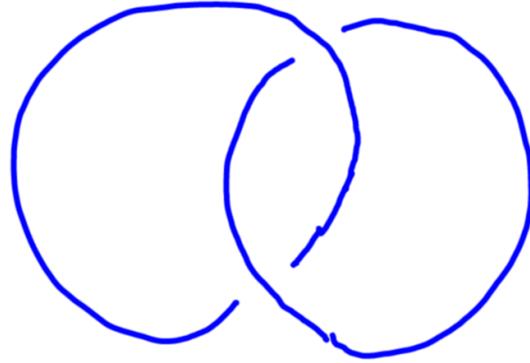
A knot is a smooth injective map $S^1 \rightarrow \mathbb{R}^3$. Two knots are isotopic (equivalent) if one is obtained from the other by a self-diffeomorphism of \mathbb{R}^3 . Link: $S^1 \cup \dots \cup S^1 \rightarrow \mathbb{R}^3$

Knot invariant: $f: \{\text{knots}\} \rightarrow X$

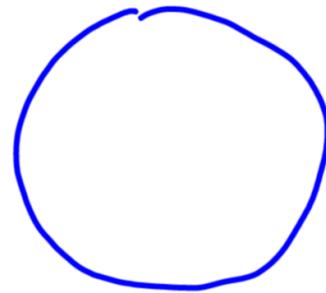
f depends only on the equivalence class



trefoil knot

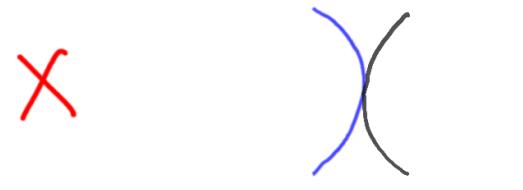


Hopf link

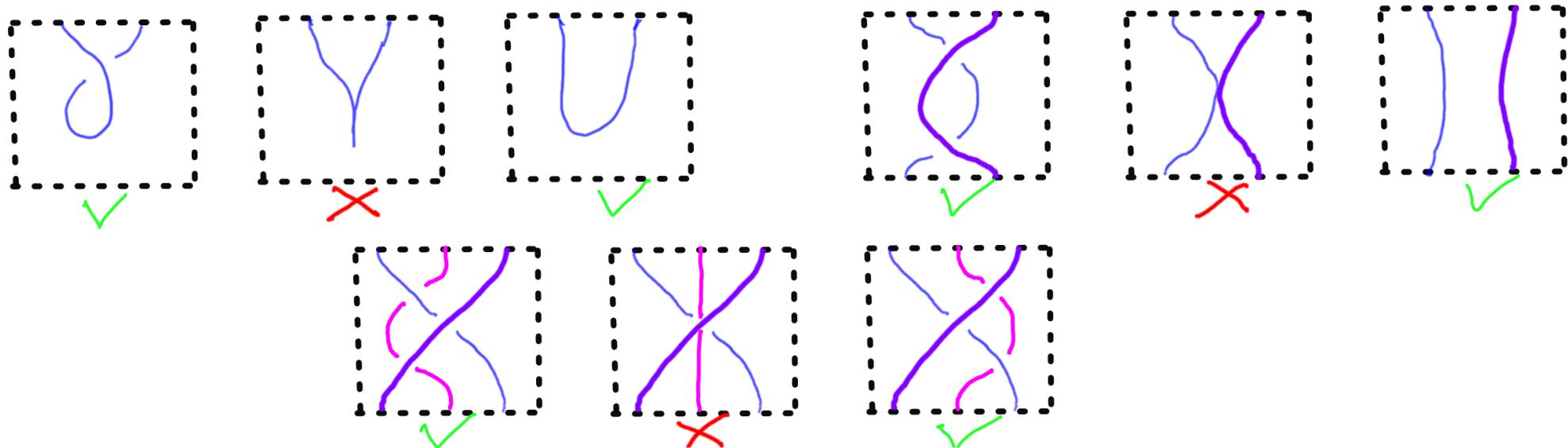


unknot

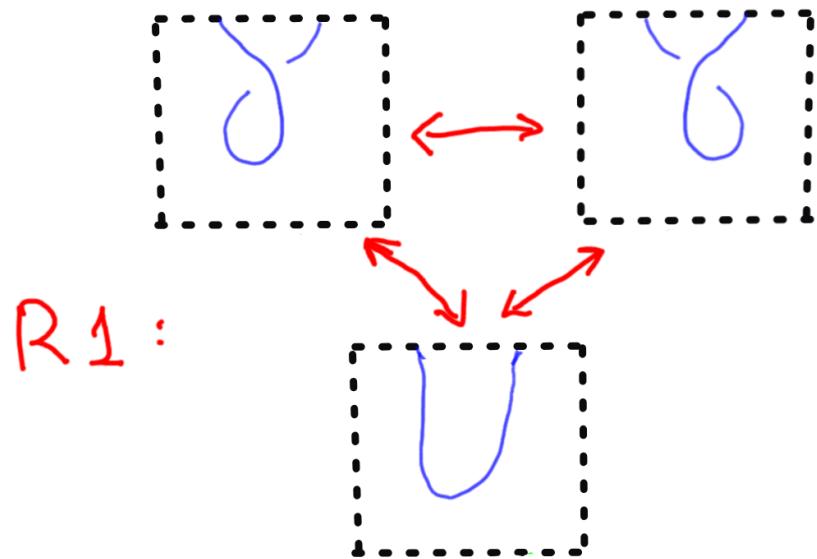
Instead of 3D knots, one considers f defined on 2D projections of knots, i.e. **knot (or link) diagrams** (see examples above). These are (unions of) smooth closed plane curves with finitely many self-intersections (**crossings**) where

-  - no "cusps" are allowed ;
-  - crossings must be transversal
-   - only 2 strands can cross at a given point and each crossing is labelled to show which strand is "above".

When \mathbb{R}^3 is continuously deformed, a knot $K: S^1 \rightarrow \mathbb{R}^3$ is deformed to K' isotopic to K . Yet the plane diagrams D of K and D' of K' may not be isotopic in \mathbb{R}^2 : this happens if, during deformation, the diagram passes through a "prohibited" configuration, such as



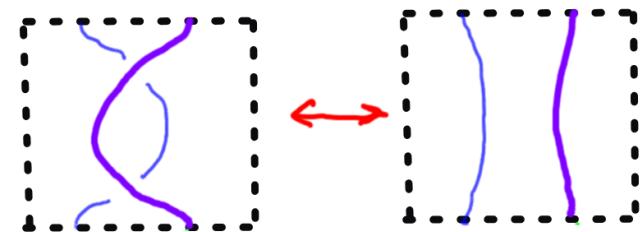
Reidemeister moves



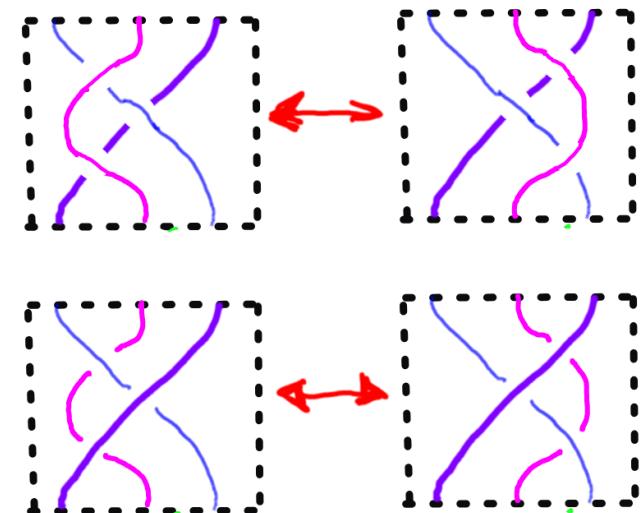
R1:

R0: an isotopy of \mathbb{R}^2

R2:



R3:



THM If D, D' are
diagrams of isotopic knots K, K'
then $D \xrightarrow{\text{Reidemeister}} D'$.

Corollary A function $f: \{ \text{knot diagrams in } \mathbb{R}^2 \} \rightarrow X$
gives a knot invariant if, and only if,
 $D \xrightarrow{\text{Reidemeister moves}} D' \implies f(D) = f(D')$.

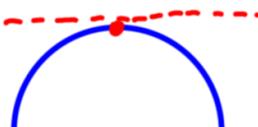
Sliced tangle diagrams

We fix a "vertical direction" (= "time arrow") in \mathbb{R}^2 which we will always draw downwards.

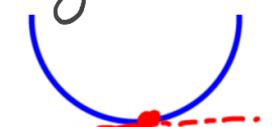
We consider only diagrams satisfying (1) & (2) below:

(1) there are finitely many critical points,

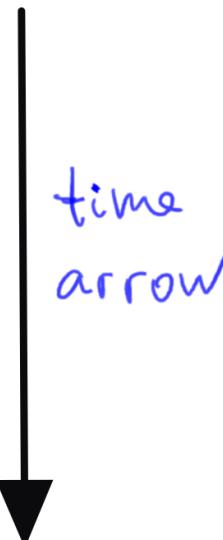
either



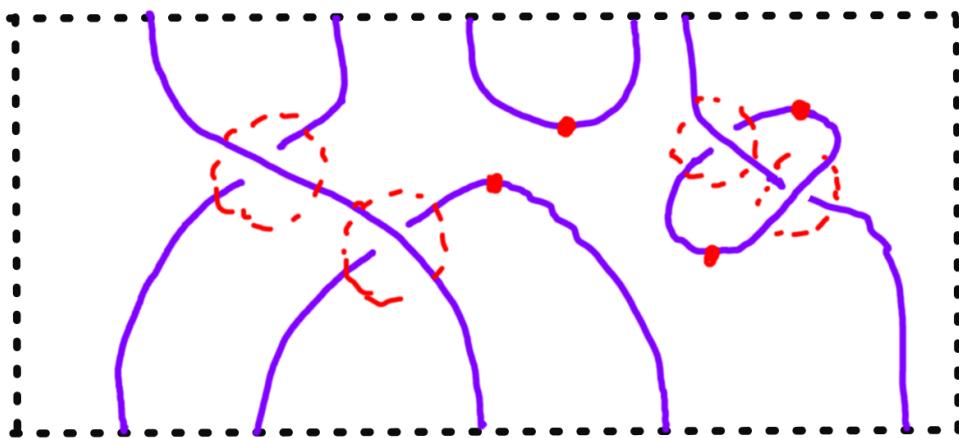
or



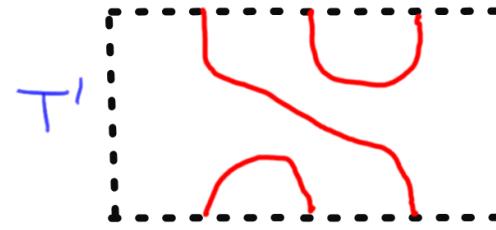
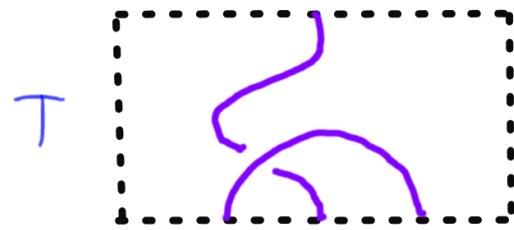
(2) all crossings are at 45° to the time arrow



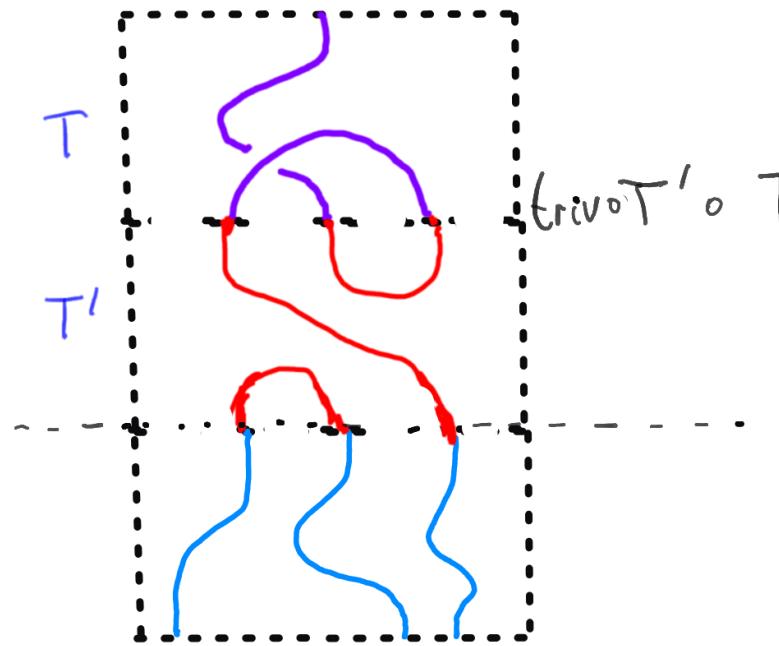
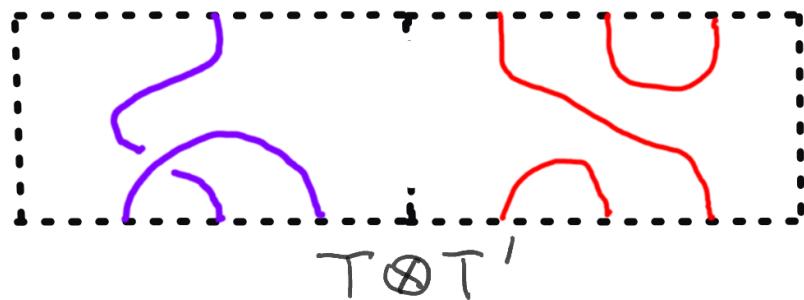
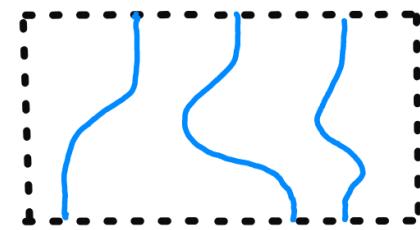
A tangle diagram is an intersection of a ^{"regular"} link diagram with a box (horizontal/vertical rectangle) where strands intersect only top & bottom of the box and always vertically.



Operations on tangle diagrams :



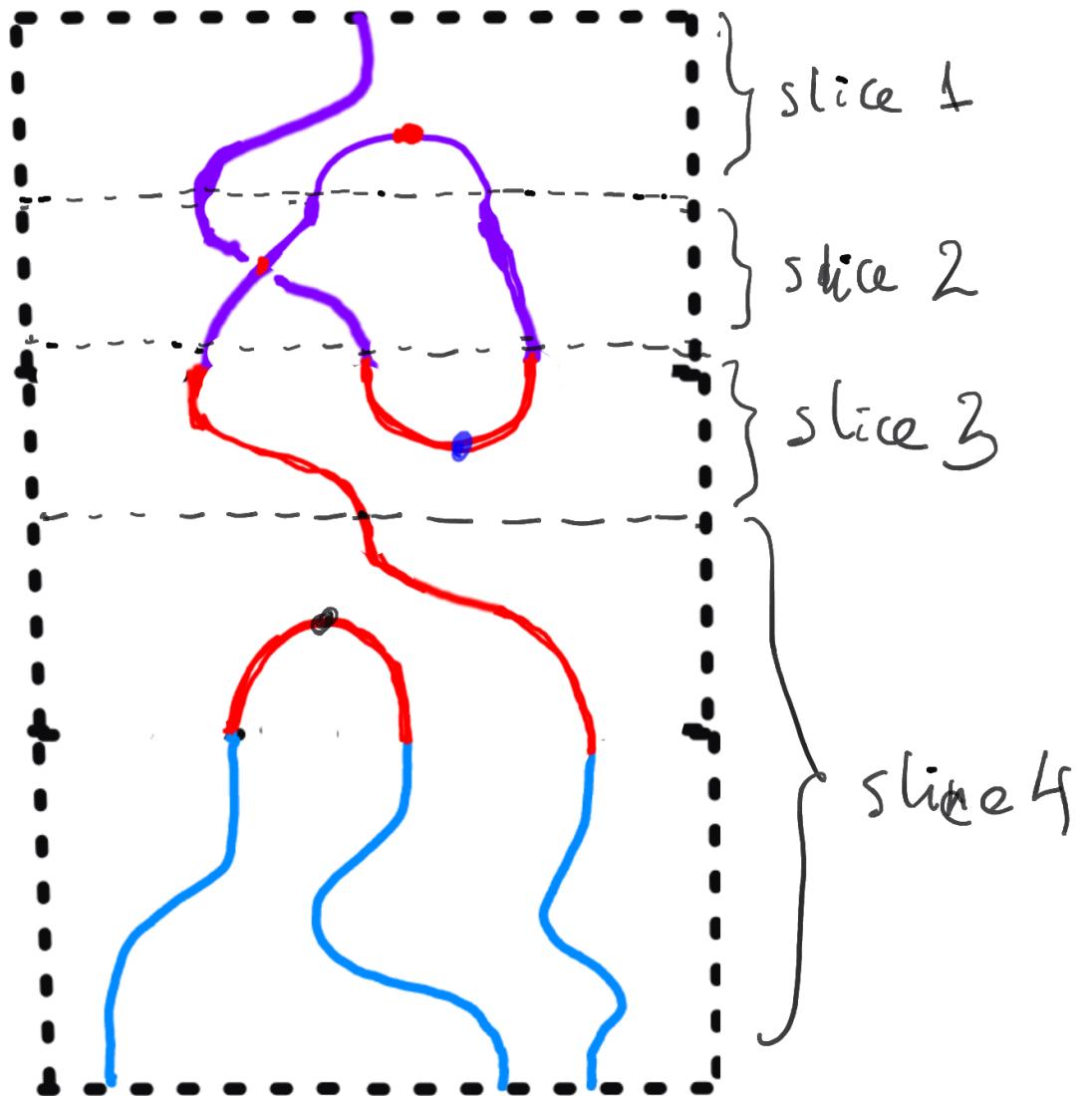
a trivial diagram
no crit. points
no crossings



Up to a regular isotopy preserving all crossings and all critical points,



every regular tangle diagram is equivalent to a sliced tangle diagram: a composition of boxes each of which contains at most one crossing or critical point.



We would like to construct $f: \{\text{sliced link diagrams}\} \rightarrow X$
which would give a knot and link invariant.

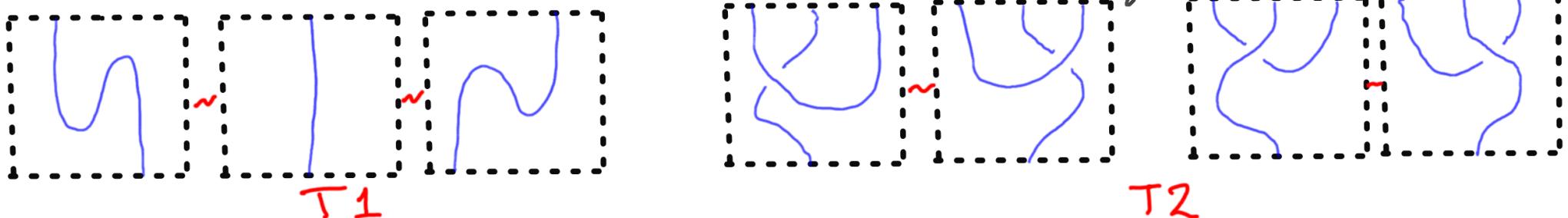
What kind of equivalence of sliced diagrams
should preserve the value of f to guarantee it's an invariant?

We would like to construct $f: \{\text{sliced link diagrams}\} \rightarrow X$
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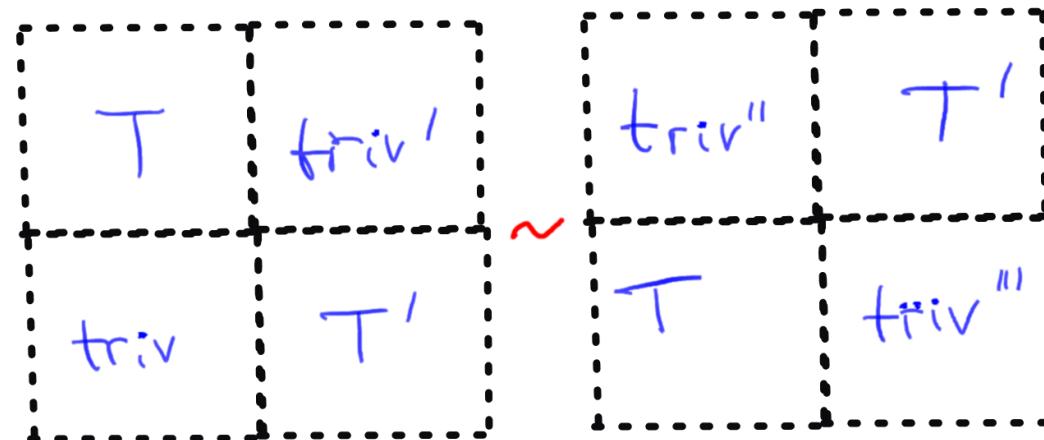
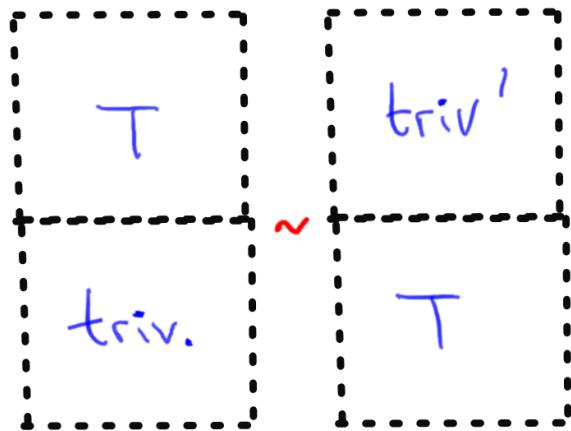
What kind of equivalence of sliced diagrams
should preserve the value of f to guarantee it's an invariant?

THM (Turaev, Freyd-Yetter, 1988-9) f is an isotopy invariant
iff f is unchanged under the Turaev moves:

- Reidemeister moves R1-R3 (for tangle diagrams - in boxes)



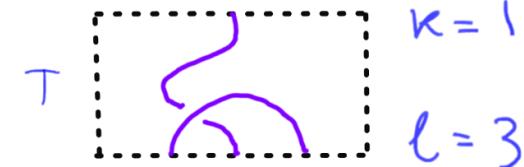
- as well as



The Operator Bracket

The next construction assigns, to each sliced tangle diagram T , a value $\langle T \rangle$ in the set of linear operators $V^{\otimes k} \rightarrow V^{\otimes l}$ where V is a fixed vector space, $k = \#$ of inputs of T , $l = \#$ of outputs of T . $\langle T \rangle$ is a value in the set of linear operators $V^{\otimes k} \rightarrow V^{\otimes l}$.

$V =$ vector space which is fixed throughout



The bracket $\langle T \rangle$ will be defined for all sliced tangle diagrams T and will automatically satisfy

$$\langle T \otimes T' \rangle = \langle T \rangle \otimes \langle T' \rangle \quad \langle T' \circ T \rangle = \langle T' \rangle \circ \langle T \rangle$$

$$\langle \text{trivial with } k \text{ strands} \rangle = \text{id}_{V^{\otimes k}} \rightarrow V^{\otimes k}$$

To define an operator bracket, we must choose V (a vector space) and three linear maps:

$$R: V \otimes V \rightarrow V \otimes V$$

called "R-matrix"

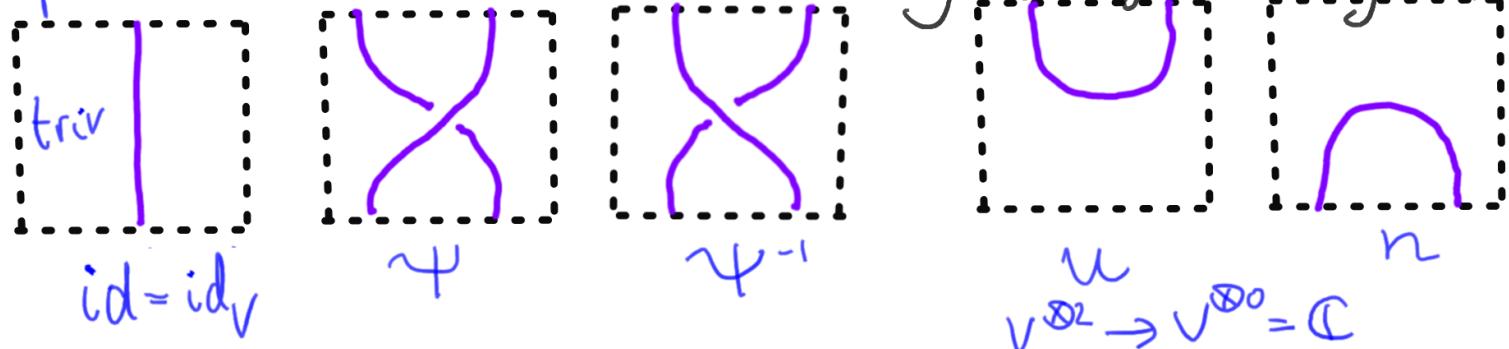
$$u: V \otimes V \rightarrow \mathbb{C}$$

cup map

$$n: \mathbb{C} \rightarrow V \otimes V$$

cap map

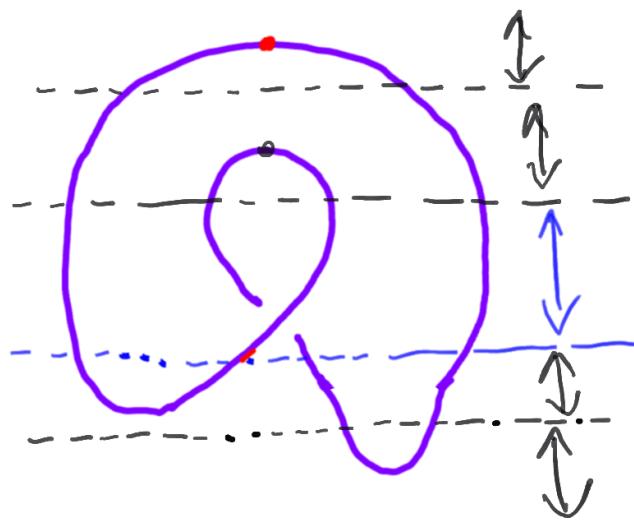
We assign operator value to elementary tangle diagrams
as follows:



$$\psi = \tau \circ R : V \otimes V \rightarrow V \otimes V$$

A slice is: $\langle T_1 \otimes T_2 \otimes \dots \otimes T_m \rangle \stackrel{\text{def}}{=} \langle T_1 \rangle \otimes \dots \otimes \langle T_m \rangle$
define $\langle T' \otimes T \rangle = \langle T' \rangle \circ \langle T \rangle,$

Example Suppose V , $R: V^{\otimes 2} \rightarrow V^{\otimes 2}$,
are chosen. Calculate $\langle T \rangle$ for the
knot diagram given below.



$$\begin{array}{c}
 \mathbb{C} \\
 \downarrow \otimes V \\
 V \otimes V \otimes V \xrightarrow{n} \text{id} \otimes \text{id} \otimes \text{id} \\
 \downarrow \otimes V \\
 V \otimes V \otimes V \otimes V \\
 \downarrow \otimes V \\
 V \otimes V \xrightarrow{u \otimes \text{id} \otimes \text{id}} u \\
 \downarrow \otimes V \\
 \mathbb{C}
 \end{array}$$

{ linear maps $\mathbb{C} \rightarrow \mathbb{C} \cong \mathbb{C}$

$$\begin{aligned}
 u: V^{\otimes 2} &\rightarrow \mathbb{C} \\
 n: \mathbb{C} &\rightarrow V^{\otimes 2}
 \end{aligned}$$

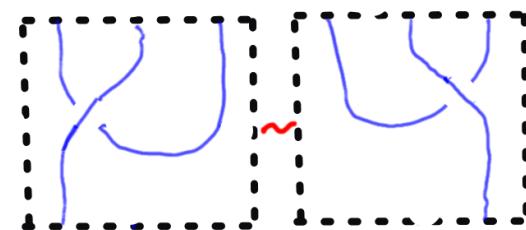
Can we make sure that the operator bracket $\langle \rangle = \langle \rangle_{R,\text{run}}$ is an isotopy invariant?

We need to check that $\langle \rangle$ does not change under the Turaev moves, which mean constraints (equations) on R, u and n :

$$\langle \text{---} \text{---} \text{---} \text{---} \text{---} \text{---} \text{---} \text{---} \rangle = \langle | \rangle = \langle \text{---} \text{---} \text{---} \text{---} \text{---} \text{---} \text{---} \text{---} \rangle$$

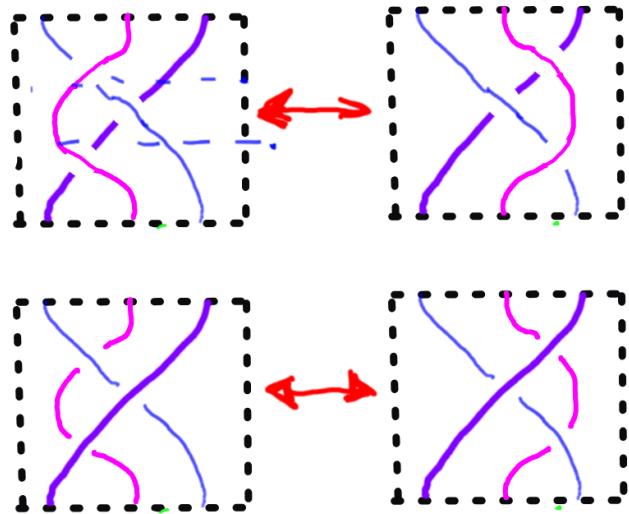
$\text{id} = (\text{id} \otimes u)(n \otimes \text{id})$

(equations) on R , u and n :



$$R2: \quad \begin{array}{c} \text{Diagram showing } (\text{id} \otimes u)(\psi \otimes \text{id}) = (u \otimes \text{id})(\text{id} \otimes \psi^{-1}) \\ \text{and } \psi^{-1} \circ \psi = \text{id}_{V^{\otimes 2}} \end{array}$$

R_3 :



$$(\varphi = \tau \circ R)$$

constraint on Ψ :

$$\Psi_{12} \Psi_{23} \Psi_{12} = \Psi_{23} \Psi_{12} \Psi_{23}$$

(as maps $V^{\otimes 3} \rightarrow V^{\otimes 3}$)
i.e. Braided Equation

$$R_{12} R_{13} R_{23} = R_{23} R_{13} R_{12}$$

Q.Y.B.E.

How to construct solutions to the equations
given by the Turaev moves $R1, R2, R3, T1, T2$?

THM Assume that H is a Hopf algebra;

$R \in H \otimes H$ is a quasitriangular structure on H ;

V is a finite-dimensional H -module, i.e. vector space with an H -action $\triangleright : H \otimes V \rightarrow V$;

$u : V \otimes V \rightarrow \mathbb{C}$ is a bilinear pairing which is non-degenerate and is invariant under \triangleright ,

meaning $u(h \triangleright x, y) = u(x, S(h) \triangleright y)$ $\forall x, y \in V$,
 $h \in H$

Consider R, u, n :

$$R : V \otimes V \rightarrow V \otimes V,$$

$$u : V \otimes V \rightarrow \mathbb{C}$$

$$n : \mathbb{C} \rightarrow V \otimes V, \quad n(1_{\mathbb{C}}) =$$

$$R(x \otimes y) = R \triangleright (x \otimes y)$$

as given

$$\sum_{i=1}^{\dim V} e_i \otimes f_i$$

dual bases w.r.t. u

Then the operator bracket $\langle \quad \rangle$ defined by
 R, u, n is invariant with respect to:

$$R_2 : \langle \overbrace{}^{} \rangle = \langle \overbrace{}^{} \rangle \quad \checkmark$$

$$\checkmark T_1 : \langle \text{J} \rangle = \langle \text{I} \rangle = \langle \text{L} \rangle$$

$$R_3 : \langle \overbrace{}^{(QYBE \text{ for } Q)} \rangle = \langle \overbrace{}^{(QYBE \text{ for } Q)} \rangle \quad \checkmark$$

$$\checkmark T_2 : \langle \text{Y} \rangle = \langle \text{U} \rangle$$

[not R_1] $\langle \text{J}' \rangle = \langle \text{U} \rangle$