# Hashing

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Data Structures (CS 223)

# 1 The Dictionary Problem

Given a set  $\mathcal{X}$  of n integers from  $\{0, 1, 2, \ldots, U-1\}$ , the problem is to design a data structure using which we can quickly verify whether  $\mathcal{X}$  contains an input integer key or not. Thus, for the set  $\mathcal{X} = \{5, 9, 19, 1, 24, 27, 32\}$ , the data structure must report true for key = 19 (or for any  $key \in \mathcal{X}$ ) and false for key = 200 (or for any  $key \notin \mathcal{X}$ ).

Of course the data structure has to be fast, as without such a restriction, we can simply scan through  $\mathcal{X}$  and answer the query in O(n) time. Additionally, the data structure should ideally support insertion of new numbers and deletion of existing numbers. Thus, we seek for a data structure over  $\mathcal{X}$  that supports the following operations:

- search(key): detect if key is present in  $\mathcal{X}$  or not
- insert(x): insert x into  $\mathcal{X}$
- delete(x): delete x from  $\mathcal{X}$

We have already seen binary search trees can support all these operations. In fact, binary search trees discussed in class can be improved to support these operations in worst case  $O(\log n)$  time.

Can we do even better? Using hashing, we can support these operations in O(1) time. However, we will look at an extremely simplified form.

### 2 The Naive Solution

Let us look at the most basic approach. We create a table A[U]. (Implementation wise, A can be thought of as an array.) Now, we set A[x] = 1 if  $x \in \mathcal{X}$  and A[x] = 0, otherwise. Thus, we can easily support the following operations in O(1) time as follows:

- search(key): by checking the value of A[key]
- insert(x): by setting A[x] = 1
- delete(x): by setting A[x] = 0

Refer to Figure 1. The set  $\mathcal{X}$  contains 9 and A[9] = 1, whereas  $\mathcal{X}$  does not contain 4 and A[4] = 0. To insert 10, we simply set A[10] = 1 and to delete 14, we simply set A[14] = 0.

Unfortunately, although very simplistic, the solution has a major disadvantage – it occupies too much space. Suppose  $U \gg n$ , i.e., the maximum value in  $\mathcal{X}$  is much higher than the size of  $\mathcal{X}$ . Then to store a small number of values, we create a gigantic array.

	0	0	0	1	0	1	0	1	0	1	0	1	0	0	1
•	0	1	2	3	4	5	6	7	8	9	10	11	12	13	$\overline{14}$

Figure 1: A naive hash table for the set  $\mathcal{X} = \{14, 3, 9, 11, 5, 7\}$  where the universe is  $\{0, 1, 2, \dots, 14\}$  of size U = 15

# 3 A Space-Efficient Solution

To alleviate the space issue, we take the following two-pronged approach:

- reduce the size of table A to some upper bound, say  $TABLE\_SIZE$ . Initialize each cell of the array to -1.
- use a hash function, say  $h(x) = x\%TABLE\_SIZE$ , where % denotes the modulo operator

## 3.1 Simple Scenario

Suppose there does not exist two integers x and y in  $\mathcal{X}$ , which satisfy h(x) = h(y). Under this assumption, we can can slightly modify our technique:

set 
$$A[h(x)] = x$$
 if  $x \in \mathcal{X}$  and  $A[h(x)] = -1$ , otherwise

Under this scenario, we can again support the above operations in O(1) time as follows:

- search(key): return true if A[key] >= 0 else return false
- insert(x): set A[h(x)] = x
- delete(x): set A[h(x)] = -1

So if  $TABLE\_SIZE$  is not too large, we have a good solution.

Refer to Figure 2. The set  $\mathcal{X}$  contains 14 and A[14%10] = A[4] = 14, whereas  $\mathcal{X}$  does not contain 26 and A[26%10] = A[6] = -1. To insert 10, we simply set A[10%10] = A[0] = 10 and to delete 14, we simply set A[14%10] = A[4] = -1.

-1	11	-1	3	14	15	-1	7	-1	9	
0	1	2	3	4	5	6	7	8	9	

Figure 2: A hash table for the set  $\mathcal{X} = \{14, 3, 9, 11, 15, 7\}$  where  $TABLE\_SIZE = 10$  and hash function  $h(x) = x\%TABLE\_SIZE$ . Note that 14, 11, and 15 get hashed to positions 4, 1, and 5, because 14%10 = 4, 11%10 = 1, 15%10 = 5.

### 3.2 Collision

Unfortunately, the assumption above is rather too stringent. So, let us remove it.

Immediately we run into a problem – if two numbers x and y are such that h(x) = h(y), then they *collide* into the same position in the table A. There is now no way of telling whether  $\mathcal{X}$  contains x, or y, or both, since we can keep only value in the array cell.

One of the standard ways of removing these collisions is called *separate chaining*.

### 3.3 Separate Chaining

The idea is to modify the structure of table A. Instead of A[i] being a standard array cell, we let it be a linked list. (Implementation wise, we can imagine A to be an array of linked lists.)

Now, we can support the operations as follows:

- search(key): go to the linked list A[h(key)] and scan it to detect if it contains key.
- insert(x): first search(x) and make sure that x is not already present. If not present, add x at the end of the linked list A[h(x)].
- delete(x): scan the linked list A[h(x)] and remove x if present. To implement this, you can search the linked list to find the position that contains x, and then do a deleteAfter on the node at the previous position.

Refer to Figure 3. The set  $\mathcal{X}$  contains 14 and the linked-list A[14%10] = A[4] contains 14, whereas  $\mathcal{X}$  does not contain 26 and A[26%10] = A[6] does not contain 6. To insert 10, we simply add 10 to the linked list A[10%10] = A[0] and to delete 14, we simply delete 14 from the linked list A[14%10] = A[4].

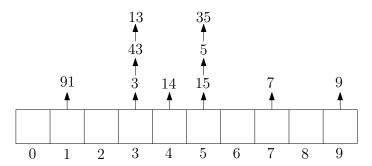


Figure 3: A hash table with separate for the set  $\mathcal{X} = \{14, 3, 9, 15, 7, 5, 35, 43, 13, 91\}$  where  $TABLE\_SIZE = 10$  and hash function  $h(x) = x\%TABLE\_SIZE$ . Note that 13, 43, and 3 get hashed to the linked list at index 3, because 13%10 = 3, 43%10 = 3, 3%10 = 3.

Of course, our O(1) time complexity is no longer guaranteed. Because, if we are really unlucky a large number of values may get hashed into the same linked list. However, with good choice of hash functions and if  $TABLE\_SIZE$  is a large prime number close to n, then collisions are usually not too high and the data structure is fast.

#### 3.4 Which hash function is better?

Usually, given a set  $\mathcal{X}$  and two hash functions, the one which reduces the number of collisions is a better choice. The number of collisions can be computed by subtracting the number of non-empty linked lists from n.