S4x Litebird

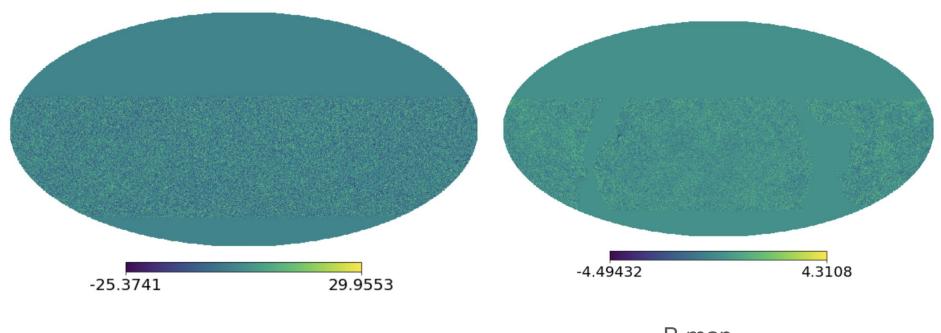
Chwide QE lensing reconstruction

Louis Legrand 8 May 2024

Maps from Shamik

25 maps, NILC E and B maps

E map



B map

_

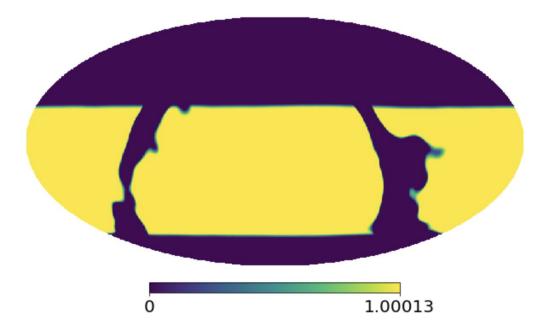
Quadratic estimator (in real space)

$${}_{1}\hat{\boldsymbol{d}}(\boldsymbol{\hat{n}}) = -\sum_{s=0,\pm 2} {}_{-s}\bar{\boldsymbol{X}}(\boldsymbol{\hat{n}}) \left[\boldsymbol{\delta}_{s}\boldsymbol{X}^{\mathrm{WF}}\right](\boldsymbol{\hat{n}}),$$
 QE deflection field
$$\mathbf{d} = \partial \phi \qquad \qquad \text{Inverse variance} \qquad \qquad \text{Wiener filtered (WF) maps}$$

- ➤ Follow Planck 2018 lensing analysis (<u>plancklens</u> code)
- (generalized) minimum variance estimator using E and B only
- IVF is done in pixel space, with fiducial spectra and mask
- QE weights (in the WF) use the gradCls

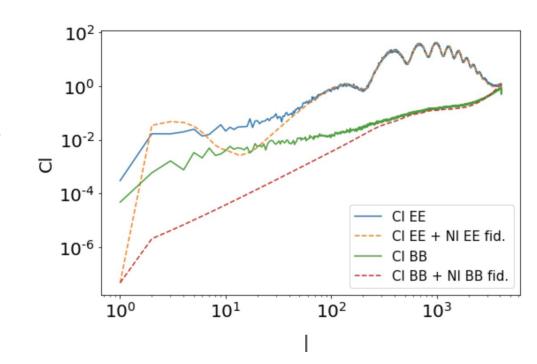
Mask

- Combination of:
 - S4 chile wide footprint with 3 degree apodization
 - Galactic dust footprint with 3 degree apodization



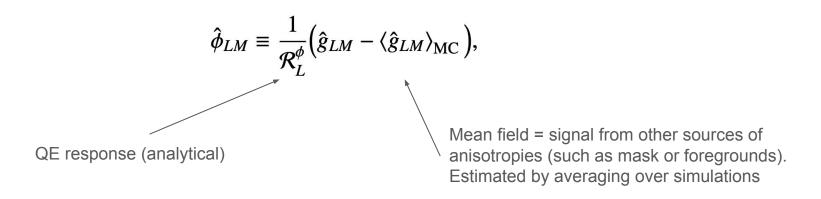
Filtering spectra

- Effective Gaussian beam of the NILC maps of 2.1 amin
- Polarisation noise estimated from the spectra (roughly) of 1.3 muK.arcmin
- I did not model the 1/f noise at low I
- Filtering is done between lmin=1 and lmax = 4096

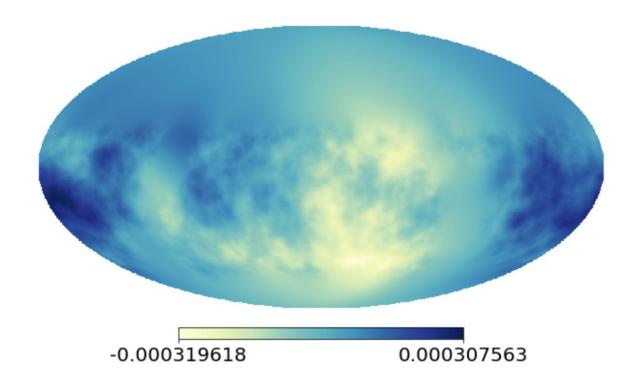


Debiased and normalised QE

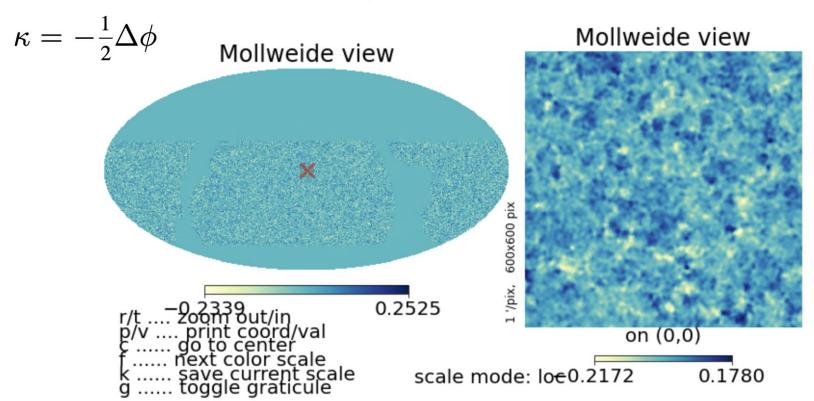
- Normalisation and mean field subtraction
- Mean field of each sim can be estimated from the other 24 simulations.



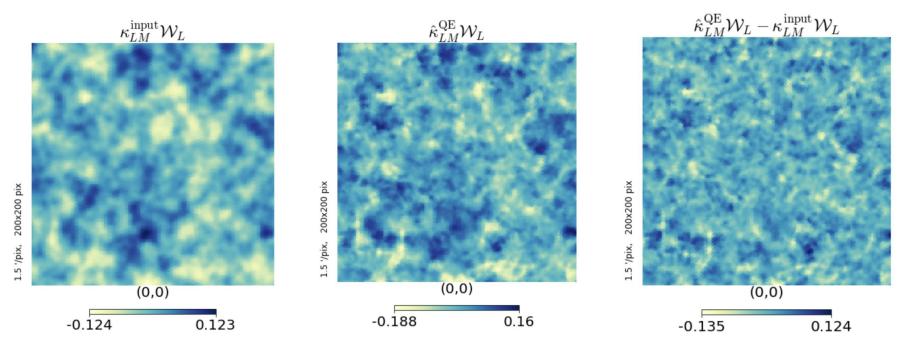
Reconstructed phi map



Wiener filtered convergence map

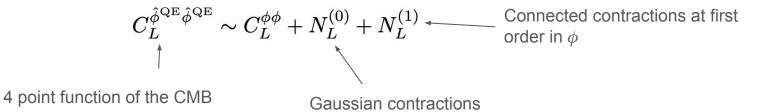


Comparison with input



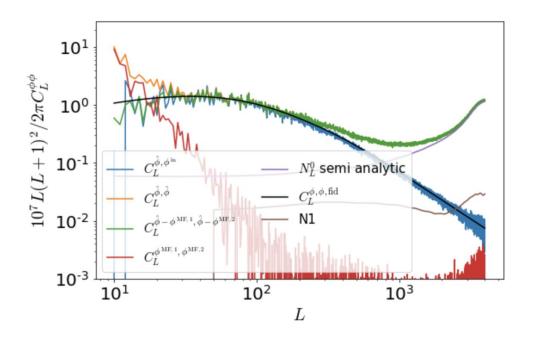
QE power spectrum

Power spectrum biases



No is estimated semi-analytically (combining fiducial spectra and spectra from the sims): unbiased at first order between the true and fiducial spectra of the maps

Mean field subtraction



Cross correlation with simulated ϕ

No mean field subtraction

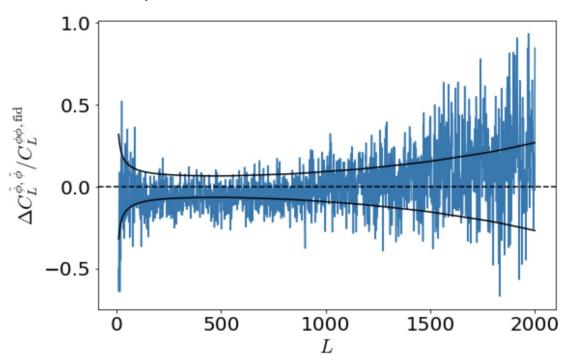
Mean field subtracted

Mean field (cross)

Men field estimated from two batches of 12 simulations (subtracting a different batch from each leg of the spectrum to lower MC variance)

Relative bias

- Subtracting N0 and N1 bias
- Black lines are the expected variance



Next steps

- Should I produce B-mode template maps?
- Use the iterative estimator to gain SNR