



THE UNIVERSITY OF TEXAS AT AUSTIN  
McCOMBS SCHOOL OF BUSINESS

# Diagnostics & Transformations

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## Lecture 12

STA 371G

Predicting the fuel economy (miles per gallon) for different car models of the 70s.



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“LINE” assumptions:

- Linearity
- Normally distributed errors
- Independent errors
- Equal Variance (Homoscedasticity)

## Predicting MPG from Horsepower

```
model<-lm(MPG ~ HP, data=auto_mpg)
summary(model)
```

Call:

```
lm(formula = MPG ~ HP, data = auto_mpg)
```

Residuals:

Min	1Q	Median	3Q	Max
-13.5710	-3.2592	-0.3435	2.7630	16.9240

Coefficients:

	Estimate	Std. Error	t value	Pr(> t )
(Intercept)	39.935861	0.717499	55.66	<2e-16 ***
HP	-0.157845	0.006446	-24.49	<2e-16 ***

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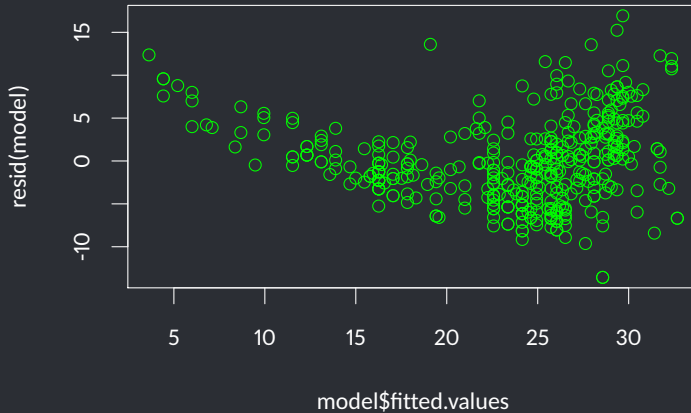
Signif. codes: 0 '\*\*\*' 0.001 '\*\*' 0.01 '\*' 0.05 '.' 0.1 ' ' 1

Residual standard error: 4.906 on 390 degrees of freedom

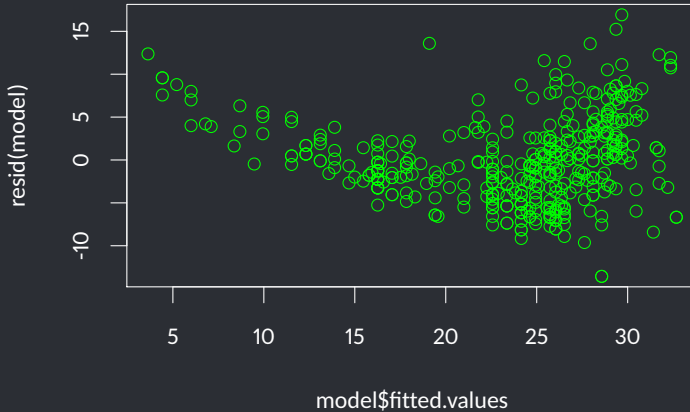
Multiple R-squared: 0.6059, Adjusted R-squared: 0.6049

F-statistic: 599.7 on 1 and 390 DF, p-value: < 2.2e-16

```
plot(model$fitted.values, resid(model), col='green')
```



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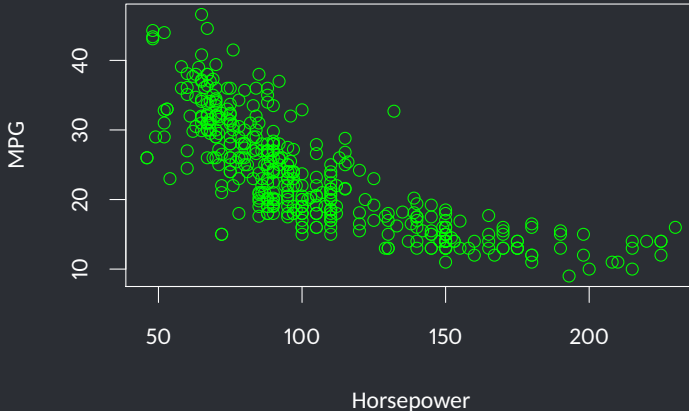


The trend in the residuals implies linearity issues.  
The “funnel” implies equal variance issues.

## Addressing the linearity issue

The relation between MPG and horsepower does not seem to be linear.

```
plot(auto_mpg$HP, auto_mpg$MPG, col='green',  
      xlab='Horsepower', ylab='MPG')
```



## Addressing the linearity issue

If we could horizontally shift the data on the far right towards left,  
the plot would look “more” linear.



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Predict the MPG of a car not from the horsepower, but from a “transformation” of the horsepower.

## Addressing the linearity issue

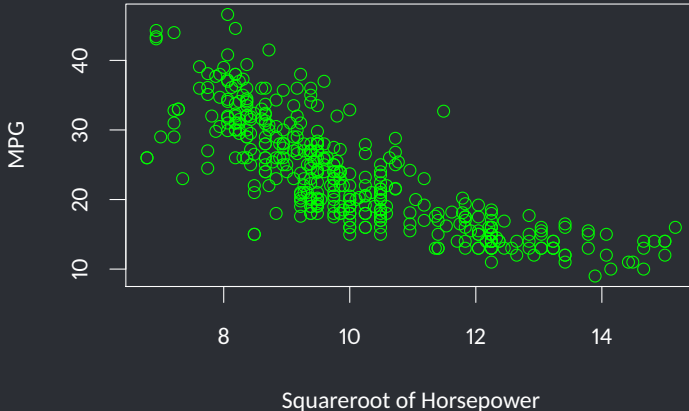
If we could horizontally shift the data on the far right towards left, the plot would look “more” linear.

Predict the MPG of a car not from the horsepower, but from a “transformation” of the horsepower.

For example, the relation between MPG and HP is not linear, the one between MPG and  $\sqrt{\text{HP}}$  is!

## Addressing the linearity issue

```
auto_mpg$HP_sqrt <- sqrt(auto_mpg$HP)
plot(auto_mpg$HP_sqrt, auto_mpg$MPG, col='green',
      xlab='Squareroot of Horsepower', ylab='MPG')
```



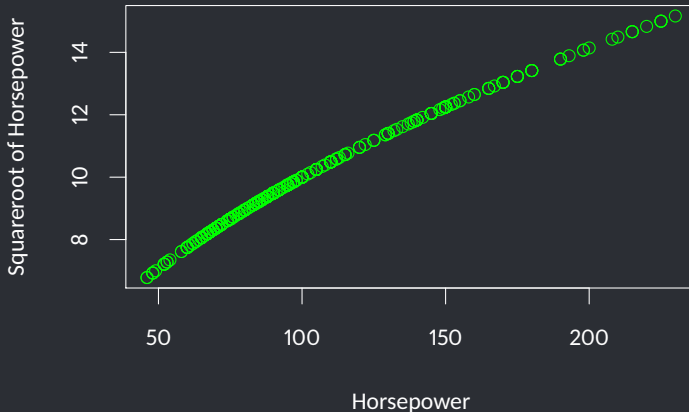
## Addressing the linearity issue

It indeed seems a bit better. Notice the change in the range of the horizontal axis.

## Addressing the linearity issue

It indeed seems a bit better. Notice the change in the range of the horizontal axis. It has changed from [49,225] to [7,15]. The shift is larger for the data on the far right.

```
plot(auto_mpg$HP, auto_mpg$HP_sqrt, col='green',  
      xlab='Horsepower', ylab='Squareroot of Horsepower')
```



## Addressing the linearity issue

```
model2<-lm(MPG ~ HP_sqrt, data=auto_mpg)
summary(model2)
```

Call:

```
lm(formula = MPG ~ HP_sqrt, data = auto_mpg)
```

Residuals:

	Min	1Q	Median	3Q	Max
	-13.9768	-3.2239	-0.2252	2.6881	16.1411

Coefficients:

	Estimate	Std. Error	t value	Pr(> t )	
(Intercept)	58.705	1.349	43.52	<2e-16	***
HP_sqrt	-3.503	0.132	-26.54	<2e-16	***

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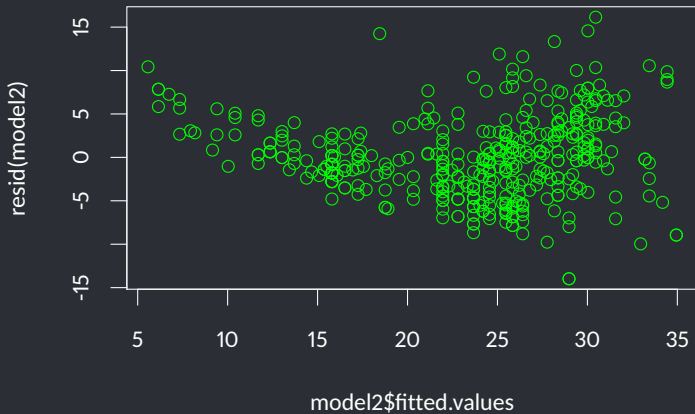
Signif. codes: 0 '\*\*\*' 0.001 '\*\*' 0.01 '\*' 0.05 '.' 0.1 ' ' 1

Residual standard error: 4.665 on 390 degrees of freedom

Multiple R-squared: 0.6437, Adjusted R-squared: 0.6428

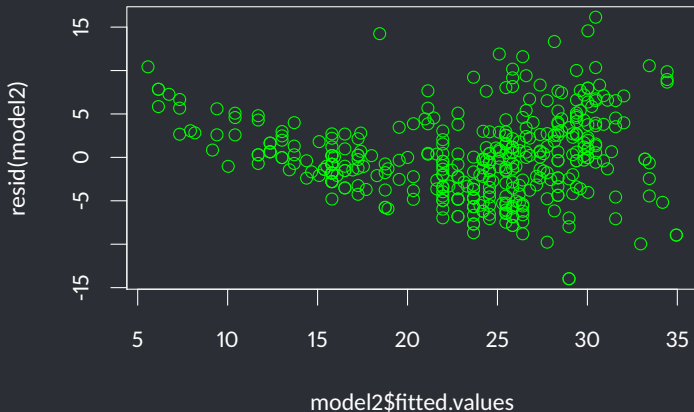
F-statistic: 704.6 on 1 and 390 DF, p-value: < 2.2e-16

```
plot(model2$fitted.values, resid(model2), col='green')
```



The trend flattened a bit.

```
plot(model2$fitted.values, resid(model2), col='green')
```



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Can we do better? Let's try some other transformation.



## Logarithmic transformation

One of the most common transformations is the logarithmic transformation with base  $e$  (natural logarithm).

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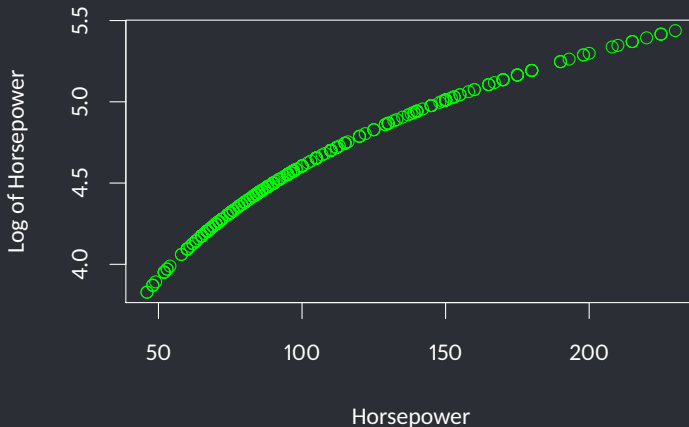
$$\log 7.389 = 2$$

In general:

$$y = e^x \rightarrow \log y = x.$$

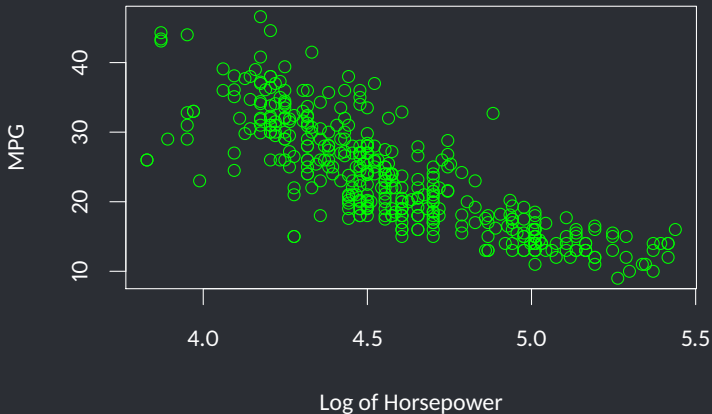
## Logarithmic transformation

```
auto_mpg$HP_ln <- log(auto_mpg$HP)  
plot(auto_mpg$HP, auto_mpg$HP_ln, col='green',  
      xlab='Horsepower', ylab='Log of Horsepower')
```



## Logarithmic transformation

```
plot(auto_mpg$HP_ln, auto_mpg$MPG, col='green',  
      xlab='Log of Horsepower', ylab='MPG')
```



```
model3<-lm(MPG ~ HP_ln, data=auto_mpg)
summary(model3)
```

Call:

```
lm(formula = MPG ~ HP_ln, data = auto_mpg)
```

Residuals:

	Min	1Q	Median	3Q	Max
	-14.2299	-2.7818	-0.2322	2.6661	15.4695

Coefficients:

	Estimate	Std. Error	t value	Pr(> t )
(Intercept)	108.6997	3.0496	35.64	<2e-16 ***
HP_ln	-18.5822	0.6629	-28.03	<2e-16 ***

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Signif. codes: 0 '\*\*\*' 0.001 '\*\*' 0.01 '\*' 0.05 '.' 0.1 ' ' 1

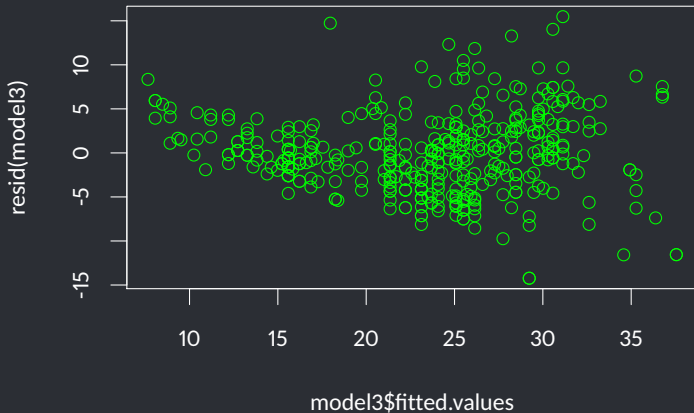
Residual standard error: 4.501 on 390 degrees of freedom

Multiple R-squared: 0.6683, Adjusted R-squared: 0.6675

F-statistic: 785.9 on 1 and 390 DF, p-value: < 2.2e-16



```
plot(model3$fitted.values, resid(model3), col='green')
```



The trend flattened even more.

## Transforming a Predictor

It is equivalent to “cutting the distribution of  $X$  into vertical slices and changing the spacing of the slices.”

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When the nonlinearity is the biggest issue in the model, transforming the predictor is a good start.

Finding the right transformation is a bit of art, field knowledge and trial and error.