### STOCHASTIC PROCESSES NOTES

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### 1. Basics

**Definition 1.1.** Let  $(\Omega, \mathcal{F}, \mathbb{P})$  be a probability space,  $(S, \mathcal{G})$  a measurable space, T an index set and  $X : T \times \Omega \to S$ . Then X is said to be a **stochastic processes** if for each  $t \in T$ ,  $X(t, \cdot)$  is  $\mathcal{F}$ - $\mathcal{G}$  measurable (i.e. X is just a collection of random variables indexed by time).

**Note 1.2.** We will work primarily with  $T = [0, \infty)$  and  $(S, \mathcal{G}) = (\mathbb{R}, \mathcal{B}(\mathbb{R}))$  and we often write  $X_t(\omega)$  to mean  $X(t, \omega)$  as well as the function  $X(\cdot, \omega)$ .

**Definition 1.3.** Let X be a process and  $\omega \in \Omega$ . The function  $X(\cdot, \omega)$  is called the **sample** path of  $\omega$ .

**Definition 1.4.** Let  $(\Omega, \mathcal{F}, \mathbb{P})$  be a probability space and  $\{\mathcal{F}_t\}_{t\geq 0}$  a collection of sub  $\sigma$ -algebras of  $\mathcal{F}$  such that for each  $s, t \in [0, \infty)$ , s < t implies that  $\mathcal{F}_s \subset \mathcal{F}_t$ . Then  $\{\mathcal{F}_t\}_{t\geq 0}$  is said to be a **filtration** of  $\mathcal{F}$ .

**Definition 1.5.** Let  $\{\mathcal{F}_t\}_{t\geq 0}$  be a filtration. Then  $\{\mathcal{F}_t\}_{t\geq 0}$  is said to be **complete** if for each  $t\in [0,\infty)$ ,  $\mathcal{F}_t$  contains all the null sets of  $\mathcal{F}$ . (i.e.  $\mathcal{F}_0$  contains all the null sets of  $\mathcal{F}$ )

**Definition 1.6.** Let  $\{\mathcal{F}_t\}_{t\geq 0}$  be a filtration. Then  $\{\mathcal{F}_t\}_{t\geq 0}$  is said to be **right continuous** if for each  $t\in [0,\infty)$ ,  $\mathcal{F}_t=\bigcap_{s>t}\mathcal{F}_s$ 

**Definition 1.7.** Let  $\{\mathcal{F}_t\}_{t\geq 0}$  be a filtration. Then  $\{\mathcal{F}_t\}_{t\geq 0}$  is said to satisfy the **usual** conditions if  $\{\mathcal{F}_t\}_{t\geq 0}$  is complete and right continuous.

**Definition 1.8.** Let  $\{\mathcal{F}_t\}_{t\geq 0}$  be a filtration. Define  $\mathcal{F}_{\infty} = \sigma(\mathcal{F}_t : t \geq 0)$ .

**Definition 1.9.** Let X be a process and  $\{\mathcal{F}_t\}_{t\geq 0}$  a filtration. Then X is said to be **adapted** to  $\{\mathcal{F}_t\}_{t\geq 0}$  if for each  $t\in [0,\infty)$ ,  $X_t$  is  $\mathcal{F}_t$  measurable

**Definition 1.10.** Let X be a process. Then the **minimal augmented filtration** of X is defined to be the smallest filtration  $\{\mathcal{F}_t\}_{t\geq 0}$  such that X is adapted to  $\{\mathcal{F}_t\}_{t\geq 0}$  and  $\{\mathcal{F}_t\}_{t\geq 0}$  satisfies the usual conditions. (here, "smallest" means that if  $\{\mathcal{G}_t\}$  is filtration satisfying the usual conditions to which X is adapted, then for each  $t \in [0, \infty)$ ,  $\mathcal{F}_t \subset \mathcal{G}_t$ )

**Definition 1.11.** Let  $(\Omega, \mathcal{F}, \mathbb{P})$  be a probability space,  $(S, \mathcal{G})$  a measurable space, T an index set and  $X: T \times \Omega \to S$  a stochastic process. We can define a function  $\Phi_X: \Omega \to S^T$  by  $\Phi_X(\omega)(t) = X(t, \omega)$ . The **law** of X is defined to be the pushforward measure of  $\mathbb{P}$  by  $\Phi_X$  and is denoted by  $\mathcal{L}_X$ . (i.e.  $\mathcal{L}_X(A) = \mathbb{P}(\Phi_X^{-1}(A))$  for  $A \in \mathcal{G}$ )

**Definition 1.12.** Let X and Y be processes. Then X and Y are said to be **modifications** if for each  $t \geq 0$ ,  $N_t = \{\omega \in \Omega : X_t(\omega) \neq Y_t(\omega)\}$  is a null set.

**Definition 1.13.** Let X and Y be processes. Then X and Y are said to be **indistinguishable** if  $N = \{\omega \in \Omega : \text{ for some } t \geq 0, X_t(\omega) \neq Y_t(\omega)\}$  is a null set.

Exercise 1. Let X and Y be processes. Suppose that X and Y are modifications and that a.s. (i.e. except on a null set) X and Y have right continuous paths. Then X and Y are indistinguishable.

Proof. By assumption,  $N_r = \{\omega \in \Omega : X_t(\omega) \text{ is not right continuous or } Y_t(\omega) \text{ is not right continuous} \}$  is a null set. Let  $\omega \in \Omega \cap N_r^c$ . Right continuity tells us that for each  $t \geq 0$ ,  $X_t(\omega) = Y_t(\omega)$  if and only if for each  $t \in [0, \infty) \cap \mathbb{Q}$ ,  $X_t(\omega) = Y_t(\omega)$ . Since X and Y are modifications, for each  $t \in [0, \infty) \cap \mathbb{Q}$ ,  $N_t = \{\omega \in \Omega : X_t(\omega) \neq Y_t(\omega)\}$  is a null set. Thus

$$N = \{\omega \in \Omega : \text{ for some } t \geq 0, X_t(\omega) \neq Y_t(\omega)\}$$

$$= (N \cap N_r) \cup (N \cap N_r^c)$$

$$= (N \cap N_r) \cup \{\omega \in \Omega \cap N_r^c : \text{ for some } t \in [0, \infty) \cap \mathbb{Q}, X_t(\omega) \neq Y_t(\omega)\}$$

$$= (N \cap N_r) \cup \bigcup_{t \in [0, \infty) \cap \mathbb{Q}} N_t$$

is a null set. Hence X and Y are indistinguishable.

**Definition 1.14.** Let X be a process. Then X is said to be **cadlag** if  $N = \{\omega \in \Omega : X_t(\omega) \text{ is not cadlag}\}$  is a null set.

**Definition 1.15.** Let X be a process and  $\{\mathcal{F}_t\}_{t\geq 0}$  be a filtration. Then X is said to be progressively measurable with respect to  $\{\mathcal{F}_t\}_{t\geq 0}$  if for each  $t\geq 0$ ,  $X|_{[0,t]\times\Omega}$  is  $\mathcal{B}([0,t])\times\mathcal{F}_t$  measurable.

**Exercise 2.** Let X be a process and  $\{\mathcal{F}_t\}_{t\geq 0}$  a filtration. Suppose that X is adapted to  $\{\mathcal{F}_t\}_{t\geq 0}$ . If each sample path of X is right continuous or each path of X is left continuous, then X is progressively measurable.

Proof. Fist suppose that each path of X is right continuous. Let  $t \geq 0$ . Define  $X_n$ :  $[0,t] \times \Omega \to \mathbb{R}$  by  $X_n(s,\omega) = X_0(\omega)\mathbf{1}_{\{0\}}(s) + \sum_{k=1}^2 X_{tk/2^n}(\omega)\mathbf{1}_{(t(k-1)/2^n,tk/2^n]}(s)$ . Since X is adapted to  $\{\mathcal{F}_t\}_{t\geq 0}$ ,  $X_n$  is  $\mathcal{B}([0,t]) \times \mathcal{F}_t$  measurable. Let  $(s,\omega) \in [0,t] \times \Omega$ . Suppose that s>0. Then for each  $n \in \mathbb{N}$ , there exists a unique  $k_n \in \mathbb{N}$  such that  $k_n \leq 2^n$  and  $t(k_n-1)/2^n < s \leq tk_n/2^n$ . Thus  $X_n(s,\omega) = X_{tk_n/2^n}(\omega)$ ,  $tk_n/2^n \geq s$  and  $tk_n/2^n \to s$ . Since each path of X is right continuous,  $X_n(s,\omega) \to X_s(\omega)$ . If s=0, then  $X_n(s,w) = X_0(\omega) = X_s(\omega)$ . Hence  $X_n(s,\omega) \to X_s(\omega)$ . Since  $X_n \to X|_{[0,t]\times\Omega}$  pointwise,  $X|_{[0,t]\times\Omega}$  is  $\mathcal{B}([0,t]) \times \mathcal{F}_t$  measurable. So X is progressively measurable.

Now suppose that each path of X is left continuous. Let  $t \geq 0$ . Define  $X_n : [0, t] \times \Omega \to \mathbb{R}$  by  $X_n(s, \omega) = \sum_{k=1}^{2^n} X_{t(k-1)/2^n}(\omega) \mathbf{1}_{[t(k-1)/2^n, tk/2^n)}(s) + X_t(\omega) \mathbf{1}_{\{t\}}(s)$ . The rest of the proof is similar to the other case, just this time utilizing left continuity.

**Exercise 3.** Let X be a process and  $\{\mathcal{F}_t\}_{t\geq 0}$  a complete filtration. Suppose that X is adapted to  $\{\mathcal{F}_t\}_{t\geq 0}$  and that X is right continuous or X is left continuous (a.s. of course). Then X is progressively measurable.

*Proof.* First we assume that X is right continuous. Let  $N = \{\omega \in \Omega : X(\cdot, \omega) \text{ is not right continuous}\}$ . By assumption, N is null and therefore for each  $t \geq 0$ ,  $N \in \mathcal{F}_t$ . Define  $\widetilde{X} : [0, \infty) \times \Omega \to [0, \infty)$  by  $\widetilde{X}(t, \omega) = X(t, \omega) \mathbf{1}_{N^c}(\omega)$ 

Since for each  $t \geq 0$ ,  $X_t$  is  $\mathcal{F}_t$  measurable and  $N^c \in \mathcal{F}_t$ , we have that  $\widetilde{X}_t$  is  $\mathcal{F}_t$  measurable and thus  $\widetilde{X}$  is adapted to  $\{\mathcal{F}_t\}_{t\geq 0}$ . By construction, each sample path of  $\widetilde{X}$  is right continuous. By the previous exercise,  $\widetilde{X}$  is porgressively measurable.

Now, let  $t \geq 0$  and  $B \in \mathcal{B}([0,t])$ . If  $0 \notin B$ , then

$$X|_{[0,t]\times\Omega}^{-1}(B) = \widetilde{X}|_{[0,t]\times\Omega}^{-1}(B)$$

. If  $0 \in B$ , then

$$X|_{[0,t]\times\Omega}^{-1}(B) = \left[X|_{[0,t]\times\Omega}^{-1}(B)\cap([0,t]\times N)\right] \cup \left[X|_{[0,t]\times\Omega}^{-1}(B)\cap([0,t]\times N^c)\right]$$

$$= X|_{[0,t]\times\Omega}^{-1}(B\setminus\{0\})\cup X|_{[0,t]\times\Omega}^{-1}(\{0\})$$

$$= \widetilde{X}|_{[0,t]\times\Omega}^{-1}(B\setminus\{0\})\cup X^{-1}(\{0\})\cup([0,t]\times N)$$

**Definition 1.16.** Let  $\{\mathcal{F}_t\}_{t\geq 0}$  be a filtration and  $T:\Omega\to [0,\infty]$  a random variable. Then T is said to be a **stopping time** for  $\{\mathcal{F}_t\}_{t\geq 0}$  if for each  $t\in [0,\infty]$ ,  $\{\omega\in\Omega:T(\omega)\leq t\}\in\mathcal{F}_t$ .

Note that if  $t = \infty$ , then

$$\{\omega \in \Omega : T(\omega) \le t\} = \Omega \in \mathcal{F}_{\infty}$$

We will typically just say that T is a stopping time when the filtration is clear.

**Proposition 1.17.** Let  $\{\mathcal{F}_t\}_{t\geq 0}$  be a filtration. Then we have the following:

- (1) if S and T are stopping times, then S + T is a stopping time.
- (2) if S is a stopping time, then for  $\alpha \geq 1$ ,  $\alpha S$  is a stopping time.
- (3) if there exists  $c \in [0, \infty]$  such that  $T \equiv c$ , then T is a stopping time.
- (4) If  $(T_n)_{n\in\mathbb{N}}$  is a sequence of stopping times, then  $\sup_{n\in\mathbb{N}} T_n$  and  $\inf_{n\in\mathbb{N}} T_n$  are stopping times.

Note that the third statement holds for  $T \equiv c$  almost surely if  $\{\mathcal{F}_t\}_{t\geq 0}$  is complete and the last statement implies that mins  $\limsup T_n$  and  $\liminf T_n$  and that for stopping times S and T,  $S \wedge T$  and  $S \vee T$  are stopping times.

The proof is similar to showing measurbaility of the same functions.

**Proposition 1.18.** Let  $\{\mathcal{F}_t\}_{t\geq 0}$  be a right continuous filtration and  $T:\Omega\to [0,\infty]$  a random variable. Then T is a stopping time for  $\{\mathcal{F}_t\}_{t\geq 0}$  if and only if for each  $t\geq 0$ ,  $\{\omega\in\Omega:T(\omega)< t\}\in\mathcal{F}_t$ .

*Proof.* Suppose that for each  $s \geq 0$ ,  $\{\omega \in \Omega : T(\omega) < s\} \in \mathcal{F}_s$ . Let  $t \geq 0$ . Then

$$\{\omega \in \Omega : T(\omega) \le t\} = \bigcap_{n \in \mathbb{N}} \{\omega \in \Omega : T(\omega) < t + 1/n\}$$

$$\in \bigcap_{n \in \mathbb{N}} \mathcal{F}_{t+1/n}$$

$$= \mathcal{F}_t \qquad \text{(right continuity)}$$

Conversely, suppose that T is a stopping time for  $\{\mathcal{F}_t\}_{t\geq 0}$ . Let  $t\geq 0$ . Then

$$\{\omega \in \Omega : T(\omega) < t\} = \bigcup_{n \in \mathbb{N}} \{\omega \in \Omega : T(\omega) \le t - 1/n\}$$
$$\in \mathcal{F}_t$$

**Exercise 4.** Let  $\{\mathcal{F}_t\}_{t\geq 0}$  be right continuous and  $T:\Omega\to [0,\infty)$  be a stopping time for  $\{\mathcal{F}_t\}_{t\geq 0}$ . Define  $T_n:\Omega\to [0,\infty)$  by  $T_n(\omega)=k_\omega/2^n$  where  $k_\omega\in\mathbb{N}$  is the unique positive integer such that  $(k_\omega-1)/2^n\leq T(\omega)< k_\omega/2^n$ . Then for each  $n\in\mathbb{N}$ ,  $T_n$  is a stopping time for  $\{\mathcal{F}_t\}_{t\geq 0}$ . **FINISH!!!!!!!!** 

Proof. Let 
$$t \geq 0$$
.

**Definition 1.19.** Let X be a process and  $\Lambda \in \mathcal{B}(\mathbb{R})$ . Then the **hitting time** of  $\Lambda$  is defined to be the random variable  $T_{\Lambda}: \Omega \to [0, \infty]$  given by  $T_{\Lambda}(\omega) = \inf\{t > 0 : X_t(\omega) \in \Lambda\}$ .

**Theorem 1.20.** Let  $\{\mathcal{F}_t\}_{t\geq 0}$  be a complete filtration, X a right continuous process adapted to  $\{\mathcal{F}_t\}_{t\geq 0}$  and  $\Lambda \subset \mathbb{R}$  an open set. Then  $T_\Lambda$  is a stopping time for  $\{\mathcal{F}_t\}_{t\geq 0}$ .

Proof. Let  $t \geq 0$ . Note that for  $\omega \in \Omega$ , if  $X(\cdot, \omega)$  is right continuous, then since  $\Lambda$  is open, we have that  $T_{\Lambda}(\omega) < t$  if and only if there exists  $s \in (0, t)$  such that  $X_s(\omega) \in \Lambda$  if and only if there exists  $s \in \mathbb{Q} \cap (0, t)$  such that  $X_s(\omega) \in \Lambda$ . The completeness of  $\{\mathcal{F}_t\}_{t\geq 0}$  tells us that for each  $s \in [0, \infty)$ ,  $\mathcal{F}_s$  has all the null sets of  $\mathcal{F}$ . Finally,  $\Lambda$  being open and X being adapted tell us that for each s < t,  $X_s^{-1}(\Lambda) \in \mathcal{F}_s \subset \mathcal{F}_t$ .

By assumption  $N = \{\omega \in \Omega : X(\cdot, \omega) \text{ is not right continuous} \}$  is a null set, so for each  $s \in [0, \infty), N \in \mathcal{F}_s$  and  $N^c \in \mathcal{F}_s$ . The previous note implies that

$$\{\omega \in \Omega : T_{\Lambda}(\omega) < t\} = (\{\omega \in \Omega : T_{\Lambda}(\omega) < t\} \cap N^{c}) \cup (\{\omega \in \Omega : T_{\Lambda}(\omega) < t\} \cap N)$$

$$= \left(\bigcup_{s \in \mathbb{Q} \cap (0,t)} \{\omega \in \Omega : X_{s}(\omega) \in \Lambda\} \cap N^{c}\right) \cup \left(\{\omega \in \Omega : T(\omega) < t\} \cap N\right)$$

$$\in \mathcal{F}_{t}$$

Hence  $T_{\Lambda}$  is a stopping time for  $\{\mathcal{F}_t\}_{t\geq 0}$ .

Note that the same result is true if X is a left continuous process. Also, as usual, we could get rid of the assumption that  $\{\mathcal{F}_t\}_{t\geq 0}$  is complete if each sample path of X were right or left continuous instead of the paths being almost surely right or left continuous.

**Definition 1.21.** Let  $\{\mathcal{F}_t\}_{t\geq 0}$  be a filtration and T a stopping time for  $\{\mathcal{F}_t\}_{t\geq 0}$ . The **stopping algebra** of T to be  $\mathcal{F}_T = \{A \in \mathcal{F} : \text{ for each } t \geq 0, A \cap T^{-1}([0,t]) \in \mathcal{F}_t\}$ 

Note that  $\mathcal{F}_T$  is a  $\sigma$ -algebra

**Lemma 1.22.** Let  $\{\mathcal{F}_t\}_{t\geq 0}$  be a filtration and T a stopping time for  $\{\mathcal{F}_t\}_{t\geq 0}$ . Then T is  $\mathcal{F}_T$  measurable.

*Proof.* Let  $t, s \in [0, \infty]$ . Then

$$T^{-1}([0,s]) \cap T^{-1}([0,t]) = T^{-1}([0,t \wedge s])$$

$$\in \mathcal{F}_{t \wedge s}$$

$$\subset \mathcal{F}_t.$$

So for each  $s \in [0, \infty]$ ,  $T^{-1}([0, s]) \in \mathcal{F}_T$ . Hence T is  $\mathcal{F}_T$  measurable.

**Theorem 1.23.** Let  $\{\mathcal{F}_t\}_{t\geq 0}$  be a filtration and  $T:\Omega\to [0,\infty)$  a finite stopping time for  $\{\mathcal{F}_t\}_{t\geq 0}$ . Then  $\mathcal{F}_T=\sigma(X_T:X \text{ is an everywhere cadlag process adapted to } \{\mathcal{F}_t\}_{t\geq 0})$ .

Proof. Put  $\mathcal{G} = \sigma(X_T : X \text{ is an everywhere cadlag process adapted to } \{\mathcal{F}_t\}_{t\geq 0})$ . Let  $\Lambda \in \mathcal{F}_T$ . Define  $X_t(\omega) = \mathbf{1}_{\Lambda}(\omega)\mathbf{1}_{T^{-1}([0,t])}(\omega) = \mathbf{1}_{\Lambda\cap T^{-1}([0,t])}(\omega)$ . Then each sample path of X is clearly cadlag. Moreover, since  $\Lambda \in \mathcal{F}_T$ , for each  $t\geq 0$ ,  $\Lambda \cap T^{-1}([0,t]) \in \mathcal{F}_t$ . So for each  $t\geq 0$ ,  $X_t$  is  $\mathcal{F}_t$  measurable and thus X is adapted to  $\{\mathcal{F}_t\}_{t\geq 0}$ . So by definition,  $X_T$  is  $\mathcal{G}$  measurable. It is easy to see that  $X_T = \mathbf{1}_{\Lambda}$  and therefore  $\Lambda \in \mathcal{G}$ . Hence  $\mathcal{F}_T \subset \mathcal{G}$ .

Now, let X be an everywhere cadlag process adapted to  $\{\mathcal{F}_t\}_{t\geq 0}$  and  $t\geq 0$ . Define  $\phi:\Omega\to[0,\infty)\times\Omega$  by  $\phi(\omega)=(T(\omega),\omega)$ . Then  $X_T=X\circ\phi$ . For  $t\geq 0$ , define the  $\sigma$ -algebra  $\mathcal{F}_t\cap T^{-1}([0,t])$  on  $T^{-1}([0,t])$  by  $\mathcal{F}_t\cap T^{-1}([0,t])=\{A\cap T^{-1}([0,t]):A\in\mathcal{F}_t\}$ . Let  $U_1\in\mathcal{B}([0,\infty))$  and  $U_2\in\mathcal{F}_t$ . Then  $\phi|_{T^{-1}([0,t])}^{-1}(U_1\times U_2)=T^{-1}(U_1)\cap (U_2)\cap T^{-1}([0,t])$ . Since T is  $\mathcal{F}_T$  measurable,  $T^{-1}(U_1)\in\mathcal{F}_T$ . By definition,  $T^{-1}(U_1)\cap T^{-1}([0,t])\in\mathcal{F}_t\cap T^{-1}([0,t])$ . Since  $U_2\in\mathcal{F}_t$ , we have that  $\phi|_{T^{-1}([0,t])}^{-1}(U_1\times U_2)\in\mathcal{F}_t\cap T^{-1}([0,t])$ . So  $\phi|_{T^{-1}([0,t])}$  is  $(\mathcal{F}_t\cap T^{-1}([0,t]),\mathcal{B}([0,\infty))\otimes\mathcal{F}_t)$  measurable.

Since each sample path of X is cadlag and X is adapted to  $\{\mathcal{F}_t\}_{t\geq 0}$ , X is progressively measurable. In particular,  $X|_{[0,t]\times\Omega}$  is  $\mathcal{B}([0,\infty))\bigotimes \mathcal{F}_t$ ) measurable.

Hence  $X_T|_{T^{-1}([0,t])}$  is  $F_t \cap T^{-1}([0,t])$  measurable and for  $B \in \mathcal{B}([0,\infty))$ ,

$$X_T^{-1}(B) \cap T^{-1}([0,t]) = X_T|_{T^{-1}([0,t])}^{-1}(B)$$

$$\in \mathcal{F}_t \cap T^{-1}([0,t])$$

$$\subset \mathcal{F}_t$$

So  $X_T$  is  $\mathcal{F}_T$  measurable and thus  $\mathcal{G} \subset \mathcal{F}_T$ .

### 2. Martingales

**Definition 2.1.** Let  $\{\mathcal{F}_t\}_{t\geq 0}$  be a filtration and M a process. The M is said to be a **submartingale** with respect to  $\{\mathcal{F}_t\}_{t\geq 0}$  if

- (1) M is adapted to  $\{\mathcal{F}_t\}_{t\geq 0}$
- (2) for each  $t \in [0, \infty)$ ,  $\mathbb{E}[\overline{|M_t|}] < \infty$
- (3) for each  $s, t \in [0, \infty)$ , if s < t, then  $\mathbb{E}[M_t | \mathcal{F}_s] \ge M_s$

Recall that the third condition means equal except on a null set.

**Definition 2.2.** Let  $\{\mathcal{F}_t\}_{t\geq 0}$  be a filtration and M a process. The M is said to be a **supermartingale** with respect to  $\{\mathcal{F}_t\}_{t\geq 0}$  if

- (1) M is adapted to  $\{\mathcal{F}_t\}_{t\geq 0}$
- (2) for each  $t \in [0, \infty)$ ,  $\mathbb{E}[|M_t|] < \infty$
- (3) for each  $s, t \in [0, \infty)$ , if s < t, then  $\mathbb{E}[M_t | \mathcal{F}_s] \le M_s$

**Definition 2.3.** Let  $\{\mathcal{F}_t\}_{t\geq 0}$  be a filtration and M a process. The M is said to be a **sub-martingale** with respect to  $\{\mathcal{F}_t\}_{t\geq 0}$  if -M is a supermartingale with respect to  $\{\mathcal{F}_t\}_{t\geq 0}$ 

**Definition 2.4.** Let  $\{\mathcal{F}_t\}_{t\geq 0}$  be a filtration and M a process. The M is said to be a **martingale** with respect to  $\{\mathcal{F}_t\}_{t\geq 0}$  if M is a submartingale with respect to  $\{\mathcal{F}_t\}_{t\geq 0}$  and M is a supermartingale with respect to  $\{\mathcal{F}_t\}_{t\geq 0}$ .

Theorem 2.5.

# 3. Brownian Motion

# Definition 3.1.