Gradient Descent in Hilbert Space

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Banach Spaces

Definition

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Let X, Y be a normed vector spaces and $T: X \to Y$ a linear map. Then T is said to be **bounded** if there exists $C \ge 0$ such that for each $x \in X$,

$$||Tx|| \leq C||x||$$

We define

$$L(X, Y) = \{T : X \rightarrow Y : T \text{ is linear and bounded}\}$$



Let X_1, \ldots, X_n and Y be a normed vector spaces and

$$T:\prod_{j=1}^n X_j o Y$$
 a multilinear linear map. Then T is said to be

bounded if there exists $C \ge 0$ such that for each $(x_j)_{j=1}^n \in \prod_{j=1}^n X_j$,

$$||T(x_1,...,x_n)|| \leq C||x_1||...||x_n||$$

We define

$$L^n(X_1,\ldots,X_n;Y)=\{T:X\to Y:T \text{ is multilinear and bounded}\}$$

If
$$X_1, \ldots, X_n = X$$
, we write $L^n(X, Y)$ in place of $L^n(X, \ldots, X; Y)$.

Remark

Let X and Y be normed vector spaces. We may identify $L(X,L(X,\ldots,L(X,Y))\ldots)$ and $L^n(X,Y)$ via the isometric isomorphism given by $\phi\mapsto\psi_\phi$ where

$$\psi_{\phi}(x_1,x_2,\ldots,x_n)=\phi(x_1)(x_2)\ldots(x_n)$$

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Let X be a normed vector space over \mathbb{R} . We define the **dual space** of X, denoted X^* , by $X^* = L(X, \mathbb{R})$. Let $T: X \to \mathbb{R}$. Then T is said to be a **bounded linear functional on** X if $T \in X^*$.

Let X, Y be a banach spaces, $A \subset X$ open, $f : A \to Y$ and $x_0 \in A$. Then f is said to be (1-st order) Frechet differentiable at x_0 if there exists $Df(x_0) \in L(X, Y)$ such that,

$$f(x_0 + h) = f(x_0) + Df(x_0)(h) + o(||h||)$$
 as $h \to 0$

If f is Frechet differentiable at x_0 , we define the **Frechet** derivative of f at x_0 to be $Df(x_0)$. We say that f is (1-st order) **Frechet differentiable** if for each $x_0 \in A$, f is Frechet differentiable at x_0 .

If f is Frechet differentiable, we define the **Frechet derivative** of f, denoted $Df: A \rightarrow L(X, Y)$, by

$$x \mapsto Df(x)$$

Continuing inductively,



Let X, Y be a banach spaces, $A \subset X$ open, $f : A \to Y$. We define n-th order Frechet differentiablility inductively.

If f is n-1-th order Frechet differentiable, f is said to be n-th order Frechet differentiable at x_0 if $D^{n-1}f$ is Frechet differentiable at x_0 . We define $D^nf(x_0)=D(D^{n-1}f)(x_0)$.

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Note that $D^n f(x_0) \in L^n(X, Y)$.

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- ▶ Hahn-Banach Theorem

Let X, Y be Banach spaces and $f \in L(X, Y)$. Then f is Frechet differentiable and for each $x_0 \in X$, $Df(x_0) = f$.

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Result

Let X, Y, Z be Banach spaces, $f: X \to Y$, $g: Y \to Z$ and $x_0 \in X$. If f is Frechet differentiable at x_0 and g is Frechet differentiable at $f(x_0)$, then $g \circ f$ is Frechet differentiable at x_0 and

$$D(g \circ f)(x_0) = Dg(f(x_0)) \circ Df(x_0)$$

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Result

Let X, Y be a Banach spaces, $A \subset X$ open and convex and $f: A \to Y$. If f is Frechet differentiable, then for each $x, y \in A$, there exists $t \in (0,1)$ such that

$$||f(x) - f(y)|| \le ||Df(tx + (1-t)y)|| ||x - y||$$



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Result

Let X be a Banach spaces, $A \subset X$ open, $f : A \to \mathbb{R}$ and $x_0 \in A$. Suppose that f is Frechet differentiable at x_0 . If f has a local minimum at x_0 , then $Df(x_0) = 0$.

Let Y be a separable Banach space and $f \in C^1_Y(a,b)$. Then for each $x, x_0 \in (a,b)$, $x_0 < x$ implies that

- 1. f' is Bochner integrable on $(x_0, x]$
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Let Y be a separable Banach space, $A \subset X$ open and convex, $f \in C^n_Y(A)$ and $x_0 \in A$. Then

$$f(x_0 + h) = \sum_{k=0}^{n} D^k f(x_0)(h, \dots, h) + o(\|h\|^n)$$
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Result

Let H be an inner product space. Then for each $x, y \in H$, $|\langle x, y \rangle| \le ||x|| ||y||$ with equality iff $x \in \text{span}(y)$.

Let H be a Hilbert space. Define $\phi: H \to H^*$ by $x \mapsto x^*$ where

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Result

Let H be a Hilbert space. Then $\phi: H \to H^*$ defined above is an isometric isomorphism.

Let H be a Hilbert space, $f: H \to \mathbb{R}$ and $x_0 \in H$. Suppose that f is Frechet differentiable at x_0 so that $Df(x_0) \in H^*$. We define the **gradient of** f **at** x_0 , denoted $\nabla f(x_0) \in H$, by

$$\nabla f(x_0) = \phi^{-1} D f(x_0)$$

That is, $\nabla f(x_0)$ is the unique element of H such that for each $y \in H$,

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Let H be a Hilbert space, $f: H \to \mathbb{R}$ and $x_0 \in H$. If f is Frechet differentiable at x_0 , then

$$\underset{\|h\| \le 1}{\arg \min} \, Df(x_0)(h) = -\|\nabla f(x_0)\|^{-1} \nabla f(x_0)$$



Remark

In the context of Hilbert spaces, the gradient allows us generalize the gradient descent method for minimization.

The idea is as follows. If $f: H \to \mathbb{R}$ is Frechet differentiable. Then

$$f(x_0 + h) \approx f(x_0) + \langle \nabla f(x_0), h \rangle$$

for h near 0. Taking $h = -\eta \nabla f(x_0)$ for some small $\eta > 0$ insures that h is close to 0 and h is in the direction of steepest descent of $Df(x_0)(v)$ which causes $f(x_0 + h) < f(x_0)$.

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Let X be a Banach space, $A \subset X$ open and convex, $f: A \to \mathbb{R}$ convex, $x_0 \in A$. Suppose that f is 2nd order Frechet differentiable at x_0 . If $D^2f(x_0) \in L^2(X,\mathbb{R})$ is positive semi definite (resp. pos. def.), then f is convex (resp. strictly convex).

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Remark

By positive definite, we mean $D^2f(x_0)(h,h) > 0$ for $h \neq 0$.



Reproducing Kernel Hilbert Spaces

Definition

Let T be a set and $H \subset \mathbb{R}^T$ a hilbert space. For $t \in T$, we define the **evauluation functional at** t, denoted $L_t : H \to \mathbb{R}$, by

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If H is an RKHS, we define the **reproducing kernel** associated to H, denoted $K_H: T^2 \to \mathbb{R}$, by

$$K_H(s,t) = \langle K_s, K_t \rangle$$

Let T be a set and $K: T^2 \to \mathbb{R}$. If K is symmetric and positive definite, then there exists a unique reproducing kernel Hilbert space $H \subset \mathbb{R}^T$ such that $K_H = K$.

Let T be a set, $K: T^2 \to \mathbb{R}$ a symmetric, postivie definite kernel on T, $H \subset \mathbb{R}^T$ the corresponding RKHS, $t = (t_j)_{j=1}^n \subset T$ and $y = (y_j)_{j=1}^n \subset \mathbb{R}$.

Let T be a set, $K: T^2 \to \mathbb{R}$ a symmetric, postivie definite kernel on T, $H \subset \mathbb{R}^T$ the corresponding RKHS, $t = (t_j)_{j=1}^n \subset T$ and $y = (y_j)_{j=1}^n \subset \mathbb{R}$. Define $L: H \to \mathbb{R}$ by

$$L(f) = \sum_{j=1}^{n} (y_j - f(t_j))^2 + \lambda ||f||^2$$

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Then there exist $(\hat{\alpha}_j)_{i=1}^n \subset \mathbb{R}$ such that

$$\hat{f}(t) = \sum_{i=1}^{n} \hat{\alpha}_{i} K(t, t_{i})$$

Define $A \in \mathbb{R}^{n \times n}$ by $A_{i,j} = K(t_i, t_j)$. Some regular calculus shows that $\hat{\alpha} = (A + \lambda I)^{-1} y$

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Question

What if $(A + \lambda I)^{-1}$ is hard to compute?

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Answer

gradient descent

Define $Q: H \to \mathbb{R}$ by

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We can write rewrite Q(f) as

$$Q(f) = ||L_t(f) - y||_2^2$$

where $L_t \in L(H, \mathbb{R}^n)$ is given by

$$L_t(f) = (f(t_j))_{j=1}^n$$

Writing this out, we see that

$$Q(f_0 + h) = ||L_t(f_0) - y||_2^2 + 2(L_t(f_0) - y)^T L_t(h) + ||L_t(h)||_2^2$$

= $Q(f_0) + [\text{lin funct of } h] + [\text{bilin funct of } (h, h)]$

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Equating terms from Taylors theorem, we see that $D^2Q(f_0)(h,h)=2\|L_t(h)\|_2^2$, which is p.s.d. So Q is convex. Since norms are convex and $\lambda\geq 0$, L is convex.

Similar to before, writing out $L(f_0 + h)$, we get

$$L(f_0 + h) = L(f_0) + 2(L_t(f_0) - y)^T L_t(h) + 2\lambda \langle f_0, h \rangle + o(\|h\|^2)$$

Similar to before, writing out $L(f_0 + h)$, we get

$$L(f_0 + h) = L(f_0) + 2(L_t(f_0) - y)^T L_t(h) + 2\lambda \langle f_0, h \rangle + o(\|h\|^2)$$

So

$$DL(f_0)(h) = 2(L_t(f_0) - y)^T L_t(h) + 2\lambda \langle f_0, h \rangle$$

$$= 2\sum_{j=1}^n (f_0(t_j) - y_j) \langle K_{t_j}, h \rangle + 2\lambda \langle f_0, h \rangle$$

$$= \left\langle 2 \left[\sum_{j=1}^n (f_0(t_j) - y_j) K_{t_j} + \lambda f_0 \right], h \right\rangle$$

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Hence

$$\nabla L(f_0) = 2 \left[\sum_{i=1}^{n} (f_0(t_i) - y_j) K_{t_j} + \lambda f_0 \right]$$

Applications to Gaussian Processes

Remark

Let T be a set and $x=(x_j)_{j=1}^n\in T^n$, $y=(y_j)_{j=1}^n\in \mathbb{R}^n$. From Gaussian processes, we know that if

$$y_i = f(x_i) + \epsilon_i$$

 $\epsilon_i \sim N(0, \sigma^2)$
 $f \sim GP(0, c)$

Then

$$f|x, y \sim GP(\tilde{\mu}, \tilde{c})$$

where

$$\tilde{\mu}(t) = c(t, x)[c(x, x) + \sigma^2 I]^{-1}y$$

and

$$\tilde{c}(s,t) = c(s,t) - c(s,x)[c(x,x) + \sigma^2 I]^{-1}c(x,t)$$

If $c(x,x) + \sigma^2 I$ is too costly to invert, we may set up the following convex optimization problem to approximate the posterior mean and posterior covariance functions:

$$\hat{h}(t) = \operatorname*{arg\,min}_{h \in H} \sum_{j=1}^{n} (y_j - h(t_j))^2 + \sigma^2 \|h\|_{H}$$

where H is the RKHS corresponding to the p.d. kernel c

References

- analysis notes
- ► integration notes
- ► RKHS's
- ► Representer Theorem