INTRODUCTION TO PROBABILITY

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1. Basic Probability

2. Probability

2.1. Distributions.

Definition 2.1.1. Let Ω be a set and $\mathcal{P} \subset \mathcal{P}(X)$. Then \mathcal{P} is said to be a π -system on Ω if for each $A, B \in \mathcal{P}$, $A \cap B \in \mathcal{P}$.

Definition 2.1.2. Let Om be a set and $\mathcal{L} \subset \mathcal{P}(\Omega)$. Then \mathcal{L} is said to be a λ -system on Ω if

- (1) $\mathcal{L} \neq \emptyset$
- (2) for each $A \in \mathcal{L}$, $A^c \in \mathcal{L}$
- (3) for each $(A_n)_{n\in\mathbb{N}}\subset\mathcal{L}$, if $(A_n)_{n\in\mathbb{N}}$ is disjoint, then $\bigcup_{n\in\mathbb{N}}A_n\in\mathcal{L}$

Exercise 2.1.3. Let Ω be a set and \mathcal{L} a λ -system on Ω . Then

 $(1) \Omega, \varnothing \in \mathcal{L}$

Proof. Straightforward.

Definition 2.1.4. Let Ω be a set and $\mathcal{C} \subset \mathcal{P}(\Omega)$. Put

$$\mathcal{S} = \{ \mathcal{L} \subset \mathcal{P}(\Omega) : \mathcal{L} \text{ is a } \lambda \text{-system on } \Omega \text{ and } \mathcal{C} \subset \mathcal{L} \}$$

We define the λ -system on Ω generated by \mathcal{C} , $\lambda(\mathcal{C})$, to be

$$\lambda(\mathcal{C}) = \bigcap_{\mathcal{L} \in \mathcal{S}} \mathcal{L}$$

Exercise 2.1.5. Let Ω be a set and $\mathcal{C} \subset \mathcal{P}(\Omega)$. If \mathcal{C} is a λ -system and \mathcal{C} is a π -system, then \mathcal{C} is a σ -algebra.

Proof. Suppose that \mathcal{C} is a λ -system and \mathcal{C} is a π -system. Then we need only verify the third axiom in the definition of a σ -algebra. Let $(A_n)_{n\in\mathbb{N}}\subset\mathcal{C}$. Define $B_1=A_1$ and for $n\geq 2$,

define
$$B_n = A_n \cap \left(\bigcup_{k=1}^{n-1} A_k\right)^c = A_n \cap \left(\bigcap_{k=1}^{n-1} A_k^c\right) \in \mathcal{C}$$
. Then $(B_n)_{n \in \mathbb{N}}$ is disjoint and therefore $\bigcup_{n \in \mathbb{N}} A_n = \bigcup_{n \in \mathbb{N}} B_n \in \mathcal{C}$.

Theorem 2.1.6. (Dynkin's Theorem)

Let Ω be a set.

- (1) Let \mathcal{P} be a π -system on Ω and \mathcal{L} a λ -system on Ω . If $\mathcal{P} \subset \mathcal{L}$, then $\sigma(\mathcal{P}) \subset \mathcal{L}$.
- (2) Let \mathcal{P} be a π -system on Ω . Then $\sigma(\mathcal{P}) = \lambda(\mathcal{P})$

Exercise 2.1.7. Let (Ω, \mathcal{F}) be a measurable space and μ, ν probability measures on (Ω, \mathcal{F}) . Put $\mathcal{L}_{\mu,\nu} = \{A \in \mathcal{F} : \mu(A) = \nu(A)\}$. Then $\mathcal{L}_{\mu,\nu}$ is a λ -system on Ω .

Proof.

- (1) $\varnothing \in \mathcal{L}_{\mu,\nu}$.
- (2) Let $A \in \mathcal{L}_{\mu,\nu}$. Then $\mu(A) = \nu(A)$. Thus

$$\mu(A^c) = 1 - \mu(A)$$
$$= 1 - \nu(A)$$
$$= \nu(A^c)$$

So $A^c \in \mathcal{L}_{\mu,\nu}$.

(3) Let $(A_n)_{n\in\mathbb{N}}\subset\mathcal{L}_{\mu,\nu}$. So for each $n\in\mathbb{N}$, $\mu(A_n)=\nu(A_n)$. Suppose that $(A_n)_{n\in\mathbb{N}}$ is disjoint. Then

$$\mu\left(\bigcup_{n\in\mathbb{N}} A_n\right) = \sum_{n\in\mathbb{N}} \mu(A_n)$$
$$= \sum_{n\in\mathbb{N}} \nu(A_n)$$
$$= \nu\left(\bigcup_{n\in\mathbb{N}} A_n\right)$$

Hence $\bigcup_{n\in\mathbb{N}} A_n \in \mathcal{L}_{\mu,\nu}$.

Exercise 2.1.8. Let (Ω, \mathcal{F}) be a measurable space, μ, ν probability measures on (Ω, \mathcal{F}) and $\mathcal{P} \subset \mathcal{A}$ a π -system on Ω . Suppose that for each $A \in \mathcal{P}$, $\mu(A) = \nu(A)$. Then for each $A \in \sigma(\mathcal{P})$, $\mu(A) = \nu(A)$.

Proof. Using the previous exercise, we see that $\mathcal{P} \subset \mathcal{L}_{\mu,\nu}$. Dynkin's theorem implies that $\sigma(\mathcal{P}) \subset \mathcal{L}_{\mu,\nu}$. So for each $A \in \sigma(\mathcal{P})$, $\mu(A) = \nu(A)$.

Definition 2.1.9. Let $F : \mathbb{R} \to \mathbb{R}$. Then F is said to be a **probability distribution** function if

- (1) F is right continuous
- (2) F is increasing
- (3) $F(-\infty) = 0$ and $F(\infty) = 1$

Definition 2.1.10. Let P be a probability measure on $(\mathbb{R}, \mathcal{B}(\mathbb{R}))$. We define $F_P : \mathbb{R} \to \mathbb{R}$, by

$$F_P(x) = P((-\infty, x])$$

We call F_P the probability distribution function of P.

Exercise 2.1.11. Let (Ω, \mathcal{F}, P) be a probability measure. Then F_P is a probability distribution function.

Proof. (1) Let $x \in \mathbb{R}$ and $(x_n)_{n \in \mathbb{N}} \subset [x, \infty)$. Suppose that $x_n \to x$. Then $(x, x_n] \to \emptyset$ because $\limsup_{n \to \infty} (x, x_n] = \emptyset$. Thus

$$F(x_n) - F(x) = P((x, x_n]) \to P(\emptyset) = 0$$

This implies that

$$F(x_n) \to F(x)$$

. So F is right continuous.

- (2) Clearly F_P is increasing.
- (3) Continuity from below tells us that

$$F(-\infty) = \lim_{n \to -\infty} F(n) = \lim_{n \to -\infty} P((-\infty, n]) = 0$$

and continuity from above tell us that

$$F(\infty) = \lim_{n \to \infty} F(n) = \lim_{n \to \infty} P((-\infty, n]) = 1$$

Exercise 2.1.12. Let μ, ν be probability measures on $(\mathbb{R}, \mathcal{B}(\mathbb{R}))$. Then $F_{\mu} = F_{\nu}$ iff $\mu = \nu$.

Proof. Clearly if $\mu = \nu$, then $F_{\mu} = F_{\nu}$. Conversely, suppose that $F_{\mu} = F_{\nu}$. Then for each $x \in \mathbb{R}$,

$$\mu((-\infty, x]) = F_{\mu}(x)$$

$$= F_{\nu}(x)$$

$$= \nu((-\infty, x])$$

Put $C = \{(-\infty, x] : x \in \mathbb{R}\}$. Then C is a π -system and for each $A \in C$, $\mu(A) = \nu(A)$. Hence for each $A \in \sigma(C) = \mathcal{B}(\mathbb{R})$, $\mu(A) = \nu(A)$. So $\mu = \nu$.

Definition 2.1.13. Let (Ω, \mathcal{F}, P) be a probability space and $X : \Omega \to \mathbb{R}^n$. Then X is said to be a **random vector** on (Ω, \mathcal{F}) if X is \mathcal{F} - $\mathcal{B}(\mathbb{R}^n)$ measurable. If n = 1, then X is said to be a **random variable**. We define

$$L_n^0(\Omega, \mathcal{F}, P) = \{X : \Omega \to \mathbb{R}^n : X \text{ is a random vector}\}$$

and

$$L_n^p(\Omega, \mathcal{F}, P) = \left\{ X \in L_n^0 : \int ||X||^p dP < \infty \right\}$$

Definition 2.1.14. Let (Ω, \mathcal{F}, P) be a probability space and X a random variable on (Ω, \mathcal{F}) . We define the **probability distribution** of $X, P_X : \mathcal{B}(R) \to [0, 1]$, to be the measure

$$P_X = X_*P$$

That is, for each $A \in \mathcal{B}(\mathbb{R})$,

$$P_X(A) = P(X^{-1}(F))$$

We define the **probability distribution function** of $X, F_X : \mathbb{R} \to [0, 1]$, to be

$$F_X = F_{P_X}$$

Definition 2.1.15. Let (Ω, \mathcal{F}, P) be a probability space and X a random variable on (Ω, \mathcal{F}) . If $P_X \ll m$, we define the **probability density** of X, $f_X : \mathbb{R} \to \mathbb{R}$, by

$$f_X = \frac{dP_X}{dm}$$

Exercise 2.1.16. Let (Ω, \mathcal{F}, P) be a probability space and $(X_n)_{n \in \mathbb{N}}$ be a sequence of random variables on (Ω, \mathcal{F}) . Then for each $x \in \mathbb{R}$,

$$\mathbb{P}\bigg(\liminf_{n\to\infty} X_n > x\bigg) \le \liminf_{n\to\infty} P(X_n > x)$$

Proof. Let $\omega \in \left\{ \liminf_{n \to \infty} X_n > x \right\}$. Then $x < \liminf_{n \to \infty} X_n(\omega) = \sup_{n \in \mathbb{N}} \left(\inf_{k \ge n} X_k(\omega) \right)$. So there exists $n^* \in \mathbb{N}$ such that $x < \inf_{k \ge n^*} X_k(\omega)$. Then for each $k \in \mathbb{N}$, $k \ge n^*$ implies that $x < X_k(\omega)$. So there exists $n^* \in \mathbb{N}$ such that for each $k \in \mathbb{N}$, $k \ge n^*$ implies that $\mathbf{1}_{\{X_k > x\}}(\omega) = 1$. Hence $\inf_{k \ge n^*} \mathbf{1}_{\{X_k > x\}}(\omega) = 1$. Thus $\liminf_{n \to \infty} \mathbf{1}_{\{X_k > x\}}(\omega) = \sup_{n \in \mathbb{N}} \left(\inf_{k \ge n} \mathbf{1}_{\{X_k > x\}}(\omega) \right) = 1$. Therefore

 $\omega \in \liminf_{n \to \infty} \{X_k > x\}$ and we have shown that

$$\left\{ \liminf_{n \to \infty} X_n > x \right\} \subset \liminf_{n \to \infty} \{X_k > x\}$$

Then

$$P\left(\liminf_{n\to\infty} X_n > x\right) \le P\left(\liminf_{n\to\infty} \{X_k > x\}\right)$$
$$\le \liminf_{n\to\infty} P(\{X_k > x\})$$

Definition 2.1.17. Let (Ω, \mathcal{F}, P) be a probability space and $X \in L^+(\Omega) \cup L^1$. Define the **expectation of X**, E[X], to be

$$E[X] = \int XdP$$

.

2.2. Independence.

Definition 2.2.1. Let (Ω, \mathcal{F}, P) be a probability space and $\mathcal{C} \subset \mathcal{F}$. Then \mathcal{C} is said to be **independent** if for each $(A_i)_{i=1}^n \subset \mathcal{C}$,

$$P\bigg(\bigcap_{k=1}^{n} A_k\bigg) = \prod_{k=1}^{n} P(A_k)$$

Definition 2.2.2. Let (Ω, \mathcal{F}, P) be a probability space and $\mathcal{C}_1, \dots, \mathcal{C}_n \subset \mathcal{F}$. Then $\mathcal{C}_1, \dots, \mathcal{C}_n$ are said to be **independent** if for each $A_1 \in \mathcal{C}_1, \dots, A_n \in \mathcal{C}_n, A_1, \dots, A_n$ are independent.

Note 2.2.3. We will explicitly say that for each $i = 1, \dots, n$, C_i is independent when talking about the independence of the elements of C_i to avoid ambiguity.

Definition 2.2.4. Let (Ω, \mathcal{F}, P) be a probability space and X_1, \dots, X_2 random variables on (Ω, \mathcal{F}) . Then X_1, \dots, X_n are said to be **independent** if for each $B_1, \dots, B_n \in \mathcal{B}(\mathbb{R})$, $X_1^{-1}B_1, \dots, X_n^{-1}B_n$ are independent.

Exercise 2.2.5. Let (Ω, \mathcal{F}, P) be a probability space and X_1, \dots, X_n random variables on (Ω, \mathcal{F}) . Then X_1, \dots, X_n are independent iff $\sigma(X_1), \dots, \sigma(X_n)$ are independent.

Proof. Suppose that X_1, \dots, X_n are independent. Let $A_1, \in \sigma(X_1), \dots, A_n \in \sigma(A_n)$. Then for each $i = 1, \dots, n$, there exists $B_i \in \mathcal{B}(\mathbb{R})$ such that $A_i = X_i^{-1}(B_i)$. Then A_1, \dots, A_n are independent. Hence $\sigma(X_1), \dots, \sigma(X_n)$ are independent. Conversely, suppose that $\sigma(X_1), \dots, \sigma(X_n)$ are independent. Let $B_1, \dots, B_n \in \mathcal{B}(\mathbb{R})$. Then for each $i = 1, \dots, n, X_i^{-1}B_i \in \sigma(X_i)$. Then $X_1^{-1}B_1, \dots, X_n^{-1}B_n$ are independent. Hence X_1, \dots, X_n are independent. \square

Exercise 2.2.6. Let (Ω, \mathcal{F}, P) be a probability space, X_1, \dots, X_n random variables on (Ω, \mathcal{F}) and $\mathcal{F}_1, \dots, \mathcal{F}_n \subset \mathcal{F}$ a collection of σ -algebras on Ω . Suppose that for each $i = 1, \dots, n, X_i$ is \mathcal{F}_i -measurable. If $\mathcal{F}_1, \dots, \mathcal{F}_n$ are independent, then X_1, \dots, X_n are independent.

Proof. For each $i=1,\cdots,n,\ \sigma(X_i)\subset\mathcal{F}_i$. So $\sigma(X_1),\cdots,\sigma(X_n)$ are independent. Hence X_1,\cdots,X_n are independent. \square

Exercise 2.2.7. Let (Ω, \mathcal{F}, P) be a probability space and $\mathcal{C}_1, \dots, \mathcal{C}_n \subset \mathcal{F}$. Suppose that for each $i = 1, \dots, n$, \mathcal{C}_i is a π -system and $\mathcal{C}_1, \dots, \mathcal{C}_n$ are independent, then $\sigma(\mathcal{C}_1), \dots, \sigma(\mathcal{C}_n)$ are independent.

Proof. Let $A_2 \in \mathcal{C}_2$. Define $\mathcal{L} = \{A \in \mathcal{F} : P(A \cap A_2) = P(A)P(A_2)\}$. Then

- (1) $\Omega \in \mathcal{L}$
- (2) If $A \in \mathcal{L}$, then

$$P(A^{c} \cap A_{2}) = P(A_{2}) - P(A_{2} \cap A)$$

$$= P(A_{2}) - P(A_{2})P(A)$$

$$= (1 - P(A))P(A_{2})$$

$$= P(A^{c})P(A_{2})$$

So $A^c \in \mathcal{L}$

(3) If $(B_n)_{n\in\mathbb{N}}\subset\mathcal{L}$ is disjoint, then

$$P\left(\left[\bigcup_{n\in\mathbb{N}}B_{n}\right]\cap A_{2}\right) = P\left(\bigcup_{n\in\mathbb{N}}B_{n}\cap A_{2}\right)$$

$$= \sum_{n\in\mathbb{N}}P(B_{n}\cap A_{2})$$

$$= \sum_{n\in\mathbb{N}}P(B_{n})P(A_{2})$$

$$= \left[\sum_{n\in\mathbb{N}}P(B_{n})\right]P(A_{2})$$

$$= P\left(\bigcup_{n\in\mathbb{N}}A_{n}\right)P(A_{2})$$

So
$$\bigcup_{n\in\mathbb{N}} B_n \in \mathcal{L}$$
.

Thus \mathcal{L} is a λ -system. Since $\mathcal{C}_1 \subset \mathcal{L}$ is a π -system, Dynkin's theorem tells us that $\sigma(\mathcal{C}_1) \subset \mathcal{L}$. Since $A_2 \in \mathcal{C}_2$ is arbitrary $\sigma(\mathcal{C}_1)$ and \mathcal{C}_2 are independent. The same reasoning implies that $\sigma(\mathcal{C}_1)$ and $\sigma(\mathcal{C}_2)$ are independent. Let $A_2 \in \mathcal{C}_1, \dots, A_n \in \mathcal{C}_n$ We may do the same process with

$$\mathcal{L} = \left\{ A \in \mathcal{F} : P\left(A \cap \left(\bigcap_{i=2}^{n} A_i\right)\right) = P(A) \prod_{i=2}^{n} P(A_i) \right\}$$

and conclude that $\sigma(\mathcal{C}_1), \mathcal{C}_2, \cdots, \mathcal{C}_n$ are independent. Which, using the same reasoning would imply that $\sigma(\mathcal{C}_1), \cdots, \sigma(\mathcal{C}_n)$ are independent.

Exercise 2.2.8. Let (Ω, \mathcal{F}, P) be a probability space, X_1, \dots, X_n random variables on (Ω, \mathcal{F}) . Then X_1, \dots, X_n are independent iff for each $x_1, \dots, x_n \in \mathbb{R}$,

$$P(X_1 \le x_1, \dots, X_n \le x_n) = \prod_{i=1}^n P(X_i \le x_i)$$

Proof. Suppose that X_1, \dots, X_n are independent. Then $\sigma(X_1), \dots, \sigma(X_n)$ are independent. Let $x_1, \dots, x_n \in \mathbb{R}$. Then for each $i = 1, \dots, n$, $\{X_i \leq x_i\} \in \sigma(X_i)$. Hence

 $P(X_1 \leq x_1, \dots, X_n \leq x_n) = \prod_{i=1}^n P(X_i \leq x_i)$. Conversely, suppose that for each

$$x_1, \dots, x_n \in \mathbb{R}, P(X_1 \le x_1, \dots, X_n \le x_n) = \prod_{i=1}^n P(X_i \le x_i). \text{ Define } \mathcal{C} = \{(-\infty, x] : x \in \mathbb{R}\}.$$

Then $\mathcal{B}(\mathbb{R}) = \sigma(\mathcal{C})$. For each $i = 1, \dots, n$, define $\mathcal{C}_i = X_i^{-1}\mathcal{C}$. Then for each $i = 1, \dots, n$, \mathcal{C}_i is a π -system and

$$\sigma(C_i) = \sigma(X^{-1}(C))$$

$$= X_i^{-1}(\sigma(C))$$

$$= X_i^{-1}(\mathcal{B}(\mathbb{R}))$$

$$= \sigma(X_i)$$

By assumption, C_1, \dots, C_n are independent. The previous exercise tells us that $\sigma(X_1), \dots, \sigma(X_n)$ are independent. Then X_1, \dots, X_n are independent.

Exercise 2.2.9. Let Let (Ω, \mathcal{F}, P) be a probability space and X_1, \dots, X_n random variables on (Ω, \mathcal{F}) . Define $X = (X_1, \dots, X_n)$. If X_1, \dots, X_n are independent, then

$$P_X = \prod_{i=1}^n P_{X_i}$$

.

Proof. Let $A_1, \dots, A_n \in \mathcal{B}(\mathbb{R})$. Then

$$P_X(A_1 \times \dots \times A_n) = P(X \in A_1 \times \dots \times \in A_n)$$

$$= P(X_1 \in A_1, \dots, X_n \in A_n)$$

$$= P(X_1 \in A_1) \dots P(X_n \in A_n)$$

$$= P_{X_1}(A_1) \dots P_{X_n}(A_n)$$

$$= \prod_{i=1}^n P_{X_i}(A_1 \times \dots \times A_n)$$

Put

$$\mathcal{P} = \{A_1 \times \cdots \times A_n : A_1 \in \mathcal{B}(R), \cdots, A_n \in \mathcal{B}(R)\}$$

Then \mathcal{P} is a π -system and

$$\sigma(\mathcal{P}) = \mathcal{B}(R) \otimes \cdots \otimes \mathcal{B}(R) = \mathcal{B}(\mathbb{R}^n)$$

A previous exercise then tells us that $P_X = \prod_{i=1}^n P_{X_i}$

Exercise 2.2.10. Let Let (Ω, \mathcal{F}, P) be a probability space, X_1, \dots, X_n random variables on (Ω, \mathcal{F}) and $f_1, \dots, f_n : \mathbb{R} \to \mathbb{R} \in L^0$. Suppose that $f_1 \circ X_1, \dots, f_n \circ X_n \in L^+(\Omega)$ or $f_1 \circ X_1, \dots, f_n \circ X_n \in L^1(\Omega)$. If X_1, \dots, X_n are independent, then

$$E[f_1(X_1)\cdots f_n(X_n)] = \prod_{i=1}^n E[f_i(X_i)]$$

Proof. Define the random vector $X: \Omega \to \mathbb{R}^n$ by $X = (X_1, \dots, X_n)$ and $g: \mathbb{R}^n \to \mathbb{R}$ by $g(x_1, \dots, x_n) = f_1(x_1) \dots f_n(x_n)$. Suppose that for each $i = 1, \dots, n, f_i \in L^+(\mathbb{R})$. Then $g \in L^+(\mathbb{R}^n)$ and by change of variables,

$$E[f_1(X_1)\cdots f_n(X_n)] = E[g(X)]$$

$$= \int_{\Omega} g \circ X dP$$

$$= \int_{\mathbb{R}^n} g(x) dP_X(x)$$

$$= \int_{R^n} g(x) d\prod_{i=1}^n P_{X_i}(x)$$

$$= \prod_{i=1}^n \int_{\mathbb{R}} f_i(x) dP_{X_i}(x)$$

$$= \prod_{i=1}^n \int_{\Omega} f_i \circ X dP$$

$$= \prod_{i=1}^n E[f_i(X_i)]$$

If for each $i = 1, \dots, n$, $f_i \in L^1(\mathbb{R}, P_{X_i})$, then following the above reasoning with |g| tells us that $g \in L^1(\mathbb{R}^n, P_X)$ and we use change of variables and Fubini's theorem to get the same result.

2.3. L^p Spaces for Probability.

Note 2.3.1. Recall that for a probability space (Ω, \mathcal{F}, P) and $1 \leq p \leq q \leq \infty$ we have $L^q \subset L^p$ and for each $X \in L^q$, $||X||_p \leq ||X||_q$. Also recall that for $X, Y \in L^2$, we have that $||XY||_1 \leq ||X||_2 ||X||_2$.

Definition 2.3.2. Let (Ω, \mathcal{F}, P) be a probability space and $X \in L^2$. Define the **variance** of X, Var(X), to be

$$Var(X) = E[(X - E[X])^{2}]$$

.

Definition 2.3.3. Let (Ω, \mathcal{F}, P) be a probability space and $X, Y \in L^2$. Define the

Definition 2.3.4. Let (Ω, \mathcal{F}, P) be a probability space and $X, Y \in L^2$. Define the **covariance of** X **and** Y, Cov(X, Y), to be

$$Cov(X,Y) = E[(X - E[X])(Y - E[Y])]$$

Exercise 2.3.5. Let (Ω, \mathcal{F}, P) be a probability space and $X, Y \in L^2$. Then the covariance is well defined and $Cov(X, Y)^2 \leq Var(X)Var(Y)$

Proof. By Holder's inequality,

$$|Cov(X,Y)| = \left| \int (X - E[X])(Y - E[Y])dP \right|$$

$$\leq \int |(X - E[X])(Y - E[Y])|dP$$

$$= ||(X - E[X])(Y - E[Y])||_{1}$$

$$\leq ||X - E[X]||_{2}||(Y - E[Y])||_{2}$$

$$= \left(\int |X - E[X]|^{2}dP \right)^{\frac{1}{2}} \left(|Y - E[Y]|^{2} \right)^{\frac{1}{2}}$$

$$= Var(X)^{\frac{1}{2}}Var(Y)^{\frac{1}{2}}$$

So $Cov(X, Y)^2 \leq Var(X)Var(Y)$.

Exercise 2.3.6. Let (Ω, \mathcal{F}, P) be a measure space and $X, Y \in L^2$. Then

- (1) Cov(X,Y) = E[XY] E[X]E[Y]
- (2) If X, Y are independent, then Cov(X,Y) = 0
- (3) $Var(X) = E[X^{2}] E[X]^{2}$
- (4) for each $a, b \in \mathbb{R}$, $Var(aX + b) = a^2 Var(X)$.
- (5) Var(X+Y) = Var(X) + Var(Y) + 2Cov(X,Y)

Proof.

(1) We have that

$$Cov(X,Y) = E[(X - E[X])(Y - E[Y])]$$

$$= E[XY - E[Y]X - E[X]Y + E[X]E[Y]]$$

$$= E[XY] - E[X]E[Y] - E[X]E[Y] + E[X]E[Y]$$

$$= E[XY] - E[X]E[Y]$$

(2) Suppose that X, Y are independent. Then E[XY] = E[X]E[Y]. Hence

$$Cov(X,Y) = E[XY] - E[X]E[Y]$$
$$= E[X]E[Y] - E[X]E[Y]$$
$$= 0$$

(3) Part (1) implies that

$$Var(X) = Cov(X, X)$$
$$= E[X^{2}] - E[X]^{2}$$

(4) Let $a, b \in \mathbb{R}$. Then

$$\begin{split} Var(aX+b) &= E[(aX+b)^2] - E[aX+b]^2 \\ &= E[a^2X^2 + 2abX + b^2] - (aE[X]+b)^2 \\ &= a^2E[X^2] + 2abE[X] + b^2 - (a^2E[X]^2 + 2abE[X] + b^2) \\ &= a^2(E[X^2] - E[X]^2) \\ &= a^2Var(X) \end{split}$$

(5) We have that

$$\begin{split} Var(X+Y) &= E[(X+Y)^2] - E[X+Y]^2 \\ &= E[X^2 + 2XY + Y^2] - (E[X] + E[Y])^2 \\ &= E[X^2] + 2E[XY] + E[Y^2] - (E[X]^2 + 2E[X]E[Y] + E[Y]^2) \\ &= (E[X^2] - E[X]^2) + (E[Y^2] - E[Y]^2) + 2(E[XY] - E[X]E[Y]) \\ &= Var(X) + Var(Y) + 2Cov(X, Y) \end{split}$$

Definition 2.3.7. Let (Ω, \mathcal{F}, P) be a probability space and $X, Y \in L^2$. The **correlation** of **X** and **Y**, Cor(X, Y), is defined to be

$$Cor(X,Y) = \frac{Cov(X,Y)}{\sqrt{Var(X)Var(Y)}}$$

Exercise 2.3.8.

Exercise 2.3.9. Jensen's Inequality Let (Ω, \mathcal{F}, P) be a probability space, $X \in L^1$ and $\phi : \mathbb{R} \to \mathbb{R}$. If ϕ is convex, then

$$\phi(E[X]) \le E[\phi(X)]$$

Proof. Put $x_0 = E[X]$. Since ϕ is convex, there exist $a, b \in \mathbb{R}$ such that $\phi(x_0) = ax_0 + b$ and for each $x \in \mathbb{R}$, $\phi(x) \ge ax + b$. Then

$$E[\phi(X)] = \int \phi(X)dP$$

$$\geq \int [aX + b]dP$$

$$= a \int XdP + b$$

$$= aE[X] + b$$

$$= ax_0 + b$$

$$= \phi(x_0)$$

$$= \phi(E[X])$$

Exercise 2.3.10. Markov's Inequality: Let (Ω, \mathcal{F}, P) be a probability space and $X \in L^+$. Then for each $a \in (0, \infty)$,

$$P(X \ge a) \le \frac{E[X]}{a}$$

Proof. Let $a \in (0, \infty)$. Then $a\mathbf{1}_{\{X \geq a\}} \leq X\mathbf{1}_{\{X \geq a\}}$. Thus

$$aP(X \ge a) = \int a\mathbf{1}_{\{X \ge a\}} dP$$
$$= \int X\mathbf{1}_{\{X \ge a\}} dP$$
$$\leq \int X dP$$
$$= E[X]$$

Therefore

$$P(X \ge a) \le \frac{E[X]}{a}$$

.

Exercise 2.3.11. Chebychev's Inequality: Let (Ω, \mathcal{F}, P) be a probability space and $X \in L^2$. Then for each $a \in (0, \infty)$,

$$P(|X - E[X]| \ge a) \le \frac{Var(X)}{a^2}$$

Proof. Let $a \in (0, \infty)$. Then

$$\begin{split} P(|X-E[X]| \geq a) &= P((X-E[X])^2 \geq a^2) \\ &\leq \frac{E[(X-E[X])^2]}{a^2} \\ &= \frac{Var(X)}{a^2} \end{split}$$

Exercise 2.3.12. Chernoff's Bound: Let (Ω, \mathcal{F}, P) be a probability space and $X \in L^2$. Then for each $a, t \in (0, \infty)$,

$$P(X \ge a) \le e^{-ta} E[e^{tX}]$$

Proof. Let $a, t \in (0, \infty)$. Then

$$P(X \ge a) = P(tX \ge ta)$$
$$= P(e^{tX} \ge e^{ta})$$
$$\le e^{-ta}E[e^{tX}]$$

Exercise 2.3.13. Weak Law of Large Numbers: Let (Ω, \mathcal{F}, P) be a probability space $(X_i)_{i \in \mathbb{N}} \subset L^2$. Suppose that $(X_i)_{i \in \mathbb{N}}$ are iid. Then

$$\frac{1}{n} \sum_{i=1}^{n} X_i \xrightarrow{P} E[X_1]$$

Proof. Put $\mu = E[X_1]$ and $\sigma^2 = Var(X_1)$. Then

$$E[\frac{1}{n}\sum_{i=1}^{n} X_{i}] = \frac{1}{n}\sum_{i=1}^{n} E[X_{i}]$$

$$= \frac{1}{n}\sum_{i=1}^{n} \mu$$

$$= \mu$$

and

$$Var(\frac{1}{n}\sum_{i=1}^{n}X_i) = \frac{1}{n^2}Var(\sum_{i=1}^{n}X_i)$$
$$= \frac{1}{n^2}\sum_{i=1}^{n}Var(X_i)$$
$$= \frac{1}{n^2}\sum_{i=1}^{n}\sigma^2$$
$$= \frac{\sigma^2}{n}$$

Let $\epsilon > 0$. Then

$$P\left(\left|\frac{1}{n}\sum_{i=1}^{n}X_{i} - E[X_{1}]\right| \ge \epsilon\right) = P\left(\left|\frac{1}{n}\sum_{i=1}^{n}X_{i} - \mu\right| \ge \epsilon\right)$$

$$= P\left(\left|\frac{1}{n}\sum_{i=1}^{n}X_{i} - E\left[\frac{1}{n}\sum_{i=1}^{n}X_{i}\right]\right| \ge \epsilon\right)$$

$$\le \frac{Var\left(\frac{1}{n}\sum_{i=1}^{n}X_{i}\right)}{\epsilon^{2}}$$

$$= \frac{\sigma^{2}/n}{\epsilon^{2}}$$

$$= \frac{\sigma^{2}}{n\epsilon^{2}} \to 0$$

So

$$\frac{1}{n} \sum_{i=1}^{n} X_i \xrightarrow{P} E[X_1]$$

2.4. Borel Cantelli Lemma.

Exercise 2.4.1. Borel Cantelli Lemma:

Let (Ω, \mathcal{F}, P) be a probability space and $(A_n)_{n \in \mathbb{N}} \subset \mathcal{F}$.

- (1) If $\sum_{n\in\mathbb{N}} P(A_n) < \infty$, then $P(\limsup_{n\to\infty} A_n) = 0$. (2) If $(A_n)_{n\in\mathbb{N}}$ are independent and $\sum_{n\in\mathbb{N}} P(A_n) = \infty$, then $P(\limsup_{n\to\infty} A_n) = 1$

Proof.

(1) Suppose that $\sum_{n\in\mathbb{N}} P(A_n) < \infty$. Recall that

$$\limsup_{n \to \infty} A_n = \left\{ \omega \in \Omega : \sum_{n \in \mathbb{N}} 1_{A_n}(\omega) = \infty \right\}$$

Then

$$\infty > \sum_{n \in \mathbb{N}} P(A_n)$$

$$= \sum_{n \in \mathbb{N}} \int 1_{A_n} dP$$

$$= \int \sum_{n \in \mathbb{N}} 1_{A_n} dP$$

Thus $\sum_{n\in\mathbb{N}} 1_{A_n} < \infty$ a.e. and $P(\limsup_{n\to\infty} A_n) = 0$. (2) Suppose that $(A_n)_{n\in\mathbb{N}}$ are independent and $\sum_{n\in\mathbb{N}} P(A_n) = \infty$.

Exercise 2.4.2. Let (Ω, \mathcal{F}, P) be a probability space and $(X_n)_{n \in \mathbb{N}} \subset L^0$ and $X \in L^0$.

- (1) If for each $\epsilon > 0$, $\sum_{n \in \mathbb{N}} P(|X_n X| \ge \epsilon) < \infty$, then $X_n \to X$ a.e.
- (2) If $(X_n)_{n\in\mathbb{N}}$ are independent and there exists $\epsilon > 0$ such that $\sum_{n\in\mathbb{N}} P(|X_n X| \ge \epsilon) = \infty$, then $X_n \not\to X$ a.e.

Proof.

(1) For $\epsilon > 0$ and $n \in \mathbb{N}$, set $A_n(\epsilon) = \{\omega \in \Omega : |X_n(\omega) - X(\omega)| \ge \epsilon\}$. Suppose that for each $\epsilon > 0$, $\sum_{n \in \mathbb{N}} P(|X_n - X| \ge \epsilon) < \infty$. The Borel-Cantelli lemma implies that for each $m \in \mathbb{N}$,

$$P(\limsup_{n\to\infty} A_n(1/m)) = 0$$

Let $\omega \in \Omega$. Then $X_n(\omega) \not\to X(\omega)$ iff

$$\omega \in \bigcup_{m \in \mathbb{N}} \limsup_{n \to \infty} A_n(1/m)$$

So

$$P(X_n \not\to X) = P\bigg(\bigcup_{m \in \mathbb{N}} \limsup_{n \to \infty} A_n(1/m)\bigg)$$

$$\leq \sum_{m \in \mathbb{N}} P(\limsup_{n \to \infty} A_n(1/m))$$

$$= 0$$

Hence $X_n \to X$ a.e.

(2)

3. Probability on locally compact Groups

Note 3.0.1. In this section, familiarity with Haar measure will be assumed. This section is intended as a continuation of section 7 of [3].

3.1. Action on Probability Measures.

Note 3.1.1. We recall some notation from section 7.1 of [3].

- $l_g \in \text{Homeo}(G), \ l_g(x) = gc$ $L_g \in \text{Sym}(L_0(G)), \ L_g f = f \circ l_g^{-1}$ We continue from section 7

Note 3.1.2. The next exercise generalizes the notion of a scale-family.

Exercise 3.1.3. Let (Ω, \mathcal{F}, P) be a probability space, G a locally compact group, μ a left Haar measure on $G, X \in L_G^0$ and $g \in G$. If $P_X \ll \mu$, then $f_{gX} = L_g f_X$.

Proof. Suppose that $P_X \ll \mu$. Let $A \in \mathcal{B}(G)$. Then

$$P_{gX}(A) = P(gX \in A)$$

$$= P(X \in g^{-1}A)$$

$$= P_X(g^{-1}A)$$

$$= P_X(l_g^{-1}(A))$$

$$= l_{g_*}P_X(A)$$

$$= g \cdot P_X(A)$$

The previous exercise tells us that $f_{gX} = L_g f_X$.

4. Weak Convergence of Measures

5. CONDITIONAL EXPECTATION AND PROBABILITY

5.1. Conditional Expectation.

Exercise 5.1.1. Doob-Dynkin Lemma:

Let Ω be a nonempty set, (Ω', \mathcal{F}') a measurable space $X : \Omega \to \Omega'$ and $Z : \Omega \to \mathbb{R}^n$. Suppose that Im $X \in \mathcal{F}'$. Then Z is $\sigma(X)$ - $\mathcal{B}(\mathbb{R}^n)$ measurable iff there exists $\phi : \Omega' \to \mathbb{R}^n$ such that ϕ is \mathcal{F}' - $\mathcal{B}(\mathbb{R}^n)$ measurable and $Z = \phi \circ X$.

Proof. Suppose that there exists $\phi: \Omega' \to \mathbb{R}^n$ such that ϕ is \mathcal{F}' - $\mathcal{B}(\mathbb{R}^n)$ measurable and $Z = Y \circ X$. Since X is $\sigma(X)$ - \mathcal{F}' measurable, $Z = \phi \circ X$ is $\sigma(X)$ - $\mathcal{B}(\mathbb{R}^n)$ measurable. Conversely, suppose that Z is $\sigma(X)$ - $\mathcal{B}(\mathbb{R}^n)$ measurable. For now, suppose that n = 1 and N is simple. Then there exists a partition $(A_i)_{i=1}^k \subset \sigma(X)$ of Ω and $(a_i)_{i=1}^k \in \mathbb{R}$ such that

$$Z = \sum_{i=1}^{k} a_i 1_{A_i}$$

By definition of $\sigma(X)$, there exists a partition $(B_i)_{i=1}^k \subset \mathcal{F}'$ such that for each $i=1,\dots,k$, $A_i=X^{-1}(B_i)$. Define

$$\phi = \sum_{i=1}^{k} a_i 1_{B_i}$$

Since $(B_i)_{i=1}^k$ partitions Ω' ,

$$\phi \circ X = \sum_{i=1}^{k} a_i 1_{X^{-1}(B_i)}$$
$$= \sum_{i=1}^{k} a_i 1_{A_i}$$
$$= Z$$

More generally, if Z is $\sigma(X)$ - $\mathcal{B}(\mathbb{R})$ measurable, there exits a sequence $(Z_j)_{j\in\mathbb{N}}$ of simple $\sigma(X)$ - $\mathcal{B}(\mathbb{R})$ measurable functions such that for each $j\in N$ $0\leq |Z_j|\leq |Z_{j+1}|\leq |Z|$ and $Z_j\xrightarrow{\text{p.w.}} Z$.

Therefore, as shown previously, there exists a sequence $(\phi_j)_{j\in\mathbb{N}}$ of \mathcal{F}' - $\mathcal{B}(\mathbb{R})$ -measurable simple functions such that for each $j\in\mathbb{N},\ Z_j=\phi_j\circ X$. Let $b\in\mathrm{Im}\,X$. Then there exists $a\in\Omega$ such that X(a)=b. So

$$\phi_j(b) = \phi_j \circ X(a)$$
$$= Z_j(a)$$
$$\to Z(a)$$

Thus we may define $\phi: \Omega' \to \mathbb{R}$ by

$$\phi = \lim_{j \to \infty} \phi_j 1_{\operatorname{Im} X}$$

Then ϕ is measurable since $\operatorname{Im} X \in \mathcal{F}'$ and $Z = \phi \circ X$. For $n \geq 1$, we may write $Z = (Z_1, \dots, Z_n)$ where for each $i = 1, \dots, n$, Z_i is $\sigma(X) - \mathcal{B}(\mathbb{R})$ measurable and apply the result from above to obtain $\phi = (\phi_1, \dots, \phi_n)$ where for each $i = 1, \dots, n$, ϕ_i is $\mathcal{F}' - \mathcal{B}(\mathbb{R})$ measurable and $Z_i = \phi_i \circ X$. Then $Z = \phi \circ X$.

Exercise 5.1.2. Let (Ω, \mathcal{F}, P) be a probability space, \mathcal{G} a sub σ -alg of \mathcal{F} and $X \in L^1(\Omega, \mathcal{F}, P)$. Define $P_{\mathcal{G}} = P|_{\mathcal{G}}$ and $Q : \mathcal{G} \to [0, \infty)$ by $Q(G) = \int_G X dP$. Then $Q \ll P_{\mathcal{G}}$.

Proof. Let $G \in \mathcal{G}$. Suppose that $P_{\mathcal{G}}(G) = 0$. By definition, P(G) = 0. So Q(G) = 0 and $Q \ll P_{\mathcal{G}}$.

Definition 5.1.3. Let (Ω, \mathcal{F}, P) be a probability space, \mathcal{G} a sub σ -alg of \mathcal{F} and $X, Y \in L^1(\Omega, \mathcal{F}, P)$. Then Y is said to be a **conditional expectation of** X **given** \mathcal{G} if

- (1) Y is \mathcal{G} -measurable
- (2) for each $G \in \mathcal{G}$,

$$\int_{G} Y dP = \int_{G} X dP$$

To denote this, we write $Y = E[X|\mathcal{G}]$

Exercise 5.1.4. Existence of Conditional Expectation:

Let (Ω, \mathcal{F}, P) be a probability space, \mathcal{G} a sub σ -alg of \mathcal{F} and $X \in L^1(\Omega, \mathcal{F}, P)$. Define Q and $P_{\mathcal{G}}$ as in the previous exercise. Define $Y = dQ/dP_{\mathcal{G}}$. Then Y is a conditional expectation of X given \mathcal{G} .

Proof. The Radon-Nikodym theorem implies that Y is \mathcal{G} -measurable. Since Q is finite, so is |Q|. Since d|Q| = |Y| dP, we have that $Y \in L^1(\Omega, \mathcal{G}, P_{\mathcal{G}})$. An exercise in section 3.3 of [3], implies that for each $G \in \mathcal{G}$

$$\int_{G} Y dP = \int_{G} Y dP_{\mathcal{G}}$$
$$= Q(G)$$
$$= \int_{G} X dP$$

Exercise 5.1.5. Let (Ω, \mathcal{F}, P) be a probability space, (S, \mathcal{S}) a measurable space, $X \in L^1(\Omega, \mathcal{F}, P)$ and $\Theta \in L^0_S(\Omega, \mathcal{F})$. Suppose that for each $\theta \in S$, $\{\theta\} \in \mathcal{S}$. Then there exists $h \in L^0(S, \mathcal{S})$ such that for each $B \in \mathcal{S}$,

$$\int_{\Theta^{-1}(B)} X \, dP = \int_B h \, dP_{\Theta}$$

5.2. Conditional Probability.

Definition 5.2.1. Let (A, \mathcal{A}) be a measurable space, (B, \mathcal{B}, P_Y) a probability space and $Q: B \times \mathcal{A} \to [0, 1]$. Then Q is said to be a **stochastic transition kernel from** (B, \mathcal{B}, P) **to** (A, \mathcal{A}) if

- (1) for each $E \in \mathcal{A}$, $Q(\cdot, E)$ is \mathcal{B} -measurable
- (2) for P-a.e. $b \in B$, $Q(b, \cdot)$ is a probability measure on (A, A)

Definition 5.2.2. Let (Ω, \mathcal{F}, P) be a probability space, $X, Y \in L_n^0(\Omega, \mathcal{F}, P)$ and $Q : \mathbb{R}^n \times \mathcal{F} \to [0, 1]$. Then Q is said to be a **conditional probability distribution of** X **given** Y if

(1) Q is a stochastic transition kernel from $(\mathbb{R}^n, \mathcal{B}(\mathbb{R}^n), P_Y)$ to $(\mathbb{R}^n, \mathcal{B}(\mathbb{R}^n))$

(2) for each $A, B \in \mathcal{F}$,

$$\int_{B} Q(y, A)dP_{Y}(y) = P(X \in A, Y \in B)$$

Note 5.2.3. It is helpful to connect this notion of conditional probability with the elementary one by writing $Q(y, A) = P(X \in A|Y = y)$. If $P_Y \ll \mu$, then property (2) in the definition becomes

$$P(X \in A, Y \in B) = \int_{B} Q(y, A) dP_{Y}(y)$$
$$= \int_{B} P(X \in A | Y = y) f_{Y}(y) d\mu(y)$$

as in a first course on probability.

Exercise 5.2.4. Let (Ω, \mathcal{F}, P) be a probability space, $X, Y \in L_n^0$ and $Q : \mathbb{R}^n \times \mathcal{F} \to [0, 1]$. Suppose that for each $A \in \mathcal{F}$, $Q(\cdot, A)$ is $\mathcal{B}(\mathbb{R}^n)$ -measurable, for P_Y -a.e. $y \in \mathbb{R}^n$, $P_{X|Y}(y, \cdot)$ is a probability measure on (Ω, \mathcal{F}) and $Q(Y, A) = P(X \in A|Y)$ a.e. Then Q is a conditional probability of X given Y.

Proof. By assumption, for each $A \in \mathcal{F}$, $Q(\cdot, A)$ is $\mathcal{B}(\mathbb{R}^n)$ -measurable and for P_Y -a.e. $y \in \mathbb{R}^n$, $Q(y, \cdot)$ is a probability measure on (Ω, \mathcal{F}) . Let $A, B \in \mathcal{F}$. Then

$$\int_{B} Q(y, A)dP_{Y}(y) = \int_{Y^{-1}(B)} Q(Y(\omega), A)dP(\omega)$$

$$= \int_{Y^{-1}(B)} P(X \in A|Y)dP$$

$$= \int_{Y^{-1}(B)} E[1_{X^{-1}(A)}|Y]dP$$

$$= \int_{Y^{-1}(B)} 1_{X^{-1}(A)}dP$$

$$= \int 1_{X^{-1}(A)} 1_{Y^{-1}(B)}dP$$

$$= \int 1_{X^{-1}(A)\cap Y^{-1}(B)}dP$$

$$= P(X \in A, Y \in B)$$

So Q is a conditional probability distribution of X given Y.

Definition 5.2.5. Let (Ω, \mathcal{F}, P) be a probability space, $X, Y \in L_n^0$ and μ a σ -finite measure on $(\mathbb{R}^n, \mathcal{B}(\mathbb{R}^n))$. Suppose that $P_X, P_Y \ll \mu$. Then $P_{X,Y} \ll \mu^2$. Let $f_X = dP_X/d\mu$, $f_Y = dP_Y/d\mu$ and $f_{X,Y} = dP_{X,Y}/d\mu^2$. Define $f_{X|Y} : \mathbb{R}^n \times \mathbb{R}^n$ by

$$f_{X|Y}(x,y) = \begin{cases} \frac{f_{X,Y}(x,y)}{f_Y(y)}, & y \in \text{supp } Y \\ 0, & y \notin \text{supp } Y \end{cases}$$

Then $f_{X|Y}$ is called the **conditional probability density of** X **given** Y.

Exercise 5.2.6. Let (Ω, \mathcal{F}, P) be a probability space, $X, Y \in L_n^0$ and μ a σ -finite measure on $(\mathbb{R}^n, \mathcal{B}(\mathbb{R}^n))$. Suppose that $P_X, P_Y \ll \mu$. Define $Q : \mathbb{R}^n \times \mathcal{F} \to [0, 1]$ by

$$Q(y,A) = \int_{A} f_{X|Y}(x,y) d\mu(x)$$

Then Q is a conditional probability distribution of X given Y.

Proof. By the Fubini-Tonelli Theorem, for each $A \in \mathcal{F}$, $Q(\cdot, A)$ is $\mathcal{B}(\mathbb{R}^n)$ -measurable and for P_Y -a.e. $y \in \mathbb{R}^n$, $Q(y, \cdot)$ is a probability measure on (Ω, \mathcal{F}) . Let $A, B \in \mathcal{F}$. Then

$$\int_{B} Q(y, A) dP_{Y}(y) = \int_{B} \left[\int_{A} f_{X|Y}(x, y) d\mu(x) \right] dP_{Y}(y)
= \int_{B \cap \text{supp } Y} \left[\int_{A \cap \text{supp } Y} \frac{f_{X,Y}(x, y)}{f_{Y}(y)} d\mu(x) f_{Y}(y) \right] d\mu(y)
= \int_{B \cap \text{supp } Y} \left[\int_{A} f_{X,Y}(x, y) d\mu(x) \right] d\mu(y)
= P(X \in A, Y \in B \cap \text{supp } Y)
= P(X \in A, Y \in B)$$

Theorem 5.2.7. Let (Ω, \mathcal{F}, P) be a probability space, $X, Y \in L_n^1(\Omega, \mathcal{F}, P)$. Suppose that $\operatorname{Im} X \in \mathcal{B}(\mathbb{R}^n)$. Then there exists a conditional probability distribution of Y given X.

6. Markov Chains

Definition 6.0.1. Let (Ω, \mathcal{F}, P) be a probability space and $(X_n)_{n \in \mathbb{N}_0} \in L_n^0$. Then $(X_n)_{n \in \mathbb{N}_0}$ is said to be a **homogeneous Markov chain** if for each $A \in \mathcal{F}$ and $n \in \mathbb{N}$, $P(X_n \in A|X_1, \dots, X_{n-1}) = P(X_1 \in A|X_0)$ a.e.

7. STOCHASTIC INTEGRATION

Exercise 7.0.1. Let (Ω, \mathcal{F}, P) be a probability space, X a set \mathcal{A}_0 an algebra, $\mu_0 : \mathcal{A}_0 \to \mathbb{C}$ and $B : \mathcal{A}_0 \to L^2(\Omega, \mathcal{F}, P)$. Suppose that

- (1) $B(\varnothing) = 0$
- (2) for each $E, F \in \mathcal{A}_0$, if $E \cap F = \emptyset$, then $B(E \cup F) = B(E) + B(F)$
- (3) $E[B(E)B(F)^*] = \mu_0(E \cap F)$

Then

- (1) for each $E \in \mathcal{A}_0$, $\mu_0(E) = E[|B(E)|^2]$.
- (2) for each $E \in \mathcal{A}_0$, $0 \le \mu_0(E) < \infty$
- (3) for each $E, F \in \mathcal{A}_0$, if $E \cap F = \emptyset$, then $\mu_0(E \cup F) = \mu_0(E) + \mu_0(F)$

Proof.

- (1) Clear
- (2) Clear
- (3) Let $E, F \in \mathcal{A}_0$. Suppose that $E \cap F = \emptyset$. Then

$$E[B(E)B(F)^*] = \mu_0(E \cap F)$$

$$= \mu_0(\varnothing)$$

$$= E[|B(\varnothing)|^2]$$

$$= E[0]$$

$$= 0$$

This implies that

$$\mu_0(E \cup F) = \mathbb{E}[|B(E \cup F)|^2]$$

$$= \mathbb{E}[|B(E) + B(F)|^2]$$

$$= \mathbb{E}[|B(E)|^2] + \mathbb{E}[|B(F)|^2] + 2\text{ReE}[B(E)B(F)^*]$$

$$= \mu_0(E) + \mu_0(F) + 0$$

$$= \mu_0(E) + \mu_0(F)$$

Definition 7.0.2. Let (Ω, \mathcal{F}, P) be a probability space, X a set \mathcal{A}_0 an algebra, $\mu_0 : \mathcal{A}_0 \to [0, \infty)$ a premeasure and $B : \mathcal{A}_0 \to L^2(\Omega, \mathcal{F}, P)$. Suppose that

- (1) $B(\emptyset) = 0$
- (2) for each $E, F \in \mathcal{A}_0$, if $E \cap F = \emptyset$, then $B(E \cup F) = B(E) + B(F)$
- (3) $E[B(E)B(F)^*] = \mu_0(E \cap F)$

Then B is said to be a stochastic premeasure with sturcture μ_0

References

- Introduction to Analysis
 Introduction to Group Theory
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