Introduction to Differential Geometry

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Notation

 $\begin{array}{ll} \mathcal{M}_+(X,\mathcal{A}) & \text{ finite measures on } (X,\mathcal{A}) \\ v & \text{ velocity} \end{array}$

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Preface

cc-by-nc-sa

2 Notation

Chapter 1

Review of Fundamentals

1.1 Set Theory

Definition 1.1.0.1. Let $\{A_i\}_{i\in I}$ be a collection of sets. The **disjoint union of** $\{A_i\}_{i\in I}$, denoted $\coprod_{i\in I} A_i$, is defined by

$$\coprod_{i \in I} A_i = \bigcup_{i \in I} \{i\} \times A_i$$

We define the **natural projection map**, denoted $\pi: \coprod_{i \in I} A_i \to I$, by $\pi(i, a) = i$.

Definition 1.1.0.2. Let E and M be sets, $\pi: E \to B$ a surjection and $\sigma: B \to E$. Then σ is said to be a section of (E, M, π) if $\pi \circ \sigma = \mathrm{id}_M$.

Note 1.1.0.3. Let $\{A_i\}_{i\in I}$ be a collection of sets and $\sigma:I\to\coprod_{i\in I}A_i$. We will typically be interested in sections σ of $\left(\coprod_{i\in I}A_i,I,\pi\right)$.

Exercise 1.1.0.4. Let $\{A_i\}_{i\in I}$ be a collection of sets and $\sigma: I \to \coprod_{i\in I} A_i$. Then σ is a section of $\coprod_{i\in I} A_i$ iff for each $i\in I$, $\sigma(i)\in A_i$

Proof. Clear. \Box

1.2 Linear Algebra

Note 1.2.0.1. We denote the standard basis on \mathbb{R}^n by (e_1, \ldots, e_n) .

Definition 1.2.0.2. Let $A \in \mathbb{R}^{n \times n}$. Then A is said to be **invertible** if $\det(A) \neq 0$. We denote the set of $n \times n$ invertible matrices by $GL(n,\mathbb{R})$.

Exercise 1.2.0.3. Let $A, B \in \mathbb{R}^{n \times n}$. Then AB = I iff BA = I.

Proof.

• (\Longrightarrow): Suppose that AB = I. Then

$$\ker B \subset \ker AB \\
= \ker I \\
= \{0\}$$

so that $\ker B = \{0\}$. Hence $\operatorname{Im} B = \mathbb{R}^n$ and B is surjective. Then

$$IB = BI$$
$$= B(AB)$$
$$= (BA)B$$

Since B is surjective, I = BA.

• (\Leftarrow) : Immediate by the previous part.

Definition 1.2.0.4. Let $A \in \mathbb{R}^{n \times p}$. Then A is said to be an **orthogonal matrix** if $A^*A = I$. We denote the set of $n \times p$ orthogonal matrices by O(n, p). We write O(n) in place of O(n, n).

Exercise 1.2.0.5. Define $\phi: S_n \to GL(n, \mathbb{R})$ by

$$\phi(\sigma) = \begin{pmatrix} e_{\sigma(1)}^* \\ \vdots \\ e_{\sigma(n)}^* \end{pmatrix}$$

Then

1. for each $A \in \mathbb{R}^{n \times p}$,

$$(\phi(\sigma)A)_{i,j} = A_{\sigma(i),j}$$

i.e. left multiplying A by $\phi(\sigma)$ the the same as permuting the rows of A by σ

2. ϕ is a group homomorphism

Proof. 1. Let $A \in \mathbb{R}^{n \times p}$. Then

$$(\phi(\sigma)A)_{i,j} = \langle e^*_{\sigma(i)}, Ae_j \rangle$$
$$= A_{\sigma(i),j}$$

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2. Let $\sigma, \tau \in S_n$. Part (1) implies that

$$\phi(\sigma\tau) = \begin{pmatrix} e^*_{\sigma\tau(1)} \\ \vdots \\ e^*_{\sigma\tau(n)} \end{pmatrix}$$

$$= \begin{pmatrix} e^*_{\sigma(1)} \\ \vdots \\ e^*_{\sigma(n)} \end{pmatrix} \begin{pmatrix} e^*_{\tau(1)} \\ \vdots \\ e^*_{\tau(n)} \end{pmatrix}$$

$$= \phi(\sigma)\phi(\tau)$$

Since $\sigma, \tau \in S_n$ are arbitrary, ϕ is a group homomorphism.

Definition 1.2.0.6. Define $\phi: S_n \to GL(n, \mathbb{R})$ as in the previous exercise. Let $P \in GL(n, \mathbb{R})$. Then P is said to be a **permutation matrix** if there exists $\sigma \in S_n$ such that $P = \phi(\sigma)$. We denote the set of $n \times n$ permutation matrices by Perm(n).

Exercise 1.2.0.7. We have that

- 1. Perm(n) is a subgroup of $GL(n, \mathbb{R})$
- 2. Perm(n) is a subgroup of O(n)

Proof.

- 1. By definition, $\operatorname{Perm}(n) = \operatorname{Im} \phi$. Since $\phi : S_n \to GL(n, \mathbb{R})$ is a group homomorphism, $\operatorname{Im} \phi$ is a subgroup of $GL(n, \mathbb{R})$. Hence $\operatorname{Perm}(n)$ is a subgroup of $GL(n, \mathbb{R})$.
- 2. Let $P \in \text{Perm}(n)$. Then there exists $\sigma \in S_n$ such that $P = \phi(\sigma)$. Then

$$PP^* = \begin{pmatrix} e_{\sigma(1)}^* \\ \vdots \\ e_{\sigma(n)}^* \end{pmatrix} \begin{pmatrix} e_{\sigma(1)}^* \\ \vdots \\ e_{\sigma(n)}^* \end{pmatrix}^*$$

$$= \begin{pmatrix} e_{\sigma(1)}^* \\ \vdots \\ e_{\sigma(n)}^* \end{pmatrix} \begin{pmatrix} e_{\sigma(1)} & \cdots & e_{\sigma(n)} \end{pmatrix}$$

$$= (\langle e_{\sigma(i)}, e_{\sigma(j)} \rangle)_{i,j}$$

$$= I$$

A previous exercise implies that $P^*P = I$. Hence $P \in O(n)$. Since $P \in \operatorname{Perm}(n)$ is arbitrary, $\operatorname{Perm}(n) \subset O(n)$. Part (1) implies that $\operatorname{Perm}(n)$ is a group. Hence $\operatorname{Perm}(n)$ is a subgroup of O(n)

Note 1.2.0.8. We will write P_{σ} in place of $\phi(\sigma)$.

Exercise 1.2.0.9. Let $Z \in \mathbb{R}^{p \times n}$. If rank Z = k, then there exist $\sigma \in S_n$, $\tau \in S_p$ and $A \in GL(k, \mathbb{R})$, such that for each $i, j \in \{1, \ldots, k\}$,

$$(P_{\tau}ZP_{\sigma}^*)_{i,j} = A_{i,j}$$

Proof. Suppose that rank Z - k. Then there exist $i_1, \ldots, i_k \in \{1, \ldots, p\}$ such that $i_1 < \cdots < i_k$ and $\{e_{i_1}^* Z, \ldots, e_{i_k}^* Z\}$ is linearly independent. Set

$$Z' = \begin{pmatrix} e_{i_1}^* Z \\ \vdots \\ e_{i_k}^* Z \end{pmatrix}$$

Then rank Z' = k. Hence there exist $j_1, \ldots, j_k \in \{1, \ldots, n\}$ such that $j_1 < \cdots < j_k$, and $\{Z'e_{i_1}, \ldots, Z'e_{i_k}\}$ is linearly independent. Set

$$A = \begin{pmatrix} Z'e_{i_1} & \cdots & Z'e_{i_k} \end{pmatrix}$$

Then $A \in \mathbb{R}^{k \times k}$ and rank A = k. Thus $A \in GL(k, \mathbb{R})$. Choose $\sigma \in S_n$ and $\tau \in S_p$ such that $\sigma(1) = j_1, \ldots, \sigma(k) = j_k$ and $\tau(1) = i_1, \ldots, \tau(k) = i_k$. Let $a, b \in \{1, \ldots, k\}$. By construction,

$$\begin{split} (P_{\tau}ZP_{\sigma}^*)_{a,b} &= Z_{\tau(a),\sigma(b)} \\ &= Z_{i_a,j_b} \\ &= A_{a,b} \end{split}$$

Definition 1.2.0.10. Let $A \in \mathbb{R}^{n \times p}$. Then A is said to be a **diagonal matrix** if for each $i \in [n]$ and $j \in [p]$, $i \neq j$ implies that $A_{i,j} = 0$. We denote the set of $n \times p$ diagonal matrices by $D(n, p, \mathbb{R})$. We write $D(n, \mathbb{R})$ in place of $D(n, n, \mathbb{R})$.

Definition 1.2.0.11. For (n,k), (m,l) diag $_{p,(n\times p)}: \mathbb{R}^p \to \mathbb{R}^{n\times p}$ and diag $_{n,(n\times p)}: \mathbb{R}^p \to \mathbb{R}^{n\times p}$ by diag(v) FINISH!!!

Definition 1.2.0.12. Let $A \in \mathbb{R}^{n \times n}$ and $\lambda \in \sigma(A)$. Suppose that A is symmetric. We define the **geometric multiplicity** of λ , denoted $\mu(\lambda)$, by

$$\mu(\lambda) = \dim \ker([\phi_{\alpha}] - \lambda I)$$

Definition 1.2.0.13. Let V be an n-dimensional vector space, $U \subset V$ a k-dimensional subspace and $(e_j)_{j=1}^n \subset V$ a be a basis. Then $(e_j)_{j=1}^n$ is said to be **adapted to** U if $(e_j)_{j=1}^k$ is a basis for U.

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1.3 Calculus

1.3.1 Differentiation

Definition 1.3.1.1. Let $n \ge 1$. For $i = 1, \dots, n$, define $x^i : \mathbb{R}^n \to \mathbb{R}$ by $x^i(a^1, \dots, a^n) = a^i$. The functions $(x^i)_{i=1}^n$ are called the **standard coordinate functions on** \mathbb{R}^n .

Definition 1.3.1.2. Let $U \subset \mathbb{R}^n$ be open, $f: U \to \mathbb{R}$ and $a \in U$. Then f is said to be **differentiable with** respect to x^i at a if

$$\lim_{h \to 0} \frac{f(a + he^i) - f(a)}{h}$$

exists. If f is differentiable with respect to x^i at a, we define the **partial derivative of** f with respect to x^i at a, denoted

$$\frac{\partial f}{\partial x^i}(a)$$
 or $\frac{\partial}{\partial x^i}f$

to be the limit above.

Definition 1.3.1.3. Let $U \subset \mathbb{R}^n$ be open and $f: U \to \mathbb{R}$. Then f is said to be **differentiable with respect to** x^i if for each $a \in U$, f is differentiable with respect to x^i at a.

Exercise 1.3.1.4. Let $U \subset \mathbb{R}^n$ be open, $f: U \to \mathbb{R}$ and $a \in U$. Suppose that $\frac{\partial^2 f}{\partial x^i x^j}$ and $\frac{\partial^2 f}{\partial x^j x^i}$ exist and are continuous at a. Then

$$\frac{\partial^2 f}{\partial x^i x^j}(a) = \frac{\partial^2 f}{\partial x^j x^i}(a)$$

Proof.

Definition 1.3.1.5. Let $U \subset \mathbb{R}^n$ be open and $f: U \to \mathbb{R}$. Then f is said to be **smooth** if for each $i_1, \dots, i_k \in \{1, \dots, n\}$, $\frac{\partial^k f}{\partial i_1 \cdots i_k}$ exists and is continuous on U.

Definition 1.3.1.6. Let $U \subset \mathbb{R}^n$, $f: U \to \mathbb{R}$. Then f is said to be **smooth** if there exists $U' \subset \mathbb{R}^n$ and $f': U' \to \mathbb{R}$ such that $U \subset U'$, U' is open, $f'|_U = f$ and f' is smooth. The set of smooth functions on U is denoted $C^{\infty}(U)$.

Theorem 1.3.1.7. Taylor's Theorem:

Let $U \subset \mathbb{R}^n$ be open and convex, $p \in U$, $f \in C^{\infty}(U)$ and $T \in \mathbb{N}$. Then there exist $(g_{\alpha})_{|\alpha|=T+1} \subset C^{\infty}(U)$ such that for each $x \in U$,

$$f(x) = \sum_{k=0}^{T} \left[\sum_{|\alpha|=k} (x-p)^{\alpha} \partial^{\alpha} f(p) \right] + \sum_{|\alpha|=T+1} (x-p)^{\alpha} g_{\alpha}(x)$$

and for each $|\alpha| = T + 1$,

$$g_{\alpha}(p) = \frac{1}{(T+1)!} \partial^{\alpha} f(p)$$

Proof. See analysis notes

Definition 1.3.1.8. Let $U \subset \mathbb{R}^n$ and $F: U \to \mathbb{R}^m$. Let x^1, \dots, x^n be the standard coordinate functions on \mathbb{R}^n and y_1, \dots, y_m be the standard coordinate functions on \mathbb{R}^m . For $i \in \{1, \dots, m\}$, we define the *i*th component of F, denoted $F^i: U \to \mathbb{R}$, by

$$F^i = y^i \circ F$$

Thus $F = (F_1, \cdots, F_m)$

Definition 1.3.1.9. Let $U \subset \mathbb{R}^n$ be open and $F: U \to \mathbb{R}^m$. Then F is said to be **smooth** if for each $i \in \{1, \dots, m\}$, the ith component of $F, F^i: U \to \mathbb{R}$, is smooth.

Definition 1.3.1.10. Let $U \subset \mathbb{R}^n$ and $F: U \to \mathbb{R}^m$. Then F is said to be **smooth** if for each $x \in U$, there exists $U_x \in \mathcal{N}_x$ and $\tilde{F}: U_x \to \mathbb{R}^m$ such that U_x is open, \tilde{F} is smooth and $\tilde{F}|_{U \cap U_x} = F|_{U \cap U_x}$.

Definition 1.3.1.11. Let $U \subset \mathbb{R}^n$ and $V \subset \mathbb{R}^m$ and $F : U \to V$. Then F is said to be a **diffeomorphism** if F is a bijection and F, F^{-1} are smooth.

Exercise 1.3.1.12. Let $U \subset \mathbb{R}^n$ and $V \subset \mathbb{R}^m$ and $F : U \to V$. If F is a diffeomorphism, then F is a homeomorphism.

Proof. Suppose that F is a diffeomorphism. By definition, F is a bijection and F and F^{-1} are smooth. Thus, F and F^{-1} are continuous and F is a homeomorphism.

Definition 1.3.1.13. Let $U \subset \mathbb{R}^n$ be open, $p \in U$ and $F : U \to \mathbb{R}^m$. We define the **Jacobian of** F **at** p, denoted $\frac{\partial F}{\partial x}(p) \in \mathbb{R}^{m \times n}$, by

$$\left(\frac{\partial F}{\partial x}(p)\right)_{i,j} = \frac{\partial F^i}{\partial x^j}(p)$$

Exercise 1.3.1.14. Inverse Function Theorem:

Let $U, V \subset \mathbb{R}^n$ be open and $F: U \to V$.

Exercise 1.3.1.15. Let $U, V \subset \mathbb{R}^n$ and $F: U \to V$. Then F is a diffeomorphism iff for each $p \in U$, there exists a relatively open neighborhood $N \subset U$ of p such that $F|_N: N \to F(N)$ is a diffeomorphism

Proof. content...

Exercise 1.3.1.16. Let $\sigma \in S_n$. Define $\phi_{\sigma} : \mathbb{R}^n \to \mathbb{R}^n$ by $\phi(x^1, \dots, x^n) = \phi(x^{\sigma(1), \dots, x^{\sigma(n)}})$. Then $D\phi = P_{\sigma}$

Definition 1.3.1.17. Let $\sigma \in S_n$ and $x = (x^1, \dots, x^n) \in \mathbb{R}^n$. We define $\sigma x \in \mathbb{R}^n$ by

$$\sigma x = (x^{\sigma(1)}, \dots, x^{\sigma(n)})$$

We define the **permutation action** of S_n on \mathbb{R}^n to be the map $S_n \times \mathbb{R}^n \to \mathbb{R}^n$ given by $(\sigma, x) \mapsto \sigma x$

Definition 1.3.1.18. Let $\sigma \in S_n$, U a set, $V \subset \mathbb{R}^n$ and $\phi : U \to \mathbb{R}^n$ with $\phi = (x^1, \dots, x^m)$. We define $\sigma \phi : U \to \mathbb{R}^n$ by

$$\sigma\phi = (x^{\sigma(1)}, \dots, x^{\sigma(n)})$$

We define the **permutation action** of S_n on $(\mathbb{R}^n)^U$ to be the map $S_n \times (\mathbb{R}^n)^U \to \mathbb{R}^n$ given by $(\sigma, \phi) \mapsto \sigma \phi$.

Exercise 1.3.1.19. Let $\sigma \in S_m$. Then for each $p \in \mathbb{R}^n$, $D(\sigma \operatorname{id}_{\mathbb{R}^n})(p) = P_{\sigma}$.

Proof. Note that since $\mathrm{id}_{\mathbb{R}^n}=(\pi_1,\ldots,\pi_n)$, we have that $\sigma\,\mathrm{id}_{\mathbb{R}^n}=(\pi_{\sigma(1)},\ldots,\pi_{\sigma(n)})$. Let $p\in\mathbb{R}^n$. Then

$$D(\sigma \operatorname{id}_{\mathbb{R}^n})(p) = \left(\frac{\partial \pi_i \circ \sigma \operatorname{id}_{\mathbb{R}^n}}{\partial x^j}(p)\right)_{i,j}$$

$$= \left(\frac{\partial \pi_{\sigma(i)}}{\partial x^j}(p)\right)_{i,j}$$

$$= P_{\sigma}\left(\frac{\partial \pi_i}{\partial x^j}(p)\right)_{i,j}$$

$$= P_{\sigma}\left(\frac{\partial \pi_i \circ \operatorname{id}_{\mathbb{R}^n}}{\partial x^j}(p)\right)_{i,j}$$

$$= P_{\sigma}D\operatorname{id}_{\mathbb{R}^n}(p)$$

$$= P_{\sigma}I$$

$$= P_{\sigma}$$

1.4. TOPOLOGY

1.4 Topology

Definition 1.4.0.1. Let $(X, \mathbb{T}_X), (Y, \mathcal{T}_Y)$ be topological spaces and $f: X \to Y$. Then f is said to be **continuous** if for each $U \in \mathcal{T}$, $f^{-1}(U) \in \mathcal{T}_X$.

Definition 1.4.0.2. Let $(X, \mathcal{T}_X), (Y, \mathcal{T}_Y)$ be topological spaces and $f: X \to Y$. Then f is said to be a homeomorphism if f is a bijection and f, f^{-1} are continuous.

Definition 1.4.0.3. Let X, Y be topological spaces. Then X and Y are said to be **homeomorphic** if there exists $f: X \to Y$ such that f is a homeomorphism. If X and Y are homeomorphic, we write $X \cong Y$.

Theorem 1.4.0.4. Let $m, n \in \mathbb{N}$. If $m \neq n$, then $\mathbb{R}^m \ncong \mathbb{R}^n$

Chapter 2

Multilinear Algebra

2.1 (r,s)-Tensors

Definition 2.1.0.1. Let V_1, \ldots, V_k, W be vector spaces and $\alpha: \prod_{i=1}^n V_i \to W$. Then α is said to be **multilinear** if for each $i \in \{1, \cdots, k\}, v \in V, c \in \mathbb{R}$ and $v_1, \cdots, v_k \in V$,

$$\alpha(v_1, \dots, v_i + cv, \dots, v_k) = \alpha(v_1, \dots, v_i, \dots, v_k) + c\alpha(v_1, \dots, v_i, \dots, v_k)$$

We define

$$L(V_1, \dots, V_k; W) = \left\{ \alpha : \prod_{i=1}^n V_i \to W : \alpha \text{ is multilinear} \right\}$$

Note 2.1.0.2. For the remainder of this section we let V denote an n-dimensional vector space with basis $\{e^1, \dots, e^n\}$ with dual space V^* and dual basis $\{\epsilon_1, \dots, \epsilon_n\}$ defined by $\epsilon^i(e^j) = \delta_{i,j}$. We identify V with V^{**} by the isomorphism $V \to V^{**}$ defined by $v \mapsto \hat{v}$ where $\hat{v}(\alpha) = \alpha(v)$ for each $\alpha \in V^*$.

Definition 2.1.0.3. Let $\alpha: (V^*)^r \times V^s \to \mathbb{R}$. Then α is said to be an (r,s)-tensor on V if $\alpha \in$ $L(\underbrace{V^*,\ldots,V^*}_r,\underbrace{V,\ldots,V}_s;\mathbb{R})$. The set of all (r,s)-tensors on V is denoted $T^r_s(V)$. When r=s=0, we set $T^r_s=\mathbb{R}$.

Exercise 2.1.0.4. We have that $T_s^r(V)$ is a vector space.

Proof. Clear.

Exercise 2.1.0.5. Under the identification of V with V^{**} as noted above, we have that $V = T_0^1(V)$.

Proof. By definition,

$$V = V^{**}$$

$$= L(V^*; \mathbb{R})$$

$$= T_0^1(V)$$

Definition 2.1.0.6. Let $\alpha \in T^{r_1}_{s_1}(V)$ and $\beta \in T^{r_2}_{s_2}(V)$. We define the **tensor product of** α **with** β , denoted $\alpha \otimes \beta \in T^{r_1+r_2}_{s_1+s_2}(V)$, by

$$\alpha \otimes \beta(v^*, w^*, v, w) = \alpha(v^*, v)\beta(w^*, w)$$

for each $v^* \in (V^*)^{r_1}$, $w^* \in (V^*)^{r_2}$, $v \in V^{s_1}$ and $w \in V^{s_2}$.

When $r_1 = s_1 = r_2 = s_2 = 0$ (so that $\alpha, \beta \in \mathbb{R}$), we set $\alpha \otimes \beta = \alpha \beta$.

Definition 2.1.0.7. We define the **tensor product**, denoted $\otimes : T_{s_1}^{r_1}(V) \times T_{s_2}^{r_2}(V) \to T_{s_1+s_2}^{r_1+r_2}(V)$ by

$$(\alpha, \beta) \mapsto \alpha \otimes \beta$$

Exercise 2.1.0.8. The tensor product $\otimes : T_{s_1}^{r_1}(V) \times T_{s_2}^{r_2}(V) \to T_{s_1+s_2}^{r_1+r_2}(V)$ is well defined.

 ${\it Proof.}$ Tedious but straightforward.

Exercise 2.1.0.9. The tensor product $\otimes : T_{s_1}^{r_1}(V) \times T_{s_2}^{r_2}(V) \to T_{s_1+s_2}^{r_1+r_2}(V)$ is associative.

Proof. Let $\alpha \in T^{r_1}_{s_1}(V)$, $\beta \in T^{r_2}_{s_2}(V)$ and $\gamma \in T^{r_3}_{s_3}(V)$. Then for each $u^* \in (V^*)^{r_1}, v^* \in (V^*)^{r_2}, w^* \in (V^*)^{r_3}, u \in V^{s_1}, v \in V^{s_2}, w \in V^{s_3}$,

$$(\alpha \otimes \beta) \otimes \gamma(u^*, v^*, w^*, u, v, w) = (\alpha \otimes \beta)(u^*, v^*, u, v)\gamma(w^*, w)$$

$$= [\alpha(u^*, u)\beta(v^*, v)]\gamma(w^*, w)$$

$$= \alpha(u^*, u)[\beta(v^*, v)\gamma(w^*, w)]$$

$$= \alpha(u^*, u)(\beta \otimes \gamma)(v^*, w^*, v, w)$$

$$= \alpha \otimes (\beta \otimes \gamma)(u^*, v^*, w^*, u, v, w)$$

So that

$$(\alpha \otimes \beta) \otimes \gamma = \alpha \otimes (\beta \otimes \gamma)$$

Exercise 2.1.0.10. The tensor product $\otimes : T_{s_1}^{r_1}(V) \times T_{s_2}^{r_2}(V) \to T_{s_1+s_2}^{r_1+r_2}(V)$ is bilinear.

Proof.

1. Linearity in the first argument:

Let $\alpha, \beta \in T_{s_1}^{r_1}(V)$, $\gamma \in T_{s_2}^{r_2}(V)$, $\lambda \in \mathbb{R}$, $v^* \in (V^*)^{r_1}$, $w^* \in (V^*)^{r_2}$, $vinV^{s_1}$ and $w \in V^{s_2}$. To see that the tensor product is linear in the first argument, we note that

$$\begin{split} [(\alpha + \lambda \beta) \otimes \gamma](v^*, w^*, v, w) &= (\alpha + \lambda \beta)(v^*, v)\gamma(w^*, w) \\ &= [\alpha(v^*, v) + \lambda \beta(v^*, v)]\gamma(w^*, w) \\ &= \alpha(v^*, v)\gamma(w^*, w) + \lambda \beta(v^*, v)\gamma(w^*, w) \\ &= \alpha \otimes \gamma(v^*, w^*, v, w) + \lambda(\beta \otimes \gamma)(v^*, w^*, v, w) \\ &= [\alpha \otimes \gamma + \lambda(\beta \otimes \gamma)](v^*, w^*, v, w) \end{split}$$

So that

$$(\alpha + \lambda \beta) \otimes \gamma = \alpha \otimes \gamma + \lambda(\beta \otimes \gamma)$$

2. Linearity in the second argument: Similar to (1).

Definition 2.1.0.11.

- 1. Define $\mathcal{I}_{\otimes k} = \{(i_1, i_2, \dots, i_k) \in \mathbb{N}^k : i_1, \dots, i_k \leq n\}$. Each element $I \in \mathcal{I}_k$ is called an **unordered** multi-index of length k. Recall that $\#\mathcal{I}_{\otimes k} = n^k$.
- 2. Define $\mathcal{I}_{\wedge k} = \{(i_1, i_2, \dots, i_k) \in \mathbb{N}^k : i_1 < i_2 < \dots < i_k \le n\}$. Each element $I \in \mathcal{I}_k$ is called an **ordered** multi-index of length k. Recall that $\#\mathcal{I}_{\wedge k} = \binom{n}{k}$.

 $e^I = (e^{i_1}, \cdots, e^{i_k})$

Note 2.1.0.12. For the remainder of this section we will write \mathcal{I}_k in place of $\mathcal{I}_{\otimes k}$.

Definition 2.1.0.13. Let $I = \{(i_1, i_2, \dots, i_k) \in \mathcal{I}_k\}$.

1. Define
$$\epsilon^I \in (V^*)^k$$
 and $e_I \in V^k$ by
$$\epsilon^I = (\epsilon^{i_1}, \cdots, \epsilon^{i_k})$$
 and

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2. Define $e^{\otimes I} \in T_0^k(V)$ and $\epsilon^{\otimes I} \in T_k^0(V)$ by

$$e^{\otimes I} = e^{i_1} \otimes \cdots \otimes e^{i_k}$$

and

$$\epsilon^{\otimes I} = \epsilon^{i_1} \otimes \cdots \otimes \epsilon^{i_k}$$

Exercise 2.1.0.14. Let $\alpha, \beta \in T_s^r(V)$. If for each $I \in \mathcal{I}_r, J \in \mathcal{I}_s, \ \alpha(\epsilon^I, e^J) = \beta(\epsilon^I, e^J)$, then $\alpha = \beta$.

Proof. Suppose that for each $I \in \mathcal{I}_r, J \in \mathcal{I}_s$, $\alpha(\epsilon^I, e^J) = \beta(\epsilon^I, e^J)$. Let $v_1^*, \dots, v_r^* \in V^*$ and $v_1, \dots, v_s \in V$. For each $i \in \{1, \dots, r\}$ and $j \in \{1, \dots, s\}$, write

$$v_i^* = \sum_{k_i=1}^n a_{i,k_i} \epsilon^{k_i}$$

and

$$v_j = \sum_{l_j=1}^n b_{j,l_j} e^{l_j}$$

Then

$$\alpha(v_1^*, \dots, v_r^*, v_1, \dots, v_s) = \sum_{k_1, \dots, k_r = 1}^n \sum_{l_1, \dots, l_s = 1}^n \prod_{i=1}^r \prod_{j=1}^s a_{i, k_i} b_{j, l_j} \alpha(\epsilon^{k_1}, \dots, \epsilon^{k_r}, e^{l_1}, \dots, e^{l_s})$$

$$= \sum_{k_1, \dots, k_r = 1}^n \sum_{l_1, \dots, l_s = 1}^n \prod_{i=1}^r \prod_{j=1}^s a_{i, k_i} b_{j, l_j} \beta(\epsilon^{k_1}, \dots, \epsilon^{k_r}, e^{l_1}, \dots, e^{l_s})$$

$$= \beta(v_1^*, \dots, v_r^*, v_1, \dots, v_s)$$

So that $\alpha = \beta$.

Exercise 2.1.0.15. Let $I, K \in \mathcal{I}_r$ and $J, L \in \mathcal{I}_s$. Then $e^{\otimes I} \otimes \epsilon^{\otimes J}(\epsilon^K, e^L) = \delta_{I,K}\delta_{J,L}$.

Proof. Write $I = (i_1, ..., i_r), K = (k_1, ..., k_r)$ and $J = (j_1, ..., j_s), L = (l_1, ..., l_s)$. Then

$$e^{\otimes I} \otimes \epsilon^{\otimes J}(\epsilon^{K}, e^{L}) = e^{\otimes I}(\epsilon^{K}) \epsilon^{\otimes J}(e^{L})$$

$$= e^{i_{1}} \otimes \cdots \otimes e^{i_{r}}(\epsilon^{k_{1}}, \dots, \epsilon^{k_{r}}) \epsilon^{j_{1}} \otimes \cdots \otimes \epsilon^{j_{s}}(e^{l_{1}}, \dots, e^{l_{s}})$$

$$= \left[\prod_{m=1}^{r} e^{i_{m}}(\epsilon^{k_{m}})\right] \left[\prod_{n=1}^{s} \epsilon^{j_{n}}(e^{l_{n}})\right]$$

$$= \left[\prod_{m=1}^{r} \delta_{i_{m}, k_{m}}\right] \left[\prod_{n=1}^{s} \delta_{j_{n}, l_{n}}\right]$$

$$= \delta_{I, K} \delta_{J, L}$$

Exercise 2.1.0.16. The set $\{e^{\otimes I} \otimes \epsilon^{\otimes J} : I \in \mathcal{I}_r, J \in \mathcal{I}_s\}$ is a basis for $T^r_s(V)$ and dim $T^r_s(V) = n^{r+s}$.

Proof. Let $(a_J^I)_{I\in\mathcal{I}_r,J\in\mathcal{I}_s}\subset\mathbb{R}$. Let $\alpha=\sum\limits_{(I,J)\in\mathcal{I}_r\times\mathcal{I}_s}a_J^Ie^{\otimes I}\otimes\epsilon^{\otimes J}$. Suppose that $\alpha=0$. Then for each $(I,J)\in\mathcal{I}_r\times\mathcal{I}_s$, $\alpha(\epsilon^I,e^J)=a_J^I=0$. Thus $\{e^{\otimes I}\otimes\epsilon^{\otimes J}:I\in\mathcal{I}_r,J\in\mathcal{I}_s\}$ is linearly independent. Let $\beta\in T_s^r(V)$. For $(I,J)\in\mathcal{I}_r\times\mathcal{I}_s$, put $b_J^I=\beta(\epsilon^J,e^I)$. Define $\mu=\sum\limits_{(I,J)\in\mathcal{I}_r\times\mathcal{I}_s}b_J^Ie^{\otimes I}\otimes\epsilon^{\otimes J}\in T_s^r(V)$. Then for each $(I,J)\in\mathcal{I}_r\times\mathcal{I}_s$, $\mu(\epsilon^I,e^J)=b_J^I=\beta(\epsilon^I,e^J)$. Hence $\mu=\beta$ and therefore $\beta\in\mathrm{span}\{e^{\otimes I}\otimes\epsilon^{\otimes J}\}$.

2.2 Covariant k-Tensors

2.2.1 Symmetric and Alternating Covariant k-Tensors

Definition 2.2.1.1. Let $\alpha: V^k \to \mathbb{R}$. Then α is said to be a **covariant k-tensor on V** if $\alpha \in T_k^0(V)$. We denote the set of covariant k-tensors by $T_k(V)$.

Definition 2.2.1.2. For $\sigma \in S_k$ and $\alpha \in T_k(V)$, define the $\sigma \alpha : V^k \to \mathbb{R}$ by

$$\sigma\alpha(v_1,\cdots,v_k)=\alpha(v_{\sigma(1)},\cdots,v_{\sigma(k)})$$

We define the **permutation action** of of S_k on $T_k(V)$ to be the map $S_k \times T_k(V) \to T_k(V)$ given by $(\sigma, \alpha) \mapsto \sigma \alpha$

Exercise 2.2.1.3. The permutation action of S_k on $T_k(V)$ is a group action.

Proof.

- 1. Clearly for each $\sigma \in S_k$ and $\alpha \in T_k(V)$, $\sigma \alpha \in T_k(V)$.
- 2. Clearly for each $\alpha \in T_k(V)$, $e\alpha = \alpha$.
- 3. Let $\tau, \sigma \in S_k$ and $\alpha \in T_k(V)$. Then for each $v_1, \dots, v_k \in V$,

$$(\tau\sigma)\alpha(v_1,\dots,v_k) = \alpha(v_{\tau\sigma(1)},\dots,v_{\tau\sigma(k)})$$
$$= \tau\alpha(v_{\sigma(1)},\dots,v_{\sigma(k)})$$
$$= \tau(\sigma\alpha)(v_1,\dots,v_k)$$

Exercise 2.2.1.4. Let $\sigma \in S_k$. Then $L_{\sigma}: T_k(V) \to T_k(V)$ given by $L_{\sigma}(\alpha) = \sigma \alpha$ is a linear transformation.

Proof. Let $\alpha, \beta \in T_k(V)$, $c \in \mathbb{R}$ and $v_1, \dots, v_k \in V$. Then

$$\sigma(c\alpha + \beta)(v_1, \dots, v_k) = (c\alpha + \beta)(v_{\sigma(1)}, \dots, v_{\sigma(k)})$$

$$= c\alpha(v_{\sigma(1)}, \dots, v_{\sigma(k)}) + \beta(v_{\sigma(1)}, \dots, v_{\sigma(k)})$$

$$= c\sigma\alpha(v_1, \dots, v_k) + \sigma\beta(v_1, \dots, v_k)$$

So $\sigma(c\alpha + \beta) = c\sigma\alpha + \sigma\beta$.

Definition 2.2.1.5. Let $\alpha \in T_k(V)$. Then α is said to be

- symmetric if for each $\sigma \in S_k$, $\sigma \alpha = \alpha$
- antisymmetric if for each $\sigma \in S_k$, $\sigma \alpha = \operatorname{sgn}(\sigma) \alpha$
- alternating if for each $v_1, \ldots, v_k \in V$, if there exists $i, j \in \{1, \ldots, k\}$ such that $v_i = v_j$, then $\alpha(v_1, \cdots, v_k) = 0$.

We denote the set of symmetric k-tensors on V by $\Sigma^k(V)$. We denote the set of alternating k-tensors on V by $\Lambda^k(V)$.

Exercise 2.2.1.6. Let $\alpha \in T_k(V)$. Then α is antisymmetric iff α is alternating.

Proof. Suppose that α is antisymmetric. Let $v_1, \ldots, v_k \in V$. Suppose that there exists $i, j \in \{1, \ldots, k\}$ such that $v_i = v_j$. Define $\sigma \in S_k$ by $\sigma = (i, j)$. Then

$$\alpha(v_1, \dots, v_i, \dots, v_j, \dots, v_k) = \alpha(v_1, \dots, v_j, \dots, v_i, \dots, v_k)$$

$$= \sigma(\alpha)(v_1, \dots, v_i, \dots, v_j, \dots, v_k)$$

$$= \operatorname{sgn}(\sigma)\alpha(v_1, \dots, v_i, \dots, v_j, \dots, v_k)$$

$$= -\alpha(v_1, \dots, v_i, \dots, v_j, \dots, v_k)$$

Therefore $2\alpha(v_1, \dots, v_i, \dots, v_j, \dots, v_k) = 0$ which implies that $\alpha(v_1, \dots, v_i, \dots, v_j, \dots, v_k) = 0$. Hence α is alternating.

Conversely, suppose that α is alternating. Let $i, j \in \{1, \dots, k\}$ and $v_1, \dots, v_k \in V$. Then

$$0 = \alpha(v_1, \dots, v_i + v_j, \dots, v_i + v_j, \dots, v_k)$$

= $\alpha(v_1, \dots, v_i, \dots, v_j, \dots, v_k) + \alpha(v_1, \dots, v_j, \dots, v_i, \dots, v_k)$

Since $i, j \in \{1, ..., k\}$ and $v_1, ..., v_k \in V$ are arbitrary, we have that for each $\tau \in S_k$, τ is a transposition implies that

$$\tau \alpha = -\alpha$$
$$= \operatorname{sgn}(\tau)\alpha$$

Let $n \in \mathbb{N}$. Suppose that for each $\tau_1, \ldots, \tau_{n-1} \in S_k$ if for each $j \in \{1, \ldots, n-1\}$, τ_j is a transposition, then $(\tau_1 \cdots \tau_{n-1})\alpha = \sigma(\tau_1 \cdots \tau_{n-1})\alpha$. Let $\tau_1, \ldots, \tau_n \in S_k$. Suppose that for each $j \in \{1, \ldots, n\}$, τ_j is a transposition. Then

$$(\tau_1 \cdots \tau_n)\alpha = (\tau_1 \cdots \tau_{n-1})(\tau_n \alpha)$$

$$= (\tau_1 \cdots \tau_{n-1})(\operatorname{sgn}(\tau_n)\alpha)$$

$$= (\operatorname{sgn}(\tau_n)(\tau_1 \cdots \tau_{n-1})\alpha)$$

$$= (\operatorname{sgn}(\tau_n)\operatorname{sgn}((\tau_1 \cdots \tau_{n-1})\alpha))$$

$$= \operatorname{sgn}(\tau_1 \cdots \tau_n)\alpha$$

By induction, for each $n \in \mathbb{N}$ and $\tau_1, \ldots, \tau_n \in S_k$, if for each $j \in \{1, \ldots, n\}$, τ_j is a transposition, then $(\tau_1 \cdots \tau_n)\alpha = \operatorname{sgn}(\tau_1 \cdots \tau_n)\alpha$. Now let $\sigma \in S_k$. Then there exist $n \in \mathbb{N}$ and $\tau_1, \ldots, \tau_n \in S_k$ such that $\sigma = \tau_1 \cdots \tau_n$ and for each $j \in \{1, \ldots, n\}$, τ_j is a transposition. Hence

$$\sigma\alpha = (\tau_1 \cdots \tau_n)\alpha$$
$$= \operatorname{sgn}(\tau_1 \cdots \tau_n)\alpha$$
$$= \operatorname{sgn}(\sigma)\alpha$$

Therefore α is antisymmetric.

Definition 2.2.1.7. Define the symmetric operator $S: T_k(V) \to \Sigma^k(V)$ by

$$\operatorname{Sym}(\alpha) = \frac{1}{k!} \sum_{\sigma \in S_k} \sigma \alpha$$

Define the alternating operator $A: T_k(V) \to \Lambda^k(V)$ by

$$Alt(\alpha) = \frac{1}{k!} \sum_{\sigma \in S_k} sgn(\sigma)\sigma\alpha$$

Exercise 2.2.1.8.

- 1. For $\alpha \in T_k(V)$, $\operatorname{Sym}(\alpha)$ is symmetric.
- 2. For $\alpha \in T_k(V)$, Alt (α) is alternating.

Proof.

1. Let $\alpha \in T_k(V)$ and $\sigma \in S_k$. Then

$$\sigma \operatorname{Sym}(\alpha) = \sigma \left[\frac{1}{k!} \sum_{\tau \in S_k} \tau \alpha \right]$$
$$= \frac{1}{k!} \sum_{\tau \in S_k} \sigma \tau \alpha$$
$$= \frac{1}{k!} \sum_{\tau \in S_k} \tau \alpha$$
$$= \operatorname{Sym}(\alpha)$$

2. Let $\alpha \in T_k(V)$ and $\sigma \in S_k$. Then

$$\begin{split} \sigma \operatorname{Alt}(\alpha) &= \sigma \bigg[\frac{1}{k!} \sum_{\tau \in S_k} \operatorname{sgn}(\tau) \tau \alpha \bigg] \\ &= \frac{1}{k!} \sum_{\tau \in S_k} \operatorname{sgn}(\tau) \sigma \tau \alpha \\ &= \frac{1}{k!} \sum_{\tau \in S_k} \operatorname{sgn}(\sigma) \operatorname{sgn}(\sigma \tau) \sigma \tau \alpha \\ &= \operatorname{sgn}(\sigma) \frac{1}{k!} \sum_{\tau \in S_k} \operatorname{sgn}(\sigma \tau) \sigma \tau \alpha \\ &= \operatorname{sgn}(\sigma) \frac{1}{k!} \sum_{\tau \in S_k} \operatorname{sgn}(\tau) \tau \alpha \\ &= \operatorname{sgn}(\sigma) \operatorname{Alt}(\alpha) \end{split}$$

Exercise 2.2.1.9.

1. For $\alpha \in \Sigma^k(V)$, $\operatorname{Sym}(\alpha) = \alpha$.

2. For $\alpha \in \Lambda^k(V)$, $Alt(\alpha) = \alpha$.

Proof.

1. Let $\alpha \in \Sigma^k(V)$. Then

$$\operatorname{Sym}(\alpha) = \frac{1}{k!} \sum_{\sigma \in S_k} \sigma \alpha$$
$$= \frac{1}{k!} \sum_{\sigma \in S_k} \alpha$$
$$= \alpha$$

2. Let $\alpha \in \Lambda^k(V)$. Then

$$Alt(\alpha) = \frac{1}{k!} \sum_{\sigma \in S_k} sgn(\sigma)\sigma\alpha$$
$$= \frac{1}{k!} \sum_{\sigma \in S_k} sgn(\sigma)^2\alpha$$
$$= \alpha$$

Exercise 2.2.1.10. The symmetric operator $S: T_k(V) \to \Sigma^k(V)$ and the alternating operator $A: T_k(V) \to \Lambda^k(V)$ are linear.

Proof. Clear. \Box

Exercise 2.2.1.11. Let $\alpha \in T_k(V)$ and $\beta \in T_l(V)$. Then

- 1. $Alt(Alt(\alpha) \otimes \beta) = Alt(\alpha \otimes \beta)$
- 2. $Alt(\alpha \otimes Alt(\beta)) = Alt(\alpha \otimes \beta)$

Proof. First note that if we fix $\mu \in S_{k+1}$, then for each $\tau \in S_k$, choosing $\sigma = \mu \tau^{-1}$ yields $\sigma \tau = \mu$. For each $\mu \in S_{k+l}$, the map $\phi_{\mu} : S_k \to S_{k+l}$ given by $\phi_{\mu}(\tau) = \mu \tau^{-1}$ is injective. Thus for each $\mu \in S_{k+l}$, we have that $\#\{(\sigma,\tau) \in S_{k+l} \times S_k : \mu = \sigma \tau\} = k!$

1. Then

$$\operatorname{Alt}(\operatorname{Alt}(\alpha) \otimes \beta) = \frac{1}{(k+l)!} \sum_{\sigma \in S_{k+l}} \operatorname{sgn}(\sigma) \sigma \left[\operatorname{Alt}(\alpha) \otimes \beta \right]$$

$$= \frac{1}{(k+l)!} \sum_{\sigma \in S_{k+l}} \operatorname{sgn}(\sigma) \sigma \left[\left(\frac{1}{k!} \sum_{\tau \in S_k} \operatorname{sgn}(\tau) \tau \alpha \right) \otimes \beta \right]$$

$$= \frac{1}{(k+l)!} \sum_{\sigma \in S_{k+l}} \operatorname{sgn}(\sigma) \sigma \left[\frac{1}{k!} \sum_{\tau \in S_k} \operatorname{sgn}(\tau) (\tau \alpha) \otimes \beta \right]$$

$$= \frac{1}{(k+l)!} \sum_{\sigma \in S_{k+l}} \operatorname{sgn}(\sigma) \sigma \left[\frac{1}{k!} \sum_{\tau \in S_k} \operatorname{sgn}(\tau) \tau (\alpha \otimes \beta) \right]$$

$$= \frac{1}{k!(k+l)!} \sum_{\sigma \in S_{k+l}} \sum_{\tau \in S_k} \operatorname{sgn}(\sigma \tau) \sigma \tau (\alpha \otimes \beta)$$

$$= \frac{k!}{k!(k+l)!} \sum_{\mu \in S_{k+l}} \operatorname{sgn}(\mu) \mu (\alpha \otimes \beta)$$

$$= \frac{1}{(k+l)!} \sum_{\mu \in S_{k+l}} \operatorname{sgn}(\mu) \mu (\alpha \otimes \beta)$$

$$= \operatorname{Alt}(\alpha \otimes \beta)$$

2. Similar to (1).

2.2.2 Exterior Product

Definition 2.2.2.1. Let $\alpha \in \Lambda^k(V)$ and $\beta \in \Lambda^l(V)$. The **exterior product** of α and β is defined to be the map $\alpha \wedge \beta \in \Lambda^{k+l}(V)$ given by

$$\alpha \wedge \beta = \frac{(k+l)!}{k!l!} \operatorname{Alt}(\alpha \otimes \beta)$$

Thus $\wedge : \Lambda^k(V) \times \Lambda^l(V) \to \Lambda^{k+l}(V)$.

Exercise 2.2.2.2. The exterior product $\wedge : \Lambda^k(V) \times \Lambda^l(V) \to \Lambda^{k+l}(V)$ is bilinear.

Proof. Clear. \Box

Exercise 2.2.2.3. The exterior product $\wedge : \Lambda^k(V) \times \Lambda^l(V) \to \Lambda^{k+l}(V)$ is associative.

Proof. Let $\alpha \in \Lambda^k(V)$, $\beta \in \Lambda^l(V)$ and $\gamma \in \Lambda^m(V)$. Then

$$(\alpha \wedge \beta) \wedge \gamma = \left[\frac{(k+l)!}{k!l!} \operatorname{Alt}(\alpha \otimes \beta) \right] \wedge \gamma$$

$$= \frac{(k+l+m)!}{(k+l)!m!} \operatorname{Alt} \left(\left[\frac{(k+l)!}{k!l!} \operatorname{Alt}(\alpha \otimes \beta) \right] \otimes \gamma \right)$$

$$= \frac{(k+l+m)!}{(k+l)!m!} \frac{(k+l)!}{k!l!} \operatorname{Alt}(\operatorname{Alt}(\alpha \otimes \beta) \otimes \gamma)$$

$$= \frac{(k+l+m)!}{m!} \frac{1}{k!l!} \operatorname{Alt}((\alpha \otimes \beta) \otimes \gamma)$$

$$= \frac{(k+l+m)!}{k!(l+m)!} \frac{(l+m)!}{l!m!} \operatorname{Alt}(\alpha \otimes (\beta \otimes \gamma))$$

$$= \frac{(k+l+m)!}{k!(l+m)!} \frac{(l+m)!}{l!m!} \operatorname{Alt}(\alpha \otimes \operatorname{Alt}(\beta \otimes \gamma))$$

$$= \frac{(k+l+m)!}{k!(l+m)!} \operatorname{Alt}(\alpha \otimes \frac{(l+m)!}{l!m!} \operatorname{Alt}(\beta \otimes \gamma))$$

$$= \frac{(k+l+m)!}{k!(l+m)!} \operatorname{Alt}(\alpha \otimes (\beta \wedge \gamma))$$

$$= \alpha \wedge (\beta \wedge \gamma)$$

Exercise 2.2.2.4. Let $\alpha_i \in \Lambda^{k_i}(V)$ for $i = 1, \dots, m$. Then

$$\bigwedge_{i=1}^m \alpha_i = \frac{(\sum_{i=1}^m k_i)!}{\prod_{i=1}^m k_i!} \operatorname{Alt} \left(\bigotimes_{i=1}^m \alpha_i \right)$$

Proof. To see that the statment is true in the case m=3, the proof of the previous exercise tells us that indeed

$$\alpha_1 \wedge \alpha_2 \wedge \alpha_3 = \frac{(k_1 + k_2 + k_3)!}{k_1! k_2! k_3!} \operatorname{Alt}(\alpha_1 \otimes \alpha_2 \otimes \alpha_3)$$

Now, suppose that the statement is true for each $3 \le m \le m_0$. Then the proof of the previous exercise tells us the

$$\bigwedge_{i=1}^{m_0+1} \alpha_i = \left(\bigwedge_{i=1}^{m_0-1} \alpha_i\right) \wedge \alpha_{m_0} \wedge \alpha_{m_0+1}$$

$$= \frac{\left(\sum_{i=1}^{m_0-1} k_i + k_{m_0} + k_{m_0+1}\right)!}{\left(\sum_{i=1}^{m_0-1} k_i\right)! k_{m_0}! k_{m_0+1}!} \operatorname{Alt} \left(\left[\bigwedge_{i=1}^{m_0-1} \alpha_i\right] \otimes \alpha_{m_0} \otimes \alpha_{m_0+1}\right)$$

$$= \frac{\left(\sum_{i=1}^{m_0-1} k_i + k_{m_0} + k_{m_0+1}\right)!}{\left(\sum_{i=1}^{m_0-1} k_i\right)! k_{m_0}! k_{m_0+1}!} \operatorname{Alt} \left(\left[\underbrace{\sum_{i=1}^{m_0-1} k_i\right}!}_{\prod_{i=1}^{m_0-1} k_i!} \operatorname{Alt} \left(\bigotimes_{i=1}^{m_0-1} \alpha_i\right)\right] \otimes \alpha_{m_0} \otimes \alpha_{m_0+1}\right)$$

$$= \frac{\left(\sum_{i=1}^{m_0+1} k_i\right)!}{\prod_{i=1}^{m_0+1} k_i!} \operatorname{Alt} \left(\left[\bigotimes_{i=1}^{m_0-1} \alpha_i\right] \otimes \alpha_{m_0} \otimes \alpha_{m_0+1}\right)$$

$$= \frac{\left(\sum_{i=1}^{m_0+1} k_i\right)!}{\prod_{i=1}^{m_0+1} k_i!} \operatorname{Alt} \left(\bigotimes_{i=1}^{m_0-1} \alpha_i\right) \otimes \alpha_{m_0} \otimes \alpha_{m_0+1}\right)$$

$$= \frac{\left(\sum_{i=1}^{m_0+1} k_i\right)!}{\prod_{i=1}^{m_0+1} k_i!} \operatorname{Alt} \left(\bigotimes_{i=1}^{m_0+1} \alpha_i\right)$$

Exercise 2.2.2.5. Define $\tau \in S_{k+l}$ by

$$\tau = \begin{pmatrix} 1 & 2 & \cdots & l & l+1 & l+2 & \cdots & l+k \\ 1+k & 2+k & \cdots & l+k & 1 & 2 & \cdots & k \end{pmatrix}$$

Then the inversion number of τ is kl. (Hint: inversion number)

Proof.

$$N(\tau) = \sum_{i=1}^{l} k$$
$$= kl$$

Since $\operatorname{sgn}(\tau) = (-1)^{N(\tau)}$ we know that $\operatorname{sgn}(\tau) = (-1)^{kl}$.

Exercise 2.2.2.6. Let $\alpha \in \Lambda^k(V)$, $\beta \in \Lambda^l(V)$. Then

$$\alpha \wedge \beta = (-1)^{kl} \beta \wedge \alpha$$

Proof. Define $\tau \in S_{k+l}$ as in the previous exercise. Note that For $\sigma \in S_{k+l}$ and $v_1, \dots, v_{k+l} \in V$, we have that

$$\begin{split} \sigma\tau(\beta\otimes\alpha)(v_1,\cdots,v_l,v_{l+1},\cdots v_{l+k}) &= \beta\otimes\alpha(v_{\sigma\tau(1)},\cdots,v_{\sigma\tau(l)},v_{\sigma\tau(l+1)},\cdots v_{\sigma\tau(l+k)}) \\ &= \beta(v_{\sigma\tau(1)},\cdots,v_{\sigma\tau(l)})\alpha(v_{\sigma\tau(l+1)},\cdots v_{\sigma\tau(l+k)}) \\ &= \beta(v_{\sigma(1+k)},\cdots,v_{\sigma(l+k)})\alpha(v_{\sigma(1)},\cdots v_{\sigma(k)}) \\ &= \alpha(v_{\sigma(1)},\cdots v_{\sigma(k)})\beta(v_{\sigma(1+k)},\cdots,v_{\sigma(l+k)}) \\ &= \alpha\otimes\beta(v_{\sigma(1)},\cdots v_{\sigma(k)},v_{\sigma(1+k)},\cdots,v_{\sigma(l+k)}) \\ &= \alpha\otimes\beta(v_{\sigma(1)},\cdots v_{\sigma(k)},v_{\sigma(1+k)},\cdots,v_{\sigma(l+k)}) \\ &= \sigma(\alpha\otimes\beta)(v_1,\cdots,v_k,v_{1+k},\cdots v_{l+k}) \end{split}$$

Thus $\sigma \tau(\beta \otimes \alpha) = \sigma(\alpha \otimes \beta)$. Then

$$\beta \wedge \alpha = \frac{(k+l)!}{k!l!} \operatorname{Alt}(\beta \otimes \alpha)$$

$$= \frac{(k+l)!}{k!l!} \frac{1}{(k+l)!} \sum_{\sigma \in S_{k+l}} \operatorname{sgn}(\sigma) \sigma(\beta \otimes \alpha)$$

$$= \frac{(k+l)!}{k!l!} \frac{1}{(k+l)!} \sum_{\sigma \in S_{k+l}} \operatorname{sgn}(\sigma\tau) \sigma\tau(\beta \otimes \alpha)$$

$$= \operatorname{sgn}(\tau) \frac{(k+l)!}{k!l!} \frac{1}{(k+l)!} \sum_{\sigma \in S_{k+l}} \operatorname{sgn}(\sigma) \sigma(\alpha \otimes \beta)$$

$$= \operatorname{sgn}(\tau) \frac{(k+l)!}{k!l!} \operatorname{Alt}(\alpha \otimes \beta)$$

$$= \operatorname{sgn}(\tau) \alpha \wedge \beta$$

$$= (-1)^{kl} \alpha \wedge \beta$$

Exercise 2.2.2.7. Let $\alpha \in \Lambda^k(V)$. If k is odd, then $\alpha \wedge \alpha = 0$.

Proof. Suppose that k is odd. The previous exercise tells us that

$$\alpha \wedge \alpha = (-1)^{k^2} \alpha \wedge \alpha$$
$$= -\alpha \wedge \alpha$$

Thus $\alpha \wedge \alpha = 0$.

Exercise 2.2.2.8. Fundamental Example:

Let $\alpha_1, \dots, \alpha_m \in \Lambda^1(V)$ and $v_1, \dots, v_m \in V$. Then

$$\left(\bigwedge_{i=1}^{m} \alpha_i\right)(v_1, \cdots, v_m) = \det(\alpha_i(v_j))$$

Proof. The previous exercises tell us that

$$\begin{split} \bigg(\bigwedge_{i=1}^m \alpha_i\bigg)(v_1,\cdots,v_m) &= m! \operatorname{Alt}\bigg(\bigotimes_{i=1}^m \alpha_i\bigg)(v_1,\cdots,v_m) \\ &= m! \bigg[\frac{1}{m!} \sum_{\sigma \in S_m} \operatorname{sgn}(\sigma) \sigma\bigg(\bigotimes_{i=1}^m \alpha_i\bigg)\bigg](v_1,\cdots,v_m) \\ &= \sum_{\sigma \in S_m} \operatorname{sgn}(\sigma)\bigg(\bigotimes_{i=1}^m \alpha_i\bigg)(v_{\sigma(1)},\cdots,v_{\sigma(m)}) \\ &= \sum_{\sigma \in S_m} \operatorname{sgn}(\sigma) \prod_{i=1}^m \alpha_i(v_{\sigma(i)}) \\ &= \det(\alpha_i(v_j)) \end{split}$$

Note 2.2.2.9. Recall that $\mathcal{I}_{\wedge k} = \{(i_1, i_2, \cdots, i_k) \in \mathbb{N}^k : i_1 < i_2 < \cdots < i_k \le n\}$ and that $\#\mathcal{I}_{\wedge k} = \binom{n}{k}$. For the remainder of this section, we will write \mathcal{I}_k in place of $\mathcal{I}_{\wedge k}$.

Definition 2.2.2.10. Let $I = \{(i_1, i_2, \cdots, i_k) \in \mathcal{I}_k.$ Define $\epsilon^{\wedge I} \in \Lambda^k(V)$ by

$$\epsilon^{\wedge I} = \epsilon^{i_1} \wedge \cdots \wedge \epsilon^{i_k}$$

Exercise 2.2.2.11. Let $I=(i_1,\cdots,i_k)$ and $J=(j_1,\cdots,j_k)\in\mathcal{I}_k$. Then $\epsilon^{\wedge I}(e^J)=\delta_{I,J}$.

Proof. Put $A = \begin{pmatrix} \epsilon^{i_1}(e^{j_1}) & \cdots & \epsilon^{i_1}(e^{j_k}) \\ & \vdots & \\ \epsilon^{i_k}(e^{j_1}) & \cdots & \epsilon^{i_k}(e^{j_k}) \end{pmatrix}$. A previous exercise tells us that $\epsilon^{\wedge I}(e^J) = \det A$. If I = J, then

 $A = I_{k \times k}$ and therefore $\epsilon^I(e^J) = 1$. Suppose that $I \neq J$. Put $l_0 = \min\{l : 1 \leq l \leq k, i_l \neq j_l\}$. If $i_{l_0} < j_{l_0}$, then all entries on the l_0 -th row of A are 0. If $i_{l_0} > j_{l_0}$, then all entries on the l_0 -th column of A are 0.

Exercise 2.2.2.12. Let $\alpha, \beta \in \Lambda^k(V)$. If for each $I \in \mathcal{I}_k$, $\alpha(e^I) = \beta(e^I)$, then $\alpha = \beta$.

Proof. Suppose that for each $I \in \mathcal{I}_k$, $\alpha(e^I) = \beta(e^I)$. Let $v_1, \dots, v_k \in V$. For $i = 1, \dots, k$, write $v_i = 1, \dots, k$

 $\sum_{j_i=1}^n a_{i,j_i} e^{j_i}$. Then

$$\alpha(v_1, \dots, v_k) = \sum_{j_1, \dots, j_k = 1}^n \left(\prod_{i=1}^k a_{i,j_i} \right) \alpha(e^{j_1}, \dots, e^{j_k})$$

$$= \sum_{j_1 \neq \dots \neq j_k}^n \left(\prod_{i=1}^k a_{i,j_i} \right) \alpha(e^{j_1}, \dots, e^{j_k})$$

$$= \sum_{J \in \mathcal{I}_k} \left[\sum_{\sigma \in S_J} \operatorname{sgn}(\sigma) \left(\prod_{i=1}^k a_{i,\sigma(j_i)} \right) \right] \alpha(e^J)$$

$$= \sum_{J \in \mathcal{I}_k} \left[\sum_{\sigma \in S_J} \operatorname{sgn}(\sigma) \left(\prod_{i=1}^k a_{i,\sigma(j_i)} \right) \right] \beta(e^J)$$

$$= \sum_{j_1, \dots, j_k = 1}^n \left(\prod_{i=1}^k a_{i,j_i} \right) \beta(e^{j_1}, \dots, e^{j_k})$$

$$= \beta(v_1, \dots, v_k)$$

Exercise 2.2.2.13. The set $\{\epsilon^{\wedge I}: I \in \mathcal{I}_k\}$ is a basis for $\Lambda^k(V)$ and dim $\Lambda^k(V) = \binom{n}{k}$.

Proof. Let $(a_I)_{I \in \mathcal{I}_k} \subset \mathbb{R}$. Let $\alpha = \sum_{I \in \mathcal{I}_k} a_I \epsilon^{\wedge I}$. Suppose that $\alpha = 0$. Then for each $J \in \mathcal{I}_k$, $\alpha(e^J) = a_J = 0$.

Thus $\{\epsilon^{\wedge I}: I \in \mathcal{I}_k\}$ is linearly independent. Let $\beta \in \Lambda^k(V)$. For $I \in \mathcal{I}_k$, put $b_I = \beta(e^I)$. Define $\mu = \sum_{I \in \mathcal{I}_k} b_I \epsilon^{\wedge I} \in \Lambda^k(V)$. Then for each $J \in \mathcal{I}_k$, $\mu(e^J) = b_J = \beta(e^J)$. Hence $\mu = \beta$ and therefore $\beta \in \text{span}\{\epsilon^{\wedge I}: I \in \mathcal{I}_k\}$.

2.2.3 Interior Product

Definition 2.2.3.1. Let V be a finite dimensional vector space and $v \in V$. We define **interior multiplication by** v, denoted $\iota_v : T_k \to T_{k-1}$, by

$$\iota_v \alpha(w_1, \dots, w_{k-1}) = \alpha(v, w_1, \dots, w_{k-1})$$

Exercise 2.2.3.2. Let V be a finite dimensional vector space and $v \in V$. Then $\iota_v|_{\Lambda^k(V)} : \Lambda^k(V) \to \Lambda^{k-1}(V)$.

Proof. Let $\alpha \in \Lambda^k(V)$. Define $\beta \in \Lambda^k(V)$ by $\beta(w_1, \dots, w_k) = \alpha(w_k, w_1, \dots, w_{k-1})$. Let $\sigma \in S_{k-1}$. Define $\tau \in S_k$ by $\tau(j) = \begin{cases} 1 & j = k \\ \sigma(j) & j \neq k \end{cases}$. Let $w_1, \dots, w_{k-1} \in V$. Set $w_k = v$. Then

$$\sigma(\iota_{v}\alpha)(w_{1},\ldots,w_{k-1}) = \iota_{v}\alpha(w_{\sigma(1)},\ldots,w_{\sigma(k-1)})$$

$$= \alpha(v,w_{\sigma(1)},\ldots,w_{\sigma(k-1)})$$

$$= \beta(w_{\sigma(1)},\ldots,w_{\sigma(k-1)},v)$$

$$= \beta(w_{\sigma(1)},\ldots,w_{\sigma(k-1)},w_{k})$$

$$= \beta(w_{\tau(1)},\ldots,w_{\tau(k-1)},w_{\tau(k)})$$

$$= \operatorname{sgn}(\tau)\beta(w_{1},\ldots,w_{k-1},w_{k})$$

$$= \operatorname{sgn}(\sigma)\beta(w_{1},\ldots,w_{k-1},v)$$

$$= \operatorname{sgn}(\sigma)\alpha(v,w_{1},\ldots,w_{k-1})$$

$$= \operatorname{sgn}(\sigma)(\iota_{v}\alpha)(w_{1},\ldots,w_{k-1})$$

Since $w_1, \ldots, w_{k-1} \in V$ are arbitrary, $\sigma(\iota_v \alpha) = \operatorname{sgn}(\sigma) \iota_v \alpha$. Hence $\iota_v \alpha \in \Lambda^{k-1}(V)$.

2.3 (0,2)-Tensors

Definition 2.3.0.1. Let V be a finite dimensional vector space, $v \in V$ and $\alpha \in T_2^0(V)$. Then α is said to be **degenerate** if there exists $v \in V$ such that for each $w \in V$, $\alpha(v, w) = 0$ and $v \neq 0$.

Definition 2.3.0.2. Let V be a finite dimensional vector space, $\alpha \in T_2^0(V)$. We define $\phi_\alpha : V \to V^*$ by

$$\phi_{\alpha}(v) = \iota_v \alpha$$

Exercise 2.3.0.3. Let V be a finite dimensional vector space, $\alpha \in T_2^0(V)$. Then $\phi_\alpha \in L(V; V^*)$.

Proof. Let $v_1, v_2 \in V$ and $\lambda \in \mathbb{R}$. Then for each $w \in V$,

$$\phi_{\alpha}(v_1 + \lambda v_2)(w) = (\iota_{v_1 + \lambda v_2}\alpha)(w)$$

$$= \alpha(v_1 + \lambda v_2, w)$$

$$= \alpha(v_1, w) + \lambda \alpha(v_2, w)$$

$$= (\iota_{v_1}\alpha)(w) + \lambda(\iota_{v_2}\alpha)(w)$$

$$= \phi_{\alpha}(v_1)(w) + \lambda \phi_{\alpha}(v_2)(w)$$

$$= [\phi_{\alpha}(v_1) + \lambda \phi_{\alpha}(v_2)](w)$$

Therefore, $\phi_{\alpha}(v_1 + \lambda v_2) = \phi_{\alpha}(v_1) + \lambda \phi_{\alpha}(v_2)$. Thus $\phi_{\alpha} \in L(V; V^*)$.

Exercise 2.3.0.4. Let V be a finite dimensional vector space and $\alpha \in T_2^0(V)$. Then α is nondegenerate iff ϕ_{α} is an isomorphism.

Proof.

• (\Longrightarrow :) Suppose that α is nondegenerate. Let $v \in \ker \phi_{\alpha}$. Then for each $w \in V$,

$$\alpha(v, w) = (\iota_v \alpha)(w)$$
$$= \phi_{\alpha}(v)(w)$$
$$= 0$$

Since α is nondegenerate, v = 0. Since $v \in \ker \phi_{\alpha}$ is arbitrary, $\ker \phi_{\alpha} = \{0\}$. Hence ϕ_{α} is injective. Since $\dim V = \dim V^*$, ϕ_{α} is surjective. Hence ϕ_{α} is an isomorphism.

(⇐= :)

Suppose that ϕ_{α} is an isomorphism. Let $v \in V$. Suppose that for each $w \in V$, $\alpha(v, w) = 0$. Then for each $w \in V$,

$$\phi_{\alpha}(v)(w) = (\iota_{v}\alpha)(w)$$
$$= \alpha(v, w)$$
$$= 0$$

Thus $\phi_{\alpha}(v) = 0$ which implies that $v \in \ker \phi_{\alpha}$. Since ϕ_{α} is an isomorphism, v = 0. Hence α is nondegenerate.

Exercise 2.3.0.5. Let V be a finite dimensional vector space and $\alpha \in T_2^0(V)$. Then

- 1. $[\phi_{\alpha}]_{i,j} = \alpha(e_i, e_i)$
- 2. for each $v, w \in V$,

$$\alpha(v, w) = [w]^* [\phi_{\alpha}][v]$$

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Proof. 1. Set $A = [\phi_{\alpha}]$. Let $i, j \in \{1, ..., n\}$. By definition,

$$\phi_{\alpha}(e_j) = \sum_{k=1}^{n} A_{k,j} \epsilon^k$$

Then

$$\phi_{\alpha}(e_j)(e_i) = \sum_{k=1}^{n} A_{k,j} \epsilon^k(e_i)$$
$$= \sum_{k=1}^{n} A_{k,j} \delta_{k,i}$$
$$= A_{i,j}$$

2. Let $v, w \in V$. Then there exist $(v^i)_{i=1}^n, (w^j)_{j=1}^n \subset \mathbb{R}$ such that $v = \sum_{i=1}^n v^i e_i$ and $w = \sum_{j=1}^n v^j e_i$. Part (1) implies that

$$\alpha(v, w) = \sum_{i=1}^{n} \sum_{j=1}^{n} v^{i} w^{j} \alpha(e_{i}, e_{j})$$

$$= \sum_{i=1}^{n} \sum_{j=1}^{n} v^{i} w^{j} [\phi_{\alpha}]_{j,i}$$

$$= \sum_{i=1}^{n} \sum_{j=1}^{n} [v]_{i} [w]_{j} [\phi_{\alpha}]_{j,i}$$

$$= [w]^{*} [\phi_{\alpha}] [v]$$

2.3.1 Scalar Product Spaces

Definition 2.3.1.1. Let V be a finite dimensional vector space and $\alpha \in \Sigma^2(V)$. Then α is said to be

- positive semidefinite if for each $v \in V$, $\alpha(v, v) \geq 0$
- **positive definite** if for each $v \in V$, $v \neq 0$ implies that $\alpha(v, v) > 0$
- negative semidefinite if $-\alpha$ is positive semidefinite
- negative definite if $-\alpha$ is positive definite

Exercise 2.3.1.2. Let V be a finite dimensional vector space and $\alpha \in \Sigma^2(V)$. Then

- 1. α is positive definite iff for each $\lambda \in \sigma([\phi_{\alpha}]), \lambda > 0$
- 2. α is positive definite iff for each $\lambda \in \sigma([\phi_{\alpha}]), \lambda \geq 0$

Proof.

1. Suppose that α is positive definite. Write $\sigma(\phi_{\alpha}) = \{\lambda_1, \dots, \lambda_n\}$. Define $\Lambda \in \mathbb{R}^{n \times n}$ by $\Lambda = \operatorname{diag}(\lambda_1, \dots, \lambda_n)$. Since α is symmetric, $[\phi_{\alpha}]$ is symmetric. There exists $U \in O(n)$ such that $[\phi_{\alpha}] = U\Lambda U^*$. FINISH!!!

Definition 2.3.1.3. Let V be a finite dimensional vector space and $\alpha \in \Sigma^2(V)$. Then α is said to be a scalar product if α is nondegenerate. In this case, (V, α) is said to be a scalar product space.

Definition 2.3.1.4. Let V be a finite dimensional vector space and $\alpha \in \Sigma^2(V)$ a scalar product on V. We define the **index** of α , denoted ind α by

ind $\alpha = \max\{\dim W : W \text{ is a subspace of } V \text{ and } \alpha|_{W\times W} \text{ is negative definite}\}$

Definition 2.3.1.5. Let (V, α) be a scalar product space.

- Let $v_1, v_2 \in V$. Then v_1 and v_2 are said to be **orthogonal** if $\alpha(v_1, v_2) = 0$.
- Let $U \subset V$ be a subspace. We define the **orthogonal subspace** of U, denoted by U^{\perp} , by

$$U^{\perp} = \{ v \in V : \text{ for each } u \in U, \, \alpha(u, v) = 0 \}$$

Exercise 2.3.1.6. Let (V, α) be a scalar product space and $U \subset V$ a subspace. Then U^{\perp} is a subspace of V.

Proof. We note that since $U^{\perp} = \bigcap_{u \in U} \ker \phi_{\alpha}(u)$, U^{\perp} is a subspace of V.

Exercise 2.3.1.7. Let (V, α) be an n-dimensional scalar product space, $U \subset V$ a k-dimensional subspace and $(e_j)_{j=1}^n \subset V$ a basis for V. Suppose that $(e_j)_{j=1}^k$ is a basis for U. Then for each $v \in V$, $v \in U^{\perp}$ iff for each $j \in [k]$, $\alpha(v, e_j) = 0$.

Proof. Let $v \in V$.

- (\Longrightarrow): Suppose that $v \in U^{\perp}$. Since $(e_j)_{j=1}^k \subset U$, we have that for each $j \in [k]$, $\alpha(v, e_j) = 0$.
- (\Leftarrow): Suppose that for each $j \in [k]$, $\alpha(v, e_j) = 0$. Let $u \in U$. Then there exist $(a^j)_{j=1}^k \subset \mathbb{R}$ such that $u = \sum_{j=1}^k a^j u_j$. This implies that

$$\alpha(v, u) = \sum_{j=1}^{k} a^{j} \alpha(v, u_{j})$$
$$= 0$$

Since $u \in U$ is arbitrary, we have that $v \in U^{\perp}$.

Exercise 2.3.1.8. Let (V, α) be a scalar product space and $U \subset V$ a subspace. Then

- 1. $\dim V = \dim U + \dim U^{\perp}$
- 2. $(U^{\perp})^{\perp} = U$

Proof. 1. Set $n = \dim V$ and $k = \dim U$. Choose a basis $(e_j)_{j=1}^n$ such that $(e_j)_{j=1}^k$ is a basis for U.

2.

Exercise 2.3.1.9. Let V be a finite dimensional vector space and $\alpha \in \Sigma^2(V)$. Set $\sigma([\phi_{\alpha}])^- = {\lambda \in \sigma([\phi_{\alpha}]) : \lambda < 0}$. Then

$$\operatorname{ind} \alpha = \sum_{\lambda \in \sigma([\phi_{\alpha}])^{-}} \mu(\lambda)$$

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Proof. Since α is symmetric, there exist $U \in O(n)$ and $\Lambda \in D(n,\mathbb{R})$ such that $[\phi_{\alpha}] = U\Lambda U^*$. Define $(u_j)_{j=1}^n \subset V$ by $u_j = \sum_{i=1}^n U_{i,j} e_j$. Define $J^- = \{j \in [n] : \Lambda_{j,j} < 0\}$, $n^- = \#J^-$ and $V^- = \operatorname{span}\{u_j : j \in J^-\}$. Let $v \in V^-$. Then there exist $(a^j)_{j \in J^-}$ such that $v = \sum_{j \in J^-} a^j u_j$. We note that

$$\begin{split} U^*[\phi_\alpha]U &= U^*(U\Lambda U^*)U \\ &= (U^*U)\Lambda(U^*U) \\ &= I\Lambda I \\ &= \Lambda \end{split}$$

A previous exercise implies that

$$\begin{split} \alpha(v,v) &= \sum_{j \in J^{-}} \sum_{k \in J^{-}} a^{j} a^{k} \alpha(u_{j},u_{k}) \\ &= \sum_{j \in J^{-}} \sum_{k \in J^{-}} a^{j} a^{k} [u_{j}]^{*} [\phi_{\alpha}] [u_{k}] \\ &= \sum_{j \in J^{-}} \sum_{k \in J^{-}} a^{j} a^{k} ([e_{j}]^{*} U^{*}) [\phi_{\alpha}] (U[e_{k}]) \\ &= \sum_{j \in J^{-}} \sum_{k \in J^{-}} a^{j} a^{k} (U^{*} [\phi_{\alpha}] U)_{j,k} \\ &= \sum_{j \in J^{-}} \sum_{k \in J^{-}} a^{j} a^{k} (\Lambda)_{j,k} \\ &= \sum_{j \in J^{-}} |a^{j}|^{2} \Lambda_{j,j} \\ &< 0 \end{split}$$

Since $v \in V^-$ is arbitrary, $\alpha|_{V^- \times V^-}$ is negative definite. Thus

$$\operatorname{ind} \alpha \ge \dim V^-$$
$$= n^-$$

Set $J^+ = (J^-)^c$. Let $W \subset V$ be a subspace. Suppose that $\alpha|_{W \times W}$ is negative definite. For the sake of contradiction, suppose that there exists $j_0 \in J^+$ such that $u_{j_0} \in W$. Then

$$\alpha(u_{j_0}, u_{j_0}) = [u_{j_0}]^* [\phi_{\alpha}] [u_{j_0}]$$

$$= [u_{j_0}]^* U \Lambda U^* [u_{j_0}]$$

$$= \Lambda_{j_0, j_0}$$

$$> 0$$

which is a contradiction since $\alpha|_{W\times W}$ is negative definite. Thus for each $j\in J^+, u_j\notin W$.

2.3.2 Symplectic Vector Spaces

Definition 2.3.2.1. Let V be a finite dimensional vector space and $\omega \in \Lambda^2(V)$. Then ω is said to be a symplectic form if ω is nondegenerate. In this case (V, ω) is said to be a symplectic space.

Exercise 2.3.2.2. Let V be a 2n-dimensional vector space with basis $(a_j, b_j)_{j=1}^n$ and corresponding dual basis $(\alpha^j, \beta^j)_{j=1}^n$. Define $\omega \in \Lambda^2(V)$ by

$$\omega = \sum_{j=1}^{n} \alpha^{j} \wedge \beta^{j}$$

Then

1. for each $j, k \in \{1, ..., n\}$,

(a)
$$\omega(a_i, a_k) = 0$$

(b)
$$\omega(b_j, b_k) = 0$$

(c)
$$\omega(a_j, b_k) = \delta_{j,k}$$

2. (V, ω) is a symplectic space

Proof.

1. Let $j, k \in \{1, \dots, n\}$.

(a)

$$\omega(a_j, a_k) = \sum_{l=1}^n \alpha^l \wedge \beta^l(a_j, a_k)$$
$$= \sum_{l=1}^n [\alpha^l(a_j)\beta^l(a_k) - \alpha^l(a_k)\beta^l(a_j)]$$
$$= 0$$

(b) Similar to (a)

(c)

$$\omega(a_j, b_k) = \sum_{l=1}^n \alpha^l \wedge \beta^l(a_j, b_k)$$

$$= \sum_{l=1}^n [\alpha^l(a_j)\beta^l(b_k) - \alpha^l(b_k)\beta^l(a_j)]$$

$$= \sum_{l=1}^n \alpha^l(a_j)\beta^l(b_k)$$

$$= \sum_{l=1}^n \delta_{j,l}\delta_{l,k}$$

$$= \delta_{j,k}$$

2. Let $v \in V$. Then there exist $(q^j, p^j)_{j=1}^n \subset \mathbb{R}$ such that $v = \sum_{j=1}^n q^j a_j + p^j b_j$. Suppose that for each $w \in V$, $\omega(v, w) = 0$. Let $k \in \{1, \dots, n\}$. Then

$$0 = \omega(v, a_k)$$

$$= \sum_{j=1}^{n} q^j \omega(a_j, a_k) + p^j \omega(b_j, a_k)$$

$$= \sum_{j=1}^{n} p^j \delta_{j,k}$$

$$= p^k$$

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Similarly,

$$0 = \omega(v, b_k)$$

$$= \sum_{j=1}^{n} q^j \omega(a_j, b_k) + p^j \omega(b_j, b_k)$$

$$= \sum_{j=1}^{n} q^j \delta_{j,k}$$

$$= q^k$$

Since $k \in \{1, ..., n\}$ is arbitrary, v = 0. Hence ω is nondegenerate. Therefore (V, ω) is symplectic.

Exercise 2.3.2.3. Let (V, ω) be a symplectic space. Then dim V is even.

Proof. Set $n = \dim V$. Let $(e_j)_{j=1}^n$ be a basis for V. Define $[\omega] \in \mathbb{R}^{n \times n}$ by $[\omega]_{i,j} = \omega(e_i, e_j)$. Since $\omega \in \Lambda^2(V)$, $[\omega]^* = -[\omega]$. Therefore

$$det[\omega] = det[\omega]^*$$

$$= det(-[\omega])$$

$$= (-1)^n det[\omega]$$

For the sake of contradiction, suppose that n is odd. Then $\det[\omega] = -\det[\omega]$ which implies that $\det[\omega] = 0$. Since ω is nondegenerate, $[\omega] \in GL(n, \mathbb{R})$. This is a contradiction. Hence n is even.

Definition 2.3.2.4. Let (V, ω) be a symplectic space and $S \subset V$ a subspace. We define the **symplectic** complement of V, denoted S^{\perp} , by

$$S^{\perp} = \{ v \in V : \text{ for each } w \in S, \, \omega(v, w) = 0 \}$$

Exercise 2.3.2.5. Let (V, ω) be a symplectic space and $S \subset V$ a subspace. Then S^{\perp} is a subspace.

Proof. We note that

$$S^{\perp} = \bigcap_{v \in S} \ker \iota_v \omega$$

Hence S^{\perp} is a subspace.

Exercise 2.3.2.6. Let (V, ω) be a symplectic space and $S \subset V$ a subspace. Then

$$\dim V = \dim S + \dim S^{\perp}$$

Proof.

Exercise 2.3.2.7. Let (V, ω) be a symplectic space and $S \subset V$ a subspace. Then $(S^{\perp})^{\perp} = S$.

Proof. Let $v \in (S^{\perp})^{\perp}$. Then for each $w \in S^{\perp}$, $\omega(v, w) = 0$.

Chapter 3

Smooth Manifolds

3.1 Topological Manifolds

Exercise 3.1.0.1. We have that \mathbb{R} is homeomorphic to $(0, \infty)$

Proof. Define $f: \mathbb{R} \to (0, \infty)$ by $f(x) = e^x$. Then f is a homeomorphism.

Definition 3.1.0.2. Let $n \in \mathbb{N}$. We define the **upper half space** of \mathbb{R}^n , denoted \mathbb{H}^n , by

$$\mathbb{H}^n = \{(x_1, x_2, \cdots, x_n) \in \mathbb{R}^n : x_n \ge 0\}$$

and we define

$$\partial \mathbb{H}^n = \{(x_1, x_2, \cdots, x_n) \in \mathbb{R}^n : x_n = 0\}$$

Int
$$\mathbb{H}^n = \{(x_1, x_2, \cdots, x_n) \in \mathbb{R}^n : x_n > 0\}$$

We endow \mathbb{H}^n , $\partial \mathbb{H}^n$ and $\operatorname{Int} \mathbb{H}^n$ with the subspace topology inherited from \mathbb{R}^n .

We define the projection map $\pi: \partial \mathbb{H}^n \to \mathbb{R}^{n-1}$ by

$$\pi(x_1, \dots, x_{n-1}, 0) = (x_1, \dots, x_{n-1})$$

Definition 3.1.0.3. We define $\mathbb{R}^0 = \{0\}$ and $\mathbb{H}^0 = \emptyset$ endowed with the discrete topology.

Exercise 3.1.0.4. Let $n \in \mathbb{N}$.

- 1. $\partial \mathbb{H}^n$ is homeomorphic to \mathbb{R}^{n-1}
- 2. Int \mathbb{H}^n is homeomorphic to \mathbb{R}^n

Proof.

1. Let $\pi: \partial \mathbb{H}^n \to \mathbb{R}^{n-1}$ be the projection map given by

$$\pi(x_1,\ldots,x_{n-1},0)=(x_1,\ldots,x_{n-1})$$

Then π is a homeomorphism.

2. Define $f: \mathbb{R}^n \to \operatorname{Int} \mathbb{H}^n$ by $f(x_1, \dots, x_{n-1}, x_n) = (x_1, \dots, x_{n-1}, e^{x_n})$. Then f is a homeomorphism.

Definition 3.1.0.5. Let (M, \mathcal{T}) be a topological space and $n \in \mathbb{N}_0$. Let $U \subset M$ and $V \subset \mathbb{H}^n$ and $\phi : U \to V$. Then (U, ϕ) is said to be a *n*-coordinate chart on (M, \mathcal{T}) if

- $U \in \mathcal{T}$
- $V \in \mathcal{T}_{\mathbb{H}^n}$

• ϕ is a $(\mathcal{T} \cap U, \mathcal{T}_{\mathbb{H}^n} \cap V)$ -homeomorphism

We denote the set of all *n*-coordinate charts on M by $X^n(M, \mathcal{T})$.

Note 3.1.0.6. We will write $X^n(M)$ in place of $X^n(M,\mathcal{T})$ when the topology is not ambiguous.

Definition 3.1.0.7. Let M be a topological space and $n \in \mathbb{N}$. Then M is said to be **locally Euclidean of dimension** n if for each $p \in M$, there exists $(U, \phi) \in X^n(M)$ such that $p \in U$.

Definition 3.1.0.8. Let M be a topological space and $n \in \mathbb{N}$. Then M is said to be an n-dimensional topological manifold if

- 1. M is Hausdorff
- 2. M is second-countable
- 3. M is locally Euclidean of dimension n

Theorem 3.1.0.9. Topological Invariance of Dimension:

Let M be an n-dimensional toplogical manifold and N a p-dimensional toplogical manifold. If M and N are homeomorphic, then n = p.

Note 3.1.0.10. In light of the previous theorem, we write X(M) in place of $X^n(M)$ and refer to n-coordinate charts as coordinate charts when the context is clear.

Definition 3.1.0.11. Let M be an n-dimensional topological manifold and $(U, \phi) \in X(M)$. Then (U, ϕ) is said to be an

- interior chart if $\phi(U)$ is open in \mathbb{R}^n
- boundary chart if $\phi(U)$ is open in \mathbb{H}^n and $\phi(U) \cap \partial \mathbb{H}^n \neq \emptyset$

We denote the set of all interior charts on M and the set of all boundary charts on M by $X_{\text{Int}}(M)$ and $X_{\partial}(M)$ respectively.

Exercise 3.1.0.12. Let M be an n-dimensional topological manifold. Then

- 1. $X(M) = X_{\text{Int}}(M) \cup X_{\partial}(M)$
- 2. $X_{\text{Int}}(M) \cap X_{\partial}(M) = \emptyset$

Proof.

1. By definition, $X_{\text{Int}}(M) \cup X_{\partial}(M) \subset X(M)$. Let $(U, \phi) \in X(M)$. Since (U, ϕ) is a coordinate chart on M, $\phi(U)$ is open in \mathbb{R}^n or $\phi(U)$ is open in \mathbb{H}^n . If $\phi(U)$ is open in \mathbb{R}^n , then

$$(U, \phi) \in X_{\operatorname{Int}}(M)$$

 $\subset X_{\operatorname{Int}}(M) \cup X_{\partial}(M)$

Suppose that $\phi(U)$ is open in \mathbb{H}^n . If $\phi(U) \cap \partial \mathbb{H}^n = \emptyset$, then $\phi(U)$ is open in \mathbb{R}^n and

$$(U, \phi) \in X_{\operatorname{Int}}(M)$$

 $\subset X_{\operatorname{Int}}(M) \cup X_{\partial}(M)$

Suppose that $\phi(U) \cap \partial \mathbb{H}^n \neq \emptyset$. Then

$$(U, \phi) \in X_{\partial}(M)$$

 $\subset X_{\operatorname{Int}}(M) \cup X_{\partial}(M)$

Since $(U, \phi) \in X(M)$ is arbitrary, $X(M) \subset X_{\operatorname{Int}}(M) \cup X_{\partial}(M)$. Therefore $X(M) = X_{\operatorname{Int}}(M) \cup X_{\partial}(M)$.

2. For the sake of contradiction, suppose that $X_{\operatorname{Int}}(M) \cup X_{\partial}(M) \neq \emptyset$. Then there exists $(U, \phi) \in X(M)$ such that $(U, \phi) \in X_{\operatorname{Int}}(M)$ and $(U, \phi) \in X_{\partial}(M)$. Therefore $\phi(U)$ is open in \mathbb{R}^n , $\phi(U)$ is open in \mathbb{H}^n and $\phi(U) \cap \partial \mathbb{H}^n \neq \emptyset$. Since $\phi(U)$ is open in \mathbb{R}^n and $\phi(U) \subset \mathbb{H}^n$, $\phi(U) \subset \operatorname{Int} \mathbb{H}^n$ and therefore $\phi(U) \cap \partial \mathbb{H}^n = \emptyset$ which is a contradiction.

Definition 3.1.0.13. Let M be an n-dimensional topological manifold. We define the

• **interior** of M, denoted Int M, by

Int
$$M = \{ p \in M : \text{there exists } (U, \phi) \in X_{\text{Int}}(M) \text{ such that } p \in U \}$$

• boundary of M, denoted ∂M , by

$$\partial M = \{ p \in M : \text{there exists } (V, \psi) \in X_{\partial}(M) \text{ such that } p \in V \text{ and } \psi(p) \in \partial \mathbb{H}^n \}$$

Exercise 3.1.0.14. Let M be an n-dimensional topological manifold. Let $(U, \phi) \in X_{\operatorname{Int}}(M)$. Then $U \subset \operatorname{Int} M$.

Proof. Let $p \in U$. Since $(U, \phi) \in X_{\text{Int}}(M)$ and $p \in U$, by definition, $p \in \text{Int } M$. Since $p \in U$ is arbitrary, $U \subset \text{Int } M$.

Exercise 3.1.0.15. Let M be an n-dimensional topological manifold, $(U, \phi) \in X_{\partial}(M)$ and $p \in U$. If $\phi(p) \notin \partial \mathbb{H}^n$, then $p \in \text{Int } M$.

Proof. Suppose that $\phi(p) \notin \partial \mathbb{H}^n$. Then $\phi(p) \in \operatorname{Int} \mathbb{H}^n$. Hence there exists $B' \subset \phi(U)$ such that B' is open in \mathbb{R}^n and $\phi(p) \in B'$. Set $U' = \phi^{-1}(B')$ and $\phi' = \phi|_{U'}$. Then U' is open in M and $\phi' : U' \to B'$ is a homeomorphism. Hence $(U', \phi') \in X_{\operatorname{Int}}(M)$. Since $\phi(p) \in B'$, we have that $p \in U'$. By definition, $p \in \operatorname{Int} M$.

Exercise 3.1.0.16. Let M be an n-dimensional topological manifold. Then

- 1. $M = \operatorname{Int} M \cup \partial M$
- 2. Int $M \cap \partial M = \emptyset$

Hint: simply connected

Proof.

1. By definition, $\operatorname{Int} M \cup \partial M \subset M$. Let $p \in M$. Since M is a manifold, there exists $(U, \phi) \in X(M)$ such that $p \in U$. A previous exercise implies that $(U, \phi) \in X_{\operatorname{Int}}(M) \cup X_{\partial}(M)$. If $(U, \phi) \in X_{\operatorname{Int}}(M)$, then by definition,

$$p \in \operatorname{Int} M$$
$$\subset \operatorname{Int} M \cup \partial M$$

Suppose that $(U, \phi) \in X_{\partial}(M)$. If $\phi(p) \in \partial \mathbb{H}^n$, then by definition,

$$p \in \partial M$$
$$\subset \operatorname{Int} M \cup \partial M$$

Suppose that $\phi(p) \notin \partial \mathbb{H}^n$. The previous exercise implies that $p \in \text{Int } M$. Therefore,

$$p \in \operatorname{Int} M$$
$$\subset \operatorname{Int} M \cup \partial M$$

Since $p \in M$ is arbitrary, $M \subset \operatorname{Int} M \cup \partial M$. Therefore $M = \operatorname{Int} M \cup \partial M$.

2. For the sake of contradiction, suppose that Int $M \cap \partial M \neq \emptyset$. Then there exists $p \in M$ such that $p \in \text{Int } M \cap \partial M$. By definition, there exists $(U, \phi) \in X_{\text{Int}}(M)$, $(V, \psi) \in X_{\partial}(M)$ such that $p \in U \cap V$ and $\psi(p) \in \partial \mathbb{H}^n$. Note that $\psi(U \cap V)$ is open in \mathbb{H}^n , $\phi(U \cap V)$ is open in \mathbb{R}^n and $\phi|_{U \cap V} \circ (\psi|_{U \cap V})^{-1}$: $\psi^{-1}(U \cap V) \to \phi(U \cap V)$ is a homeomorphism.

Since $\psi(U \cap V)$ is open in \mathbb{H}^n , there exists an $B_{\psi} \subset \psi(U \cap V)$ such that B_{ψ} is open in \mathbb{H}^n , B_{ψ} is simply connected and $\psi(p) \in B_{\psi}$. Set $B_{\phi} = \phi \circ \psi^{-1}(B_{\psi})$. Since $\phi(U \cap V)$ is open in \mathbb{R}^n , B_{ϕ} is open in \mathbb{R}^n . Since B_{ψ} is simply connected and $\phi|_{U \cap V} \circ (\psi|_{U \cap V})^{-1} : \psi^{-1}(U \cap V) \to \phi(U \cap V)$ is a homeomorphism, B_{ϕ} is simply connected.

Set $B'_{\phi} = B_{\phi} \setminus \{\phi(p)\}$ and $B'_{\psi} = B_{\psi} \setminus \{\psi(p)\}$. Then $\phi \circ \psi^{-1} : B'_{\psi} \to B'_{\phi}$ is a homeomorphism. Since $\psi(p) \in \partial \mathbb{H}^n$, B'_{ψ} is simply connected. Since B_{ϕ} is open in \mathbb{R}^n , B'_{ϕ} is not simply connected. This is a contradiction since B'_{ϕ} is homeomorphic to B'_{ψ} . So $\partial M \cap \operatorname{Int} M = \emptyset$.

Exercise 3.1.0.17. Let M be an n-dimensional topological manifold. Then

- 1. Int M is open
- 2. ∂M is closed

Proof.

- 1. Let $p \in \text{Int } M$. Then there exists $(U, \phi) \in X_{\text{Int}}(M)$ such that $p \in U$. By definition, U is open and a previous exercise implies that $U \subset \text{Int } M$. Since $p \in \text{Int } M$ is arbitrary, we have that for each $p \in \text{Int } M$, there exists $U \subset \text{Int } M$ such that U is open. Hence Int M is open.
- 2. Since $\partial M = (\operatorname{Int} M)^c$, and $\operatorname{Int} M$ is open, we have that ∂M is closed.

Exercise 3.1.0.18. Let M be an n-dimensional topological manifold, $(U, \phi) \in X(M)$ and $p \in U$. If $p \in \partial M$, then $(U, \phi) \in X_{\partial}(M)$.

Hint: simply connected

Proof. Suppose that $p \in \partial M$. Then there exists a $(V, \psi) \in X_{\partial}(M)$ such that $p \in V$ and $\psi(p) \in \partial \mathbb{H}^n$. Note that $\psi(U \cap V)$ is open in \mathbb{H}^n , $\phi(U \cap V)$ is open in \mathbb{R}^n and $\phi|_{U \cap V} \circ (\psi|_{U \cap V})^{-1} : \psi^{-1}(U \cap V) \to \phi(U \cap V)$ is a homeomorphism.

Since $\psi(U \cap V)$ is open in \mathbb{H}^n , there exists $B_{\psi} \subset \psi(U \cap V)$ such B_{ψ} is open in \mathbb{H}^n , B_{ψ} is simply connected and $\psi(p) \in B_{\psi}$. Set $B_{\phi} = \phi \circ \psi^{-1}(B_{\psi})$.

For the sake of contradiction, suppose that $(U, \phi) \in X_{\text{Int}}(M)$. Then $\phi(U)$ is open in \mathbb{R}^n . Hence $\phi(U \cap V)$ is open in \mathbb{R}^n and B_{ϕ} is open in \mathbb{R}^n . Since $\phi|_{U \cap V} \circ (\psi|_{U \cap V})^{-1} : \psi^{-1}(U \cap V) \to \phi(U \cap V)$ is a homeomorphism, B_{ϕ} is simply connected. Set $B'_{\phi} = B_{\phi} \setminus \{\phi(p)\}$ and $B'_{\psi} = B_{\psi} \setminus \{\psi(p)\}$. Since $\psi(p) \in \partial \mathbb{H}^n$, B'_{ψ} is simply connected. Since B_{ϕ} is open in \mathbb{R}^n , B'_{ϕ} is not simply connected. This is a contradiction since B'_{ϕ} is homeomorphic to B'_{ψ} . So $(U, \phi) \notin X_{\text{Int}}(M)$. Since $(X_{\text{Int}}(M))^c = X_{\partial}(M)$, we have that $(U, \phi) \in X_{\partial}(M)$.

Exercise 3.1.0.19. Let M be an n-dimensional topological manifold, $(U, \phi) \in X_{\partial}(M)$ and $p \in U$. Then

- 1. $p \in \partial M$ iff $\phi(p) \in \partial \mathbb{H}^n$
- 2. $p \in \operatorname{Int} M \text{ iff } \phi(p) \in \operatorname{Int} \mathbb{H}^n$

Proof.

1. Suppose that $p \in \partial M$. For the sake of contradiction, suppose that $\phi(p) \notin \partial \mathbb{H}^n$. Then $\phi(p) \in \operatorname{Int} \mathbb{H}^n$. Hence there exists $B' \subset \phi(U)$ such that B' is open in \mathbb{R}^n and $\phi(p) \in B'$. Set $U' = \phi^{-1}(B')$ and $\phi' = \phi|_{U'}$. Then $p \in U'$ and $(U', \phi') \in X_{\operatorname{Int}}(M)$. Since $p \in U'$, the previous exercise implies that $(U', \phi') \in X_{\partial}(M)$. This is a contradiction since $X_{\operatorname{Int}}(M) \cap X_{\partial}(M) = \emptyset$. So $\phi(p) \in \partial \mathbb{H}^n$. Conversely, suppose that $\phi(p) \in \partial \mathbb{H}^n$. By definition, $p \in \partial M$.

2. A previous exercise implies that Int $M = (\partial M)^c$. Part (1) implies that

$$p \in (\partial M)^c$$
$$= \operatorname{Int} M$$

if and only if

$$\phi(p) \in (\partial \mathbb{H}^n)^c$$
$$= \operatorname{Int} \mathbb{H}^n$$

Exercise 3.1.0.20. Let M be an n-dimensional topological manifold and $p \in M$. Then $p \in \partial M$ iff for each $(U, \phi) \in X(M)$, $p \in U$ implies that $(U, \phi) \in X_{\partial}(M)$ and $\phi(p) \in \partial \mathbb{H}^n$.

Proof. Suppose that $p \in \partial M$. Let $(U, \phi) \in X(M)$. Suppose that $p \in U$. The previous two exercises imply that $(U, \phi) \in X_{\partial}(M)$ and $\phi(p) \in \partial \mathbb{H}^n$.

Conversely, suppose that for each $(U, \phi) \in X(M)$, $p \in U$ implies that $(U, \phi) \in X_{\partial}(M)$ and $\phi(p) \in \partial \mathbb{H}^n$. Since M is a manifold, there exists $(U, \phi) \in X(M)$ such that $p \in U$. By assumption, $(U, \phi) \in X_{\partial}(M)$ and $\phi(p) \in \partial \mathbb{H}^n$. By definition, $p \in \partial M$.

Exercise 3.1.0.21. Let M be an n-dimensional topological manifold. Let $(U, \phi) \in X_{\partial}(M)$. Then

- 1. $\phi(U \cap \partial M) = \phi(U) \cap \partial \mathbb{H}^n$
- 2. $\phi(U \cap \operatorname{Int} M) = \phi(U) \cap \operatorname{Int} \mathbb{H}^n$

Proof.

1. Since $(U, \phi) \in X_{\partial}(M)$, a previous exercise implies that for each $p \in U$, $p \in \partial M$ iff $\phi(p) \in \partial \mathbb{H}^n$. Let $q \in \phi(U \cap \partial M)$. Then there exists $p \in U \cap \partial M$ such that $\phi(p) = q$. Since $p \in \partial M$, $\phi(p) \in \partial \mathbb{H}^n$. Hence

$$q = \phi(p)$$

$$\in \phi(U) \cap \partial \mathbb{H}^n$$

Since $q \in \phi(U \cap \partial M)$ is arbitrary, $\phi(U \cap \partial M) \subset \phi(U) \cap \partial \mathbb{H}^n$.

Let $q \in \phi(U) \cap \partial \mathbb{H}^n$. Then there exists $p \in U$ such that $q = \phi(p)$. Since $\phi(p) \in \partial \mathbb{H}^n$, we have that $p \in \partial M$. Hence $p \in U \cap \partial M$ and

$$q = \phi(p)$$
$$\in \phi(U \cap \partial M)$$

Since $q \in \phi(U) \cap \partial \mathbb{H}^n$ is arbitrary, $\phi(U) \cap \partial \mathbb{H}^n \subset \phi(U \cap \partial M)$. Thus $\phi(U \cap \partial M) = \phi(U) \cap \partial \mathbb{H}^n$.

2. Since $(U, \phi) \in X_{\partial}(M)$, a previous exercise implies that for each $p \in U$, $p \in \text{Int } M$ iff $\phi(p) \in \text{Int } \mathbb{H}^n$. Let $q \in \phi(U \cap \text{Int } M)$. Then there exists $p \in U \cap \text{Int } M$ such that $\phi(p) = q$. Since $p \in \text{Int } M$, $\phi(p) \in \text{Int } \mathbb{H}^n$. Hence

$$q = \phi(p)$$

$$\in \phi(U) \cap \operatorname{Int} \mathbb{H}^n$$

Since $q \in \phi(U \cap \operatorname{Int} M)$ is arbitrary, $\phi(U \cap \operatorname{Int} M) \subset \phi(U) \cap \operatorname{Int} \mathbb{H}^n$.

Let $q \in \phi(U) \cap \operatorname{Int} \mathbb{H}^n$. Then there exists $p \in U$ such that $q = \phi(p)$. Since $\phi(p) \in \operatorname{Int} \mathbb{H}^n$, we have that $p \in \operatorname{Int} M$. Hence $p \in U \cap \operatorname{Int} M$ and

$$q = \phi(p)$$
$$\in \phi(U \cap \partial M)$$

Since $q \in \phi(U) \cap \partial \mathbb{H}^n$ is arbitrary, $\phi(U) \cap \partial \mathbb{H}^n \subset \phi(U \cap \operatorname{Int} M)$. Thus $\phi(U \cap \operatorname{Int} M) = \phi(U) \cap \operatorname{Int} \mathbb{H}^n$.

Definition 3.1.0.22. Let M be an n-dimensional topological manifold and $\pi: \partial \mathbb{H}^n \to \mathbb{R}^{n-1}$ the projection map. For $(U, \phi) \in X_{\partial}(M)$, we define $\bar{U} \subset \partial M$ and $\bar{\phi}: \bar{U} \to \pi(\phi(\bar{U}))$ by $\bar{U} = U \cap \partial M$ and $\bar{\phi} = \pi \circ \phi|_{\bar{U}}$ respectively.

Exercise 3.1.0.23. Let M be an n-dimensional topological manifold, and $\lambda: \partial \mathbb{H}^n \to \mathbb{R}^{n-1}$ a homeomorphism. Then $\{(\bar{U}, \bar{\phi}): (U, \phi) \in X_{\partial}(M)\} \subset X_{\mathrm{Int}}^{n-1}(\partial M)$.

Proof. Let $(U, \phi) \in X_{\partial}(M)$.

- 1. Since U is open in M, $\bar{U} = U \cap \partial M$ is open in ∂M .
- 2. Since $(U, \phi) \in X_{\partial}(M)$, $\phi(U)$ is open in \mathbb{H}^n . A previous exercise implies that $\phi(\bar{U}) = \phi(U) \cap \partial \mathbb{H}^n$ which is open in $\partial \mathbb{H}^n$. Since $\pi : \partial \mathbb{H}^n \to \mathbb{R}^{n-1}$ is a homeomorphism, we have that $\pi(\phi(\bar{U}))$ is open in \mathbb{R}^{n-1} .
- 3. Since $\phi|_{\bar{U}}: \bar{U} \to \phi(U) \cap \partial \mathbb{H}^n$ and $\pi|_{\phi(\bar{U})}: \phi(\bar{U}) \to \lambda(\phi(\bar{U}))$ are homeomorphisms, we have that $\bar{\phi} = \pi|_{\phi(\bar{U})} \circ \phi|_{\bar{U}}$ is a homeomorphism.

Hence
$$(\bar{U}, \bar{\phi}) \in X^{n-1}_{\text{Int}}(\partial M)$$
.

Exercise 3.1.0.24. Let M be an n-dimensional topological manifold. Then

- 1. ∂M is an (n-1)-dimensional topological manifold
- 2. $\partial(\partial M) = \emptyset$

Proof.

- 1. (a) Since M is Hausdorff, ∂M is Hausdorff.
 - (b) Since M is second-countable, ∂M is second countable.
 - (c) Let $p \in \partial M$. Then there exists $(U, \phi) \in X_{\partial}(M)$ such that $\phi(p) \in \partial \mathbb{H}^n$. Then $p \in \overline{U}$ and the previous exercise implies that $(\overline{U}, \overline{\phi}) \in X_{\operatorname{Int}}^{n-1}(\partial M)$. Thus ∂M is locally Euclidean of dimension n-1.

Hence ∂M is an (n-1)-dimensional topological manifold.

2. Let $p \in \partial M$. Part (1) implies that there exists $(U, \phi) \in X^{n-1}_{\operatorname{Int}}(\partial M)$ such that $p \in U$. Thus $p \in \operatorname{Int} \partial M$. Since $p \in \partial M$ is arbitrary, $\operatorname{Int} \partial M = \partial M$. Hence

$$\partial(\partial M) = (\operatorname{Int}(\partial M))^{c}$$
$$= (\partial M)^{c}$$
$$= \varnothing$$

Exercise 3.1.0.25. Let M be an n-dimensional topological manifold, $(U, \phi) \in X(M)$ and $U' \subset U$. If U' is open in M, then $(U', \phi|_{U'}) \in X^n(M)$.

Proof. Suppose that U' is open in M. Set $\phi' = \phi|_{U'}$.

- By assumption U' is open in M.
- Since U' is open in M, we have that $U' = U' \cap U$ is open in U. Since ϕ is a homeomorphism and U' is open in U, we have that $\phi(U')$ is open in $\phi(U)$. By assumption $\phi(U)$ is open in \mathbb{R}^n or $\phi(U)$ is open in \mathbb{H}^n . Therefore $\phi'(U')$ is open in \mathbb{R}^n or $\phi'(U')$ is open in \mathbb{H}^n .
- Since $\phi: U \to V$ is a homeomorphism, $\phi': U' \to \phi'(U')$ is a homeomorphism.

So
$$(U', \phi') \in X^n(M)$$
.

Note 3.1.0.26. Since U is open in M, U' being open in U is equivalent to U' being open in M, so we could have also assumed that U' is open in U.

Exercise 3.1.0.27. Let M be an n-dimensional topological manifold and $U \subset M$. If U is open, then

$$X^n(U) = \{(V, \psi) \in X^n(M) : V \subset U\}$$

Proof. Suppose that U is open and set $A = \{(V, \psi) \in X^n(M) : V \subset U\}$. Let $(V, \psi) \in X^n(U)$. By definition of $X^n(U)$, V is open in U. Thus, there exists $W \subset M$ such that W is open in M and $V = U \cap W$. Since U is open in M, we have that $V = U \cap W$ is open in M. Hence $(V, \psi) \in X^n(M)$ which implies that $(V, \psi) \in A$. Since $(V, \psi) \in X^n(U)$ is arbitary, $X^n(U) \subset A$.

Conversely, suppose that $(V, \psi) \in A$. Then $(V, \psi) \in X^n(M)$ and $V \subset U$. By definition of $X^n(M)$, V is open in M. Since $V \subset U$, we have that $V = V \cap U$ is open in U. Hence $(V, \psi) \in X^n(U)$. Since $(V, \psi) \in X^n(U)$ is arbitary, $A \subset X^n(U)$. Hence $X^n(A) = A$.

Exercise 3.1.0.28. Let M be an n-dimensional topological manifold, $(U, \phi) \in X(M)$ and $U' \subset U$. If U' is open in M, then $(U', \phi|_{U'}) \in X^n(U)$.

Proof. Suppose that U' is open in M. A previous exercise implies that $(U', \phi') \in X^n(M)$. The previous exercise implies that $(U', \phi') \in X^n(U)$.

Exercise 3.1.0.29. Topological Open Submanifolds:

Let M be an n-dimensional topological manifold and $U \subset M$ open. Then U is an n-dimensional topological manifold.

Proof.

- 1. Since M is Hausdorff, U is Hausdorff.
- 2. M is second-countable, U is second countable.
- 3. Let $p \in U$. Since then there exists $(V, \psi) \in X^n(M)$ such that $p \in V$. Set $V' = U \cap V$ and $\psi' = \psi|_{U \cap V}$. The previous exercise implies that $(V', \psi') \in X^n(U)$. Therefore U is locally Euclidean of dimension n.

Hence U is an n-dimensional topological manifold.

Exercise 3.1.0.30. Let M be an n-dimensional topological manifold and $U \subset M$. If U is open, then

- 1. $X_{\text{Int}}(U) = \{(V, \psi) \in X_{\text{Int}}(M) : V \subset U\}$
- 2. $X_{\partial}(U) = \{(V, \psi) \in X_{\partial}(M) : V \subset U\}$

Proof. Suppose that U is open in M.

- 1. Set $A = \{(V, \psi) \in X_{\operatorname{Int}}(M) : V \subset U\}$. Let $(V, \psi) \in X_{\operatorname{Int}}(U)$. By definition of $X_{\operatorname{Int}}(U)$, V is open in U and $\phi(V)$ is open in \mathbb{R}^n . Since U is open in M, V is open in M. Hence $(V, \psi) \in X_{\operatorname{Int}}(M)$. Since U is open in M, V is open in M. Hence $(V, \psi) \in X_{\operatorname{Int}}(M)$ which implies that $(V, \psi) \in A$. Since $(V, \psi) \in X_{\operatorname{Int}}(U)$ is arbitrary, $X_{\operatorname{Int}}(U) \subset A$. Conversely, let $(V, \psi) \in A$. Then $(V, \psi) \in X_{\operatorname{Int}}(M)$ and $V \subset U$. By definition of $X_{\operatorname{Int}}(M)$, V is open in M and $\phi(V)$ is open in \mathbb{R}^n . Thus $V = V \cap U$ is open in U. So $(V, \psi) \in X_{\operatorname{Int}}(U)$. Since $(V, \psi) \in A$ is arbitrary, $A \subset X_{\operatorname{Int}}(U)$. Thus $X_{\operatorname{Int}}(U) = A$.
- 2. Set $B = \{(V, \psi) \in X_{\partial}(M) : V \subset U\}$. Let $(V, \psi) \in X_{\partial}(U)$. By definition of $X_{\partial}(U)$, V is open in U, $\phi(V)$ is open in \mathbb{H}^n and $\partial \mathbb{H}^n \cap \phi(V) \neq \varnothing$. Since U is open in M, V is open in M. Hence $(V, \psi) \in X_{\partial}(M)$, which implies that $(V, \psi) \in B$. Since $(V, \psi) \in X_{\partial}(U)$ is arbitrary, $X_{\partial}(U) \subset B$. Conversely, let $(V, \psi) \in B$. Then $(V, \psi) \in X_{\partial}(M)$ and $V \subset U$. By definition of $X_{\partial}(M)$, V is open in V, V is open in V is open in V. So V is open in V is open in V is open in V. So V is arbitrary, V is open in V is open in V is open in V. Since V is arbitrary, V is arbitrary, V is open in V is open in V. So V is open in V is open in V. So V is open in V is open in V is open in V. So V is open in V. So V is open in V is open in V is open in V is open in V. Since V is open in V

Exercise 3.1.0.31. Let M be an n-dimensional topological manifold and $U \subset M$. If U is open, then $\partial U = \partial M \cap U$.

Proof. Suppose that U is open. Let $p \in \partial U$. Then there exists $(V, \psi) \in X_{\partial}(U)$ such that $p \in V$ and $\psi(p) \in \partial \mathbb{H}^n$. Since U is open, the previous exercise implies that $(V, \psi) \in X_{\partial}(M)$. Thus $p \in \partial M$. Since $p \in \partial U$ is arbitrary, $\partial U \subset \partial M$. Since $\partial U \subset U$, we have that $\partial U \subset \partial M \cap U$.

Conversely, let $p \in \partial M \cap U$. Since $p \in \partial M$, there exists $(V, \psi) \in X_{\partial}(M)$ such that $p \in V$ and $\psi(p) \in \partial \mathbb{H}^n$. Set $V' = V \cap U$ and $\psi' = \psi|_{V'}$. Then $p \in V'$ since V and U are open in M, V' is open in M. A previous exercise implies that $(V', \psi') \in X(M)$. Since $p \in \partial M$, a previous exercise implies that $(V', \psi') \in X_{\partial}(M)$. The previous exercise implies that $(V', \psi') \in X_{\partial}(U)$. Since $\psi'(p) \in \partial \mathbb{H}^n$, $p \in \partial U$. Since $p \in \partial M \cap U$ is arbitrary, $\partial M \cap U \subset \partial U$. Hence $\partial U = \partial M \cap U$.

label exercises and reference them!!!

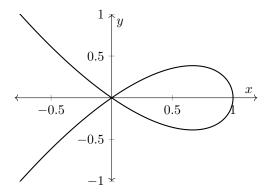
Exercise 3.1.0.32. Graph of Continuous Function:

Let $f \in C(\mathbb{R})$. Set $M = \{(x,y) \in \mathbb{R}^2 : f(x) = y\}$ (i.e. the graph of f). Then M is a 1-dimensional manifold.

Proof. Set $U = \mathbb{R}$ and define $\phi : U \to M$ by $\phi(x) = (x, f(x))$. Then $\phi^{-1} = \pi_1$. Since f is continuous, ϕ is continuous. Since π_1 is continuous, ϕ is a homeomorphism.

Exercise 3.1.0.33. Nodal Cubic:

Let $M = \{(x,y) \in \mathbb{R}^2 : y^2 = x^2 - x^3\}$. We equip M with the subspace topology.



Then M is not a 1-dimensional topological manifold.

Hint: connected components

Proof. Suppose that M is a 1-dimensional manifold. Set p=(0,0). Then there exists $(U,\phi)\in X(M)$ such that $p\in U$. Since $\phi(U)$ is open (in $\mathbb R$ or $\mathbb H$), there exists a $B\subset \phi(U)$ such that B is open (in $\mathbb R$ or $\mathbb H$), B is connected and $\phi(p)\in B$. Set $V=\phi^{-1}(B),\ V'=V\setminus\{p\}$ and $B'=B\setminus\{\phi(p)\}$. Then $\phi:V\to B$ and $\phi':V'\to B'$ are homeomorphisms. Since B is open (in $\mathbb R$ or $\mathbb H$) and connected, B' has at most two connected components. Then V' This is a contradiction since V' has four connected components and B' and V' are homeomorphic.

Exercise 3.1.0.34. Topological Manifold Chart Lemma:

Let M be a set, Γ an index set and for each $\alpha \in \Gamma$, $U_{\alpha} \subset M$ and $\phi_{\alpha} : U_{\alpha} \to \mathbb{H}^n$. Suppose that

- for each $\alpha \in \Gamma$, $\phi_{\alpha}(U_{\alpha}) \in \mathcal{T}_{\mathbb{H}^n}$
- for each $\alpha, \beta \in \Gamma$, $\phi_{\alpha}(U_{\alpha} \cap U_{\beta}) \in \mathcal{T}_{\mathbb{H}^n}$
- for each $\alpha \in \Gamma$, $\phi_{\alpha}: U_{\alpha} \to \phi_{\alpha}(U_{\alpha})$ is a bijection
- for each $\alpha, \beta \in \Gamma$, $\phi_{\beta}|_{U_{\alpha} \cap U_{\beta}} \circ (\phi_{\alpha}|_{U_{\alpha} \cap U_{\beta}})^{-1} : \phi_{\alpha}(U_{\alpha} \cap U_{\beta}) \to \phi_{\beta}(U_{\alpha} \cap U_{\beta})$ is continuous
- there exists $\Gamma' \subset \Gamma$ such that Γ' is countable and $M \subset \bigcup_{\alpha \in \Gamma'} U_{\alpha}$

• for each $p, q \in M$, there exists $\alpha \in \Gamma$ such that $p, q \in U_{\alpha}$ or there exist $\alpha, \beta \in \Gamma$ such that $p \in U_{\alpha}$, $q \in U_{\beta}$ and $U_{\alpha} \cap U_{\beta} = \emptyset$

Define

- $\mathcal{B} = \{\phi_{\alpha}^{-1}(V) : V \in \mathcal{T}_{\mathbb{H}^n} \text{ and } \alpha \in \Gamma\}$
- $\mathcal{T}_M = \tau(\mathcal{B})$

Then

- 1. \mathcal{B} is a basis for \mathcal{T}_M **Hint:** For $B_1, B_2 \subset \mathbb{H}^n$, $\phi_{\alpha_1}^{-1}(B_1) \cap \phi_{\alpha_2}^{-1}(B_2) = \phi_{\alpha_1}^{-1}(B_1 \cap [\phi_{\alpha_1}|_{U_{\alpha_1} \cap U_{\alpha_2}} \circ (\phi_{\alpha_2}|_{U_{\alpha_1} \cap U_{\alpha_2}})^{-1}(B_2)])$
- 2. (M, \mathcal{T}_M) is an *n*-dimensional topological manifold
- 3. \mathcal{T}_M is the unique topology \mathcal{T} on M such that $(U_\alpha, \phi_\alpha)_{\alpha \in \Gamma} \subset X^n(M, \mathcal{T})$

Proof.

- 1. By assumption, $M \subset \bigcup_{\alpha \in \Gamma} U_{\alpha}$
 - Let $A_1, A_2 \in \mathcal{B}$ and $p \in A_1 \cap A_2$. By definition, there exist $\alpha_1, \alpha_2 \in \Gamma$ and $B_1, B_2 \subset \mathbb{H}^n$ such that B_1, B_2 are open in \mathbb{H}^n and

$$A_1 = \phi_{\alpha_1}^{-1}(B_1)$$

$$\subset U_{\alpha_1}$$

$$A_2 = \phi_{\alpha_2}^{-1}(B_2)$$

$$\subset U_{\alpha_2}$$

Set $\psi_1 = \phi_{\alpha_1}|_{U_{\alpha_1} \cap U_{\alpha_2}}$ and $\psi_2 = \phi_{\alpha_2}|_{U_{\alpha_1} \cap U_{\alpha_2}}$. We note that

$$\psi_1^{-1}(B_1) = U_{\alpha_2} \cap \phi_{\alpha_1}^{-1}(B_1) \qquad \qquad \psi_2^{-1}(B_2) = U_{\alpha_1} \cap \phi_{\alpha_2}^{-1}(B_2)$$

$$= U_{\alpha_2} \cap A_1 \qquad \qquad = U_{\alpha_1} \cap A_2$$

$$\subset U_{\alpha_1} \cap U_{\alpha_2} \qquad \qquad \subset U_{\alpha_1} \cap U_{\alpha_2}$$

Let $q \in \phi_{\alpha_1}^{-1}(B_1 \cap [\psi_1 \circ \psi_2^{-1}(B_2)])$. Then $\phi_{\alpha_1}(q) \in B_1 \cap [\psi_1 \circ \psi_2^{-1}(B_2)]$. Hence $\phi_{\alpha_1}(q) \in B_1$ and $\phi_{\alpha_1}(q) \in \psi_1 \circ \psi_2^{-1}(B_2)$. This implies that

$$q \in \phi_{\alpha_1}^{-1}(B_1)$$
$$= A_1$$

and since $\psi_2^{-1}(B_2) \subset U_{\alpha_1} \cap U_{\alpha_2}$ and $\phi_{\alpha_1}: U_{\alpha_1} \to \phi_{\alpha_1}(U_{\alpha_1})$ is a bijection, we have that

$$q \in \phi_{\alpha_1}^{-1}(\psi_1 \circ \psi_2^{-1}(B_2))$$

= $\psi_2^{-1}(B_2)$
= $U_{\alpha_1} \cap A_2$

Thus

$$q \in A_1 \cap (U_{\alpha_1} \cap A_2)$$
$$= A_1 \cap A_2$$

Since $q \in \phi_{\alpha_1}^{-1}(B_1 \cap [\psi_1 \circ \psi_2^{-1}(B_2)])$ is arbitrary, we have that $\phi_{\alpha_1}^{-1}(B_1 \cap [\psi_1 \circ \psi_2^{-1}(B_2)]) \subset A_1 \cap A_2$. Conversely, let

$$q \in A_1 \cap A_2$$

= $\phi_{\alpha_1}^{-1}(B_1) \cap \phi_{\alpha_2}^{-1}(B_2)$

Then $\phi_{\alpha_1}(q) \in B_1$ and $\phi_{\alpha_2}(q) \in B_2$. Since $A_1 \cap A_2 \subset U_{\alpha_1} \cap U_{\alpha_2}$, we have that

$$\psi_2(q) = \phi_{\alpha_2}(q)$$
$$\in B_2$$

which implies that $q \in \psi_2^{-1}(B_2)$. Therefore

$$\phi_{\alpha_1}(q) = \psi_1(q) \in \psi_1(\psi_2^{-1}(B_2)) = \psi_1 \circ \psi_2^{-1}(B_2)$$

Hence $\phi_{\alpha_1}(q) \in B_1 \cap [\psi_1 \circ \psi_2^{-1}(B_2)]$. This implies that $q \in \phi_{\alpha_1}^{-1}(B_1 \cap [\psi_1 \circ \psi_2^{-1}(B_2)])$. Since $q \in A_1 \cap A_2$ is arbitrary, we have that $A_1 \cap A_2 \subset \phi_{\alpha_1}^{-1}(B_1 \cap [\psi_1 \circ \psi_2^{-1}(B_2)])$. Thus

$$A_1 \cap A_2 = \phi_{\alpha_1}^{-1}(B_1 \cap [\psi_1 \circ \psi_2^{-1}(B_2)])$$

 $\in \mathcal{B}$

Thus \mathcal{B} is a basis for \mathcal{T}_M .

2. (a) (locally Euclidean of dimension n):

Let $\alpha \in \Gamma$. By definition, for each $B \subset \mathcal{T}_{\mathbb{H}^n}$,

$$\phi_{\alpha}^{-1}(B) \in \mathcal{B}$$

$$\subset \mathcal{T}_{\Lambda}$$

Hence ϕ_{α} is continuous.

Let $A \in \mathcal{T}_{U_{\alpha}}$. Then there exists $U \subset \mathcal{T}_M$ such that $A = U \cap U_{\alpha}$. Since \mathcal{B} is a basis for \mathcal{T}_M , there exists $\Gamma' \subset \Gamma$, $(V_{\beta})_{\beta \in \Gamma'} \subset \mathcal{T}_{\mathbb{H}^n}$ such that $U = \bigcup_{\beta \in \Gamma'} \phi_{\beta}^{-1}(V_{\beta})$. Thus

$$A = U \cap U_{\alpha}$$

$$= \left[\bigcup_{\beta \in \Gamma'} \phi_{\beta}^{-1}(V_{\beta}) \right] \cap U_{\alpha}$$

$$= \bigcup_{\beta \in \Gamma'} [\phi_{\beta}^{-1}(V_{\beta}) \cap U_{\alpha}]$$

Let $\beta \in \Gamma'$. Since $\phi_{\alpha}(U_{\alpha} \cap U_{\beta}) \subset \phi_{\alpha}(U_{\alpha})$ and $\phi_{\alpha}(U_{\alpha} \cap U_{\beta}) \in \mathcal{T}_{\mathbb{H}^n}$, we have that

$$\phi_{\alpha}(U_{\alpha} \cap U_{\beta}) = \phi_{\alpha}(U_{\alpha}) \cap \phi_{\alpha}(U_{\alpha} \cap U_{\beta})$$
$$\in \mathcal{T}_{\phi_{\alpha}(U_{\alpha})}$$

Therefore $\mathcal{T}_{\phi_{\alpha}(U_{\alpha}\cap U_{\beta})} \subset \mathcal{T}_{\phi_{\alpha}(U_{\alpha})}$. Since $(\phi_{\beta}|_{U_{\alpha}\cap U_{\beta}}) \circ (\phi_{\alpha}|_{U_{\alpha}\cap U_{\beta}})^{-1} : \phi_{\alpha}(U_{\alpha}\cap U_{\beta}) \to \phi_{\beta}(U_{\alpha}\cap U_{\beta})$ is continuous, we have that $(\phi_{\beta}|_{U_{\alpha}\cap U_{\beta}}) \circ (\phi_{\alpha}|_{U_{\alpha}\cap U_{\beta}})^{-1} : \phi_{\alpha}(U_{\alpha}\cap U_{\beta}) \to \mathbb{H}^{n}$ is continuous and therefore

$$[(\phi_{\beta}|_{U_{\alpha}\cap U_{\beta}})\circ(\phi_{\alpha}|_{U_{\alpha}\cap U_{\beta}})^{-1}]^{-1}(V_{\beta})\in\mathcal{T}_{\phi_{\alpha}(U_{\alpha}\cap U_{\beta})}$$
$$\subset\mathcal{T}_{\phi_{\alpha}(U_{\alpha})}$$

Since $\beta \in \Gamma'$ is arbitrary, we have that

$$\phi_{\alpha}(A) = \phi_{\alpha} \left(\bigcup_{\beta \in \Gamma'} [\phi_{\beta}^{-1}(V_{\beta}) \cap U_{\alpha}] \right)$$

$$= \bigcup_{\beta \in \Gamma'} \phi_{\alpha}(\phi_{\beta}^{-1}(V_{\beta}) \cap U_{\alpha})$$

$$= \bigcup_{\beta \in \Gamma'} (\phi_{\alpha}|_{U_{\alpha} \cap U_{\beta}}) \circ (\phi_{\beta}|_{U_{\alpha} \cap U_{\beta}})^{-1}(V_{\beta})$$

$$= \bigcup_{\beta \in \Gamma'} [(\phi_{\beta}|_{U_{\alpha} \cap U_{\beta}}) \circ (\phi_{\alpha}|_{U_{\alpha} \cap U_{\beta}})^{-1}]^{-1}(V_{\beta})$$

$$\in \mathcal{T}_{\phi_{\alpha}(U_{\alpha})}$$

Since $A \in \mathcal{T}_{U_{\alpha}}$ is arbitrary, $\phi_{\alpha}^{-1}: \phi_{\alpha}(U_{\alpha}) \to U_{\alpha}$ is continuous. Hence $\phi_{\alpha}: U_{\alpha} \to \phi_{\alpha}(U_{\alpha})$ is a homeomorphism and $(U_{\alpha}, \phi_{\alpha}) \in X^{n}(M)$. Since $M = \bigcup_{\alpha \in \Gamma} U_{\alpha}$, we have that M is locally Euclidean of dimension n.

(b) (Hausdorff):

Let $p, q \in M$. Suppose that $p \neq q$. Then there exists $\alpha \in \Gamma$ such that $p, q \in U_{\alpha}$ or there exist $\alpha, \beta \in \Gamma$ such that $p \in U_{\alpha}, q \in U_{\beta}$ and $U_{\alpha} \cap U_{\beta} = \emptyset$.

- Suppose that there exists $\alpha \in \Gamma$ such that $p, q \in U_{\alpha}$. Since $p \neq q$, $\phi_{\alpha}(p) \neq \phi_{\alpha}(q)$. Since \mathbb{H}^n is Hausdorff, there exist $V_p, V_q \subset \phi(U_{\alpha})$ such that V_p and V_q are open in \mathbb{H}^n , $p \in V_p$, $q \in V_q$ and $V_p \cap V_q = \emptyset$. Set $U_p = \phi_{\alpha}^{-1}(V_p)$ and $U_q = \phi_{\alpha}^{-1}V_q$. Then U_p, U_q are open, $p \in U_p$, $q \in U_q$ and $U_q \cap U_p = \emptyset$.
- Suppose that there exist $\alpha, \beta \in \Gamma$ such that $p \in U_{\alpha}$, $q \in U_{\beta}$ and $U_{\alpha} \cap U_{\beta} = \emptyset$. Set $U_p = U_{\alpha}$ and $U_q = U_{\beta}$. Then U_p, U_q are open, $p \in U_p$, $q \in U_q$ and $U_q \cap U_p = \emptyset$.

Thus for each $p,q\in M$ there exist $U_p,U_q\subset M$ such that U_p,U_q are open, $p\in U_p,\,q\in U_q$ and $U_q\cap U_p=\varnothing$. Hence

(c) (second-countable):

By assumption, there exists $\Gamma' \subset \Gamma$ such that Γ' is countable and $M \subset \bigcup_{\alpha \in \Gamma'} U_{\alpha}$. Let $\alpha \in \Gamma'$. Since $\phi_{\alpha}(U_{\alpha}) \in \mathcal{T}_{\mathbb{H}^n}$ and \mathbb{H}^n is second-countable, we have that $\phi_{\alpha}(U_{\alpha})$ is second-countable. Since $\phi_{\alpha}: U_{\alpha} \to \phi_{\alpha}(U_{\alpha})$ is a homeomorphism, we have that U_{α} is second-countable. Since $M = \bigcup_{\alpha \in \Gamma'} U_{\alpha}$, an exercise in topology cite implies that M is second-countable.

3. Let \mathcal{T} be a topology on M. Suppose that $(U_{\alpha}, \phi_{\alpha})_{\alpha \in \Gamma} \subset X^{n}(M, \mathcal{T})$. Then for each $\alpha \in \Gamma$, $U_{\alpha} \in \mathcal{T}$ and $\phi_{\alpha} : U_{\alpha} \to \phi_{\alpha}(U_{\alpha})$ is a $(\mathcal{T} \cap U_{\alpha}, \mathcal{T}_{\mathbb{H}^{n}} \cap \phi_{\alpha}(U_{\alpha}))$ -homeomorphism. Let $U \in \mathcal{B}$. By definition, there exists $\alpha \in \Gamma$ and $V \in \mathcal{T}_{\mathbb{H}^{n}}$ such that $U = \phi_{\alpha}^{-1}(V)$. Since $U_{\alpha} \in \mathcal{T}$, we have that $\mathcal{T} \cap U_{\alpha} \subset \mathcal{T}$. Since $V \cap \phi_{\alpha}(U_{\alpha}) \in \mathcal{T}_{\mathbb{H}^{n}} \cap \phi_{\alpha}(U_{\alpha})$, and ϕ_{α} is a $(\mathcal{T} \cap U_{\alpha}, \mathcal{T}_{\mathbb{H}^{n}} \cap \phi_{\alpha}(U_{\alpha}))$ -homeomorphism, we have that

$$U = \phi_{\alpha}^{-1}(V)$$

$$= \phi_{\alpha}^{-1}(V \cap \phi_{\alpha}(U_{\alpha}))$$

$$\in \mathcal{T} \cap U_{\alpha}$$

$$\subset \mathcal{T}$$

Since $U \in \mathcal{B}$ is arbitrary, $\mathcal{B} \subset \mathcal{T}$. Therefore

$$\mathcal{T}_M = \tau(\mathcal{B})$$

$$\subset \tau(\mathcal{T})$$

$$= \mathcal{T}$$

Conversely, Let $U \in \mathcal{T}$ and $\alpha \in \Gamma$. Then $U \cap U_{\alpha} \in \mathcal{T} \cap U_{\alpha}$. Since $\phi_{\alpha} : U_{\alpha} \to \phi_{\alpha}(U_{\alpha})$ is a $(\mathcal{T} \cap U_{\alpha}, \mathcal{T}_{\mathbb{H}^{n}} \cap \phi_{\alpha}(U_{\alpha}))$ -homeomorphism, we have that $\phi_{\alpha}(U \cap U_{\alpha}) \in \mathcal{T}_{\mathbb{H}^{n}} \cap \phi_{\alpha}(U_{\alpha})$. Since $U_{\alpha} \in \mathcal{T}_{M}$, $\mathcal{T}_{M} \cap U_{\alpha} \subset \mathcal{T}_{M}$. Since $\phi_{\alpha} : U_{\alpha} \to \phi_{\alpha}(U_{\alpha})$ is a $(\mathcal{T}_{M} \cap U_{\alpha}, \mathcal{T}_{\mathbb{H}^{n}} \cap \phi_{\alpha}(U_{\alpha}))$ -homeomorphism, we have that

$$U \cap U_{\alpha} = \phi_{\alpha}^{-1}(\phi_{\alpha}(U \cap U_{\alpha}))$$

$$\in \mathcal{T}_{M} \cap U_{\alpha}$$

$$\subset \mathcal{T}_{M}$$

Then

$$U = U \cap M$$

$$= U \cap \left(\bigcup_{\alpha \in \Gamma} U_{\alpha}\right)$$

$$= \bigcup_{\alpha \in \Gamma} (U \cap U_{\alpha})$$

$$\in \mathcal{T}_{M}$$

Since $U \in \mathcal{T}$ is arbitrary, $\mathcal{T} \subset \mathcal{T}_M$. Thus $\mathcal{T} = \mathcal{T}_M$.

Exercise 3.1.0.35. Let M be a set, Γ an index set and for each $\alpha \in \Gamma$, $U_{\alpha} \subset M$ and $\phi_{\alpha} : U_{\alpha} \to \mathbb{H}^n$. Suppose that

- for each $\alpha \in \Gamma$, $\phi_{\alpha}(U_{\alpha}) \in \mathcal{T}_{\mathbb{H}^n}$
- for each $\alpha, \beta \in \Gamma$, $\phi_{\alpha}(U_{\alpha} \cap U_{\beta}) \in \mathcal{T}_{\mathbb{H}^n}$
- for each $\alpha \in \Gamma$, $\phi_{\alpha} : U_{\alpha} \to \phi_{\alpha}(U_{\alpha})$ is a bijection
- for each $\alpha, \beta \in \Gamma$, $\phi_{\beta}|_{U_{\alpha} \cap U_{\beta}} \circ (\phi_{\alpha}|_{U_{\alpha} \cap U_{\beta}})^{-1} : \phi_{\alpha}(U_{\alpha} \cap U_{\beta}) \to \phi_{\beta}(U_{\alpha} \cap U_{\beta})$ is continuous
- there exists $\Gamma' \subset \Gamma$ such that Γ' is countable and $M \subset \bigcup_{\alpha \in \Gamma'} U_{\alpha}$
- for each $p, q \in M$, there exists $\alpha \in \Gamma$ such that $p, q \in U_{\alpha}$ or there exist $\alpha, \beta \in \Gamma$ such that $p \in U_{\alpha}$, $q \in U_{\beta}$ and $U_{\alpha} \cap U_{\beta} = \emptyset$

Then there exists a unique topology \mathcal{T}_M on M such that (M, \mathcal{T}_M) is an n-dimensional topological manifold and $(U_{\alpha}, \phi_{\alpha})_{\alpha \in \Gamma} \subset X^n(M, \mathcal{T}_M)$.

Proof. Immediate by previous exercise.

3.2 Smooth Manifolds

Definition 3.2.0.1. Let M be an n-dimensional topological manifold and $(U, \phi), (V, \psi) \in X(M)$. Then (U, ϕ) and (V, ψ) are said to be **smoothly compatible** if

$$\psi|_{U\cap V}\circ(\phi|_{U\cap V})^{-1}:\phi(U\cap V)\to\psi(U\cap V)$$
 is a diffeomorphism

Definition 3.2.0.2. Let M be an n-dimensional topological manifold.

- Let $A \subset X(M)$. Then A is said to be an **atlas on** M if $M \subset \bigcup_{(U,\phi) \in A} U$.
- Let \mathcal{A} be an atlas on M. Then \mathcal{A} is said to be **smooth** if for each $(U, \phi), (V, \psi) \in \mathcal{A}, (U, \phi)$ and (V, ψ) are smoothly compatible.
- Let \mathcal{A} be a smooth atlas on M. Then \mathcal{A} is said to be **maximal** if for each smooth atlas \mathcal{B} on M, $\mathcal{A} \subset \mathcal{B}$ implies that $\mathcal{A} = \mathcal{B}$. A maximal smooth atlas on M is called a **smooth structure on** M.
- Let \mathcal{A} be an atlas on M. Then (M, \mathcal{A}) is said to be an n-dimensional smooth manifold if \mathcal{A} is a smooth structure on M.

Exercise 3.2.0.3. Let M be an n-dimensional topological manifold and \mathcal{B} a smooth atlas on M. Then there exists a unique smooth structure \mathcal{A} on M such that $\mathcal{B} \subset \mathcal{A}$.

Proof. Define

$$\mathcal{A} = \{(U, \phi) \in X(M) : \text{ for each } (V, \psi) \in \mathcal{B}, (U, \phi) \text{ and } (V, \psi) \text{ are smoothly compatible} \}$$

Clearly $\mathcal{B} \subset \mathcal{A}$. Let (U, ϕ) and $(V, \psi) \in \mathcal{A}$. Define $F : \phi(U \cap V) \to \psi(U \cap V)$ by

$$F = \psi|_{U \cap V} \circ (\phi|_{U \cap V})^{-1}$$

Let $q \in \phi(U \cap V)$. Set $p = \phi^{-1}(q)$. Since $p \in U \cap V \subset M$, there exists $(W, \chi) \in \mathcal{B}$ such that $p \in W$. By definition of \mathcal{A} , $\psi|_{W \cap V} \circ (\chi|_{W \cap V})^{-1} : \chi(W \cap V) \to \psi(W \cap V)$ and $\chi|_{U \cap W} \circ (\phi|_{U \cap W})^{-1} : \phi(U \cap W) \to \chi(U \cap W)$ are diffeomorphisms. Set $N = U \cap W \cap V$. Then $q \in \phi(N) \subset \phi(U \cap V)$ and

$$F|_{\phi(N)} = \psi|_{N} \circ (\phi|_{N})^{-1}$$

= $[\psi|_{N} \circ (\chi|_{N})^{-1}] \circ [\chi|_{N} \circ (\phi|_{N})^{-1}]$

is a diffeomorphism. Thus, for each $q \in \phi(U \cap V)$, there exists $N' \subset \phi(U \cap V)$ such that $F|_{N'}$ is a diffeomorphism. Hence F is a diffeomorphism and (U, ϕ) , (V, ψ) are smoothly compatible. Therefore \mathcal{A} is a smooth atlas.

To see that \mathcal{A} is maximal, let \mathcal{B}' be a smooth atlas on M. Suppose that $\mathcal{A} \subset \mathcal{B}'$ and let $(U, \phi) \in \mathcal{B}'$. By definition, for each chart $(V, \psi) \in \mathcal{B}'$, (U, ϕ) and (V, ψ) are smoothly compatible. Since $\mathcal{B} \subset \mathcal{A} \subset \mathcal{B}'$, we have that $(U, \phi) \in \mathcal{A}$. So $\mathcal{A} = \mathcal{B}'$ and \mathcal{A} is a maximal smooth atlas on M.

Exercise 3.2.0.4. Let (M, \mathcal{A}) be an *n*-dimensional smooth manifold, $(U, \phi) \in \mathcal{A}$ and $U' \subset U$. If U' is open, then $(U', \phi|_{U'}) \in \mathcal{A}$.

Proof. Set $\phi' = \phi|_{U'}$. A previous exercise implies that $(U', \phi') \in X(U)$. Define $\mathcal{B} = \mathcal{A} \cup \{(U', \phi')\}$. Let $(V, \psi) \in \mathcal{B}$. If $(V, \psi) = (U', \phi')$, then

$$\phi' \circ \psi^{-1} = \mathrm{id}_{U'}$$

which is a diffeomorphism. Thus (U', ϕ') , (V, ψ) are smoothly compatible. Suppose that $(V, \psi) \in \mathcal{A}$. Since \mathcal{A} is smooth, $\psi|_{U\cap V} \circ (\phi|_{U\cap V})^{-1} : \phi(U\cap V) \to \psi(U\cap V)$ is a diffeomorphism. Therefore $\psi|_{U'\cap V} \circ (\phi'|_{U'\cap V})^{-1} : \phi'(U'\cap V) \to \psi(U'\cap V)$ is a diffeomorphism and (U', ϕ') , (V, ψ) are smoothly compatible. Since $(V, \psi) \in \mathcal{A}$ is arbitrary, \mathcal{B} is smooth. Since \mathcal{A} is maximal and $\mathcal{A} \subset \mathcal{B}$, we have that $\mathcal{A} = \mathcal{B}$ and $(U', \phi') \in \mathcal{A}$.

Exercise 3.2.0.5. Let (M, \mathcal{A}) be a n-dimensional smooth manifold and $U \subset M$ open. Set $\mathcal{B} = \{(V, \psi) \in \mathcal{A} : V \subset U\}$. Then \mathcal{B} is a smooth atlas on U.

Proof.

• Some previous exercises imply that U is an n-dimensional topological manifold and $X(U) = \{(V, \psi) \in X(M) : V \subset U\}$. Since

$$\mathcal{B} \subset \mathcal{A}$$
$$\subset X(M)$$

we have that $\mathcal{B} \subset X(U)$. Let $p \in U$. Then there exists $(V, \psi) \in \mathcal{A}$ such that $p \in V$. Set $V' = U \cap V$ and $\psi' = \psi|_{V'}$. The previous exercise implies that $(V', \psi') \in \mathcal{A}$. By definition, $(V', \psi') \in \mathcal{B}$. Since $p \in U$ is arbitrary, we have that for each $p \in U$, there exists $(V', \psi') \in \mathcal{B}$ such that $p \in V'$. Hence \mathcal{B} is an atlas on U.

• Let $(V_1, \psi_1), (V_2, \psi_2) \in \mathcal{B}$. Then $(V_1, \psi_1), (V_2, \psi_2) \in \mathcal{A}$. Since \mathcal{A} is smooth, (V_1, ψ_1) and (V_2, ψ_2) are smoothly compatible. Since $(V_1, \psi_1), (V_2, \psi_2) \in \mathcal{B}$ are arbitrary, \mathcal{B} is smooth.

Definition 3.2.0.6. Smooth Open Submanifold:

Let (M, \mathcal{A}) be an *n*-dimensional smooth manifold and $U \subset M$ open. A previous exercise implies that U is an *n*-dimensional topological manifold. We define $\mathcal{A}|_U \subset X(U)$ to be the unique smooth structure on U such that $\{(V, \psi) \in \mathcal{A} : V \subset U\} \subset \mathcal{A}|_{\mathcal{U}}$. Then $(U, \mathcal{A}|_U)$ is said to be a **smooth open submanifold of** (M, \mathcal{A}) .

Exercise 3.2.0.7. Let $\pi: \partial \mathbb{H}^n \to \mathbb{R}^{n-1}$ be the projection map given by $\pi(x_1, \dots, x_{n-1}, 0) = (x_1, \dots, x_{n-1})$. Then π is a diffeomorphism.

Proof. Define projection map $\pi': \mathbb{R}^n \to \mathbb{R}^{n-1}$ by $\pi'(x_1, \dots, x_{n-1}, x_n) = (x_1, \dots, x_{n-1})$. Then \mathbb{R}^n is an open neighborhood of ∂H^n , $\pi'|_{\partial H^n} = \pi$ and π' is smooth. Then by definition, π is smooth. Clearly, π^{-1} is smooth. So π is a diffeomorphism.

Definition 3.2.0.8. Let (M, \mathcal{A}) be a n-dimensional smooth manifold and $\pi : \partial \mathbb{H}^n \to \mathbb{R}^{n-1}$ the projection map. Recall that for $(U, \phi) \in X^n_{\partial}(M)$, the (n-1)-coordinate chart $(\bar{U}, \bar{\phi}) \in X^{n-1}_{\mathrm{Int}}(\partial M)$ is defined by $\bar{U} = U \cap \partial M$ and $\bar{\phi} = \pi|_{\phi(\bar{U})} \circ \phi|_{\bar{U}}$. We define

$$\overline{\mathcal{A}} = \{(\bar{U}, \bar{\phi}) : (U, \phi) \in \mathcal{A} \cap X_{\partial}^n(M)\}\$$

Exercise 3.2.0.9. Let (M, \mathcal{A}) be a n-dimensional smooth manifold. Then $\overline{\mathcal{A}}$ is a smooth atlas on ∂M .

Proof.

- A previous exercise implies that ∂M is an (n-1)-dimensional topological manifold. Let $p \in \partial M$. Then there exists $(U,\phi) \in \mathcal{A}$ such that $p \in U$. Since $\mathcal{A} \subset X^n(M)$ and $p \in \partial M$, we have that $p \in \overline{U}$ and a previous exercise implies that $(U,\phi) \in X^n_{\partial}(M)$. By definition of $\overline{\mathcal{A}}$, $(\overline{U},\overline{\phi}) \in \overline{\mathcal{A}}$. Since $p \in \partial M$ is arbitrary, $\overline{\mathcal{A}}$ is an atlas on ∂M .
- Let $(\bar{U}, \bar{\phi})$, $(\bar{V}, \bar{\psi}) \in \bar{\mathcal{A}}$. Since (U, ϕ) and (V, ψ) are smoothly compatible, $\psi|_{U \cap V} \circ (\phi|_{U \cap V})^{-1}$ is a diffeomorphism. Thus $\psi|_{\bar{U} \cap \bar{V}} \circ (\phi|_{\bar{U} \cap \bar{V}})^{-1}$ is a diffeomorphism. Since $\pi|_{\phi(U \cap V)}$ and $\pi|_{\psi(U \cap V)}$ are diffeomorphisms, $\pi|_{\phi(\bar{U} \cap \bar{V})}$ and $\pi|_{\psi(\bar{U} \cap \bar{V})}$ are diffeomorphisms. Then

$$\begin{split} \bar{\psi}|_{\bar{U}\cap\bar{V}} \circ (\bar{\phi}|_{\bar{U}\cap\bar{V}})^{-1} &= \left[\pi|_{\psi(\bar{U}\cap\bar{V})} \circ \psi|_{\bar{U}\cap\bar{V}}\right] \circ \left[(\phi|_{\bar{U}\cap\bar{V}})^{-1} \circ (\pi|_{\phi(\bar{U}\cap\bar{V})})^{-1}\right] \\ &= \pi|_{\psi(\bar{U}\cap\bar{V})} \circ \left[\psi|_{\bar{U}\cap\bar{V}} \circ (\phi|_{\bar{U}\cap\bar{V}})^{-1}\right] \circ (\pi|_{\phi(\bar{U}\cap\bar{V})})^{-1} \end{split}$$

is a diffeomorphism. Therefore $(\bar{U}, \bar{\phi})$ and $(\bar{V}, \bar{\psi})$ are smoothly compatible. Since $(\bar{U}, \bar{\phi}), (\bar{V}, \bar{\psi}) \in \overline{\mathcal{A}}$ are arbitrary, \mathcal{A} is smooth.

Definition 3.2.0.10. Let (M, \mathcal{A}) be a n-dimensional smooth manifold. We define $\mathcal{A}|_{\partial M}$ to be the unique smooth structure on ∂M such that $\overline{\mathcal{A}} \subset \mathcal{A}|_{\partial M}$. We define the **smooth boundary submanifold of** M to be $(\partial M, \mathcal{A}|_{\partial M})$.

Exercise 3.2.0.11. Smooth Manifold Chart Lemma:

Let M be a set, Γ an index set and for each $\alpha \in \Gamma$, $U_{\alpha} \subset M$ and $\phi_{\alpha} : U_{\alpha} \to \mathbb{H}^n$. Suppose that

- (a) for each $\alpha \in \Gamma$, $\phi_{\alpha}(U_{\alpha}) \in \mathcal{T}_{\mathbb{H}^n}$
- (b) for each $\alpha, \beta \in \Gamma$, $\phi_{\alpha}(U_{\alpha} \cap U_{\beta}) \in \mathcal{T}_{\mathbb{H}^n}$
- (c) for each $\alpha \in \Gamma$, $\phi_{\alpha} : U_{\alpha} \to \phi_{\alpha}(U_{\alpha})$ is a bijection
- (d) for each $\alpha, \beta \in \Gamma$, $\phi_{\beta}|_{U_{\alpha} \cap U_{\beta}} \circ (\phi_{\alpha}|_{U_{\alpha} \cap U_{\beta}})^{-1} : \phi_{\alpha}(U_{\alpha} \cap U_{\beta}) \to \phi_{\beta}(U_{\alpha} \cap U_{\beta})$ is smooth
- (e) there exists $\Gamma' \subset \Gamma$ such that Γ' is countable and $M \subset \bigcup_{\alpha \in \Gamma'} U_{\alpha}$
- (f) for each $p, q \in M$, there exists $\alpha \in \Gamma$ such that $p, q \in U_{\alpha}$ or there exist $\alpha, \beta \in \Gamma$ such that $p \in U_{\alpha}$, $q \in U_{\beta}$ and $U_{\alpha} \cap U_{\beta} = \emptyset$

Then there exists a unique smooth structure \mathcal{A} on M such that (M, \mathcal{A}) is an n-dimensional smooth manifold and $(U_{\alpha}, \phi_{\alpha})_{\alpha \in \Gamma} \subset \mathcal{A}$.

Proof. Define

- $\mathcal{B} = \{\phi_{\alpha}^{-1}(V) : \alpha \in \Gamma \text{ and } V \in \mathcal{T}_{\mathbb{H}^n}\}$
- $\mathcal{T}_M = \tau(\mathcal{B})$
- $\mathcal{A}' = \{(U_{\alpha}, \phi_{\alpha}) : \alpha \in \Gamma\}.$

The topological manifold chart lemma implies that (M, \mathcal{T}_M) is an n-dimensional topological manifold and $\mathcal{A}' \subset X^n(M, \mathcal{T}_M)$. Since $M = \bigcup_{\alpha \in \Gamma} U_\alpha$, \mathcal{A}' is an atlas on M. Since for each $\alpha, \beta \in \Gamma$, $\phi_\beta|_{U_\alpha \cap U_\beta} \circ (\phi_\alpha|_{U_\alpha \cap U_\beta})^{-1} : \phi_\alpha(U_\alpha \cap U_\beta) \to \phi_\beta(U_\alpha \cap U_\beta)$ is smooth, we have that \mathcal{A}' is smooth. A previous exercise implies that there exists a unique smooth structure \mathcal{A} on M such that $\mathcal{A}' \subset \mathcal{A}$.

3.3 Smooth Maps

Definition 3.3.0.1. Let (M, \mathcal{A}) be a smooth manifold and $f: M \to \mathbb{R}$. Then f is said to be smooth if for each coordinate chart $(U, \phi) \in \mathcal{A}$, $f \circ \phi^{-1} : \phi(U) \to \mathbb{R}$ is smooth. The set of all smooth functions on M is denoted $C^{\infty}(M)$.

Exercise 3.3.0.2. Let (M, \mathcal{A}) be a smooth manifold. Then $C^{\infty}(M)$ is a vector space.

Proof. Let $f, g \in C^{\infty}(M)$, $\lambda \in \mathbb{R}$ and $(U, \phi) \in \mathcal{A}$. By assumption, $f \circ \phi^{-1}$ and $g \circ \phi^{-1}$ are smooth. Hence

$$(f + \lambda g) \circ \phi^{-1} = f \circ \phi^{-1} + \lambda g \circ \phi^{-1}$$

is smooth. Since $(U, \phi) \in \mathcal{A}$ is arbitrary, $f + \lambda g \in C^{\infty}(M)$. Since $f, g \in C^{\infty}(M)$ and $\lambda \in \mathbb{R}$ are arbitrary, $C^{\infty}(M)$ is a vector space.

Exercise 3.3.0.3. Let (M, \mathcal{A}) be a smooth manifold, \mathcal{B} an atlas on M and $f: M \to \mathbb{R}$. Suppose that $\mathcal{B} \subset \mathcal{A}$. Then f is smooth iff for each $(U, \phi) \in \mathcal{B}$, $f \circ \phi^{-1} : \phi(U) \to \mathbb{R}$ is smooth.

Proof.

- (\Longrightarrow): Suppose that f is smooth. Let $(U, \phi) \in \mathcal{B}$. Since $\mathcal{B} \subset \mathcal{A}$, $(U, \phi) \in \mathcal{A}$. Since f is smooth, $f \circ \phi^{-1}$ is smooth. Since $(U, \phi) \in \mathcal{B}$ is arbitrary, we have that for each $(U, \phi) \in \mathcal{B}$, $f \circ \phi^{-1}$ is smooth.
- (\Leftarrow): Suppose that for each $(V, \psi) \in \mathcal{B}$, $f \circ \psi^{-1} : \psi(V) \to \mathbb{R}$ is smooth. Let $(U, \phi) \in \mathcal{A}$ and $q \in \phi(U)$. Set $p = \phi^{-1}(q)$. Since \mathcal{B} is an atlas, there exists $(V, \psi) \in \mathcal{B}$ such that $p \in V$. Since $\mathcal{B} \subset \mathcal{A}$, $(V, \psi) \in \mathcal{A}$. Set $W = U \cap V$ and $\tilde{\phi} = \phi|_W$ and $\tilde{\psi} = \psi|_W$. We note that $\phi(W) \in \mathcal{N}_q$ and $\phi(W)$ is open. An exercise in the section on smooth manifolds implies that $(W, \tilde{\phi}), (W, \tilde{\psi}) \in \mathcal{A}$. Therefore $\tilde{\psi} \circ \tilde{\phi}^{-1} : \phi(W) \to \psi(W)$ is smooth. By assumption, $f \circ \psi^{-1} : \psi(V) \to \mathbb{R}$ is smooth. This implies that $(f \circ \psi^{-1})|_{\psi(W)} : \psi(W) \to \mathbb{R}$ is smooth. Hence

$$\begin{split} (f \circ \phi^{-1})|_{\phi(W)} &= f \circ \tilde{\phi}^{-1} \\ &= f \circ (\tilde{\psi}^{-1} \circ \tilde{\psi}) \circ \tilde{\phi}^{-1} \\ &= (f \circ \tilde{\psi}^{-1}) \circ (\tilde{\psi} \circ \tilde{\phi}^{-1}) \end{split}$$

is smooth. Since $q \in \phi(U)$ is arbitrary, for each $q \in \phi(U)$, there exists $A \in \mathcal{N}_q$ such that A is open and $(f \circ \phi^{-1})|_A : A \to \mathbb{R}$ is smooth. This implies that $f \circ \phi^{-1} : \phi(U) \to \mathbb{R}$ is smooth. Since $(U, \phi) \in \mathcal{A}$ is arbitrary, f is smooth.

Exercise 3.3.0.4. Let (M, \mathcal{A}) be a smooth manifold, $(U, \phi) \in \mathcal{A}$ with $\phi = (x^1, \dots, x^n)$, $p \in U$ and $f \in C^{\infty}(M)$. Then $f|_{U} \in C^{\infty}(U)$.

Proof. Let
$$\Box$$

Definition 3.3.0.5. Let (M, \mathcal{A}) be a smooth manifold, $(U, \phi) \in \mathcal{A}$ with $\phi = (x^1, \dots, x^n)$, $f \in C^{\infty}(U)$ and $i \in \{1, \dots, n\}$. We define the **partial derivative of** f with **respect to** x^i , denoted

$$\partial f/\partial x^i:U\to\mathbb{R} \text{ or } \partial_i f:U\to\mathbb{R}$$

by

$$\frac{\partial f}{\partial x^i}(p) = \frac{\partial}{\partial u^i}[f\circ\phi^{-1}](\phi(p))$$

or equivalently,

$$\frac{\partial f}{\partial x^i} = \left(\frac{\partial}{\partial u^i} [f \circ \phi^{-1}]\right) \circ \phi$$

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Exercise 3.3.0.6. Let (M, \mathcal{A}) be a smooth manifold, $(U, \phi) \in \mathcal{A}$ with $\phi = (x^1, \dots, x^n)$, $f \in C^{\infty}(U)$ and $i \in \{1, \dots, n\}$. Then $\partial/\partial x^i : C^{\infty}(U) \to C^{\infty}(U)$ is linear.

Exercise 3.3.0.7. Let (M, \mathcal{A}) be a smooth manifold, $(U, \phi) \in \mathcal{A}$ with $\phi = (x^1, \dots, x^n)$, $f \in C^{\infty}(U)$ and $i, j \in \{1, \dots, n\}$. Then

$$\frac{\partial}{\partial x^i} \frac{\partial}{\partial x^j} f = \left(\frac{\partial}{\partial u^i} \frac{\partial}{\partial u^j} [f \circ \phi^{-1}] \right) \circ \phi$$

Proof.

$$\begin{split} \frac{\partial}{\partial x^{i}} \frac{\partial}{\partial x^{j}} f &= \frac{\partial}{\partial x^{i}} \left(\frac{\partial}{\partial x^{j}} f \right) \\ &= \frac{\partial}{\partial x^{i}} \left(\left[\frac{\partial}{\partial u^{j}} [f \circ \phi^{-1}] \right] \circ \phi \right) \\ &= \left(\frac{\partial}{\partial u^{i}} \left[\left(\left[\frac{\partial}{\partial u^{j}} [f \circ \phi^{-1}] \right] \circ \phi \right) \circ \phi^{-1} \right] \right) \circ \phi \\ &= \left(\frac{\partial}{\partial u^{i}} \left[\frac{\partial}{\partial u^{j}} [f \circ \phi^{-1}] \right] \right) \circ \phi \\ &= \left(\frac{\partial}{\partial u^{i}} \frac{\partial}{\partial u^{j}} [f \circ \phi^{-1}] \right) \circ \phi \end{split}$$

Exercise 3.3.0.8. Let (M, \mathcal{A}) be a smooth manifold, $(U, \phi) \in \mathcal{A}$ with $\phi = (x^1, \dots, x^n)$ and $i, j \in \{1, \dots, n\}$. Then

$$\frac{\partial}{\partial x^i} \frac{\partial}{\partial x^j} = \frac{\partial}{\partial x^j} \frac{\partial}{\partial x^i}$$

Proof. Let $f \in C^{\infty}(U)$. Since $f \circ \phi^{-1}$ is smooth,

$$\frac{\partial}{\partial u^i}\frac{\partial}{\partial u^j}[f\circ\phi^{-1}]=\frac{\partial}{\partial u^j}\frac{\partial}{\partial u^i}[f\circ\phi^{-1}]$$

The previous exercise implies that

$$\begin{split} \frac{\partial}{\partial x^i} \frac{\partial}{\partial x^j} f &= \left(\frac{\partial}{\partial u^i} \frac{\partial}{\partial u^j} [f \circ \phi^{-1}] \right) \circ \phi \\ &= \left(\frac{\partial}{\partial u^j} \frac{\partial}{\partial u^i} [f \circ \phi^{-1}] \right) \circ \phi \\ &= \frac{\partial}{\partial x^j} \frac{\partial}{\partial x^i} f \end{split}$$

Exercise 3.3.0.9. Let (M, \mathcal{A}) be a smooth manifold, $(U, \phi) \in \mathcal{A}$ with $\phi = (x^1, \dots, x^n)$ and $f \in C^{\infty}(U)$. Then for each $\alpha \in \mathbb{N}_0^n$,

$$\partial^{\alpha} f = (\partial^{\alpha} [f \circ \phi^{-1}]) \circ \phi$$

Proof. The claim is clearly true when $|\alpha| = 0$ or by definition if $|\alpha| = 1$. Let $n \in \mathbb{N}$ and suppose the claim is true for each $|\alpha| \in \{1, \ldots, n-1\}$. Then there exists $i \in \{1, \ldots, n\}$ such that $\alpha_i \geq 1$. Hence

$$\begin{split} \partial^{\alpha} f &= \partial^{e^i} (\partial^{\alpha - e^i} f) \\ &= \partial^{e^i} (\partial^{\alpha - e^i} [f \circ \phi^{-1}] \circ \phi) \\ &= (\partial^{e^i} [(\partial^{\alpha - e^i} [f \circ \phi^{-1}] \circ \phi) \circ \phi^{-1}]) \circ \phi \\ &= (\partial^{e^i} [\partial^{\alpha - e^i} [f \circ \phi^{-1}]]) \circ \phi \\ &= (\partial^{\alpha} [f \circ \phi^{-1}]) \circ \phi \end{split}$$

Exercise 3.3.0.10. Taylor's Theorem:

Let (M, \mathcal{A}) be a smooth manifold, $(U, \phi) \in \mathcal{A}$ with $\phi = (x^1, \dots, x^n)$ and $\phi(U)$ convex, $p \in U$, $f \in C^{\infty}(U)$ and $T \in \mathbb{N}$. Then there exist $(g_{\alpha})_{|\alpha|=T+1} \subset C^{\infty}(U)$ such that

$$f = \sum_{k=0}^{T} \left[\sum_{|\alpha|=k} (x-p)^{\alpha} \partial^{\alpha} f(x_0) \right] + \sum_{|\alpha|=T+1} (x^i - x^i(p))^{\alpha} g_{\alpha}$$

and for each $|\alpha| = T + 1$,

$$g_{\alpha}(p) = \frac{1}{(T+1)!} \partial^{\alpha} f(p)$$

Proof. Since $\phi(U)$ is open and convex and $f \circ \phi^{-1} \in C^{\infty}(\phi(U))$, Taylors therem in section 2.1 implies that there exist $(\tilde{g}_{\alpha})_{|\alpha|=T+1} \subset C^{\infty}(\phi(U))$ such that for each $q \in U$,

$$f \circ \phi^{-1}(\phi(q)) = \sum_{k=0}^{T} \left[\sum_{|\alpha|=k} (x^{i}(q) - x^{i}(p))^{\alpha} \partial^{\alpha} [f \circ \phi^{-1}](\phi(p)) \right] + \sum_{|\alpha|=T+1} (x^{i}(q) - x^{i}(p))^{\alpha} \tilde{g}_{\alpha}(\phi(q))$$

and for each $|\alpha| = T + 1$,

$$\tilde{g}_{\alpha}(\phi(p)) = \frac{1}{(T+1)!} \partial^{\alpha} [f \circ \phi^{-1}](\phi(p))$$
$$= \frac{1}{(T+1)!} \partial^{\alpha} f(p)$$

For $|\alpha| = T + 1$, set $g_{\alpha} = \tilde{g} \circ \phi$. Then

$$f(q) = f \circ \phi^{-1}(\phi(q))$$

$$= \sum_{k=0}^{T} \left[\sum_{|\alpha|=k} (x^{i}(q) - x^{i}(p))^{\alpha} \partial^{\alpha} [f \circ \phi^{-1}](\phi(p)) \right] + \sum_{|\alpha|=T+1} (x^{i}(q) - x^{i}(p))^{\alpha} \tilde{g}_{\alpha}(\phi(q))$$

$$= \sum_{k=0}^{T} \left[\sum_{|\alpha|=k} (x^{i}(q) - x^{i}(p))^{\alpha} \partial^{\alpha} f(p) \right] + \sum_{|\alpha|=T+1} (x^{i}(q) - x^{i}(p))^{\alpha} g_{\alpha}(q)$$

Definition 3.3.0.11. Let (N, \mathcal{B}) be a smooth manifold and $F: M \to N$. Then F is said to be

• smooth if for each $(U, \phi) \in \mathcal{A}$ and $(V, \psi) \in \mathcal{B}$.

$$\psi \circ F \circ \phi^{-1} : \phi(U \cap F^{-1}(V)) \to \psi(F(U) \cap V)$$

is smooth

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• a diffeomorphism if F is a bijection and F, F^{-1} are smooth.

Exercise 3.3.0.12. Let (M, \mathcal{A}) and (N, \mathcal{B}) be smooth manifold and $F : M \to N$. If F is smooth, then F is continuous.

Proof. Suppose that F is smooth. Let $p \in M$. Choose $(U, \phi) \in \mathcal{A}$ and $(V, \psi) \in \mathcal{B}$ such that $p \in U$ and $F(p) \in V$. Put $\tilde{U} = U \cap F^{-1}(V)$ and $\tilde{V} = F(U) \cap V$. Define $\tilde{\phi} : \tilde{U} \to \phi(\tilde{U})$ and $\tilde{\psi} : \tilde{V} \to \psi(\tilde{V})$ by

$$\tilde{\phi} = \phi|_{\tilde{U}}, \ \tilde{\phi} = \psi|_{\tilde{V}}$$

Then $\tilde{\phi}$ and $\tilde{\psi}$ are homeomorphisms, $p \in \tilde{U}$ and $F(\tilde{U}) \subset \tilde{V}$. Define $\tilde{F}: \phi(\tilde{U}) \to \psi(\tilde{V})$ by

$$\tilde{F} = \tilde{\psi} \circ F \circ \tilde{\phi}^{-1}$$

By definition, \tilde{F} is smooth and therefore continuous. Since ϕ and ψ are homeomorphisms and $F|_{\tilde{U}}=\tilde{\psi}^{-1}\circ\tilde{F}\circ\tilde{\phi}$, we have that $F|_{\tilde{U}}$ is continuous. In particular, F is continuous at p and since $p\in M$ is arbitrary, F is continuous.

Exercise 3.3.0.13. Let (M, \mathcal{A}) and (N, \mathcal{B}) be smooth manifold and $F : M \to N$. If F is a diffeomorphism, then F is a homeomorphism.

Proof. Suppose that F is a diffeomorphism. By definition, F and F^{-1} are smooth. The previous exercise implies that F and F^{-1} are continuous. Hence F is a homeomorphism.

Exercise 3.3.0.14. Let (N, \mathcal{B}) be a smooth manifold and $F: M \to N$ a diffeomorphism. Then for each $(U, \phi) \in \mathcal{A}$, $(F(U), \phi \circ F^{-1}) \in \mathcal{B}$.

Proof. Let $(V, \psi) \in \mathcal{B}$.

- 1. Since ϕ and F^{-1} are homeomorphisms, $\phi \circ F^{-1} : F(U) \cap V \to \phi(U \cap F^{-1}(V))$ is a homeomorphism
- 2. Since F is a diffeomorphism,

$$\phi \circ F^{-1} \circ \psi^{-1} : \psi(F(U) \cap V) \to \phi(U \cap F^{-1}(V))$$

and

$$\psi \circ F \circ \phi^{-1} : \phi(F^{-1}(V) \cap U) \to \psi(V \cap F(U))$$

are smooth.

Therefore $(F(U), \phi \circ F^{-1})$ and (V, ψ) are smoothly compatible. Since \mathcal{B} is maximal, $(F(U), \phi \circ F^{-1}) \in \mathcal{B}$.

Definition 3.3.0.15. Let (N, \mathcal{B}) be a smooth n-dimensional manifold, $F: M \to N$ smooth and $(V, \psi) \in \mathcal{B}$ with $\psi = (y^1, \dots, y^n)$. For $i \in \{1, \dots, n\}$, We define the i-th component of F with respect to (V, ψ) , denoted $F^i: V \to \mathbb{R}$, by

$$F^i = y^i \circ F$$

3.4 Partitions of Unity

Definition 3.4.0.1. Let $p \in M$, $U \in \mathcal{N}_a$ open and $\rho \in C_c^{\infty}(M)$. Then ρ is said to be a **bump function at** \mathbf{p} supported in U if

- 1. $\rho \geq 0$
- 2. there exists $V \in \mathcal{N}_p$ such that V is open and $\rho|_V = 1$
- 3. $\operatorname{supp} \rho \subset U$

Exercise 3.4.0.2. Define $f: \mathbb{R} \to \mathbb{R}$ by

$$f(t) = \begin{cases} e^{-\frac{1}{1-t^2}} & t \in (-1,1) \\ 0 & t \notin (-1,1) \end{cases}$$

Then $f \in C_c^{\infty}(\mathbb{R})$.

Proof.

3.5 The Tangent Space

Definition 3.5.0.1. Let $(U, \phi) \in \mathcal{A}$ with $\phi = (x^1, \dots, x^n)$ and $p \in U$. For $i \in \{1, \dots, n\}$, define the partial derivative with respect to x^i at p, denoted

$$\frac{\partial}{\partial x^i}\Big|_p: C^{\infty}(M) \to \mathbb{R}, \text{ or } \partial_i|_p: C^{\infty}(M) \to \mathbb{R}$$

by

$$\left. \frac{\partial}{\partial x^i} \right|_p f = \frac{\partial f}{\partial x^i}(p)$$

Exercise 3.5.0.2. Let $(U, \phi) \in \mathcal{A}$ with $\phi = (x^1, \dots, x^n)$ and $p \in U$. Then for each $i, j \in \{1, \dots, n\}$, we have that

$$\frac{\partial}{\partial x^i} x^j(p) = \delta_{i,j}$$

Proof. Let $i, j \in \{1, \dots, n\}$. Then

$$\frac{\partial}{\partial x^{i}} \Big|_{p} x^{i} = \frac{\partial}{\partial u^{i}} \Big|_{\phi(p)} x^{i} \circ \phi^{-1}$$

$$= \frac{\partial}{\partial u^{i}} \Big|_{\phi(p)} u^{i} \circ \phi \circ \phi^{-1}$$

$$= \frac{\partial}{\partial u^{i}} \Big|_{\phi(p)} u^{i}$$

$$= \delta_{i,j}$$

Exercise 3.5.0.3. Change of Coordinates:

Let $(U, \phi), (V, \psi) \in \mathcal{A}$ with $\phi = (x^1, \dots, x^n)$ and $\psi = (y^1, \dots, y^n), p \in U \cap V$ and $f \in C^{\infty}(M)$. Then for each $i \in \{1, \dots, n\}$,

$$\left. \frac{\partial}{\partial y^i} \right|_p = \sum_{j=1}^n \frac{\partial}{\partial x^j} y^i(p) \frac{\partial}{\partial x^i} \right|_p$$

Proof. Put $h = \phi \circ \psi^{-1}$ and write $h = (h_1, \dots, h_n)$. Then $\phi = h \circ \psi$ and $\psi^{-1} = \phi^{-1} \circ h$. By definition and the chain rule, we have that

$$\begin{split} \frac{\partial}{\partial y^{i}} \bigg|_{p} f &= \frac{\partial}{\partial u^{i}} \bigg|_{\psi(p)} f \circ \psi^{-1} \\ &= \frac{\partial}{\partial u^{i}} \bigg|_{\psi(p)} f \circ \phi^{-1} \circ h \\ &= \sum_{j=1}^{n} \left(\frac{\partial}{\partial u^{j}} \bigg|_{h \circ \psi(p)} f \circ \phi^{-1} \right) \left(\frac{\partial}{\partial u^{i}} \bigg|_{\psi(p)} h_{j} \right) \\ &= \sum_{j=1}^{n} \left(\frac{\partial}{\partial u^{j}} \bigg|_{\phi(p)} f \circ \phi^{-1} \right) \left(\frac{\partial}{\partial u^{i}} \bigg|_{\psi(p)} x^{j} \circ \psi^{-1} \right) \\ &= \sum_{j=1}^{n} \left(\frac{\partial}{\partial x^{i}} \bigg|_{p} f \right) \left(\frac{\partial}{\partial y^{i}} \bigg|_{p} x^{j} \right) \end{split}$$

Definition 3.5.0.4. Let $p \in M$ and $v : C^{\infty}(M) \to \mathbb{R}$. Then v is said to be **Leibnizian** if for each $f, g \in C^{\infty}(M)$,

$$v(fg) = v(f)g(p) + f(p)v(g)$$

and v is said to be a **derivation at** p if for each $f, g \in C^{\infty}(M)$ and $a \in \mathbb{R}$,

- 1. v is linear
- 2. v is Leibnizian

We define the **tangent space of** M **at** p, denoted T_pM , by

$$T_pM = \{v : C^{\infty}(M) \to \mathbb{R} : v \text{ is a derivation at } p\}$$

Exercise 3.5.0.5. Let $f \in C^{\infty}(M)$ and $v \in T_pM$. If f is constant, then vf = 0.

Proof. Suppose that f=1. Then $f^2=f$ and $v(f^2)=2v(f)$. So v(f)=2v(f) which implies that v(f)=0. If $f\neq 1$, then there exists $c\in\mathbb{R}$ such that f=c. Since v is linear, v(f)=cv(1)=0.

Exercise 3.5.0.6. Let $(U, \phi) \in \mathcal{A}$ with $\phi = (x^1, \dots, x^n)$ and $p \in U$. Then

$$\left\{ \frac{\partial}{\partial x^1} \bigg|_p, \cdots, \frac{\partial}{\partial x^n} \bigg|_p \right\}$$

is a basis for T_pM and dim $T_pM=n$.

Proof. Clearly $\frac{\partial}{\partial x^1}\Big|_p, \dots, \frac{\partial}{\partial x^n}\Big|_p \in T_pM$. Let $a_1, \dots, a_n \in \mathbb{R}$. Suppose that

$$v = \sum_{i=1}^{n} a_i \frac{\partial}{\partial x^i} \bigg|_p = 0$$

Then

$$0 = vx^{j}$$

$$= \sum_{i=1}^{n} a_{i} \frac{\partial}{\partial x^{i}} \Big|_{p} x^{j}$$

$$= a_{j}$$

Hence $\left\{ \frac{\partial}{\partial x^1} \bigg|_p, \cdots, \frac{\partial}{\partial x^n} \bigg|_p \right\}$ is independent.

Now, let $v \in T_pM$ and $f \in \mathbb{C}^{\infty}(M)$. By Taylor's theorem, there exist $g_1, \dots g_n \in C_p^{\infty}(M)$ such that

$$f = f(p) + \sum_{i=1}^{n} (x^{i} - x^{i}(p))g_{i}$$

and for each $i \in \{1, \dots, n\}$,

$$g_i(p) = \frac{\partial}{\partial x^i} \bigg|_p f$$

Then

$$v(f) = \sum_{i=1}^{n} v(x^{i} - x^{i}(p))g_{i}(p) + \sum_{i=1}^{n} (x^{i}(p) - x^{i}(p))v(g_{i})$$

$$= \sum_{i=1}^{n} v(x^{i})g_{i}(p)$$

$$= \sum_{i=1}^{n} v(x^{i})\frac{\partial}{\partial x^{i}}\Big|_{p} f$$

$$= \left[\sum_{i=1}^{n} v(x^{i})\frac{\partial}{\partial x^{i}}\Big|_{p}\right] f$$

So

$$v = \sum_{i=1}^{n} v(x^{i}) \frac{\partial}{\partial x^{i}} \bigg|_{p}$$

and

$$v \in \operatorname{span}\left\{ \left. \frac{\partial}{\partial x^1} \right|_p, \cdots, \left. \frac{\partial}{\partial x^n} \right|_p \right\}$$

Definition 3.5.0.7. Let (N, \mathcal{B}) be a smooth manifold, $F: M \to N$ smooth and $p \in M$. We define the differential of F at p, denoted $DF_p: T_pM \to T_{F(p)}N$, by

$$\left[DF_p(v)\right](f) = v(f \circ F)$$

for $v \in T_pM$ and $f \in C^{\infty}(N)$.

Exercise 3.5.0.8. Let (N, \mathcal{B}) be a smooth manifold, $F: M \to N$ smooth and $p \in M$. Then for each $v \in T_pM$, $DF_p(v)$ is a derivation.

Proof. Let $v \in T_pM, \, f, g \in C^\infty_{F(p)}(N)$ and $c \in \mathbb{R}$. Then

1.

$$DF_p(v)(f + cg) = v((f + cg) \circ F)$$

$$= v(f \circ F + cg \circ F)$$

$$= v(f \circ F) + cv(g \circ F)$$

$$= DF_p(v)(f) + cDF_p(v)(g)$$

So $DF_p(v)$ is linear.

2.

$$\begin{split} DF_p(v)(fg) &= v(fg \circ F) \\ &= v((f \circ F) * (g \circ F)) \\ &= v(f \circ F) * (g \circ F)(p) + (f \circ F)(p) * v(g \circ F) \\ &= DF_p(v)(f) * g(F(p)) + f(F(p)) * DF_p(v)(g) \end{split}$$

So $DF_p(v)$ is Leibnizian and hence $DF_p(v) \in T_{F(p)}N$

Exercise 3.5.0.9. Let (N, \mathcal{B}) be a smooth manifold, $F: M \to N$ smooth and $p \in M$. If F is a diffeomorphism, then DF_p is an isomorphism.

Proof. Suppose that F is a diffeomorphism. Since F is a homeomorphism, dim N=n. Choose $(U,\phi)\in\mathcal{A}$ such that $p\in U$. A previous exercise tells us that $(F(U),\phi\circ F^{-1})\in\mathcal{B}$. Write $\phi=(x^1,\cdots,x^n)$ and $\phi\circ F^{-1}=(y^1,\cdots,y^n)$. Let $f\in C^\infty(N)$ Then

$$\begin{split} \frac{\partial}{\partial y^i}\bigg|_{F(p)} f &= \frac{\partial}{\partial u^i}\bigg|_{\phi \circ F^{-1}(F(p))} f \circ (\phi \circ F^{-1})^{-1} \\ &= \frac{\partial}{\partial u^i}\bigg|_{\phi(p)} f \circ F \circ \phi^{-1} \\ &= \frac{\partial}{\partial x^i}\bigg|_p f \circ F \end{split}$$

Therefore

$$\left[DF_p\left(\frac{\partial}{\partial x^i}\Big|_p\right)\right](f) = \frac{\partial}{\partial x^i}\Big|_p f \circ F$$

$$= \frac{\partial}{\partial y^i}\Big|_{F(p)} f$$

Hence

$$DF_p\left(\frac{\partial}{\partial x^i}\bigg|_p\right) = \frac{\partial}{\partial y^i}\bigg|_{F(p)}$$

Since $\left\{ \frac{\partial}{\partial x^1} \bigg|_p, \cdots, \frac{\partial}{\partial x^n} \bigg|_p \right\}$ is a basis for $T_p M$ and $\left\{ \frac{\partial}{\partial y^1} \bigg|_{F(p)}, \cdots, \frac{\partial}{\partial y^n} \bigg|_{F(p)} \right\}$ is a basis for $T_{F(p)} N, D F_p$ is an isomorphism.

Exercise 3.5.0.10. Let (M, \mathcal{A}) be a smooth m-dimensional manifold, (N, \mathcal{B}) a n-dimensional smooth manifold, $F: M \to N$ smooth, $(U, \phi) \in \mathcal{A}$ with $\phi = (x^1, \dots, x^m)$ and $(V, \psi) \in \mathcal{B}$ with $\psi = (y^1, \dots, y^n)$. Suppose that $p \in U$ and $F(p) \in V$. Define the ordered bases $B_{\phi} = \left\{\frac{\partial}{\partial x^1}\bigg|_p, \dots, \frac{\partial}{\partial x^m}\bigg|_p\right\}$ and $B_{\psi} = \left\{\frac{\partial}{\partial y^1}\bigg|_{F(p)}, \dots, \frac{\partial}{\partial y^n}\bigg|_{F(p)}\right\}$. Then the matrix representation of DF_p with respect to the bases B_{ϕ} and B_{ψ} is

$$DF_p^{i,j} = \frac{\partial F^i}{\partial x^j}(p)$$

Proof. Let $(DF_p)_{B_{\phi},B_{\psi}}=(a_{i,j})_{i,j}\in\mathbb{R}^{n\times m}$. Then for each $j\in\{1,\ldots,m\}$,

$$DF_p\left(\frac{\partial}{\partial x^j}\bigg|_p\right) = \sum_{i=1}^n a_{i,j} \frac{\partial}{\partial y^i}\bigg|_{F(p)}$$

This implies that

$$DF_p\left(\frac{\partial}{\partial x^j}\Big|_p\right)(y^k) = \sum_{i=1}^n a_{i,j} \frac{\partial}{\partial y^i}\Big|_{F(p)}(y^k)$$
$$= \sum_{i=1}^n a_{i,j} \delta_{i,k}$$
$$= a_{k,j}$$

By definition,

$$\begin{aligned} DF_p \bigg(\frac{\partial}{\partial x^j} \bigg|_p \bigg) (y^k) &= \frac{\partial}{\partial x^j} \bigg|_p y^k \circ F \\ &= \frac{\partial}{\partial x^j} \bigg|_p F^k \\ &= \frac{\partial F^k}{\partial x^j} (p) \end{aligned}$$

Note 3.5.0.11. Since rank DF_p is independent of basis, it is independent of coordinate charts $(U, \phi) \in \mathcal{A}$ and $(V, \psi) \in \mathcal{B}$.

3.6 The Cotangent Space

Definition 3.6.0.1. Let $p \in M$. We define the **cotangent space of** M **at** p, denoted T_p^*M , by

$$T_p^*M = (T_pM)^*$$

Definition 3.6.0.2. Let $f \in C^{\infty}(M)$. We define the **differential of** f **at** p, denoted $df_p : T_pM \to \mathbb{R}$, by

$$df_p(v) = vf$$

Exercise 3.6.0.3. Let $f \in C^{\infty}(M)$ and $p \in M$. Then $df_p \in T_p^*M$.

Proof. Let $v_1, v_2 \in T_pM$ and $\lambda \in \mathbb{R}$. Then

$$df_p(v_1 + \lambda v_2) = (v_1 + \lambda v_2)f$$

$$= v_1 f + \lambda v_2 f$$

$$= df_p(v_1) + \lambda df_p(v_2)$$

So that df_p is linear and hence $df_p \in T_p^*M$.

Exercise 3.6.0.4. Let $(U, \phi) \in \mathcal{A}$ with $\phi = (x^1, \dots, x^n)$ and $p \in U$. Then for each $i, j \in \{1, \dots, n\}$,

$$dx_p^i \left(\frac{\partial}{\partial x^j} \bigg|_{p} \right) = \delta_{i,j}$$

In particular, $\{dx_p^1, \cdots, dx_p^n\}$ is the dual basis to $\left\{\frac{\partial}{\partial x^1}\bigg|_p, \cdots, \frac{\partial}{\partial x^n}\bigg|_p\right\}$ and $T_p^*M = \operatorname{span}\{dx_p^1, \cdots, dx_p^n\}$.

Proof. Let $i, j \in \{1, \dots, n\}$. Then by defintion,

$$\left[dx_p^i \left(\frac{\partial}{\partial x^i} \Big|_p \right) \right]_p = \frac{\partial}{\partial x^i} \Big|_p x^i \\
= \delta_{i,j}$$

Exercise 3.6.0.5. Let $f \in C^{\infty}(M)$, (U, ϕ) a chart on M with $\phi = (x^1, \dots, x^n)$ and $p \in U$. Then

$$df_p = \sum_{i=1}^n \frac{\partial f}{\partial x^i}(p) dx^i_p$$

Proof. Since $\{dx_p^1, \dots, dx_p^n\}$ is a basis for T_p^*M , for each there exist $a_1(p), \dots, a_n(p) \in \mathbb{R}$ such that $df_p = \sum_{i=1}^n a_i(p) dx_p^i$. Therefore, we have that

$$df_p\left(\frac{\partial}{\partial x^i}\bigg|_p\right) = \sum_{i=1}^n a_i(p) dx_p^i \left(\frac{\partial}{\partial x^i}\bigg|_p\right)$$
$$= a_j(p)$$

By definition, we have that

$$df_p \left(\frac{\partial}{\partial x^i} \Big|_p \right) = \frac{\partial}{\partial x^i} \Big|_p f$$
$$= \frac{\partial}{\partial x^j} (p)$$

So
$$a_j(p) = \frac{\partial f}{\partial x^j}(p)$$
 and

$$df_p = \sum_{i=1}^n \frac{\partial f}{\partial x^j}(p) dx_p^i$$

Chapter 4

Submersions and Immersions

4.1 Maps of Constant Rank

Definition 4.1.0.1. Let (M, \mathcal{A}) and (N, \mathcal{B}) be smooth manifolds, $F : M \to N$ a smooth map. We define the **rank map of** F, denoted rank $F : M \to \mathbb{N}_0$ by

$$\operatorname{rank}_{p} F = \dim \operatorname{Im} DF(p)$$

and F is said to have **constant rank** if for each $p, q \in M$, $\operatorname{rank}_p F = \operatorname{rank}_q F$. If F has constant rank, we define the **rank of** F, denoted $\operatorname{rank} F$, by $\operatorname{rank} F = \operatorname{rank}_p F$ for $p \in M$.

Exercise 4.1.0.2. Let (M, \mathcal{A}) and (N, \mathcal{B}) be smooth manifolds of dimensions m and n respectively, $F \in C^{\infty}(M, N)$ and $p \in M$. Suppose that $\operatorname{rank}_p F = k$. Then there exist $(U, \phi) \in \mathcal{A}_M$, $(V, \psi) \in \mathcal{A}_N$ and $A \in GL(k, \mathbb{R})$ such that for each $i, j \in \{1, \ldots, k\}$,

$$([DF(p)]_{\phi,\psi})_{i,j} = A_{i,j}$$

Proof. Define $q \in V$ by q = F(p). Choose $(U', \phi') \in \mathcal{A}$ and $(V', \psi') \in \mathcal{B}$ such that $p \in U'$ and $q \in V'$. Set $Z = [DF(p)]_{\phi',\psi'}$. By assumption, rank Z = k. An exercise in the subsection on linear algebra implies that there exist $\sigma \in S_m$, $\tau \in S_n$ and $A \in GL(k, \mathbb{R})$ such that for each $i, j \in \{1, \ldots, k\}$,

$$(P_{\tau}ZP_{\sigma}^*)_{i,j}=A_{i,j}$$

Define $\phi: U \to \sigma\phi(U)$ and $\psi: V \to \tau\psi(V)$ by

$$\phi = \sigma \phi', \quad \psi = \tau \psi'$$

A previous exercise implies that

$$[DF(p)]_{\phi,\psi} = P_{\tau}ZP_{\sigma}^*$$

Exercise 4.1.0.3. Constant Rank Theorem:

Let (M, \mathcal{A}) and (N, \mathcal{B}) be smooth manifolds of dimensions m and n respectively, $F \in C^{\infty}(M, N)$. Suppose that F has constant rank and rank F = k. Then for each $p \in M$, there exist $(U, \phi) \in \mathcal{A}$ and $(V, \psi) \in \mathcal{B}$ such that $p \in U$, $F(p) \in V$ and

$$\psi \circ F \circ \phi^{-1}(x^1, \dots, x^k, x^{k+1}, \dots, x^m) = (x^1, \dots, x^k, 0, \dots, 0)$$

Proof. Let $p \in M$. The previous exercise implies that there exist $(U_0, \phi_0) \in \mathcal{A}$, $(V_0, \psi_0) \in \mathcal{B}$ and $L \in GL(k, \mathbb{R})$ such that $p \in U$, $F(p) \in V_0$ and for each $i, j \in \{1, \dots, k\}$,

$$([DF(p)]_{\phi_0,\psi_0})_{i,j} = L_{i,j}$$

Define $\hat{M} \subset \mathbb{R}^m$, $\hat{N} \subset \mathbb{R}^n$ and $\hat{F}: \hat{M} \to \hat{N}$ by $\hat{M} = \phi_0(U_0)$, $\hat{N} = \psi_0(V_0)$ and $\hat{F} = \psi_0 \circ F \circ \phi_0^{-1}$. Set $\hat{p} = \phi_0(p)$. Let (x,y) be the standard coordinates on \mathbb{R}^m , with $\pi_x : \mathbb{R}^m \to \mathbb{R}^k$ and $\pi_y : \mathbb{R}^m \to \mathbb{R}^{m-k}$ the standard projection maps. Write $\hat{p} = (x_0, y_0)$. There exist $Q: \hat{M} \to \mathbb{R}^k$ and $R: \hat{M} \to \mathbb{R}^{n-k}$ such that $\hat{F} = (Q, R)$. By construction, $[D_x Q(x_0, y_0)] = A$. Define $G: \hat{M} \to \mathbb{R}^m$ by G(x, y) = (Q(x, y), y). Then

$$[DG(x_0, y_0)] = \begin{pmatrix} [D_x Q(x_0, y_0)] & [D_x Q(x_0, y_0)] \\ [D_x \pi_y(x_0, y_0)] & [D_y \pi_y(x_0, y_0)] \end{pmatrix}$$
$$= \begin{pmatrix} [D_x Q(x_0, y_0)] & [D_y Q(x_0, y_0)] \\ 0 & I \end{pmatrix}$$
$$= \begin{pmatrix} L & [D_y Q(x_0, y_0)] \\ 0 & I \end{pmatrix}$$

Hence

$$det([DG(x_0, y_0)]) = det(L) det(I)$$
$$= det(L)$$
$$\neq 0$$

The inverse function theorem implies that there exist $\hat{U} \subset \hat{M}$ such that \hat{U} is open, $\hat{p} \in \hat{U}$ and $G|_{\hat{U}} : \hat{U} \to G(\hat{U})$ is a diffeomorphism. Since

$$\{U_1 \times U_2 : U_1 \subset \mathbb{R}^k, U_2 \subset \mathbb{R}^{m-k} \text{ and } U_1, U_2 \text{ are open}\}$$

is a basis for the topology on \mathbb{R}^m , there exist $\hat{U}_1 \subset \mathbb{R}^k$ and $\hat{U}_2 \subset \mathbb{R}^{m-k}$ such that \hat{U}_1, \hat{U}_2 are open, $\hat{p} \in \hat{U}_1 \times \hat{U}_2$ and $\hat{U}_1 \times \hat{U}_2 \subset \hat{U}$. Set $\hat{U}_{12} = \hat{U}_1 \times \hat{U}_2$. Since $G(\hat{U}_1 \times \hat{U}_2) = Q(\hat{U}_{12}) \times \hat{U}_2$, we have that $G|_{\hat{U}_{12}} : \hat{U}_{12} \to Q(\hat{U}_{12}) \times \hat{U}_2$ is a diffeomorphism. Since π_x is open, $Q(\hat{U}_{12})$ is open. There exist $A : Q(\hat{U}_{12}) \times \hat{U}_2 \to \hat{U}_1$ and $B : Q(\hat{U}_{12}) \times \hat{U}_2 \to \hat{U}_2$ such that $G^{-1} = (A, B)$. Define $\tilde{R} : Q(\hat{U}_{12}) \times \hat{U}_2 \to \mathbb{R}^{n-k}$ by $\tilde{R}(x, y) = R(A(x, y), y)$. Let $(x, y) \in Q(\hat{U}_{12}) \times \hat{U}_2$. Then

$$(x,y) = G \circ G^{-1}(x,y)$$

= $G(A(x,y), B(x,y))$
= $(Q(A(x,y), B(x,y)), B(x,y))$

This implies that B(x, y) = y,

$$x = Q(A(x, y), B(x, y))$$
$$= Q(A(x, y), y)$$

Hand

$$G^{-1}(x,y) = (A(x,y), B(x,y))$$

= $(A(x,y), y)$

Therefore,

$$\hat{F} \circ G^{-1}(x,y) = \hat{F}(A(x,y),y)$$

$$= (Q(A(x,y),y), R(A(x,y),y))$$

$$= (x, R(A(x,y),y))$$

$$= (x, \tilde{R}(x,y))$$

We note that

$$\begin{split} [D(\hat{F}\circ G^{-1})(x,y)] &= \begin{pmatrix} [D_x\pi_x(x,y)] & [D_y\pi_x(x,y)] \\ [D_x\tilde{R}(x,y)] & [D_y\tilde{R}(x,y)] \end{pmatrix} \\ &= \begin{pmatrix} I & 0 \\ [D_x\tilde{R}(x,y)] & [D_y\tilde{R}(x,y)] \end{pmatrix} \end{split}$$

Since $G^{-1}: Q(\hat{U}_{12}) \times \hat{U}_2 \to \hat{U}_{12}$ is a diffeomorphism, we have that $[DG^{-1}(x,y)] \in GL(m,\mathbb{R})$. Since \hat{F} has constant rank and rank $\hat{F} = k$, we have that

$$\begin{aligned} \operatorname{rank}[D(\hat{F} \circ G^{-1})(x,y)] &= \operatorname{rank}([D\hat{F}(G^{-1}(x,y))][DG^{-1}(x,y)]) \\ &= \operatorname{rank}[D\hat{F}(G^{-1}(x,y))] \\ &= k \end{aligned}$$

Since rank $\begin{pmatrix} I \\ [D_x \tilde{R}(x,y)] \end{pmatrix} = k$, we have that rank $\begin{pmatrix} 0 \\ [D_y \tilde{R}(x,y)] \end{pmatrix} = 0$. Thus $[D_y \tilde{R}(x,y)] = 0$. Since $(x,y) \in Q(\hat{U}_{12}) \times \hat{U}_2$ is arbitrary, for each $(x,y) \in Q(\hat{U}_{12}) \times \hat{U}_2$,

$$\tilde{R}(x,y) = \tilde{R}(x,y_0)$$

Define $\tilde{S}: Q(\hat{U}_{12}) \to \mathbb{R}^{n-k}$ by $\tilde{S}(x) = \tilde{R}(x, y_0)$. Then for each $(x, y) \in Q(\hat{U}_{12}) \times \hat{U}_2$,

$$\hat{F} \circ G^{-1}(x,y) = (x, \tilde{S}(x))$$

Let (a,b) be the standard coordinates on \mathbb{R}^n , with $\pi_a: \mathbb{R}^n \to \mathbb{R}^k$ and $\pi_b: \mathbb{R}^n \to \mathbb{R}^{n-k}$ the standard projection maps. Write $\hat{F}(\hat{p}) = (a_0, b_0)$. Set

$$\hat{V} = [(\pi_a)|_{\hat{N}}]^{-1}(Q(\hat{U}_{12}))$$
$$= \pi_a^{-1}(Q(\hat{U}_{12})) \cap \hat{N}$$

Since $Q(\hat{U}_{12})$ is open, \hat{N} is open and π_a is continuous, we have that \hat{V} is open. Since

$$Q(\hat{U}_{12}) = (\pi_a)|_{\hat{N}} \circ \hat{F} \circ G^{-1}(Q(\hat{U}_{12}) \times \hat{U}_2)$$

= $(\pi_a)|_{\hat{N}} \circ \hat{F}(\hat{U}_{12})$

we have that $\hat{F}(\hat{U}_{12}) \subset \hat{V}$. In particular, $\hat{F}(\hat{p}) \in \hat{V}$. Define $H : \hat{V} \to \mathbb{R}^n$ by $H(a,b) = (a,b-\tilde{S}(a))$. Then $H \circ \hat{F} \circ G^{-1}(x,y) = (x,0)$. Define $(U,\phi) \in \mathcal{A}$ and $(V,\psi) \in \mathcal{N}$ by $U = \phi_0^{-1}(\hat{U}_{12})$, $V = \psi_0^{-1}(\hat{V})$, $\phi = G \circ \phi_0$ and $\psi = H \circ \psi_0$. Then for each $(x,y) \in \phi(U)$,

$$\psi \circ F \circ \phi^{-1}(x,y) = H \circ \psi_0 \circ F \circ \phi_0^{-1} \circ G^{-1}(x,y)$$
$$= H \circ \hat{F} \circ G^{-1}(x,y)$$
$$= (x,0)$$

Definition 4.1.0.4. Let (M, \mathcal{A}) and (N, \mathcal{B}) be smooth manifolds, $F: M \to N$ a smooth map. Then F is said to be

- an **immersion** if for each $p \in M$, $DF(p) : T_pM \to T_{F(p)}N$ is injective
- a submersion if for each $p \in M$, $DF(p) : T_pM \to T_{F(p)}N$ is surjective

Exercise 4.1.0.5. Let (M, \mathcal{A}) and (N, \mathcal{B}) be smooth manifolds, $F: M \to N$ a smooth map.

Definition 4.1.0.6. Let (M, \mathcal{A}) and (N, \mathcal{B}) be smooth manifolds and $F: M \to N$ smooth. Then F is said to be an **embedding** if

- 1. F is an immersion
- 2. $F: M \to F(M)$.

Note 4.1.0.7. Here the topology on F(M) is the subspace topology.

4.2 Submanifolds

Exercise 4.2.0.1. Let (M, \mathcal{A}) be a smooth manifold and $S \subset M$ open. For $(U, \phi) \in \mathcal{A}$, define $\tilde{U} \subset S$ and $\tilde{\phi} : \tilde{U} \to \phi(\tilde{U})$ by $\tilde{U} = U \cap S$ and $\tilde{\phi} = \phi|_{U \cap S}$. Set $\mathcal{B} = \{(\tilde{U}, \tilde{\phi}) : (U, \phi) \in \mathcal{A}\}$. Then \mathcal{B} is a smooth structure on S.

Proof.

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Definition 4.2.0.2. Let (M, \mathcal{A}) and (N, \mathcal{B}) be smooth manifolds. Suppose that $M \subset N$. Then (M, \mathcal{A}) is said to be

- 1. an **immersed submanifold** of (N,\mathcal{B}) if id: $M \to N$ is a smooth immersion
- 2. an **embedded submanifold** of (N, \mathcal{B}) if id: $M \to N$ is a smooth embedding

Note 4.2.0.3. Essentially, embedded submanifolds are immersed submanifolds with the subspace topology.

Note 4.2.0.4. For the remainder of this section, we assume that $k \leq n$.

Definition 4.2.0.5. Let $U \subset \mathbb{R}^n$ and $S \subset U$. Then S is said to be a k-slice of U if $S = \{u \in U : u^{k+1}, \dots, u^n = 0\}$.

Exercise 4.2.0.6. Let $U \subset \mathbb{R}^n$ and $S \subset U$. Suppose that S is a k-slice of U. Define $\pi : \mathbb{R}^n \to \mathbb{R}^k$ by

$$\pi(u^1, \dots, u^k, \dots, u^n) = (u^1, \dots, u^k)$$

Then $\pi|_S \to \pi(S)$ is a diffeomorphism.

Proof. Clear.

Definition 4.2.0.7. Let (M, \mathcal{A}) be a smooth manifold, $(U, \phi) \in \mathcal{A}$ and $S \subset U$. Then S is said to be a k-slice of U if $\phi(S)$ is a k-slice of $\phi(U)$.

Definition 4.2.0.8. Let (M, \mathcal{A}) be a smooth manifold, $S \subset M$ and $(U, \phi) \in \mathcal{A}$. Then (U, ϕ) is said to be a k-slice chart for S if $U \cap S$ is a k-slice of U.

Exercise 4.2.0.9. Let (M, \mathcal{A}) be a smooth manifold, $S \subset M$ and $(U, \phi) \in \mathcal{A}$ with $\phi = (x^1, \dots, x^n)$. If (U, ϕ) is a k-slice chart for S, then $\phi|_S = (x^1|_S, \dots, x^k|_S, 0, \dots, 0)$.

Proof. Clear. \Box

Definition 4.2.0.10. Let (M, \mathcal{A}) be a smooth manifold and $S \subset M$. Then S is said to satisfy the **local** k-slice condition if for each $p \in S$, there exists $(U, \phi) \in \mathcal{A}$ such that $p \in U$ and (U, ϕ) is a k-slice chart of S

Exercise 4.2.0.11. Let (M, \mathcal{A}) be a n-dimensional smooth manifold and $S \subset M$ a subspace. If S satisfies the local k-slice condition, then there exists a smooth structure $\tilde{\mathcal{A}}$ on S such that $(S, \tilde{\mathcal{A}})$ is an embedded submanifold of M.

Proof. Suppose that S satisfies the local k-slice condition. Define $\pi: \mathbb{R}^n \to \mathbb{R}^k$ as above Let $(U, \phi) \in \mathcal{A}$. Suppose that (U, ϕ) is a k-slice chart for S. Define $\tilde{U} = U \cap S$ and $\tilde{\phi}: \tilde{U} \to \pi \circ \phi(\tilde{U})$ by

$$\tilde{\phi} = \pi \circ \phi|_{\tilde{U}}$$

By definition, $\phi(\tilde{U})$ is a k-slice of $\phi(U)$. A previous exercise implies that $\pi|_{\phi(\tilde{U})} \to \pi \circ \phi(\tilde{U})$ is a diffeomorphism and hence a homeomorphism. Thus $\tilde{\phi}$ is a homeomorphism. Define

$$\tilde{\mathcal{B}} = \{(\tilde{U}, \tilde{\phi}) : (U, \phi) \text{ is a } k\text{-slice for } S\}$$

Let $p \in S$. By assumption, there exists $(U, \phi) \in \mathcal{A}$ such that $p \in U$ and (U, ϕ) is a k-slice chart of S. Then $(\tilde{U}, \tilde{\phi}) \in \tilde{\mathcal{B}}$ and \mathcal{A} is an atlas on S. By construction of $\tilde{\mathcal{B}}$, S is locally half Euclidean of dimension k. Since M is second countable Hausdorff, so is S in the subspace topology. Thus $(S, \tilde{\mathcal{B}})$ is a k-dimensional manifold. Let $(\tilde{U}, \tilde{\phi})$, $(\tilde{V}, \tilde{\psi}) \in \tilde{\mathcal{B}}$. Then

$$\tilde{\phi}\circ\tilde{\psi}^{-1}|_{\tilde{U}\cap\tilde{V}}=\pi|_{\phi(\tilde{U}\cap\tilde{V})}\circ\phi|_{\tilde{U}\cap\tilde{V}}\circ\psi|_{\tilde{U}\cap\tilde{V}}^{-1}\circ\pi|_{\psi(\tilde{U}\cap\tilde{V})}^{-1}$$

which is a diffeomorphism. So $(\tilde{U}, \tilde{\phi})$ and $(\tilde{V}, \tilde{\psi})$ smoothly compatible. Hence $\tilde{\mathcal{B}}$ is smooth. An exercise in section 4.1 implies that there exists a unique smooth structure $\tilde{\mathcal{A}}$ on S such that $\tilde{\mathcal{B}} \subset \tilde{\mathcal{A}}$. So $(S, \tilde{\mathcal{A}})$ is a smooth k-dimensional manifold.

Clearly id: $S \to S$ is a homeomorphism. Let $(V, \psi) \in \mathcal{A}$ and $(\tilde{U}, \tilde{\phi}) \in \tilde{\mathcal{A}}$.

Finish!! \Box

Definition 4.2.0.12.

Exercise 4.2.0.13.

Chapter 5

Vector Fields

5.1 The Tangent Bundle

Definition 5.1.0.1. Let (M, \mathcal{A}_M) be an *n*-dimensional smooth manifold. We define the **tangent bundle** of M, denoted TM, by

$$TM = \coprod_{p \in M} T_p M$$

and we define the **tangent bundle projection**, denoted $\pi: TM \to M$, by

$$\pi(p, v) = p$$

Let $(U, \phi) \in \mathcal{A}_M$ with $\phi = (x^1, \dots, x^n)$. We define $\Phi_{\phi} : \pi^{-1}(U) \to \mathbb{R}^{2n}$ by

$$\Phi_{\phi}\left(p, \sum_{j=1}^{n} \xi^{j} \frac{\partial}{\partial x^{j}} \bigg|_{p}\right) = (\phi(p), \xi^{1}, \dots, \xi^{n})$$

We define $\mathcal{T}_{TM} = \tau_{TM}(\iota_p : p \in M)$.

Exercise 5.1.0.2. $\psi: \bigcup_{p \in U} T_p M \to \mathbb{R}^n$ is given by

$$\psi\left(\sum_{j=1}^{n} \xi^{j} \frac{\partial}{\partial x^{j}} \Big|_{p}\right) = (\xi^{1}, \dots, \xi^{n})$$

$$x^k \circ \pi \circ \Phi_{\phi}^{-1}(u, v) = x^k \circ \pi(\phi^{-1}(u), \psi^{-1}(v))$$

= $x^k \circ \phi^{-1}(u)$

Therefore

$$\begin{split} \frac{\partial}{\partial \tilde{x}^i} \bigg|_{(p,\xi)} [x^k \circ \pi] &= \frac{\partial}{\partial u^i} \bigg|_{\Phi_{\phi}(p,\xi)} [x^k \circ \pi \circ \Phi_{\phi}^{-1}] \\ &= \frac{\partial}{\partial u^i} \bigg|_{(\phi(p),\psi(\xi))} [x^k \circ \pi \circ \Phi_{\phi}^{-1}] \\ &= \frac{\partial}{\partial u^i} \bigg|_{\phi(p)} [x^k \circ \phi^{-1}] \\ &= \frac{\partial}{\partial x^i} \bigg|_p x^k \\ &= \delta_{i,k} \end{split}$$

and

$$\begin{split} \frac{\partial}{\partial \tilde{y}^i}\bigg|_{(p,\xi)}[x^k\circ\pi] &= \frac{\partial}{\partial v^i}\bigg|_{\Phi_\phi(p,\xi)}[x^k\circ\pi\circ\Phi_\phi^{-1}]\\ &= \frac{\partial}{\partial v^i}\bigg|_{(\phi(p),\psi(\xi))}[x^k\circ\pi\circ\Phi_\phi^{-1}]\\ &= \frac{\partial}{\partial v^i}\bigg|_{\phi(p)}[x^k\circ\phi^{-1}]\\ &= 0 \end{split}$$

This implies that for each $i \in \{1, ..., n\}$, we have that

$$D\pi(p,\xi) \left(\frac{\partial}{\partial \tilde{x}^{i}}\Big|_{(p,\xi)}\right) (f) = \frac{\partial}{\partial \tilde{x}^{i}}\Big|_{(p,\xi)} f \circ \pi$$

$$= \sum_{k=1}^{n} \frac{\partial f}{\partial x^{k}} (\pi(p,\xi)) \frac{\partial x^{k} \circ \pi}{\partial \tilde{x}^{i}} (p,\xi)$$

$$= \sum_{k=1}^{n} \frac{\partial f}{\partial x^{k}} (p) \delta_{i,k}$$

$$= \frac{\partial f}{\partial x^{i}} (p)$$

and

$$D\pi(p,\xi) \left(\frac{\partial}{\partial \tilde{y}^i}\Big|_{(p,\xi)}\right) (f) = \frac{\partial}{\partial \tilde{y}^i}\Big|_{(p,\xi)} f \circ \pi$$

$$= \sum_{k=1}^n \frac{\partial f}{\partial x^k} (\pi(p,\xi)) \frac{\partial x^k \circ \pi}{\partial \tilde{y}^i} (p,\xi)$$

$$= \sum_{k=1}^n \frac{\partial f}{\partial x^k} (p) 0$$

$$= 0$$

Hence

$$\begin{split} V(TM)|_{\pi^{-1}(U)} &= \coprod_{(p,\xi) \in \pi^{-1}(U)} \ker D\pi(p,\xi) \\ &= \coprod_{(p,\xi) \in \pi^{-1}(U)} \operatorname{span} \left\{ \left. \frac{\partial}{\partial \tilde{y}^j} \right|_{(p,\xi)} : j \in \{1,\dots,n\} \right\} \end{split}$$

Chapter 6

Lie Theory

6.1 Lie Groups

Definition 6.1.0.1. Let G be a smooth manifold and group. Then G is said to be a **Lie group** if

- multiplication $G \times G \to G$ given by $(g,h) \mapsto gh$ is smooth
- inversion $G \to G$ given by $g \mapsto g^{-1}$ is smooth

Definition 6.1.0.2. Let $\mathfrak g$ be a vector space and $[\cdot,\cdot]:\mathfrak g\times\mathfrak g\to\mathfrak g$. Then $[\cdot,\cdot]$ is said to be a **Lie bracket** on $\mathfrak g$ if

- 1. $[\cdot, \cdot]$ is bilinear
- 2. $[\cdot, \cdot]$ is antisymmetric
- 3. $[\cdot, \cdot]$ satisfies the Jacobi identity: for each $x, w, y \in \mathcal{F}g$,

$$[x, [y, z]] + [y, [z, x]] + [z, [x, y]] = 0$$

In this case, $(\mathfrak{g}, [\cdot, \cdot])$ is said to be a **Lie algebra**.

Definition 6.1.0.3. Let $X \in$

Chapter 7

Bundles and Sections

7.1 Fiber Bundles

Note 7.1.0.1. Let U, F be sets, we write $\text{proj}_1 : U \times F \to U$ to denote the projection onto U.

Definition 7.1.0.2. Let $E, M, F \in \text{Obj}(\mathbf{Set}), \pi \in \text{Hom}_{\mathbf{Set}}(E, M)$ a surjection, $U \subset M$ and $\Phi : \pi^{-1}(U) \to U \times F$. Then (U, Φ) is said to be a **local trivialization of** E **over** U **with fiber** F if

- 1. Φ is a bijection
- 2. $\operatorname{proj}_1 \circ \Phi = \pi|_{\pi^{-1}(U)}$, i.e. the following diagram commutes:

$$\pi^{-1}(U) \xrightarrow{\Phi} U \times F$$

$$\downarrow^{\operatorname{proj}_1}$$

$$U$$

Exercise 7.1.0.3. Let $E, M, F \in \text{Obj}(\mathbf{Set})$ and $\pi \in \text{Hom}_{\mathbf{Set}}(E, M)$ a surjection, $U \subset M$ and $\Phi : \pi^{-1}(U) \to U \times F$ a local trivialization of E over U with fiber F. Then for each $A \subset U$,

$$\Phi(\pi^{-1}(A)) = A \times F$$

Hint: consider $\Phi^{-1}(A \times F)$

Proof. Let $A \subset U$. Since $\operatorname{proj}_{1}^{-1}(A) = A \times F$, we have that

$$\Phi^{-1}(A \times F) = \Phi^{-1}(\text{proj}_1^{-1}(A))$$

$$= (\text{proj}_1 \circ \Phi)^{-1}(A)$$

$$= (\pi|_{\pi^{-1}(U)})^{-1}(A)$$

$$= \pi^{-1}(A) \cap \pi^{-1}(U)$$

$$\pi^{-1}(A \cap U)$$

$$= \pi^{-1}(A)$$

Since Φ is a bijection, we have that

$$\Phi(\pi^{-1}(A)) = \Phi \circ \Phi^{-1}(A \times F)$$
$$= A \times F$$

7.1.1 Topological Fiber Bundles

Definition 7.1.1.1. Let $E, M, F \in \text{Obj}(\mathbf{Man}^0)$ and $\pi \in \text{Hom}_{\mathbf{Man}^0}(E, M)$ a surjection, $U \subset M$ and $\Phi : \pi^{-1}(U) \to U \times F$. Then (U, Φ) is said to be a **continuous local trivialization of** E **over** U **with fiber** F if

- 1. U is open
- 2. (U, Φ) is a local trivialization of E over U with fiber F
- 3. Φ is a homeomorphism

Exercise 7.1.1.2. Topological Fiber Bundle Chart Lemma:

Let $E \in \text{Obj}(\mathbf{Set})$, $M, F \in \text{Obj}(\mathbf{Man}^0)$, $\pi : E \to M$ a surjection, Γ an index set and for each $\alpha \in \Gamma$, $U_{\alpha} \subset M$ and $\Phi_{\alpha} : \pi^{-1}(U_{\alpha}) \to U_{\alpha} \times F$. Set $n = \dim M$ and $k = \dim F$. Suppose that

- for each $\alpha \in \Gamma$, $U_{\alpha} \in \mathcal{T}_{M}$
- $M \subset \bigcup_{\alpha \in \Gamma} U_{\alpha}$
- for each $\alpha \in \Gamma$, $(U_{\alpha}, \Phi_{\alpha})$ is a local trivialization of E over U_{α}
- for each $\alpha, \beta \in \Gamma$, $\Phi_{\beta}|_{\pi^{-1}(U_{\alpha} \cap U_{\beta})} \circ (\Phi_{\alpha}|_{\pi^{-1}(U_{\alpha} \cap U_{\beta})})^{-1} : (U_{\alpha} \cap U_{\beta}) \times F \to (U_{\alpha} \cap U_{\beta}) \times F$ is continuous.

Then there exist a unique topology, \mathcal{T}_E , on E such that

- 1. (E, \mathcal{T}_E) is a n + k-dimensional topological manifold
- 2. (E, \mathcal{T}_E)

 $(U_{\alpha}, \Phi_{\alpha})$ a local trivialization of E over U. Suppose that

Proof. For $\alpha \in \Gamma$, we define $X_{\alpha}^{n}(M, \mathcal{T}_{M}) \subset X^{n}(M, \mathcal{T}_{M})$ by

$$X_{\alpha}^{n}(M,\mathcal{T}_{M}) = \{(V^{M},\psi^{M}) \in X^{n}(M,\mathcal{T}_{M}) : V^{M} \subset U_{\alpha}\}$$

Choose index sets $(\Pi^M_\alpha)_{\alpha\in\Gamma}$ and Π^F such that for each $\alpha\in\Gamma$, $X^n_\alpha(M,\mathcal{T}_M)=(V^M_\mu,\psi^M_\mu)_{\mu\in\Pi^M_\alpha}$ and $X^k(F,\mathcal{T}_F)=(V^F_\nu,\psi^F_\nu)_{\nu\in\Pi^F}$. Set $\Pi^M=\coprod_{\alpha\in\Gamma}\Pi^M_\alpha$. For $(\alpha,\mu)\in\Pi^M$, $\nu\in\Pi^F$, we define $V^E_{\mu,\nu}\subset E$ and $\psi^E_{\mu,\nu}:V^E_{\mu,\nu}\to\psi^M_\mu(V^M_\mu)\times\psi^F_\nu(V^F_\nu)$ by

- $\bullet \ V^E_{\mu,\nu} = \Phi^{-1}_\alpha(V^M_\mu \times V^F_\nu)$
- $\bullet \ \psi_{\mu,\nu}^E = (\psi_{\mu}^M \times \psi_{\nu}^F) \circ \Phi_{\alpha}|_{V_{\mu,\nu}^E}$

We have the following:

- $(\alpha, \mu) \in \Pi^M$ and $\nu \in \Pi^F$. Then $\psi^E_{\mu,\nu}(V^E_{\mu,\nu}) = \psi^M_\mu(V^M_\mu) \times \psi^F_\nu(V^F_\nu)$ and thus $\psi^E_{\mu,\nu}(V^E_{\mu,\nu}) \in \mathcal{T}_{\mathbb{H}^{n+k}}$
- for each $(\alpha_1, \mu_1), (\alpha_2, \mu_2) \in \Pi^M$ and $\nu_1, \nu_2 \in \Pi^F$,

$$\begin{split} \psi^E_{\mu_1,\nu_1}(V^E_{\mu_1,\nu_1} \cap V^E_{\mu_2,\nu_2}) &= (\psi^M_{\mu_1} \times \psi^F_{\nu_1}) \circ \Phi_{\alpha_1}|_{V^E_{\mu_1,\nu_1}}(\Phi^{-1}_{\alpha_1}([V^M_{\mu_1} \times V^F_{\nu_1})] \cap [V^M_{\mu_2} \times V^F_{\nu_2}])) \\ &= (\psi^M_{\mu_1} \times \psi^F_{\nu_1})([V^M_{\mu_1} \times V^F_{\nu_1})] \cap [V^M_{\mu_2} \times V^F_{\nu_2}]) \\ &= (\psi^M_{\mu_1} \times \psi^F_{\nu_1})([V^M_{\mu_1} \cap V^M_{p_2}] \times [V^F_{\nu_1} \cap V^F_{q_2}]) \\ &= \psi^M_{\mu_1}(V^M_{\mu_1} \cap V^M_{p_2}) \times \psi^F_{\nu_1}(V^F_{\nu_1} \cap V^F_{q_2}) \\ &\in \mathcal{T}_{\square_{n+k}} \end{split}$$

• Let $(\alpha,\mu)\Pi^M$ and $\nu \in \Pi^F$. Then $\psi^E_{\mu,\nu}: V^E_{\mu,\nu} \to \psi^M_\mu(V^M_\mu) \times \psi^F_\nu(V^F_\nu)$ is a bijection

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• Let $(\alpha_1, \mu_1), (\alpha_2, \mu_2) \in \Pi^M$ and $\nu_1, \nu_2 \in \Pi^F$. For notational convenience, set $\psi_1^E = \psi_{\mu_1, \nu_1}^E, \psi_2^E = \psi_{\mu_2, \nu_2},$ $V^E = V_{\mu_1, \nu_1}^E \cap V_{\mu_2, \nu_2}^E, V^M = V_{\mu_1}^M \cap V_{\mu_2}^M$ and $V^F = V_{\nu_1}^F \cap V_{\nu_2}^F$. Then $\psi_2|_{V^E} \circ (\psi_1|_{V^E})^{-1} : \psi_1(V^E) \to \psi_2(V^E)$ is given by

$$\begin{split} \psi_{2}^{E}|_{V^{E}} \circ (\psi_{1}^{E}|_{V^{E}})^{-1} &= [(\psi_{\mu_{2}}^{M}|_{V^{M}} \times \psi_{\nu_{2}}^{F}|_{V^{F}}) \circ \Phi_{\alpha_{2}}|_{V^{E}}] \circ [(\psi_{\mu_{1}}^{M}|_{V^{M}} \times \psi_{\nu_{1}}^{F}|_{V^{F}}) \circ \Phi_{\alpha_{1}}|_{V^{E}}]^{-1} \\ &= [(\psi_{\mu_{2}}^{M}|_{V^{M}} \times \psi_{\nu_{2}}^{F}|_{V^{F}}) \circ \Phi_{\alpha_{2}}|_{V^{E}}] \circ [(\Phi_{\alpha_{1}}|_{V^{E}})^{-1} \circ (\psi_{\mu_{1}}^{M}|_{V^{M}} \times \psi_{\nu_{1}}^{F}|_{V^{F}})^{-1}] \\ &= (\psi_{\mu_{2}}^{M}|_{V^{M}} \times \psi_{\nu_{2}}^{F}|_{V^{F}}) \circ [\Phi_{\alpha_{2}}|_{V^{E}} \circ (\Phi_{\alpha_{1}}|_{V^{E}})^{-1}] \circ (\psi_{\mu_{1}}^{M}|_{V^{M}} \times \psi_{\nu_{1}}^{F}|_{V^{F}})^{-1} \end{split}$$

Since $\Phi_{\alpha_2}|_{V^E} \circ (\Phi_{\alpha_1}|_{V^E})^{-1}$ is continuous, we have that

$$\psi^E_{\mu_2,\nu_2}|_{V^E_{\mu_1,\nu_1}\cap V^E_{\mu_2,\nu_2}}\circ (\psi^E_{\mu_1,\nu_1}|_{V^E_{\mu_1,\nu_1}\cap V^E_{\mu_2,\nu_2}})^{-1}:\psi^E_{\mu_1,\nu_1}(V^E_{\mu_1,\nu_1}\cap V^E_{\mu_2,\nu_2})\to \psi^E_{\mu_2,\nu_2}(V^E_{\mu_1,\nu_1}\cap V^E_{\mu_2,\nu_2})$$

is continuous

• A previous exercise in the section on topological manifolds implies that $(V_{\mu}^{M})_{(\alpha,\mu)\in\Pi^{M}}$ is an open cover of M and $(V_{\nu}^{F})_{\nu\in\Pi^{F}}$ is an open cover of F. Since M,F are second-countable M,F are Lindelöf and there exists $S^{M}\subset\Pi^{M}$, $S^{F}\subset\Pi^{F}$ such that S^{M},S^{F} are countable and $(V_{\mu}^{M})_{(\alpha,\mu)\in S^{M}}$ is an open cover of M and $(V_{\nu}^{F})_{\nu\in\Pi^{F}}$ is an open cover of F. Then $S^{M}\times S^{F}$ is countable and $(V_{\mu}^{M}\times V_{\nu}^{F})_{(\alpha,\mu,\nu)\in S^{M}\times S^{F}}$ is an open cover of $M\times F$.

Let $a \in E$. Set $p = \pi(a)$. Choose $(\alpha, \mu) \in S^M$ such that $p \in V_\mu^M$. Since $V_\mu^M \subset U_\alpha$, $a \in \pi^{-1}(U_\alpha)$ which implies that

$$p = \pi(a)$$
$$= \operatorname{proj}_1 \circ \Phi_{\alpha}(a)$$

Set $q = \text{proj}_2 \circ \Phi_{\alpha}(a)$. Choose $\nu \in S^F$ such that $q \in V_{\nu}^F$. Then

$$\begin{split} \Phi_{\alpha_p}(a) &= (\operatorname{proj}_1 \circ \Phi_{\alpha_p}(a), \operatorname{proj}_2 \circ \Phi_{\alpha_p}(a)) \\ &= (p,q) \\ &\in V^M_\mu \times V^F_\nu \end{split}$$

Thus

$$\begin{aligned} a &\in \Phi_{\alpha_p}^{-1}(V_p^M \times V_q^F) \\ &= V_{\mu,\nu}^E \end{aligned}$$

Since $a \in E$ is arbitrary, we have that for each $a \in E$, there exists $(\alpha, \mu, \nu) \in S^M \times S^F$ such that $a \in V_{\mu,\nu}^E$. Thus

$$E \subset \bigcup_{(\alpha,\mu,\nu)\in S^M\times S^F} V_{\mu,\nu}$$

• Let $a_1, a_2 \in E$. Set $p_1 = \pi(a_1)$ and $p_2 = \pi(a_2)$. Suppose that $p_1 \neq p_2$. Since M is Hausdorff, there exist $(\alpha_1, \mu_1), (\alpha_2, \mu_2) \in \Pi^M$ such that $p_1 \in V_{\mu_1}^M$, $p_2 \in V_{\mu_2}^M$ and $V_{\mu_1}^M \cap V_{\mu_2}^M = \emptyset$. Set $q_1 = \operatorname{proj}_2 \circ \Phi_{\alpha_1}(a_1)$ and $q_2 = \operatorname{proj}_2 \circ \Phi_{\alpha_2}(a_2)$. Choose $\nu_1, \nu_2 \in \Pi^F$ such that $q_1 \in V_{\nu_1}^F$ and $q_2 \in V_{\nu_2}^F$. Then similarly to the previous part, $a_1 \in V_{\mu_1,\nu_1}^E$ and $a_2 \in V_{\mu_2,\nu_2}^E$. Then

$$\begin{split} V^E_{\mu_1,\nu_1} \cap V^E_{\mu_2,\nu_2} &= \Phi_{\alpha_1}^{-1}(V^M_{\mu_1} \times V^F_{\nu_1}) \cap \Phi_{\alpha_2}^{-1}(V^M_{\mu_2} \times V^F_{\nu_2}) \\ &\subset \pi^{-1}(V^M_{\mu_1}) \cap \pi^{-1}(V^M_{\mu_2}) \\ &= \pi^{-1}(V^M_{\mu_1} \cap V^M_{\mu_2}) \\ &= \pi^{-1}(\varnothing) \\ &= \varnothing \end{split}$$

Suppose that $p_1 = p_2$.

$$\begin{split} \Phi_{\alpha_1}(V_{\mu_1,\nu_1}^E \cap V_{\mu_2,\nu_2}^E) &= \Phi_{\alpha_1} \bigg[\Phi_{\alpha_1}^{-1}(V_{\mu_1}^M \times V_{\nu_2}^F) \cap \Phi_{\alpha_2}^{-1}(V_{\mu_2}^M \times V_{\nu_2}^F) \bigg] \\ &= (V_{\mu_1}^M \times V_{\nu_2}^F) \cap \Phi_{\alpha_1}(\Phi_{\alpha_2}^{-1}(V_{\mu_2}^M \times V_{\nu_2}^F)) \end{split}$$

Using the hint on the Topological Manifold Chart Lemma, we have that

$$\begin{split} V^E_{\mu_1,\nu_1} \cap V^E_{\mu_2,\nu_2} &= \Phi_{\alpha_1} \bigg[(V^M_{\mu_1} \times V^F_{\nu_2}) \cap \Phi_{\alpha_1}^{-1} \Phi_{\alpha_2}^{-1} (V^M_{\mu_2} \times V^F_{\nu_2}) \bigg] \\ &= \Phi_{\alpha_1}^{-1} (V^M_{\mu_1} \times V^F_{\nu_2}) \cap \Phi_{\alpha_2}^{-1} (V^M_{\mu_2} \times V^F_{\nu_2}) \end{split}$$

FINISH!!!

7.1.2 Smooth Fiber Bundles

Definition 7.1.2.1. Let $E, M, F \in \text{Obj}(\mathbf{Man}^{\infty})$ and $\pi \in \text{Hom}_{\mathbf{Man}^{\infty}}(E, M)$ a surjection, $U \subset M$ and $\Phi : \pi^{-1}(U) \to U \times F$. Then (U, Φ) is said to be a **smooth local trivialization of** E **over** U **with fiber** F if

- 1. U is open
- 2. (U, Φ) is a local trivialization of E over U with fiber F
- 3. Φ is a diffeomorphism

Definition 7.1.2.2. Let $E, M, F \in \text{Obj}(\mathbf{Man}^{\infty})$ and $\pi \in \text{Hom}_{\mathbf{Man}^{\infty}}(E, M)$ a surjection. Then (E, M, π, F) is said to be a **smooth fiber bundle with total space** E, **base space** M, **fiber** F **and projection** π if for each $p \in M$, there exist $U \in \mathcal{N}_p$ and $\Phi : \pi^{-1}(U) \to U \times F$ such that U is open and (U, Φ) is a smooth local trivialization of E over U with fiber F. For $p \in M$, we define the **fiber over** p, denoted E_p , by $E_p = \pi^{-1}(\{p\})$.

Note 7.1.2.3. When the context is clear, we will supress the fiber manifold F.

Definition 7.1.2.4. Let (E_1, M_1, π_1, F_1) and (E_2, M_2, π_2, F_2) be smooth fiber bundles, $\Phi \in \operatorname{Hom}_{\mathbf{Man}^{\infty}}(E_1, E_2)$ and $\phi \in \operatorname{Hom}_{\mathbf{Man}^{\infty}}(M_1, M_2)$. Then (Φ, ϕ) is said to be a **smooth bundle morphism** from (E_1, M_1, π_1, F_1) to (E_2, M_2, π_2, F_2) if $\pi_2 \circ \Phi = \phi \circ \pi_1$, i.e. the following diagram commutes:

$$E_1 \xrightarrow{\Phi} E_2$$

$$\pi_1 \downarrow \qquad \qquad \downarrow \pi_2$$

$$M_1 \xrightarrow{\phi} M_2$$

Definition 7.1.2.5. We define the category of smooth fiber bundles, denoted \mathbf{Bun}^{∞} , by

- Obj(\mathbf{Bun}^{∞}) = { $(E, M, \pi, F) : (E, M, \pi, F)$ is a smooth fiber bundle}
- For $(E_1, M_1, \pi_1, F_1), (E_2, M_2, \pi_2, F_2) \in \text{Obj}(\mathbf{Bun}^{\infty}),$

$$\operatorname{Hom}_{\mathbf{Bun}^{\infty}}((E_1, M_1, \pi_1, F_1), (E_2, M_2, \pi_2, F_2)) = \{(\Phi, \phi) : (\Phi, \phi) \text{ is a smooth bundle morphism from } (E_1, M_1, \pi_1, F_1) \text{ to } (E_2, M_2, \pi_2, F_2)\}$$

- For
 - $-(E_1, M_1, \pi_1, F_1), (E_2, M_2, \pi_2, F_2), (E_3, M_3, \pi_3) \in \text{Obj}(\mathbf{Bun}^{\infty})$
 - $-(\Phi_{12}, \phi_{12}) \in \operatorname{Hom}_{\mathbf{Bun}^{\infty}}((E_1, M_1, \pi_1, F_1), (E_2, M_2, \pi_2, F_2))$
 - $-(\Phi_{23}, \phi_{23}) \in \text{Hom}_{\mathbf{Bun}^{\infty}}((E_2, M_2, \pi_2, F_2), (E_3, M_3, \pi_3))$

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we define
$$(\Phi_{23}, \phi_{23}) \circ (\Phi_{12}, \phi_{12}) \in \operatorname{Hom}_{\mathbf{Bun}^{\infty}}((E_1, M_1, \pi_1, F_1), (E_3, M_3, \pi_3))$$
 by
$$(\Phi_{23}, \phi_{23}) \circ (\Phi_{12}, \phi_{12}) = (\Phi_{23} \circ \Phi_{12}, \phi_{23} \circ \phi_{12})$$

Exercise 7.1.2.6. We have that \mathbf{Bun}^{∞} is a full subcategory of $(\mathrm{id}_{\mathbf{Man}^{\infty}} \downarrow \mathrm{id}_{\mathbf{Man}^{\infty}})$.

Proof. Set $\mathcal{C} = (\mathrm{id}_{\mathbf{Man}^{\infty}} \downarrow \mathrm{id}_{\mathbf{Man}^{\infty}})$. We note that

- $Obj(\mathbf{Bun}^{\infty}) \subset Obj(\mathcal{C})$
- for each $(E_1, M_1, \pi_1, F_1), (E_2, M_2, \pi_2, F_2) \in \text{Obj}(\mathbf{Bun}^{\infty}),$

$$\operatorname{Hom}_{\mathbf{Bun}^{\infty}}((E_1, M_1, \pi_1, F_1), (E_2, M_2, \pi_2, F_2)) = \operatorname{Hom}_{\mathcal{C}}((E_1, M_1, \pi_1, F_1), (E_2, M_2, \pi_2, F_2))$$

So \mathbf{Bun}^{∞} is a full subcategory of \mathcal{C} .

Exercise 7.1.2.7. Let $(E, M, \pi, F) \in \mathbf{Bun}^{\infty}$ and (U, Φ) a local trivialization of E over U and (V, Ψ) a local trivialization of E over V. Then

- 1. $\operatorname{proj}_{U \cap V} \circ \Psi|_{\pi^{-1}(U \cap V)} \circ (\Phi|_{\pi^{-1}(U \cap V)})^{-1} = \operatorname{proj}_1$
- 2. there exists $\sigma \in \operatorname{Hom}_{\mathbf{Man}^{\infty}}((U \cap V) \times F, F)$ such that for each $p \in U \cap V$, $\sigma(p, \cdot) : F \to F$ is a diffeomorphism.

Proof.

1. By definition, the following diagram commutes:

$$(U \cap V) \times F \xleftarrow{\Phi} \pi^{-1}(U \cap V) \xrightarrow{\Psi} (U \cap V) \times F$$

$$\downarrow proj_1 \qquad \downarrow proj_1$$

$$\operatorname{proj}_{1} \circ \Psi|_{\pi^{-1}(U \cap V)} \circ (\Phi|_{\pi^{-1}(U \cap V)})^{-1} = \operatorname{proj}_{1}$$

2. there exists $\sigma \in \operatorname{Hom}_{\operatorname{Man}^{\infty}}((U \cap V) \times F, F)$ such that for each $p \in U \cap V$ and $x \in F$,

$$\Psi|_{\pi^{-1}(U\cap V)}\circ (\Phi|_{\pi^{-1}(U\cap V)})^{-1}(p,x)=(p,\sigma(p,x))$$

and $\sigma(p,\cdot): F \to F$ is a diffeomorphism.

Definition 7.1.2.8. Let $(E, M, \pi, F) \in \mathbf{Bun}^{\infty}$ and $(U_{\alpha}, \Phi_{\alpha})_{\alpha \in A}$ a collection of smooth local trivializations of E. Then $(U_{\alpha}, \Phi_{\alpha})_{\alpha \in A}$ is said to be a **fiber bundle atlas** if for each $p \in M$, there exists $\alpha \in A$ such that $p \in U_{\alpha}$. For $\alpha, \beta \in A$, we define ϕ

7.2 G-Bundles

Definition 7.2.0.1. Let G be a Lie group and $(E, M, \pi, F) \in \text{Obj}(\mathbf{Bun}^{\infty})$. Then

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7.3 Vector Bundles

Note 7.3.0.1. Let M be a set and $p \in M$. We endow $\{p\} \times \mathbb{R}^n$ with the natural vector space structure such that $\{p\} \times \mathbb{R}^k \cong \mathbb{R}^k$.

Definition 7.3.0.2. Let $E, M \in \text{Obj}(\mathbf{Man}^{\infty})$ and $\pi \in \text{Hom}_{\mathbf{Man}^{\infty}}(E, M)$ a surjection. Then (E, M, π) is said to be a rank k smooth vector bundle if

- 1. $(E, M, \pi, \mathbb{R}^k) \in \text{Obj}(\mathbf{Bun}^{\infty})$
- 2. for each $p \in M$, E_p is a k-dimensional real vector space
- 3. for each smooth local trivialization (U, Φ) of E over U with fiber \mathbb{R}^k and $p \in U$,

$$\Phi|_{E_n}: E_p \to \{p\} \times \mathbb{R}^k$$

is a vector space isomorphism

In this case we define the rank of (E, M, π) , denoted rank (E, M, π) , by rank $(E, M, \pi) = k$.

Definition 7.3.0.3. We define the category of smooth vector bundles, denoted \mathbf{VecBun}^{∞} , by

- Obj(VecBun^{∞}) = { $(E, M, \pi) : (E, M, \pi)$ is a smooth vector bundle}
- For $(E_1, M_1, \pi_1), (E_2, M_2, \pi_2) \in \text{Obj}(\mathbf{VecBun}^{\infty})$ with $\text{rank}(E_1, M_1, \pi_1) = k_1$ and $\text{rank}(E_2, M_2, \pi_2) = k_2$,

$$\text{Hom}_{\mathbf{VecBun}^{\infty}}((E_1, M_1, \pi_1), (E_2, M_2, \pi_2)) = \text{Hom}_{\mathbf{Bun}^{\infty}}((E_1, M_1, \pi_1, \mathbb{R}^{k_1}), (E_2, M_2, \pi_2, \mathbb{R}^{k_2}))$$

Exercise 7.3.0.4. We have that $VecBun^{\infty}$ is a full subcategory of Bun^{∞} .

Proof. We note that

- $\mathrm{Obj}(\mathbf{VecBun}^{\infty}) \subset \mathrm{Obj}(\mathbf{Bun}^{\infty})$
- for each $(E_1, M_1, \pi_1), (E_2, M_2, \pi_2) \in \text{Obj}(\mathbf{Bun}^{\infty})$ with $\text{rank}(E_1, M_1, \pi_1) = k_1$ and $\text{rank}(E_2, M_2, \pi_2) = k_2$,

$$\operatorname{Hom}_{\mathbf{VecBun}^{\infty}}((E_1, M_1, \pi_1), (E_2, M_2, \pi_2)) = \operatorname{Hom}_{\mathbf{Bun}^{\infty}}((E_1, M_1, \pi_1, \mathbb{R}^{k_1}), (E_2, M_2, \pi_2, \mathbb{R}^{k_2}))$$

So \mathbf{Bun}^{∞} is a full subcategory of \mathcal{C} .

Exercise 7.3.0.5. Let $M \in \text{Obj}(\mathbf{Man}^{\infty})$. Set $n = \dim M$, $E = M \times \mathbb{R}^k$ and define $\pi : E \to M$ by $\pi(p, x) = p$. Then (E, M, π) is a rank k smooth vector bundle.

Proof.

- 1. For each $p \in M$, $\pi_1^{-1}(\{p\}) = \{p\} \times \mathbb{R}^k$ is an n-dimensional real vector space.
- 2. Let $p \in M$. Set U = M. Then $\pi^{-1}(U) = E$. Define $\Phi : \pi^{-1}(U) \to U \times \mathbb{R}^k$ by $\Phi = \mathrm{id}_E$. Then (U, Φ) is a smooth local trivialization of E over U.
- 3. Let $p \in M$. Then $\Phi|_{\pi^{-1}(\{p\})} : \pi^{-1}(\{p\}) \to \{p\} \times \mathbb{R}^k$ is clearly an isomorphism.

Exercise 7.3.0.6. Smooth Vector Bundle Chart Lemma:

Let $M \in \text{Obj}(\mathbf{Man}^{\infty})$. Denote the topology on M by \mathcal{T}_{M} . Suppose that for each $p \in M$, there exists $E_{p} \in \text{Obj}(\mathbf{Vect}_{\mathbb{R}})$ such that $\dim E_{p} = k$. We define $E \in \text{Obj}(\mathbf{Set})$ and $\pi \in \text{Hom}_{\mathbf{Set}}(E, M)$ by

$$E = \coprod_{p \in M} E_p$$

and $\pi(p,v)=p$. Let Γ be an index set and $(U_{\alpha})_{\alpha\in\Gamma}\subset\mathcal{T}_{M}$. Suppose that

1.
$$M \subset \bigcup_{\alpha \in \Gamma} U_{\alpha}$$

- 2. for each $\alpha \in \Gamma$, there exists $\Phi_{\alpha} : \pi^{-1}(U_{\alpha}) \to U_{\alpha} \times \mathbb{R}^{k}$ such that
 - $\Phi_{\alpha}: \pi^{-1}(U_{\alpha}) \to U_{\alpha} \times \mathbb{R}^{k}$ is a bijection
 - $\Phi_{\alpha}|_{E_p}: E_p \to \{p\} \times \mathbb{R}^k$ is a vector space isomorphism
- 3. for each $\alpha, \beta \in \Gamma$, there exists $\tau_{\alpha,\beta}: U_{\alpha} \cap U_{\beta} \to GL(k,\mathbb{R})$ such that
 - $\tau_{\alpha,\beta}: U_{\alpha} \cap U_{\beta} \to GL(k,\mathbb{R})$ is smooth
 - $\Phi_{\alpha}|_{\pi^{-1}(U_{\alpha}\cap U_{\beta})} \circ (\Phi_{\beta}|_{\pi^{-1}(U_{\alpha}\cap U_{\beta})})^{-1} : (U_{\alpha}\cap U_{\beta}) \times \mathbb{R}^{k} \to (U_{\alpha}\cap U_{\beta}) \times \mathbb{R}^{k}$ is given by

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7.4 Bundle Morphisms

Definition 7.4.0.1. Let (E, M, π_E) and (F, N, π_F) be smooth fiber bundles and $\Phi: E \to F$ and $\phi: M \to N$. Then (Φ, ϕ) is said to be a **smooth fiber bundle morphism** from (E, M, π_E) to (F, N, π_F) if Φ is smooth, ϕ is smooth and $\pi_F \circ \Phi = \phi \circ \pi_E$, i.e. the following diagram commutes:

$$\begin{array}{ccc} E & \stackrel{\Phi}{\longrightarrow} & F \\ \pi_E \downarrow & & \downarrow \pi_F \\ M & \stackrel{\phi}{\longrightarrow} & N \end{array}$$

and we write $(\Phi, \phi) : (E, M, \pi_E) \to (F, N, \pi_F)$.

Exercise 7.4.0.2. Let (E, M, π_E) and (F, N, π_F) be smooth fiber bundles and $(\Phi, \phi) : (E, M, \pi_E) \to (F, N, \pi_F)$. Suppose that (Φ, ϕ) is smooth. Then for each $p \in M$,

$$\Phi^{-1}(F_{\phi(p)}) = E_p$$

Proof. Let $p \in M$. Set $q = \phi(p)$. Then

$$\begin{split} \Phi^{-1}(F_q) &= \Phi^{-1}(\pi_F^{-1}(\{q\})) \\ &= (\pi_F \circ \Phi)^{-1}(\{q\}) \\ &= (\phi \circ \pi_E)^{-1}(\{q\}) \\ &= \pi_E^{-1}(\phi^{-1}(\{\phi(p)\})) \end{split}$$

FINISH!!!, multiple fibers get mapped to same fiber

7.5 Subbundles

7.6 Vertical and Horizontal Subbundles

Definition 7.6.0.1. Let $(E, M, \pi_M) \in \text{Obj}(\mathbf{Bun}^{\infty})$. We define the **vertical bundle associated to** (E, M, π_M) , denoted $(VE, M, \pi_V) \in \mathbf{Bun}^{\infty}$, by

$$VE = \coprod_{q \in E} \ker D\pi(q)$$

relocate this to after tangent bundle is introduced

Exercise 7.6.0.2. Let (M, \mathcal{A}) be an n-dimensional smooth manifold and $(U, \phi) \in \mathcal{A}$ with $\phi = (x^1, \dots, x^n)$, $(\pi^{-1}(U), \Phi_{\phi}) \in \mathcal{A}_{TM}$ the induced chart on TM with $\Phi_{\phi} = (\tilde{x}^1, \dots, \tilde{x}^n, \tilde{y}^1, \dots, \tilde{y}^n)$. Then

$$V(TM)|_{\pi^{-1}(U)} = \coprod_{(p,\xi) \in \pi^{-1}(U)} \operatorname{span} \left\{ \frac{\partial}{\partial \tilde{y}^j} \bigg|_{(p,\xi)} : j \in \{1,\dots,n\} \right\}$$

Split into smaller exercises

Proof. Let $f \in C^{\infty}(M)$ and $(u^1, \dots, u^n, v^1, \dots, v^n)$ the standard coordinates on $\mathbb{R}^n \times \mathbb{R}^n$. We note that by definition, $\Phi_{\phi}(p,\xi) = (\phi(p), \psi(\xi))$ where $\psi : \bigcup_{p \in U} T_pM \to \mathbb{R}^n$ is given by

$$\psi\left(\sum_{j=1}^{n} \xi^{j} \frac{\partial}{\partial x^{j}} \Big|_{p}\right) = (\xi^{1}, \dots, \xi^{n})$$

$$x^{k} \circ \pi \circ \Phi_{\phi}^{-1}(u, v) = x^{k} \circ \pi(\phi^{-1}(u), \psi^{-1}(v))$$
$$= x^{k} \circ \phi^{-1}(u)$$

Therefore

$$\begin{split} \frac{\partial}{\partial \tilde{x}^i} \bigg|_{(p,\xi)} [x^k \circ \pi] &= \frac{\partial}{\partial u^i} \bigg|_{\Phi_{\phi}(p,\xi)} [x^k \circ \pi \circ \Phi_{\phi}^{-1}] \\ &= \frac{\partial}{\partial u^i} \bigg|_{(\phi(p),\psi(\xi))} [x^k \circ \pi \circ \Phi_{\phi}^{-1}] \\ &= \frac{\partial}{\partial u^i} \bigg|_{\phi(p)} [x^k \circ \phi^{-1}] \\ &= \frac{\partial}{\partial x^i} \bigg|_p x^k \\ &= \delta_{i,k} \end{split}$$

and

$$\begin{split} \frac{\partial}{\partial \tilde{y}^i} \bigg|_{(p,\xi)} [x^k \circ \pi] &= \frac{\partial}{\partial v^i} \bigg|_{\Phi_{\phi}(p,\xi)} [x^k \circ \pi \circ \Phi_{\phi}^{-1}] \\ &= \frac{\partial}{\partial v^i} \bigg|_{(\phi(p),\psi(\xi))} [x^k \circ \pi \circ \Phi_{\phi}^{-1}] \\ &= \frac{\partial}{\partial v^i} \bigg|_{\phi(p)} [x^k \circ \phi^{-1}] \\ &= 0 \end{split}$$

This implies that for each $i \in \{1, ..., n\}$, we have that

$$\begin{split} D\pi(p,\xi) \bigg(\frac{\partial}{\partial \tilde{x}^i} \bigg|_{(p,\xi)} \bigg) (f) &= \frac{\partial}{\partial \tilde{x}^i} \bigg|_{(p,\xi)} f \circ \pi \\ &= \sum_{k=1}^n \frac{\partial f}{\partial x^k} (\pi(p,\xi)) \frac{\partial x^k \circ \pi}{\partial \tilde{x}^i} (p,\xi) \\ &= \sum_{k=1}^n \frac{\partial f}{\partial x^k} (p) \delta_{i,k} \\ &= \frac{\partial f}{\partial x^i} (p) \end{split}$$

and

$$\begin{split} D\pi(p,\xi) \bigg(\frac{\partial}{\partial \tilde{y}^i} \bigg|_{(p,\xi)} \bigg) (f) &= \frac{\partial}{\partial \tilde{y}^i} \bigg|_{(p,\xi)} f \circ \pi \\ &= \sum_{k=1}^n \frac{\partial f}{\partial x^k} (\pi(p,\xi)) \frac{\partial x^k \circ \pi}{\partial \tilde{y}^i} (p,\xi) \\ &= \sum_{k=1}^n \frac{\partial f}{\partial x^k} (p) 0 \\ &= 0 \end{split}$$

Hence

$$\begin{split} V(TM)|_{\pi^{-1}(U)} &= \coprod_{(p,\xi) \in \pi^{-1}(U)} \ker D\pi(p,\xi) \\ &= \coprod_{(p,\xi) \in \pi^{-1}(U)} \operatorname{span} \left\{ \left. \frac{\partial}{\partial \tilde{y}^j} \right|_{(p,\xi)} : j \in \{1,\dots,n\} \right\} \end{split}$$

7.7 The Tangent Bundle

Definition 7.7.0.1. We define the **tangent bundle of** M, denoted TM, by

$$TM = \coprod_{p \in M} T_p M$$

We denote the natrual projection map by $\pi: TM \to M$.

Definition 7.7.0.2. Let $(U, \phi) \in \mathcal{A}$ with $\phi = (x^1, \dots, x^n)$. Define $\tilde{U} \subset TM$ and $\tilde{\phi} : \tilde{U} \to \phi(U) \times \mathbb{R}^n$ by

$$\bullet \ \tilde{U}=\pi^{-1}(U)$$

•

$$\tilde{\phi}\left(\left.\sum_{i=1}^{n} v^{i} \frac{\partial}{\partial x^{i}}\right|_{p}\right) = (\phi(p), v)$$

$$= (x^{1}(p), \dots, x^{n}(p), v^{1}, \dots, v^{n})$$

Exercise 7.7.0.3. Let $(U, \phi) \in \mathcal{A}$ with $\phi = (x^1, \dots, x^n)$. Then $\tilde{\phi} : \tilde{U} \to \phi(U) \times \mathbb{R}$ is a bijection.

7.8 The cotangent Bundle

Definition 7.8.0.1. We define the **cotangent bundle of** M, denoted T^*M , by

$$T^*M = \coprod_{p \in M} T_p^*M$$

7.9 The (r, s)-Tensor Bundle

Definition 7.9.0.1. 1. the cotangent bundle of M, denoted T^*M , by

$$T^*M = \coprod_{p \in M} T_p^*M$$

2. the (r, s)-tensor bundle of M, denoted $T_s^r M$, by

$$T_s^r M = \coprod_{p \in M} T_s^r(T_p M)$$

3. the k-alternating tensor bundle of M, denoted $\Lambda^k(M)$, by

$$\Lambda^k M = \coprod_{p \in M} \Lambda^k(T_p M)$$

7.10. VECTOR FIELDS 79

7.10 Vector Fields

Definition 7.10.0.1. Let $X: M \to TM$. Then X is said to be a **vector field on** M if for each $p \in M$, $X_p \in T_pM$.

For $f \in \mathbb{C}^{\infty}(M)$, we define $Xf : M \to \mathbb{R}$ by

$$(Xf)_p = X_p(f)$$

and X is said to be **smooth** if for each $f \in \mathbb{C}^{\infty}(M)$, Xf is smooth. We denote the set of smooth vector fields on M by $\Gamma^{1}(M)$.

Definition 7.10.0.2. Let $f \in C^{\infty}(M)$ and $X, Y \in \Gamma^{1}(M)$. We define

• $fX \in \Gamma^1(M)$ by

$$(fX)_p = f(p)X_p$$

• $X + Y \in \Gamma^1(M)$ by

$$(X+Y)_p = X_p + Y_p$$

Exercise 7.10.0.3. The set $\Gamma^1(M)$ is a $C^{\infty}(M)$ -module.

Proof. Clear. \Box

Exercise 7.10.0.4. Let $X \in \Gamma^1(M)$ and $(U, \phi) \in \mathcal{A}$ with $\phi = (x^1, \dots, x^n)$. Then

$$X|_{U} = \sum_{i=1}^{n} (Xx^{i}) \frac{\partial}{\partial x^{i}}$$

Proof. Let $p \in M$. Then $X_p \in T_pM$ and $\left\{ \frac{\partial}{\partial x^1} \bigg|_p, \cdots, \frac{\partial}{\partial x^n} \bigg|_p \right\}$ is a basis of T_pM . So there exist $f_1(p), \cdots, f_n(p) \in \mathbb{R}$

 \mathbb{R} such that $X_p = \sum_{i=1}^n f^i(p) \frac{\partial}{\partial x^i} \Big|_p$. Let $j \in \{1, \dots, n\}$. Then,

$$X_p(x^j) = \sum_{i=1}^n f^i(p) \frac{\partial}{\partial x^j} x^i(p)$$
$$= f_j(p)$$

Hence $Xx^j = f_j$ and $X|_U = \sum_{i=1}^n (Xx^i) \frac{\partial}{\partial x^i}$.

Exercise 7.10.0.5. Let $(U, \phi) \in \mathcal{A}$ with $\phi = (x^1, \dots, x^n)$. Then for each $i \in \{1, \dots, n\}$,

$$\frac{\partial}{\partial x^i} \in \Gamma(U)$$

Proof. Let $i \in \{1, \dots, n\}$ and $f \in C^{\infty}(M)$. Define $g: M \to \mathbb{R}$ by $g = \frac{\partial}{\partial x^i} f$. Let $(V, \psi) \in \mathcal{A}$. Then for each $x \in \psi(U \cap V)$,

$$g \circ \psi^{-1}(x) = \frac{\partial}{\partial x^i} \Big|_{\psi^{-1}(x)} f$$

$$= \frac{\partial}{\partial u^i} \Big|_{\phi \circ \psi^{-1}(x)} f \circ \phi^{-1}$$

$$= \frac{\partial}{\partial u^i} [f \circ \phi^{-1}] (\phi \circ \psi^{-1}(x))$$

Since $f \circ \phi^{-1}$ and $\phi \circ \psi^{-1}$ are smooth, $g \circ \psi^{-1}$ is smooth and hence g is smooth. Since $f \in C^{\infty}(M)$ was arbitrary, by definition, $\frac{\partial}{\partial x^i}$ is smooth.

7.11 1-Forms

Definition 7.11.0.1. Let $\omega: M \to T^*M$. Then ω is said to be a 1-form on M if for each $p \in M$, $\omega_p\in T_p^*M.$ For each $X\in\Gamma^1(M),$ we define $\omega(X):M\to\mathbb{R}$ by

$$\omega(X)_p = \omega_p(X_p)$$

and ω is said to be **smooth** if for each $X \in \Gamma^1(M)$, $\omega(X)$ is smooth. The set of smooth 1-forms on M is denoted $\Gamma_1(M)$.

Definition 7.11.0.2. Let $f \in C^{\infty}(M)$ and $\alpha, \beta \in \Gamma^{1}(M)$. We define

• $f\alpha \in \Gamma_1(M)$ by

$$(f\omega)_p = f(p)\omega_p$$

• $\alpha + \beta \in \Gamma^1(M)$ by

$$(\alpha + \beta)_p = \alpha_p + \beta_p$$

Exercise 7.11.0.3. The set $\Gamma_1(M)$ is a $C^{\infty}(M)$ -module.

Proof. Clear.

Exercise 7.11.0.4.

7.12 (r, s)-Tensor Fields

Definition 7.12.0.1. Let $\alpha: M \to T_s^r M$. Then α is said to be an (r,s)-tensor field on M if for each $p \in M$, $\alpha_p \in T_s^r(T_p M)$.

For each $\omega \in \Gamma_1(M)^r$ and $X \in \Gamma^1(M)^s$, we define $\alpha(\omega, X) : M \to \mathbb{R}$ by

$$\alpha(\omega, X)_p = \alpha_p(\omega_p, X_p)$$

and α is said to be **smooth** if for each $\omega \in \Gamma_1(M)^r$ and $X \in \Gamma^1(M)^s$, $\alpha(\omega, X)$ is smooth. The set of smooth (r, s)-tensor fields on M is denoted $T_s^r(M)$.

Definition 7.12.0.2. Let $f \in C^{\infty}(M)$ and $\alpha, \beta \in T_s^r(M)$. We define

• $f\alpha: M \to T_s^r M$ by

$$(f\omega)_p = f(p)\omega_p$$

• $\alpha + \beta : M \to T_s^r M$ by

$$(\alpha + \beta)_p = \alpha_p + \beta_p$$

Exercise 7.12.0.3. Let $f \in C^{\infty}(M)$ and $\alpha, \beta \in T_s^r(M)$. Then

1. $f\alpha \in T_s^r(M)$ by

$$(f\omega)_p = f(p)\omega_p$$

2. $\alpha + \beta \in T_s^r(M)$ by

$$(\alpha + \beta)_p = \alpha_p + \beta_p$$

Proof. Clear.

Exercise 7.12.0.4. The set $T_s^r(M)$ is a $C^{\infty}(M)$ -module.

Proof. Clear.

Definition 7.12.0.5. Let $\alpha_1 \in \Gamma_{s_1}^{r_1}(M)$ and $\alpha_2 \in \Gamma_{s_2}^{r_2}(M)$. We define the **tensor product of** α **with** β , denoted $\alpha \otimes \beta : M \to T_{s_1+s_2}^{r_1+r_2}M$, by

$$(\alpha \otimes \beta)_p = \alpha_p \otimes \beta_p$$

Exercise 7.12.0.6. Let $\alpha_1 \in \Gamma_{s_1}^{r_1}(M)$ and $\alpha_2 \in \Gamma_{s_2}^{r_2}(M)$. Then $\alpha_1 \otimes \alpha_2 \in \Gamma_{s_1+s_2}^{r_1+r_2}(M)$

Proof. Let $\omega_1 \in \Gamma_1(M)^{r_1}$, $\omega_2 \in \Gamma_1(M)^{r_2}$, $X_1 \in \Gamma^1(M)^{s_1}$ and $X_2 \in \Gamma^1(M)^{s_2}$. By definition,

$$\alpha_1 \otimes \alpha_2(\omega_1, \omega_2, X_1, X_2) = \alpha_1(\omega_1, X_1)\alpha_2(\omega_2, X_2)$$

This implies that $\alpha_1 \otimes \alpha_2$ is smooth since α_1 and α_2 are smooth by assumption.

Definition 7.12.0.7. We define the **tensor product**, denoted $\otimes : \Gamma_{s_1}^{r_1}(M) \times \Gamma_{s_2}^{r_2}(M) \to \Gamma_{s_1+s_2}^{r_1+r_2}(M)$ by

$$(\alpha_1, \alpha_2) \mapsto \alpha_1 \otimes \alpha_2$$

Exercise 7.12.0.8. The tensor product $\otimes : \Gamma_{s_1}^{r_1}(M) \times \Gamma_{s_2}^{r_2}(M) \to \Gamma_{s_1+s_2}^{r_1+r_2}(M)$ is associative.

Proof. Clear.

Exercise 7.12.0.9. The tensor product $\otimes : \Gamma_{s_1}^{r_1}(M) \times \Gamma_{s_2}^{r_2}(M) \to \Gamma_{s_1+s_2}^{r_1+r_2}(M)$ is $C^{\infty}(M)$ -bilinear.

Proof. Clear. \Box

Definition 7.12.0.10. Let (N, \mathcal{B}) be a smooth manifold, $F: M \to N$ a smooth map and $\alpha \in \Gamma_k^0(N)$. We define the **pullback of** α **by** F, denoted $F^*\alpha \in \Gamma_k^0(M)$, by

$$(F^*\alpha)_p(v_1,\ldots,v_k) = \alpha_{F(p)}(DF_p(v_1),\ldots,DF_p(v_k))$$

for $p \in M$ and $v_1, \ldots, v_k \in T_pM$

Exercise 7.12.0.11. Let (M, \mathcal{A}) , (N, \mathcal{B}) and (L, \mathcal{C}) be smooth manifolds, $F: M \to N$ and $G: N \to L$ smooth maps, $\alpha \in \Gamma_k^0(N)$, $\beta \in \Gamma_k^0(N)$, $\gamma \in \Gamma_k^0(L)$ and $f \in C^{\infty}(N)$. Then

- 1. $F^*(f\alpha) = (f \circ F)F^*\alpha$
- 2. $F^*(\alpha \otimes \beta) = F^*\alpha \otimes F^*\beta$
- 3. $F^*(\alpha + \beta) = F^*\alpha + F^*\beta$
- 4. $(G \circ F)^* \gamma = F^* (G^* \gamma)$
- 5. $id_N^*\alpha = \alpha$

Proof.

1.

$$[F^*(f\alpha)]_p(v_1, \dots, v_k) = (f\alpha)_{F(p)}(DF_p(v_1), \dots, DF_p(v_k))$$

= $f(F(p))\alpha_{F(p)}(DF_p(v_1), \dots, DF_p(v_k))$
= $(f \circ F)(p)(F^*\alpha)_p(v_1, \dots, v_k)$

So that $F^*(f\alpha) = (f \circ F)F^*\alpha$

2.

 F^*

Definition 7.12.0.12.

Exercise 7.12.0.13.

Proof.

Exercise 7.12.0.14. Let $\alpha \in T_s^r(M)$ and $(U, \phi) \in \mathcal{A}$ with $\phi = (x^1, \dots, x^n)$. Then there exist $(f_J^I)_{I \in \mathcal{I}_r, J \in \mathcal{I}_s} \subset C^{\infty}(M)$ such that

$$\alpha|_{U} = \sum_{(I,J)\in\mathcal{I}_{r}\times\mathcal{I}_{s}} f_{J}^{I} \partial_{x^{\otimes I}} \otimes dx^{\otimes J}$$

Proof. Let $p \in M$. Then $\omega_p \in T^r_s(T_pM)$ and $\left\{\partial_{x^{\otimes I}}|_p \otimes dx_p^{\otimes J}\right\}$ is a basis of $T^r_s(T_pM)$. So there exist $(f_J^I(p))_{I \in \mathcal{I}_r, J \in \mathcal{I}_s} \subset \mathbb{R}$ such that

$$\omega_p = \sum_{(I,J)\in\mathcal{I}_r\times\mathcal{I}_s} f_J^I(p)\partial_{x^{\otimes I}}|_p \otimes dx_p^{\otimes J}$$

Let $(K, L) \in \mathcal{I}_r \times \mathcal{I}_s$. Then

$$\alpha_p(dx_p^K, \partial_{x^L}|_p) = \sum_{(I,J)\in\mathcal{I}_r\times\mathcal{I}_s} f_J^I(p)\partial_{x^{\otimes I}}|_p \otimes dx_p^{\otimes J}(dx_p^K, \partial_{x^L}|_p)$$

$$= \sum_{(I,J)\in\mathcal{I}_r\times\mathcal{I}_s} f_J^I(p)\partial_{x^{\otimes I}}|_p(dx_p^K)dx_p^{\otimes J}(\partial_{x^L}|_p)$$

$$= f_L^K(p)$$

By assumption, the map $p \mapsto \alpha(dx^K, \partial_{x^L})_p$ is smooth, so that $f_L^K \in C^{\infty}(U)$.

Definition 7.12.0.15.

7.13 Differential Forms

Definition 7.13.0.1. We define

$$\Lambda^k(TM) = \coprod_{p \in M} \Lambda^k(T_pM)$$

Definition 7.13.0.2. Let $\omega: M \to \Lambda^k(TM)$. Then ω is said to be a k-form on M if for each $p \in M$, $\omega_p \in \Lambda^k(T_pM)$.

For each $X \in \Gamma^1(M)^k$, we define $\omega(X): M \to \mathbb{R}$ by

$$\omega(X)_p = \omega_p(X_p)$$

and ω is said to be **smooth** if for each $X \in \Gamma^1(M)^k$, $\omega(X)$ is smooth. The set of smooth k-forms on M is denoted $\Omega^k(M)$.

Note 7.13.0.3. Observe that

1.
$$\Omega^k(M) \subset \Gamma^0_k(M)$$

$$2. \ \Omega^0(M) = C^{\infty}(M)$$

Exercise 7.13.0.4. The set $\Omega^k(M)$ is a $C^{\infty}(M)$ -submodule of $\Gamma^0_k(M)$.

Proof. Clear. \Box

Definition 7.13.0.5. Define the exterior product

$$\wedge: \Omega^k(M) \times \Omega^l(M) \to \Omega^{k+l}(M)$$

by

$$(\alpha \wedge \beta)_p = (\alpha)_p \wedge (\beta)_p$$

Note 7.13.0.6. For $f \in \Omega^0(M)$ and $\alpha \in \Omega^k(M)$, we have that $f \wedge \alpha = f\alpha$.

Exercise 7.13.0.7. The exterior product $\wedge : \Omega^k(M) \times \Omega^l(M) \to \Omega^{k+l}(M)$ is well defined.

Proof. Let $\alpha \in \Omega^k(M)$, $\beta \in \Omega^l(M)$, $(x^i)_{i=1}^k \subset \Gamma^1(M)$, $(y^j)_{i=1}^l \subset \Gamma^1(M)$ and $p \in M$. Then

$$\alpha \wedge \beta(X_1, \dots, X_{k+l})_p = (\alpha \wedge \beta)_p(X_1(p), \dots, X_{k+l}(p))$$

$$= \frac{(k+l)!}{k!l!} \operatorname{Alt}(\alpha_p \otimes \beta_p)(X_1(p), \dots, X_{k+l}(p))$$

$$= \frac{1}{k!l!} \sum_{\sigma \in S_{k+l}} \operatorname{sgn}(\sigma) \sigma(\alpha_p \otimes \beta_p)(X_1(p), \dots, X_{k+l}(p))$$

$$= \frac{1}{k!l!} \sum_{\sigma \in S_{k+l}} \operatorname{sgn}(\sigma)(\alpha_p \otimes \beta_p)(X_{\sigma(1)}(p), \dots, X_{\sigma(k+l)}(p))$$

$$= \frac{1}{k!l!} \sum_{\sigma \in S_{k+l}} \operatorname{sgn}(\sigma) \alpha_p(X_{\sigma(1)}(p), \dots, X_{\sigma(k)}(p)) \beta(X_{\sigma(k+1)(p)}, \dots, X_{\sigma(k+l)}(p))$$

$$= \frac{1}{k!l!} \sum_{\sigma \in S_{k+l}} \operatorname{sgn}(\sigma) \alpha_p(X_{\sigma(1)}(p), \dots, X_{\sigma(k)}(p)) \beta(X_{\sigma(k+1)(p)}, \dots, X_{\sigma(k+l)}(p))$$

Exercise 7.13.0.8. The exterior product $\wedge : \Omega^k(M) \times \Omega^l(M) \to \Omega^{k+l}(M)$ is $C^{\infty}(M)$ -bilinear.

Proof.

1. $C^{\infty}(M)$ -linearity in the first argument: Let $\alpha \in \Omega^k(M)$, $\beta, \gamma \in \Omega^l(M)$, $f \in C^{\infty}(M)$ and $p \in M$. Bilinearity of $\Lambda : \Lambda^k(T_pM) \times \Lambda^l(T_pM) \to \Lambda^{k+l}(T_pM)$ implies that

$$\begin{split} [(\beta + f\gamma) \wedge \alpha]_p &= (\beta + f\gamma)_p \wedge \alpha_p \\ &= (\beta_p + f(p)\gamma_p) \wedge \alpha_p \\ &= \beta_p \wedge \alpha_p + f(p)(\gamma_p \wedge \alpha_p) \\ &= [\beta \wedge \alpha + f(\gamma \wedge \alpha)]_p \end{split}$$

So that

$$(\beta + f\gamma) \wedge \alpha = \beta \wedge \alpha + f(\gamma \wedge \alpha)$$

and $\wedge: \Omega^k(M) \times \Omega^l(M) \to \Omega^{k+l}(M)$ is $C^{\infty}(M)$ -linear in the first argument.

2. $C^{\infty}(M)$ -linearity in the second argument: Similar to (1).

Note 7.13.0.9. All of the results from multilinear algebra apply here.

Definition 7.13.0.10. We define the **exterior derivative** $d: \Omega^k(M) \to \Omega^{k+1}(M)$ inductively by

- 1. $d(d\alpha) = 0$ for $\alpha \in \Omega^p(M)$
- 2. df(X) = Xf for $f \in \Omega^0(M)$
- 3. $d(\alpha \wedge \beta) = d\alpha \wedge \beta + (-1)^p \alpha \wedge d\beta$ for $\alpha \in \Omega^p(M)$ and $\beta \in \Omega^q(M)$
- 4. extending linearly

Exercise 7.13.0.11. Let (U, ϕ) be a chart on M with $\phi = (x^1, \dots, x^n)$. Then on U, for each $i, j \in \{1, \dots, n\}$,

$$dx^i \left(\frac{\partial}{\partial x^j}\right) = \delta_{i,j}$$

In particular, for each $p \in U$, $\{dx_p^1, \cdots, dx_p^n\}$ is the dual basis to $\left\{\frac{\partial}{\partial x^1}\bigg|_p, \cdots, \frac{\partial}{\partial x^n}\bigg|_p\right\}$ and $T_p^*M = \mathrm{span}\{dx_p^1, \cdots, dx_p^n\}$.

Proof. Let $p \in U$ and $i, j \in \{1, \dots, n\}$. Then by defintion,

$$\left[dx^{i} \left(\frac{\partial}{\partial x^{j}} \right) \right]_{p} = \left(\frac{\partial}{\partial x^{j}} x^{i} \right)_{p}$$

$$= \frac{\partial}{\partial x^{i}} \Big|_{p} x^{i}$$

$$= \delta_{i,j}$$

Exercise 7.13.0.12. Let $f \in C^{\infty}(M)$ and (U, ϕ) be a chart on M with $\phi = (x^1, \dots, x^n)$. Then

$$df|_{U} = \sum_{i=1}^{n} \frac{\partial f}{\partial x^{i}} dx^{i}$$

Proof. Let $p \in U$. Since $\{dx^1, \dots, dx^n\}$ is a basis for $\Lambda(T_pM)$, for each there exist $a_1(p), \dots, a_n(p) \in \mathbb{R}$ such that $df_p = \sum_{i=1}^n a^i(p) dx_p^i$. Therefore, we have that

$$df_p\left(\frac{\partial}{\partial x^i}\bigg|_p\right) = \sum_{i=1}^n a^i(p) dx_p^i \left(\frac{\partial}{\partial x^i}\bigg|_p\right)$$
$$= a_j(p)$$

By definition, we have that

$$df_p \left(\frac{\partial}{\partial x^i} \Big|_p \right) = \frac{\partial}{\partial x^i} \Big|_p f$$
$$= \frac{\partial f}{\partial x^j} (p)$$

So $a_j(p) = \frac{\partial f}{\partial x^j}(p)$ and

$$df_p = \sum_{i=1}^{n} \frac{\partial f}{\partial x^j}(p) dx_p^i$$

Therefore

$$df|_{U} = \sum_{i=1}^{n} \frac{\partial f}{\partial x^{i}} dx^{i}$$

Exercise 7.13.0.13. Let $f \in \Omega^0(M)$. If f is constant, then df = 0.

Proof. Suppose that f is constant. Let $p \in M$. Choose $(U, \phi) \in \mathcal{A}$ such that $p \in U$. Write $\phi = (x_1, \dots, x_n)$. Then for each $i \in \{1, \dots, n\}$,

$$\left. \frac{\partial}{\partial x^i} \right|_p f = 0$$

This implies that

$$df_p = \sum_{i=1}^n \frac{\partial f}{\partial x^j}(p) dx_p^i$$
$$= 0$$

Exercise 7.13.0.14.

Definition 7.13.0.15. Let $(U, \phi) \in \mathcal{A}$ with $\phi = (x^1, \dots, x^n)$ and $I = (i_1, \dots, i_k) \in \mathcal{I}_k$. We define

$$dx^i = dx_{i_1} \wedge \dots \wedge dx_{i_k} \in \Omega^k(M)$$

and we define

$$\frac{\partial}{\partial x^i} = \left(\frac{\partial}{\partial x^{i_1}}, \cdots, \frac{\partial}{\partial x^{i_k}}\right)$$

Note 7.13.0.16. We have that

1.

$$dx^i \left(\frac{\partial}{\partial x^j} \right) = \delta_{I,J}$$

2. Since $\frac{\partial}{\partial x^i} \in \Gamma(U)^k$, by definition, for each $\omega \in \Omega^k(U)$,

$$\omega\bigg(\frac{\partial}{\partial x^i}\bigg)\in C^\infty(U)$$

Exercise 7.13.0.17. Let $\omega \in \Omega^k(M)$ and (U, ϕ) be a chart on M with $\phi = (x^1, \dots, x^n)$. Then

$$\omega = \sum_{I \in \mathcal{I}_k} \omega \left(\frac{\partial}{\partial x^i} \right) dx^i$$

Proof. Let $p \in U$. Since $\{dx_p^i : I \in \mathcal{I}_k\}$ is a basis for $\Lambda^k(T_pM)$, there exists $(f_I(p))_{I \in \mathcal{I}} \subset \mathbb{R}$ such that $\omega_p = \sum_{I \in \mathcal{I}_k} f_I(p) dx_p^i$. So for each $J \in \mathcal{I}_k$,

$$\omega\left(\frac{\partial}{\partial x^{j}}\right) = \sum_{I \in \mathcal{I}_{k}} f_{I} dx^{i} \left(\frac{\partial}{\partial x^{j}}\right)$$
$$= f_{J}$$

Exercise 7.13.0.18. Let $\omega \in \Omega^k(M)$ and (U, ϕ) be a chart on M with $\phi = (x^1, \dots, x^n)$. If $\omega = \sum_{I \in \mathcal{I}_k} f_I dx^i$, then

$$d\omega = \sum_{I \in \mathcal{I}_k} \sum_{i=1}^n \frac{\partial f_I}{\partial x^i} dx^i \wedge dx^i$$

,

Proof. First we note that

$$d(f_I dx^i) = df_I \wedge dx^i + (-1)^0 f d(dx^i)$$

$$= df_I \wedge dx^i$$

$$= \left(\sum_{i=1}^n \frac{\partial f_I}{\partial x^i} dx^i\right) \wedge dx^i$$

$$= \sum_{i=1}^n \frac{\partial f_I}{\partial x^i} dx^i \wedge dx^i$$

Then we extend linearly.

Definition 7.13.0.19. Let (N, \mathcal{B}) be a smooth manifold and $F: M \to N$ be a diffeomorphism. Define the **pullback of** F, denoted $F^*: \Omega^k(N) \to \Omega^k(M)$ by

$$(F^*\omega)_p(v_1,\cdots,v_k)=\omega_{F(p)}(DF_p(v_1),\cdots,DF_p(v_k))$$

for $\omega \in \Omega^k(N)$, $p \in M$ and $v_1, \dots, v_k \in T_pM$

Chapter 8

Connections

8.1 Koszul Connections

Definition 8.1.0.1. Let $(E, M, \pi) \in \text{Obj}(\mathbf{VecBun}^{\infty})$ and $\nabla : \mathfrak{X}(M) \times \Gamma(E) \to \Gamma(E)$. Then ∇ is said to be a Koszul connection on E in the first representation if

- 1. for each $\sigma \in \Gamma(E)$, $\nabla(\cdot, \sigma)$ is $C^{\infty}(M)$ -linear
- 2. for each $X \in \mathfrak{X}(M)$, $\nabla(X, \cdot)$ is \mathbb{R} -linear
- 3. for each $X \in \mathfrak{X}(M)$, $\sigma \in \Gamma(E)$ and $f \in C^{\infty}(M)$,

$$\nabla(X, f\sigma) = f \nabla(X, \sigma) + X(f)\sigma$$

Definition 8.1.0.2. Let $(E, M, \pi) \in \text{Obj}(\mathbf{VecBun}^{\infty})$ be a smooth vector bundle and $\nabla : \Gamma(E) \to T^*M \otimes \Gamma(E)$. Then ∇ is said to be a **Koszul connection on** E **in the second representation** if

- 1. ∇ is \mathbb{R} -linear
- 2. for each $\sigma \in \Gamma(E)$ and $f \in C^{\infty}(M)$,

$$\nabla(f\sigma) = f \,\nabla\,\sigma + df \otimes \sigma$$

Note 8.1.0.3. When the context is clear, we will write $\nabla_X Y$ in place of $\nabla(X, Y)$ and we will refer to ∇ as a connection.

Exercise 8.1.0.4. Define $\phi: \Gamma(E)^{\mathfrak{X}(M) \times \Gamma(E)} \to [T^*M \otimes \Gamma(E)]^{\Gamma(E)}$ by

$$\phi(\nabla)(X) = \nabla_X \, \sigma$$

Then ∇ is a Koszul connection on E in the first representation iff $\phi(\nabla)$ Koszul connection on E in the second representation.

Proof.

Exercise 8.1.0.5. Let $(E, M, \pi) \in \text{Obj}(\mathbf{VecBun}^{\infty})$, ∇ a connection on $E, X \in \mathfrak{X}(M)$ and $Y \in \Gamma(E)$. If X = 0 or Y = 0, then $\nabla_X Y = 0$.

Proof.

• If X = 0, then

$$\nabla_X Y = \nabla_{0X} Y$$
$$= 0 \nabla_X Y$$
$$= 0$$

• Similarly, if Y = 0, then $\nabla_X Y = 0$.

Exercise 8.1.0.6. Let (E, M, π) be a smooth vector bundle, ∇ a connection on $E, X \in \mathfrak{X}(M), Y \in \Gamma(E)$ and $p \in M$. If $X \sim_p 0$ or $Y \sim_p 0$, then $[\nabla_X Y]_p = 0$.

Proof.

• Suppose that $X \sim_p 0$. Then there exists $U \subset M$ such that U is open and $X|_U = 0$. Choose $\phi \in C^{\infty}(M)$ such that supp $\phi \subset U$ and $\phi \sim_p 1$. Then $\phi X = 0$. The previous exercise implies that $\nabla_{\phi X} Y = 0$. Therefore

$$\nabla_X Y = \nabla_{\phi X + (1-\phi)X} Y$$

$$= \nabla_{\phi X} Y + \nabla_{(1-\phi)X} Y$$

$$= 0 + (1-\phi) \nabla_X Y$$

$$= (1-\phi) \nabla_X Y$$

Hence

$$[\nabla_X Y]_p = [(1 - \phi) \nabla_X Y]_p$$
$$= (1 - \phi(p))[\nabla_X Y]_p$$
$$= 0$$

• Suppose that $Y \sim_p 0$. Then there exists $U \subset M$ such that U is open and $Y|_U = 0$. Choose $\phi \in C^{\infty}(M)$ such that supp $\phi \subset U$ and $\phi \sim_p = 1$. Then $\phi Y = 0$. The previous exercise implies that $\nabla_X \phi Y = 0$. Since $\phi \sim_p 1$, we have that $1 - \phi \sim_p 0$. Thus $X(1 - \phi) \sim_p 0$ and

$$\nabla_X Y = \nabla_X [\phi Y + (1 - \phi)Y]$$

$$= \nabla_X [\phi Y] + \nabla_X [(1 - \phi)Y]$$

$$= \nabla_X [(1 - \phi)Y]$$

$$= (1 - \phi) \nabla_X Y + [X(1 - \phi)] \nabla_X Y$$

Hence

$$[\nabla_X Y]_p = (1 - \phi(p))[\nabla_X Y]_p + [X(1 - \phi)](p)[\nabla_X Y]_p$$

= 0

Exercise 8.1.0.7. Let (E, M, π) be a smooth vector bundle and ∇ a connection on E. Then for each $X_1, X_2 \in \mathfrak{X}(M)$ and $Y_1, Y_2 \in \Gamma(E)$, $X_1 \sim_p X_2$ and $Y_1 \sim_p Y_2$ implies that $[\nabla_{X_1} Y_1]_p = [\nabla_{X_2} Y_2]_p$.

Proof. Let $X_1, X_2 \in \mathfrak{X}(M)$ and $Y_1, Y_2 \in \Gamma(E)$. Suppose that $X_1 \sim_p X_2$ and $Y_1 \sim_p Y_2$. Define $X \in \mathfrak{X}(M)$ and $Y \in \Gamma(E)$ by $X = X_2 - X_1$ and $Y = Y_2 - Y_1$. Then $X \sim_p 0$ and $Y \sim_p 0$. The previous exercise implies

that $[\nabla_X Y_1]_p = 0$ and $[\nabla_{X_2} Y]_p = 0$. Therefore

$$\begin{split} [\nabla_{X_1} \, Y_1]_p &= [\nabla_{X_1} \, Y_1]_p + [\nabla_X \, Y_1]_p \\ &= [\nabla_{X_1} \, Y_1 + \nabla_X \, Y_1]_p \\ &= [\nabla_{X_1 + X} \, Y_1]_p \\ &= [\nabla_{X_2} \, Y_1]_p \\ &= [\nabla_{X_2} \, Y_1]_p + [\nabla_{X_2} \, Y]_p \\ &= [\nabla_{X_2} \, Y_1 + \nabla_{X_2} \, Y]_p \\ &= [\nabla_{X_2} \, (Y_1 + Y)]_p \\ &= [\nabla_{X_2} \, Y_2]_p \end{split}$$

Exercise 8.1.0.8. Let (E, M, π) be a smooth vector bundle, ∇ a connection on E and $U \subset M$. If U is open, then there exists a unique connection $\nabla^U : \mathfrak{X}(U) \times \Gamma(E|_U) \to \Gamma(E|_U)$ such that for each $X \in \mathfrak{X}(M)$ and $Y \in \Gamma(E)$,

$$\nabla^{U}_{X|_{U}} Y|_{U} = (\nabla_{X} Y)|_{U}$$

Chapter 9

Semi-Riemannian Geometry

Definition 9.0.0.1. Let M be a manifold and $g \in \Gamma(\Sigma^2 M)$. Then g is said to be nondegenerate if for each $p \in M$, g_p is nondegenerate.

Definition 9.0.0.2. Let M be a manifold and $g \in \Gamma(\Sigma^2 M)$. Then g is said to be a **metric tensor field** on M if

- 1. g is nondegenerate
- 2. g has constant index

In this case (M, g) is said to be a **semi-Riemannian manifold**

Definition 9.0.0.3. Define Interval FINISH!!!

Definition 9.0.0.4. Let $(E, M, \pi) \in \text{Obj}(\mathbf{Bun}^{\infty})$, $I \subset \mathbb{R}$ an interval, $\alpha \in \text{Hom}_{\mathbf{Man}^{\infty}}(I, M)$ and $\gamma \in \text{Hom}_{\mathbf{Man}^{\infty}}(I, E)$. Then γ is said to be a **section of** E **over** α if $\pi \circ \gamma = \alpha$. We denote the set of sections of E over α by $\Gamma(E, \alpha)$.

Definition 9.0.0.5. Let $(E, M, \pi) \in \text{Obj}(\mathbf{Bun}^{\infty})$, $I \subset \mathbb{R}$ an interval, $\alpha \in \text{Hom}_{\mathbf{Man}^{\infty}}(I, M)$ and $\gamma \in \Gamma(E, \alpha)$. Then γ is said to be said to be **extendible** if there exists $U \in \mathcal{N}_{\alpha(I)}$ and $\tilde{\gamma} \in \Gamma(E|_{U})$ such that U is open and $\tilde{\gamma} \circ \alpha = \gamma$.

Exercise 9.0.0.6. figure 8 not extendible FINISH!!!

Exercise 9.0.0.7. Let $(E, M, \pi) \in \text{Obj}(\mathbf{VecBun}^{\infty})$, ∇ a connection on $E, I \subset \mathbb{R}$ an interval and $\alpha \in \text{Hom}_{\mathbf{Man}^{\infty}}(I, M)$. There exists a unique $D_{\alpha} : \Gamma(E, \alpha) \to \Gamma(E, \alpha)$ such that

1. for each $\lambda \in \mathbb{R}$ and $\gamma, \sigma \in \Gamma(E, \alpha)$,

$$D_{\alpha}(\gamma + \lambda \sigma) = D_{\alpha}\gamma + \lambda D_{\alpha}\sigma$$

2. for each $f \in C^{\infty}(I)$ and $\gamma \in \Gamma(E, \alpha)$,

$$D_{\alpha}(f\gamma) = f'\gamma + fD_{\alpha}\gamma$$

3. for each $\gamma \in \Gamma(E)$, if $\tilde{\gamma}$ extends γ , then

$$D_{\alpha}\gamma = \nabla_{\alpha'}\,\gamma$$

Proof.

Chapter 10

Riemannian Geometry

Definition 10.0.0.1. Let M be a smooth manifold and $g \in T_2^0(M)$ a metric tensor on M. We define $\hat{g} \in T_0^2(M)$ by $\hat{g}(\omega, \eta) = g(\phi_g^{-1}(\omega), \phi_g^{-1}(\eta))$.

Exercise 10.0.0.2. content...

Exercise 10.0.0.3. Let (M,g) be a semi-Riemannian manifold and $(U,\phi) \in \mathcal{A}$. Then the induced metric $\langle \rangle_{T^*M\otimes TM}$ on $T^*M\otimes TM$ is given by

$$\left\langle dx^i \otimes \frac{\partial}{\partial x^k}, dx^j \otimes \frac{\partial}{\partial x^l} \right\rangle_{T^*M \otimes TM} = g^{i,j} g_{kl}$$

Proof. We have that

$$\left\langle dx^{i} \otimes \frac{\partial}{\partial x^{k}}, dx^{j} \otimes \frac{\partial}{\partial x^{l}} \right\rangle_{T^{*}M \otimes TM} = \left\langle dx^{i}, dx^{j} \right\rangle_{T^{*}M} \left\langle \frac{\partial}{\partial x^{k}}, \frac{\partial}{\partial x^{l}} \right\rangle_{TM}$$
$$= g^{i,j} g_{k,l}$$

Exercise 10.0.0.4. Let (M,g) be an *n*-dimensional Riemannian manifold.

1. There exists $\lambda \in \Omega^n(M)$ such that for each orthonormal frame e_1, \ldots, e_n ,

$$\lambda(e_1,\ldots,e_n)=1$$

Hint: Choose a frame z_1, \ldots, z_n on M with corresponding dual frame ζ^1, \ldots, ζ^n . Define

$$\lambda = \det[g(z_i, z_j)]^{1/2} \zeta^1 \wedge \dots \wedge \zeta^n$$

2. Let $N \in \mathfrak{X}(M)$ be the outward pointing normal to ∂M and $X \in \mathfrak{X}(M)$. Then

$$\int_{M} \operatorname{div} X \lambda = \int_{\partial M} g(X, N) \tilde{\lambda}$$

3. For each $u \in \mathbb{C}^{\infty}(M)$ and $X \in \mathfrak{X}(M)$, we have that

$$\operatorname{div}(uX) = u\operatorname{div}(X) + du(X)$$

and therefore

$$\int_{M} du(X)\lambda = \int_{\partial M} ug(X, N)\tilde{\lambda} - \int_{M} u \operatorname{div}(X)\lambda$$

Proof.

1. Let z_1, \ldots, z_n be a frame on M and ζ^1, \ldots, ζ^n with corresponding dual frame ζ^1, \ldots, ζ^n . Define

$$\lambda = \det[g(z_i, z_j)]^{1/2} \zeta^1 \wedge \dots \wedge \zeta^n$$

Let e_1, \ldots, e_n , be an orthonormal frame on M with corresponding dual coframe $\epsilon^1, \ldots, \epsilon^n$. Let $i, j \in \{1, \ldots, n\}$. Then there exist $(a_{k,i}) \subset \mathbb{R}$ such that $\zeta^i = \sum_{k=1}^n a_{k,i} \epsilon^k$. Then

$$\hat{g}(\epsilon^j, \zeta^i) = \sum_{k=1}^n a_{k,i} \hat{g}(\epsilon^j, \epsilon^k)$$

$$= \sum_{k=1}^n a_{k,i} g(\phi_g^{-1}(\epsilon^j), \phi_g^{-1}(\epsilon^k))$$

$$= \sum_{k=1}^n a_{k,i} g(e_j, e_k)$$

$$= \sum_{k=1}^n a_{k,i} \delta_{j,k}$$

$$= a_{j,i}$$

which implies that

$$\delta_{i,j} = \zeta^{i}(z_{j})$$

$$= \sum_{k=1}^{n} a_{k,i} \epsilon^{k}(z_{j})$$

$$= \sum_{k=1}^{n} a_{k,i} g(e_{k}, z_{j})$$

$$= \sum_{k=1}^{n} \hat{g}(\epsilon^{k}, \zeta^{i}) g(e_{k}, z_{j})$$

Define $U, V \in \mathbb{R}^{n \times n}$ by $U_{i,k} = \hat{g}(\zeta^i, \epsilon^k)$ and $V_{k,j} = g(e_k, z_j)$. Then from above, we have that UV = I. Since $U, V \in \mathbb{R}^{n \times n}$, VU = I. Hence $U = V^{-1}$. Since

$$\zeta^{i}(e_{j}) = \sum_{k=1}^{n} a_{k,i} \epsilon^{k}(e_{j})$$

$$= \sum_{k=1}^{n} a_{k,i} \delta_{k,j}$$

$$= a_{j,i}$$

$$= \hat{g}(\epsilon^{j}, \zeta^{i})$$

$$= U_{i,j}$$

and

$$g(z_{i}, z_{j}) = \left(\sum_{k=1}^{n} g(e_{k}, z_{i})e_{k}, \sum_{l=1}^{n} g(e_{l}, z_{j})e_{l}\right)$$

$$= \sum_{k=1}^{n} \sum_{l=1}^{n} g(e_{k}, z_{i})g(e_{l}, z_{j})g(e_{k}, e_{l})$$

$$= \sum_{k=1}^{n} \sum_{l=1}^{n} g(e_{k}, z_{i})g(e_{l}, z_{j})\delta_{k,l}$$

$$= \sum_{k=1}^{n} g(e_{k}, z_{i})g(e_{k}, z_{j})$$

$$= (V^{*}V)_{i,j}$$

we have that

$$\lambda(e_1, \dots, e_n) = \det[g(z_i, z_j)]^{1/2} \zeta^1 \wedge \dots \wedge \zeta^n(e_1, \dots, e_n)$$

$$= \det[g(z_i, z_j)]^{1/2} \det[\zeta^i(e_j)]$$

$$= \det(V^*V)^{1/2} \det U$$

$$= \det V(\det V)^{-1}$$

$$= 1$$

2. Choose an orthonormal frame $e_1, \ldots, e_{n-1} \in \mathfrak{X}(\partial M)$ with dual coframe $\epsilon^1, \ldots, \epsilon^{n-1}$. Define $\nu \in \Omega^1(M)$ to be the dual covector to N. We note that N, e_1, \ldots, e_{n-1} is an orthonormal frame on $\mathfrak{X}(M)$. Let $X_1, \ldots, X_{n-1} \in \mathfrak{X}(\partial M)$. Since for each $j \in \{1, \ldots, n-1\}$, $X_j \in \mathfrak{X}(\partial M)$ and for each $p \in \partial M$, $N_p \in (T_p \partial M)^{\perp}$, we have that for each $j \in \{1, \ldots, n-1\}$, $g(X_j, N) = 0$. This implies that

$$\iota^* \iota_X \lambda(X_1, \dots, X_{n-1}) = \lambda(X, X_1, \dots, X_{n-1}) \\
= \nu \wedge \epsilon^1 \wedge \dots \wedge \epsilon^{n-1}(X, X_1, \dots, X_{n-1}) \\
= \det \begin{pmatrix} \nu(X) & \nu(X_1) & \dots & \nu(X_{n-1}) \\ \epsilon^1(X) & \epsilon^1(X_1) & \dots & \epsilon^1(X_{n-1}) \\ \vdots & & & \vdots \\ \epsilon^{n-1}(X) & \epsilon^{n-1}(X_1) & \dots & \epsilon^{n-1}(X_{n-1}) \end{pmatrix} \\
= \det \begin{pmatrix} g(X, N) & g(X_1, N) & \dots & g(X_{n-1}, N) \\ \epsilon^1(X) & \epsilon^1(X_1) & \dots & \epsilon^1(X_{n-1}) \\ \vdots & & & \vdots \\ \epsilon^{n-1}(X) & \epsilon^{n-1}(X_1) & \dots & \epsilon^{n-1}(X_{n-1}) \end{pmatrix} \\
= g(X, N) \det(\epsilon^i(X_j)) \\
= g(X, N) \tilde{\lambda}(X_1, \dots, X_n) \\
= g(X, N) \tilde{\lambda}(X_1, \dots, X_n)$$

Therefore $\iota^*\iota_X\lambda = g(X,N)\tilde{\lambda}$ and

$$\int_{M} \operatorname{div} X \lambda = \int_{M} d(\iota_{X} \lambda)$$

$$= \int_{\partial M} \iota^{*}(\iota_{X} \lambda)$$

$$= \int_{\partial M} g(X, N) \tilde{\lambda}$$

3. We note that

$$0 = \iota_X(du \wedge \lambda)$$

= $\iota_X(du) \wedge \lambda - du \wedge (\iota_X \lambda)$
= $du(X)\lambda - du \wedge (\iota_X \lambda)$

which implies that

$$\operatorname{div}(uX)\lambda = d(\iota_{uX}\lambda)$$

$$= d(\iota_{uX}\lambda)$$

$$= du \wedge (\iota_{x}\lambda) + ud(\iota_{x}\lambda)$$

$$= du(X)\lambda + u\operatorname{div}(X)\lambda$$

$$= [du(X) + u\operatorname{div}(X)]\lambda$$

This implies that $\operatorname{div}(uX) = du(X) + u\operatorname{div}(X)$. From before, we have that

$$\begin{split} \int_{M} du(X)\lambda &= \int_{M} \operatorname{div}(uX)\lambda - \int_{M} u \operatorname{div}(X)\lambda \\ &= \int_{\partial M} g(uX,N)\tilde{\lambda} - \int_{M} u \operatorname{div}(X)\lambda \\ &= \int_{\partial M} u g(X,N)\tilde{\lambda} - \int_{M} u \operatorname{div}(X)\lambda \end{split}$$

Exercise 10.0.0.5.

$$\operatorname{div}(X) = \sum_{j=1}^{n} (\nabla_{\partial_j} X)^j$$

Proof. We have that

$$\begin{split} \nabla_{\partial_i}(X) &= \sum_{j=1}^n \nabla_{\partial_i}(X^j \partial_j) \\ &= \sum_{j=1}^n \left[X^j \nabla_{\partial_i} \, \partial_j + \partial_i(X^j) \partial_j \right] \\ &= \sum_{j=1}^n \left[X^j (\sum_{k=1}^n \Gamma^k_{i,j} \partial_k) + \partial_i(X^j) \partial_j \right] \\ &= \sum_{j=1}^n \left[X^j \left(\sum_{k=1}^n \Gamma^k_{i,j} \partial_k \right) + \partial_i(X^j) \partial_j \right] \\ &= \sum_{j=1}^n X^j \left(\sum_{k=1}^n \Gamma^k_{i,j} \partial_k \right) + \sum_{j=1}^n \partial_i(X^j) \partial_j \\ &= \sum_{k=1}^n \left(\sum_{j=1}^n X^j \Gamma^k_{i,j} \right) \partial_k + \sum_{k=1}^n \partial_i(X^k) \partial_k \\ &= \sum_{k=1}^n \left[\left(\sum_{i=1}^n X^j \Gamma^k_{i,j} \right) + \partial_i(X^k) \right] \partial_k \end{split}$$

so that $(\nabla_{\partial_i}(X))^i = \left(\sum_{j=1}^n X^j \Gamma_{i,j}^i\right) + \partial_i(X^i)$. We note that

$$\operatorname{div}(X) = \sum_{i=1}^{n} \operatorname{div}(X^{i} \partial_{i})$$

$$= \sum_{i=1}^{n} [X^{i} \operatorname{div}(\partial_{i}) + dx^{i}(\partial_{i})]$$

$$= \sum_{i=1}^{n} [X^{i} \operatorname{div}(\partial_{i}) + 1]$$

Since $\lambda = [\det g(\partial_i, \partial_j)]^{1/2} dx^1 \wedge \cdots \wedge dx^n = (\det g)^{1/2} dx$, we have that

$$\begin{split} d(\iota_{\partial_i}\lambda) &= d((\det g)^{1/2}\iota_{\partial_i}dx) \\ &= d[(\det g)^{1/2}]\iota_{\partial_i}dx + (\det g)^{1/2}d(\iota_{\partial_i}dx) \\ &= d[(\det(g)^{1/2}]\sum_{k=1}^n (-1)^{k-1}dx^1 \wedge \dots \wedge \widehat{dx^k} \wedge \dots dx^n + (\det g)^{1/2}\sum_{k=1}^n (-1)^{k-1}dx^1 \wedge \dots \wedge \widehat{dx^k} \wedge \dots dx^n) \end{split}$$

FINISH!!!

Exercise 10.0.0.6. Let (M,g) be a Riemannian manifold.

1. For each $u, v \in C^{\infty}(M)$. Then

(a)
$$\int_M u \Delta v \lambda + \int_M g(\nabla u, \nabla v) \lambda = \int_{\partial M} u N(v) \tilde{\lambda}$$
 (b)

(b)
$$\int_{M} [u\Delta v - v\Delta u]\lambda = \int_{\partial M} [uN(v) - vN(u)]\tilde{\lambda}$$

- 2. (a) If $\partial M \neq \emptyset$, then for each $u, v \in C^{\infty(M)}$, u and v are harmonic and $u|_{\partial M} = v|_{\partial M}$ implies that u = v.
 - (b) If $\partial M = \emptyset$, then for each $u \in C^{\infty}(M)$, u is harmonic implies that u is constant.

Proof.

1. Let $u, v \in C^{\infty}(M)$. Then

(a)

$$\begin{split} \int_{M} u \Delta v \lambda &= \int_{M} u \mathrm{div}(\nabla \, v) \lambda \\ &= \int_{\partial M} u g(\nabla \, v, N) \tilde{\lambda} - \int_{M} du(\nabla \, v) \lambda \\ &= \int_{\partial M} u dv(N) \tilde{\lambda} - \int_{M} g(\nabla \, u, \nabla \, v) \lambda \\ &= \int_{\partial M} u N(v) \tilde{\lambda} - \int_{M} g(\nabla \, u, \nabla \, v) \lambda \end{split}$$

(b) From above, we have that

$$\begin{split} \int_{M} [u \Delta v - v \Delta u] \lambda &= \int_{M} u \Delta v \lambda - \int_{M} v \Delta u \lambda \\ &= \int_{\partial M} u N(v) \tilde{\lambda} - \int_{M} g(\nabla u, \nabla v) \lambda - \left(\int_{\partial M} v N(u) \tilde{\lambda} - \int_{M} g(\nabla v, \nabla u) \lambda \right) \\ &= \int_{\partial M} u N(v) \tilde{\lambda} - \int_{\partial M} v N(u) \tilde{\lambda} \\ &= \int_{\partial M} [u N(v) - v N(u)] \tilde{\lambda} \end{split}$$

2. (a) Suppose that $\partial M \neq \emptyset$. Let $u, v \in C^{\infty(M)}$. Suppose that u and v are harmonic and $u|_{\partial M} = v|_{\partial M}$. Then u - v is harmonic and

$$\begin{split} \int_{M} \|\nabla(u-v)\|_{g}^{2} \lambda &= \int_{M} g(\nabla(u-v), \nabla(u-v)) \lambda \\ &= 0 + \int_{M} g(\nabla(u-v), \nabla(u-v)) \lambda \\ &= \int_{M} (u-v) \Delta(u-v) \lambda + \int_{M} g(\nabla(u-v), \nabla(u-v)) \lambda \\ &= \int_{\partial M} (u-v) N(u-v) \tilde{\lambda} \\ &= 0 \end{split}$$

Thus $\nabla(u-v)=0$ and u-v is constant. Since $u|_{\partial M}=v|_{\partial M}$, we have that u-v=0 and thus u=v

(b) Suppose that $\partial M = \emptyset$. Let $u \in C^{\infty}(M)$. Suppose that u is harmonic. Then

$$\int_{M} \|\nabla u\|_{g}^{2} \lambda = \int_{M} g(\nabla u, \nabla u) \lambda$$

$$= 0 + \int_{M} g(\nabla u, \nabla u) \lambda$$

$$= \int_{M} u \Delta u \lambda + \int_{M} g(\nabla u, \nabla u) \lambda$$

$$= \int_{\partial M} (u - v) g(\nabla (u - v), N) \tilde{\lambda}$$

$$= 0$$

Therefore $\nabla u - 0$ and u is constant.

Chapter 11

Symplectic Geometry

11.1 Symplectic Manifolds

Definition 11.1.0.1. Let $M \in \text{Obj}(\mathbf{Man}^{\infty})$ and $\omega \in \Omega^2(M)$. Then ω is said to be **symplectic** if

- 1. ω is nondegenerate
- 2. ω is closed

Chapter 12

Extra

Definition 12.0.0.1. When working in \mathbb{R}^n , we introduce the formal objects dx^1, dx_2, \dots, dx^n . Let $I = (i_1, i_2, \dots, i_k) \in \mathcal{I}_{k,n}$ and $\phi : \mathbb{R}^k \to \mathbb{R}^n$. Write $\phi = (\phi_1, \phi_2, \dots, \phi_n)$. We formally define $dx^i = dx_{i_1} \wedge dx_{i_2} \wedge \dots \wedge dx_{i_k}$ and $\phi_I = (\phi_{i_1}, \phi_{i_2}, \dots, \phi_{i_k})$.

Definition 12.0.0.2. Let $k \in \{0, 1, \dots, n\}$. We define a $C^{\infty}(\mathbb{R}^n)$ -module of dimension $\binom{n}{k}$, denoted $\Gamma^k(\mathbb{R}^n)$ to be

$$\Phi_k(\mathbb{R}^n) = \begin{cases} C^{\infty}(\mathbb{R}^n) & k = 0\\ \operatorname{span}\{dx^i : I \in \mathcal{I}_{k,n}\} & k \ge 1 \end{cases}$$

For each $\omega \in \Phi_k(\mathbb{R}^n)$ and $\chi \in \Gamma^l(\mathbb{R}^n)$, we may form their **exterior product**, denoted by $\omega \wedge \chi \in \Gamma^{k+l}(\mathbb{R}^n)$. Thus the exterior product is a map $\wedge : \Phi_k(\mathbb{R}^n) \times \Gamma^l(\mathbb{R}^n) \to \Gamma^{k+l}(\mathbb{R}^n)$. The exterior product is characterized by the following properties:

- 1. the exterior product is bilinear
- 2. for each $\omega \in \Phi_k(\mathbb{R}^n)$ and $\chi \in \Gamma^l(\mathbb{R}^n)$, $\omega \wedge \chi = -\chi \wedge \omega$
- 3. for each $\omega \in \Phi_k(\mathbb{R}^n)$, $\omega \wedge \omega = 0$
- 4. for each $f \in C^{\infty}(\mathbb{R}^n)$ and $\omega \in \Phi_k(\mathbb{R}^n)$, $f \wedge \omega = f\omega$

We call $\Phi_k(\mathbb{R}^n)$ the differential k-forms on \mathbb{R}^n . Let ω be a k-form on \mathbb{R}^n . If $k \geq 1$, then for each $I \in \mathcal{I}_{k,n}$, there exists $f_I \in C^{\infty}(\mathbb{R}^n)$ such that $\omega = \sum_{I \in \mathcal{I}_{k,n}} f_I dx^i$

Note 12.0.0.3. The terms dx^1, dx_2, \dots, dx^n are are a sort of place holder for the coordinates of a point $x = (x_1, x_2, \dots, x_n) \in \mathbb{R}^n$. When we work with functions $\phi : \mathbb{R}^k \to \mathbb{R}^n$, we will have different coordinates and to avoid confusion, we will write $\{du^1, du_2, \dots, du_k\}$ when referencing the coordinates on \mathbb{R}^k and $\{dx^1, dx_2, \dots, dx^n\}$ when referencing the coordinates on \mathbb{R}^n .

Exercise 12.0.0.4. Let $B_{n\times n}=(b_{i,j})\in [C^{\infty}(M)]^{n\times n}$ be an $n\times n$ matrix. Then

$$\bigwedge_{i=1}^{n} \left(\sum_{j=1}^{n} b_{i,j} dx^{j} \right) = (\det B) dx^{1} \wedge dx_{2} \wedge \dots \wedge dx^{n}$$

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Proof. Bilinearity of the exterior product implies that

$$\bigwedge_{i=1}^{n} \left(\sum_{j=1}^{n} b_{i,j} dx^{j} \right) = \left(\sum_{j=1}^{n} b_{1,j} dx^{j} \right) \wedge \left(\sum_{j=1}^{n} b_{2,j} dx^{j} \right) \wedge \dots \wedge \left(\sum_{j=1}^{n} b_{n,j} dx^{j} \right)$$

$$= \sum_{j_{1}, \dots, j_{n}=1}^{n} \left(\prod_{i=1}^{n} b_{i,j_{i}} \right) dx_{j_{1}} \wedge dx_{j_{2}} \wedge \dots \wedge dx_{j_{n}}$$

$$= \sum_{j_{1} \neq \dots \neq j_{n}} \left(\prod_{i=1}^{n} b_{i,j_{i}} \right) dx_{j_{1}} \wedge dx_{j_{2}} \wedge \dots \wedge dx_{j_{n}}$$

$$= \left[\sum_{\sigma \in S_{n}} \operatorname{sgn}(\sigma) \left(\prod_{i=1}^{n} b_{i,\sigma(i)} \right) \right] dx_{1} \wedge dx_{2} \wedge \dots \wedge dx_{n}$$

$$= (\det B) dx_{1} \wedge dx_{2} \wedge \dots \wedge dx_{n}$$

Definition 12.0.0.5. Let $f: \mathbb{R}^n \to \mathbb{R}$ be a 0-form on \mathbb{R}^n . We define a 1-form, denoted df, on \mathbb{R}^n by

$$df = \sum_{i=1}^{n} \frac{\partial f}{\partial x^i} dx^i$$

Let $\omega = \sum_{I \in \mathcal{I}_{k,n}} f_I dx^i$ be a k-form on \mathbb{R}^n . We can define a differential k+1-form, denoted $d\omega$, on \mathbb{R}^n by

$$d\omega = \sum_{I \in \mathcal{I}_{k,n}} df_I \wedge dx^i$$

Exercise 12.0.0.6. On \mathbb{R}^3 , put

1. $\omega_0 = f_0$

2. $\omega_1 = f_1 dx^1 + f_2 dx_2 + f_2 dx_3$

3. $\omega_2 = f_1 dx_2 \wedge dx_3 - f_2 dx^1 \wedge dx_3 + f_3 dx^1 \wedge dx_2$

Show that

1. $d\omega_0 = \frac{\partial f_0}{\partial x^1} dx^1 + \frac{\partial f_0}{\partial x^2} dx_2 + \frac{\partial f_0}{\partial x^3} dx_3$

2.
$$d\omega_1 = \left(\frac{\partial f_3}{\partial x^2} - \frac{\partial f_2}{\partial x^3}\right) dx_2 \wedge dx_3 + \left(\frac{\partial f_3}{\partial x^1} - \frac{\partial f_1}{\partial x^3}\right) dx^1 \wedge dx_3 + \left(\frac{\partial f_2}{\partial x^1} - \frac{\partial f_1}{\partial x^2}\right) dx^1 \wedge dx_2$$

3.
$$d\omega_2 = \left(\frac{\partial f_1}{\partial x^1} + \frac{\partial f_2}{\partial x^2} + \frac{\partial f_3}{\partial x^3}\right) dx^1 \wedge dx_2 \wedge dx_3$$

Proof. Straightforward.

Exercise 12.0.0.7. Let $I \in \mathcal{I}_{k,n}$. Then there is a unique $I_* \in \mathcal{I}_{n-k,n}$ such that $dx^i \wedge dx_{I_*} = dx^1 \wedge dx_2 \wedge \cdots \wedge dx^n$.

Definition 12.0.0.8. We define a linear map $*: \Phi_k(\mathbb{R}^n) \to \Gamma^{n-k}(\mathbb{R}^n)$ called the **Hodge *-operator** by

$$*\sum_{I\in\mathcal{I}_{k,n}} f_I dx^i = \sum_{I\in\mathcal{I}_{k,n}} f_I dx_{I_*}$$

Definition 12.0.0.9. Let $\phi : \mathbb{R}^k \to \mathbb{R}^n$ be smooth. Write $\phi = (\phi_1, \phi_2, \dots, \phi_n)$. We define $\phi^* : \Phi_k(\mathbb{R}^n) \to \Phi_k(\mathbb{R}^k)$ via the following properties:

- 1. for each 0-form f on \mathbb{R}^n , $\phi^* f = f \circ \phi$
- 2. for $i = 1, \dots, n, \phi^* dx^i = d\phi_i$
- 3. for an s-form ω , and a t-form χ on \mathbb{R}^n , $\phi^*(\omega \wedge \chi) = (\phi^*\omega) \wedge (\phi^*\chi)$
- 4. for *l*-forms ω, χ on \mathbb{R}^n , $\phi^*(\omega + \chi) = \phi^*\omega + \phi^*\chi$

Exercise 12.0.0.10. Let $M \subset \mathbb{R}^n$ be a k-dimensional smooth submanifold of \mathbb{R}^n , $\phi: U \to V$ a smooth parametrization of M, $\omega = \sum_{I \in \mathcal{I}_{k,n}} f_I dx^i$ an k-form on \mathbb{R}^n . Then

$$\phi^*\omega = \left(\sum_{I \in \mathcal{I}_k} (f_I \circ \phi)(\det v\phi_I)\right) du^1 \wedge du_2 \wedge \dots \wedge du_k$$

Proof. By definition,

$$\phi^* \omega = \phi^* \sum_{I \in \mathcal{I}_{k,n}} f_I dx^i$$
$$= \sum_{I \in \mathcal{I}_{k,n}} (\phi^* f_I) \phi^* dx^i$$
$$= \sum_{I \in \mathcal{I}_{k,n}} (f_I \circ \phi) d\phi_I$$

A previous exercise tells us that for each $I \in \mathcal{I}_{k,n}$,

$$d\phi_{I} = d\phi_{i_{1}} \wedge d\phi_{i_{2}} \wedge \dots \wedge d\phi_{i_{n}}$$

$$= \left(\sum_{j=1}^{n} \frac{\partial \phi_{i_{1}}}{\partial u^{j}} du^{j}\right) \wedge \left(\sum_{j=1}^{n} \frac{\partial \phi_{i_{2}}}{\partial u^{j}} du^{j}\right) \wedge \dots \wedge \left(\sum_{j=1}^{n} \frac{\partial \phi_{i_{k}}}{\partial u^{j}} du^{j}\right)$$

$$= \left(\det v\phi_{I}\right) du^{1} \wedge du_{2} \wedge \dots \wedge du_{k}$$

Therefore

$$\phi^* \omega = \sum_{I \in \mathcal{I}_{k,n}} (f_I \circ \phi) d\phi_I$$

$$= \sum_{I \in \mathcal{I}_{k,n}} (f_I \circ \phi) (\det v \phi_I) du^1 \wedge du_2 \wedge \dots \wedge du_k$$

$$= \left(\sum_{I \in \mathcal{I}_{k,n}} (f_I \circ \phi) (\det v \phi_I) \right) du^1 \wedge du_2 \wedge \dots \wedge du_k$$

12.1 Integration of Differential Forms

Definition 12.1.0.1. Let $U \subset \mathbb{R}^k$ be open and $\omega = f dx^1 \wedge dx_2 \wedge \cdots \wedge dx_k$ a k-form on \mathbb{R}^k . Define

$$\int_{U} \omega = \int_{U} f dx$$

Definition 12.1.0.2. Let $M \subset \mathbb{R}^n$ be a k-dimensional oriented smooth submanifold of \mathbb{R}^n , ω a k-form on \mathbb{R}^n and $\phi: U \to V$ a local smooth, orientation-preserving parametrization of M. Define

$$\int_{V} \omega = \int_{U} \phi^* \omega$$

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Exercise 12.1.0.3.

Theorem 12.1.0.4. Stokes Theorem:

Let $M \subset \mathbb{R}^n$ be a k-dimensional oriented smooth submanifold of \mathbb{R}^n and ω a k-1-form on \mathbb{R}^n . Then

$$\int_{\partial M} \omega = \int_M d\omega$$

Appendix A

Summation

Appendix B

Asymptotic Notation

Bibliography

- [1] Introduction to Algebra
- [2] Introduction to Analysis
- [3] Introduction to Fourier Analysis
- [4] Introduction to Measure and Integration