

MALA and Barker's Proposal: Gradient-Based MCMC Methods

- ▶ Background: From RWM to gradient-based methods
- ▶ Langevin dynamics and discretization
- ▶ Metropolis-Adjusted Langevin Algorithm (MALA)
- ▶ Optimal scaling theory
- ▶ Barker's Proposal: An alternative approach
- ▶ Comparison and practical considerations

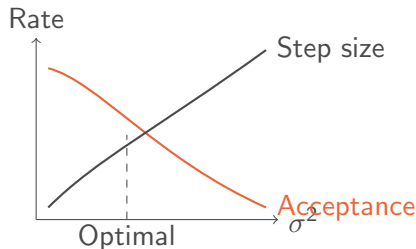
Random Walk Metropolis: The Challenge

Random Walk Metropolis (RWM):

$$q^* = q + \sigma W, \quad W \sim N(0, I_d)$$

Fundamental Trade-off:

- ▶ Large σ : Low acceptance
- ▶ Small σ : Slow exploration
- ▶ Optimal: $\sigma = \mathcal{O}(d^{-1/2})$



Problem: In high dimensions, RWM becomes inefficient

- ▶ Optimal acceptance rate: 0.234
- ▶ Curse of dimensionality: step size $\propto 1/d$

From Langevin Diffusion to MALA

Continuous Langevin Diffusion:

$$dX_t = \frac{1}{2} \nabla \log \pi(X_t) dt + dB_t$$

- ▶ Has π as stationary distribution
- ▶ Gradient provides drift toward high-probability regions

Euler-Maruyama Discretization (ULA):

$$X^{(t)} = X^{(t-1)} + \frac{\epsilon}{2} \nabla \log \pi(X^{(t-1)}) + \sqrt{\epsilon} W$$

Problem π is **not** the invariant distribution of ULA!

Solution: Add Metropolis-Hastings correction \Rightarrow MALA

Metropolis-Adjusted Langevin Algorithm

Algorithm 1 MALA

Input: Initial $X^{(0)}$, step size ϵ , target π , proposal q

for $t = 1, 2, \dots$ **do**

Propose: $X^* = X^{(t-1)} + \frac{\epsilon}{2} \nabla \log \pi(X^{(t-1)}) + \sqrt{\epsilon} W$

Compute acceptance ratio:

$$\alpha = \min \left\{ 1, \frac{\pi(X^*) q(X^{(t-1)} | X^*)}{\pi(X^{(t-1)}) q(X^* | X^{(t-1)})} \right\}$$

Accept $X^{(t)} = X^*$ with probability α , else $X^{(t)} = X^{(t-1)}$

end for

Optimal Scaling Theory

Maximizing Expected Squared Jump Distance (ESJD)

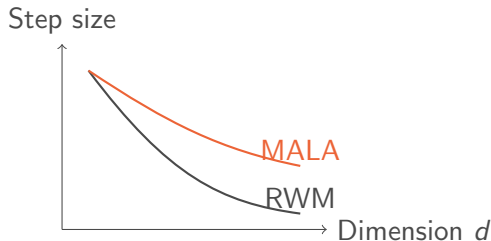
$$\mathbb{E} [\|X^{(t+1)} - X^{(t)}\|^2]$$

Dimension Scaling:

- ▶ RWM: $\sigma = \mathcal{O}(d^{-1})$
- ▶ MALA: $\sigma = \mathcal{O}(d^{-1/3})$

Optimal Acceptance:

- ▶ RWM: 0.234
- ▶ MALA: 0.574



Implication: MALA maintains larger step sizes in high dimensions

- ▶ Better exploration efficiency
- ▶ Faster convergence to target distribution
- ▶ **Catch** - requires gradient computation

Local-Balanced Proposals

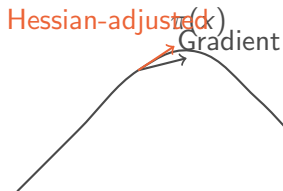
General Framework: Use local information about π

First-order (MALA):

$$X^* = X^{(t-1)} + \frac{\epsilon}{2} \nabla \log \pi(X^{(t-1)}) + \sqrt{\epsilon} W$$

Second-order:

$$X^* = X^{(t-1)} + \frac{\epsilon}{2} [\nabla^2 \log \pi(X^{(t-1)})]^{-1} \nabla \log \pi(X^{(t-1)}) + \sqrt{\epsilon} W$$



Higher-order methods better approximate local geometry

Barker's Proposal: An Alternative Approach

Key Idea: Use gradient to stochastically bias proposal direction

Proposal Density: $Q_B(x, dy) = \frac{2}{1 + e^{-\nabla \log \pi(x)^T (y-x)}} K(x, dy)$

where $K(x, dy)$ is a base kernel (e.g., Gaussian)

Algorithm 2 1D case with Gaussian kernel

Sample $Z \sim N(0, \sigma^2)$

Calculate $p(x, z) = 1/(1 + \exp(-Z^T \nabla \log \pi(x)))$:

Set $b(x, z) = 1$ with probability $p(x, z)$, else $b(x, z) = -1$

Propose $Y = x + b(x, z)Z$

Apply Metropolis-Hastings acceptance

MALA vs Barker's Proposal

Both use gradient information, but differently

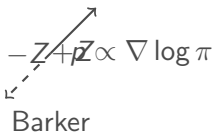
MALA:

- ▶ Deterministic drift
- ▶ $X^* = X + \frac{\epsilon}{2} \nabla \log \pi + \text{noise}$
- ▶ Gradient always adds to proposal
- ▶ Well-studied optimal scaling
- ▶ Proven efficiency in high dimensions



Barker:

- ▶ Stochastic direction choice
- ▶ Probability depends on gradient
- ▶ May flip proposal direction
- ▶ More recent theoretical development
- ▶ Potentially better for certain targets



Summary and Practical Considerations

Key Takeaways:

- ▶ Gradient information dramatically improves MCMC efficiency
- ▶ MALA: Proven workhorse with $O(d^{-1/3})$ scaling
- ▶ Barker: Promising alternative with different mixing properties
- ▶ Both methods correct discretization bias via Metropolis step

When to use which?

Choose MALA when:

- ▶ High-dimensional problems
- ▶ Gradients are cheap
- ▶ Well-conditioned targets
- ▶ Need proven reliability

Consider Barker when:

- ▶ Exploring alternatives
- ▶ Specific target structure
- ▶ Research applications
- ▶ Robustness needed

Both methods: Major improvements over RWM!