### Introduction

#### What is Slice Sampling?

A "black-box" auxiliary variable Markov Chain Monte Carlo (MCMC) method that avoids the need to tune hyperparameters. Introduced by Neal (2003).

The idea of slice sampling. Suppose we wish to sample from a distribution for a variable, x, taking values in some subset of  $R^n$ , whose density is proportional to some function f(x). We can do this by sampling uniformly from the (n+1)-dimensional region that lies under the plot of f(x). This idea can be formalized by introducing an auxiliary real variable, y, and defining a joint distribution over x and y that is uniform over the region U=(x,y):0< y< f(x) below the curve or surface defined by f(x). That is, the joint density for (x,y) is

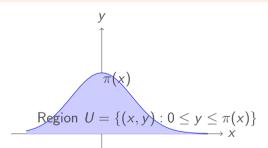
$$p(x,y) = \frac{1}{Z} \begin{cases} 1, & \text{if } 0 < y < f(x) \\ 0, & \text{otherwise} \end{cases}$$

where  $Z = \int f(x)dx$ . The marginal density for x is then

# **Intuition Behind Slice Sampling**

#### The Fundamental Idea

To sample from  $\pi(x)$ , we can sample uniformly from the region under the curve of  $\pi(x)$ 



#### Step 1: Vertical Slice

- ightharpoonup Given current position x
- ▶ Sample height  $y \sim \text{Uniform}(0, \pi(x))$

#### Step 2: Horizontal Slice

- ► Sample new *x* uniformly from slice
- ►  $S = \{x : \pi(x) > v\}$

## The Slice Sampling Algorithm

#### Basic Algorithm

**Given:** Current state  $x_t$ , target distribution  $\pi(x)$ 

#### Algorithm

- 1. **Sample auxiliary variable:** Draw  $y \sim \text{Uniform}(0, \pi(x_t))$
- 2. **Find the slice:** Identify  $S = \{x : \pi(x) \ge y\}$
- 3. Sample from the slice: Draw  $x_{t+1} \sim \mathsf{Uniform}(S)$

The Challenge: Finding and Sampling from S In practice, finding  $S = \{x : \pi(x) \ge y\}$  can be difficult!

Key Idea: Leave Distribution Invariant

# **How to sample from** *S*

#### The Stepping Out Procedure

- 1. Create initial interval:
- 2.  $L = x_t w \cdot U$ , R = L + w, where  $U \sim \text{Uniform}(0, 1)$
- 3. Step out left:
- 4. While  $\pi(L) > y$ : L = L w
- 5. Step out right:
- 6. While  $\pi(R) > y$ : R = R + w

#### The Shrinking Procedure

- 1. Sample and shrink:
- 2. Loop:  $x' \sim \text{Uniform}(L, R)$
- 3. If  $\pi(x') \ge y$ : accept  $x_{t+1} = x'$
- 4. Else: shrink [L, R] by setting L = x' or R = x'

#### Adaptive Nature

The algorithm automatically adapts to the local scale of  $\pi(x)$ . Wide regions are explored with large steps, narrow regions with small steps.

Alternative procedures exist for sampling from S (e.g. doubling multi-dimensional

# Why w is Not a Critical Tuning Parameter

#### The Width Parameter w: Efficiency vs. Correctness

Yes, w IS technically a tuning parameter, BUT...

# Traditional MCMC (e.g., RW-Metropolis)

- ▶ Poor tuning  $\rightarrow$  Poor mixing
- $ightharpoonup \sigma$  too small ightharpoonup Tiny steps, stuck
- $ightharpoonup \sigma$  too large ightarrow High rejection
- ► Can take exponentially long
- ► Affects correctness in finite time

#### Slice Sampling with w

- **Poor**  $w \rightarrow$  More computation
- ightharpoonup w too small ightharpoonup Many step-outs
- ightharpoonup w too large ightharpoonup More shrinking
- ► Always finds correct slice
- Only affects efficiency

#### Why w is Robust: The Self-Correcting Mechanism

Case 1:  $w \ll \text{typical slice width}$  Case 2:  $w \gg \text{typical slice width}$ 

# Why Slice Sampling Converges

#### **Formal Convergence Properties**

#### 1. Detailed Balance

Let T(x'|x) be the transition kernel. We need:  $\pi(x) \cdot T(x'|x) = \pi(x') \cdot T(x|x')$ 

#### **Proof sketch:**

- ▶ Given x, sample  $y \sim \text{Uniform}(0, \pi(x))$
- ▶ Probability density of moving from x to x':

$$T(x'|x) = \int_0^{\min(\pi(x), \pi(x'))} \frac{1}{\pi(x)} \cdot \frac{1}{|S_y|} dy$$

where  $|S_v|$  is the length of slice  $\{z : \pi(z) \ge y\}$ 

▶ This is symmetric:  $T(x'|x) = T(x|x') \Rightarrow$  detailed balance holds

#### 2. Irreducibility

For any x, x' where  $\pi(x) > 0$  and  $\pi(x') > 0$ :

# **Convergence: Additional Mathematical Details**

#### Detailed Balance - Complete Argument

Consider augmented state space (x, y) with invariant distribution:

$$\pi^*(x,y) = \frac{1}{7} \cdot \mathbf{1}\{0 \le y \le \pi(x)\}\$$

where  $Z = \int \pi(x) dx$  is the normalization constant.

#### The Gibbs Sampler View

Slice sampling is a Gibbs sampler on the augmented space:

- ▶ **Step 1:** Sample  $y|x \sim \text{Uniform}(0, \pi(x))$
- ▶ **Step 2:** Sample  $x|y \sim \text{Uniform}(\{x : \pi(x) > y\})$

Each conditional distribution is correct:

$$p(y|x) = \frac{1}{f(x)} \cdot \mathbf{1}\{0 \le y \le \pi(x)\}$$
 (1)

# **Summary**

#### Advantages of Slice Sampling

- √ No rejection step (unlike MH)
- ✓ Self-adapting to different scales
- ✓ Only requires  $\pi(x)$  evaluation
- $\checkmark$  Minimal tuning (only w)
- √ Guaranteed convergence

#### Common Uses

- ▶ Bayesian inference
- ▶ Hierarchical models
- ► Within Gibbs samplers

#### Disadvantages

- × Computationally expensive
- × Difficult in high dimensions
- × Slow for multimodal distributions

#### Best For

- ► Univariate sampling
- Unusual distributions
- ► Avoiding tuning phase