

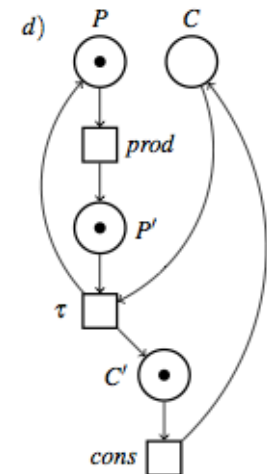
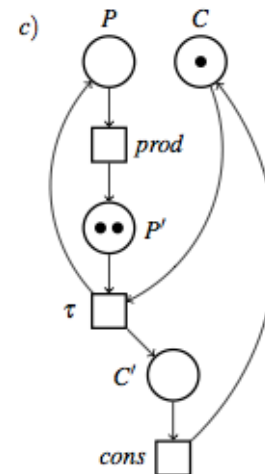
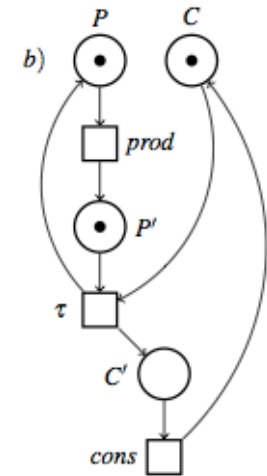
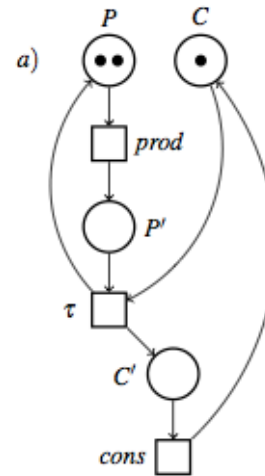
# Lezione 30 MSC

## Petri Nets: Basic Definitions

Roberto Gorrieri

# Modello distribuito non-interleaving

- Stato globale  
= multinsieme di stati locali
- Transizioni coinvolgono solo qualche stato locale
- Token game
- Parallelismo esplicito
- Esempio: 2 produttori e un consumatore



# Multiset (1)

A *multiset*  $M$  over a set  $A$  is an unordered, possibly infinite, list of elements of  $A$ , where no element of  $A$  can occur infinitely many times.

This is usually represented as a set with *multiplicities*; for instance,  $M = \{a, \tau, a, \tau, \tau\}$  is a multiset over the set  $A = \{a, \tau\}$  with two occurrences of action  $a$  and three occurrences of action  $\tau$ .

Given a countable set  $S$ , a *finite multiset* over  $S$  is a function  $m : S \rightarrow \mathbb{N}$  such that the *support set*  $\text{dom}(m) = \{s \in S \mid m(s) \neq 0\}$  is finite. The *multiplicity* of  $s$  in  $m$  is given by the number  $m(s)$ .

The set of all finite multisets over  $S$ , denoted by  $M_{\text{fin}}(S)$ , is ranged over by  $m$ , possibly indexed.

A multiset  $m$  such that  $\text{dom}(m) = \emptyset$  is called *empty* and is denoted by  $\emptyset$ , with abuse of notation.

# Multiset (2)

**Ordering:** We write  $m \subseteq m'$  if  $m(s) \leq m'(s)$  for all  $s \in S$ . We also write  $m \subset m'$  if  $m \subseteq m'$  and  $m(s) < m'(s)$  for some  $s \in S$ .

- The operator  $\oplus$  **denotes multiset union** and is defined as follows:  $(m \oplus m')(s) = m(s) + m'(s)$ ; the operation  $\oplus$  is commutative, associative and has  $\emptyset$  as neutral element.
- If  $m_2 \subseteq m_1$ , then we can define **multiset difference**, denoted by the operator  $\ominus$ , as follows:  $(m_1 \ominus m_2)(s) = m_1(s) - m_2(s)$ .
- The **scalar product** of a number  $j$  with a multiset  $m$  is the multiset  $j \cdot m$  defined as  $(j \cdot m)(s) = j \cdot (m(s))$ .

A finite multiset  $m$  over  $S = \{s_1, s_2, \dots\}$  can be represented as  $k_1 \cdot s_{i_1} \oplus k_2 \cdot s_{i_2} \oplus \dots \oplus k_n \cdot s_{i_n}$ , where  $\text{dom}(m) = \{s_{i_1}, \dots, s_{i_n}\} \subseteq S$  and  $k_j = m(s_{i_j}) > 0$  for  $j = 1, \dots, n$ . If  $S$  is finite, i.e.,  $S = \{s_1, \dots, s_n\}$ , then a finite multiset can be represented also as  $k_1 \cdot s_1 \oplus k_2 \cdot s_2 \oplus \dots \oplus k_n \cdot s_n$ , where  $k_j = m(s_j) \geq 0$  for  $j = 1, \dots, n$ .  $\square$

# Place/Transition Petri Net

**Definition 3.2. (P/T Petri net)** A labeled *Place/Transition* Petri net (P/T net for short) is a tuple  $N = (S, A, T)$ , where

- $S$  is the countable set of *places*, ranged over by  $s$  (possibly indexed),
- $A \subseteq \text{Lab}$  is the countable set of *labels*, ranged over by  $\ell$  (possibly indexed), and
- $T \subseteq (\mathcal{M}_{\text{fin}}(S) \setminus \{\emptyset\}) \times A \times \mathcal{M}_{\text{fin}}(S)$  is the countable set of *transitions*, ranged over by  $t$  (possibly indexed), such that, for each  $\ell \in A$ , there exists a transition  $t \in T$  of the form  $(m, \ell, m')$ .

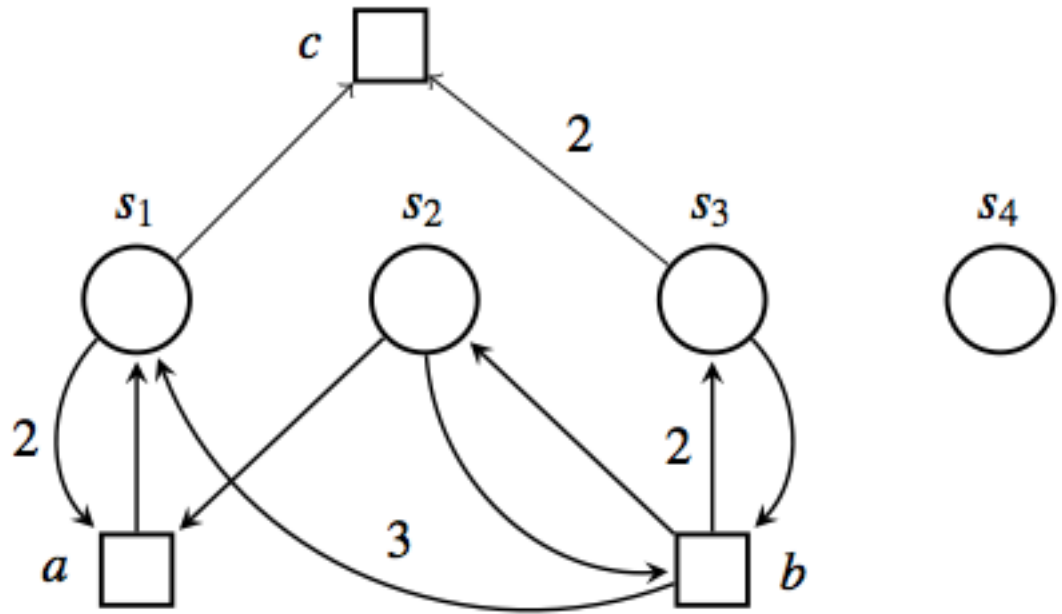
Given a transition  $t = (m, \ell, m')$ , we use the notation:

- $\bullet t$  to denote its *pre-set*  $m$  (which cannot be an empty multiset) of tokens to be consumed;
- $l(t)$  for its *label*  $\ell$ , and
- $t^\bullet$  to denote its *post-set*  $m'$  of tokens to be produced.

Hence, transition  $t$  can be also represented as  $\bullet t \xrightarrow{l(t)} t^\bullet$ . We also define pre-sets and post-sets for places as follows:  $\bullet s = \{t \in T \mid s \in t^\bullet\}$  and  $s^\bullet = \{t \in T \mid s \in \bullet t\}$ . Note that while the pre-set (post-set) of a transition is, in general, a multiset, the pre-set (post-set) of a place is a set. □

# Example

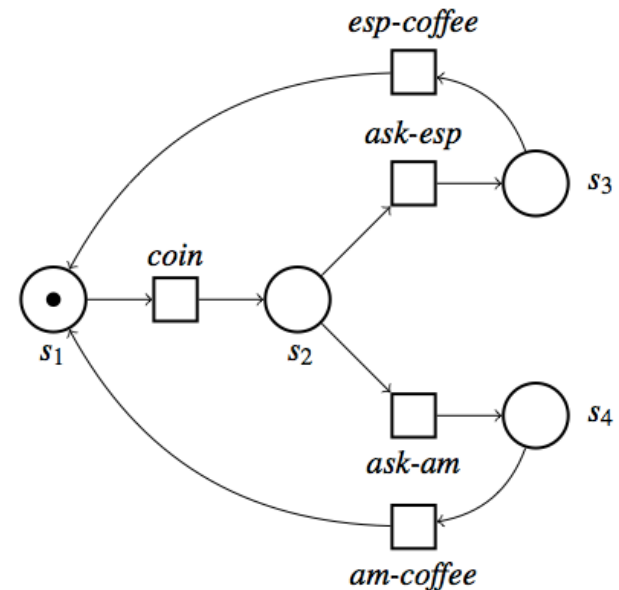
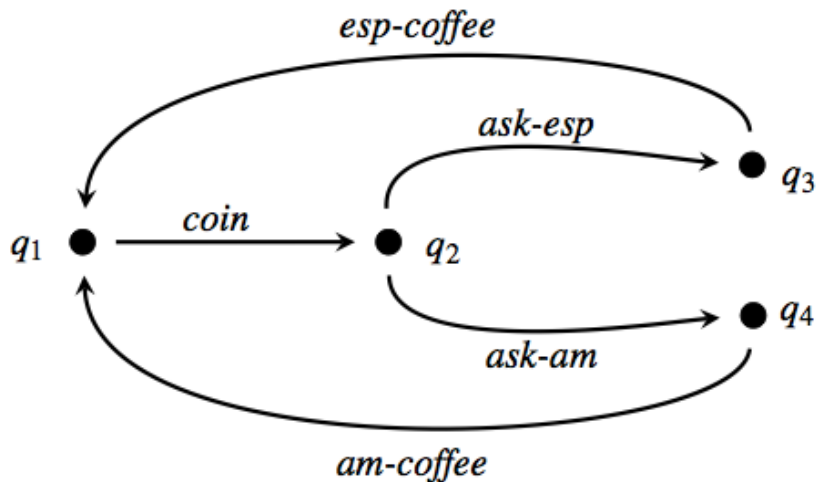
- $N = (S, A, T)$ , where  $S = \{s_1, s_2, s_3, s_4\}$ ,  $A = \{a, b, c\}$  and  $T = \{(2 \cdot s_1 \oplus s_2, a, s_1), (s_2 \oplus s_3, b, 3 \cdot s_1 \oplus s_2 \oplus 2 \cdot s_3), (s_1 \oplus 2 \cdot s_3, c, \emptyset)\}$ .



# Osservazione

- LTS's are a subclass of P/T nets.

Note that the latter is a generalization of the former: a transition system is just a special case of Petri net, where each net transition  $t = (m, a, m')$  is such that  $m$  and  $m'$  are singletons.



# P/T net system and token game

**Definition 3.3. (Marking, token, P/T net system)** A finite multiset over  $S$  is called a *marking*. Given a marking  $m$  and a place  $s$ , we say that the place  $s$  contains  $m(s)$  *tokens*, graphically represented by  $m(s)$  bullets inside place  $s$ . A *P/T net system*  $N(m_0)$  is a tuple  $(S, A, T, m_0)$ , where  $(S, A, T)$  is a P/T net and  $m_0$  is a marking over  $S$ , called the *initial marking*. We also say that  $N(m_0)$  is a *marked net*.  $\square$

**Definition 3.4. (Token game)** Given a labeled P/T net  $N = (S, A, T)$ , we say that a transition  $t$  is *enabled* at marking  $m$ , denoted by  $m[t\rangle$ , if  $\bullet t \subseteq m$ . The execution (or *firing*) of  $t$  enabled at  $m$  produces the marking  $m' = (m \ominus \bullet t) \oplus t^\bullet$ . This is written  $m[t\rangle m'$ .  $\square$

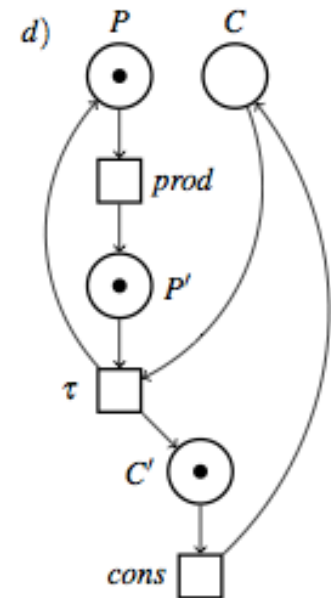
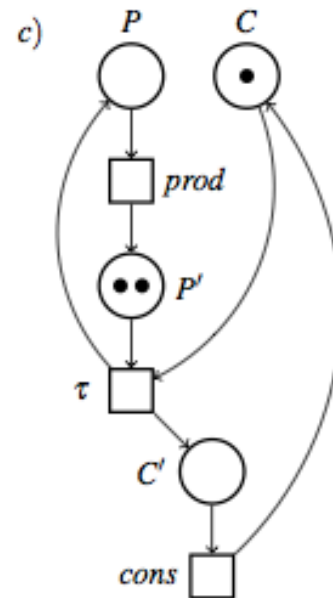
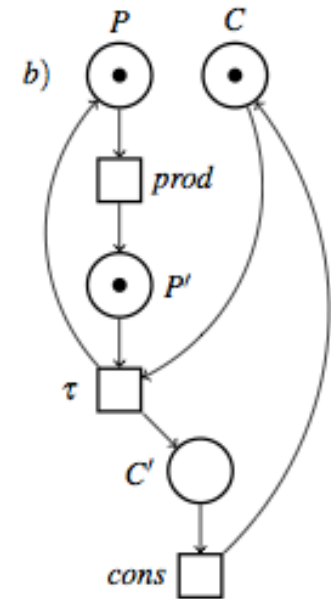
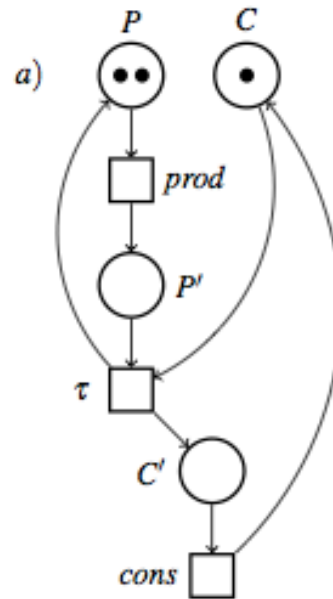
**Permissive nature of P/T Petri nets:** if  $t$  is enabled at  $m$ , then  $t$  is enabled also by any other marking  $m'$  covering  $m$ , i.e., by any  $m'$  such that  $m \subseteq m'$ .

This is in contrast with *nonpermissive* Petri nets, we will see in the following, where a transition  $t$  enabled at  $m$  may be disabled at  $m'$  because  $m'$  can contain a token in an inhibiting place for  $t$ .



## 2-Producers/ 1-Consumer

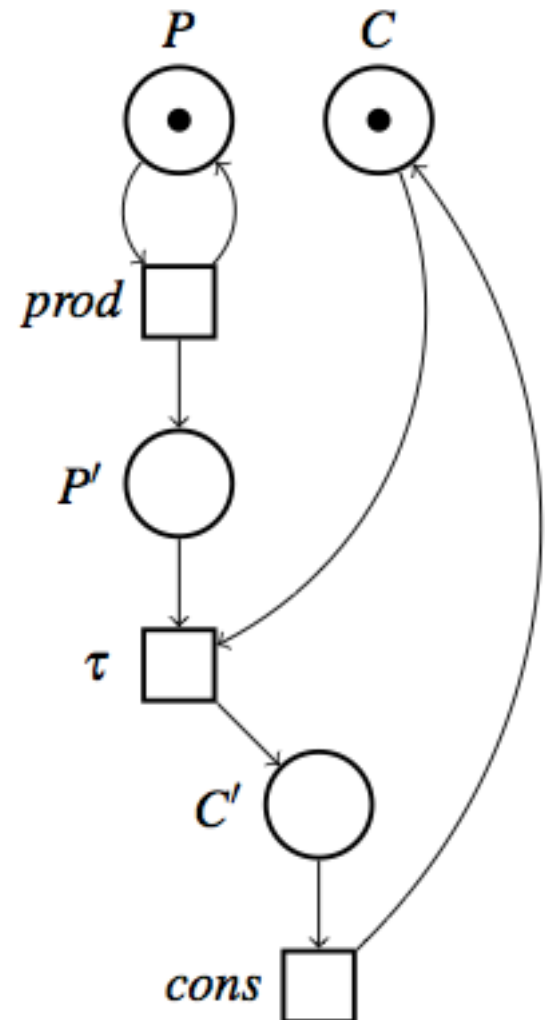
Rete bounded:  
Al massimo 2  
tokens in ogni  
place



# Unbounded Producer/Consumer

Note that place  $P'$  can hold an **unbounded number of tokens**, as the producer  $P$  can perform the initial transition **prod** repeatedly, depositing each time one token in that place.

A **finite** Petri net model for a system whose reachable markings are **infinitely** many.



# Reachable markings and firing sequences

**Definition 3.5. (Reachable markings and firing sequences)** Given a P/T net system  $N(m_0) = (S, A, T, m_0)$ , the set of markings *reachable from  $m$* , denoted  $[m\rangle$ , is defined as the least set such that

- $m \in [m\rangle$  and
- if  $m_1 \in [m\rangle$  and, for some transition  $t \in T$ ,  $m_1[t\rangle m_2$ , then  $m_2 \in [m\rangle$ .

We say that  $m$  is *reachable* if  $m$  is reachable from the initial marking  $m_0$ . A *firing sequence* starting at  $m$  is defined inductively as follows:

- $m$  is a firing sequence and
- if  $m_1[t_1\rangle m_2 \dots [t_{n-1}\rangle m_n$  (with  $m = m_1$  and  $n \geq 1$ ) is a firing sequence and  $m_n[t_n\rangle m_{n+1}$ , then  $m = m_1[t_1\rangle m_2 \dots [t_{n-1}\rangle m_n[t_n\rangle m_{n+1}$  is a firing sequence.

A firing sequence  $m = m_1[t_1\rangle m_2 \dots [t_n\rangle m_{n+1}$  is usually abbreviated as  $m[t_1 \dots t_n\rangle m_{n+1}$  and  $t_1 \dots t_n$  is called a *transition sequence* starting at  $m$  and ending at  $m_{n+1}$ .  $\square$

# Some classes of P/T nets

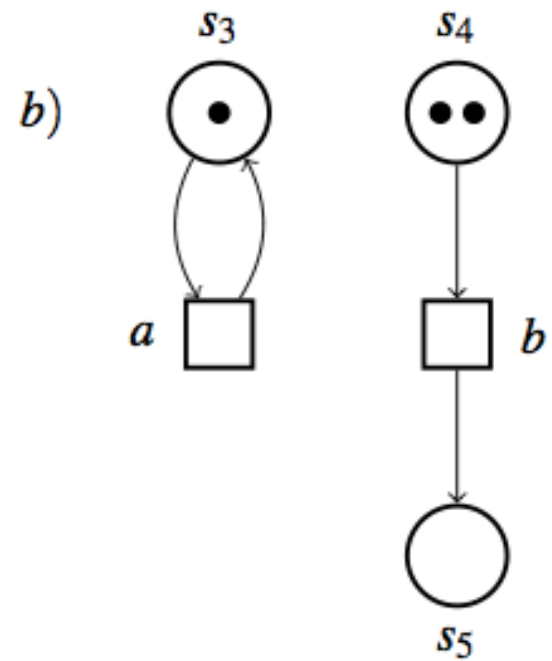
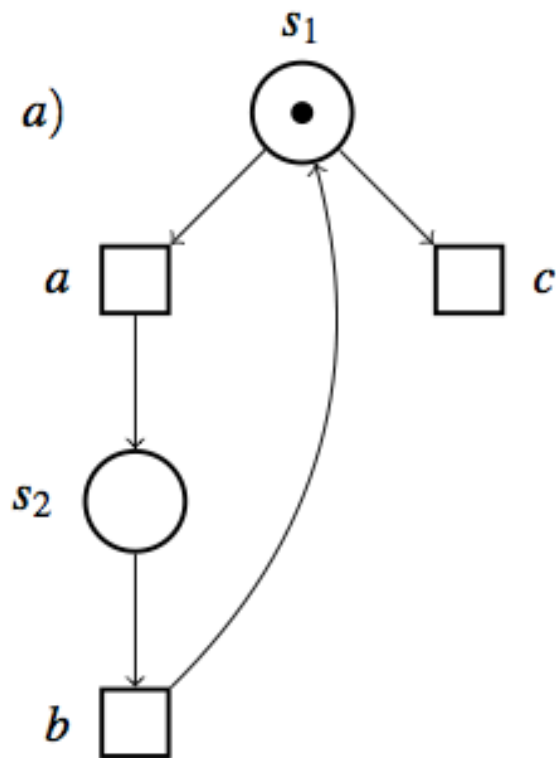
**Definition 3.6. (Classes of P/T Petri nets)** A P/T Petri net  $N = (S, A, T)$  is

- *statically acyclic* if there exists no sequence  $x_1 x_2 \dots x_n$ , such that  $n \geq 3$ ,  $x_i \in S \cup T$  for  $i = 1, \dots, n$ ,  $x_1 = x_n$ ,  $x_1 \in S$  and  $x_i \in {}^\bullet x_{i+1}$  for  $i = 1, \dots, n-1$ ;
- *distinct* if all the transitions have distinct labels: for all  $t_1, t_2 \in T$ , if  $l(t_1) = l(t_2)$ , then  $t_1 = t_2$ ;
- *finite* if both  $S$  and  $T$  are finite sets;
- a *finite-state machine* (FSM, for short) if  $N$  is finite and for all  $t \in T$ ,  $|{}^\bullet t| = 1$  and  $|t^\bullet| \leq 1$ ;
- a *BPP net* if  $N$  is finite and every transition has exactly one input place, i.e., for all  $t \in T$ ,  $|{}^\bullet t| = 1$ ;
- a *CCS net* if for all  $t \in T$ ,  $1 \leq |{}^\bullet t| \leq 2$  and if  $|{}^\bullet t| = 2$  then  $l(t) = \tau$ .

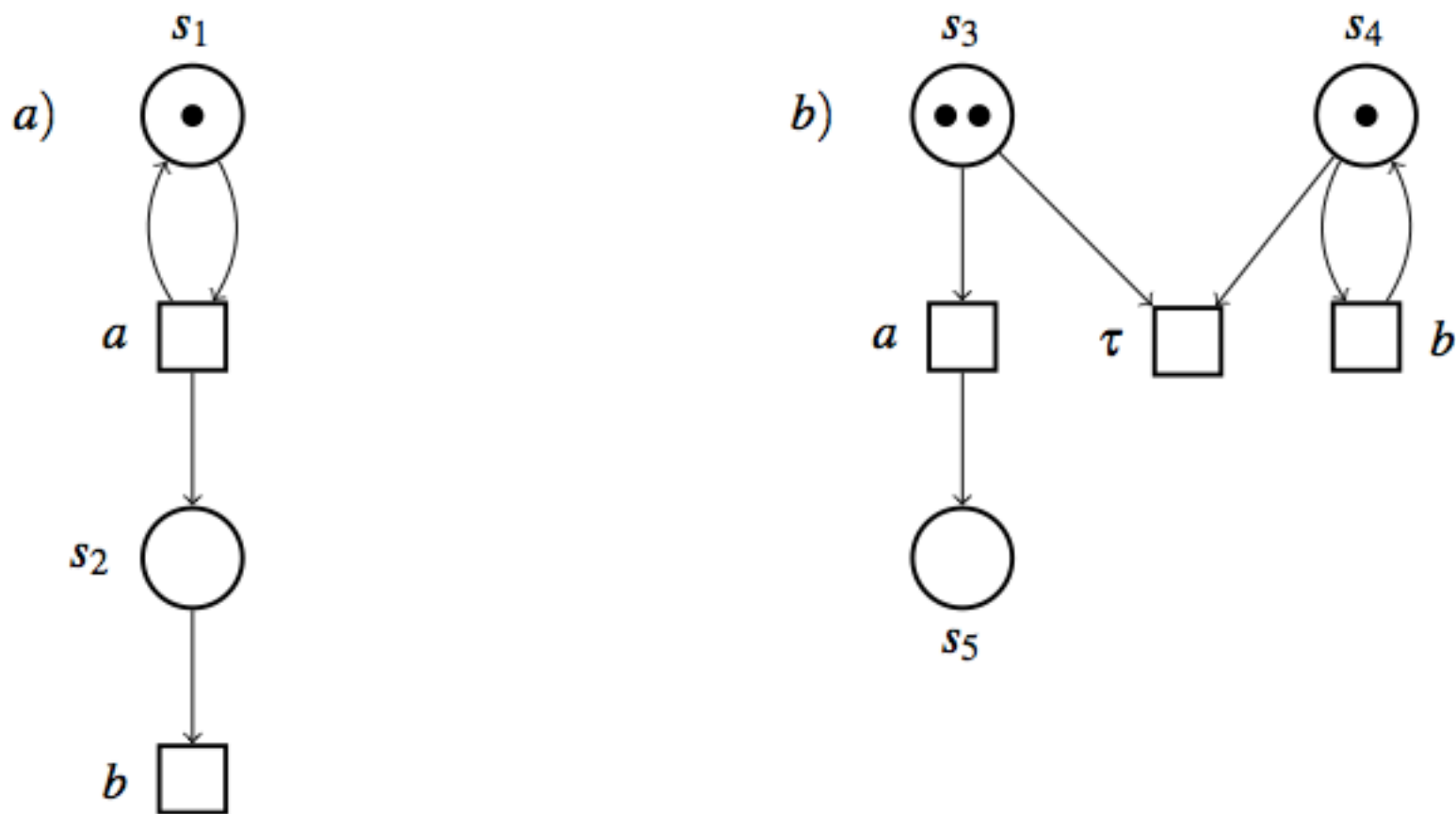
# Some classes of P/T net systems

A P/T net system  $N(m_0)$  is

- *dynamically acyclic* if there exists no  $m_1 \in [m_0\rangle$  with a nonempty (i.e, with  $n \geq 2$ ) firing sequence  $m_1[t_1\rangle m_2 \dots [t_{n-1}\rangle m_n$  such that  $m_1 \subseteq m_n$ ;
- a *sequential* FSM if  $N$  is an FSM and  $m_0$  is a singleton, i.e.,  $|m_0| = 1$ ;
- a *concurrent* FSM if  $N$  is an FSM and  $m_0$  is arbitrary;
- *k-bounded* if any place contains at most  $k$  tokens in any reachable marking, i.e.,  $\forall s \in S \ m(s) \leq k$  for all  $m \in [m_0\rangle$ ;
- *safe* if it is 1-bounded;
- *bounded* if  $\forall s \in S \ \exists k \in \mathbb{N}$  such that  $m(s) \leq k$  for all  $m \in [m_0\rangle$ . □



**Fig. 3.4** A sequential finite-state machine in (a), and a concurrent finite-state machine in (b)



**Fig. 3.5** Some further nets: a BPP net in (a), and a CCS net in (b)



**Proposition 3.1.** *Given a P/T system  $N(m_0)$ , the following hold:*

- 1. if  $N$  is an FSM net, then  $N$  is also a BPP net;*
- 2. if  $N$  is a BPP net, then  $N$  is also a finite CCS net;*
- 3. if  $N(m_0)$  is a sequential FSM, then  $N(m_0)$  is also a concurrent FSM;*
- 4. if  $N(m_0)$  is a sequential FSM, then  $N(m_0)$  is also safe;*
- 5. if  $N(m_0)$  is a concurrent FSM, then  $N(m_0)$  is also  $|m_0|$ -bounded;*
- 6. if  $N(m_0)$  is finite and bounded, then  $N(m_0)$  is also  $k$ -bounded for some suitable  $k \in \mathbb{N}$ ;*
- 7. if  $N(m_0)$  is finite and bounded, then the set  $[m_0]$  of the markings reachable from  $m_0$  is finite;*
- 8. if  $N$  is statically acyclic, then  $N(m_0)$  is dynamically acyclic;*
- 9. if  $N(m_0)$  is finite and dynamically acyclic, then the set of its firing sequences is finite.*

*Proof.* We prove only (7). Assume  $N(m_0)$  is finite and bounded, where the cardinality of the set  $S$  of places is  $n$  and the bound limit on places is  $k$ . Then, there cannot be more than  $(k+1)^n$  different markings, because each place  $s$  can hold any number of tokens in the range  $\{0, \dots, k\}$ .  $\square$



# Finite and bounded implies $k$ -bounded

Any finite net that is bounded is also  $k$ -bounded for some suitable  $k \in \mathbb{N}$ ; in fact, boundedness implies that for all  $s \in S$  there exists an upper bound  $k_s$  on the number of tokens that can be accumulated on  $s$ ; if the net is finite, then it is enough to choose the largest  $k_s$  (call it  $k'$ ), which has the property that for all  $s$ ,  $k_s \leq k'$ , so that the net is  $k'$ -bounded.

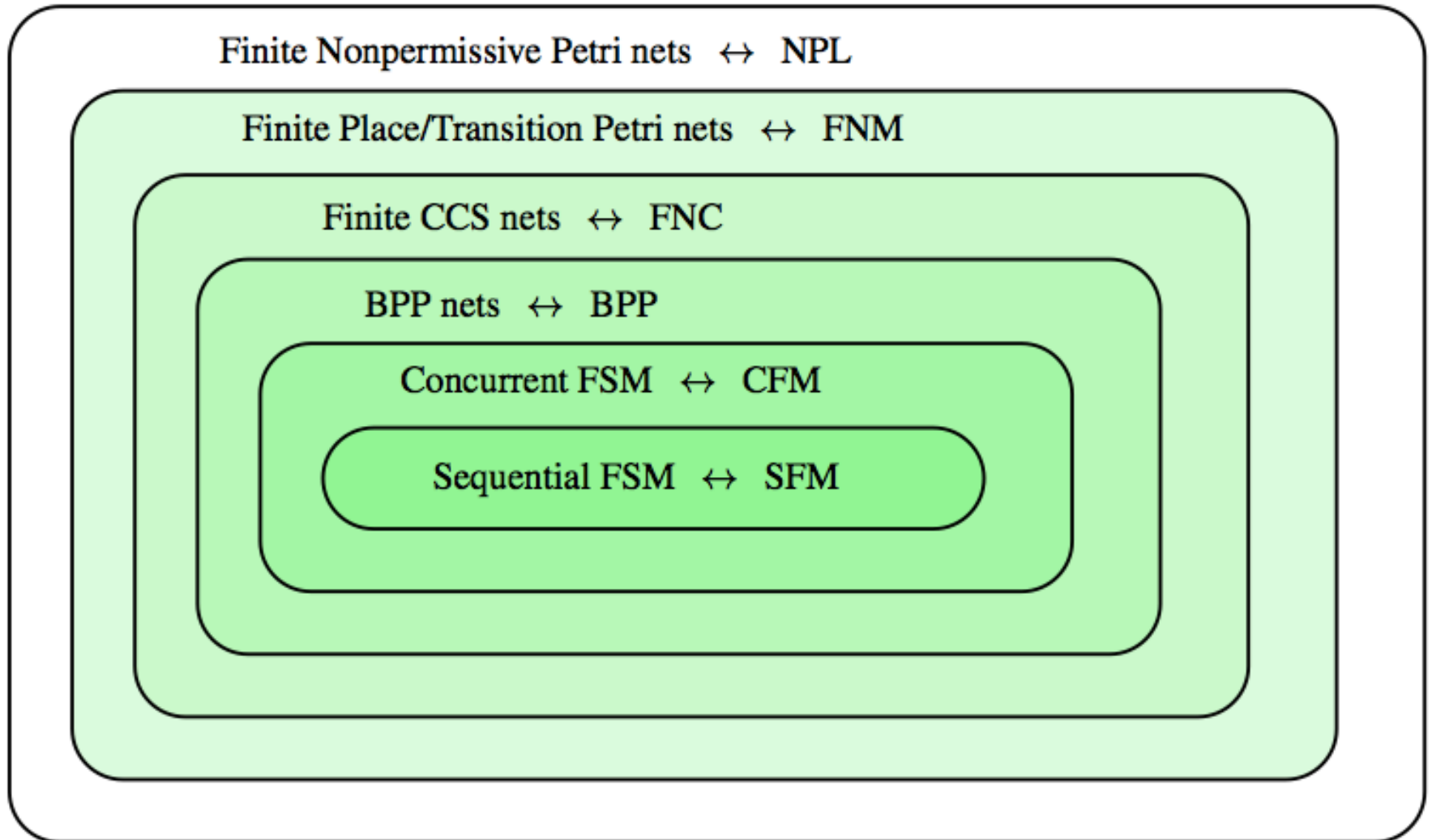
It follows that a bounded net that is not  $k$ -bounded for any  $k$  is infinite. For instance, consider the net  $N(m_0) = (S, A, T, m_0)$  — where  $S = \{s_i \mid i \in \mathbb{N}\}$ ,  $A = \{a_i \mid i \in \mathbb{N}\}$ ,  $T = \{(s_i, a_i, 2 \cdot s_{i+1}) \mid i \in \mathbb{N}\}$ ,  $m_0 = \{s_0\}$  — is an infinite net such that place  $s_i$  can hold up to  $2^i$  tokens; hence,  $N(m_0)$  is bounded, but there is no  $k$  such that  $2^i \leq k$  for all  $i \in \mathbb{N}$ .

# Why these classes?

The interest in these classes is because we will see that they are strictly related to particular process algebras derived from CCS and Multi-CCS. In particular, we will see that

- **SFM** process terms (essentially **finite-state CCS**) originate sequential FSMs (Chapter 4),
- **CFM** process terms (**finite-state CCS with an external operator of asynchronous parallelism**) represent concurrent FSMs (Section 5.1),
- **BPP** process terms are mapped to BPP nets (Section 5.2),
- **FNC** process terms (essentially **finite-net CCS**) originate finite CCS P/T nets (Chapter 6), and finally
- **FNM** process terms (essentially **finite-net Multi-CCS**) represent all finite P/T nets (Chapter 7).

# The Hierarchy



**Fig. 1.5** The hierarchy of net classes and process algebras

# Dynamically reachable subnet

**Definition 3.7. (Dynamically reachable subnet)** Given a P/T net system  $N(m_0) = (S, A, T, m_0)$ , the *dynamically reachable subnet*  $Net_d(N(m_0))$  is  $(S', A', T', m_0)$ , where

$$S' = \{s \in S \mid \exists m \in [m_0] \text{ such that } m(s) \geq 1\},$$

$$T' = \{t \in T \mid \exists m \in [m_0] \text{ such that } m[t] \geq 1\},$$

$$A' = \{\ell \mid \exists t \in T' \text{ such that } l(t) = \ell\}.$$

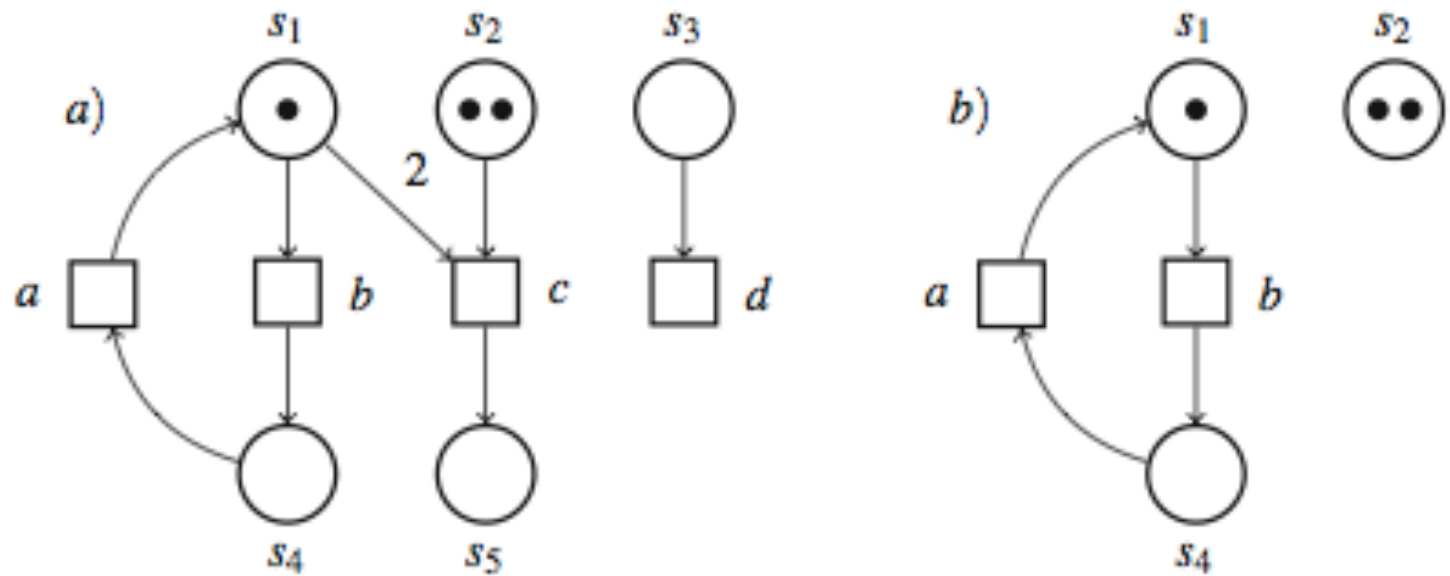
□

**Definition 3.8. (Dynamically reduced net)** A P/T net system  $N(m_0) = (S, A, T, m_0)$  is *dynamically reduced* if  $N(m_0) = Net_d(N(m_0))$ , i.e., the net system is equal to its dynamically reachable subnet.

□

- $Net_d(N(m_0))$  is algorithmically computable for any finite P/T net system (complexity: exponential)

# Example



**Fig. 3.7** A net system in (a) and its dynamically reachable subnet in (b)

# Statically reachable subnet (1)

**Definition 3.9. (Statically reachable subnet and statically reduced net)** Given a finite P/T net  $N = (S, A, T)$ , we say that a transition  $t$  is *statically enabled* by a set of places  $S' \subseteq S$ , denoted by  $S' \llbracket t \rrbracket$ , if  $\text{dom}(\bullet t) \subseteq S'$ .

Given two sets of places  $S_1, S_2 \subseteq S$ , we say that  $S_2$  is *statically reachable in one step* from  $S_1$  if there exists a transition  $t \in T$ , such that  $S_1 \llbracket t \rrbracket$ ,  $\text{dom}(t^\bullet) \not\subseteq S_1$  and  $S_2 = S_1 \cup \text{dom}(t^\bullet)$ ; this is denoted by  $S_1 \xRightarrow{t} S_2$ . The *static reachability relation*  $\Longrightarrow^* \subseteq \mathcal{P}_{fin}(S) \times \mathcal{P}_{fin}(S)$  is the least relation such that

- $S_1 \Longrightarrow^* S_1$  and
- if  $S_1 \Longrightarrow^* S_2$  and  $S_2 \xRightarrow{t} S_3$ , then  $S_1 \Longrightarrow^* S_3$ .

A set of places  $S_k \subseteq S$  is the *largest* set statically reachable from  $S_1$  if  $S_1 \Longrightarrow^* S_k$  and for all  $t \in T$  such that  $S_k \llbracket t \rrbracket$ , we have that  $\text{dom}(t^\bullet) \subseteq S_k$ .

# Statically reachable subnet (2)

Given a finite P/T net system  $N(m_0) = (S, A, T, m_0)$ , we denote by  $\llbracket \text{dom}(m_0) \rrbracket$  the largest set of places statically reachable from  $\text{dom}(m_0)$ , i.e., the largest  $S_k$  such that  $\text{dom}(m_0) \Longrightarrow^* S_k$ .

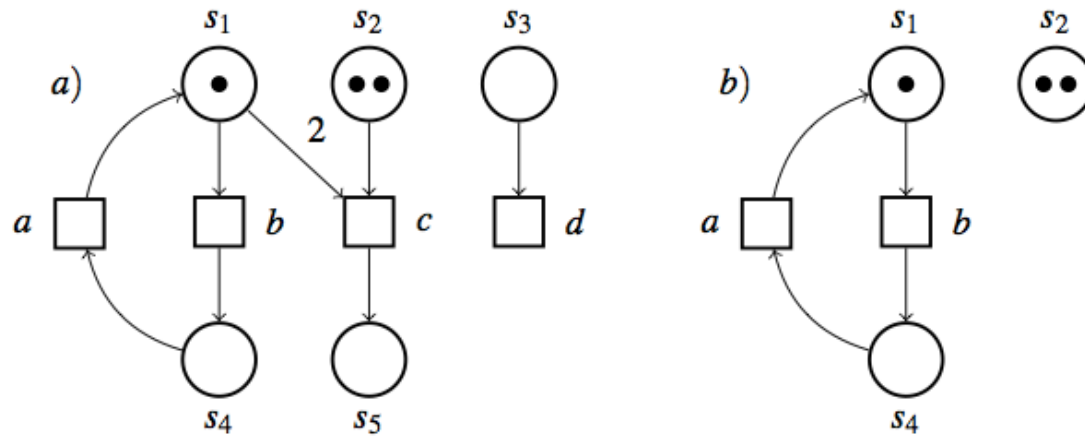
The *statically reachable subnet*  $\text{Net}_s(N(m_0))$  is the net  $(S', A', T', m_0)$ , where

$$\begin{aligned} S' &= \llbracket \text{dom}(m_0) \rrbracket, \\ T' &= \{t \in T \mid S' \llbracket t \rrbracket\}, \\ A' &= \{\ell \mid \exists t \in T' \text{ such that } l(t) = \ell\}. \end{aligned}$$

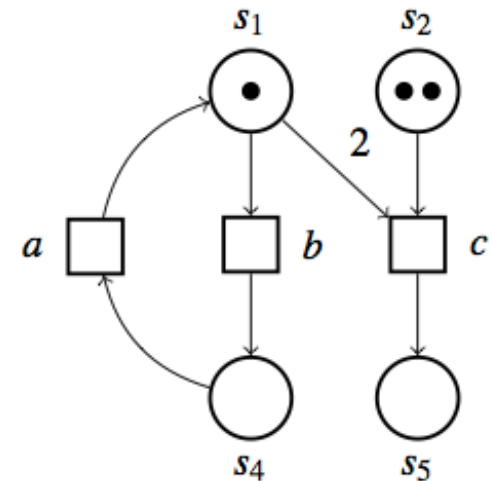
A finite P/T net system  $N(m_0) = (S, A, T, m_0)$  is *statically reduced* if  $\text{Net}_s(N(m_0)) = N(m_0)$ , i.e., the net system is equal to its statically reachable subnet.  $\square$

- $\text{Net}_s(N(m_0))$  is algorithmically computable for any finite P/T net system (complexity: polynomial)

# Example (revisited)



**Fig. 3.7** A net system in (a) and its dynamically reachable subnet in (b)



**Fig. 3.8** The statically reachable subnet of Figure 3.7(a)



# Properties

**Proposition 3.2.** *Given a P/T net system  $N(m_0) = (S, A, T, m_0)$ , if  $N(m_0)$  is dynamically reduced, then it is also statically reduced.*

**Proposition 3.3.** *Given a P/T net system  $N(m_0) = (S, A, T, m_0)$ , if its dynamically reachable subnet  $Net_d(N(m_0))$  is  $(S', A', T', m_0)$  and its statically reachable subnet  $Net_s(N(m_0))$  is  $(S'', A'', T'', m_0)$ , then  $S' \subseteq S''$ ,  $T' \subseteq T''$  and  $A' \subseteq A''$ .  $\square$*

For some classes of nets, however, the two notions coincide.

**Proposition 3.4.** *If  $N(m_0)$  is a BPP net that is statically reduced, then it is also dynamically reduced.*

*Proof.* A BPP transition  $t$  is such that  $|\bullet t| = 1$ ; therefore, the notions of dynamically enabled transition and statically enabled transition coincide.  $\square$

# Decidable Properties

- Computing  $\text{Net}_d$  and  $\text{Net}_s$  for any finite P/T net system  $N(m_0)$
- **Reachability**: deciding whether a given marking is reachable from the initial marking for a finite P/T net system (complexity: non-primitive recursive).
- **Deadlock**: deciding whether a finite P/T net system has a deadlock, i.e., reaches a marking that does not enable any transition.
- **Liveness**: a transition  $t$  is *live* if for each marking  $m$  reachable from  $m_0$  there exists a marking  $m'$  reachable from  $m$  such that  $t$  is enabled at  $m'$ . The finite P/T net system  $N(m_0)$  is *live* if each of its transitions is live. This problem is decidable.