

Sorting

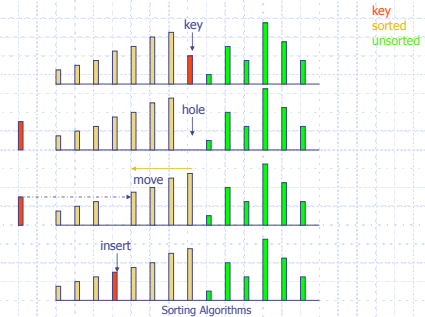
Sorting is to re-arrange an initially unordered collection of keys to produce an ordered collection.

- ◆ Insertion sort
- ◆ Bubble sort
- ◆ Merge sort

Sorting Algorithms

1

Sorting - Insertion sort



Sorting Algorithms

2

Example

```

9| 5 8 1 2
5 9| 8 1 2
5 9| 8 1 2
5 8 9| 1 2
5 8 9| 1 2
1 5 8 9| 2
1 5 8 9| 2
1 5 8 9| 2
1 2 5 8 9|
    
```

Sorting Algorithms

3

Sorting - Insertion sort

◆ Complexity

- For each item
 - Scan $O(n)$
 - Shift up $O(n)$
 - Insert $O(1)$
 - Total $O(n)$
- For n items $O(n^2)$

$O(n)$

$O(n)$

$O(1)$

$O(n)$

Sorting Algorithms

4

```

void InsertionSort(SortingArray A) {
    /* assume: typedef enum {false, true} Boolean; has been declared */
    int i;
    KeyType K;
    Boolean NotFinished;
    /* For each i in the range 1:n-1, let key K be the key, A[i]. Then */
    /* insert K into the subarray A[0:i-1] in ascending order */
    for (i = 1; i < n; ++i) { /* scanning */
        K = A[i];
        j = i;
        NotFinished = (A[j-1] > K);
        while (NotFinished) {
            A[j] = A[j-1]; /* move A[j-1] one space to the right */
            j--;
            if (j > 0) {
                NotFinished = (A[j-1] > K);
            } else {
                NotFinished = false;
            }
        }
        /* insert key K into hole opened up by moving previous keys to the right */
        A[j] = K;
    }
}
    
```

Sorting Algorithms

5

Sorting – Bubble sort

◆ From the first element

- Exchange pairs if they're out of order
 - ◆ Last one must now be the largest
- Repeat from the first to $n-1$
- Stop when you have only one element to check

Sorting Algorithms

6

Example

9	5	8	1	2		1	2		5	8	9
5	9	8	1	2		1	2		5	8	9
5	8	9	1	2		1	2		5	8	9
5	8	1	9	2							
5	8	1	2		9						
5	8	1	2		9						
5	1	8	2		9						
5	1	2		8	9						
1	5	2		8	9						

Sorting Algorithms

7

Bubble Sort

```
/* Bubble sort for integers */
#define SWAP(a,b) { int t; t=a; a=b; b=t; }
void bubble( int a[], int n ) {
    int i, j;
    for(i=0; i<n; i++) { /* n passes thru the array */
        /* From start to the end of unsorted part */
        for(j=1; j<(n-i); j++) {
            /* If adjacent items out of order, swap */
            if( a[j-1]>a[j] ) SWAP(a[j-1],a[j]);
        }
    }
}
```

$O(1)$ statement

Inner loop
 $n-1, n-2, n-3, \dots, 1$ iterations

Sorting Algorithms

8

```
void BubbleSort(SortingArray A) {
    int i;
    KeyType Temp;
    Boolean NotDone;
    do {
        NotDone = false; /* initially, assume NotDone is false */
        for (i = 0; i < n-1; ++i) {
            if (A[i] > A[i+1]) { /* the pair (A[i], A[i+1]) is out of order */
                /* exchange A[i] and A[i+1] to put them in sorted order */
                Temp = A[i]; A[i] = A[i+1]; A[i+1] = Temp;
                /* if you swapped you need another pass */
                NotDone = true;
            }
        }
    } while (NotDone); /* NotDone == false iff no pair of keys was */
    /* swapped on the last pass */
}
```

Sorting Algorithms

9

Sorting - Simple

- ◆ Bubble sort
 - $O(n^2)$
 - Very simple code
- ◆ Insertion sort
 - Slightly better than bubble sort
 - Fewer comparisons
 - Also $O(n^2)$
- ◆ But HeapSort is $O(n \log n)$
- ◆ Where would you use bubble or insertion sort?

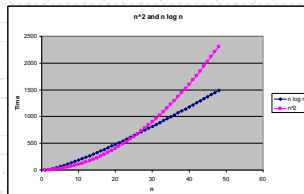
Sorting Algorithms

10

Simple Sorts

◆ Bubble Sort or Insertion Sort

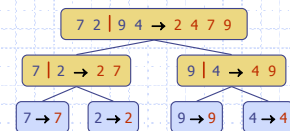
- Use when n is small
- Simple code compensates for low efficiency!



Sorting Algorithms

11

Merge Sort



Divide-and-Conquer

- ◆ **Divide-and-conquer** is a general algorithm design paradigm:
 - **Divide**: divide the input data S in two disjoint subsets S_1 and S_2
 - **Recur**: solve the subproblems associated with S_1 and S_2
 - **Conquer**: combine the solutions for S_1 and S_2 into a solution for S
- ◆ The base case for the recursion are subproblems of size 0 or 1
- ◆ **Merge-sort** is a sorting algorithm based on the divide-and-conquer paradigm
 - ◆ Like heap-sort
 - It uses a comparator
 - It has $O(n \log n)$ running time
 - ◆ Unlike heap-sort
 - It does not use an auxiliary priority queue
 - It accesses data in a sequential manner (suitable to sort data on a disk)

Sorting Algorithms

13

Merge-Sort

- ◆ Merge-sort on an input sequence S with n elements consists of three steps:
 - **Divide**: partition S into two sequences S_1 and S_2 of about $n/2$ elements each
 - **Recur**: recursively sort S_1 and S_2
 - **Conquer**: merge S_1 and S_2 into a unique sorted sequence

```
function mergeSort(S, C, n)
    Input list S with n
    elements, comparator C
    Output list S sorted
    according to C
    if (n > 1) {
        (S1, S2) = partition(S, n/2)
        mergeSort(S1, C, n/2)
        mergeSort(S2, C, n/2)
        S = merge(S1, S2)
    }
```

Sorting Algorithms

14

Merging Two Sorted Sequences

- ◆ The conquer step of merge-sort consists of merging two sorted sequences A and B into a sorted sequence S containing the union of the elements of A and B
- ◆ Merging two sorted sequences, each with $n/2$ elements and implemented by means of a doubly linked list, takes $O(n)$ time

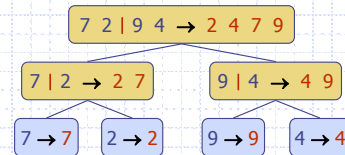
```
function merge(A, B)
    Input list A and B with
    n/2 elements each
    Output sorted list of A ∪ B
    S = empty list
    while (!isEmpty(A) ∧ !isEmpty(B))
        if (first_element(A) < first_element(B))
            insertLast(S, remove_first(A));
        else
            insertLast(S, remove_first(B));
    while (!isEmpty(A))
        insertLast(S, remove_first(A));
    while (!isEmpty(B))
        insertLast(S, remove_first(B));
    return S
```

Sorting Algorithms

15

Merge-Sort Tree

- ◆ An execution of merge-sort is depicted by a binary tree
 - each node represents a recursive call of merge-sort and stores
 - unsorted sequence before the execution and its partition
 - sorted sequence at the end of the execution
 - the root is the initial call
 - the leaves are calls on subsequences of size 0 or 1

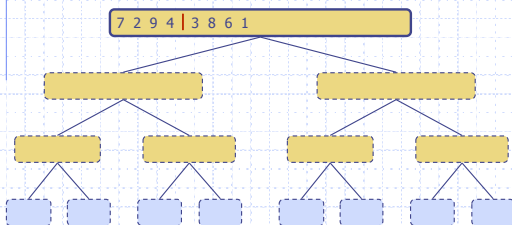


Sorting Algorithms

16

Execution Example

- ◆ Partition

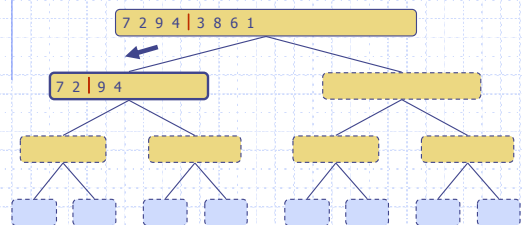


Sorting Algorithms

17

Execution Example (cont.)

- ◆ Recursive call, partition

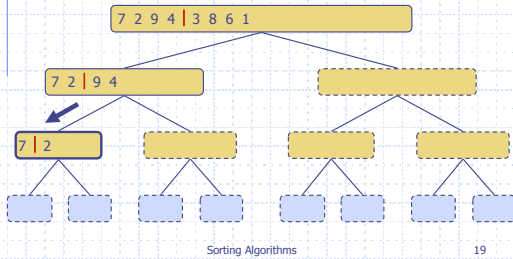


Sorting Algorithms

18

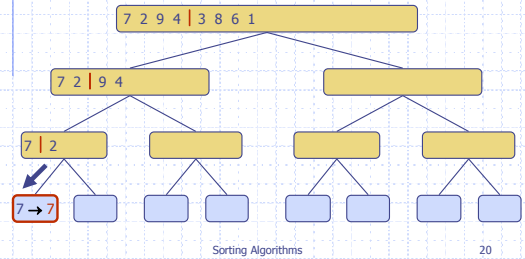
Execution Example (cont.)

Recursive call, partition



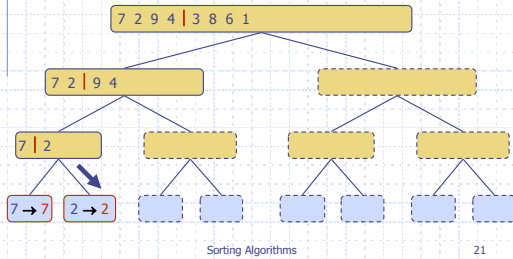
Execution Example (cont.)

Recursive call, base case



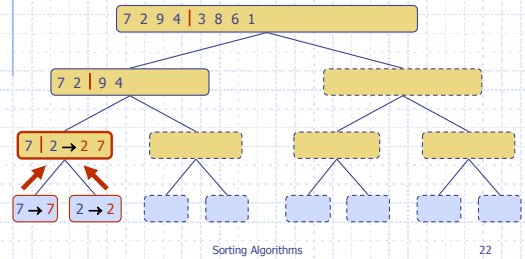
Execution Example (cont.)

Recursive call, base case



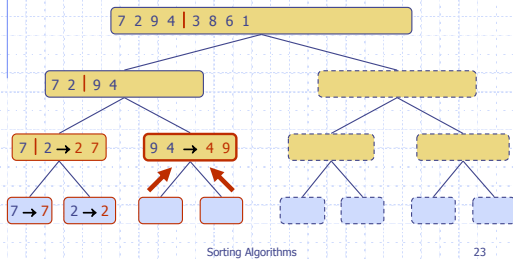
Execution Example (cont.)

Merge



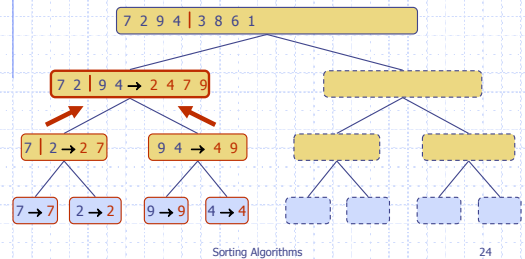
Execution Example (cont.)

Recursive call, ..., base case, merge



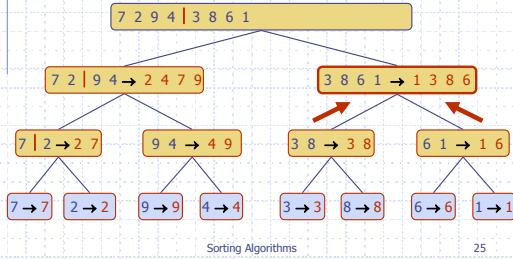
Execution Example (cont.)

Merge



Execution Example (cont.)

Recursive call, ..., merge, merge

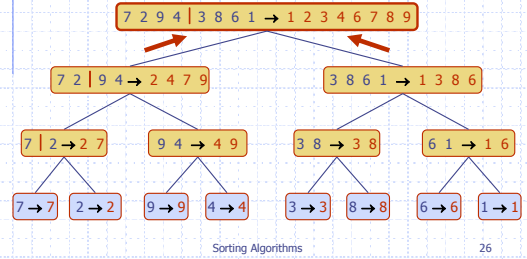


Sorting Algorithms

25

Execution Example (cont.)

Merge



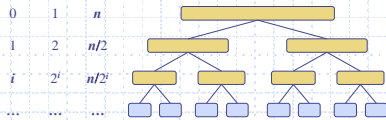
Sorting Algorithms

26

Analysis of Merge-Sort

- The height h of the merge-sort tree is $O(\log n)$
 - at each recursive call we divide in half the sequence,
- The overall amount of work done at the nodes of depth i is $O(n)$
 - we partition and merge 2^i sequences of size $n/2^i$
 - we make 2^{i-1} recursive calls
- Thus, the total running time of merge-sort is $O(n \log n)$

depth #seqs size



Sorting Algorithms

27

Summary of Sorting Algorithms

Algorithm	Time	Notes
insertion-sort	$O(n^2)$	<ul style="list-style-type: none"> slow in-place for small data sets ($< 1K$)
bubble-sort	$O(n^2)$	<ul style="list-style-type: none"> slow in-place for small data sets ($< 1K$)
heap-sort	$O(n \log n)$	<ul style="list-style-type: none"> fast in-place for large data sets
merge-sort	$O(n \log n)$	<ul style="list-style-type: none"> fast for large data sets

Sorting Algorithms

28