Liquid Ensemble Selection for Continual Learning

Carter Blair, Ben Armstrong, Kate Larson



Outline

- I.Intro and Motivation
- 2. Liquid Democracy
- 3. Our Approach
- 4. Results
- 5. Future Directions



Traditional machine learning

Training

Deployment



Traditional machine learning

Training

Deployment

The world is non-stationary

Training

Deployment

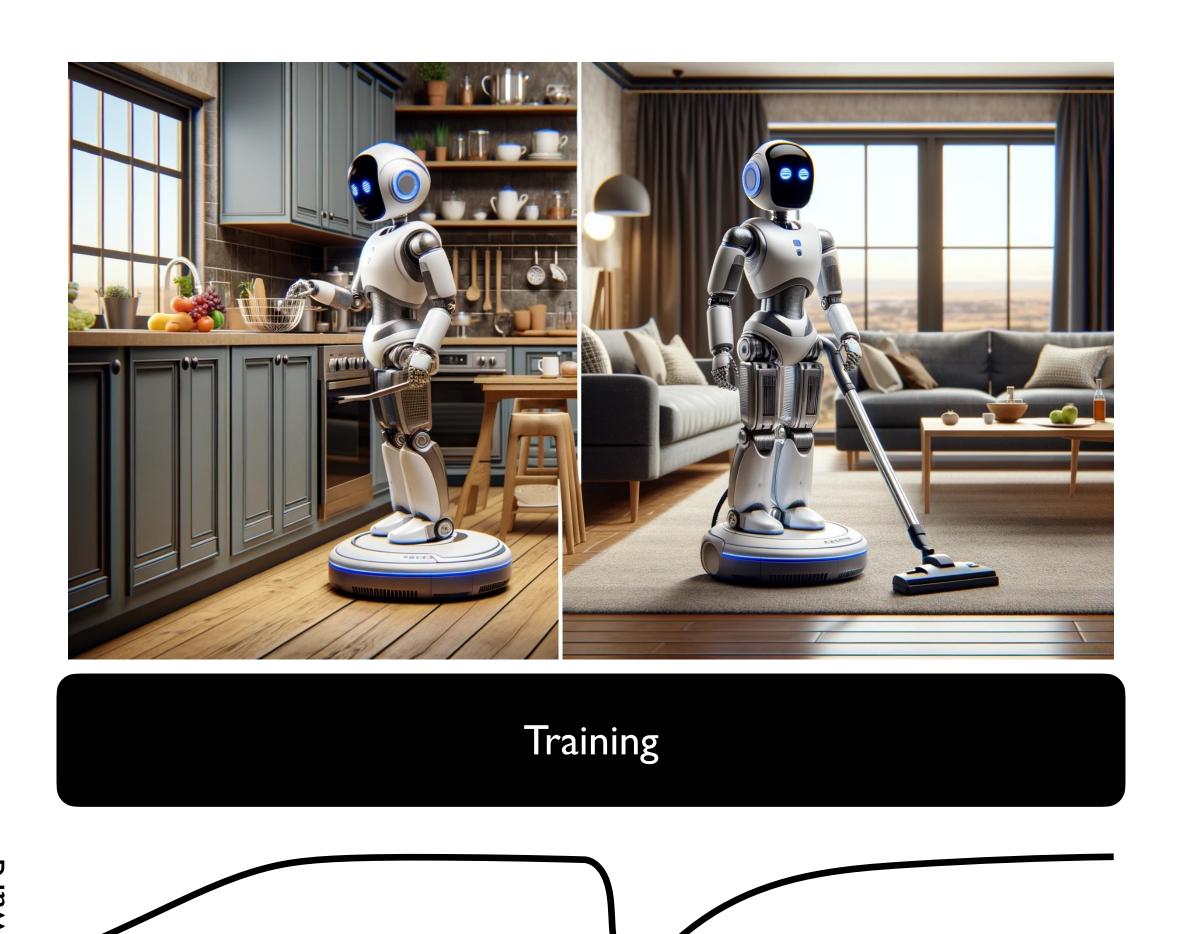




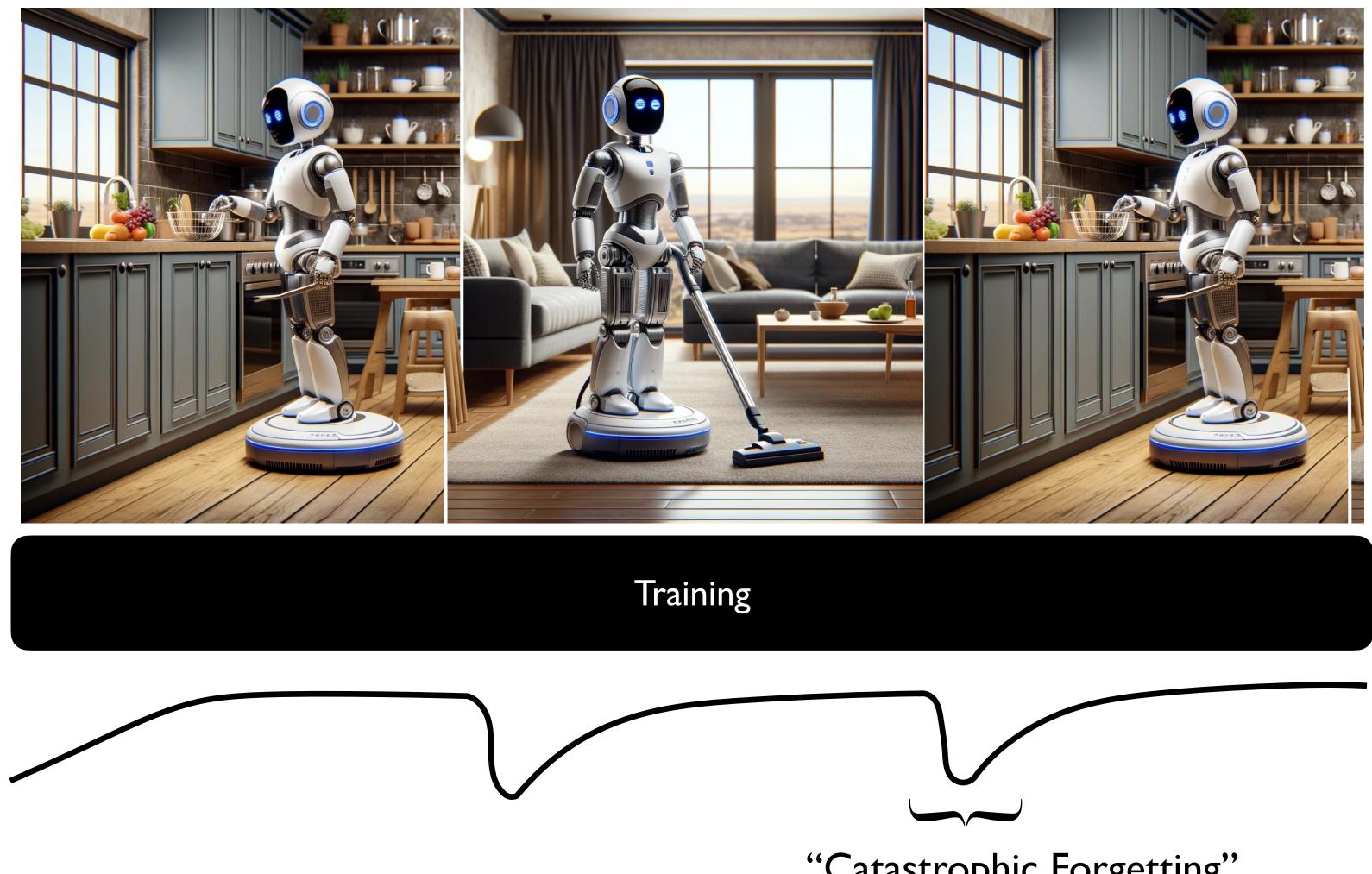






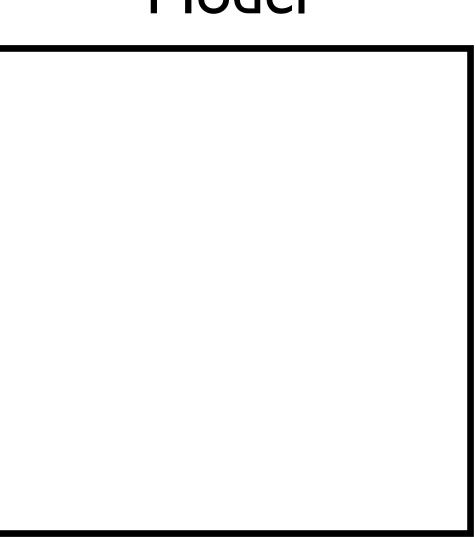








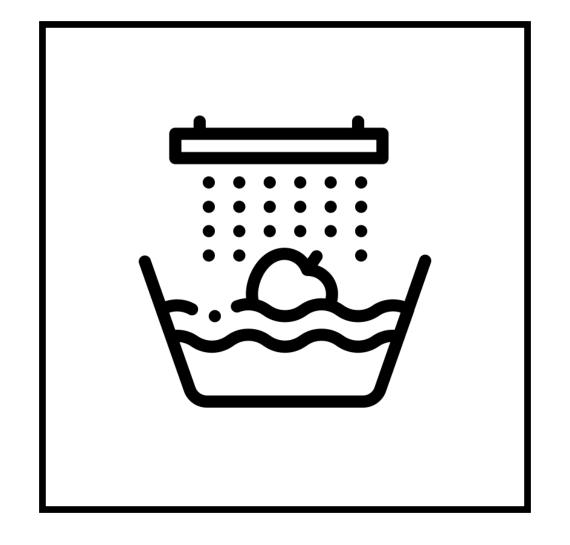






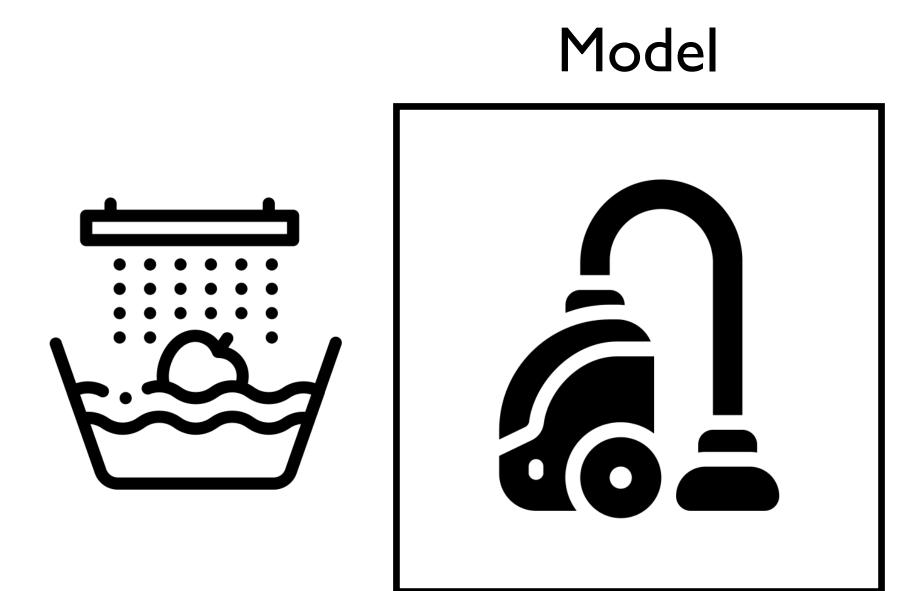


Model











Continual Learning

Setting: Infinite stream of non-stationary data

Goal: Accumulate knowledge without forgetting what's already been learned



Our Approach

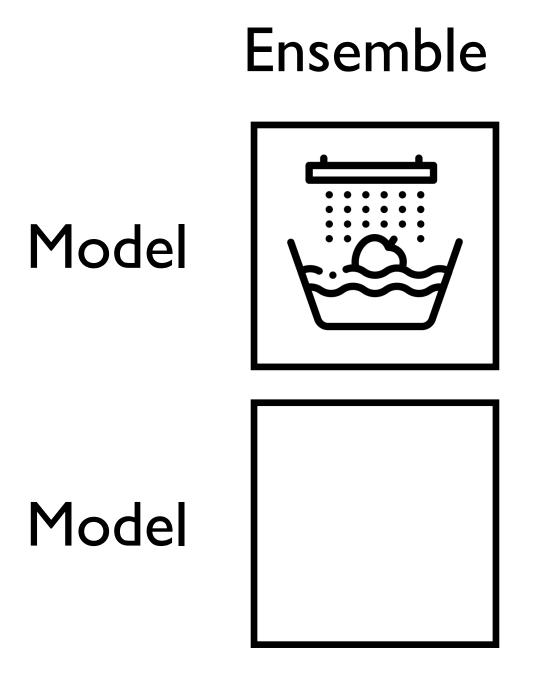


Allow models to acquire new knowledge without forgetting old knowledge by selecting which members of an ensemble are learning at any given time





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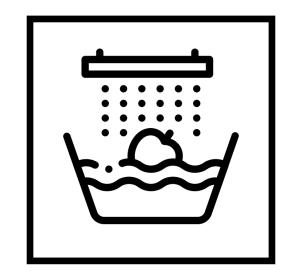




Allow models to acquire new knowledge without forgetting old knowledge by selecting which members of an ensemble are learning at any given time

Ensemble

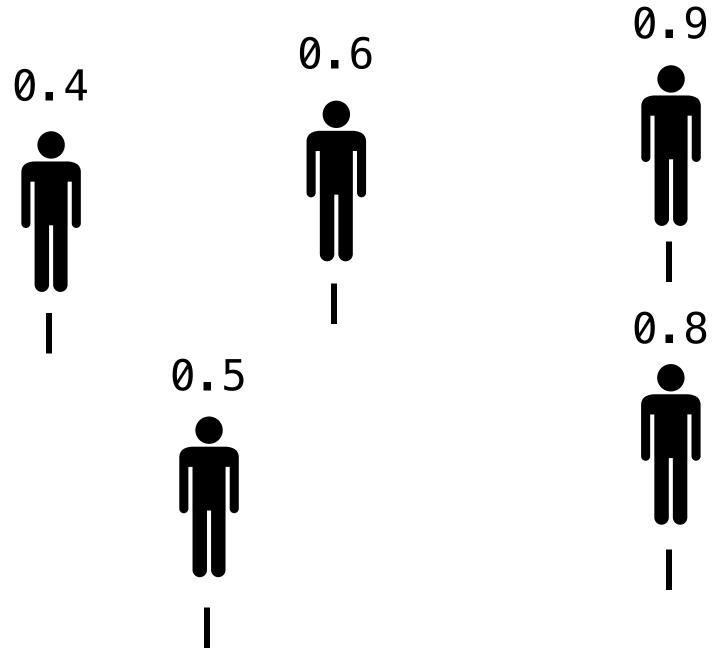
Model

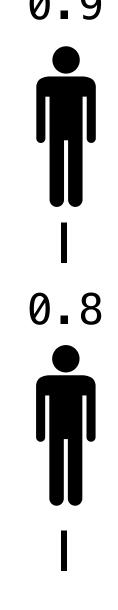


Model

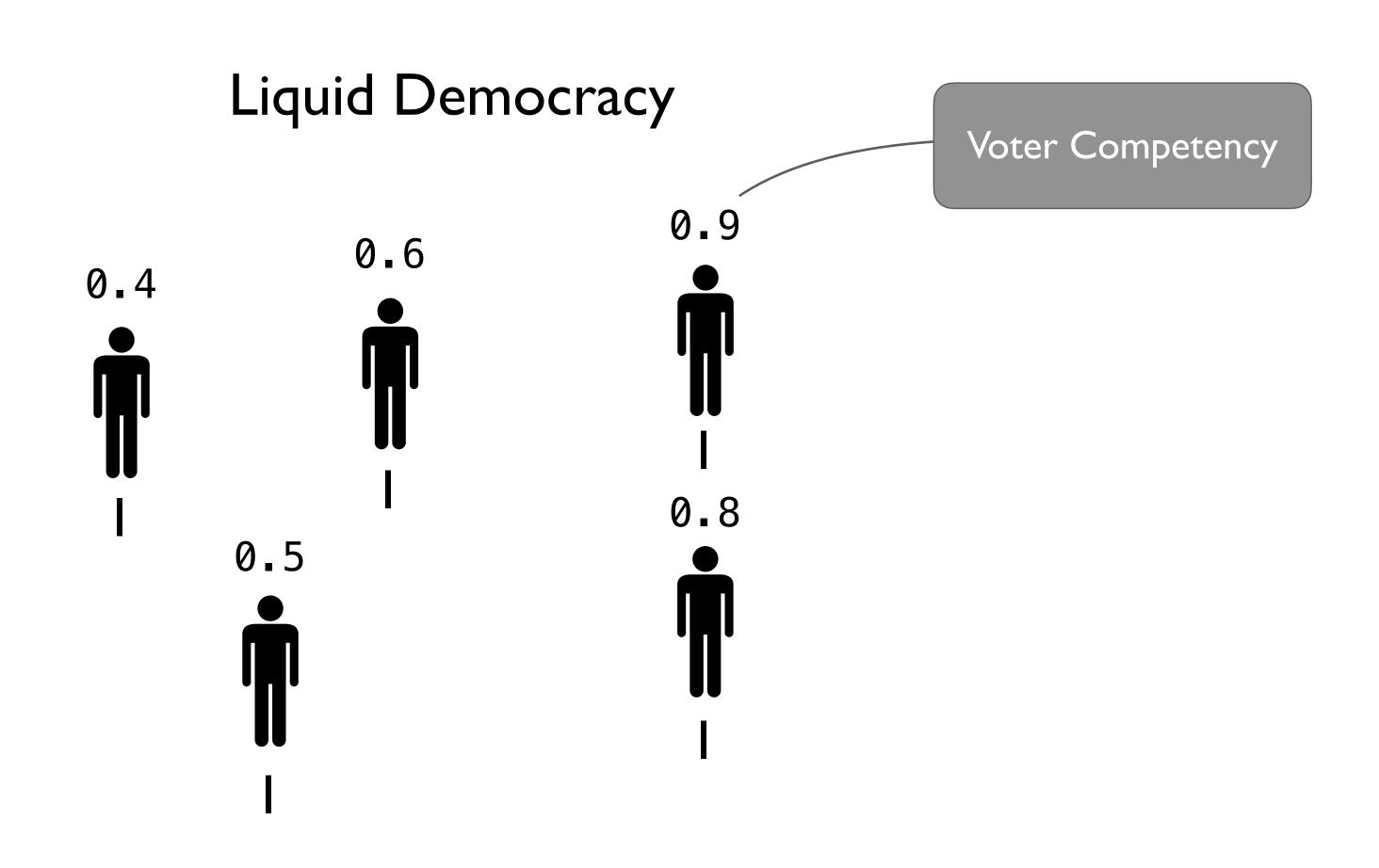




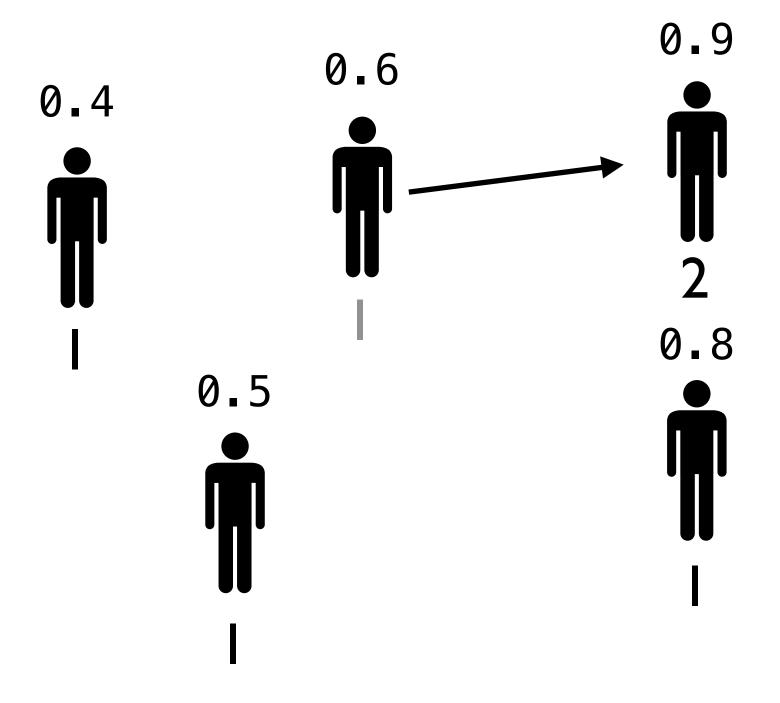




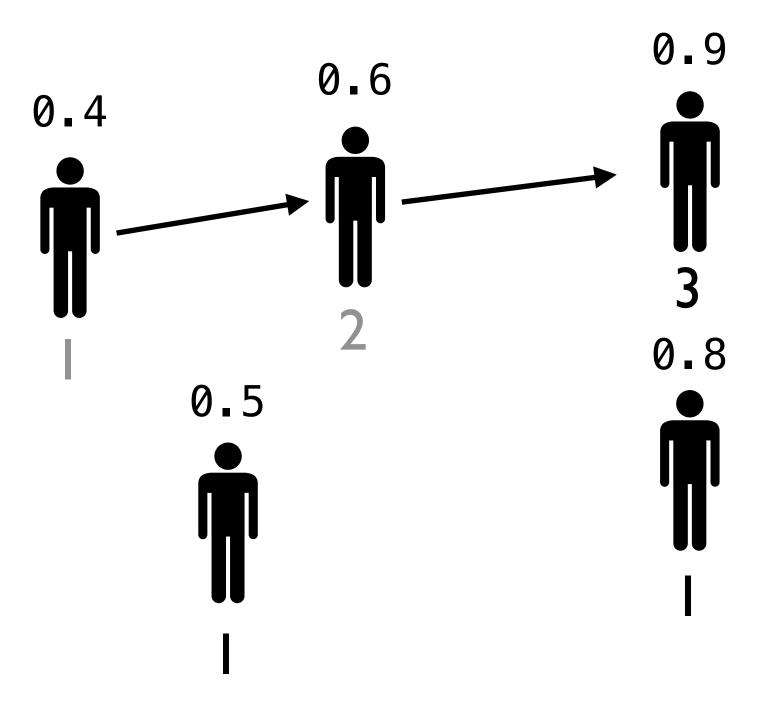




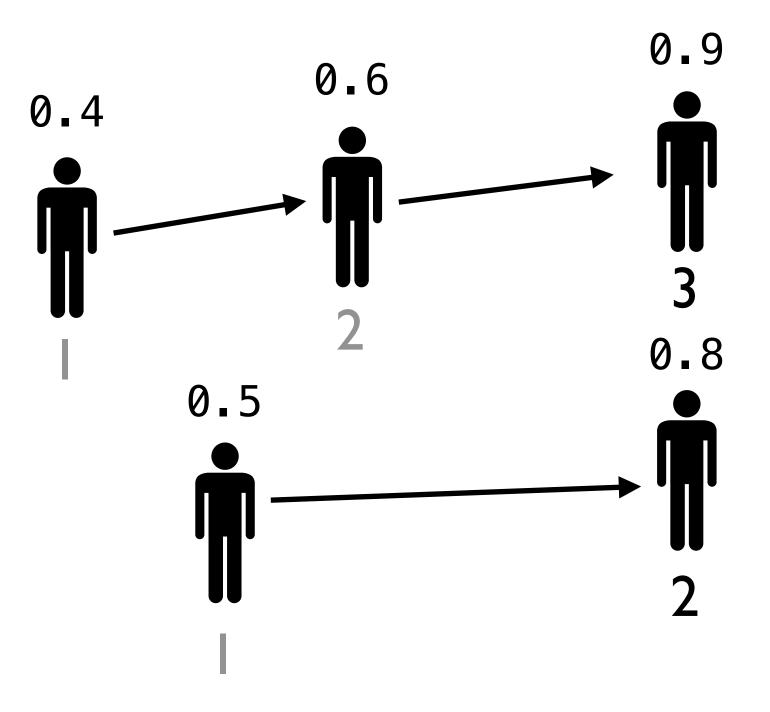




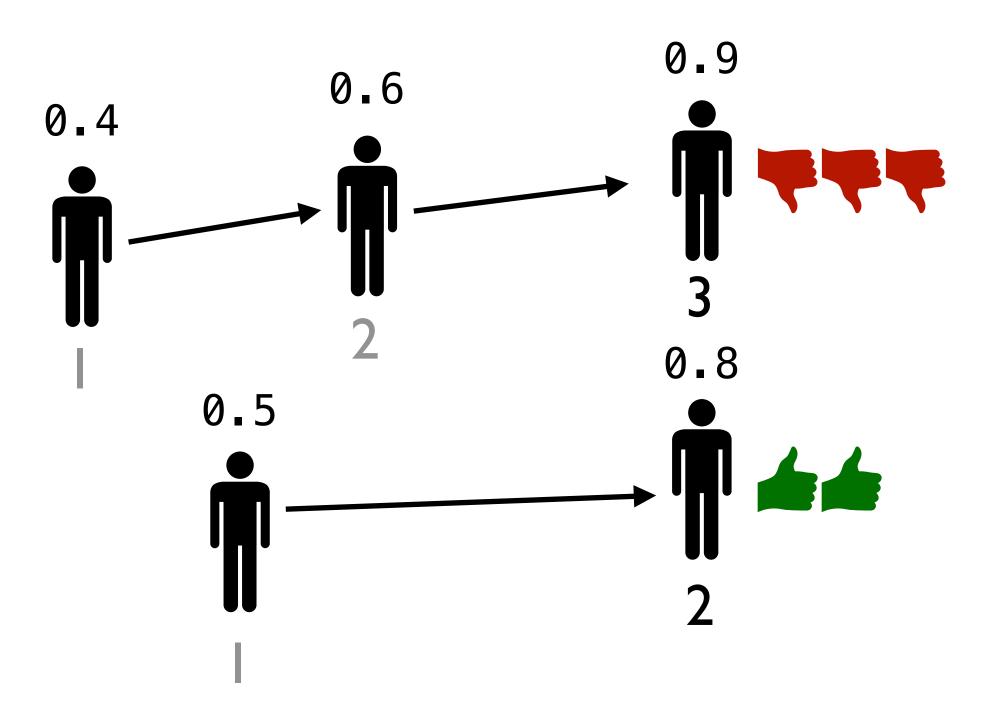




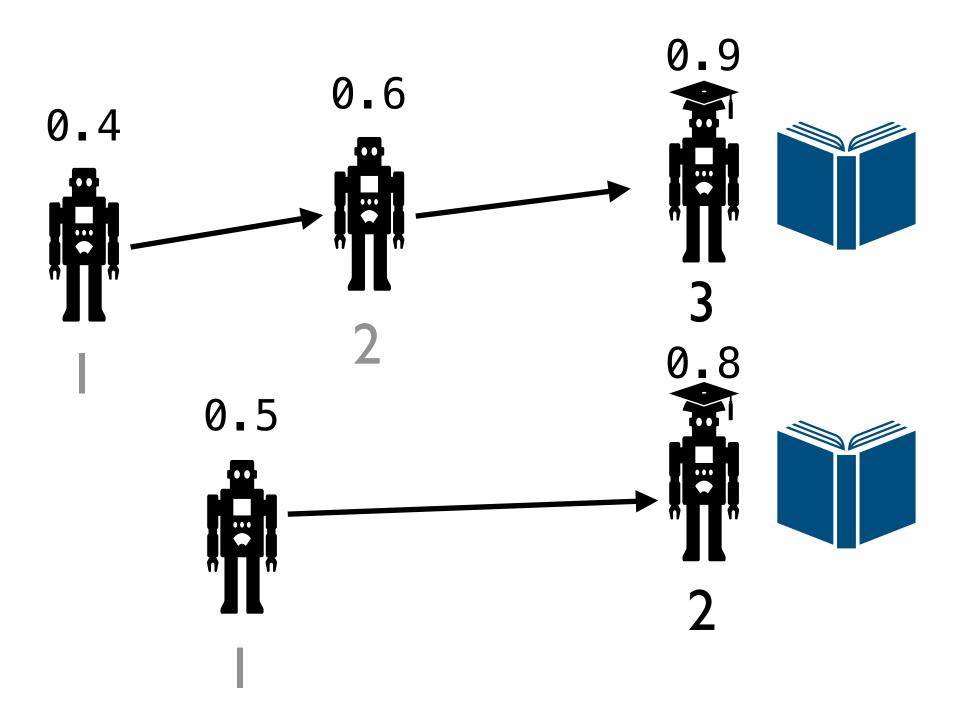




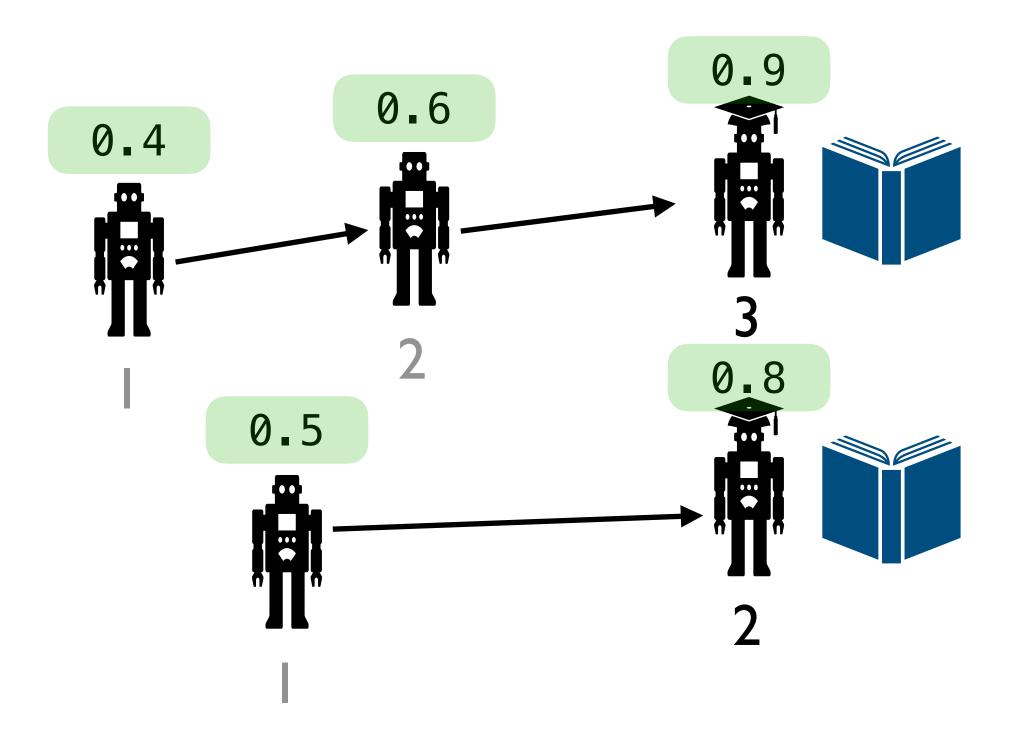




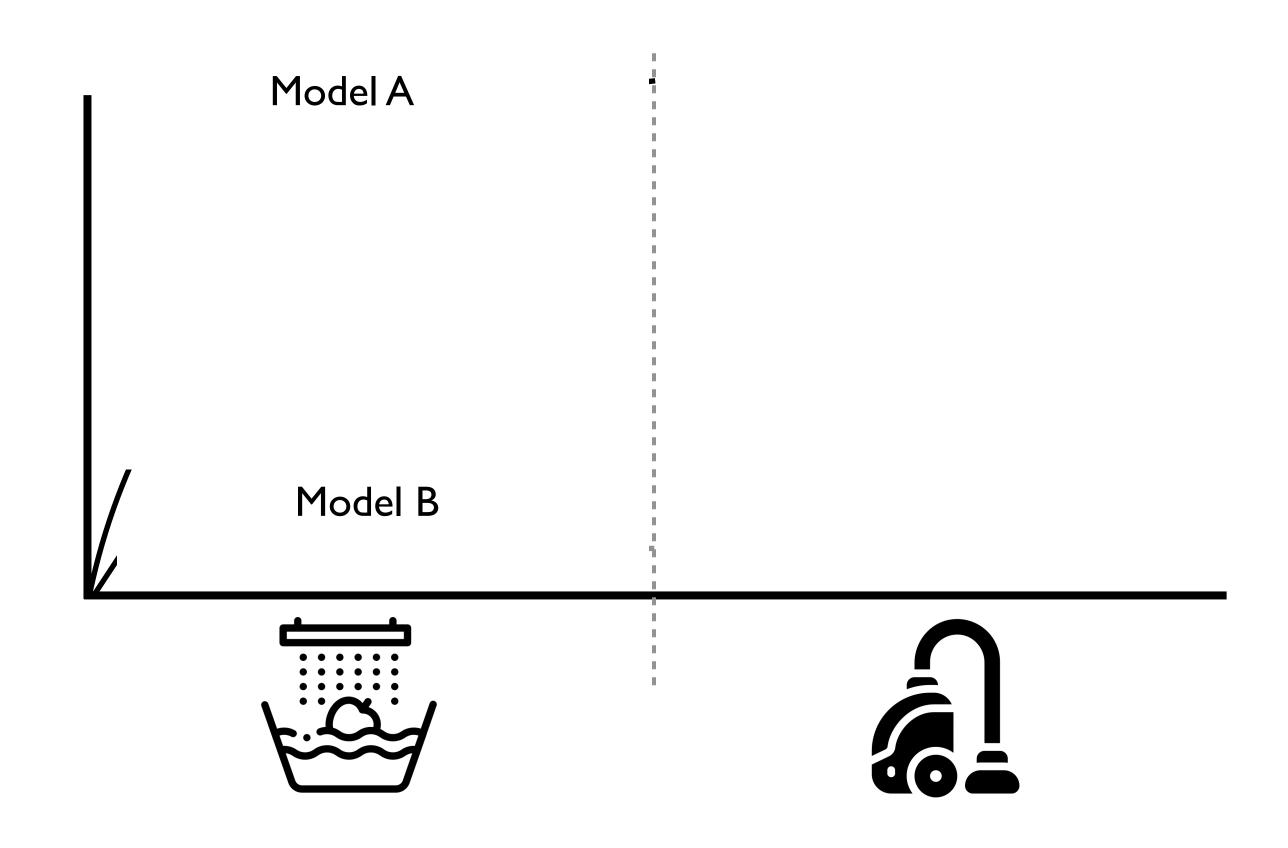




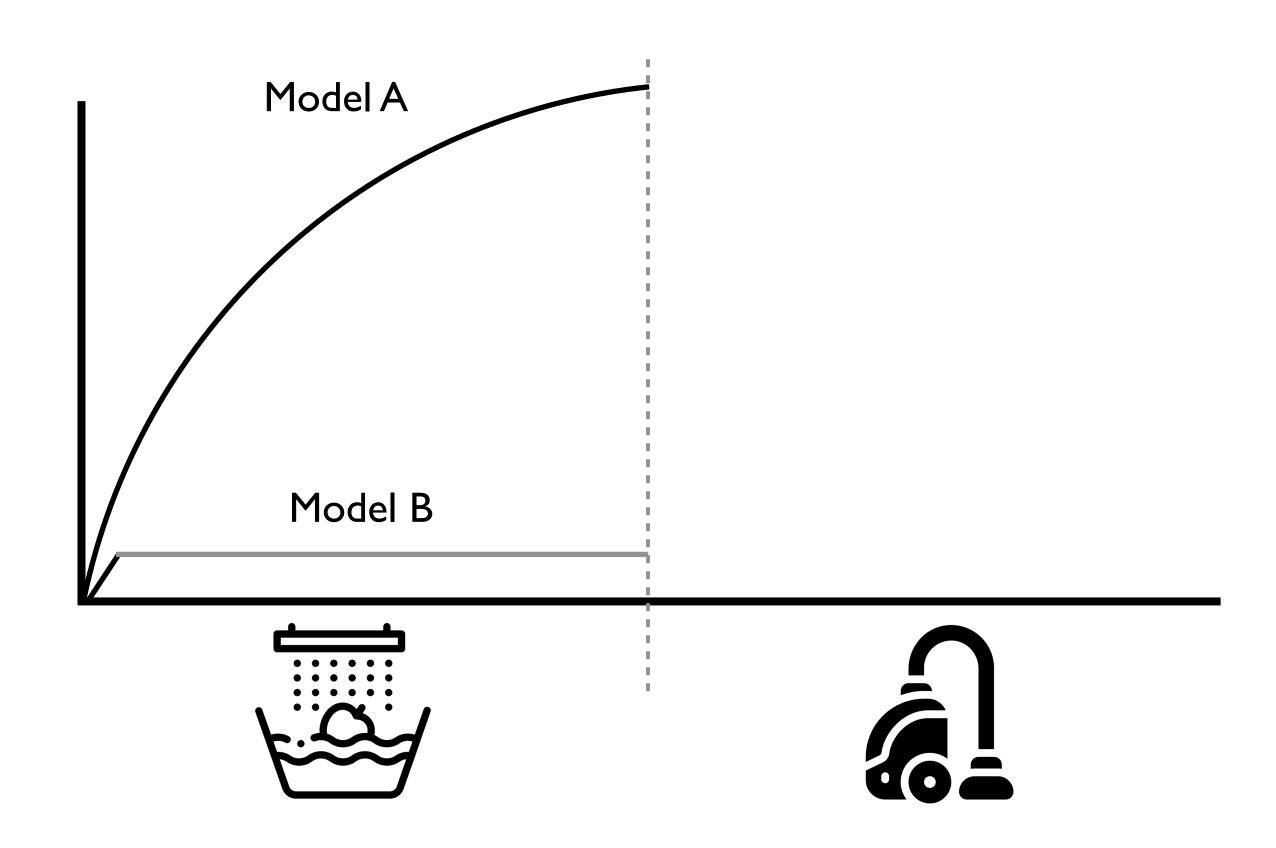




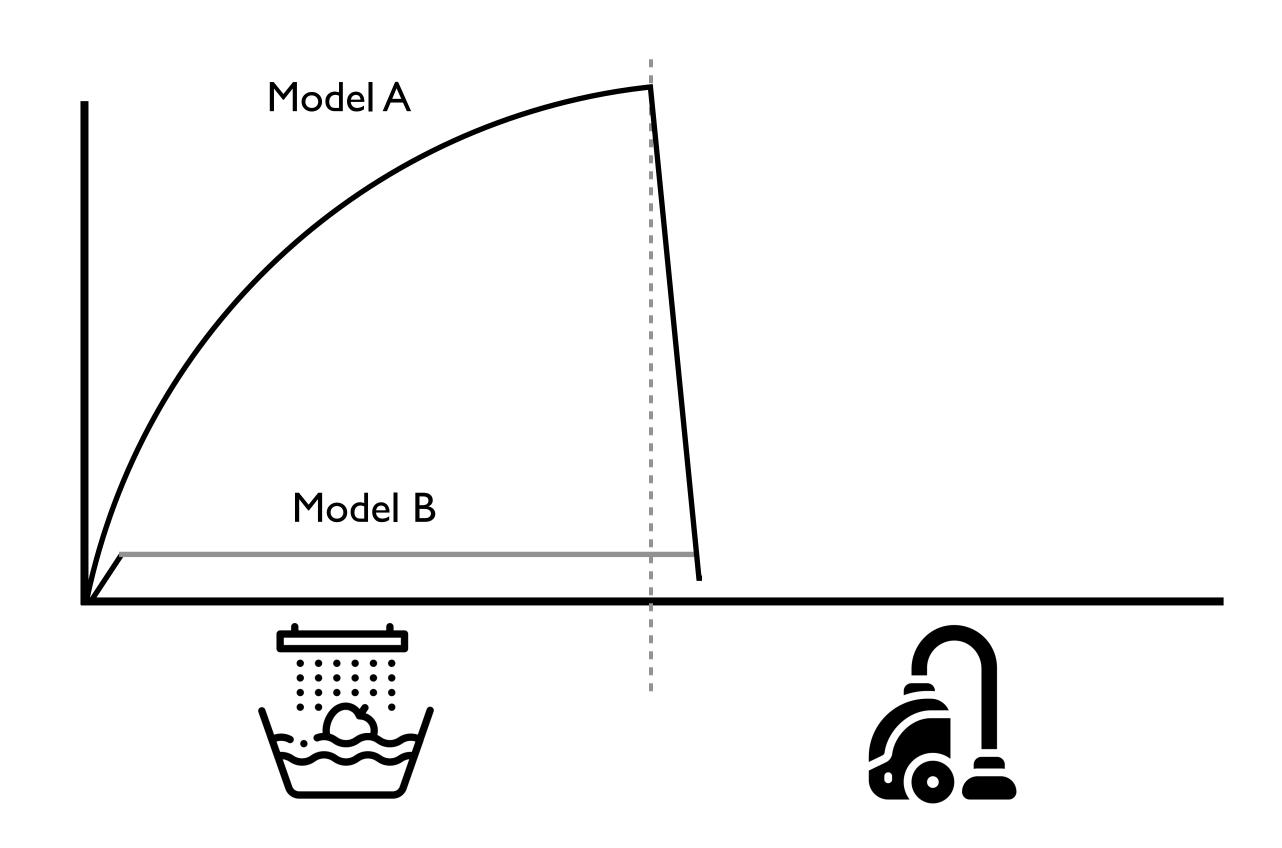




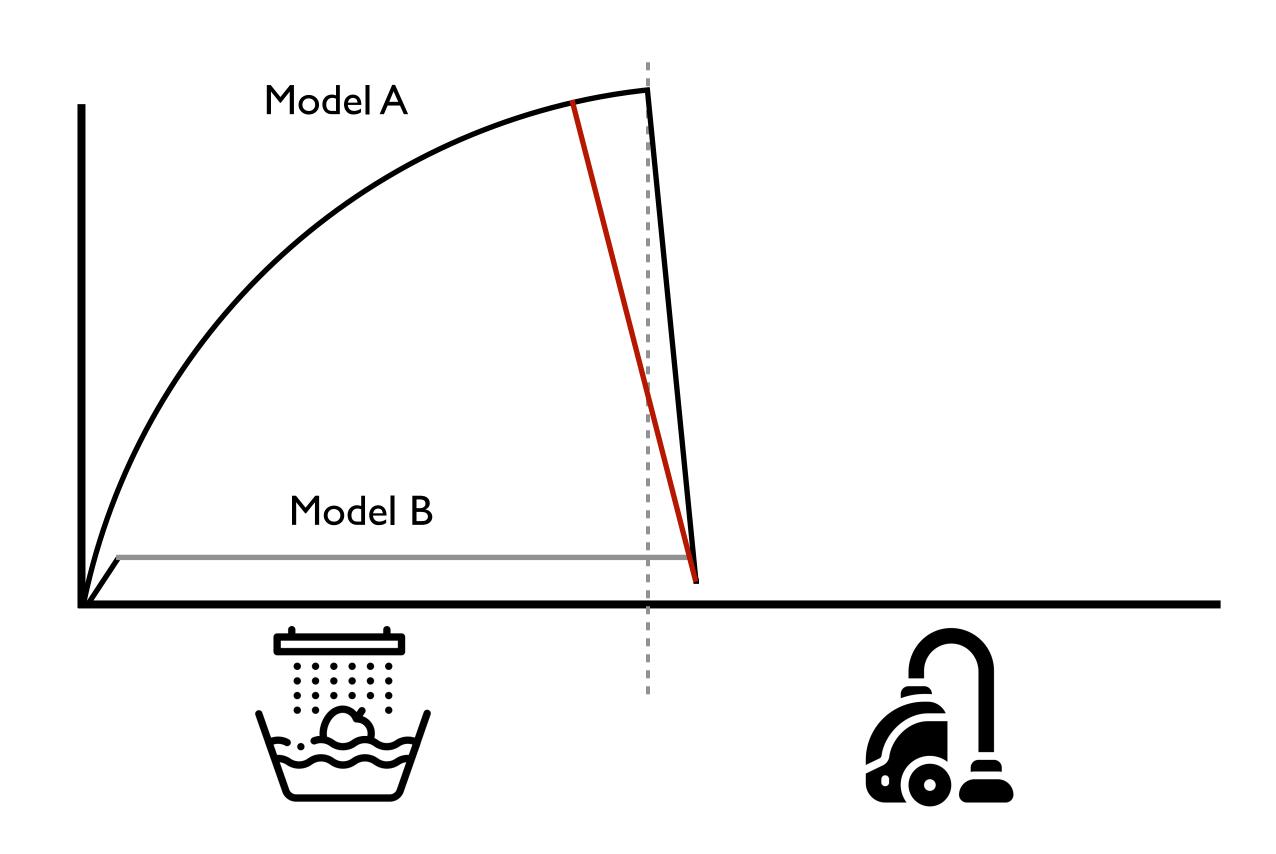




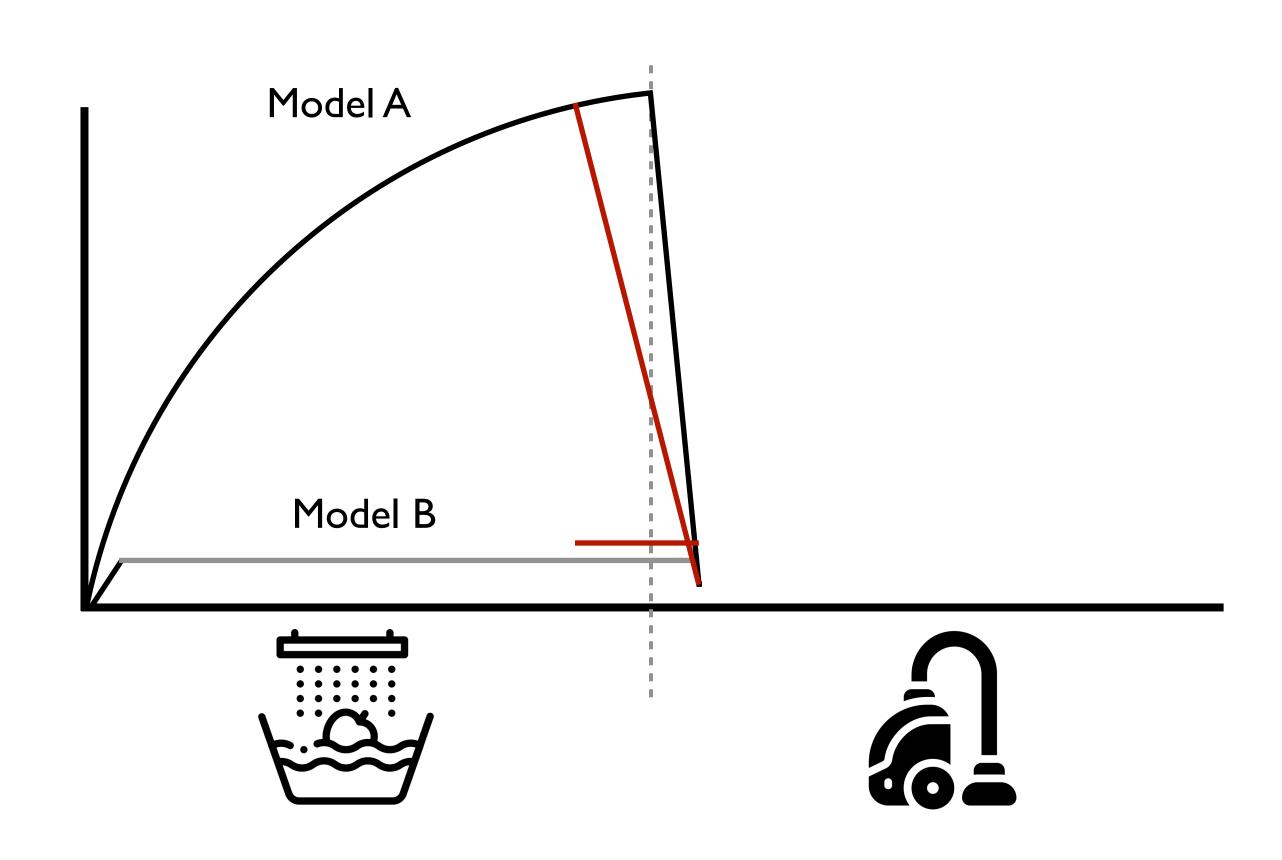




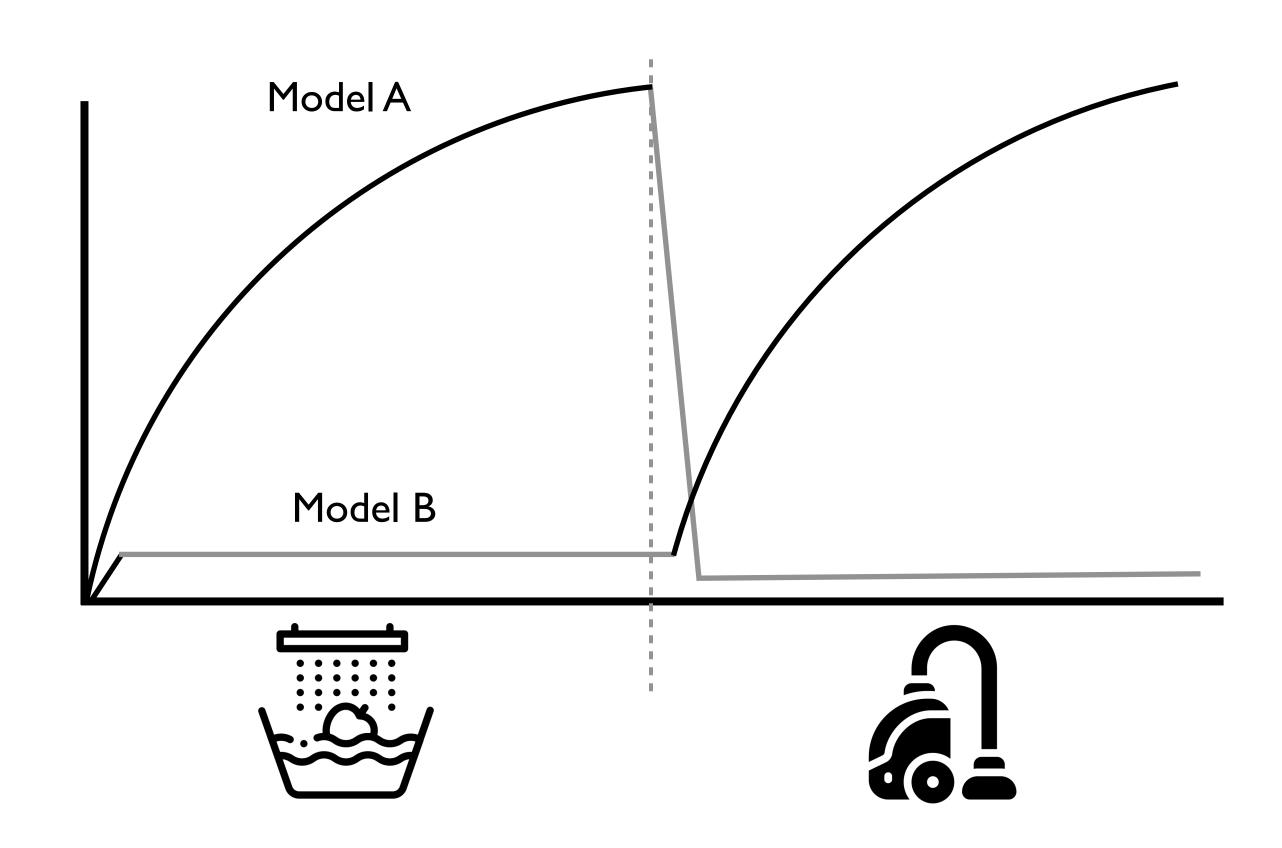




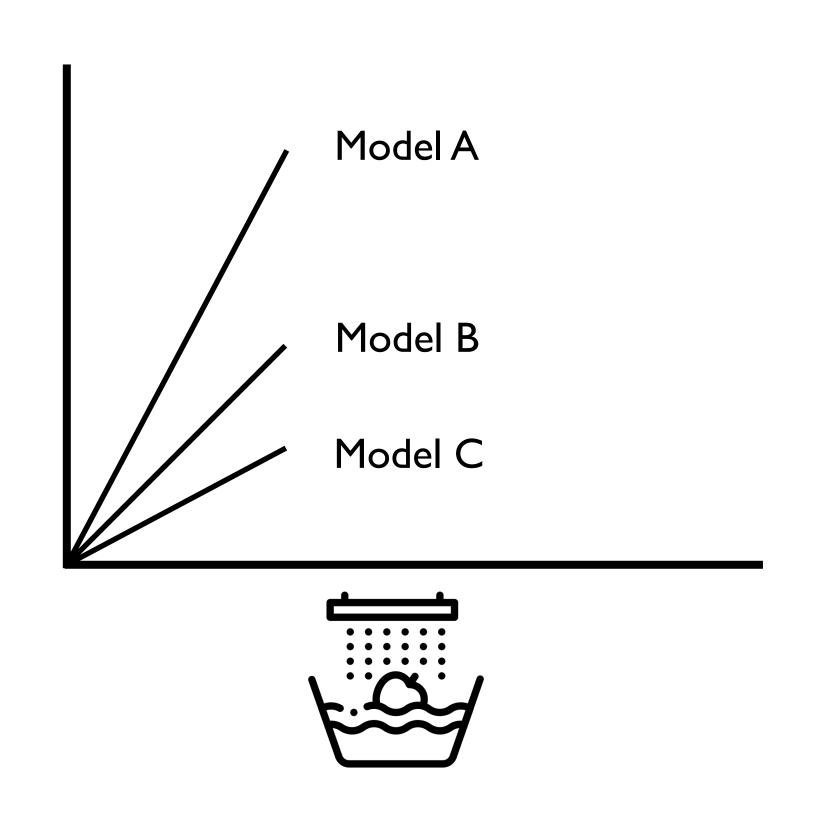










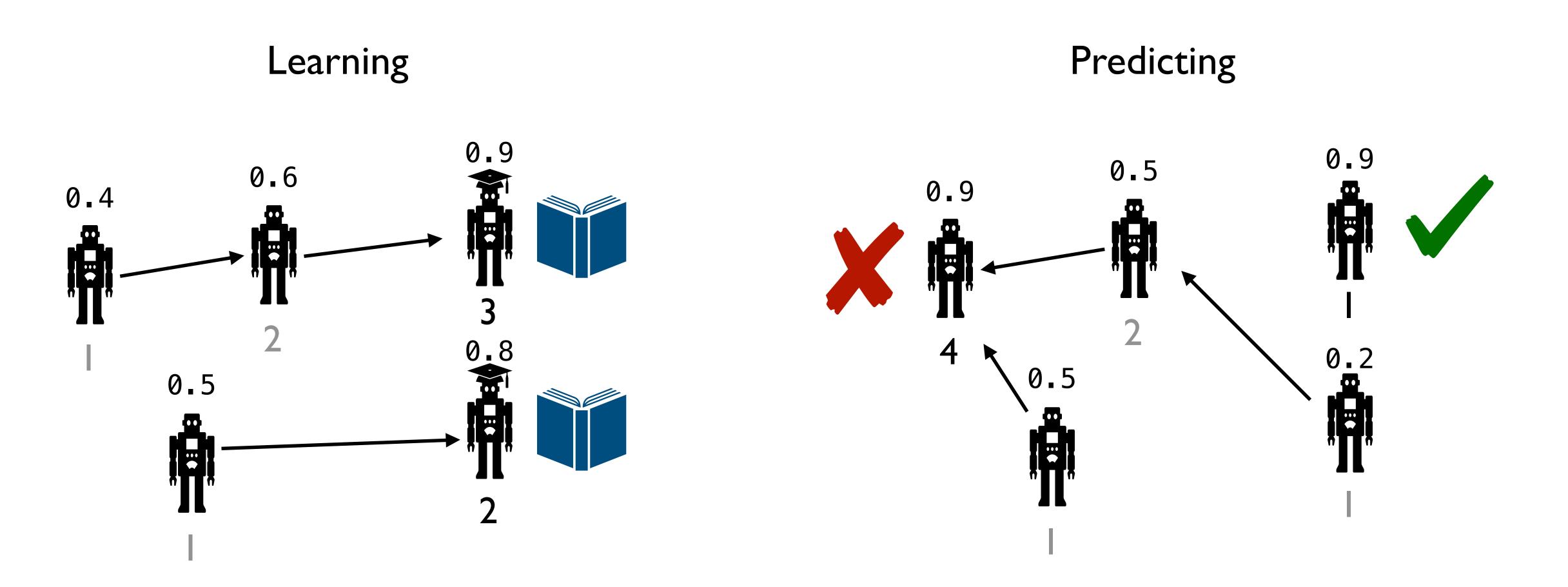


- Neural networks lose plasticity over time
- In expectation, models that have learned more will have a lower learning rate (less plasticity)
- We should delegate the learning of new tasks to models that have learned the least

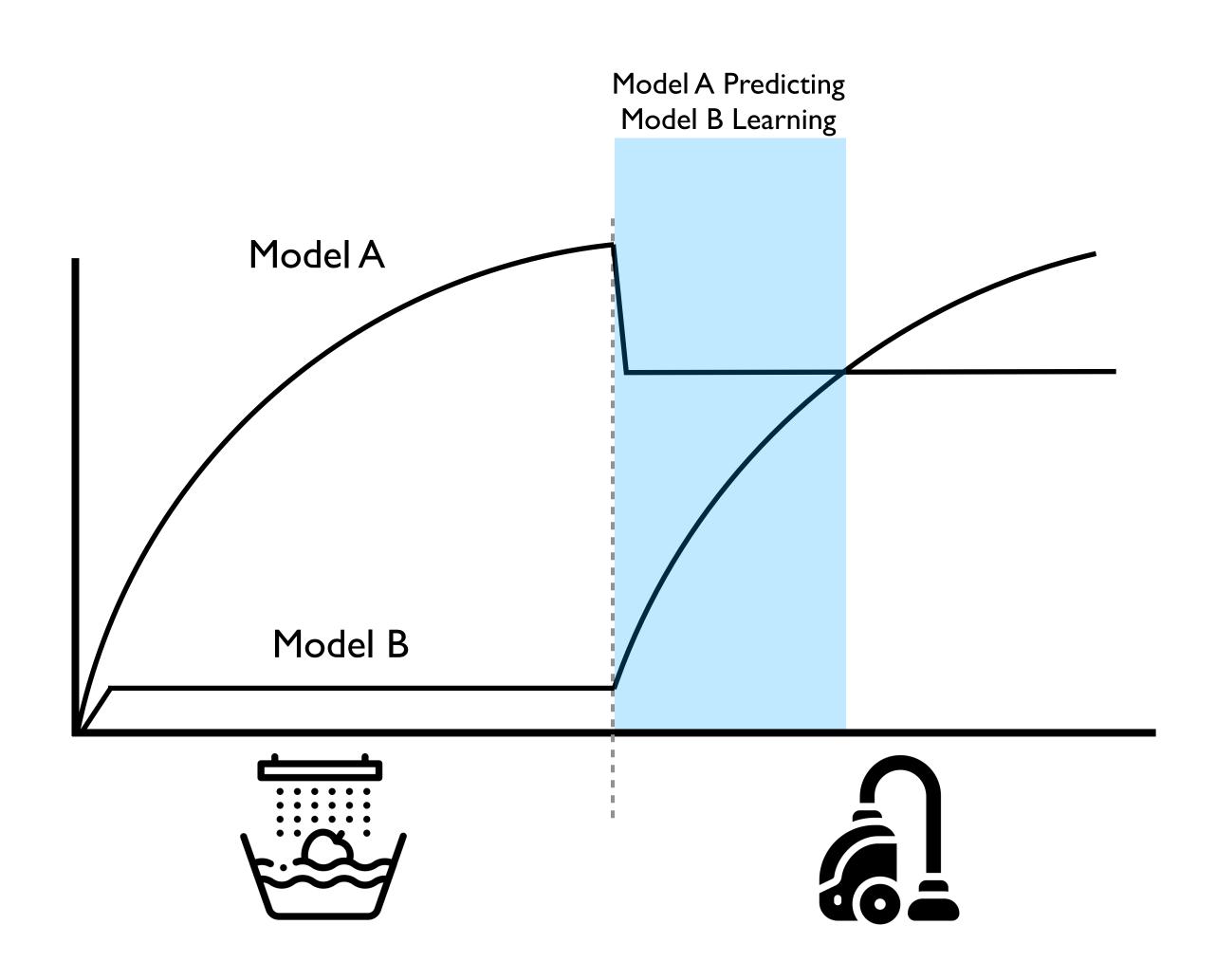
Lyle, Clare, Zeyu Zheng, Evgenii Nikishin, Bernardo Avila Pires, Razvan Pascanu, and Will Dabney. "Understanding Plasticity in Neural Networks." In International Conference on Machine Learning, pp. 23190-23211. PMLR, 2023.



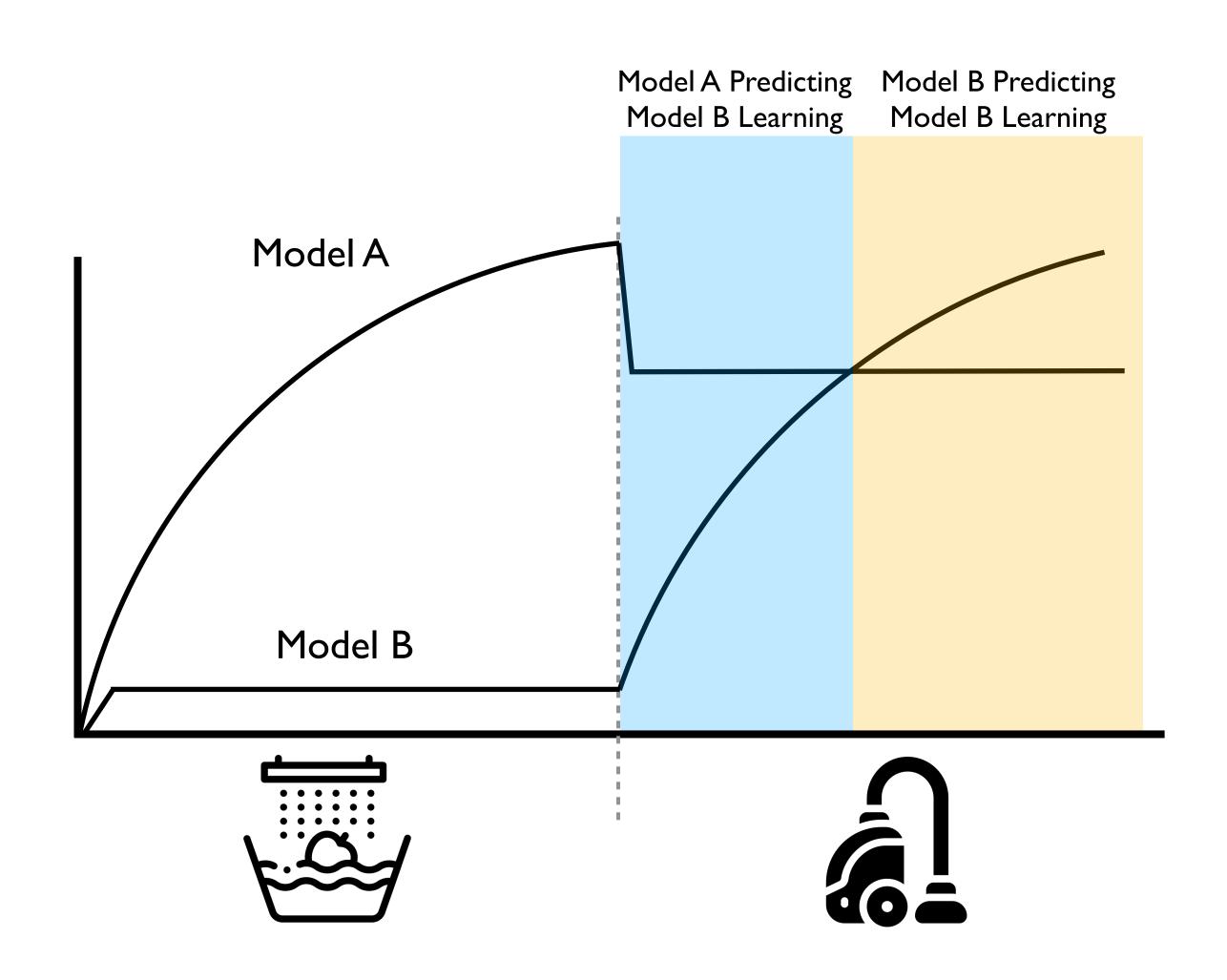














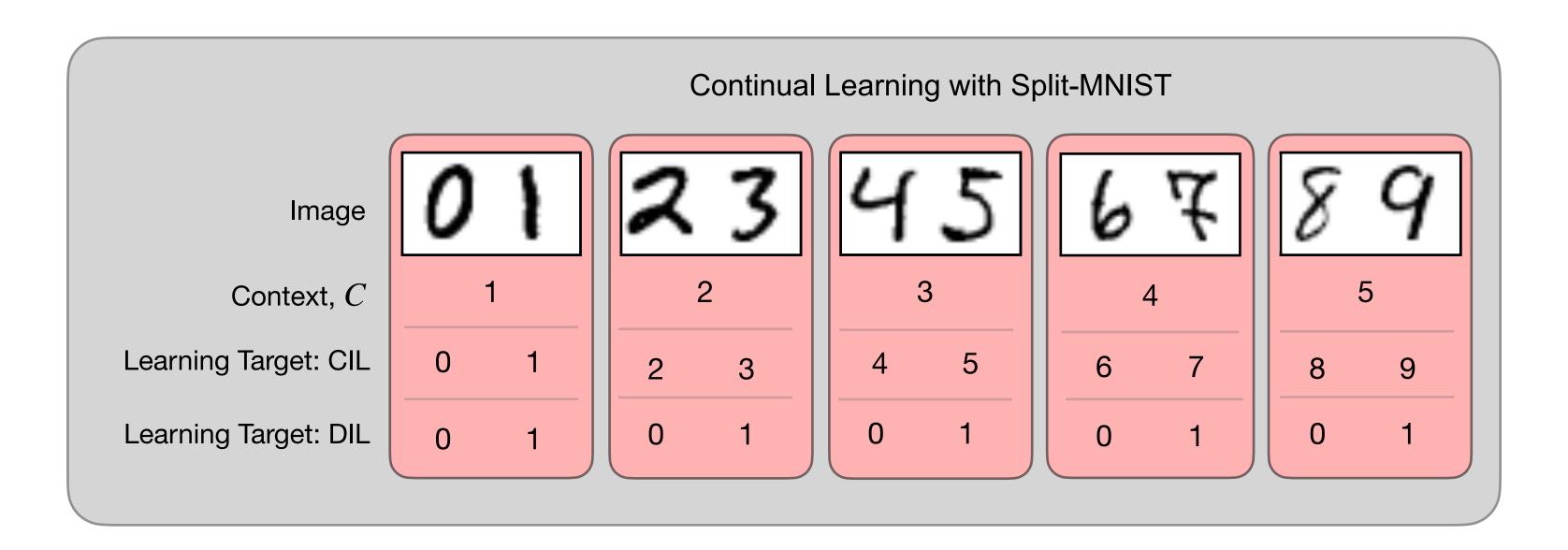
WATERLOO

Liquid Ensemble Selection

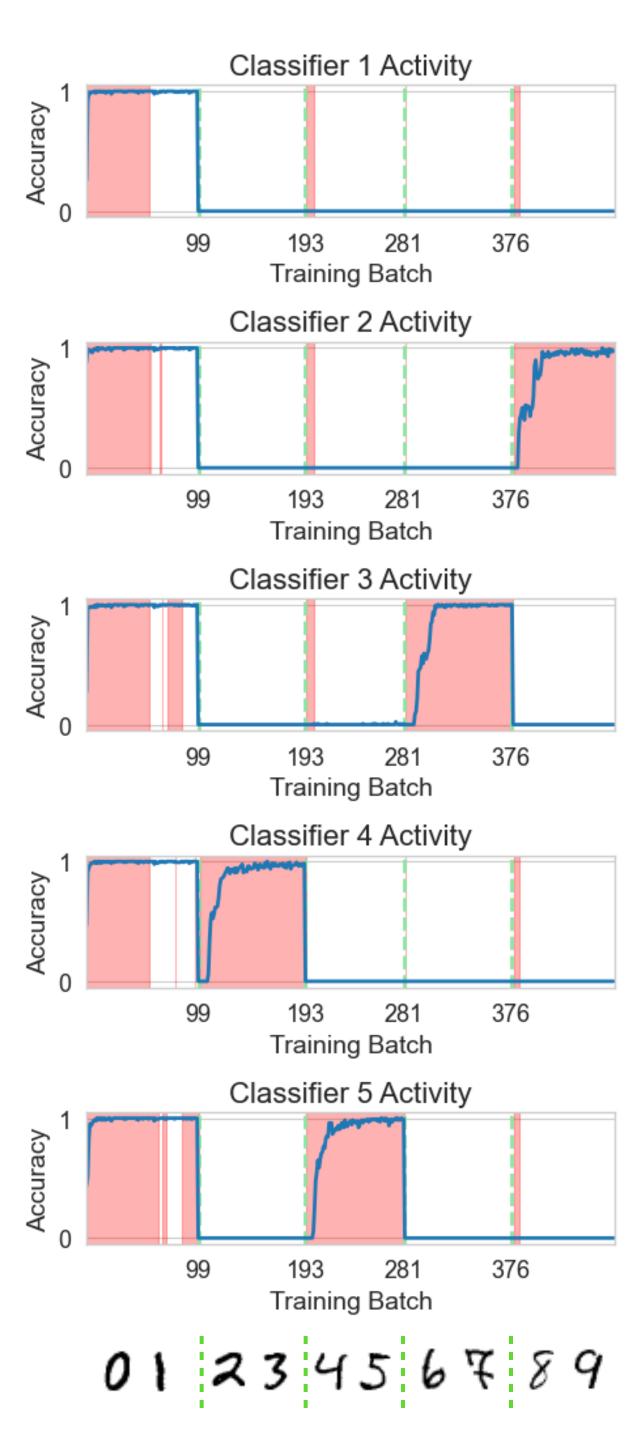
Learning Predicting 0.5 0.6 0.9 0.4 Student-Expert $k-\mathsf{BAT}$ 0.2 0.5







- Class Incremental Learning (CIL): Each context has a different set of classes
- Domain Incremental Learning (DIL): Each context has the same classes, but different underlying distributions mapping to those classes



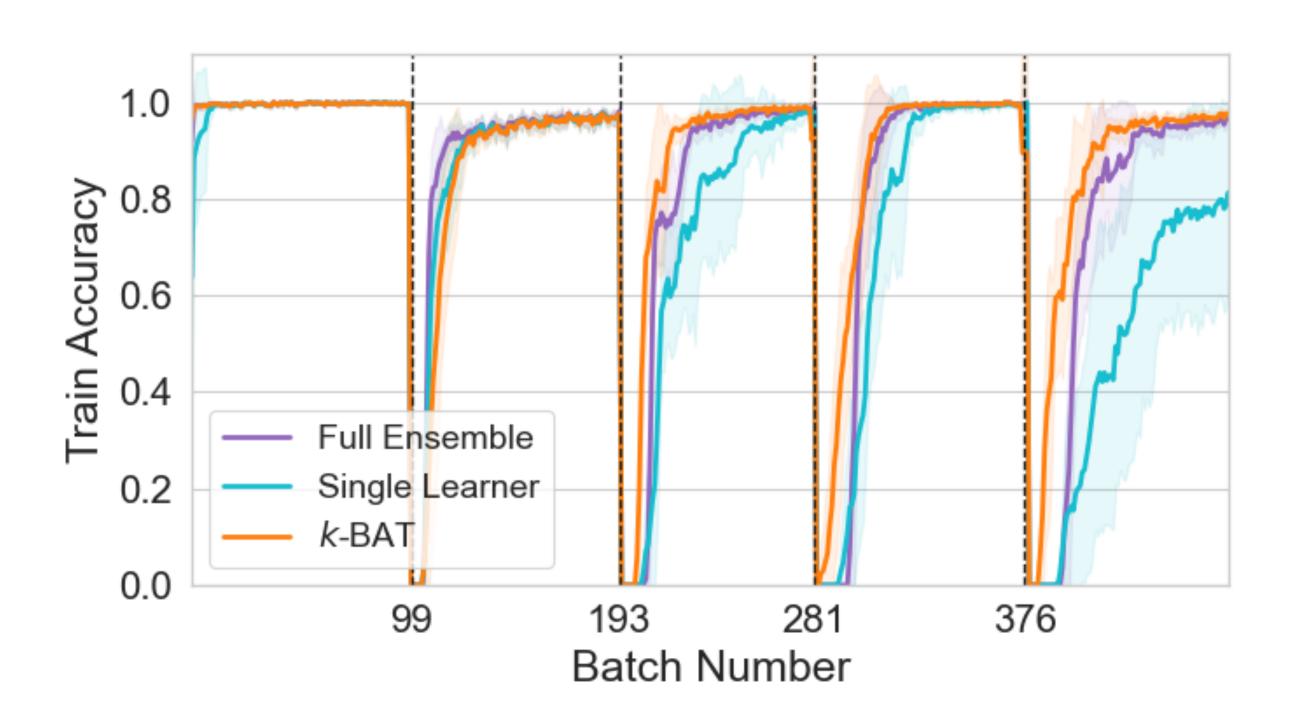
Results



- The ensemble members do not know when the task changes
- Yet, the classifiers effectively divide and conquer



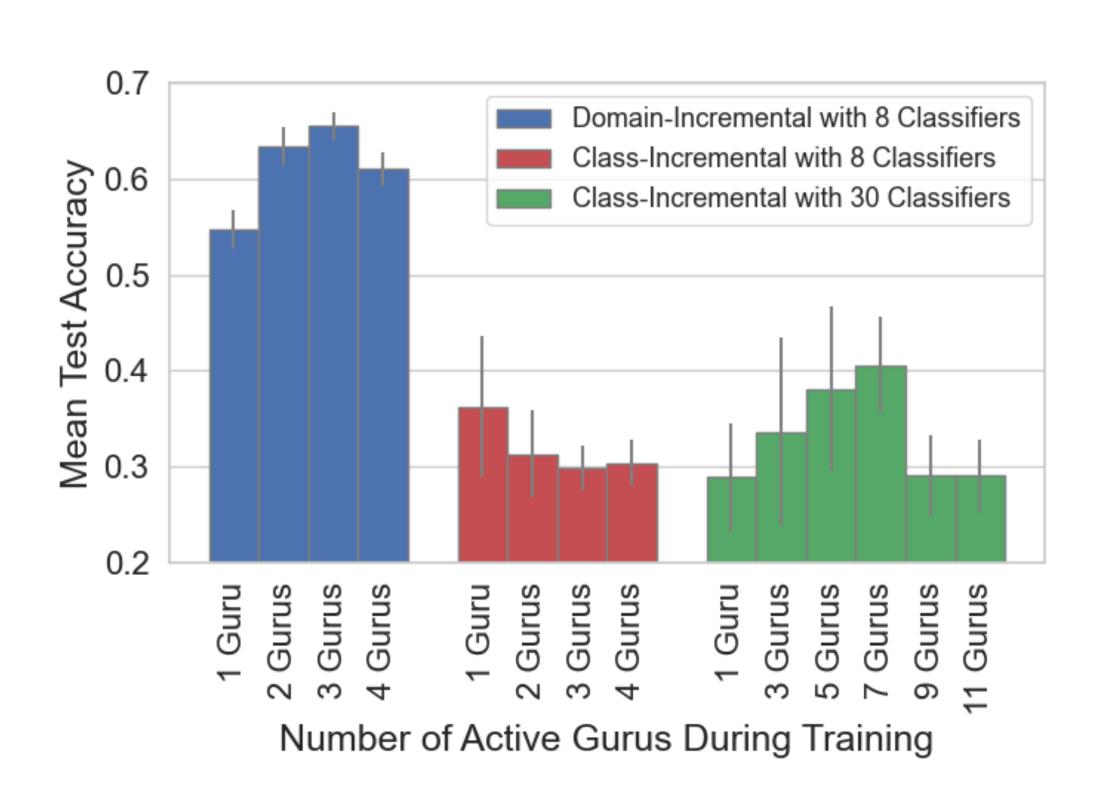




In later contexts, the single model has greatly reduced plasticity







Sometimes, having more ensemble members learning is helpful, and sometimes it's not

Moving Forward

- Continual learning is a relatively new field where social choice could be usefully applied
 - Online allocation of training
 - Representation of contexts
 - Aggregation of prediction

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