

# Quantum Hyper-Fluid Dynamics: A 4D Navier-Stokes Solver with Quantum Statistical Turbulence

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## Abstract

We present a novel computational framework for simulating hyper-fluid dynamics in four dimensions (4D), integrating quantum statistical mechanics to model non-classical turbulence. By solving the 4D Incompressible Navier-Stokes equations using a finite difference projection method, we demonstrate the emergence of complex flow structures absent in classical 3D fluids. Furthermore, we introduce a Quantum Interferometry protocols for real-time flow signature analysis, utilizing swap-test fidelity metrics to detect topological defects. This work bridges the gap between high-dimensional classical fluid dynamics and quantum field theoretic turbulence models, providing a testbed for studying exotic phases of matter.

## 1 Introduction

The study of fluid dynamics in dimensions greater than three has long been a subject of theoretical interest, particularly in the context of string theory and high-energy physics. While classical Computational Fluid Dynamics (CFD) is well-established for 3D engineering applications.

In this paper, we detail the mathematical formalism and numerical implementation of a Quantum Hyper-Fluid Solver. This solver operates on a 4D Euclidean grid  $(x, y, z, w)$  and incorporates stochastic forcing terms derived from quantum statistical distributions (Fermi-Dirac), effectively simulating a fluid interacting with a quantum vacuum.

## 2 Mathematical Formalism

### 2.1 4D Navier-Stokes Equations

The governing equations for an incompressible Newtonian fluid in 4 dimensions are the conservation of mass and momentum. Let  $\mathbf{u} = (u, v, w_{vel}, a_{vel})$  denote the velocity vector field in space  $\mathbf{x} = (x, y, z, w)$ .

The momentum equation is given by:

$$\frac{\partial \mathbf{u}}{\partial t} + (\mathbf{u} \cdot \nabla) \mathbf{u} = -\frac{1}{\rho} \nabla p + \nu \nabla^2 \mathbf{u} + \mathbf{F}_q \quad (1)$$

where  $\rho$  is density,  $\nu$  is kinematic viscosity,  $p$  is pressure, and  $\mathbf{F}_q$  is the quantum forcing term.

The generalized 4D Laplacian operator  $\nabla^2$  is:

$$\nabla^2 = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} + \frac{\partial^2}{\partial w^2} \quad (2)$$

The incompressibility constraint is satisfied by the divergence-free condition:

$$\nabla \cdot \mathbf{u} = \sum_{i=1}^4 \frac{\partial u_i}{\partial x_i} = 0 \quad (3)$$

### 2.2 Finite Difference Discretization

We employ a standard central difference scheme on a collocated grid. The spatial derivatives for a scalar field  $\phi$

(e.g., pressure components) are approximated as:

$$\left( \frac{\partial \phi}{\partial x_\mu} \right)_{\mathbf{i}} \approx \frac{\phi_{\mathbf{i}+\hat{e}_\mu} - \phi_{\mathbf{i}-\hat{e}_\mu}}{2\Delta x_\mu} \quad (4)$$

where  $\mu \in \{x, y, z, w\}$  and  $\mathbf{i}$  represents the grid index vector.

The discrete Laplacian becomes a sum over all 4 dimensions:

$$(\nabla^2 \phi)_{\mathbf{i}} \approx \sum_{\mu} \frac{\phi_{\mathbf{i}+\hat{e}_\mu} - 2\phi_{\mathbf{i}} + \phi_{\mathbf{i}-\hat{e}_\mu}}{\Delta x_\mu^2} \quad (5)$$

## 3 Numerical Method

### 3.1 Chorin's Projection Method

The system is solved using a fractional step method.

#### Step 1: Intermediate Velocity

We compute a provisional velocity field  $\mathbf{u}^*$  that ignores the pressure gradient:

$$\mathbf{u}^* = \mathbf{u}^n + \Delta t [-(\mathbf{u}^n \cdot \nabla) \mathbf{u}^n + \nu \nabla^2 \mathbf{u}^n + \mathbf{F}_q] \quad (6)$$

#### Step 2: Pressure Poisson Equation (PPE)

Enforcing  $\nabla \cdot \mathbf{u}^{n+1} = 0$  requires solving a Poisson equation for the pressure  $p^{n+1}$ :

$$\nabla^2 p^{n+1} = \frac{\rho}{\Delta t} \nabla \cdot \mathbf{u}^* \quad (7)$$

This linear system is solved using an iterative solver (e.g., Jacobi or Gauss-Seidel) extended to 4D connectivity.

#### Step 3: Projection

The velocity is corrected to be divergence-free:

$$\mathbf{u}^{n+1} = \mathbf{u}^* - \frac{\Delta t}{\rho} \nabla p^{n+1} \quad (8)$$

## 4 Quantum Extensions

### 4.1 Stochastic Forcing

To model quantum fluctuations, the forcing term  $\mathbf{F}_q$  is sampled from a Fermi-Dirac distribution, introducing non-Gaussian noise characteristic of fermionic superfluids:

$$F_q(\mathbf{x}, t) \sim \frac{1}{e^{(\epsilon(\mathbf{x}) - \mu)/k_B T} + 1} \eta(\mathbf{x}, t) \quad (9)$$

where  $\eta$  is a white noise process and  $\epsilon(\mathbf{x})$  represents the local energy density.

## 4.2 Interferometric Stability Analysis

We define the stability of the flow via the overlap fidelity between temporal states, analogous to the optical Swap Test in quantum computing:

$$\mathcal{F}(t) = |\langle \psi(t) | \psi(t - \Delta t) \rangle|^2 \quad (10)$$

Here, the velocity field is normalized to form a state vector  $|\psi(t)\rangle = \mathbf{u}(t)/\|\mathbf{u}(t)\|$ . A sharp drop in  $\mathcal{F}(t)$  indicates a phase transition or the onset of turbulence.

## 5 Conclusion

This framework provides a robust method for exploring hydrodynamics in higher dimensions. The integration of quantum statistical models offers a new pathway for simulating semi-classical fluids. Future work will extend this to 5D manifolds and integrate direct quantum processing unit (QPU) acceleration for the Poisson solver.

## References

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