

Another expression of the singularity coefficient for a constant right hand side

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We consider the following problem (see CC18 for all details)

$$\left| \begin{array}{l} \text{Find } u = u_r + b\zeta s, \ b \in \mathbb{C}, \ u_r \in H^1(D_\rho), \ \zeta \in C^\infty([0, 1], D_\rho), \ s \notin H^1(D_\rho), \ \text{s.t.:} \\ \operatorname{div}(\varepsilon^{-1}\nabla u) + k_0^2\mu u = 0 \quad \text{in } D_\rho \\ u = f \quad \text{on } \partial D_\rho \end{array} \right. \quad (1)$$

We define the singular complement z as the solution to the homogeneous problem

$$\left| \begin{array}{l} \text{Find } z = \zeta(s^* + cs) + \tilde{z}, \ c \in \mathbb{C}, \ \tilde{z} \in H^1(D_\rho) \text{ such that:} \\ \operatorname{div}(\varepsilon^{-1}\nabla z) + k_0^2\mu z = 0 \quad \text{in } D_\rho \\ z = 0 \quad \text{on } \partial D_\rho \end{array} \right. \quad (2)$$

Defining $w := c\zeta s + \tilde{z}$, solving Problem (2) is equivalent to solving:

$$\left| \begin{array}{l} \text{Find } w \text{ such that:} \\ \operatorname{div}(\varepsilon^{-1}\nabla w) + k_0^2\mu w = -\operatorname{div}(\varepsilon^{-1}\nabla(\zeta s^*)) - k_0^2\mu \zeta s^* \quad \text{in } D_\rho \\ w = 0 \quad \text{on } \partial D_\rho \end{array} \right. \quad (3)$$

Using the singular complement z , one can show after integration by parts on a perforated domain at the corner (and taking the limit) that the singularity coefficient admits the expression

$$b = -\frac{\int_{\partial D_\rho} \varepsilon^{-1} f \partial_r \tilde{z} \, d\sigma}{2\lambda \int_{-\pi}^{\pi} \varepsilon^{-1} \Phi^2 \, d\theta}. \quad (4)$$

The goal of these notes is to derive another formula in the specific case where f is constant. The reasons are two-fold: it is a simple case to test and formulas can be simplified, this can avoid to compute a normal derivative numerically to compute (4).

1 Lift the solution and new expression

First let us define $\tilde{f} \in H^1(D_\rho)$, the continuous extension of f over the domain D_ρ : for example consider $\tilde{f} = cst = f$ in D_ρ for constant right-hand side. Then we solve (1) for the lifted solution $u_l = u - \tilde{f} \in H_0^1(D_\rho)$:

$$\left| \begin{array}{l} \text{Find } u_l = u - \tilde{f}, \text{ s.t.:} \\ \operatorname{div}(\varepsilon^{-1} \nabla u_l) + k_0^2 \mu u_l = -k_0^2 \mu \tilde{f} \quad \text{in } D_\rho \\ u_l = 0 \quad \text{on } \partial D_\rho \end{array} \right. \quad (5)$$

Above we have used the fact that $\operatorname{div}(\varepsilon^{-1} \nabla \tilde{f}) = 0$.

Considering $0 < \delta < \rho$, using Problems (2)-(5) we have

$$- \int_{D_\rho \setminus \overline{D_\delta}} \varepsilon^{-1} \nabla u_l \cdot \nabla z + k_0^2 \int_{D_\rho \setminus \overline{D_\delta}} \mu u_l z + \int_{\partial D_\delta} \varepsilon^{-1} \partial_n u_l z = -k_0^2 \int_{D_\rho \setminus \overline{D_\delta}} \mu \tilde{f} z$$

and

$$- \int_{D_\rho \setminus \overline{D_\delta}} \varepsilon^{-1} \nabla z \cdot \nabla u_l + k_0^2 \int_{D_\rho \setminus \overline{D_\delta}} \mu z u_l + \int_{\partial D_\delta} \varepsilon^{-1} \partial_n z u_l = 0,$$

leading to

$$\int_{\partial D_\delta} \varepsilon^{-1} \partial_n u_l z - \int_{\partial D_\delta} \varepsilon^{-1} \partial_n z u_l = -k_0^2 \int_{D_\rho \setminus \overline{D_\delta}} \mu \tilde{f} z \quad (6)$$

Using the fact that

$$\lim_{\delta \rightarrow 0} \int_{\partial D_\delta} \varepsilon^{-1} (\partial_r u_l z - \partial_r z u_l) d\sigma = 2b \lambda \int_{-\pi}^{\pi} \varepsilon^{-1} \Phi^2 d\theta \quad (7)$$

We obtain the alternate expression of b :

$$b = -k_0^2 \frac{\int_{D_\rho} \mu \tilde{f} z}{2\lambda \int_{-\pi}^{\pi} \varepsilon^{-1} \Phi^2 d\theta}. \quad (8)$$

for which there is no normal derivative to approximate. Contrary to (4) we will need the full knowledge of z for that coefficient.

For numerical tests with a constant right-hand side we will use formula (8). Note that if we have a smooth data (meaning for any non constant chosen extension $\tilde{f} \in H_0^1(D_\rho)$), one can use the same method leading to the following expression:

$$b = \frac{\int_{D_\rho} \varepsilon^{-1} \nabla \tilde{f} \cdot \nabla z - k_0^2 \int_{D_\rho} \mu \tilde{f} z}{2\lambda \int_{-\pi}^{\pi} \varepsilon^{-1} \Phi^2 d\theta}, \quad (9)$$

where we used the fact that $\int_{D_\rho} \operatorname{div}(\varepsilon^{-1} \nabla \tilde{f}) z = - \int_{D_\rho} \varepsilon^{-1} \nabla \tilde{f} \cdot \nabla z + \int_{\partial D_\rho} \varepsilon^{-1} \partial_r \tilde{f} z$, and $z = 0$ on ∂D_ρ . In that case the right-hand side in (5) is slightly modified as well.

2 Variational formulation for the regular part

Once b is computed, one can solve the problem only for the regular part $u_{l,r} = u_r - \tilde{f} = u_l - b\zeta s$:

$$\left| \begin{array}{l} \text{Find } u_{l,r} \text{ s.t.:} \\ \operatorname{div}(\varepsilon^{-1} \nabla u_{l,r}) + k_0^2 \mu u_{l,r} = -k_0^2 \mu \tilde{f} - b \operatorname{div}(\varepsilon^{-1} \nabla(\zeta s)) - b k_0^2 \mu \zeta s \quad \text{in } D_\rho \\ u_{l,r} = 0 \quad \text{on } \partial D_\rho \end{array} \right. \quad (10)$$

Note that the right-hand side is still well defined. This leads to the following variational formulation

$$\left| \begin{array}{l} \text{Find } u_{l,r} \in H_0^1(D_\rho) \text{ s.t.: } \forall v' \in H_0^1(D_\rho) \\ - \int_{D_\rho} \varepsilon^{-1} \nabla u_{l,r} \cdot \overline{\nabla v'} + k_0^2 \int_{D_\rho} \mu u_{l,r} \overline{v'} = - \int_{D_\rho} k_0^2 \mu \tilde{f} \overline{v'} + b \int_{D_\rho} \varepsilon^{-1} \nabla(\zeta s) \cdot \overline{\nabla v'} - b k_0^2 \int_{D_\rho} \mu \zeta s \overline{v'} \end{array} \right. \quad (11)$$

Using the expression of the cutt-off function we have (for $\delta < l < \rho$):

$$\left| \begin{array}{l} \text{Find } u_{l,r} \text{ s.t.:} \\ \operatorname{div}(\varepsilon^{-1} \nabla u_{l,r}) + k_0^2 \mu u_{l,r} = -k_0^2 \mu \tilde{f} - b k_0^2 \mu s \quad \text{in } D_\delta \\ \operatorname{div}(\varepsilon^{-1} \nabla u_{l,r}) + k_0^2 \mu u_{l,r} = -k_0^2 \mu \tilde{f} - b \operatorname{div}(\varepsilon^{-1} \nabla(\eta s)) - b k_0^2 \mu \eta s \quad \text{in } D_{l,\delta} := D_l \setminus \overline{D_\delta} \\ \operatorname{div}(\varepsilon^{-1} \nabla u_{l,r}) + k_0^2 \mu u_{l,r} = -k_0^2 \mu \tilde{f} \quad \text{in } D_\rho \\ u_{l,r} = 0 \quad \text{on } \partial D_\rho \end{array} \right. \quad (12)$$

leading to the variational formulation

$$\left| \begin{array}{l} \text{Find } u_{l,r} \in H_0^1(D_\rho) \text{ s.t.: } \forall v' \in H_0^1(D_\rho) \\ - \int_{D_\rho} \varepsilon^{-1} \nabla u_{l,r} \cdot \overline{\nabla v'} + k_0^2 \int_{D_\rho} \mu u_{l,r} \overline{v'} = - \int_{D_\rho} k_0^2 \mu \tilde{f} \overline{v'} - b \int_{D_{l,\delta}} \operatorname{div}(\varepsilon^{-1} \nabla(\zeta s)) \overline{v'} - b k_0^2 \int_{D_\rho} \mu \zeta s \overline{v'} \\ \iff \\ - \int_{D_\rho} \varepsilon^{-1} \nabla u_{l,r} \cdot \overline{\nabla v'} + k_0^2 \int_{D_\rho} \mu u_{l,r} \overline{v'} = - \int_{D_\rho} k_0^2 \mu \tilde{f} \overline{v'} + b \int_{D_{l,\delta}} \varepsilon^{-1} \nabla(\zeta s) \cdot \overline{\nabla v'} \\ + b \int_{\partial D_\delta} \varepsilon^{-1} \partial_r s \overline{v'} - b k_0^2 \int_{D_\rho} \mu \zeta s \overline{v'} \end{array} \right. \quad (13)$$

3 Numerical method

Based on CC18 we discretize terms differently depending on the the parts (singular or regular) involved. For (11), the left-hand side and the first term on the right-hand side are discretized with standard FEM, and the last tow terms in the right-hand side are discretized using Newton-Cotes quadrature rules. With the CC18 notations we have

$$(-\mathbb{K}_\varepsilon + k_0^2 \mathbb{M}_\mu) U = -k_0^2 \mathbb{M}_\mu F - b(\mathbb{A}_0 + \mathbb{B}_0) S$$